

# **Concepts So Far**

**ARM processor and memory architecture**

**ARM assembly language and machine code**

**Raspberry Pi peripherals and GPIO**

**C**

- **Relationship between C statements and assembly language instructions**
- **Relationship between C types and allocation of data in memory (including pointers)**

# Where Are We Going?

## Functions (today)



**Modules and libraries: combining files using the linker**

**Memory management: loading the program into memory and allocating memory while running**

**Communication: Serial protocol and ASCII, boot loader, printf**

**Bare metal stuff: cooler stuff from PAL and DE**

# Anatomy of C Function

```
int factorial(int n)
{
    int product = 1;
    for (int i = 2; i <= n; i++)
        product *= i;
    return product;
}
```

**Call and return**

**Pass arguments**

**Return value**

**Local variables**

***Complication:***

***nested function calls***

# **Call and Return**

**// excerpted from blink.s**

**loop:**

**ldr r0, =SET0       // set pin high**

**str r1, [r0]**

**mov r2, #DELAY     // delay**

**subs r2, #1**

**bne .-4**

**ldr r0, =CLR0       // set pin low**

**str r1, [r0]**

**mov r2, #DELAY     // delay**

**subs r2, #1**

**bne .-4**

**b loop**

```
ldr r0, =SET0
str r1, [r0]
b delay
ldr r0, =CLR0
str r1, [r0]
b delay
b loop
```

delay:

```
mov r2, #DELAY
subs r2, #1
bne .-4
```

// but...

how to return when loop finished?

```
ldr r0, =SET0
str r1, [r0]
mov r14, pc // note that pc=.+8
b delay
ldr r0, =CLR0
str r1, [r0]
mov r14, pc
b delay
b loop
```

delay:

```
mov r2, #DELAY
subs r2, #1
bne .-4
mov pc, r14
```

```
ldr r0, =SET0
str r1, [r0]
mov r0, #DELAY
mov r14, pc
b delay
ldr r0, =CLR0
str r1, [r0]
mov r0, #DELAY
mov r14, pc
b delay
b loop
```

delay:

```
subs r0, #1
bne .-4
mov pc, r14
```



**// Call and Return**

**// b - branch**

**// New variations of branch**

**// branch and link (call)**

**b~~l~~ delay // pc=delay, lr=.<sup>+</sup>4 (=pc-4)**

**// branch to address in reg lr (return)**

**b~~x~~ lr // pc=lr**

# **Arguments and Return Values**

...

**mov r0, #DELAY**

**bl delay**

...

**// Conventions**

**r0-r3 used to pass values as arguments**

**r0-r1 used to return values**

# **ABI**

**ABI = Application Binary Interface**

**Conventions for calling functions**

**Allows different languages to  
interoperate**

**ARM uses extended-ABI (eabi) as in arm-  
none-eabi**

# Callers and Callees

## Nomenclature

- ***caller*** - function doing the calling
- ***callee*** - function called

# Register Ownership

**r0-r3 callee-owned registers**

- **Callee can change these registers**
- **Caller can not assume the values are the same as when the callee was called**

**r4-r13 are caller-owned registers**

- **Callee should not change these registers**
- **They should be the same when the function returns; callers assumes they are the same**

# Discuss

- 1. What does the callee need to do if it wants to use a register that the caller owns?**
- 2. What is the advantage of making most registers caller-owned?**
- 3. What happens to argument  $r0$  passed by the caller to the callee, if the callee calls another function that has an argument ( $r0$ )?**

# **Callee-Saved**

**1. The callee saves registers only if the callee needs to use them; if the callee does not use them, there is no need to save them**

**More efficient than having the caller save and restores all these registers**

**2.  $r0$  will be overwritten when passing an argument; if callee still needs it, should save it**

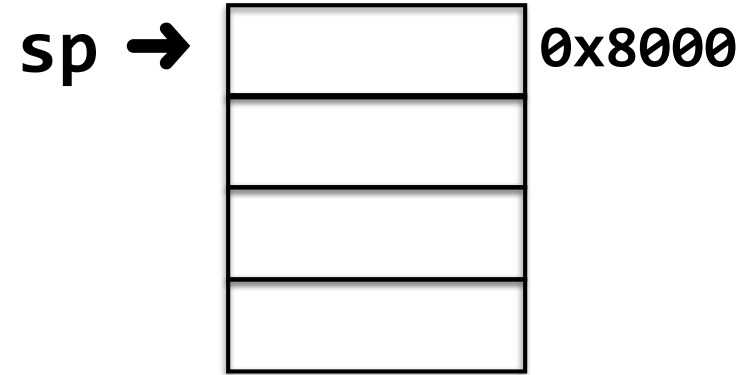
**Where does the callee save registers?**



