ARM

Assembly Language and Machine Code

Concepts

Types of ALU instructions

Bits and bit operations

Condition codes

Branches

Addressing modes in loads & stores

```
// Program to turn on an LED
#define FSEL2 0x20200008
ldr r0, =FSEL2
mov r1, #1
                    ; GPI020 Output
str r1, [r0]
#define SET0 0x2020001C
1dr r0, = SET0
mov r1, \#(1 << 20); Bit 20
str r1, [r0]
loop: b loop
```

3 Types of Instructions

- 1. Data processing instructions
- 2. Loads from and stores to memory
- 3. Branches to new program locations

Data Processing Instructions

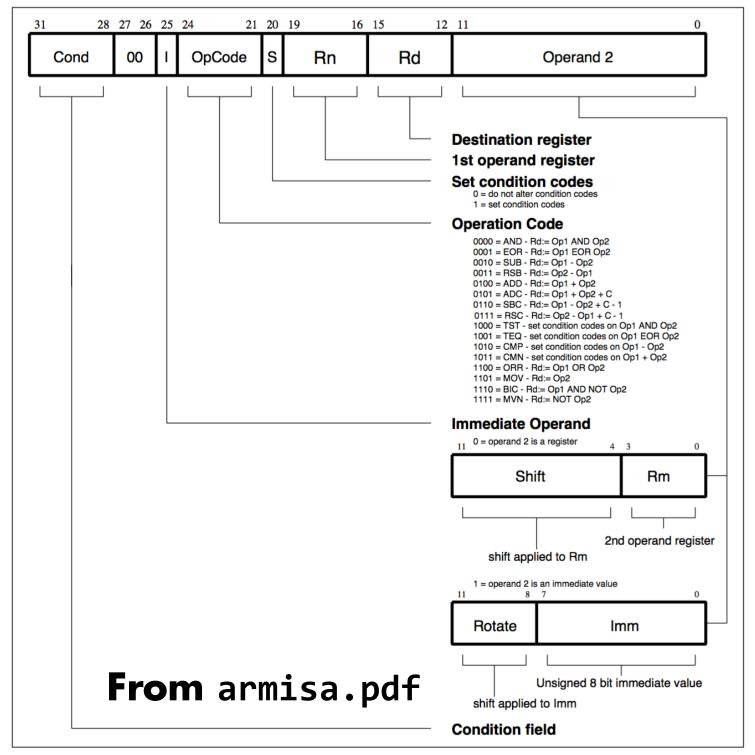


Figure 4-4: Data processing instructions

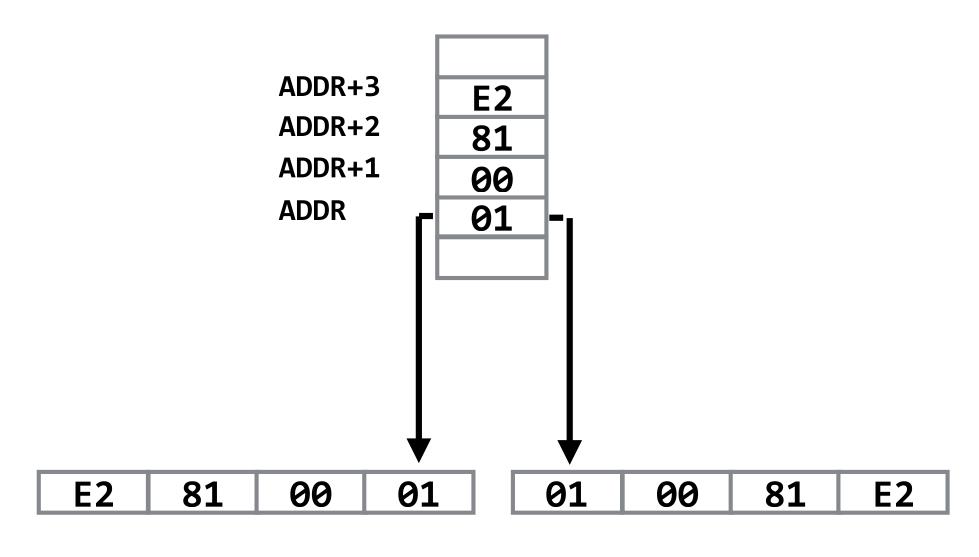
```
# data processing instruction
# ra = rb op #imm
# #imm = uuuu uuuu
```

```
op rb ra imm
1110 00 1 0000 0 bbbb aaaa 0000 uuuu uuuu
add r0, r1, #1
```

