

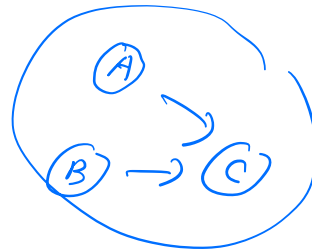
Dr

int a, b, c, d, e;

c = a + b ; // A

d = a + c ; // B

e = c + d ; // C



scheduler

A

B

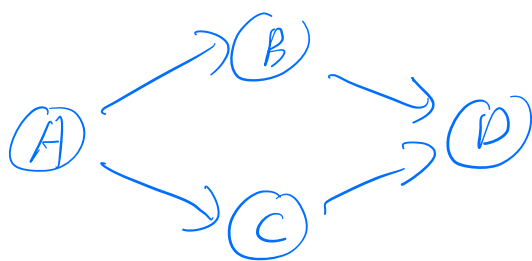
C

D

① build graph

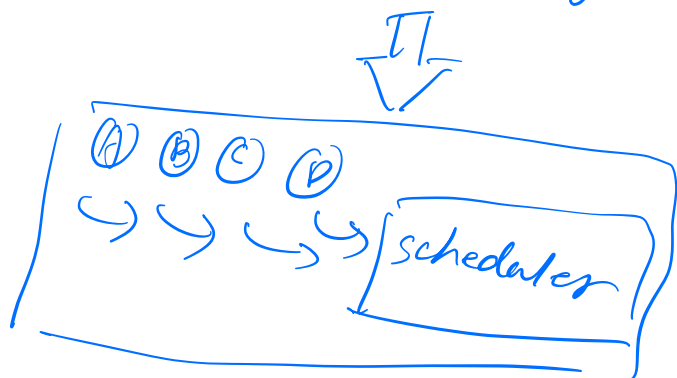
②

① Taskflow Workflow

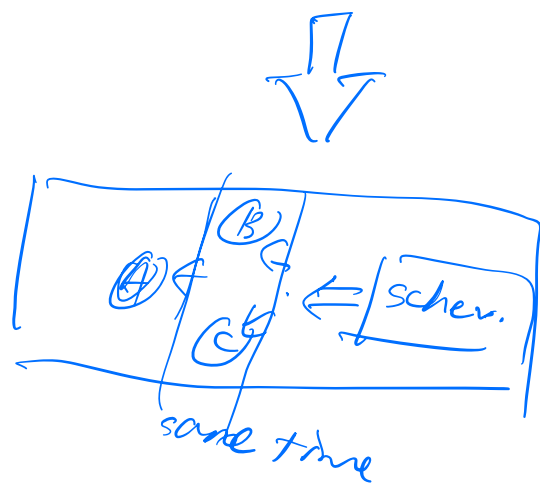


workflow

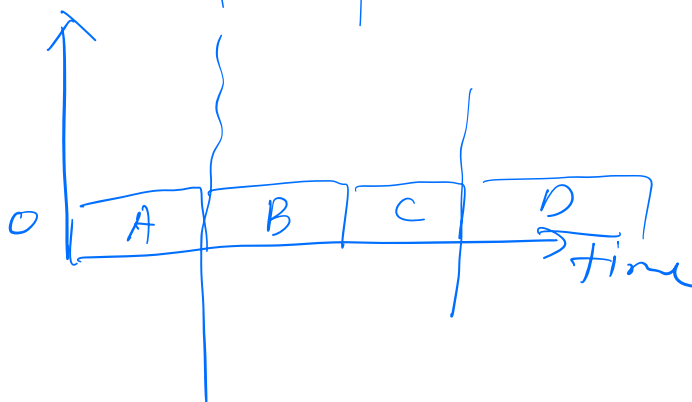
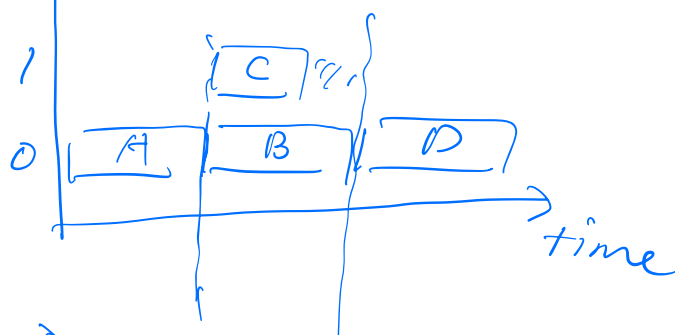
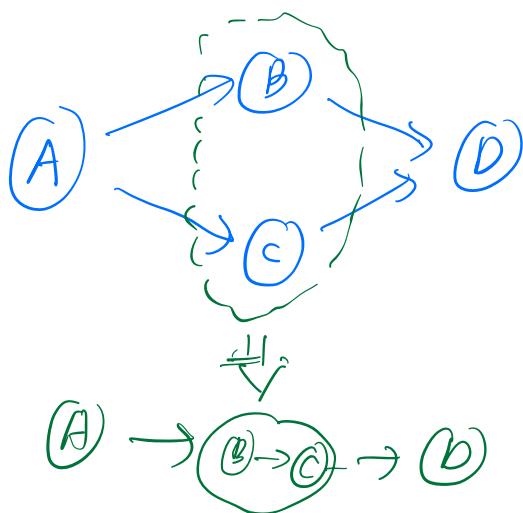
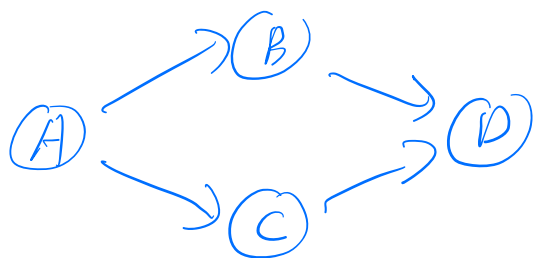
1. construct the graph → 2. execute the graph