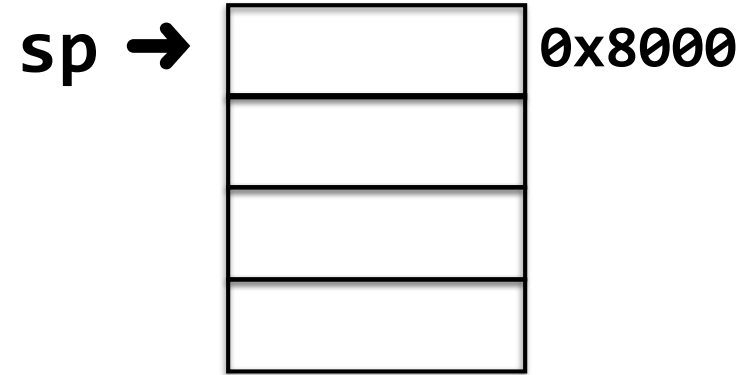
**Saving Registers**

**The Stack to the Rescue**

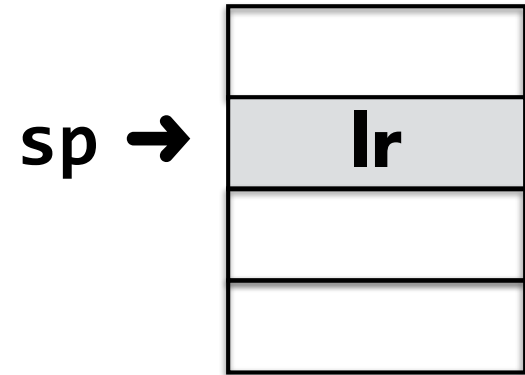
```
// start.s  
// unsigned *sp = 0x8000;  
mov sp, #0x8000
```



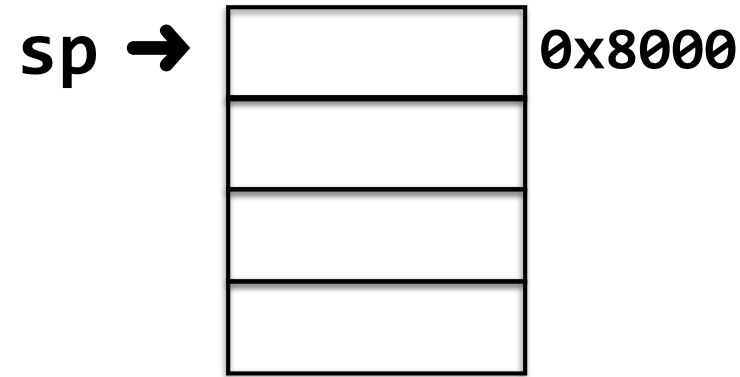
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// start.s
// unsigned *sp = 0x8000;
mov sp, #0x8000
```



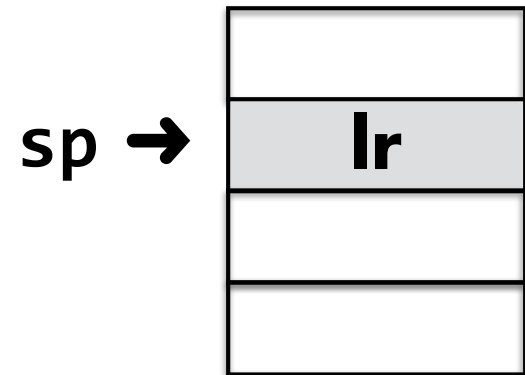
```
// push
// *--sp = lr
// decrement sp before store
str lr, [sp, #-4]!
push {lr}
```



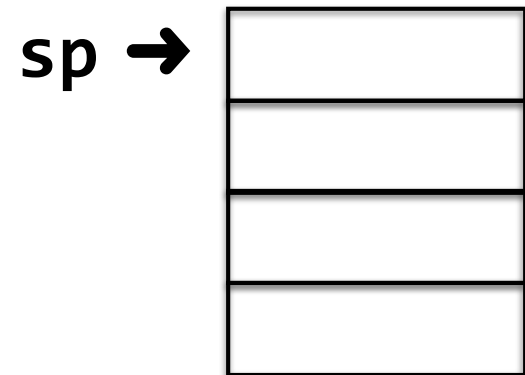
```
// start.s
// unsigned *sp = 0x8000;
mov sp, #0x8000
```

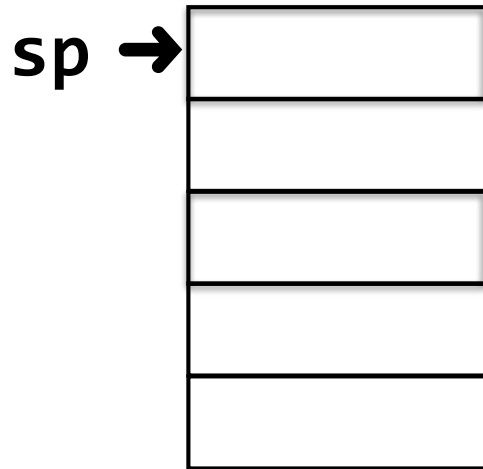