| Assembly | Code | Operations | |
|-----------------|------|--------------------|--|
| AND | 0000 | ra=rb&rc | |
| EOR (XOR) | 0001 | ra=rb^rc | |
| SUB | 0010 | ra=rb-rc | |
| RSB | 0011 | ra=rc-rb | |
| ADD | 0100 | ra=rb+rc | |
| ADC | 0101 | ra=rb+rc+CARRY | |
| SBC | 0110 | ra=rb-rc+(1-CARRY) | |
| RSC | 0111 | ra=rc-rb+(1-CARRY) | |
| TST | 1000 | rb&rc (ra not set) | |
| TEQ | 1001 | rb^rc (ra not set) | |
| CMP | 1010 | rb-rc (ra not set) | |
| CMN | 1011 | rb+rc (ra not set) | |
| ORR (OR) | 1100 | ra=rb rc | |
| MOV | 1101 | ra=rc | |
| BIC | 1110 | ra=rb&~rc | |
| MVN | 1111 | ra=~rc | |

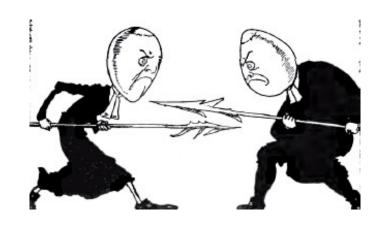
```
# data processing instruction
# ra = rb op #imm
# #imm = uuuu uuuu
```

```
# data processing instruction
# ra = rb op #imm
# #imm = uuuu uuuu
         op rb ra
                              imm
1110 00 1 0000 0 bbbb aaaa 0000 uuuu uuuu
add r0, r1, #1
         add r1 r0
1110 00 1 0100 0 0001 0000 0000 0000 0001
1110 0010 1000 0000 0001 0000 0000 0001
                    0
```



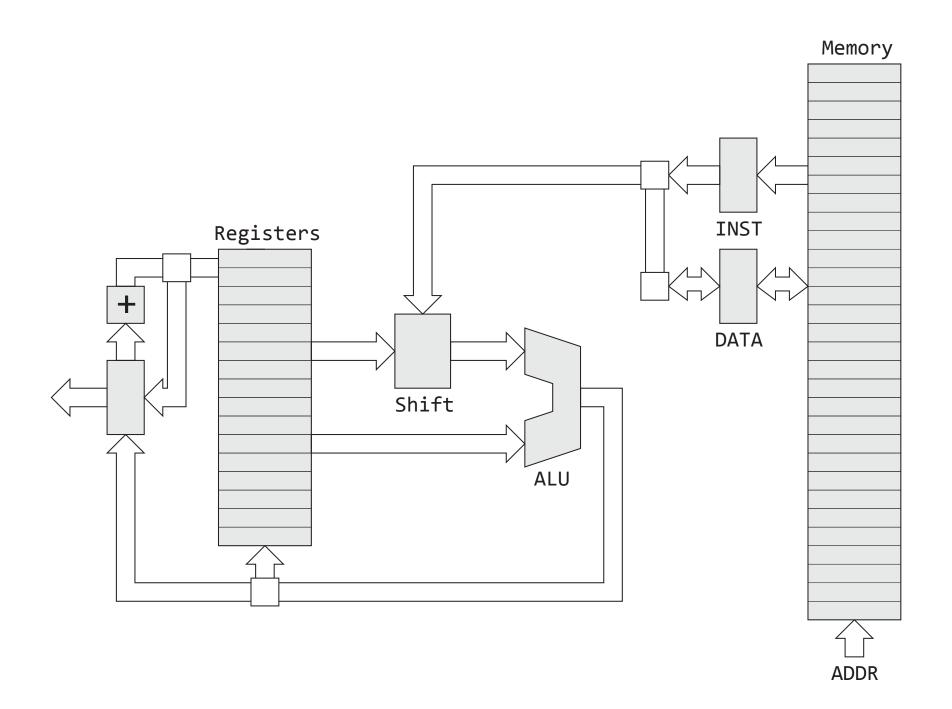
little-endian

big-endian (lowest byte first) (highest byte first)