i.e. scheduling

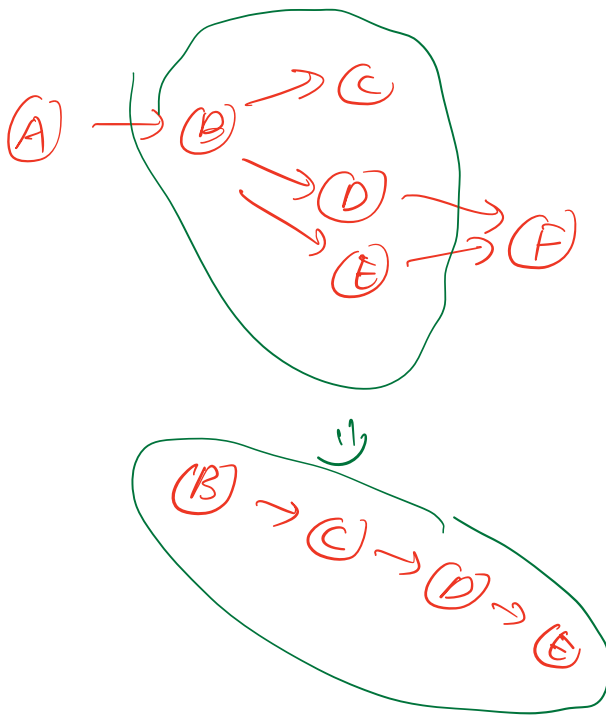
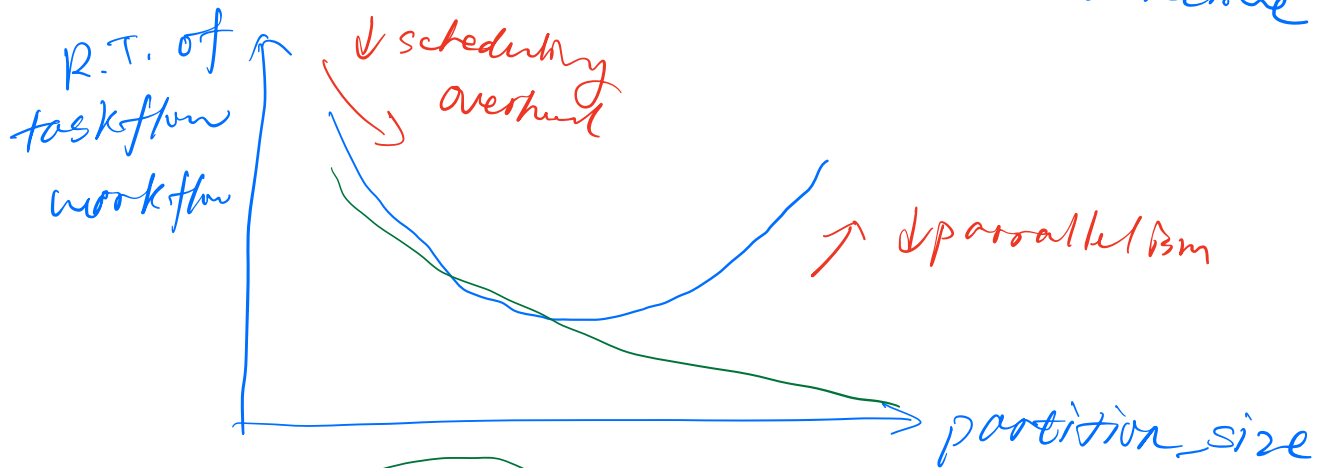


