Import biblioteki **TensorFlow** (https://www.tensorflow.org/) z której będziemy korzystali w uczeniu maszynowym:

```
import tensorflow as tf
import matplotlib.pyplot as plt
import numpy as np
import pandas as pd
df = pd.read_csv('Boston.csv')
print(df)
```

		Unnamed: 0		crim	zn	indus	chas	nox	rm	age	dis	rad	\
	0	1		0.00632	18.0	2.31	0	0.538	6.575	65.2	4.0900	1	
	1	2		0.02731	0.0	7.07	0	0.469	6.421	78.9	4.9671	2	
	2	3		0.02729	0.0	7.07	0	0.469	7.185	61.1	4.9671	2	
	3		4	0.03237	0.0	2.18	0	0.458	6.998	45.8	6.0622	3	
	4	. 5		0.06905	0.0	2.18	0	0.458	7.147	54.2	6.0622	3	
	501		502	0.06263	0.0	11.93	0	0.573	6.593	69.1	2.4786	1	
	502		503	0.04527	0.0	11.93	0	0.573	6.120	76.7	2.2875	1	
	503		504	0.06076	0.0	11.93	0	0.573	6.976	91.0	2.1675	1	
	504		505	0.10959	0.0	11.93	0	0.573	6.794	89.3	2.3889	1	
	505	506		0.04741	0.0	11.93	0	0.573	6.030	80.8	2.5050	1	
		tax	ptrati	o black	lsta	t medv							
	0	296	15.	3 396.90	4.9	8 24.0							
	1	242	17.	8 396.90	9.1	4 21.6							
	2	242	17.	8 392.83	4.0	3 34.7							
	3	222	18.	7 394.63	2.9	4 33.4							
	4	222	18.	7 396.90	5.3	3 36.2							
		• • • • • • • • • • • • • • • • • • • •											
	501	273	21.	0 391.99	9.6	7 22.4							
	502	273	21.	0 396.90	9.0	8 20.6							
	503	273	21.	0 396.90	5.6	4 23.9							
	504	273	21.	0 393.45	6.4	8 22.0							
	505	273	21.		7.8								

[506 rows x 15 columns]

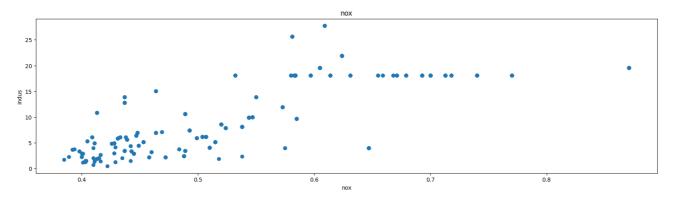
df.head()

	Unnamed:	crim	zn	indus	chas	nox	rm	age	dis	rad	tax	ptratio	
0	1	0.00632	18.0	2.31	0	0.538	6.575	65.2	4.0900	1	296	15.3	;
1	2	0.02731	0.0	7.07	0	0.469	6.421	78.9	4.9671	2	242	17.8	;
2	3	0.02729	0.0	7.07	0	0.469	7.185	61.1	4.9671	2	242	17.8	;
3	4	0.03237	0.0	2.18	0	0.458	6.998	45.8	6.0622	3	222	18.7	,
4												→	

nox=df.iloc[:,6]

```
nox
```

```
0
            6.575
     1
            6.421
     2
            7.185
     3
            6.998
     4
            7.147
            . . .
     501
            6.593
     502
            6.120
     503
            6.976
     504
            6.794
     505
            6.030
     Name: rm, Length: 506, dtype: float64
indus=df.iloc[:,14]
indus
     0
            24.0
     1
            21.6
     2
            34.7
     3
            33.4
     4
            36.2
            . . .
     501
            22.4
     502
            20.6
            23.9
     503
     504
            22.0
     505
            11.9
     Name: medv, Length: 506, dtype: float64
plt.figure(figsize=(20, 5))
features = ['nox']
target = df['indus']
for i, col in enumerate(features):
    plt.subplot(1, len(features) , i+1)
    x = df[col]
    y = target
    plt.scatter(x, y, marker='o')
    plt.title(col)
    plt.xlabel(col)
    plt.ylabel('indus')
plt.show()
```



nox

0	6.5	575			
1	6.4	421			
2	7.3	185			
3	6.9	998			
4	7.3	147			
		•			
501	6.5	593			
502	6.3	120			
503	6.9	976			
504	6.7	794			
505	6.6	930			
Name:	rm,	Length:	506,	dtype:	float64

df.corr()