```
// push
// *--sp = lr
// decrement sp before store
str lr, [sp, #-4]!
push {lr}
```



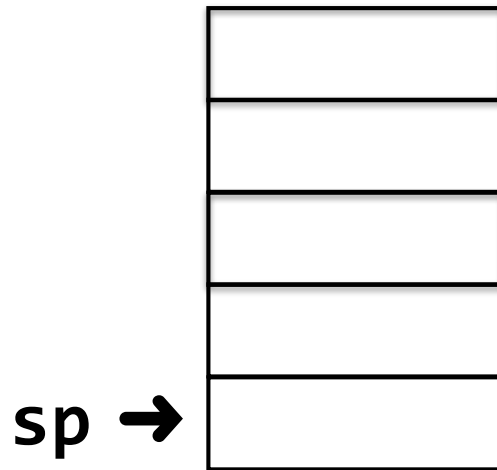
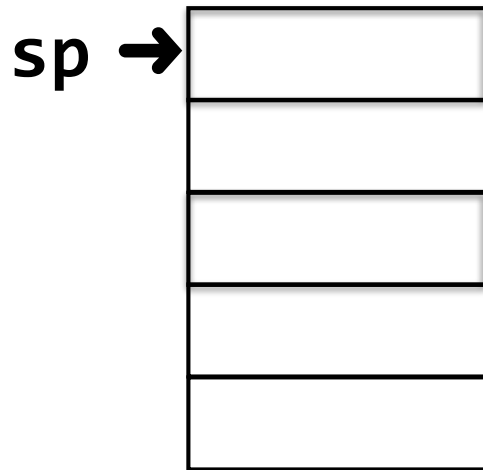
```
// pop
// lr = *sp++
// increment sp after load
pop {lr}
ldr lr, [sp], #4
```





```
int binky(int x)
{
    int y = x + 2;
    return y;
}
```

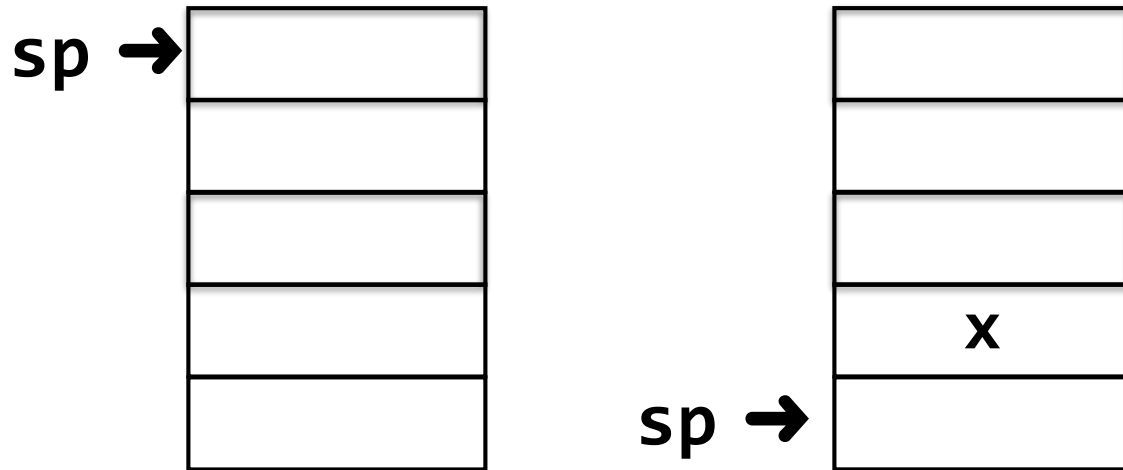
```
binky:
    sub sp, sp, #16
    str r0, [sp, #4]
    ldr r3, [sp, #4]
    add r3, r3, #2
    str r3, [sp, #12]
    ldr r3, [sp, #12]
    mov r0, r3
    add sp, sp, #16
    bx  lr
```



**EABI requires *sp* to be *aligned* to a multiple of 8**

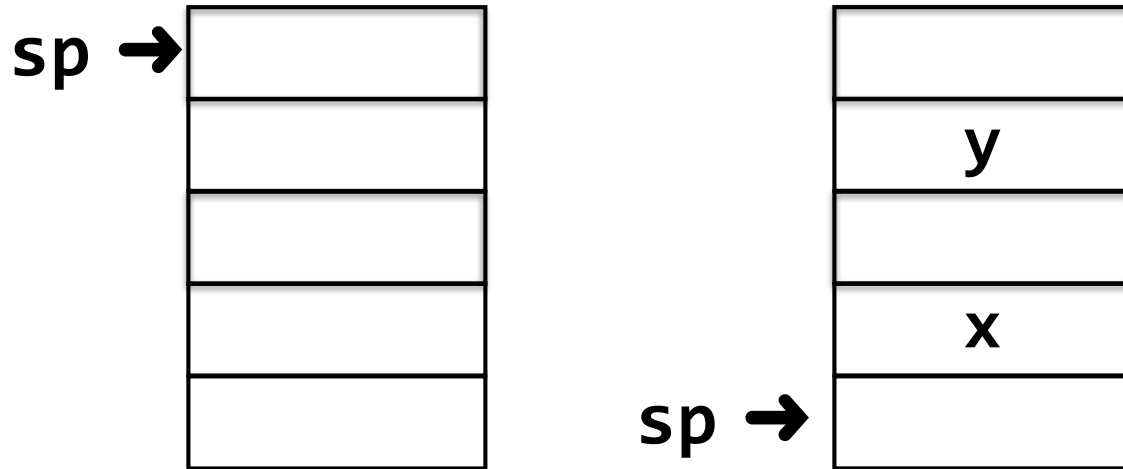
```
int binky(int x)
{
    int y = x + 2;
    return y;
}
```

```
binky:
    sub sp, sp, #16
    str r0, [sp, #4]
    ldr r3, [sp, #4]
    add r3, r3, #2
    str r3, [sp, #12]
    ldr r3, [sp, #12]
    mov r0, r3
    add sp, sp, #16
    bx  lr
```



