

Import biblioteki **TensorFlow** (<https://www.tensorflow.org/>) z której będziemy korzystali w **uczeniu maszynowym**:

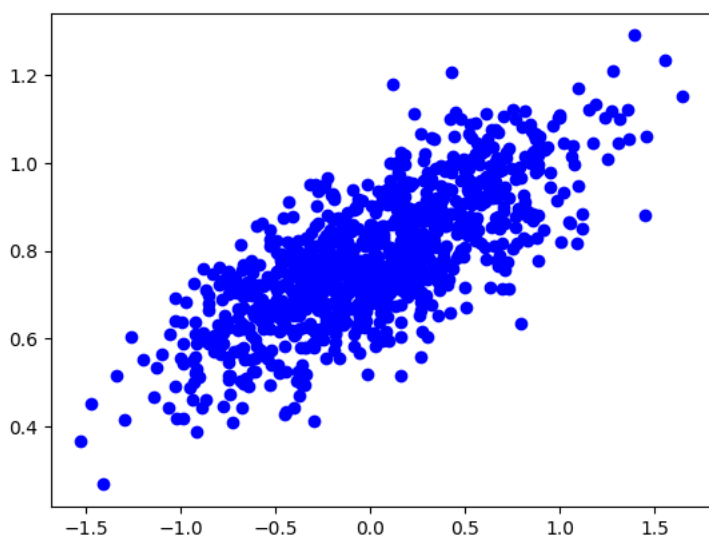
```
import tensorflow as tf
import matplotlib.pyplot as plt
import numpy as np
```

```
number_of_points = 1000
x_point = []
y_point = []
```

```
a = 0.22
b = 0.78
```

```
for i in range(number_of_points):
    x = np.random.normal(0.0,0.5)
    y = (a*x+b)+np.random.normal(0.0,0.1)
    x_point.append(x)
    y_point.append(y)
```

```
plt.scatter(x_point,y_point,c='b')
plt.show()
```



```
real_x = np.array(x_point)
real_y = np.array(y_point)
```

```
import keras
from keras.models import Sequential
from keras.layers import Dense
```

Definiujemy model:

```
model = Sequential()
```

Dodajemy **jedną warstwę** (Dense) z **jednym neuronem** (units=1) z **biasem** (use\_bias=True) i **liniową funkcją aktywacji** (activation="linear"):

```
model.add(Dense(units = 1, use_bias=True, input_dim=1, activation = "linear"))
```

Definiujemy **optymalizator** i **błąd** (średni błąd kwadratowy - MSE). **Współczynnik uczenia** = 0.1

```
opt = tf.keras.optimizers.SGD(learning_rate=0.1)
```

```
model.compile(loss='MSE',optimizer=opt)
```

```
model.summary()
```

```
Model: "sequential"
```

Layer (type)	Output Shape	Param #
dense (Dense)	(None, 1)	2

=====

Total params: 2 (8.00 Byte)

Trainable params: 2 (8.00 Byte)

Non-trainable params: 0 (0.00 Byte)

=====

Proces **uczenia**:

```
epochs = 1000
h = model.fit(real_x,real_y, verbose=0, epochs=epochs, batch_size=100)
```

```
Loss = h.history['loss']
Loss

0.009976331144571304,
0.009992128238081932,
0.009996611624956131,
0.009984729811549187,
0.009986542165279388,
0.009986688382923603,
0.009975828230381012,
0.009974825195968151,
0.009980661794543266,
0.00998423621058464,
0.009978027082979679,
0.009987233206629753,
0.009984341450035572,
0.00999152660369873,
0.009998512454330921,
0.009997275657951832,
0.009981083683669567,
0.009973958134651184,
0.009996677748858929,
0.009979743510484695,
0.00997694581747055,
0.009980532340705395,
0.009982114657759666,
0.009985162876546383,
0.00998216774314642,
0.009988078847527504,
0.009986065328121185,
0.00998198427259922,
0.009990599006414413,
0.009999380446970463,
0.009991451166570187,
0.009998592548072338,
0.009995047934353352,
0.009999320842325687,
0.00997804757207632,
0.0099936006590724,
0.009997382760047913,
0.009975423105061054,
0.009991454891860485,
0.0099792294204233508,
0.009989317506551743,
0.00997554324567318,
0.00998847745358944,
0.00998824741691351,
0.009990261867642403,
0.009993656538426876,
0.009980959817767143,
0.009979212656617165,
0.010000030510127544,
0.010004711337387562,
0.00998886302113533,
0.009985696524381638,
0.009980960749089718,
0.009991595521569252,
0.009976213797926903,
0.01000884547829628,
0.00997899565845728,
0.00998386088758707]
```