		Unnamed: 0	crim	zn	indus	chas	nox	rm	
	Unnamed:	1.000000	0.407407	-0.103393	0.399439	-0.003759	0.398736	-0.079971	0.1
	crim	N 4N74N7	1 000000	_ ∪ 	U 108283	_Ი ᲘᲜᲜጲႭᲔ	N 42NQ72	_N 2102 <i>4</i> 7	۸ ،
df.cc	orr()								
		Unnamed:	crim	zn	indus	chas	nox	rm	
	Unnamed:	1.000000	0.407407	-0.103393	0.399439	-0.003759	0.398736	-0.079971	0.1
	crim	0.407407	1.000000	-0.200469	0.406583	-0.055892	0.420972	-0.219247	0.0
	zn	-0.103393	-0.200469	1.000000	-0.533828	-0.042697	-0.516604	0.311991	-0.
	indus	0.399439	0.406583	-0.533828	1.000000	0.062938	0.763651	-0.391676	0.0
	chas	-0.003759	-0.055892	-0.042697	0.062938	1.000000	0.091203	0.091251	0.0
	nox	0.398736	0.420972	-0.516604	0.763651	0.091203	1.000000	-0.302188	0.
	rm	-0.079971	-0.219247	0.311991	-0.391676	0.091251	-0.302188	1.000000	-0.1
	age	0.203784	0.352734	-0.569537	0.644779	0.086518	0.731470	-0.240265	1.0
	dis	-0.302211	-0.379670	0.664408	-0.708027	-0.099176	-0.769230	0.205246	-0.
	rad	0.686002	0.625505	-0.311948	0.595129	-0.007368	0.611441	-0.209847	0.4
	tax	0.666626	0.582764	-0.314563	0.720760	-0.035587	0.668023	-0.292048	0.
	ptratio	0.291074	0.289946	-0.391679	0.383248	-0.121515	0.188933	-0.355501	0.1
	black	-0.295041	-0.385064	0.175520	-0.356977	0.048788	-0.380051	0.128069	-0.1
	Istat	0.258465	0.455621	-0.412995	0.603800	-0.053929	0.590879	-0.613808	0.0

```
real_x = np.array(nox)
real_y = np.array(indus)
```