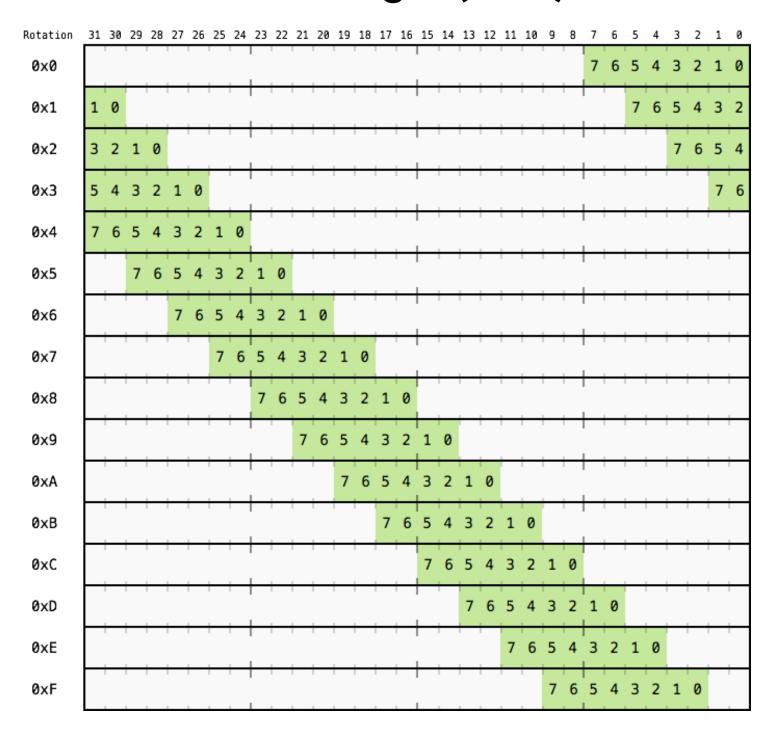


The 'little-endian' and 'big-endian' terminology which is used to denote the two approaches [to addressing memory] is derived from Swift's Gulliver s Travels. The inhabitants of Lilliput, who are well known for being rather small, are, in addition, constrained by law to break their eggs only at the little end. When this law is imposed, those of their fellow citizens who prefer to break their eggs at the big end take exception to the new rule and civil war breaks out. The big-endians eventually take refuge on a nearby island, which is the kingdom of Blefuscu. The civil war results in many casualties.

Read: Holy Wars and a Plea For Peace, D. Cohen



Rotate Right (ROR)



```
# data processing instruction
# ra = rb op imm
# imm = (uuuu uuuu) ROR (2*iii)
```

op rb ra ror imm 1110 00 1 <mark>0000</mark> 0 <mark>bbbb</mark> aaaa iiii uuuu uuuu

```
# data processing instruction
# ra = rb op imm
# imm = (uuuu uuuu) ROR (2*iiii)
         op rb ra ror imm
1110 00 1 oooo 0 bbbb aaaa iiii uuuu uuuu
add r0, r1, #0x10000
         add r1 r0 0x01>>>2*8
1110 00 1 0100 0 0001 0000 1000 0000 0001
```

```
# data processing instruction
# ra = rb op imm
# imm = (uuuu uuuu) ROR (2*iiii)
         op rb ra ror imm
1110 00 1 oooo 0 bbbb aaaa iiii uuuu uuuu
add r0, r1, #0x10000
         add r1 r0 0x01>>>2*8
1110 00 1 0100 0 0001 0000 1000 0000 0001
1110 0010 1000 0001 0000 1000 0000 0001
           8 1
```

```
# Determine the machine code for
sub r7, r5, #0x300
# imm = (uuuu uuuu) ROR (2*iiii)
# Remember that ra is the result
           op rb ra ror imm
1110 00 1 oooo 0 bbbb aaaa iiii uuuu uuuu
// What is the machine code?
```

```
# data processing instruction
# ra = rb op imm
# imm = uuuu uuuu ROR (2*iiii)
         op rb ra ror
1110 00 1 oooo 0 bbbb aaaa iiii uuuu uuuu
sub r7, r5, #0x300
         sub r5 r7 #0x03>>>24
1110 00 1 0010 0 0101 0111 1100 0000 0011
1110 0010 0100 0101 0111 1100 0000 0011
           4 5 7 C
```