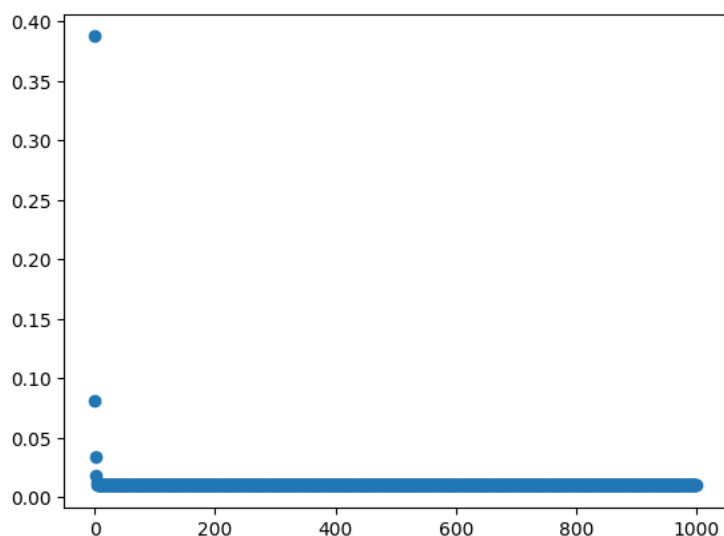
Sprawdźmy jakie są **wartości wag**:

```
weights = model.get_weights()

print(weights[0][0][0])
print(weights[1][0])    #bias
```

```
0.21798924
0.7798659
```

```
plt.scatter(np.arange(epochs), Loss)
plt.show()
```



Sprawdzenie modelu:

```
model.predict([0.6])
```

```
1/1 [=====] - 0s 94ms/step
array([[0.91065943]], dtype=float32)
```

```
model = Sequential()
```

## ▼ Verbose 1

```
model = Sequential()
```

```
model.add(Dense(units = 1, use_bias=True, input_dim=1, activation = "linear"))
```

```
opt = tf.keras.optimizers.SGD(learning_rate=0.1)
```

```
model.compile(loss='MSE', optimizer=opt)
```

```
model.summary()
```

```
Model: "sequential_2"
```