real_x

```
array([6.575, 6.421, 7.185, 6.998, 7.147, 6.43, 6.012, 6.172, 5.631, 6.004, 6.377, 6.009, 5.889, 5.949, 6.096, 5.834, 5.935, 5.99, 5.456, 5.727, 5.57, 5.965, 6.142, 5.813, 5.924, 5.599, 5.813, 6.047, 6.495, 6.674, 5.713, 6.072, 5.95, 5.701, 6.096, 5.933, 5.841, 5.85, 5.966, 6.595, 7.024, 6.77, 6.169, 6.211, 6.069, 5.682, 5.786, 6.03, 5.399, 5.602, 5.963, 6.115, 6.511, 5.998, 5.888, 7.249, 6.383, 6.816, 6.145, 5.927, 5.741, 5.966, 6.456, 6.762, 7.104, 6.29, 5.787, 5.878, 5.594, 5.885, 6.417, 5.961, 6.065, 6.245, 6.273, 6.286, 6.279, 6.14, 6.232, 5.874, 6.727, 6.619, 6.302, 6.167, 6.389, 6.63, 6.015, 6.121, 7.007, 7.079, 6.417, 6.405, 6.442, 6.211, 6.249, 6.625, 6.163, 8.069, 7.82, 7.416, 6.727, 6.781, 6.405, 6.137, 6.167, 5.851, 5.836, 6.127, 6.474, 6.229, 6.195, 6.715, 5.913, 6.092, 6.254, 5.928, 6.176,
```

```
6.021, 5.872, 5.731, 5.87, 6.004, 5.961, 5.856, 5.879, 5.986,
5.613, 5.693, 6.431, 5.637, 6.458, 6.326, 6.372, 5.822, 5.757,
6.335, 5.942, 6.454, 5.857, 6.151, 6.174, 5.019, 5.403, 5.468,
4.903, 6.13, 5.628, 4.926, 5.186, 5.597, 6.122, 5.404, 5.012,
5.709, 6.129, 6.152, 5.272, 6.943, 6.066, 6.51, 6.25, 7.489,
7.802, 8.375, 5.854, 6.101, 7.929, 5.877, 6.319, 6.402, 5.875,
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7.765, 6.144, 7.155, 6.563, 5.604, 6.153, 7.831, 6.782, 6.556,
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6.957, 8.259, 6.108, 5.876, 7.454, 8.704, 7.333, 6.842, 7.203,
7.52 , 8.398, 7.327, 7.206, 5.56 , 7.014, 8.297, 7.47 , 5.92 ,
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6.812, 7.82, 6.968, 7.645, 7.923, 7.088, 6.453, 6.23, 6.209,
6.315, 6.565, 6.861, 7.148, 6.63, 6.127, 6.009, 6.678, 6.549,
5.79 , 6.345, 7.041, 6.871, 6.59 , 6.495, 6.982, 7.236, 6.616,
7.42 , 6.849, 6.635, 5.972, 4.973, 6.122, 6.023, 6.266, 6.567,
5.705, 5.914, 5.782, 6.382, 6.113, 6.426, 6.376, 6.041, 5.708,
6.415, 6.431, 6.312, 6.083, 5.868, 6.333, 6.144, 5.706, 6.031,
6.316, 6.31, 6.037, 5.869, 5.895, 6.059, 5.985, 5.968, 7.241,
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6.683, 7.016, 6.216, 5.875, 4.906, 4.138, 7.313, 6.649, 6.794,
6.38 , 6.223, 6.968, 6.545, 5.536, 5.52 , 4.368, 5.277, 4.652,
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6.406, 6.219, 6.485, 5.854, 6.459, 6.341, 6.251, 6.185, 6.417,
6.749, 6.655, 6.297, 7.393, 6.728, 6.525, 5.976, 5.936, 6.301,
6.081, 6.701, 6.376, 6.317, 6.513, 6.209, 5.759, 5.952, 6.003,
5.926, 5.713, 6.167, 6.229, 6.437, 6.98, 5.427, 6.162, 6.484,
5.304, 6.185, 6.229, 6.242, 6.75, 7.061, 5.762, 5.871, 6.312,
6.114, 5.905, 5.454, 5.414, 5.093, 5.983, 5.983, 5.707, 5.926,
5.67, 5.39, 5.794, 6.019, 5.569, 6.027, 6.593, 6.12, 6.976,
6.794, 6.03])
```