Bit Manipulations

```
// May replace
#define FSEL2 0x20200008
ldr r0, =FSEL2
// with
mov r0, #0x20000000 // #(0x20>>>8)
orr r0, #0x00200000 // #(0x20>>>16)
orr r0, #0x00000008
```

```
GPIO2 5 GPIO 24
                                 GPIO23
GPIO 29
     GPIO 28
           GPIO 27
                GPIO 26
                                      GPIO 22
                                            GPIO<sub>2</sub> 1
                                                 GPIO20
// FSEL2 into r0
mov r0, #0x20000000 // #(0x20>>>8)
orr r0, #0x00200000 // #(0x20>>>16)
orr r0, #0x0000008
// Set GPIO 20 to OUTPUT
mov r1, #1
str r1, [r0]
// Also set GPIO 21 to OUTPUT
// How?
```

GPIO20

```
GPIO 27 GPIO 26 GPIO 25 GPIO 24 GPIO 23
                                      GPIO 22
GPIO 29
     GPIO 28
                                            GPIO<sub>2</sub> 1
// FSEL2 into r0
mov r0, #0x20000000 // #(0x20>>>8)
orr r0, #0x00200000 // #(0x20>>>16)
orr r0, #0x0000008
// Set GPIO 20 and 21 both to OUTPUT
mov r1, #1
orr r1, \#(1<<3)
str r1, [r0]
```

GPIO20

```
GPIO 27 GPIO 26 GPIO 2 5 GPIO 24 GPIO 2 3
GPIO 29
     GPIO 28
                                    GPIO 22
                                         GPIO2 1
// FSEL2 into r0
mov r0, #0x20000000 // #(0x20>>>8)
orr r0, #0x00200000 // #(0x20>>>16)
orr r0, #0x0000008
// Set GPIO 20 to OUTPUT
mov r1, #1
// Set GPIO 21 to OUTPUT
ldr r1, [r0]
bic r1, \#(0x7<<3)
orr r1, \#(0x1<<3)
str r1, [r0]
```

Condition Codes

```
// loop
#define DELAY 0x3F0000
mov r2, #DELAY
loop:
    subs r2, r2, #1 // set cond code
    bne loop
```

Condition Codes

z - Result is O

N - Result is <0

C - Carry generated

V - Arithmetic overflow

Carry and overflow will be covered later

```
# data processing instruction
# ra = rb op #imm
# #imm = uuuu uuuu ROR (2*iii)
#
# s - set condition code
#
        rb ra
    op
1110 00 1 oooo s bbbb aaaa iiii uuuu uuuu
```

```
# data processing instruction
# ra = rb op imm
# imm = uuuu uuuu ROR (2*iiii)
# s=1 means set condition code
         op s rb ra
1110 00 1 oooo s bbbb aaaa iiii uuuu uuuu
subs r2, r2, #1
         sub s r2 r2
1110 00 1 0010 1 0010 0010 0000 0000 0001
E2 52 20 01
```

Branch Instructions

```
# branch
cond addr
cccc 101L 0000 0000 0000 0000 0000
b = bal = branch always
cond addr
1110 101L 0000 0000 0000 0000 0000
```

bne cond addr addr 101L 0000 0000 0000 0000 0000

| Code | Suffix | Flags | Meaning |
|------|--------|-----------------------------|-------------------------|
| 0000 | EQ | Z set | equal |
| 0001 | NE | Z clear | not equal |
| 0010 | cs | C set | unsigned higher or same |
| 0011 | CC | C clear | unsigned lower |
| 0100 | MI | N set | negative |
| 0101 | PL | N clear | positive or zero |
| 0110 | VS | V set | overflow |
| 0111 | VC | V clear | no overflow |
| 1000 | н | C set and Z clear | unsigned higher |
| 1001 | LS | C clear or Z set | unsigned lower or same |
| 1010 | GE | N equals V | greater or equal |
| 1011 | LT | N not equal to V | less than |
| 1100 | GT | Z clear AND (N equals V) | greater than |
| 1101 | LE | Z set OR (N not equal to V) | less than or equal |
| 1110 | AL | (ignored) | always |

Blink

```
// Configure GPIO 20 for OUTPUT
loop:
 // Turn on LED
 // delay
 // Turn off LED
 // delay
 b loop
```

```
// Program to turn on an LED
// Setup GPIO 20
#define FSEL2 0x20200008
ldr r0, =FSEL2
mov r1, #1
str r1, [r0]
// Bit 20 for GPIO 20
mov r1, \#(1<<20)
```