Layer (type)	Output Shape	Param #
dense_1 (Dense)	(None, 1)	2

=====  
 Total params: 2 (8.00 Byte)  
 Trainable params: 2 (8.00 Byte)  
 Non-trainable params: 0 (0.00 Byte)

```
epochs = 1000
```

```
h = model.fit(real_x, real_y, verbose=1, epochs=epochs, batch_size=100)
```

```
epoch 976/1000
10/10 [=====] - 0s 2ms/step - loss: 0.0100
Epoch 977/1000
10/10 [=====] - 0s 2ms/step - loss: 0.0100
Epoch 978/1000
10/10 [=====] - 0s 2ms/step - loss: 0.0100
Epoch 979/1000
10/10 [=====] - 0s 3ms/step - loss: 0.0100
Epoch 980/1000
10/10 [=====] - 0s 3ms/step - loss: 0.0100
Epoch 981/1000
10/10 [=====] - 0s 2ms/step - loss: 0.0100
Epoch 982/1000
10/10 [=====] - 0s 2ms/step - loss: 0.0100
Epoch 983/1000
10/10 [=====] - 0s 3ms/step - loss: 0.0100
Epoch 984/1000
10/10 [=====] - 0s 3ms/step - loss: 0.0100
Epoch 985/1000
10/10 [=====] - 0s 3ms/step - loss: 0.0100
Epoch 986/1000
10/10 [=====] - 0s 3ms/step - loss: 0.0100
Epoch 987/1000
10/10 [=====] - 0s 2ms/step - loss: 0.0100
Epoch 988/1000
10/10 [=====] - 0s 2ms/step - loss: 0.0100
Epoch 989/1000
10/10 [=====] - 0s 3ms/step - loss: 0.0100
Epoch 990/1000
10/10 [=====] - 0s 2ms/step - loss: 0.0100
Epoch 991/1000
10/10 [=====] - 0s 2ms/step - loss: 0.0100
Epoch 992/1000
10/10 [=====] - 0s 2ms/step - loss: 0.0100
Epoch 993/1000
10/10 [=====] - 0s 2ms/step - loss: 0.0100
Epoch 994/1000
10/10 [=====] - 0s 2ms/step - loss: 0.0100
Epoch 995/1000
10/10 [=====] - 0s 2ms/step - loss: 0.0100
Epoch 996/1000
10/10 [=====] - 0s 2ms/step - loss: 0.0100
Epoch 997/1000
10/10 [=====] - 0s 2ms/step - loss: 0.0100
Epoch 998/1000
10/10 [=====] - 0s 2ms/step - loss: 0.0100
Epoch 999/1000
10/10 [=====] - 0s 2ms/step - loss: 0.0100
Epoch 1000/1000
10/10 [=====] - 0s 2ms/step - loss: 0.0100
```

```
Loss = h.history['loss']
Loss
```

```
0.01000525988638401,
0.009983773343265057,
0.009987001307308674,
0.009989144280552864,
0.009979978203773499,
0.010005824267864227,
0.009988304227590561,
0.009980930015444756,
0.009987849742174149,
0.009997163899242878,
0.009977073408663273,
0.009979501366615295,
0.009972183033823967,
0.01000935398042202,
0.009984347969293594,
0.010026856325566769,
0.009987297467887402,
0.009978161193430424,
0.009991697035729885,
0.009975031018257141,
0.009981770068407059,
0.009983150288462639,
0.009980679489672184.
```

```
weights = model.get_weights()
```

```
print(weights[0][0][0])
```

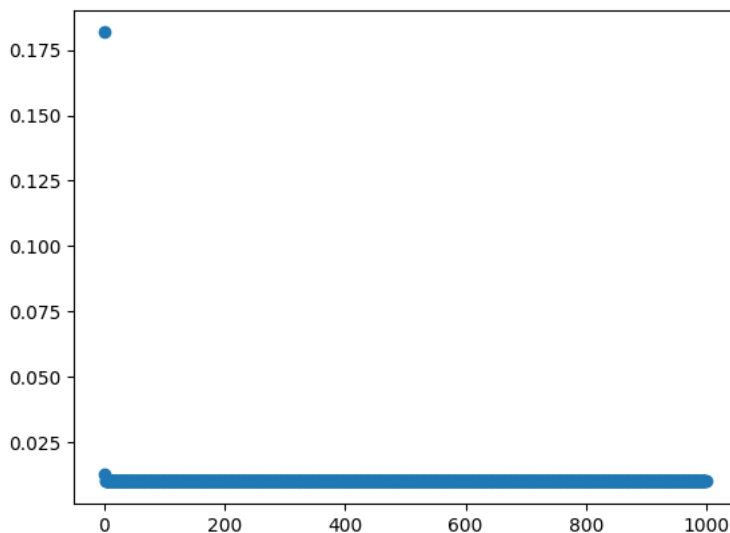
```
print(weights[1][0])    #bias
```

```
0.21753295
```

```
0.7798778
```

```
plt.scatter(np.arange(epochs), Loss)
```

```
plt.show()
```



```
model.predict([0.6])
```

```
1/1 [=====] - 0s 58ms/step
array([[0.9103975]], dtype=float32)
```

```
model = Sequential()
```