```
int binky(int x)
{
    int y = x + 2;
    return y;
}
```

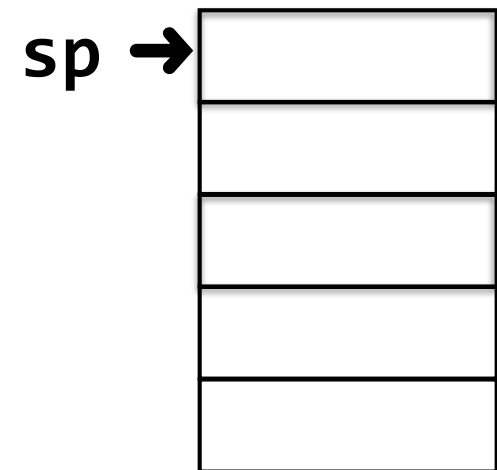
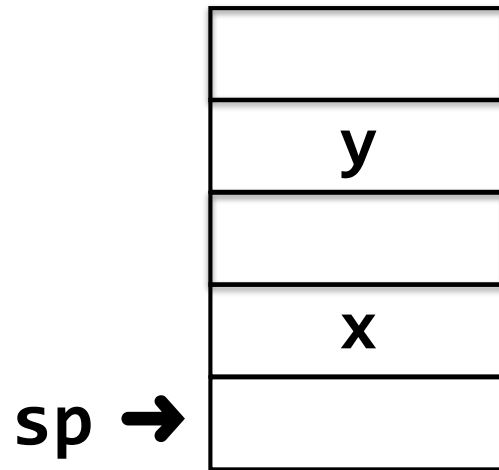
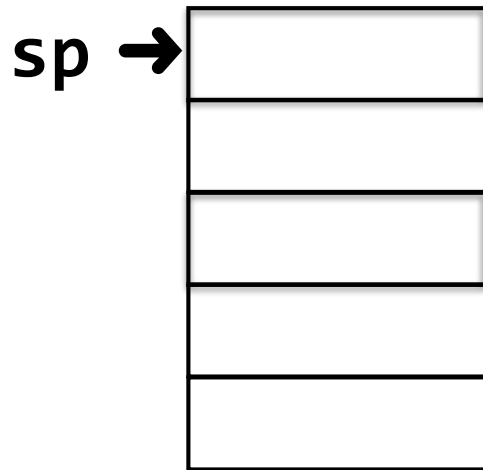
```
binky:
    sub sp, sp, #16
    str r0, [sp, #4]
    ldr r3, [sp, #4]
    add r3, r3, #2
    str r3, [sp, #12]
    ldr r3, [sp, #12]
    mov r0, r3
    add sp, sp, #16
    bx  lr
```



```
int binky(int x)
{
    int y = x + 2;
    return y;
}
```

```
binky:
    sub sp, sp, #16
    str r0, [sp, #4]
    ldr r3, [sp, #4]
    add r3, r3, #2
    str r3, [sp, #12]
    ldr r3, [sp, #12]
    mov r0, r3
    add sp, sp, #16
    bx  lr
```





```
int binky(int x)
{
    int y = x + 2;
    return y;
}
```

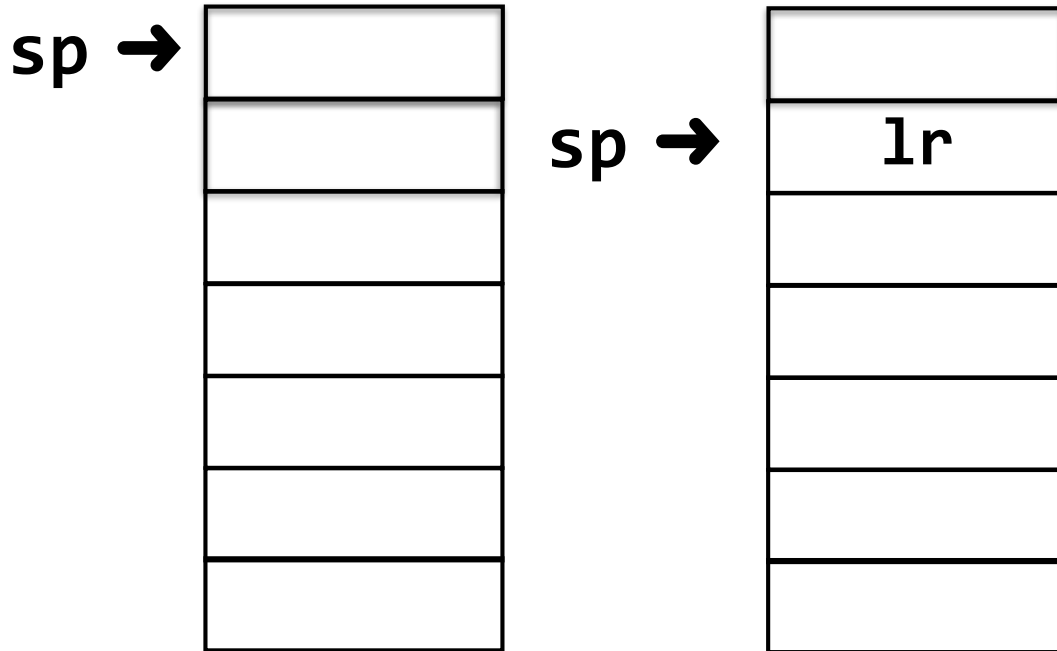
```
binky:
    sub sp, sp, #16
    str r0, [sp, #4]
    ldr r3, [sp, #4]
    add r3, r3, #2
    str r3, [sp, #12]
    ldr r3, [sp, #12]
    mov r0, r3
    add sp, sp, #16
    bx lr
```