// r0 points to GPIO SET0 register #define SET0 0x2020001C 1dr r0, = SET0str r1, [r0] // delay #define DELAY 0x3F0000 mov r2, #DELAY wait1: subs r2, #1

bne wait1

•••

```
// r0 points to GPIO CLR0 register
#define CLR0 0x20200028
ldr r0, = CLR0
str r1, [r0]
// delay
mov r2, #DELAY
wait2:
   subs r2, #1
   bne wait2
```

```
// GPIO registers don't act like memory
// r0 points to GPIO SET0 register
1dr r0, = SET0
str r1, [r0]
// r0 points to GPIO CLR0 register
1dr r0, = CLR0
str r1, [r0]
```

Orthogonal Instructions

Any operation

Register vs. immediate operands

All registers the same**

Predicated/conditional execution

Set or not set condition code

Orthogonality leads to composability

Summary

You need to understand how processors represent and execute instructions

Instruction set architecture often easier to understand by looking at the bits

Reading assembly allows you to know what the processor is doing

Rarely write assembly,

Normally write code in C (next week)

The Fun Begins ...

Labs!!

- Assembly Raspberry Pi Kit
- Read lab1 guide
- Install tool chain
- Bring \$50 lab fee

Assignment 1

■ Larson scanner

Extra Slides

Pipelining

Processors execute instructions in phases

Fetch Decode Execute

Phases are pipelined

| Fetch | Decode | Execute | | _ |
|-------|--------|---------|---------|---------|
| | Fetch | Decode | Execute | |
| | | Fetch | Decode | Execute |

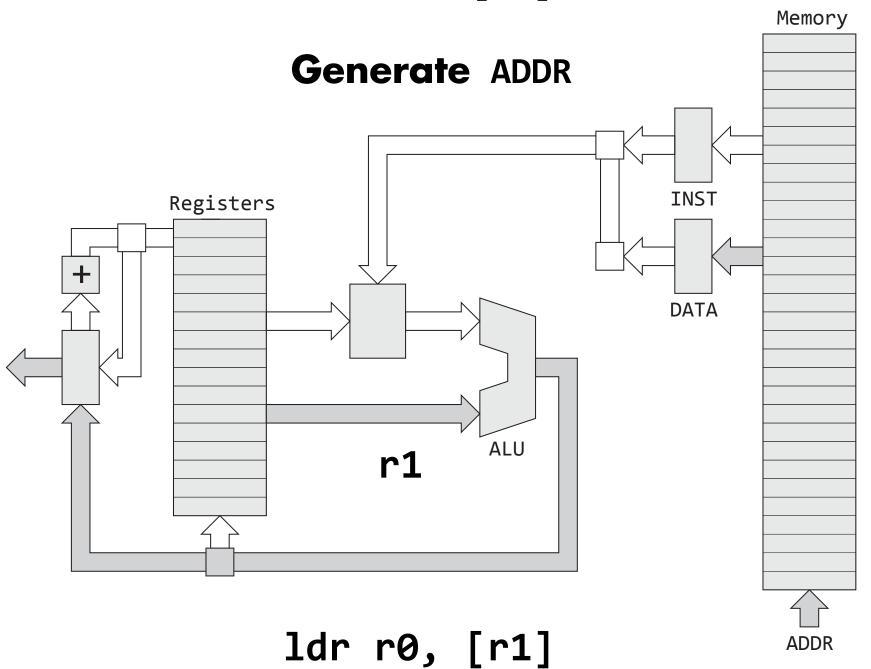
PC value is 2 instructions ahead (PC+8) of the executing instruction (PC+8)

```
// disassemble on.s
0: e59f0014
              ldr r0, [pc, #0x14]
              mov r1, #1
4: e3a01001
8: e5801000 str r1, [r0]
c: e59f000c
              ldr r0, [pc, #0x0c]
              mov r1, #0x100000
10: e3a01601
14: e5801000
              str r1, [r0]
              b 18 // [pc, -2*4]
18: eafffffe
1c: 20200008
20: 2020001c
```