## ▼ Verbose 2

```
model = Sequential()
```

```
model.add(Dense(units = 1, use_bias=True, input_dim=1, activation = "linear"))
```

```
opt = tf.keras.optimizers.SGD(learning_rate=0.1)
```

```
model.compile(loss='MSE', optimizer=opt)
```

```
model.summary()
```

Model: "sequential\_4"

Layer (type)	Output Shape	Param #
dense_2 (Dense)	(None, 1)	2

=====  
Total params: 2 (8.00 Byte)  
Trainable params: 2 (8.00 Byte)  
Non-trainable params: 0 (0.00 Byte)  
=====

```
epochs = 1000  
h = model.fit(real_x,real_y, verbose=2, epochs=epochs, batch_size=100)
```

```
Epoch 1/1000  
10/10 - 0s - loss: 0.4559 - 238ms/epoch - 24ms/step  
Epoch 2/1000  
10/10 - 0s - loss: 0.1056 - 16ms/epoch - 2ms/step  
Epoch 3/1000  
10/10 - 0s - loss: 0.0413 - 17ms/epoch - 2ms/step  
Epoch 4/1000  
10/10 - 0s - loss: 0.0205 - 17ms/epoch - 2ms/step  
Epoch 5/1000  
10/10 - 0s - loss: 0.0135 - 19ms/epoch - 2ms/step  
Epoch 6/1000  
10/10 - 0s - loss: 0.0112 - 17ms/epoch - 2ms/step  
Epoch 7/1000  
10/10 - 0s - loss: 0.0104 - 19ms/epoch - 2ms/step  
Epoch 8/1000  
10/10 - 0s - loss: 0.0101 - 19ms/epoch - 2ms/step  
Epoch 9/1000  
10/10 - 0s - loss: 0.0100 - 18ms/epoch - 2ms/step  
Epoch 10/1000  
10/10 - 0s - loss: 0.0100 - 18ms/epoch - 2ms/step  
Epoch 11/1000  
10/10 - 0s - loss: 0.0100 - 18ms/epoch - 2ms/step  
Epoch 12/1000  
10/10 - 0s - loss: 0.0100 - 18ms/epoch - 2ms/step  
Epoch 13/1000  
10/10 - 0s - loss: 0.0100 - 29ms/epoch - 3ms/step  
Epoch 14/1000  
10/10 - 0s - loss: 0.0100 - 17ms/epoch - 2ms/step  
Epoch 15/1000  
10/10 - 0s - loss: 0.0100 - 17ms/epoch - 2ms/step  
Epoch 16/1000  
10/10 - 0s - loss: 0.0100 - 20ms/epoch - 2ms/step  
Epoch 17/1000  
10/10 - 0s - loss: 0.0100 - 16ms/epoch - 2ms/step  
Epoch 18/1000  
10/10 - 0s - loss: 0.0100 - 16ms/epoch - 2ms/step  
Epoch 19/1000  
10/10 - 0s - loss: 0.0100 - 20ms/epoch - 2ms/step  
Epoch 20/1000  
10/10 - 0s - loss: 0.0100 - 18ms/epoch - 2ms/step  
Epoch 21/1000  
10/10 - 0s - loss: 0.0100 - 21ms/epoch - 2ms/step  
Epoch 22/1000  
10/10 - 0s - loss: 0.0100 - 17ms/epoch - 2ms/step  
Epoch 23/1000  
10/10 - 0s - loss: 0.0100 - 16ms/epoch - 2ms/step  
Epoch 24/1000  
10/10 - 0s - loss: 0.0100 - 26ms/epoch - 3ms/step  
Epoch 25/1000  
10/10 - 0s - loss: 0.0100 - 18ms/epoch - 2ms/step  
Epoch 26/1000  
10/10 - 0s - loss: 0.0100 - 16ms/epoch - 2ms/step  