real y

```
array([24., 21.6, 34.7, 33.4, 36.2, 28.7, 22.9, 27.1, 16.5, 18.9, 15., 18.9, 21.7, 20.4, 18.2, 19.9, 23.1, 17.5, 20.2, 18.2, 13.6, 19.6, 15.2, 14.5, 15.6, 13.9, 16.6, 14.8, 18.4, 21., 12.7, 14.5, 13.2, 13.1, 13.5, 18.9, 20., 21., 24.7, 30.8, 34.9, 26.6, 25.3, 24.7, 21.2, 19.3, 20., 16.6, 14.4, 19.4, 19.7, 20.5, 25., 23.4, 18.9, 35.4, 24.7, 31.6, 23.3, 19.6, 18.7, 16., 22.2, 25., 33., 23.5, 19.4, 22., 17.4, 20.9, 24.2, 21.7, 22.8, 23.4, 24.1, 21.4, 20., 20.8, 21.2, 20.3, 28., 23.9, 24.8, 22.9, 23.9, 26.6, 22.5, 22.2, 23.6, 28.7, 22.6, 22., 22.9, 25., 20.6, 28.4, 21.4, 38.7, 43.8, 33.2, 27.5, 26.5, 18.6, 19.3, 20.1, 19.5, 19.5, 20.4, 19.8, 19.4, 21.7, 22.8, 18.8, 18.7, 18.5, 18.3, 21.2, 19.2, 20.4, 19.3, 22., 20.3, 20.5, 17.3, 18.8, 21.4, 15.7, 16.2, 18., 14.3, 19.2, 19.6,
```

```
23. , 18.4, 15.6, 18.1, 17.4, 17.1, 13.3, 17.8, 14. , 14.4, 13.4,
15.6, 11.8, 13.8, 15.6, 14.6, 17.8, 15.4, 21.5, 19.6, 15.3, 19.4,
17. , 15.6, 13.1, 41.3, 24.3, 23.3, 27. , 50. , 50. , 50. , 22.7,
25. , 50. , 23.8, 23.8, 22.3, 17.4, 19.1, 23.1, 23.6, 22.6, 29.4,
23.2, 24.6, 29.9, 37.2, 39.8, 36.2, 37.9, 32.5, 26.4, 29.6, 50.
32., 29.8, 34.9, 37., 30.5, 36.4, 31.1, 29.1, 50., 33.3, 30.3,
34.6, 34.9, 32.9, 24.1, 42.3, 48.5, 50., 22.6, 24.4, 22.5, 24.4,
20. , 21.7, 19.3, 22.4, 28.1, 23.7, 25. , 23.3, 28.7, 21.5, 23. ,
26.7, 21.7, 27.5, 30.1, 44.8, 50., 37.6, 31.6, 46.7, 31.5, 24.3,
31.7, 41.7, 48.3, 29. , 24. , 25.1, 31.5, 23.7, 23.3, 22. , 20.1,
22.2, 23.7, 17.6, 18.5, 24.3, 20.5, 24.5, 26.2, 24.4, 24.8, 29.6,
42.8, 21.9, 20.9, 44., 50., 36., 30.1, 33.8, 43.1, 48.8, 31.,
36.5, 22.8, 30.7, 50., 43.5, 20.7, 21.1, 25.2, 24.4, 35.2, 32.4,
32. , 33.2, 33.1, 29.1, 35.1, 45.4, 35.4, 46. , 50. , 32.2, 22. ,
20.1, 23.2, 22.3, 24.8, 28.5, 37.3, 27.9, 23.9, 21.7, 28.6, 27.1,
20.3, 22.5, 29., 24.8, 22., 26.4, 33.1, 36.1, 28.4, 33.4, 28.2,
22.8, 20.3, 16.1, 22.1, 19.4, 21.6, 23.8, 16.2, 17.8, 19.8, 23.1,
21. , 23.8, 23.1, 20.4, 18.5, 25. , 24.6, 23. , 22.2, 19.3, 22.6,
19.8, 17.1, 19.4, 22.2, 20.7, 21.1, 19.5, 18.5, 20.6, 19., 18.7,
32.7, 16.5, 23.9, 31.2, 17.5, 17.2, 23.1, 24.5, 26.6, 22.9, 24.1,
18.6, 30.1, 18.2, 20.6, 17.8, 21.7, 22.7, 22.6, 25., 19.9, 20.8,
16.8, 21.9, 27.5, 21.9, 23.1, 50., 50., 50., 50., 50., 13.8,
13.8, 15. , 13.9, 13.3, 13.1, 10.2, 10.4, 10.9, 11.3, 12.3,
7.2, 10.5, 7.4, 10.2, 11.5, 15.1, 23.2, 9.7, 13.8, 12.7, 13.1,
            5., 6.3, 5.6, 7.2, 12.1, 8.3, 8.5,
12.5, 8.5,
                                                      5., 11.9,
27.9, 17.2, 27.5, 15., 17.2, 17.9, 16.3,
                                          7.,
                                               7.2,
                                                     7.5, 10.4,
                                          8.3, 10.2, 10.9, 11.,
8.8, 8.4, 16.7, 14.2, 20.8, 13.4, 11.7,
9.5, 14.5, 14.1, 16.1, 14.3, 11.7, 13.4, 9.6, 8.7,
                                                      8.4, 12.8,
10.5, 17.1, 18.4, 15.4, 10.8, 11.8, 14.9, 12.6, 14.1, 13.,
15.2, 16.1, 17.8, 14.9, 14.1, 12.7, 13.5, 14.9, 20. , 16.4, 17.7,
19.5, 20.2, 21.4, 19.9, 19. , 19.1, 19.1, 20.1, 19.9, 19.6, 23.2,
29.8, 13.8, 13.3, 16.7, 12. , 14.6, 21.4, 23. , 23.7, 25. , 21.8,
20.6, 21.2, 19.1, 20.6, 15.2, 7., 8.1, 13.6, 20.1, 21.8, 24.5,
23.1, 19.7, 18.3, 21.2, 17.5, 16.8, 22.4, 20.6, 23.9, 22. , 11.9])
```

