

Computer Systems: Network Programming (Sockets)

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Based on slides by Randal E. Bryant and David R. O'Halloran

A Programmer's View of the Internet

1. Hosts are mapped to a set of 32-bit *IP addresses*

- 128.2.203.179

2. The set of IP addresses is mapped to a set of identifiers called Internet *domain names*

- 128.2.217.3 is mapped to www.cs.cmu.edu

3. A process on one Internet host can communicate with a process on another Internet host over a *connection*

Global IP Internet (upper case)

- **Most famous example of an internet**
- **Based on the TCP/IP protocol family**
 - IP (Internet Protocol) :
 - Provides *basic naming scheme* and unreliable *delivery capability* of packets (datagrams) from *host-to-host*
 - UDP (Unreliable Datagram Protocol)
 - Uses IP to provide *unreliable* datagram delivery from *process-to-process*
 - TCP (Transmission Control Protocol)
 - Uses IP to provide *reliable* byte streams from *process-to-process* over *connections*
- **Accessed via a mix of Unix file I/O and functions from the *sockets interface***

IP Addresses

- **32-bit IP addresses are stored in an *IP address struct***
 - IP addresses are always stored in memory in *network byte order* (big-endian byte order)
 - True in general for any integer transferred in a packet header from one machine to another.
 - E.g., the port number used to identify an Internet connection.

```
/* Internet address structure */
struct in_addr {
    uint32_t    s_addr; /* network byte order (big-endian) */
};
```

Dotted Decimal Notation

- By convention, each byte in a 32-bit IP address is represented by its decimal value and separated by a period
 - IP address: `0x8002C2F2` = `128.2.194.242`
- Use `inet_ntop`, `inet_pton` functions for converting between dotted decimal notation and IP addresses
 - Use `htonl`, `htons`, `ntohl` and `ntohs` functions for network byte order conversions
- Use `getaddrinfo` and `getnameinfo` functions (described later) to convert between IP addresses and dotted decimal format.

(3) Internet Connections

- **Clients and servers communicate by sending streams of bytes over *connections*. Each connection is:**
 - *Point-to-point*: connects a pair of processes.
 - *Full-duplex*: data can flow in both directions at the same time,
 - *Reliable*: stream of bytes sent by the source is eventually received by the destination in the same order it was sent.
- **A *socket* is an endpoint of a connection**
 - *Socket address* is an `IPAddress:port` pair
- **A *port* is a 16-bit integer that identifies a process:**
 - ***Ephemeral port***: Assigned automatically by client kernel when client makes a connection request.
 - ***Well-known port***: Associated with some *service* provided by a server (e.g., port 80 is associated with Web servers)

Sockets

■ What is a socket?

- To the kernel, a socket is an endpoint of communication
- To an application, a socket is a file descriptor that lets the application read/write from/to the network
 - **Remember:** All Unix I/O devices, including networks, are modeled as files

■ Clients and servers communicate with each other by reading from and writing to socket descriptors



■ The main distinction between regular file I/O and socket I/O is how the application “opens” the socket descriptors

Socket Address Structures

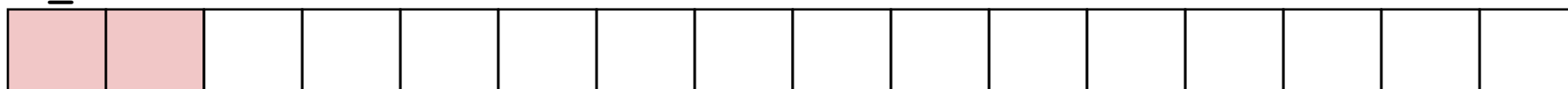
■ Generic socket address:

- For address arguments to `connect`, `bind`, and `accept`
- Necessary only because C did not have generic (`void *`) pointers when the sockets interface was designed
- For casting convenience, we adopt the Stevens convention:

```
typedef struct sockaddr SA;
```

```
struct sockaddr {  
    uint16_t  sa_family;    /* Protocol family */  
    char      sa_data[14];  /* Address data.  */  
};
```

`sa_family`



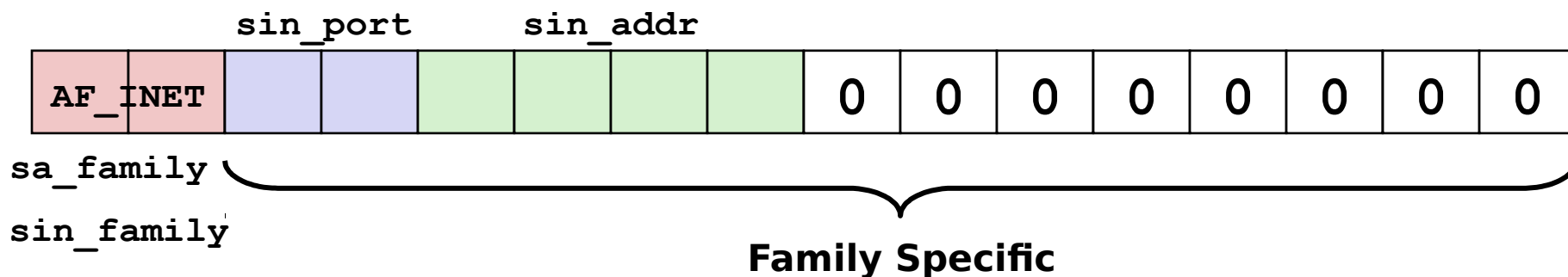
Family Specific

Socket Address Structures

■ Internet (IPv4) specific socket address:

- Must cast (`struct sockaddr_in *`) to (`struct sockaddr *`) for functions that take socket address arguments.

```
struct sockaddr_in {
    uint16_t      sin_family; /* Protocol family (always AF_INET) */
    uint16_t      sin_port;   /* Port num in network byte order */
    struct in_addr sin_addr;   /* IP addr in network byte order */
    unsigned char sin_zero[8]; /* Pad to sizeof(struct sockaddr) */
};
```



Host and Service Conversion: `getaddrinfo`

- **`getaddrinfo` is the modern way to convert string representations of hostnames, host addresses, ports, and service names to socket address structures.**
 - Replaces obsolete `gethostbyname` and `getservbyname` funcs.
- **Advantages:**
 - Reentrant (can be safely used by threaded programs).
 - Allows us to write portable protocol-independent code
 - Works with both IPv4 and IPv6
- **Disadvantages**
 - Somewhat complex
 - Fortunately, a small number of usage patterns suffice in most cases.

Host and Service Conversion: getaddrinfo

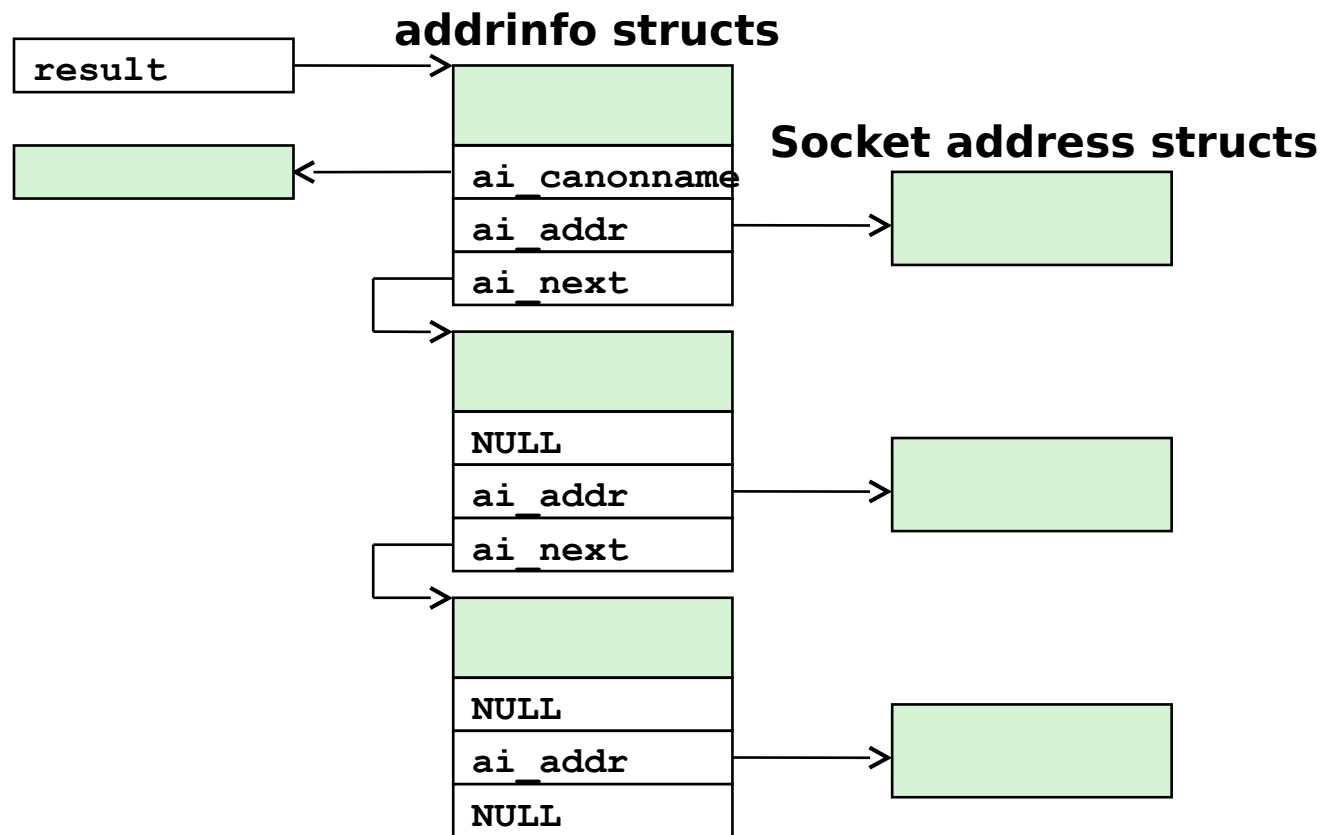
```
int getaddrinfo(const char *host,          /* Hostname or address */
               const char *service,       /* Port or service name */
               const struct addrinfo *hints, /* Input parameters */
               struct addrinfo **result);  /* Output linked list */

void freeaddrinfo(struct addrinfo *result); /* Free linked list */

const char *gai_strerror(int errcode);     /* Return error msg */
```

- **Given host and service, getaddrinfo returns result that points to a linked list of `addrinfo` structs, each of which points to a corresponding socket address struct, and which contains arguments for the sockets interface functions.**
- **Helper functions:**
 - `freeaddrinfo` frees the entire linked list.
 - `gai_strerror` converts error code to an error message.