Epoch 27/1000  
10/10 - 0s - loss: 0.0100 - 15ms/epoch - 2ms/step  
Epoch 28/1000  
10/10 - 0s - loss: 0.0100 - 16ms/epoch - 2ms/step  
Epoch 29/1000  
10/10 - 0s - loss: 0.0100 - 20ms/epoch - 2ms/step
```

```
Loss = h.history['loss']  
Loss
```

```

0.009983240626752377,
0.009986440651118755,
0.009981588460505009,
0.009990183636546135,
0.009995918720960617,
0.009990015998482704,
0.009988166391849518,
0.00999691616743803,
0.009992764331400394,
0.009987976402044296,
0.009995845146477222,
0.009979686699807644,
0.009975286200642586,
0.010006737895309925,
0.009993739426136017,
0.009979598224163055,
0.009985408745706081,
0.009985476732254028,
0.01000138372182846,
0.009978880174458027,
0.00998388827264309,
0.009987604804337025,
0.009979789145290852,
0.009980215691030025,
0.00997757725417614,
0.01000747550278902,
0.009984835051000118,
0.009978349320590496,
0.009982410818338394,
0.00998592283576727,
0.009977930225431919,
0.009994101710617542,
0.009972793981432915,
0.009991489350795746,
0.009978756308555603,
0.009980859234929085,
0.00998321920633316,
0.009992046281695366,
0.009993370622396469,
0.009988215751945972,
0.009968490339815617,
0.01002125721424818,
0.0099954754114151,
0.009979217313230038,
0.009978643618524075,
0.00999427493661642,
0.009976952336728573,
0.009981672279536724,
0.009985855780541897,

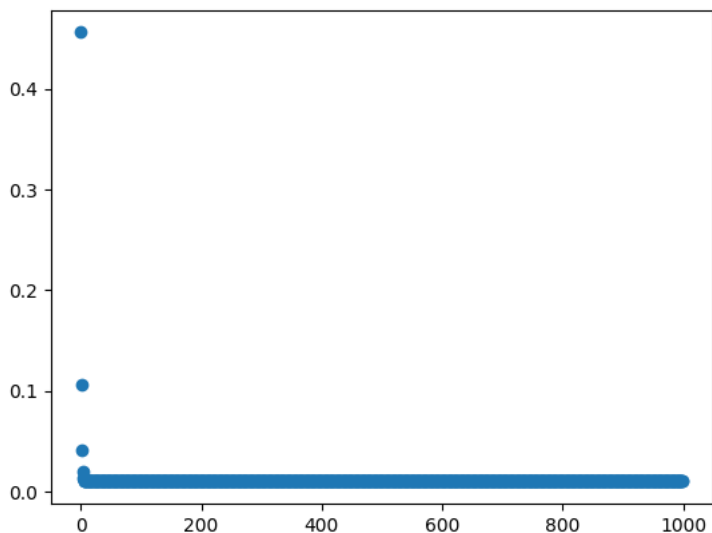
```

```
weights = model.get_weights()
```

```
print(weights[0][0][0])
print(weights[1][0])    #bias
```

```
0.21782869
0.7834272
```

```
plt.scatter(np.arange(epochs), Loss)
plt.show()
```



```
model.predict([0.6])
```

```
1/1 [=====] - 0s 59ms/step  
array([[0.91412437]], dtype=float32)
```

```
model = Sequential()
```

## ▼ Podsumowanie verbose

[+ Kod](#)[+ Tekst](#)

Keras verbose definiuje tryb wyświetlania postępu uczenia modelu, można dać wartości 0, 1 lub 2 (automatycznie jest 1). W tym trybie 0 jest definiowane jako ciche (nie ma informacji wyświetlanych o uczeniu modelu), w przypadku użycia wartości 1 potęp jest wyświetlany jako pojedyncza linia z pasekiem postępu na epokę, a wypadku wartości 2 potęp jest wyświetlany jako pojedyncza linia na epokę. PARAMETR TEN NIE MA WPŁYWU NA UCZENIE SIĘ MODELU

Nie można połączyć się z usługą reCAPTCHA. Sprawdź połączenie z internetem i załaduj ponownie zadanie reCAPTCHA.