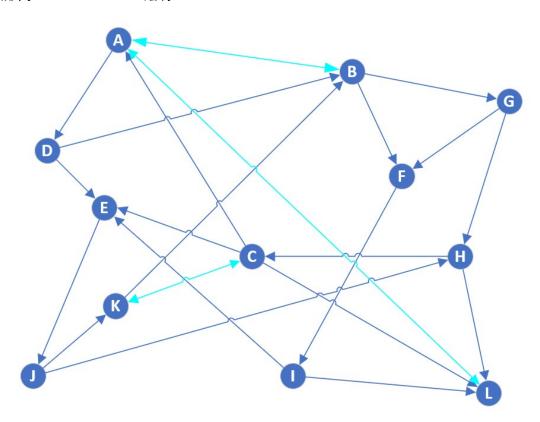
# 张宇杰 2022113573

以下程序均以该图作为输入: 蓝色为单向边, 浅蓝色为双向边

图形用 Visio Professional 绘制



# 输入序列如下:

可见于文件./my-graph/graph\_1.txt

ן טע ניי	X H./my-graph/graph_r.kt
1.	+v A
2.	+v B
3.	+v C
4.	+v D
5.	+v E
6.	+v F
7.	+v G
8.	+v H
9.	+v I
10.	+v Ј
11.	+v K
12.	+v L
13.	
14.	+e A D 1
15.	+e C A 1
16.	+e A L 1
17.	+e L A 1
18.	+e A B 1
19.	+e B A 1

```
20.
21. +e D B 1
22. +e K B 1
23. +e B F 1
24. +e B G 1
25.
26. +e C E 1
27. +e C K 1
28. +e K C 1
29. +e H C 1
30. +e C L 1
31.
32. +e D E 1
33.
34. +e E J 1
35. +e I E 1
36.
37. +e F I 1
38. +e G F 1
39.
40. +e G H 1
41.
42. +e H L 1
43. +e J H 1
44.
45. +e J K 1
46.
47. +e I L 1
```

一、分别实现无向图(或有向图)的邻接矩阵和邻接表存储结构的建立算法,分析和比较其建立算法的时间复杂度以及存储结构的空间占用情况

五、以适当的方式输入图的顶点和边,并显示相应的结果。要求顶点不少于 10 个,边不少于 13 条 (图的规模越大越好)

# 有向图,邻接矩阵

```
    #include <iostream>
    #include <fstream>
    #include ".\src\MyGraph"
    using namespace MyGraph;
    using namespace std;
```

```
8.
     int main()
9.
10.
          system("chcp 65001");
          ifstream command("./graph_1.txt");
11.
12.
13.
          AdjacencyMatrixGraph G1;
14.
          G1.commandSequence(command);
          G1.showMatrix();
15.
16.
17.
          cout << endl;</pre>
18.
     }
```

# 运行结果:

```
Active code page:
                                                          F
inf
          inf
                             inf
                                                          1
inf
                                                                    1
inf
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                             inf
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                   inf
(base) PS D:\File\大二秋\DSA\作业4\my-graph> |
```

#### 分析:

时间复杂度:每加一次边,对邻接矩阵进行一次修改,修改是O(1)的,故为O(E)

空间占用:显然为 $O(V^2)$ 

# 有向图,邻接表

```
#include <iostream>
2.
      #include <fstream>
3.
      #include ".\src\MyGraph"
5.
      using namespace MyGraph;
6.
      using namespace std;
7.
8.
      int main()
9.
          system("chcp 65001");
10.
          ifstream command("./graph_1.txt");
11.
12.
13.
          AdjacencyListGraph G1;
14.
          G1.commandSequence(command);
15.
          G1.showList();
16.
```

```
17. cout << endl;
18. }
运行结果:
```

```
(base) PS D:\File\大二秋\DSA\作业4\my-graph> .\test.exe
Active code page: 65001
A -> [D|1] -> [L|1] -> [B|1] -> end
B -> [A|1] -> [F|1] -> [G|1] -> end
C -> [A|1] -> [E|1] -> [K|1] -> [L|1] -> end
D -> [B|1] -> [E|1] -> end
E -> [J|1] -> end
F -> [I|1] -> end
G -> [F|1] -> [H|1] -> end
H -> [C|1] -> [L|1] -> end
I -> [E|1] -> [L|1] -> end
C -> [B|1] -> [C|1] -> end
C -> [B|1] -> [C|1] -> end
C -> [B|1] -> [C|1] -> end
```

分析:

时间复杂度:每加一次边,向对应邻接表插入一条边,而 vector 尾插的均摊时间复杂度为

O(1), 故整体时间复杂度为 O(E)

空间占用:显然为 O(V+E)