Batch Stochastic Gradient Descent - wykorzystujemy cały zbiór danych

```
Definicja błędu:
```

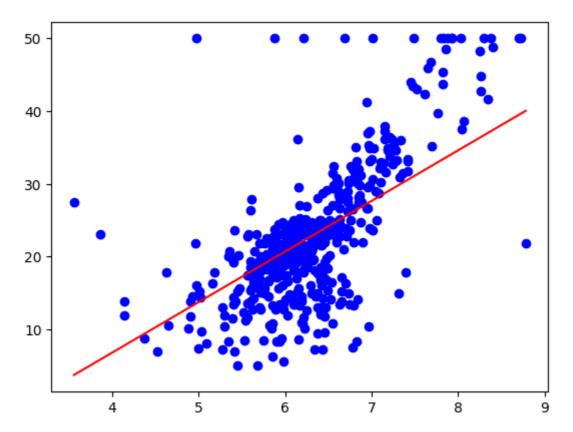
```
def loss_fn(real_y, pred_y):
    return tf.reduce_mean((real_y - pred_y)**2)
```

import random

```
20.11.2023, 12:40
    Loss = []
    epochs = 2000
    learning_rate = 0.02
    a = tf.Variable(random.random())
    b = tf.Variable(random.random())
    for _ in range(epochs):
      with tf.GradientTape() as tape:
        pred_y = a * real_x + b
        #print(pred_y)
        loss = loss_fn(real_y, pred_y)
        Loss.append(loss.numpy())
        grad_a, grad_b = tape.gradient(loss,(a, b))
      a.assign_sub(learning_rate*grad_a)
      b.assign_sub(learning_rate*grad_b)
    np.max(Loss),np.min(Loss)
         (318.53137, 45.89997)
    print(a.numpy())
    print(b.numpy())
         6.955526
         -21.015951
```

plt.scatter(np.arange(epochs),Loss)

plt.show()



Mini-batch Stochastic Gradient Descent - wykorzystujemy część zbióru danych

Definiujemy tablicę:

```
arr = np.arange(10)
arr

array([0, 1, 2, 3, 4, 5, 6, 7, 8, 9])
```

Mieszamy zawartość tablicy:

```
np.random.shuffle(arr)
arr
array([6, 8, 4, 0, 1, 2, 5, 7, 9, 3])
```

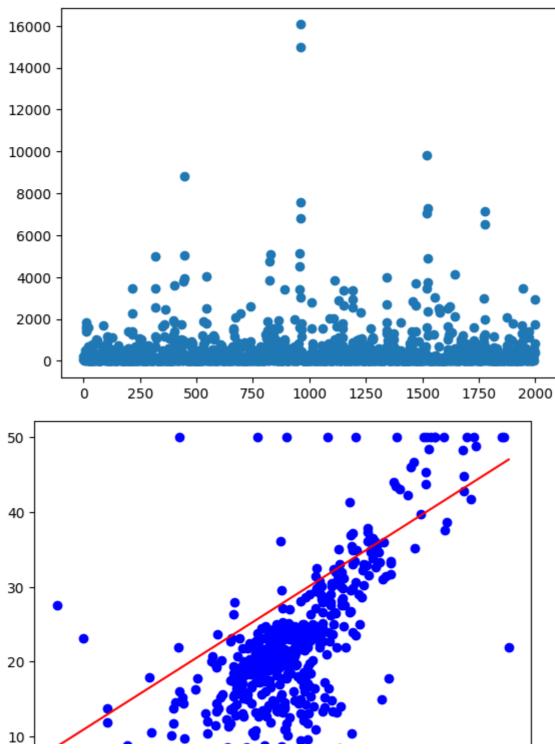
Funkcja do przetestowania:

```
def subset_dataset(x_dataset, y_dataset, subset_size):
    arr = np.arange(len(x_dataset))
    np.random.shuffle(arr)
    x_train = x_dataset[arr[0:subset_size]]
    y_train = y_dataset[arr[0:subset_size]]
    return x_train,y_train
```

Uzupełnik poniższy kod, tak aby możliwe było testowanie różnych wielkości próbki treningowwej.