② scheduling overhead. \propto # tasks in our task graph threads



(3) trade-off : scheduling overhead vs parallelism

Assumption: Comparable scheduling overhead and task runtime



④ Task graph partitioning

task-graph based application
/ task-parallel

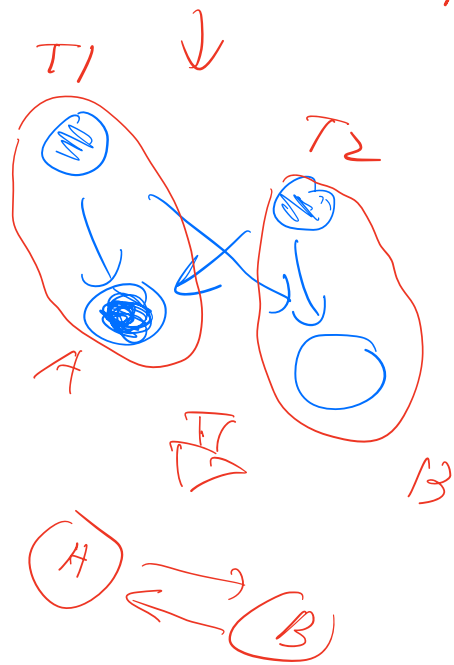
a. construct the graph → b. executing the graph

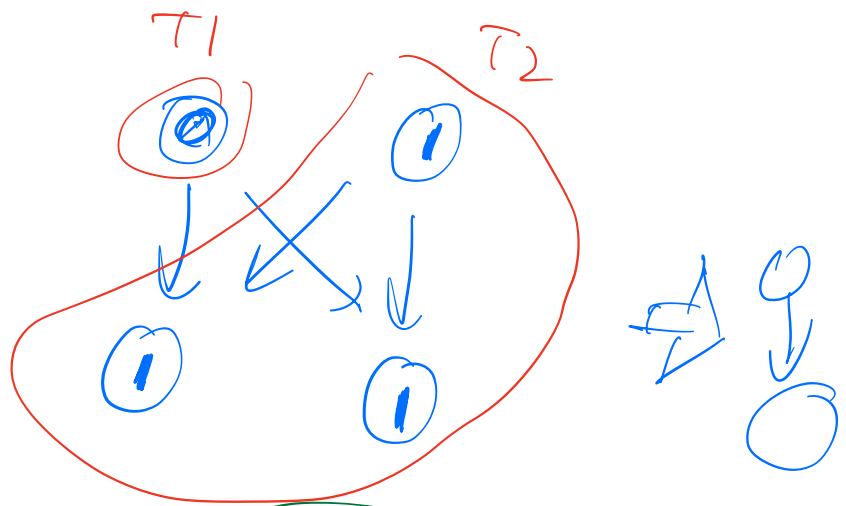


partition the graph

additional step
needs to be
fast

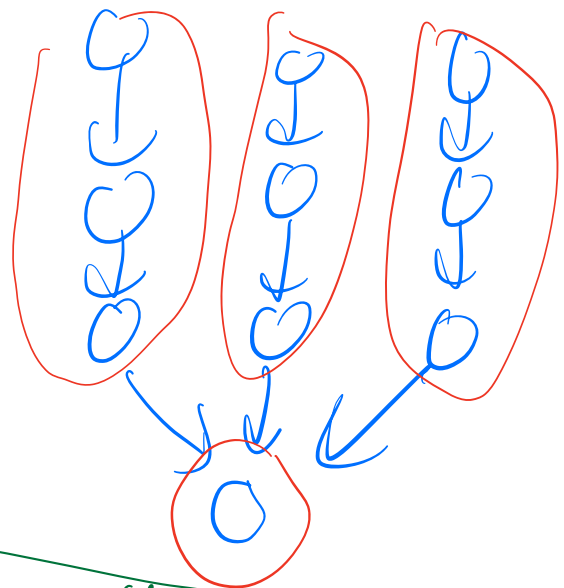
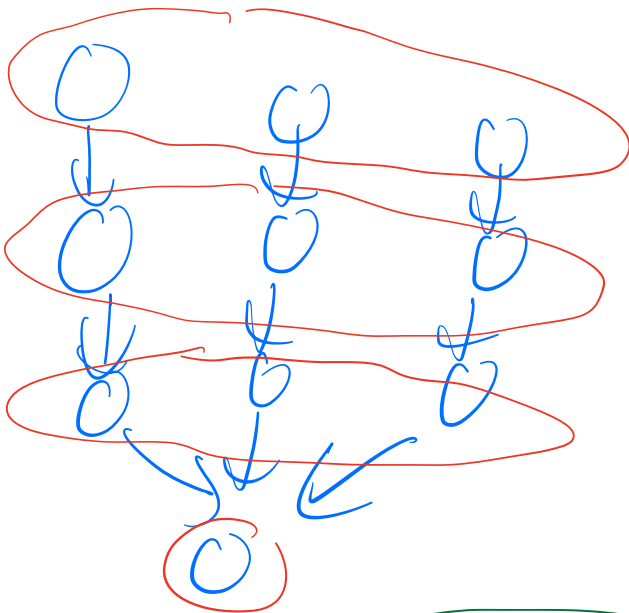
do it in parallel





no cycle

a task will always choose
the longest Par. 2D
from its dependents.



maintain parallelism
starts a different Par 2D

for each source node

Summary:

Partitioning Task Graph

- ① fast
 - ② no cycle
 - ③ maintain
parallelism
-