```
// call binky inside winky
```

```
int winky(int x)
{
    int y = binky(x+1);
    return x+y;
}
```

```
// What happens to lr
//    when you call binky?
```

**Problem: lr changes**



**Solution: push/pop lr**

**winky:**

**push {lr}**

sub sp, sp, #20

str r0, [sp, #4]

ldr r3, [sp, #4]

add r3, r3, #1

mov r0, r3

bl binky

str r0, [sp, #12]

ldr r2, [sp, #4]

ldr r3, [sp, #12]

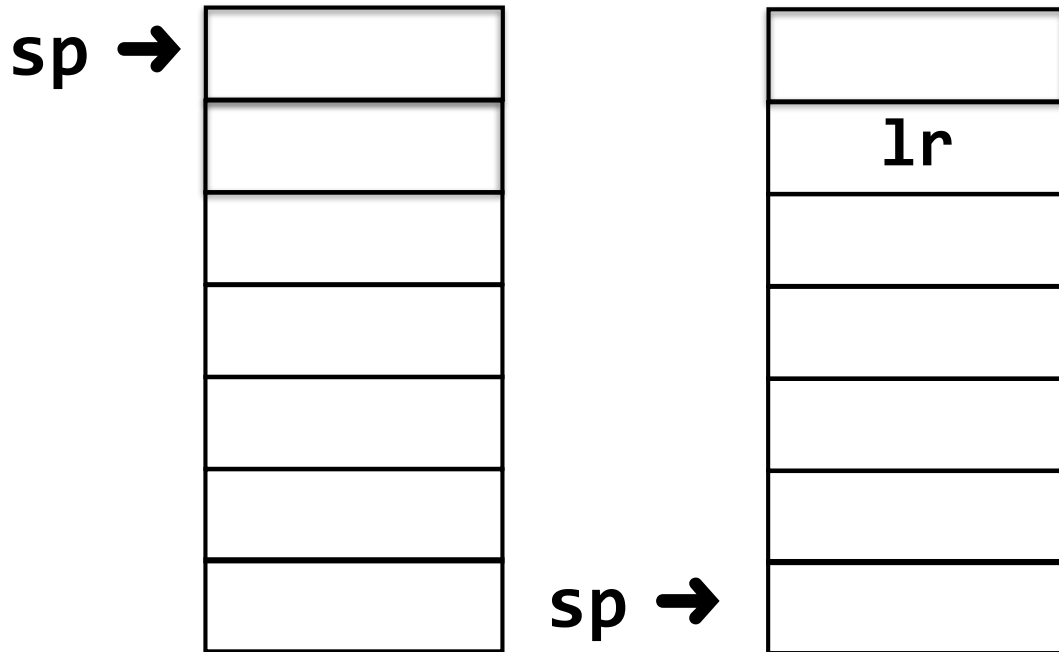
add r3, r2, r3

mov r0, r3

add sp, sp, #20

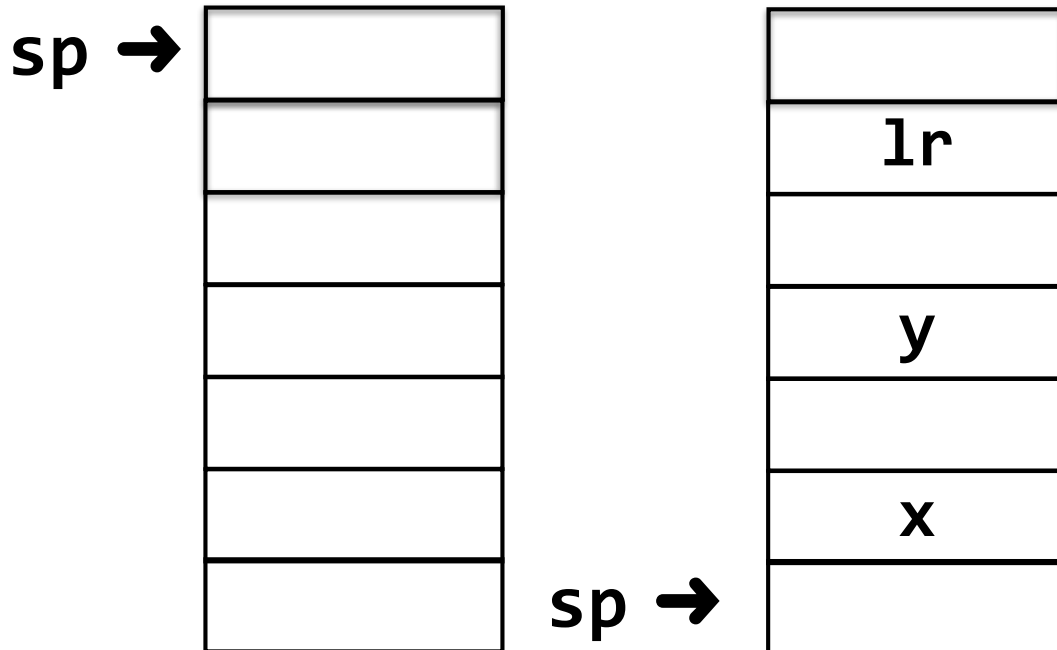
**pop {lr}**

bx lr



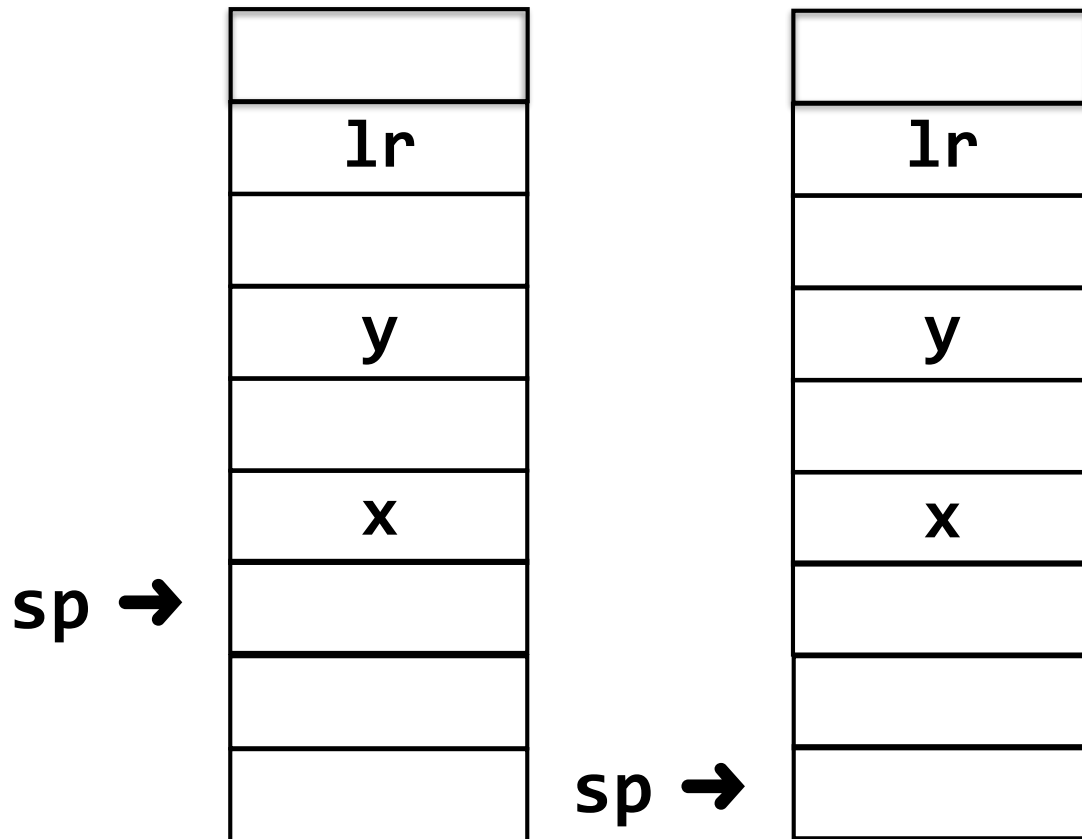
**winky:**