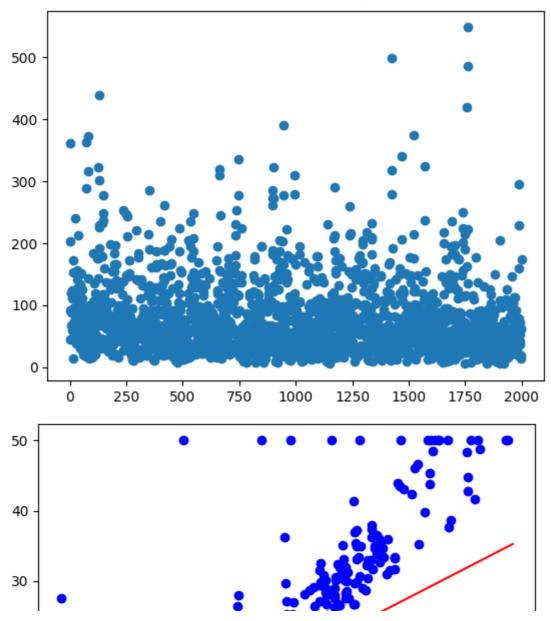
```
def mini_batch_stochastic_gradient_descent(batch_size):
  Loss = []
  epochs = 2000
  learning_rate = 0.02
  batch_size = batch_size
                              #wielkość zbioru wykorzystanego do treningu
  a = tf.Variable(random.random())
  b = tf.Variable(random.random())
  for i in range(epochs):
    real_x_batch, real_y_batch = subset_dataset(real_x,real_y,batch_size)
    with tf.GradientTape() as tape:
      pred_y = a * real_x_batch + b
      loss = loss_fn(real_y_batch, pred_y)
      Loss.append(loss.numpy())
    dloss_da, dloss_db = tape.gradient(loss,(a, b))
    a.assign sub(learning rate*dloss da) #a = a - alpha*dloss da
    b.assign sub(learning rate*dloss db) #b = b - alpha*dloss db
  print("last one loss", str(loss))
  plt.scatter(np.arange(epochs),Loss)
  plt.show()
  max = np.max(nox)
  min = np.min(nox)
  X = np.linspace(min, max, num=10)
  plt.plot(X,a.numpy()*X+b.numpy(),c='r')
  plt.scatter(nox,indus,c="b")
  plt.show()
mini_batch_stochastic_gradient_descent(1)
```

last one loss tf.Tensor(428.42133, shape=(), dtype=float32)



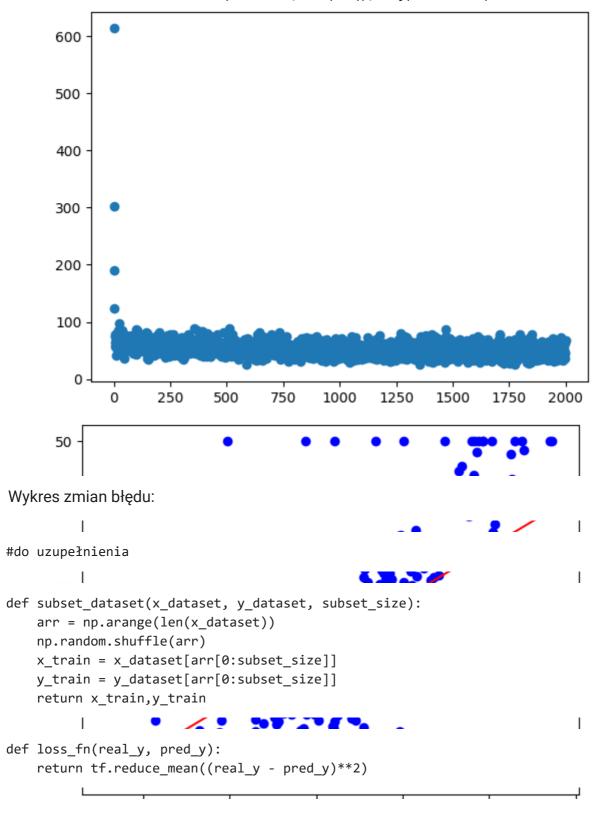
mini_batch_stochastic_gradient_descent(10)

last one loss tf.Tensor(173.78526, shape=(), dtype=float32)