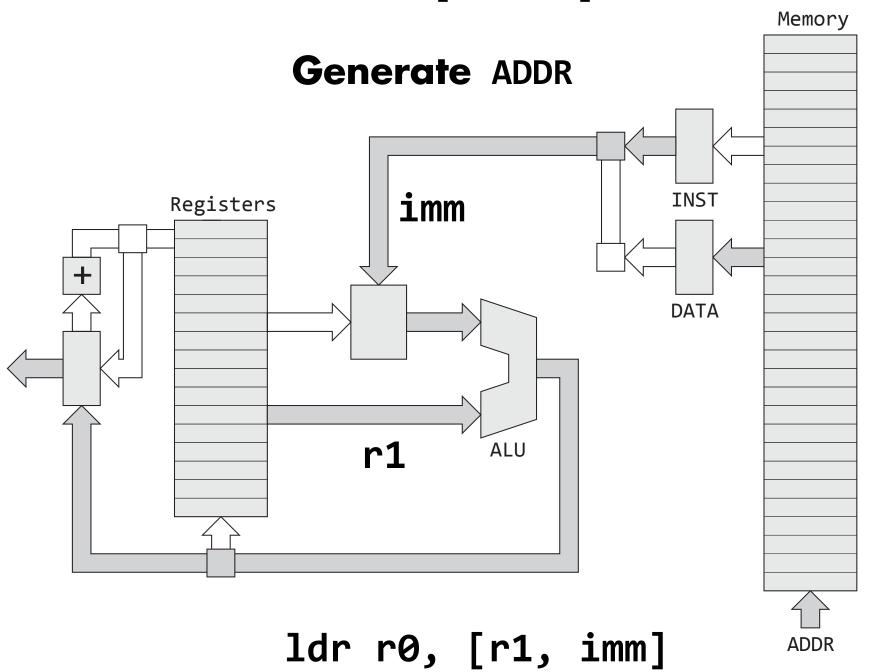
Indexed Loads

PC Relative Addressing

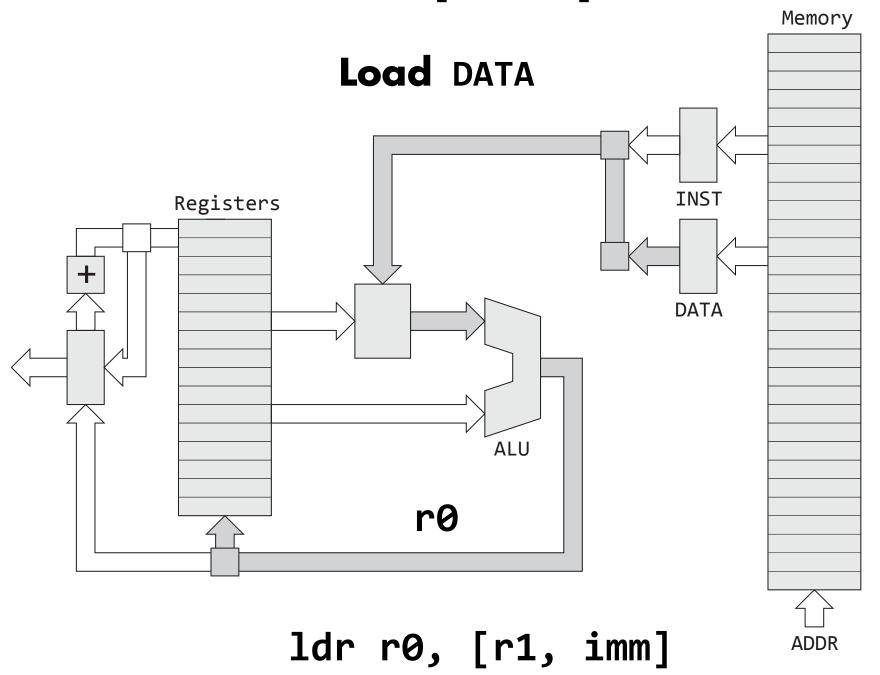
r0 = mem[r1]



r0 = mem[r1+imm]



r0 = mem[r1+imm]



```
// disassemble on.s
// PC relative addressing
 0: e59f0014
              ldr r0, [pc, #0x14]
 4: e3a01001
              mov r1, #1
 8: e5801000
              str r1, [r0]
 c: e59f000c
              ldr r0, [pc, #0x0c]
10: e3a01601
              mov r1, #0x100000
14: e5801000
              str r1, [r0]
              b 18 // [pc, -2*4]
18: eafffffe
1c: 20200008
20: 2020001c
```

```
// disassemble on.s
// PC relative addressing
 0: e59f0014
              ldr r0, [pc, #0x14]
 4: e3a01001
              mov r1, #1
 8: e5801000
              str r1, [r0]
 c: e59f000c
              ldr r0, [pc, #0x0c]
10: e3a01601
              mov r1, #0x100000
14: e5801000
              str r1, [r0]
              b 18 // [pc, -2*4]
18: eafffffe
1c: 20200008
20: 2020001c
```