```
push {lr}
sub sp, sp, #20
str r0, [sp, #4]
ldr r3, [sp, #4]
add r3, r3, #1
mov r0, r3
bl binky
str r0, [sp, #12]
ldr r2, [sp, #4]
ldr r3, [sp, #12]
add r3, r2, r3
mov r0, r3
add sp, sp, #20
pop {lr}
bx lr
```



**winky:**

```
push {lr}
sub sp, sp, #20
str r0, [sp, #4]
ldr r3, [sp, #4]
add r3, r3, #1
mov r0, r3
bl binky
str r0, [sp, #12]
ldr r2, [sp, #4]
ldr r3, [sp, #12]
add r3, r2, r3
mov r0, r3
add sp, sp, #20
pop {lr}
bx lr
```



What if sp changes?

winky:

```

push {lr}
sub sp, sp, #20
str r0, [sp, #4]
ldr r3, [sp, #4]
add r3, r3, #1
mov r0, r3
bl binky
str r0, [sp, #12]
ldr r2, [sp, #4]
ldr r3, [sp, #12]
add r3, r2, r3
mov r0, r3
add sp, sp, #20
pop {lr}
bx lr

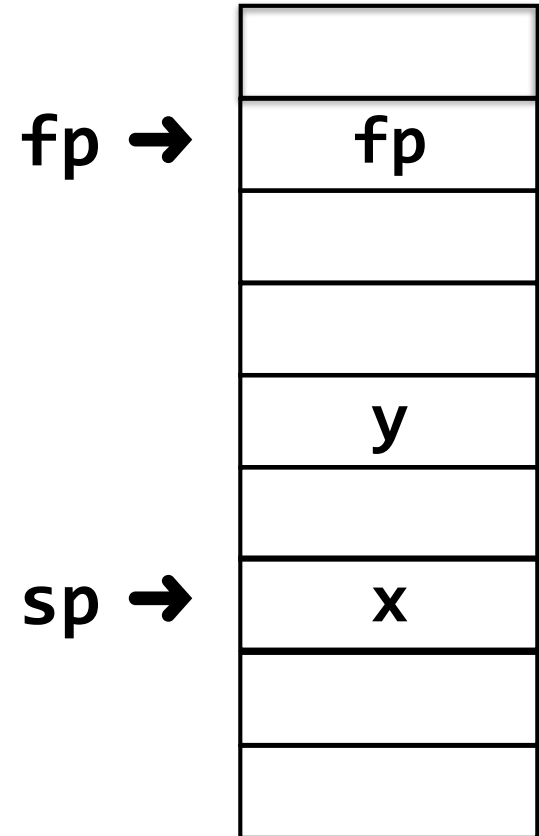
```

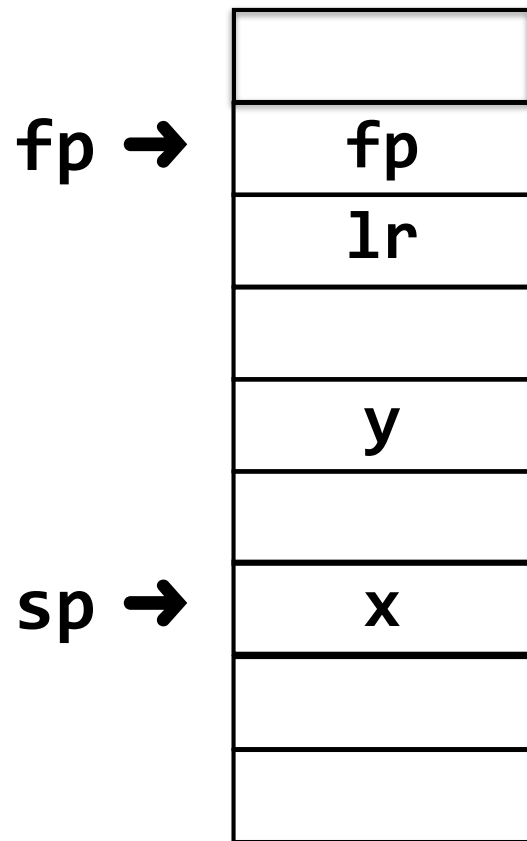
# The Frame Pointer (FP)

**Establish a stack *frame***

**Provides “anchor” for  
the local variables used  
by a function**

**Locals offset relative to  
fp**



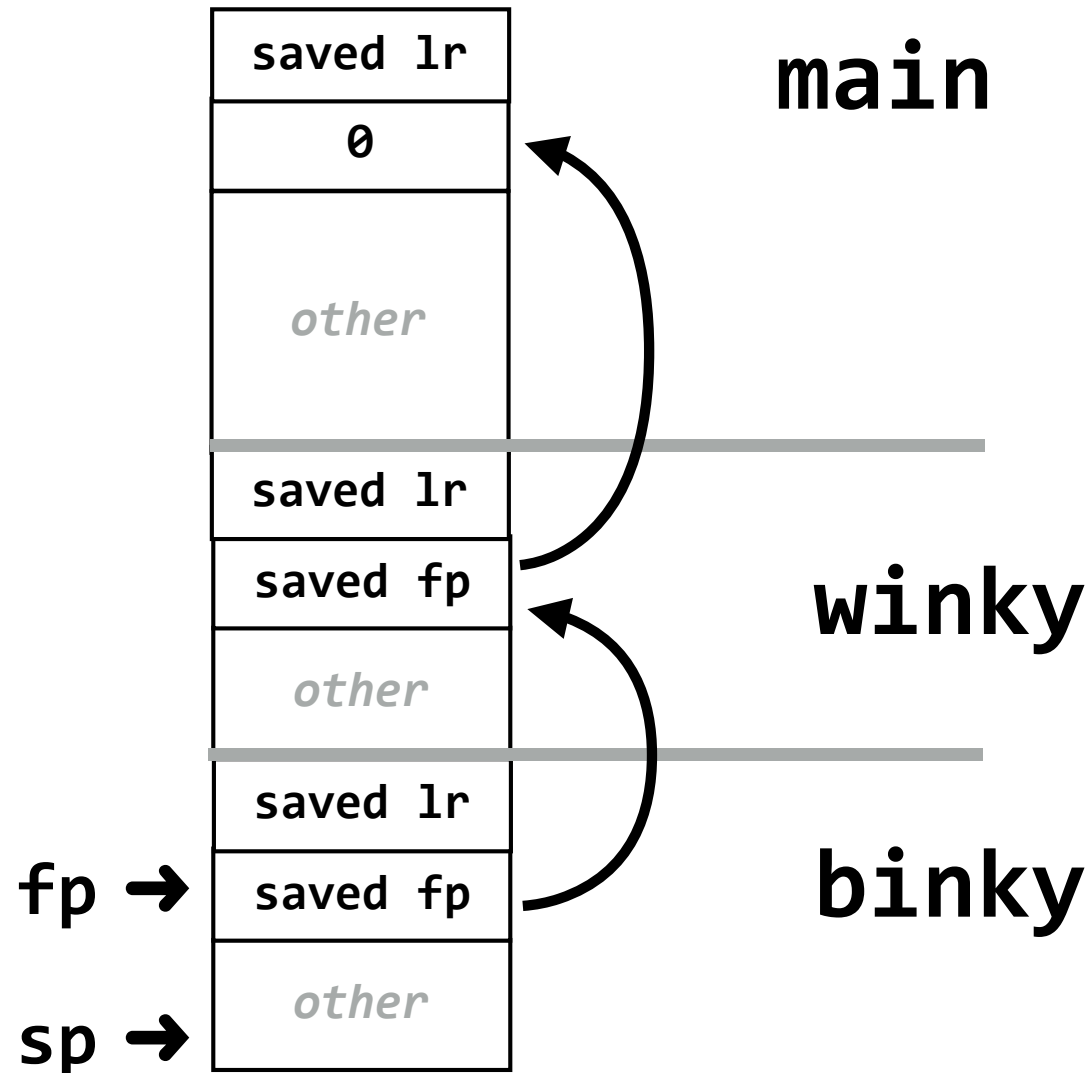


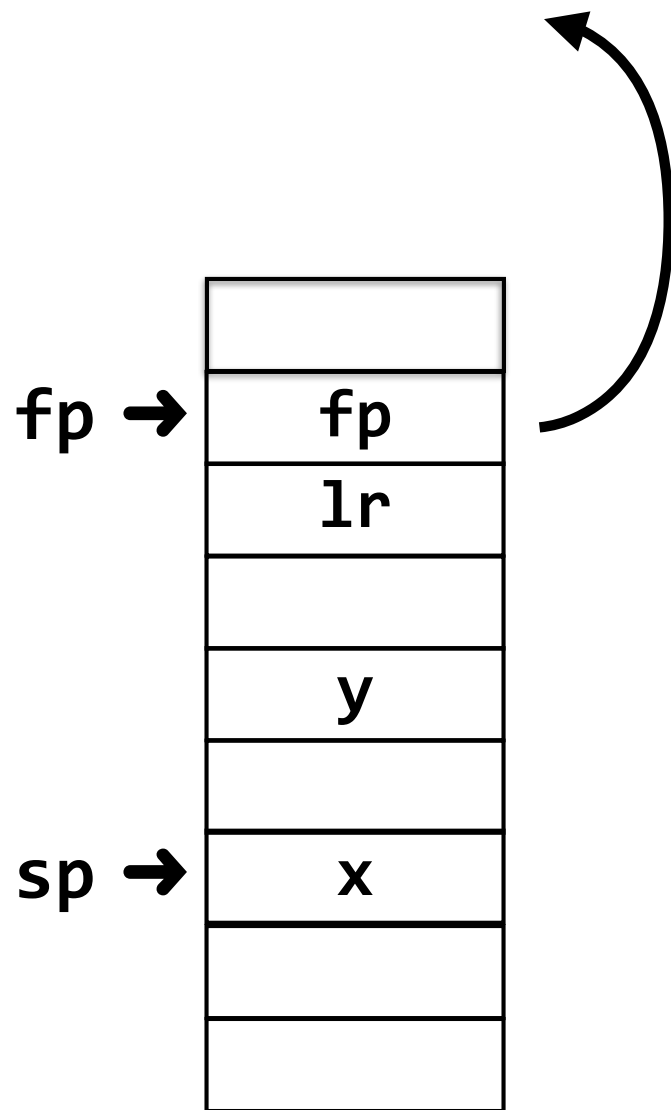
winky:

```
...  
str r0, [fp, #-16]  
ldr r3, [fp, #-16]  
add r3, r3, #1  
mov r0, r3  
bl binky  
str r0, [fp, #-8]  
ldr r2, [fp, #-16]  
ldr r3, [fp, #-8]  
add r3, r2, r3  
mov r0, r3  
...  
bx lr
```



# Create Linked List of Function Stack Frames





winky:

```
push {fp, lr}
add fp, sp, #4
sub sp, sp, #16
```

...

```
sub sp, fp, #4
pop {fp, lr}
bx lr
```

```
// start.s
```

```
// Need to initialize fp = NULL
```

```
.globl _start
```

```
_start:
```

```
    mov sp, #0x8000
```

```
    mov fp, #0 // fp=NULL
```

```
    bl main
```

```
hang:
```

```
    b hang
```

# **The Frame Pointer (FP)**

**Establishes a stack frame**

**Enables:**

- **Locals offset relative to fp (not sp, since sp may change)**
- **Backtrace for debugging**
- **Unwind stack on exception**

# Special Registers

**r4-r15 caller-owned, callee-save registers**

**r11 (fp) - special**

**r12 (ip) - special (scratch register)**

**r13 (sp) - special**

**r14 (lr) - special**

**r15 (pc) - special**

# Summary

## Calling functions:

- link register (lr)
- ABl: arguments and return values

**The stack and stack pointer (sp)**

**Stack frames and the frame pointer (fp)**

**Extra**

# ARM Addressing Modes

`str r0, [r1]` `// indirect`

Preindex, non-updating

`str r0, [r1, #4]` `// constant displacement`  
`str r0, [r1, r2]` `// variable displacement`  
`str r0, [r1, r2, lsl #4]` `// scaled index`

Preindex, writeback (update before use)

`str r0, [r1, #4]!` `// r1 pre-updated += 4`  
`str r0, [r1, r2]!`  
`str r0, [r1, r2, lsl #4]!`

Postindex (update after use)

`str r0, [r1], #4` `// r1 post-updated += 4`

...