Linked List Returned by getaddrinfo



- **Clients:** walk this list, trying each socket address in turn, until the calls to `socket` and `connect` succeed.
- **Servers:** walk the list until calls to `socket` and `bind` succeed.

addrinfo Struct

```
struct addrinfo {  
    int          ai_flags;      /* Hints argument flags */  
    int          ai_family;     /* First arg to socket function */  
    int          ai_socktype;   /* Second arg to socket function */  
    int          ai_protocol;   /* Third arg to socket function */  
    char         *ai_canonname; /* Canonical host name */  
    size_t       ai_addrlen;    /* Size of ai_addr struct */  
    struct sockaddr *ai_addr;    /* Ptr to socket address structure */  
    struct addrinfo *ai_next;    /* Ptr to next item in linked list */  
};
```

- Each **addrinfo** struct returned by **getaddrinfo** contains arguments that can be passed directly to **socket** function.
- Also points to a **socket address struct** that can be passed directly to **connect** and **bind** functions.

Host and Service Conversion: getnameinfo

- **getnameinfo is the inverse of getaddrinfo, converting a socket address to the corresponding host and service.**
 - Replaces obsolete `gethostbyaddr` and `getservbyport` funcs.
 - Reentrant and protocol independent.

```
int getnameinfo(const SA *sa, socklen_t salen, /* In: socket addr */
                char *host, size_t hostlen, /* Out: host */
                char *serv, size_t servlen, /* Out: service */
                int flags); /* optional flags */
```

Conversion Example

```
#include "csapp.h"

int main(int argc, char **argv)
{
    struct addrinfo *p, *listp, hints;
    char buf[MAXLINE];
    int rc, flags;

    /* Get a list of addrinfo records */
    memset(&hints, 0, sizeof(struct addrinfo));
    hints.ai_family = AF_INET;          /* IPv4 only */
    hints.ai_socktype = SOCK_STREAM; /* Connections only */
    if ((rc = getaddrinfo(argv[1], NULL, &hints, &listp)) != 0) {
        fprintf(stderr, "getaddrinfo error: %s\n", gai_strerror(rc));
        exit(1);
    }
}
```

hostinfo.c

Conversion Example (cont)

```
/* Walk the list and display each IP address */
flags = NI_NUMERICHOST; /* Display address instead of name */
for (p = listp; p; p = p->ai_next) {
    Getnameinfo(p->ai_addr, p->ai_addrlen,
                buf, MAXLINE, NULL, 0, flags);
    printf("%s\n", buf);
}

/* Clean up */
Freeaddrinfo(listp);

exit(0);
}
```

hostinfo.c

Do-it-yourself Recap: System-level I/O

- **What is the difference between the Unix I/O and the book's robust I/O APIs?**
- **When can short counts be returned by I/O functions? Why?**
- **What did each of the following functions do?**
 - `ssize_t rio_writen(int fd, void *usrbuf, size_t n);`
 - `ssize_t rio_readlineb(rio_t *rp, void *usrbuf, size_t maxlen);`
 - `ssize_t rio_readnb(rio_t *rp, void *usrbuf, size_t n);`

Socket Programming Example

■ Echo server and client

■ Server

- Accepts connection request
- Repeats back lines as they are typed

■ Client

- Requests connection to server
- Repeatedly:
 - Read line from terminal
 - Send to server
 - Read reply from server
 - Print line to terminal

Client**2. Start client**`open_clientfd`**1. Start server**`open_listenfd`**Server****Echo Server + Client Structure****Connection request**`accept`**Await connection request from client****Client / Server Session**`terminal read
socket write``socket read``socket read
terminal write``socket write`**3. Exchange data**`close`**EOF**`socket read`**4. Disconnect client**`close`**5. Drop client**

Client**2. Start client**`open_clientfd`**1. Start server**`open_listenfd`**Server****Echo Server + Client Structure****Connection request**`accept`**Await connection request from client****Client / Server Session**`fgets``rio_writen``rio_readlineb``rio_readlineb``fputs``rio_writen`**Exchange data**`close`**4. Disconnect client****EOF**`rio_readlineb``close`**5. Drop client**

Echo Client: Main Routine

```
#include "csapp.h"

int main(int argc, char **argv)
{
    int clientfd;
    char *host, *port, buf[MAXLINE];
    rio_t rio;

    host = argv[1];
    port = argv[2];

    clientfd = Open_clientfd(host, port);
    Rio_readinitb(&rio, clientfd);

    while (Fgets(buf, MAXLINE, stdin) != NULL) {
        Rio_writen(clientfd, buf, strlen(buf));
        Rio_readlineb(&rio, buf, MAXLINE);
        Fputs(buf, stdout);
    }
    Close(clientfd);
    exit(0);
}
```

echoclient.c

Iterative Echo Server: Main Routine

```
#include "csapp.h"
void echo(int connfd);

int main(int argc, char **argv)
{
    int listenfd, connfd;
    socklen_t clientlen;
    struct sockaddr_storage clientaddr; /* Enough room for any addr */

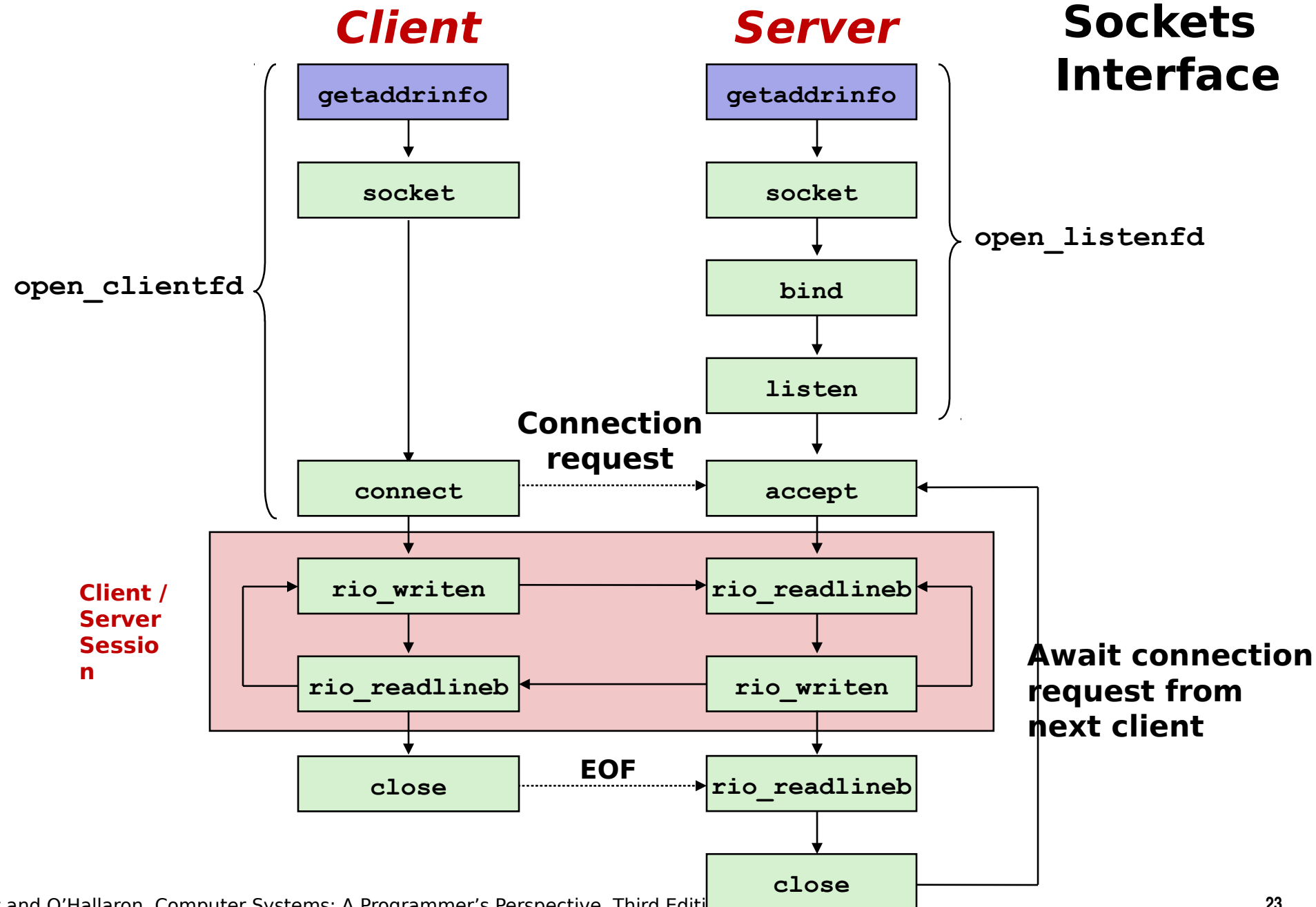
    char client_hostname[MAXLINE], client_port[MAXLINE];

    listenfd = Open_listenfd(argv[1]);
    while (1) {
        clientlen = sizeof(struct sockaddr_storage); /* Important! */
        connfd = Accept(listenfd, (SA *)&clientaddr, &clientlen);
        Getnameinfo((SA *)&clientaddr, clientlen,
                    client_hostname, MAXLINE, client_port, MAXLINE, 0);
        printf("Connected to (%s, %s)\n", client_hostname, client_port);
        echo(connfd);
        Close(connfd);
    }
    exit(0);
}
```

a }

echoserveri.c

Sockets Interface



Sockets Interface: `socket`

- Clients and servers use the `socket` function to create a *socket descriptor*:

```
int socket(int domain, int type, int protocol)
```