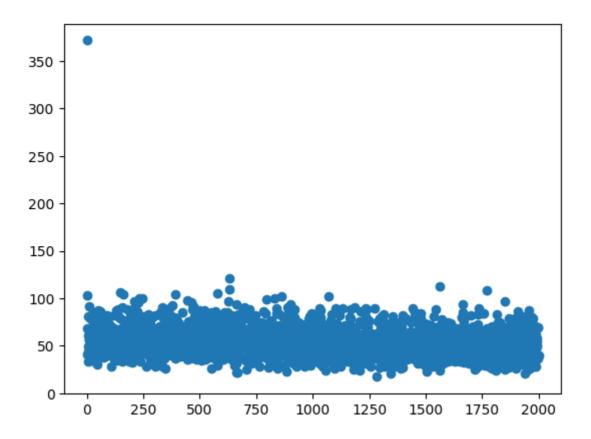


mini_batch_stochastic_gradient_descent(100)

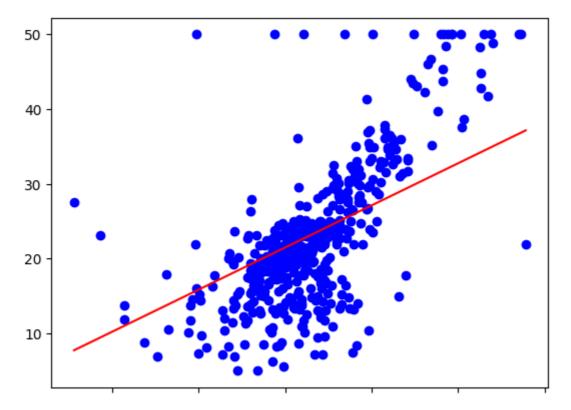
last one loss tf.Tensor(66.96526, shape=(), dtype=float32)



```
Loss = []
epochs = 2000
learning_rate = 0.01
batch_size = 50
a = tf.Variable(random.random())
b = tf.Variable(random.random())
for _ in range(epochs):
  real_nox_batch,real_medv_batch = subset_dataset(real_x,real_y,batch_size)
  with tf.GradientTape() as tape:
    pred_medv = a * real_nox_batch + b
    loss = loss_fn(real_medv_batch, pred_medv)
    Loss.append(loss.numpy())
  dloss_da, dloss_db = tape.gradient(loss,(a, b))
  a.assign_sub(learning_rate*dloss_da) #a = a - alpha*dloss_da
  b.assign_sub(learning_rate*dloss_db) #b = b - alpha*dloss_db
  plt.scatter(np.arange(epochs),Loss)
  plt.show()
```



```
max = np.max(nox)
min = np.min(nox)
X = np.linspace(min, max, num=10)
plt.plot(X,a.numpy()*X+b.numpy(),c='r')
plt.scatter(nox,indus,c="b")
plt.show()
```



Podsumowanie

Na uczenie modelu ma najwiekszy wpływ użycie batcha (bez batcha jest podawany cały zbiór uczący), małe batche mogą przyspieszyć proces uczenia, ponieważ aktualizacje wag modelu są wykonywane częściej. Dzięki temu wprowadza to pewną losowość w procesie uczenia, pomoga uniknąć utknięcia w minimach lokalnych. Model uczony z minibatchem osiąga lepsze rezultaty jeżeli chodzi o wyniki uczenia(lepiej znaleziona prosta) oraz mniejszy błąd. Model lepiej i szybciej się uczy gdy mini-batch jest większy niż gdy jest on mniejszy. Ponadto na proces uczenia modelu ma wpływ ilość epok. Za mała ilość epok skutkuje niedouczeniem modelu (model nie nauczył się wystarczająco dobrze dostosowywać się do danych treningowych), zaś gdy ilość epok jest zbyt duża następuje przeuczenie modelu (model nieuogulnia zgromadzonej wiedzy tylko "uczy się na pamięć" zbioru treningowego co sprawia, że jest nieskuteczny lub mało skuteczny dla nowych danych). Ostatnim sprawdzonym przeze mnie parametrem jest współczynnik uczenia. Jego zbyt duża wartość rowadzi do skakania wokół minimum globalnego przy czym model go nie osiągnie. W przypadku zastosowania zbyt małej wartości współczynnika uczenia proces uczenia jest bardzo wolny, a model "utyka" w minimach lokalnych.

Nie można połączyć się z usługą reCAPTCHA. Sprawdź połączenie z internetem i załaduj ponownie zadanie reCAPTCHA.