二、实现无向图(或有向图)的邻接矩阵和邻接表两种存储结构的相互转换算法

### 邻接矩阵转邻接表

```
1.
    #include <iostream>
      #include <fstream>
2.
3.
      #include ".\src\MyGraph"
using namespace MyGraph;
      using namespace std;
6.
7.
8.
      int main()
9.
10.
          system("chcp 65001");
          ifstream command("./graph_1.txt");
11.
12.
13.
          AdjacencyMatrixGraph G1;
          G1.commandSequence(command);
14.
          G1.showMatrix();
15.
```

```
16.    cout << endl;
17.
18.    AdjacencyListGraph G2 = matrixToList(G1);
19.    G2.showList();
20.    cout << endl;
21. }</pre>
```

# 运行结果:

```
(base) PS D:\File\大二秋\DSA\作业4\my-graph> .\test.exe
Active code page: 65001
A B C D E F
                                                                                                                         I
inf
                                                                                                                                       J
inf
                                                                                                                                                    K
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inf
                                                                                 inf
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                       [D|1] -> [L|1
[F|1] -> [G|1
[E|1] -> [K|1
[E|1] -> end
                                 -> [L|1]
-> [G|1]
-> [K|1]
       [B|1]
[A|1]
[A|1]
[B|1]
[J|1]
[F|1]
[C|1]
[E|1]
[H|1]
[B|1]
                                                -> end
-> [L|1] -> end
                 -> [E|1] -> end
-> end
-> end
-> [L|1] -> end
-> [L|1] -> end
-> [K|1] -> end
-> [C|1] -> end
-> end
(base) PS D:\File\大二秋\DSA\作业4\my-graph>|
```

结果正确

分析: 时间复杂度为 O(V2)

# 邻接表转邻接矩阵

```
#include <iostream>
      #include <fstream>
2.
3.
4.
      #include ".\src\MyGraph"
5.
      using namespace MyGraph;
6.
      using namespace std;
7.
8.
      int main()
9.
          system("chcp 65001");
10.
11.
          ifstream command("./graph_1.txt");
12.
13.
          AdjacencyListGraph G1;
14.
          G1.commandSequence(command);
```

```
15.    G1.showList();
16.    cout << endl;
17.
18.    AdjacencyMatrixGraph G2 = listToMatrix(G1);
19.    G2.showMatrix();
20.    cout << endl;
21. }</pre>
```

# 运行结果:

```
\DSA\作业4\my-graph> .\test.exe
                  page: 65001
-> [L|1] -> [B|1] -> end
-> [F|1] -> [G|1] -> end
-> [E|1] -> [K|1] -> [L|1] -> end
-> [E|1] -> end
       [D|1]
[A|1]
[A|1]
[B|1]
[J|1]
                 ->
                     end
       [J|1]
[F|1]
[C|1]
[E|1]
[H|1]
[B|1]
                     end
[H|1] -> end
[L|1] -> end
[L|1] -> end
[K|1] -> end
[C|1] -> end
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(base) PS D:\File\大二秋\DSA\作业4\my-graph>
```

结果正确

分析:时间复杂度为O(V+E)

三、在上述两种存储结构上,分别实现无向图(或有向图)的深度优先搜索(递归和非递归)和广度优先搜索算法。并以适当的方式存储和展示相应的搜索结果,包括:深度优先或广度优先生成森林(或生成树)、深度优先或广度优先序列和深度优先或广度优先编号。并分析搜索算法的时间复杂度和空间复杂度。

P.S. 在本次程序设计中,邻接表存储的图 AdjacencyListGraph 与邻接矩阵存储的图 AdjacencyMatrixGraph 均共用了父类 Graph 的各种搜索方法

故以下的程序以及运行结果中,仅展示对邻接表存储的图 AdjacencyListGraph 的搜索结果(因为两种存储结构的代码一致,结果也一致)

仅在分析复杂度时讨论二者的不同

### 深度优先搜索 (递归)

运行程序:

```
1. #include <iostream>
```

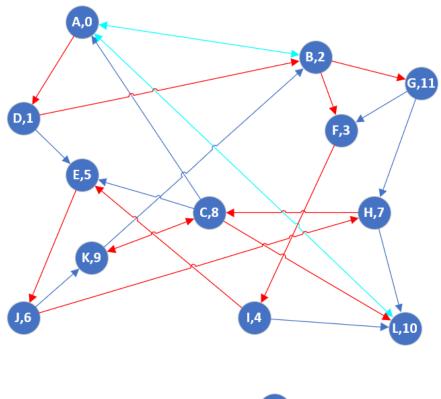
2. #include <fstream>

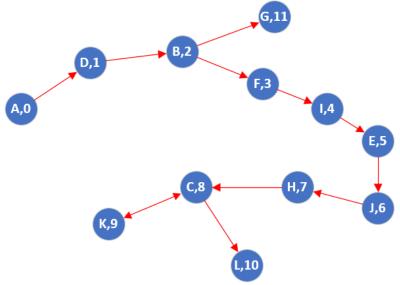
```
3.
      #include ".\src\MyGraph"
4.
5.
      using namespace MyGraph;
      using namespace std;
6.
7.
8.
      int main()
9.
10.
           system("chcp 65001");
           ifstream command("./graph_1.txt");
11.
12.
13.
           AdjacencyListGraph G1;
14.
           G1.commandSequence(command);
15.
           G1.showList();
           cout << endl;</pre>
16.
17.
18.
           G1.dfs();
           cout << endl;</pre>
19.
20.
      }
```