- Example:

```
int clientfd = socket(AF_INET, SOCK_STREAM, 0);
```



Indicates that we
are using 32-bit
IPV4 addresses



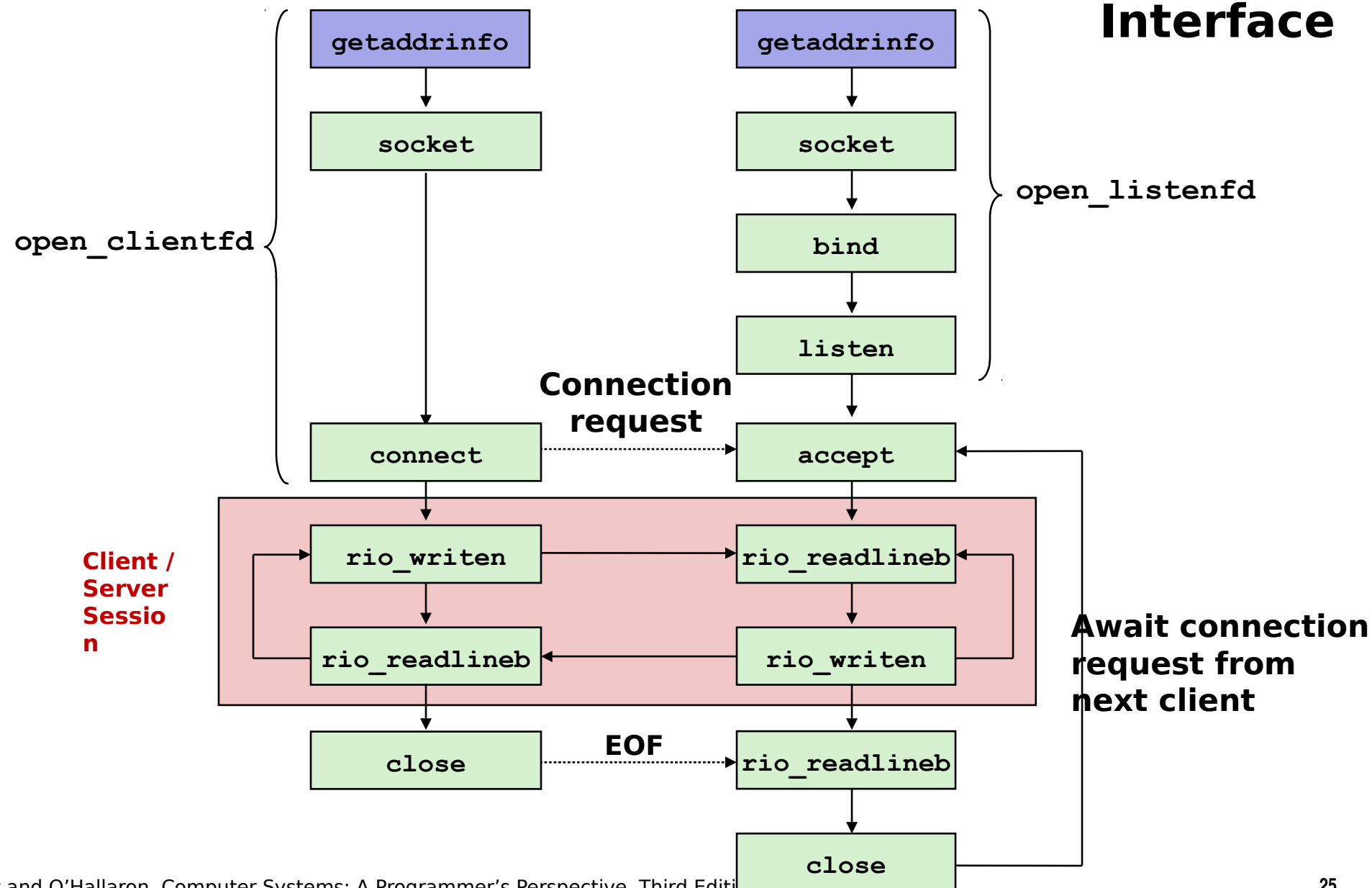
Indicates that the
socket will be the
end point of a
connection

Protocol specific! Best practice is to use `getaddrinfo` to generate the parameters automatically, so that code is protocol independent.

Sockets Interface

Client

Server



Sockets Interface: bind

- A server uses `bind` to ask the kernel to associate the server's socket address with a socket descriptor:

```
int bind(int sockfd, SA *addr, socklen_t addrlen);
```

Recall: `typedef struct sockaddr SA;`

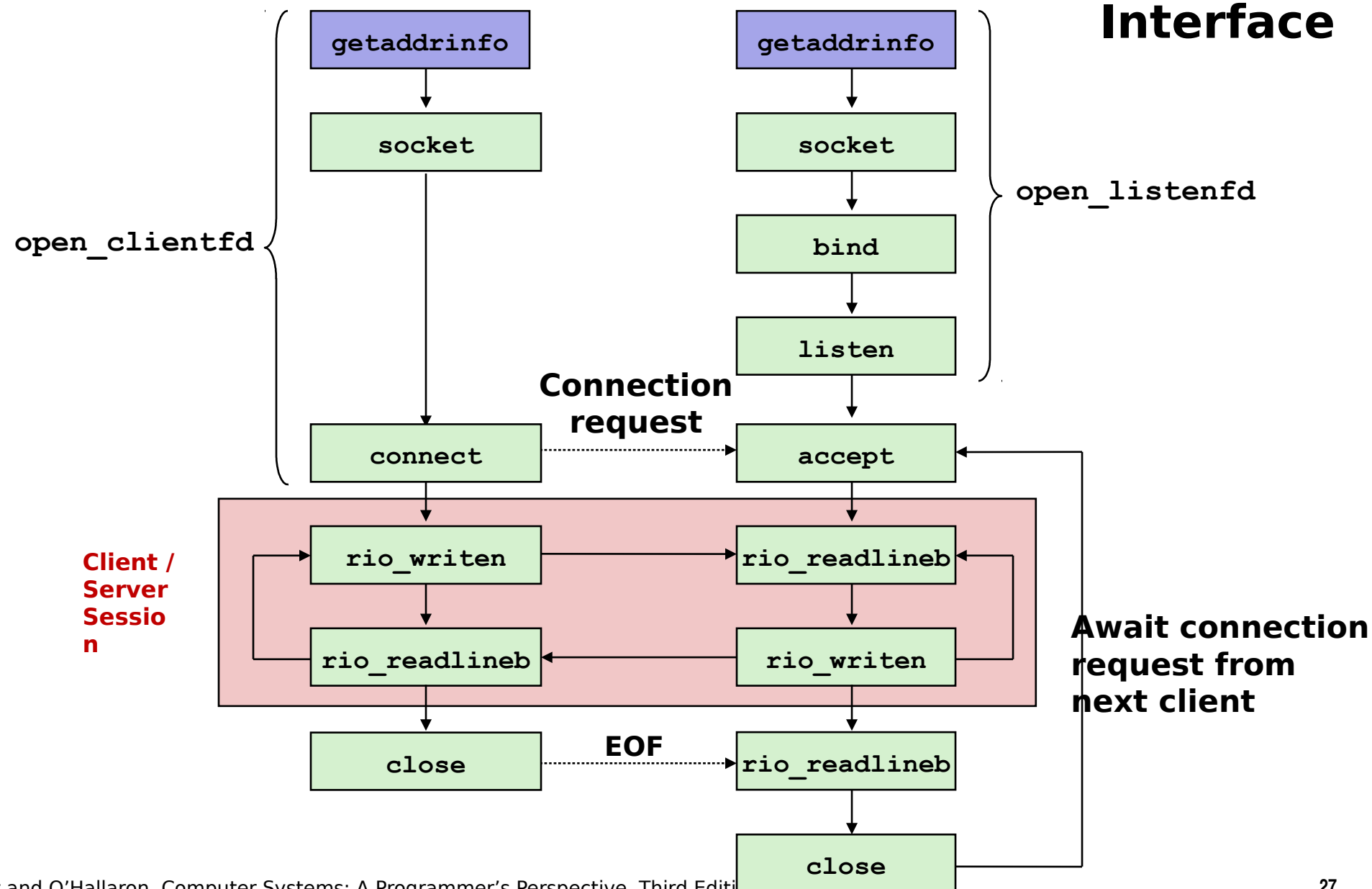
- Process can read bytes that arrive on the connection whose endpoint is `addr` by reading from descriptor `sockfd`
- Similarly, writes to `sockfd` are transferred along connection whose endpoint is `addr`

Best practice is to use `getaddrinfo` to supply the arguments `addr` and `addrlen`.

Sockets Interface

Client

Server



Sockets Interface: `listen`

- By default, kernel assumes that descriptor from `socket` function is an **active socket** that will be on the client end of a connection.
- A server calls the `listen` function to tell the kernel that a descriptor will be used by a server rather than a client:

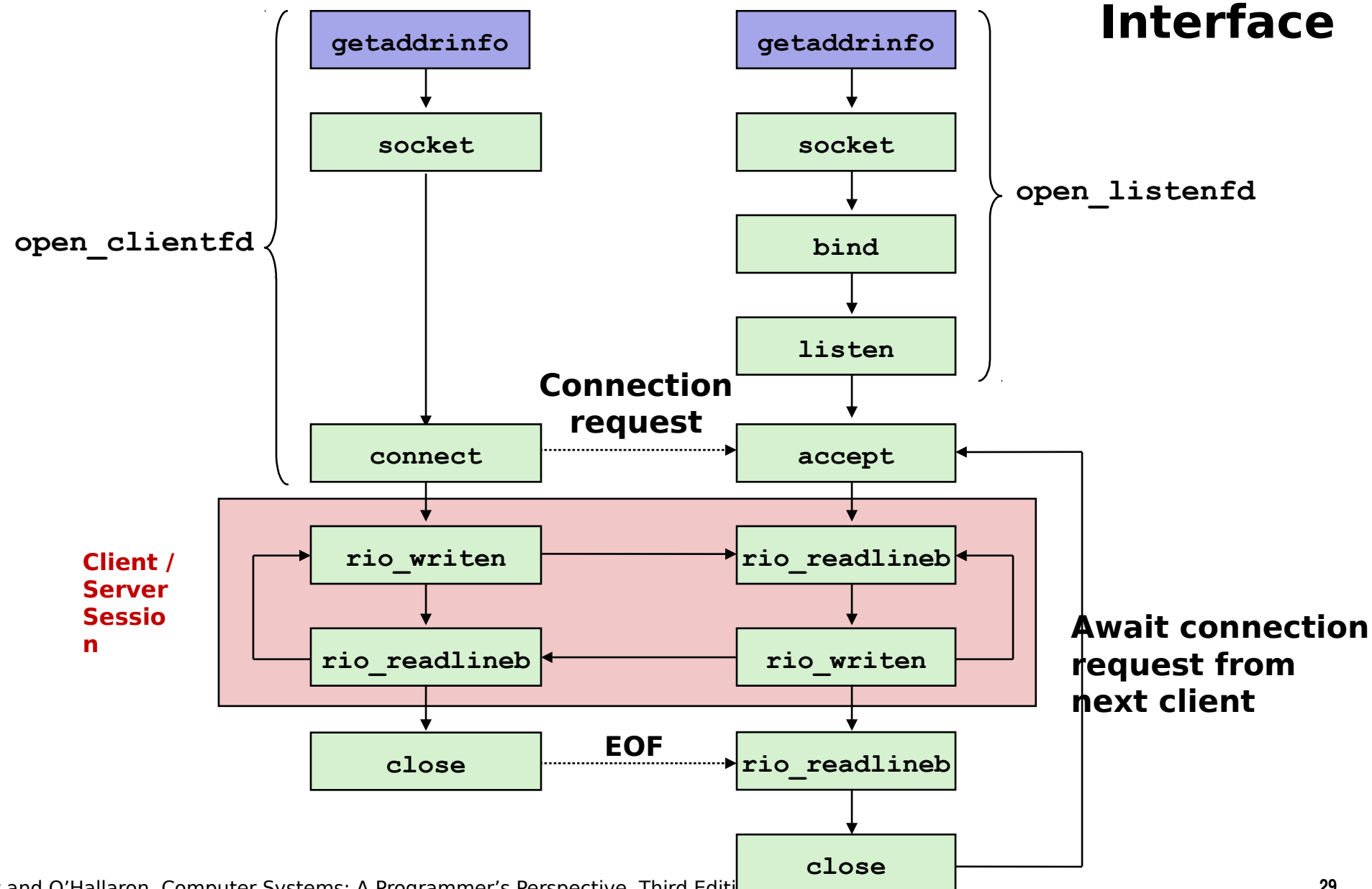
```
int listen(int sockfd, int backlog);
```

- Converts `sockfd` from an active socket to a **listening socket** that can accept connection requests from clients.
- `backlog` is a hint about the number of outstanding connection requests that the kernel should queue up before starting to refuse requests.

Sockets Interface

Client

Server



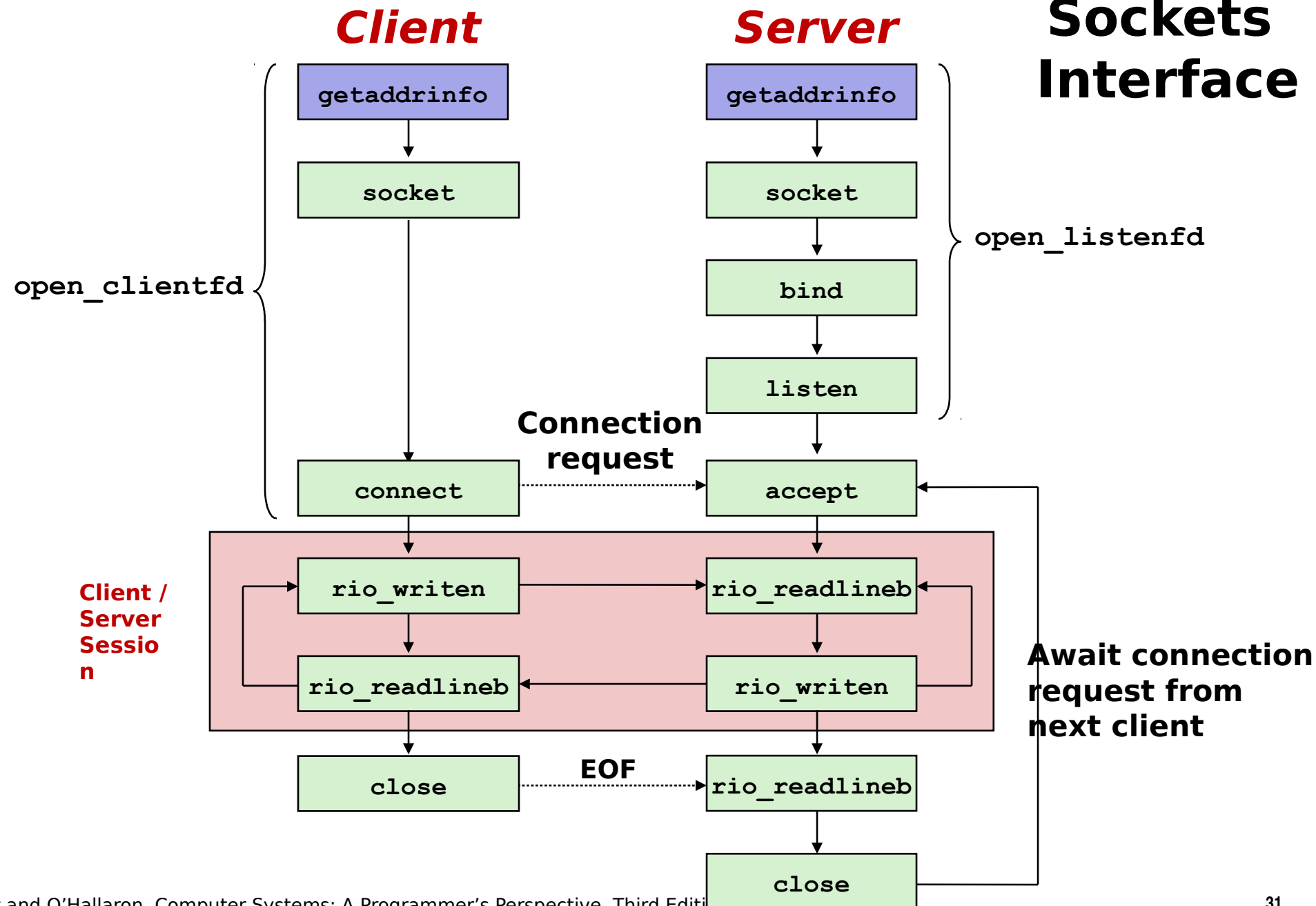
Sockets Interface: accept

- Servers wait for connection requests from clients by calling `accept`:

```
int accept(int listenfd, SA *addr, int *addrlen);
```

- Waits for connection request to arrive on the connection bound to `listenfd`, then fills in client's socket address in `addr` and size of the socket address in `addrlen`.
- Returns a ***connected descriptor*** that can be used to communicate with the client via Unix I/O routines.