### 输出结果:

```
(base) PS D:\File\大二秋\DSA\作业4\my-graph> .\test.exe
Active code page: 65001
A -> [D|1] -> [L|1] -> [B|1] -> end
B -> [A|1] -> [F|1] -> [G|1] -> end
C -> [A|1] -> [E|1] -> [K|1] -> end
D -> [B|1] -> [E|1] -> end
E -> [J|1] -> end
F -> [J|1] -> end
G -> [F|1] -> [L|1] -> end
H -> [C|1] -> [L|1] -> end
J -> [L|1] -> end
K -> [B|1] -> [C|1] -> end
C -> [A|1] -> end
D -> [B|1] -> [L|1] -> end
D -> [B|1] -> [B|1] -> [L|1] -> end
D -> [B|1] -> [B|
```

转换为图形:





# 分析:

*时间复杂度*:分为两个部分:访问每个节点花费的时间,以及在每个节点找邻居花费的时间 **对邻接矩阵**:

- 1: V 个节点需要 O(V)
- 2: 对邻接矩阵,对于节点 i,需要扫描第 i 行的每一个元素才能找到所有的邻居,需要 O(V) 故总复杂度  $O(V^2)$

# 对邻接表:

- 1: n 个节点需要 O(V)
- 2: 对邻接表,总共的找邻居时间复杂度就是遍历边表的时间复杂度。对于有向图: O(V) 故总复杂度 O(V+E)

#### 空间复杂度:

无论是邻接矩阵还是邻接表, 递归工作栈的最大深度为 V, 故空间复杂度为 O(V)

# 深度优先搜索(非递归)

### 运行程序:

```
#include <iostream>
2.
      #include <fstream>
3.
      #include ".\src\MyGraph"
4.
5.
      using namespace MyGraph;
6.
      using namespace std;
7.
8.
      int main()
9.
10.
           system("chcp 65001");
11.
           ifstream command("./graph_1.txt");
12.
           AdjacencyListGraph G1;
13.
14.
           G1.commandSequence(command);
15.
           G1.showList();
16.
           cout << endl;</pre>
17.
18.
           G1.dfs_no_rec();
19.
           cout << endl;</pre>
20.
      }
```