Sockets Interface



Sockets Interface: connect

- A client establishes a connection with a server by calling **connect**:

```
int connect(int clientfd, SA *addr, socklen_t addrlen);
```

- Attempts to establish a connection with server at socket address **addr**
 - If successful, then `clientfd` is now ready for reading and writing.
 - Resulting connection is characterized by socket pair `(x:y, addr.sin_addr:addr.sin_port)`
 - `x` is client address
 - `y` is ephemeral port that uniquely identifies client process on client host

Best practice is to use `getaddrinfo` to supply the arguments `addr` and `addrlen`.

accept Illustrated



1. Server blocks in `accept`, waiting for connection request on listening descriptor `listenfd`



2. Client makes connection request by calling and blocking in `connect`



3. Server returns `connfd` from `accept`. Client returns from `connect`. Connection is now established between `clientfd` and `connfd`

Connected vs. Listening Descriptors

■ Listening descriptor

- End point for client connection requests
- Created once and exists for lifetime of the server

■ Connected descriptor

- End point of the connection between client and server
- A new descriptor is created each time the server accepts a connection request from a client
- Exists only as long as it takes to service client

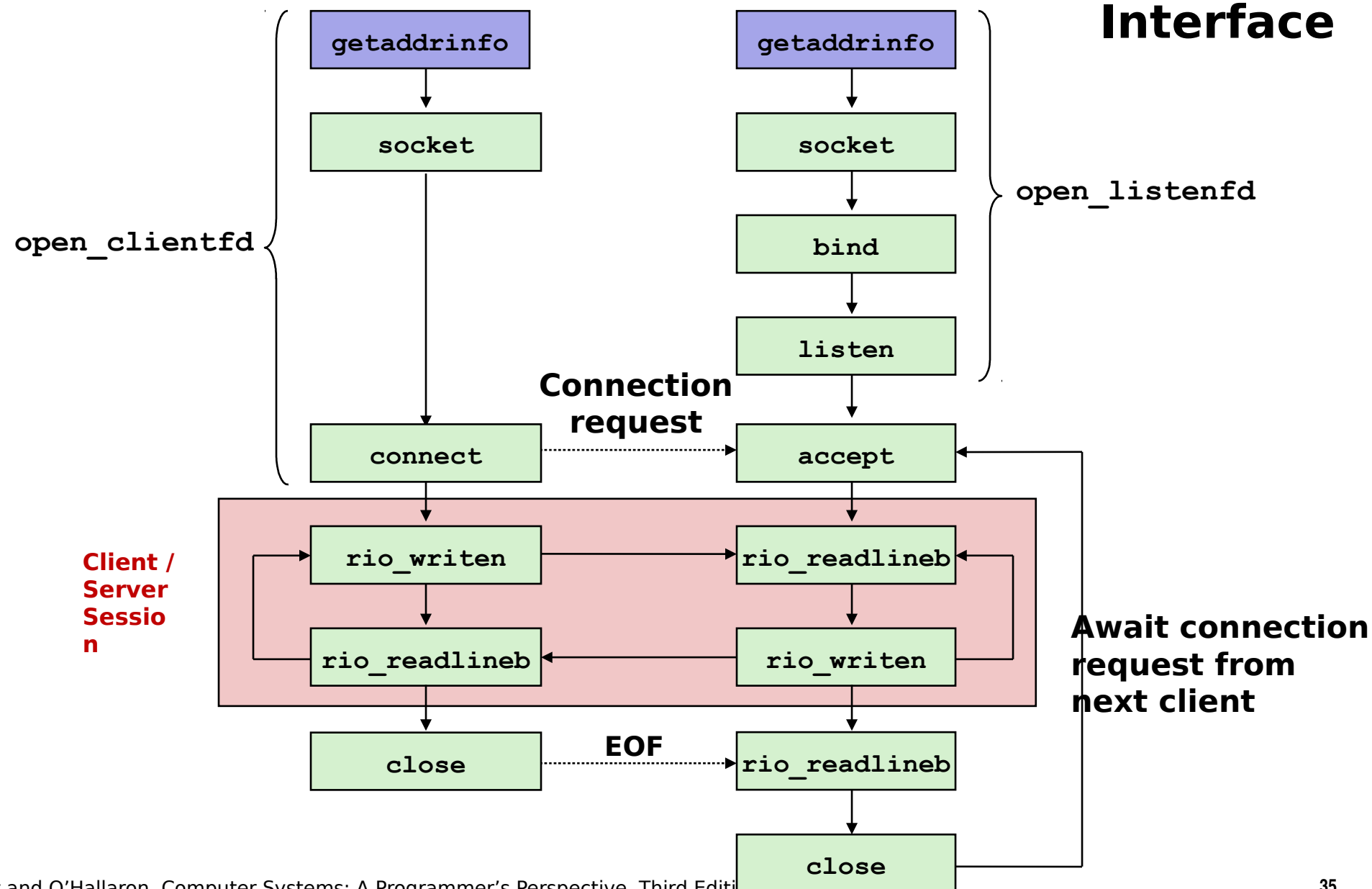
■ Why the distinction?

- Allows for concurrent servers that can communicate over many client connections simultaneously
 - E.g., Each time we receive a new request, we fork a child to handle the request

Sockets Interface

Client

Server



Sockets Helper: `open_clientfd`

■ Establish a connection with a server

```
int open_clientfd(char *hostname, char *port) {
    int clientfd;
    struct addrinfo hints, *listp, *p;

    /* Get a list of potential server addresses */
    memset(&hints, 0, sizeof(struct addrinfo));
    hints.ai_socktype = SOCK_STREAM; /* Open a connection */
    hints.ai_flags = AI_NUMERICSERV; /* ...using numeric port arg. */
    hints.ai_flags |= AI_ADDRCONFIG; /* Recommended for connections */
    Getaddrinfo(hostname, port, &hints, &listp);
```

csapp.c

Sockets Helper: open_clientfd (cont)

```
/* Walk the list for one that we can successfully connect to */
for (p = listp; p; p = p->ai_next) {
    /* Create a socket descriptor */
    if ((clientfd = socket(p->ai_family, p->ai_socktype,
                          p->ai_protocol)) < 0)
        continue; /* Socket failed, try the next */

    /* Connect to the server */
    if (connect(clientfd, p->ai_addr, p->ai_addrlen) != -1)
        break; /* Success */
    Close(clientfd); /* Connect failed, try another */
}

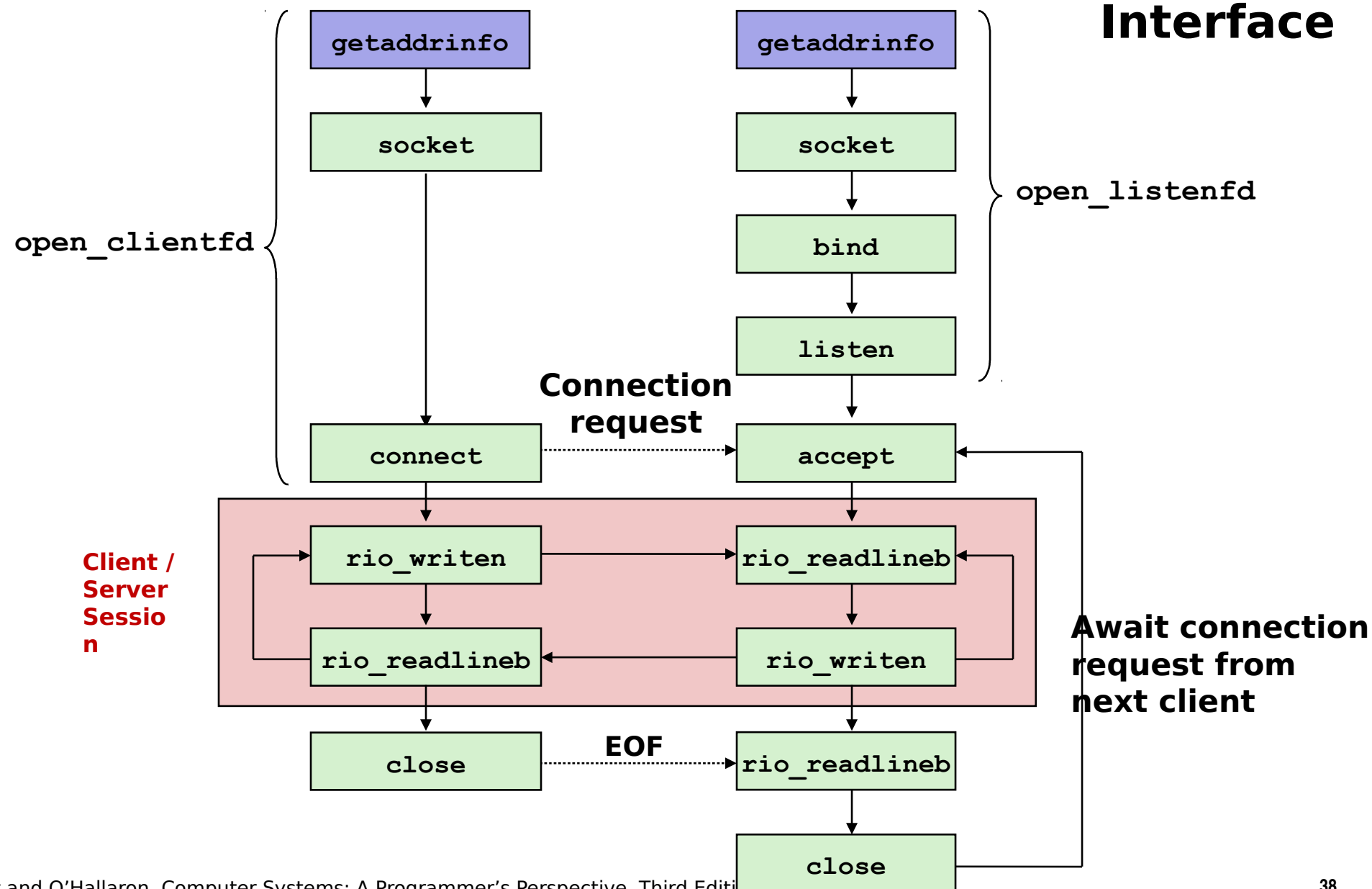
/* Clean up */
Freeaddrinfo(listp);
if (!p) /* All connects failed */
    return -1;
else /* The last connect succeeded */
    return clientfd;
}
```

csapp.c

Sockets Interface

Client

Server



Sockets Helper: `open_listenfd`

- Create a listening descriptor that can be used to accept connection requests from clients.

```
int open_listenfd(char *port)
{
    struct addrinfo hints, *listp, *p;
    int listenfd, optval=1;

    /* Get a list of potential server addresses */
    memset(&hints, 0, sizeof(struct addrinfo));
    hints.ai_socktype = SOCK_STREAM;                /* Accept connect. */
    hints.ai_flags = AI_PASSIVE | AI_ADDRCONFIG;    /* ...on any IP addr */
    hints.ai_flags |= AI_NUMERICSERV;              /* ...using port no. */
    Getaddrinfo(NULL, port, &hints, &listp);
```

csapp.c

Sockets Helper: open_listenfd (cont)

```
/* Walk the list for one that we can bind to */
for (p = listp; p; p = p->ai_next) {
    /* Create a socket descriptor */
    if ((listenfd = socket(p->ai_family, p->ai_socktype,
                          p->ai_protocol)) < 0)
        continue; /* Socket failed, try the next */

    /* Eliminates "Address already in use" error from bind */
    Setsockopt(listenfd, SOL_SOCKET, SO_REUSEADDR,
               (const void *)&optval , sizeof(int));

    /* Bind the descriptor to the address */
    if (bind(listenfd, p->ai_addr, p->ai_addrlen) == 0)
        break; /* Success */
    Close(listenfd); /* Bind failed, try the next */
}
```

csapp.c

Sockets Helper: open_listenfd (cont)

```
/* Walk the list for one that we can bind to */
for (p = listp; p; p = p->ai_next) {
    /* Create a socket descriptor */
    if ((listenfd = socket(p->ai_family, p->ai_socktype,
                          p->ai_protocol)) < 0)
        continue; /* Socket failed, try the next */

    /* Eliminates "Address already in use" error from bind */
    Setsockopt(listenfd, SOL_SOCKET, SO_REUSEADDR,
               (const void *)&optval , sizeof(int));

    /* Bind the descriptor to the address */
    if (bind(listenfd, p->ai_addr, p->ai_addrlen) == 0)
        break; /* Success */
    Close(listenfd); /* Bind failed, try the next */
}
```

csapp.c

Summary

- **Sockets used to communicate across processes over a network (even same network card)**
 - TCP sockets – Listening vs connecting sockets
 - Quirks in structs representing network addresses.
 - Use getaddrinfo() or fill up the struct yourself.
 - Usage of rio library for buffered I/O.

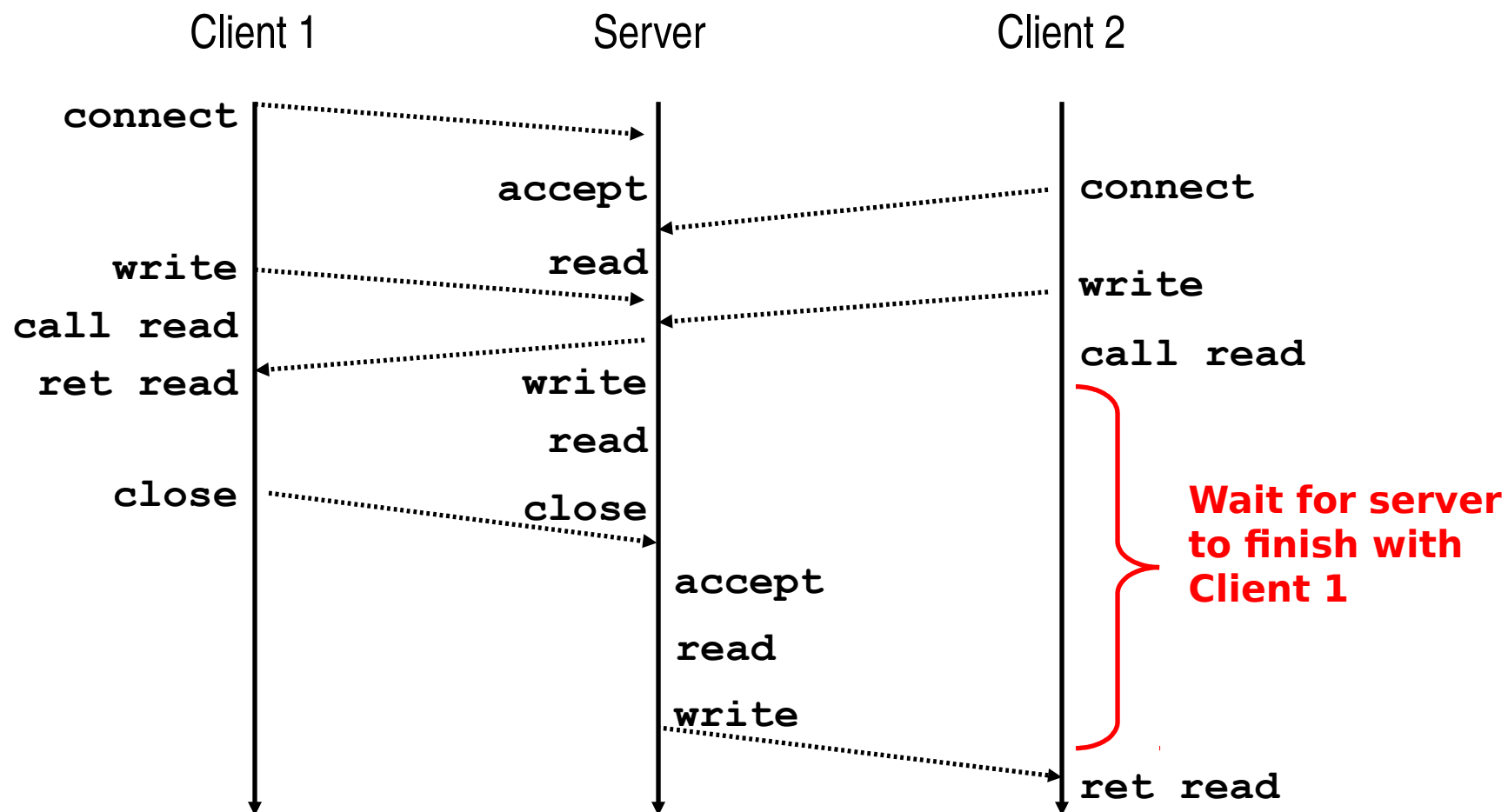
Testing Servers Using telnet

- **The telnet program is invaluable for testing servers that transmit ASCII strings over Internet connections**
 - Our simple echo server
 - Web servers
 - Mail servers

- **Usage:**
 - `linux> telnet <host> <portnumber>`
 - Creates a connection with a server running on *<host>* and listening on port *<portnumber>*