### 运行结果:

与递归实现的 dfs 一致

分析: 复杂度同递归实现的 dfs

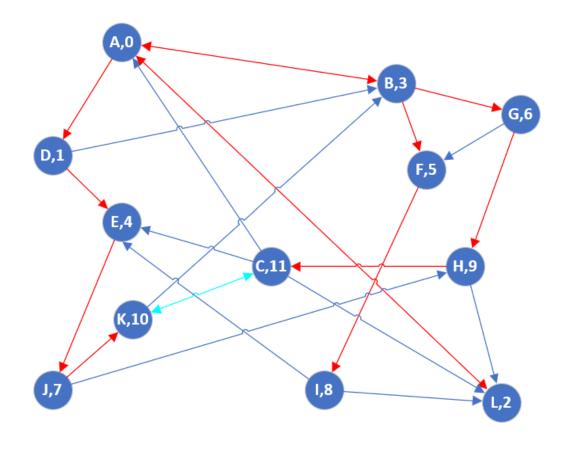
### 广度优先搜索

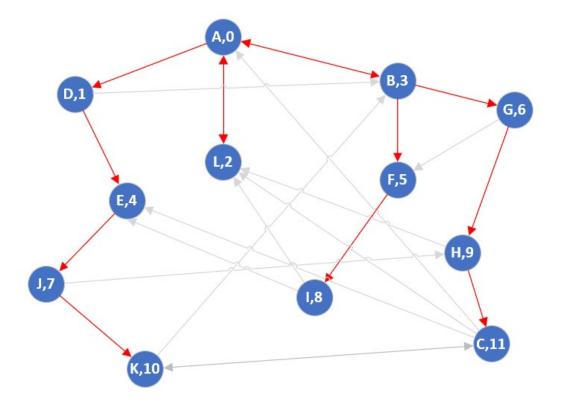
### 运行程序:

```
#include <iostream>
 2.
      #include <fstream>
 3.
      #include ".\src\MyGraph"
 4.
 5.
      using namespace MyGraph;
      using namespace std;
 6.
 7.
      int main()
 8.
 9.
           system("chcp 65001");
 10.
 11.
           ifstream command("./graph_1.txt");
 12.
 13.
           AdjacencyListGraph G1;
 14.
           G1.commandSequence(command);
 15.
           G1.showList();
 16.
           cout << endl;</pre>
 17.
 18.
           G1.bfs();
 19.
          cout << endl;</pre>
 20. }
运行结果:
```

```
(base) PS D:\File\大二秋\DSA\作业4\my-graph> .\test.exe
Active code page: 65001
A -> [D|1] -> [L|1] -> [B|1] -> end
B -> [A|1] -> [F|1] -> [G|1] -> end
C -> [A|1] -> [E|1] -> [K|1] -> [L|1] -> end
D -> [B|1] -> [E|1] -> end
E -> [J|1] -> end
F -> [J|1] -> end
G -> [F|1] -> [H|1] -> end
H -> [C|1] -> [L|1] -> end
I -> [E|1] -> [L|1] -> end
I -> [B|1] -> [C|1] -> end
L -> [B|1] -> [C|1] -> end
C -> [A|1] -> end
 Ε
                                                                                                                                                                                                                                                            K
10
J
                                                                                                                                                                 6
B
 父节点: null
                                                                                                                   D
                                             Α
                                                                                            Α
 (base) PS D:\File\大二秋\DSA\作业4\my-graph> |
```

转换为图形:





分析:

*时间复杂度*:两部分:访问每个节点花费的时间,在每个节点找邻居花费的时间 **对邻接矩阵:** 

- 1: V 个节点需要 O(V);
- 2: 由于是邻接矩阵,对于节点 i,需要扫描第 i 行的每一个元素,需要 O(V);总复杂度 O(V^2)

### 对邻接表:

- 1: n 个节点需要 O(V)
- 2: 对邻接表,总共的找邻居时间复杂度就是遍历边表的时间复杂度。对于有向图: O(V) 故总复杂度 O(V+E)

# 空间复杂度:

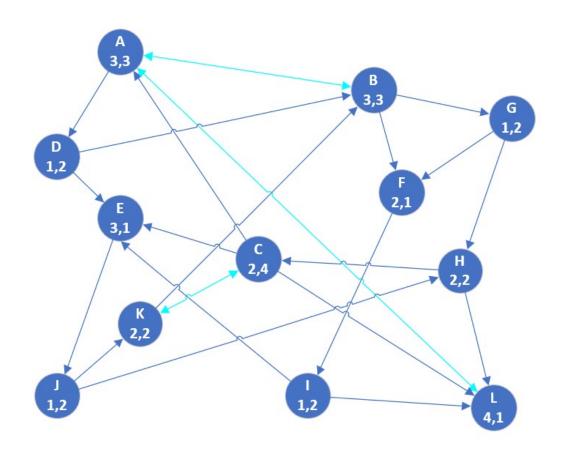
无论是邻接矩阵还是邻接表,工作队列的最大长度为 V, 故空间复杂度为 O(V)

四、(2) 对于有向图,采用"邻接表"存储结构,设计和实现计算每个顶点入度、出度和度的算法,并分析其时间复杂度

```
1. #include <iostream>
2.
      #include <fstream>
3.
      #include ".\src\MyGraph"
      using namespace MyGraph;
      using namespace std;
6.
7.
8.
      int main()
9.
          system("chcp 65001");
10.
11.
          ifstream command("./graph_1.txt");
12.
          AdjacencyListGraph G1;
13.
14.
          G1.commandSequence(command);
15.
          G1.showList();
16.
          cout << endl;</pre>
17.
18.
          G1.showDegree();
19.
          cout << endl;</pre>
20.
     }
运行结果:
```

```
(base) PS D:\File\大二秋\DSA\作业4\my-graph> .\test.exe
Active code page: 65001
A -> [D|1] -> [L|1] -> [B|1] -> end
B -> [A|1] -> [F|1] -> [G|1] -> end
C -> [A|1] -> [E|1] -> [K|1] -> end
D -> [B|1] -> [E|1] -> end
E -> [J|1] -> end
F -> [J|1] -> end
G -> [F|1] -> [H|1] -> end
H -> [C|1] -> [L|1] -> end
I -> [E|1] -> [L|1] -> end
K -> [B|1] -> [C|1] -> end
K -> [B|1] -> [C|1] -> end
U -> [A|1] -> end
C -> [A|1] -> end
```

### 绘制在图上:



### 分析:

# 时间复杂度:

要想知道一个节点的入度与出度,对于邻接表来说,必须遍历整个边表才能得知一个节点的入度与出度。时间复杂度为 O(E)

当然, 求解所有节点的入度与出度的时间复杂度也是 O(E), 需要占用空间 O(V)