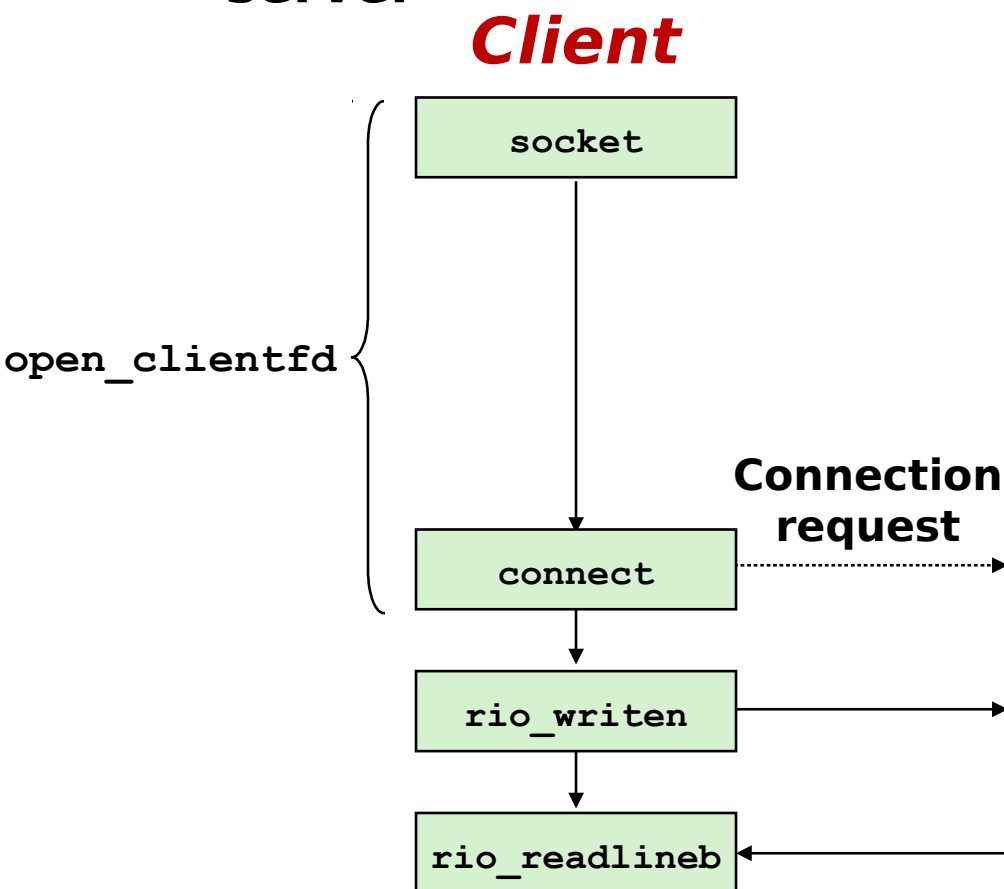
Iterative Servers

- Iterative servers process one request at a time



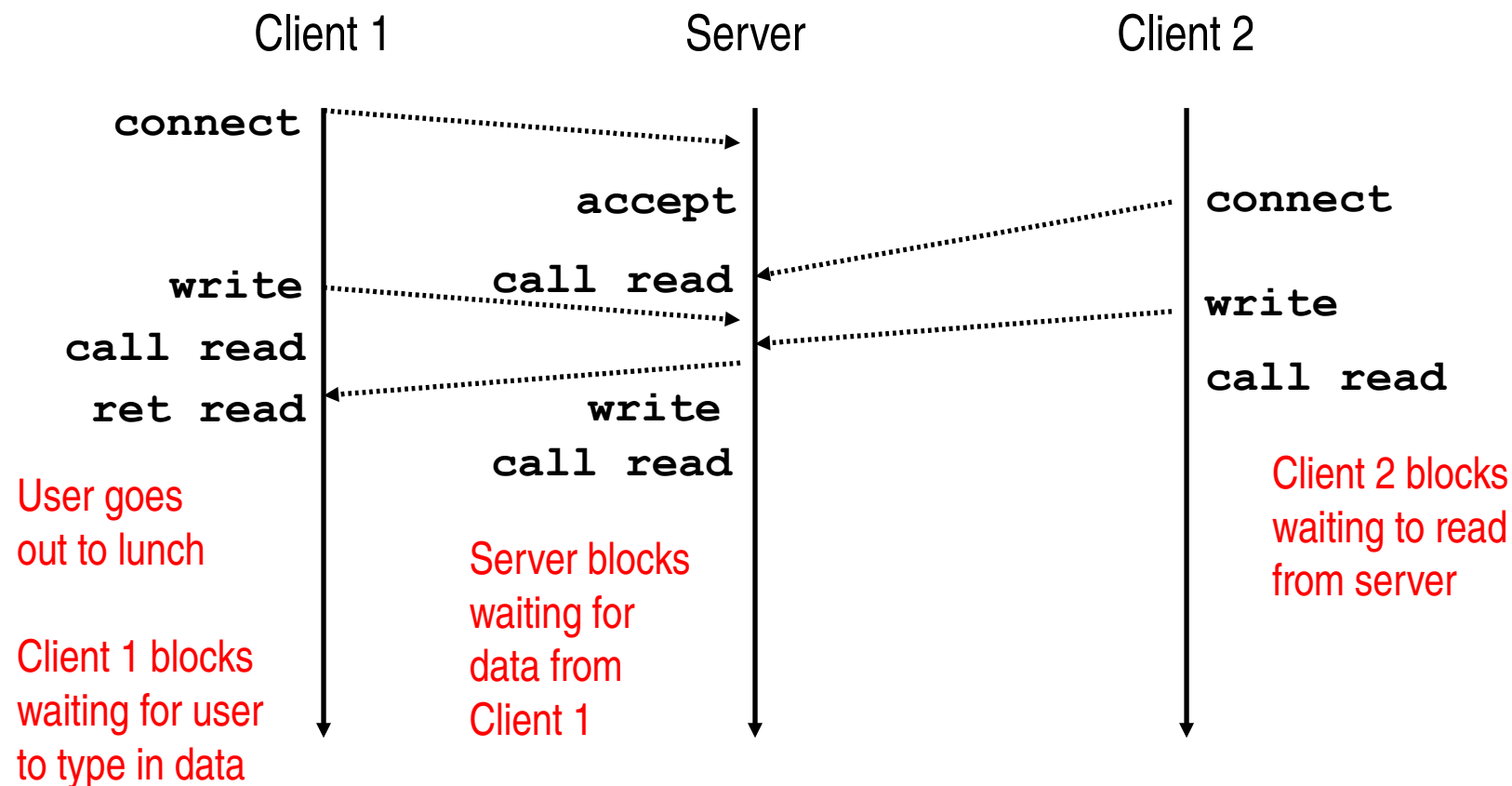
Where Does Second Client Block?

- **Second client attempts to connect to iterative server**



- **Call to connect returns**
 - Even though connection not yet accepted
 - Server side TCP manager queues request
 - Feature known as “TCP listen backlog”
- **Call to rio_writen returns**
 - Server side TCP manager buffers input data
- **Call to rio_readlineb blocks**
 - Server hasn't written anything for it to read yet.

Fundamental Flaw of Iterative Servers



- **Solution: use *concurrent servers* instead**
 - Concurrent servers use multiple concurrent flows to serve multiple clients at the same time

Approaches for Writing Concurrent Servers

Allow server to handle multiple clients concurrently

1. Process-based

- Kernel automatically interleaves multiple logical flows
- Each flow has its own private address space

2. Event-based

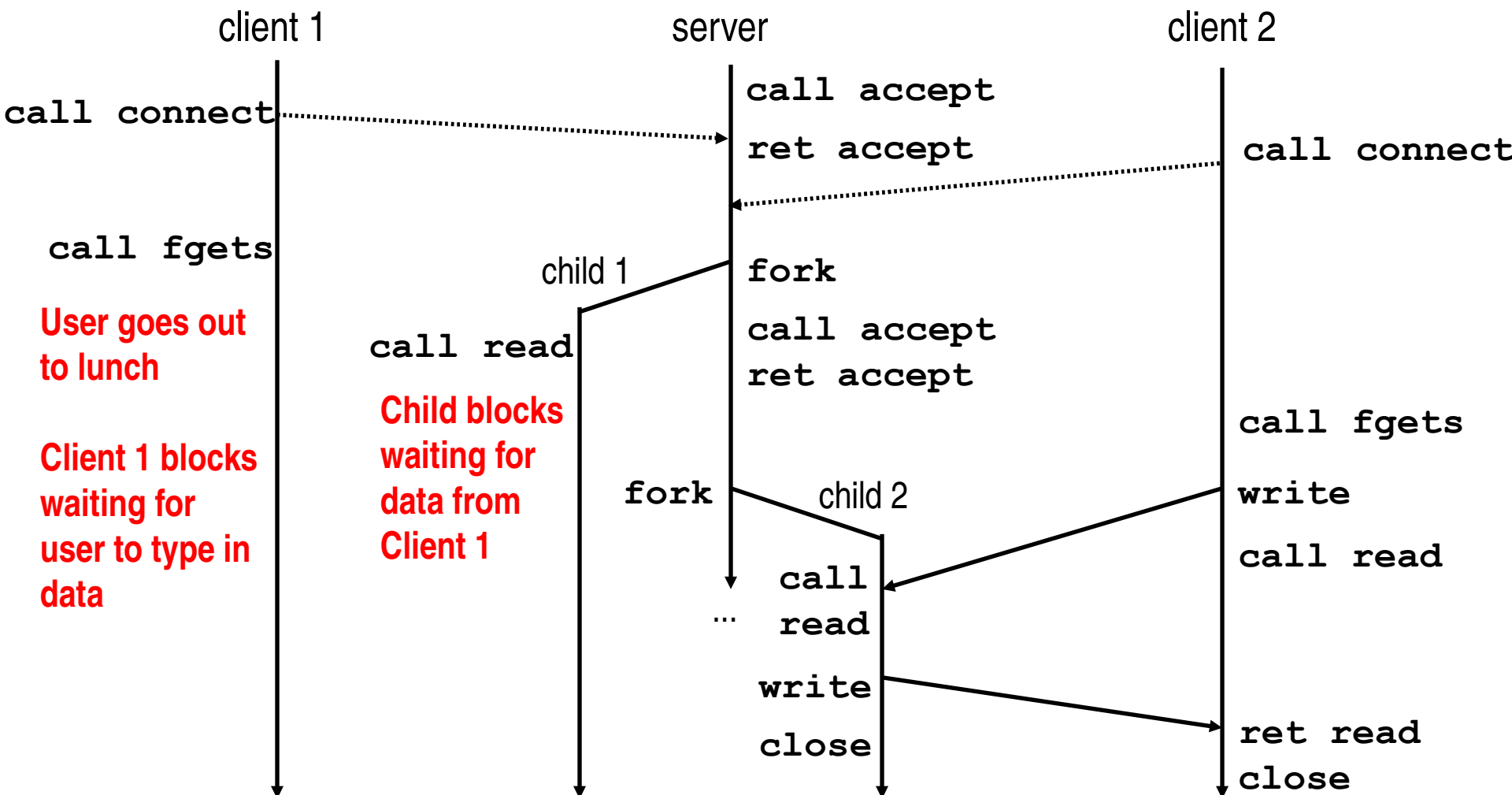
- Programmer manually interleaves multiple logical flows
- All flows share the same address space
- Uses technique called *I/O multiplexing*.

3. Thread-based

- Kernel automatically interleaves multiple logical flows
- Each flow shares the same address space
- Hybrid of of process-based and event-based.

Approach #1: Process-based Servers

- Spawn separate process for each client



Process-Based Concurrent Echo Server

```
int main(int argc, char **argv)
{
    int listenfd, connfd;
    socklen_t clientlen;
    struct sockaddr_storage clientaddr;

    Signal(SIGCHLD, sigchld_handler);
    listenfd = Open_listenfd(argv[1]);
    while (1) {
        clientlen = sizeof(struct sockaddr_storage);
        connfd = Accept(listenfd, (SA *) &clientaddr, &clientlen);
        if (Fork() == 0) {
            Close(listenfd); /* Child closes its listening socket */
            echo(connfd);    /* Child services client */
            Close(connfd);  /* Child closes connection with client */
            exit(0);        /* Child exits */
        }
        Close(connfd); /* Parent closes connected socket (important!) */
    }
}
```

echoserverp

Process-Based Concurrent Echo Server (cont)

```
void sigchld_handler(int sig)
{
    while (waitpid(-1, 0, WNOHANG) > 0)
        ;
    return;
}
```

echoserverp.c

- Reap all zombie children

Issues with Process-based Servers

- **Listening server process must reap zombie children**
 - to avoid fatal memory leak
- **Parent process must close its copy of `connfd`**
 - Kernel keeps reference count for each socket/open file
 - After fork, `refcnt(connfd) = 2`
 - Connection will not be closed until `refcnt(connfd) = 0`

Pros and Cons of Process-based Servers

- **+ Handle multiple connections concurrently**
- **+ Clean sharing model**
 - descriptors (no)
 - file tables (yes)
 - global variables (no)
- **+ Simple and straightforward**
- **– Additional overhead for process control**
- **– Nontrivial to share data between processes**
 - Requires IPC (interprocess communication) mechanisms
 - FIFO's (named pipes), System V shared memory and semaphores

Approach #2: Event-based Servers

- **Server maintains set of active connections**
 - Array of `connfd`'s
- **Repeat:**
 - Determine which descriptors (`connfd`'s or `listenfd`) have pending inputs
 - e.g., using `select` or `epoll` functions
 - arrival of pending input is an *event*
 - If `listenfd` has input, then `accept` connection
 - and add new `connfd` to array
 - Service all `connfd`'s with pending inputs
- **Details for select-based server in book**

Pros and Cons of Event-based Servers

- **+ One logical control flow and address space.**
- **+ Can single-step with a debugger.**
- **+ No process or thread control overhead.**
 - Design of choice for high-performance Web servers and search engines. e.g., Node.js, nginx, Tornado
- **– Significantly more complex to code than process- or thread-based designs.**
- **– Hard to provide fine-grained concurrency**
 - E.g., how to deal with partial HTTP request headers
- **– Cannot take advantage of multi-core**
 - Single thread of control

Approach #3: Thread-based Servers

- **Very similar to approach #1 (process-based)**
 - ...but using threads instead of processes

Threads vs. Processes

■ How threads and processes are similar

- Each has its own logical control flow
- Each can run concurrently with others (possibly on different cores)
- Each is context switched

■ How threads and processes are different

- Threads share all code and data (except local stacks)
 - Processes (typically) do not
- Threads are somewhat less expensive than processes
 - Process control (creating and reaping) twice as expensive as thread control
 - Linux numbers:
 - ~20K cycles to create and reap a process
 - ~10K cycles (or less) to create and reap a thread

Posix Threads (Pthreads) Interface

- ***Pthreads*: Standard interface for ~60 functions that manipulate threads from C programs**
 - Creating and reaping threads
 - `pthread_create()`
 - `pthread_join()`
 - Determining your thread ID
 - `pthread_self()`
 - Terminating threads
 - `pthread_cancel()`
 - `pthread_exit()`
 - `exit()` [terminates all threads] , `RET` [terminates current thread]
 - Synchronizing access to shared variables
 - `pthread_mutex_init`
 - `pthread_mutex_[un]lock`

Thread-Based Concurrent Echo Server

```
int main(int argc, char **argv)
{
    int listenfd, *connfdp;
    socklen_t clientlen;
    struct sockaddr_storage clientaddr;
    pthread_t tid;

    listenfd = Open_listenfd(argv[1]);
    while (1) {
        clientlen = sizeof(struct sockaddr_storage);
        connfdp = Malloc(sizeof(int));
        *connfdp = Accept(listenfd,
                          (SA *) &clientaddr, &clientlen);
        Pthread_create(&tid, NULL, thread, connfdp);
    }
}
```

echoserver.c

- **malloc of connected descriptor necessary to avoid deadly race**

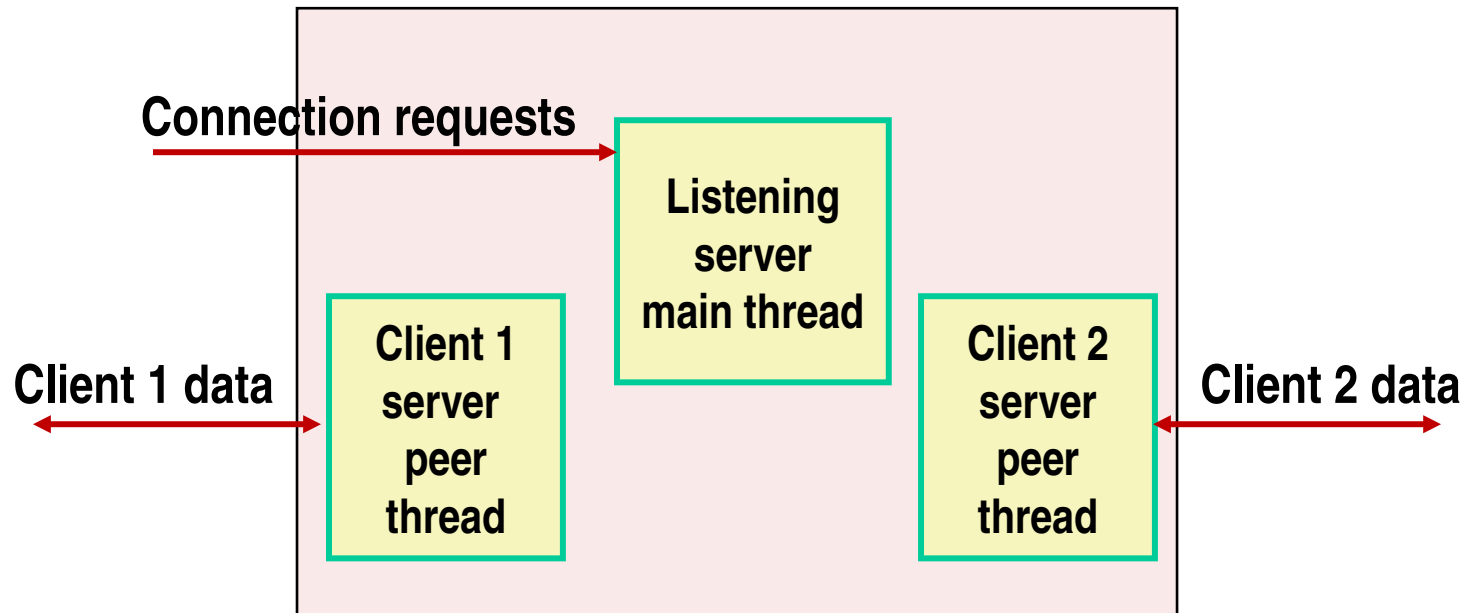
Thread-Based Concurrent Server (cont)

```
/* Thread routine */  
void *thread(void *vargp)  
{  
    int connfd = *((int *)vargp);  
    Pthread_detach(pthread_self());  
    Free(vargp);  
    echo(connfd);  
    Close(connfd);  
    return NULL;  
}
```

echoservt.c

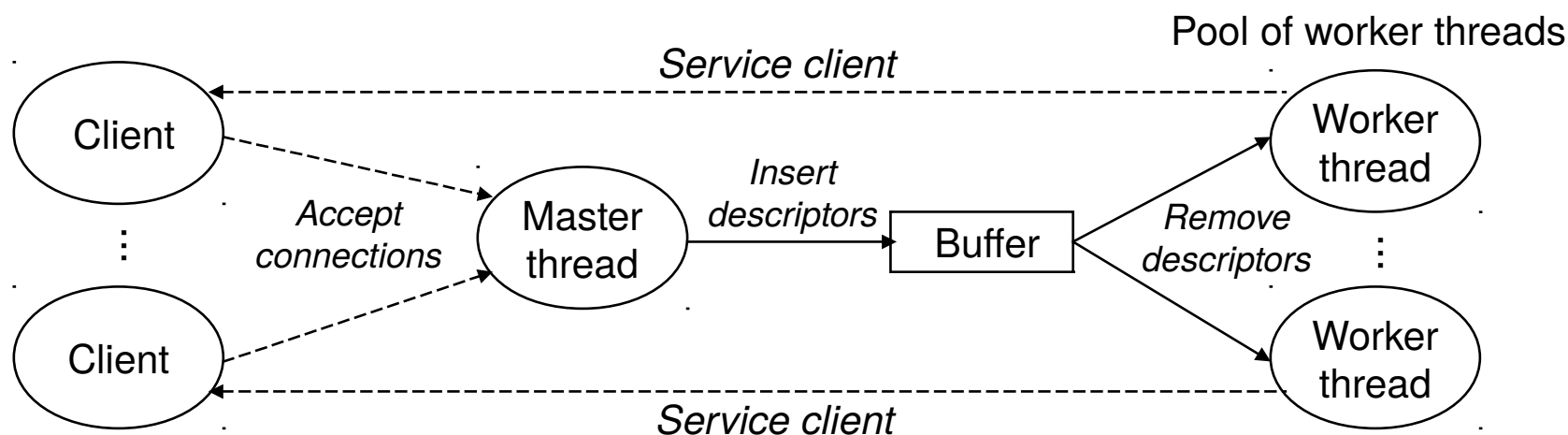
- Run thread in “detached” mode.
 - Runs independently of other threads
 - Reaped automatically (by kernel) when it terminates
- Free storage allocated to hold `connfd`.
- Close `connfd` (important!)

Thread-based Server Execution Model



- Each client handled by individual peer thread
- Threads share all process state except TID
- Each thread has a separate stack for local variables

Pre-threaded Server Model



- Clients handled using a thread-pool architecture
- Bounded/Unbounded buffer can be used for synchronization

Pros and Cons of Thread-Based Designs

- **+ Easy to share data structures between threads**
 - e.g., logging information, file cache
- **+ Threads are more efficient than processes**
- **– Unintentional sharing can introduce subtle and hard-to-reproduce errors!**
 - The ease with which data can be shared is both the greatest strength and the greatest weakness of threads
 - Hard to know which data shared & which private
 - Hard to detect by testing
 - Probability of bad race outcome very low
 - But nonzero!

Summary: Approaches to Concurrency

■ **Process-based**

- Hard to share resources: Easy to avoid unintended sharing
- High overhead in adding/removing clients

■ **Event-based**

- Tedious and low level
- Total control over scheduling
- Very low overhead
- Cannot create as fine grained a level of concurrency
- Does not make use of multi-core

■ **Thread-based**

- Easy to share resources: Perhaps too easy
- Medium overhead
- Not much control over scheduling policies
- Difficult to debug
 - Event orderings not repeatable

Code references can be found at
<http://csapp.cs.cmu.edu/3e/code.html>

Assignment A6

- Build client server portion of a distributed chat service

