d) Gurobi-Python Problem 1

Global Maximum

```
In [ ]: from gurobipy import Model, GRB
         # Create a new model
         model = Model("Problem_1_max")
          # Define continuous variables
         x1 = model.addVar(lb=-GRB.INFINITY, name="x1")
          x2 = model.addVar(lb=-GRB.INFINITY, name="x2")
         x3 = model.addVar(lb=-GRB.INFINITY, name="x3")
         # Set the objective function: f(x) = 3*x1 + 5*x2 - 3*x3^2 model.setObjective(3*x1 + 5*x2 - 3*x3*x3, GRB.MAXIMIZE)
         {\it \# Add equality constraints using addQConstr since they are quadratic:}
         # Constraint 1: 2*x1^2 - 37*x2^2 + 9*x3 == 18
model.addQConstr(2*x1*x1 - 37*x2 + 9*x3 == 18, name="c1")
         # Constraint 2: 5*x1 + x2 + 5*x3^2 == 24
         model.addQConstr(5*x1 + x2 + 5*x3*x3 == 24, name="c2")
          # Optimize the model
         model.optimize()
          # Print the results
         if model.status == GRB.OPTIMAL:
            print("Optimal solution:")
print(f" x1 = {x1.x}")
print(f" x2 = {x2.x}")
print(f" x3 = {x3.x}")
              print(f"Optimal objective value = {model.objVal}")
         print("No optimal solution found.")
```

```
Gurobi Optimizer version 12.0.1 build v12.0.1rc0 (win64 - Windows 10.0 (19045.2))
CPU model: Intel(R) Core(TM) i7-10750H CPU @ 2.60GHz, instruction set [SSE2|AVX|AVX2]
Thread count: 6 physical cores, 12 logical processors, using up to 12 threads
Optimize a model with 0 rows, 3 columns and 0 nonzeros
Model fingerprint: 0x5cc95152
Model has 1 quadratic objective term
Model has 2 quadratic constraints
Coefficient statistics:
  Matrix range [0e+00, 0e+00]
                    [2e+00, 5e+00]
  OMatrix range
  QLMatrix range [1e+00, 4e+01]
  Objective range [3e+00, 5e+00]
CPU model: Intel(R) Core(TM) i7-10750H CPU @ 2.60GHz, instruction set [SSE2|AVX|AVX2]
Thread count: 6 physical cores, 12 logical processors, using up to 12 threads
Optimize a model with 0 rows, 3 columns and 0 nonzeros
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  QMatrix range
                    [2e+00, 5e+00]
  QLMatrix range [1e+00, 4e+01]
  Objective range [3e+00, 5e+00]
  QObjective range [6e+00, 6e+00]
  Bounds range [0e+00, 0e+00]
 RHS range [0e+ww, 00000]

Capus range [2e+01, 2e+01]
Continuous model is non-convex -- solving as a MIP
Presolve time: 0.00s
Presolved: 6 rows, 4 columns, 18 nonzeros
Presolved model has 2 bilinear constraint(s)
Warning: Model contains variables with very large bounds participating
         in product terms.
         Presolve was not able to compute smaller bounds for these variables.
         Consider bounding these variables or reformulating the model.
Variable types: 4 continuous, 0 integer (0 binary)
Found heuristic solution: objective 2257.5755700
Root relaxation: unbounded, 2 iterations, 0.00 seconds (0.00 work units)
                 Current Node | Objective Bounds
 Expl Unexpl | Obj Depth IntInf | Incumbent BestBd Gap | It/Node Time

        0
        postponed
        0
        2257.57557

        0
        postponed
        0
        2257.57557

        2
        postponed
        0
        2257.57557

        2
        19
        2257.5755740

                                                                              05
     0
                                                                  - -
                                                                              05
     0
                                                                              05
   97
                                                                  - 1.1
                                                                              0s
Explored 129 nodes (111 simplex iterations) in 0.05 seconds (0.00 work units)
Thread count was 12 (of 12 available processors)
Solution count 2: 2257.58 2257.58
Optimal solution found (tolerance 1.00e-04)
Best objective 2.257575573672e+03, best bound 2.257575573961e+03, gap 0.0000%
Ontimal solution:
  x1 = -97.16265952910427
  x2 = 509.8127734171107
  x3 = -0.010244122590746783
Optimal objective value = 2257.5755736720976
 Global Minimum
```

```
In [ ]: model = Model("Problem_1_min")
        # Define continuous variables
        x1 = model.addVar(lb=-GRB.INFINITY, name="x1")
        x2 = model.addVar(lb=-GRB.INFINITY, name="x2")
        x3 = model.addVar(lb=-GRB.INFINITY, name="x3")
        # Set the objective function: f(x) = 3*x1 + 5*x2 - 3*x3^2
        model.setObjective(3*x1 + 5*x2 - 3*x3*x3, GRB.MINIMIZE)
        # Add equality constraints using addOConstr since they are quadratic:
        # Constraint 1: 2*x1^2 - 37*x2^2 + 9*x3 == 18
        model.addQConstr(2*x1*x1 - 37*x2 + 9*x3 == 18, name="c1")
        # Constraint 2: 5*x1 + x2 + 5*x3^2 == 24
        model.addQConstr(5*x1 + x2 + 5*x3*x3 == 24, name="c2")
        # Optimize the model
        model.optimize()
        # Print the results
        if model.status == GRB.OPTIMAL:
```

```
print("Optimal solution:")
     print(f" x1 = {x1.x}")
print(f" x2 = {x2.x}")
print(f" x3 = {x3.x}")
     print(f"Optimal objective value = {model.objVal}")
     print("No optimal solution found.")
Gurobi Optimizer version 12.0.1 build v12.0.1rc0 (win64 - Windows 10.0 (19045.2))
CPU model: Intel(R) Core(TM) i7-10750H CPU @ 2.60GHz, instruction set [SSE2|AVX|AVX2]
Thread count: 6 physical cores, 12 logical processors, using up to 12 threads
Optimize a model with 0 rows, 3 columns and 0 nonzeros
Model fingerprint: 0x3e262e42
Model has 1 quadratic objective term
Model has 2 quadratic constraints
Coefficient statistics:
                  [0e+00, 0e+00]
  Matrix range
  QMatrix range
                    [2e+00, 5e+00]
 QLMatrix range [1e+00, 4e+01]
Objective range [3e+00, 5e+00]
  QObjective range [6e+00, 6e+00]
  Bounds range [0e+00, 0e+00]

RHS range [0e+00, 0e+00]

QRHS range [2e+01, 2e+01]
Continuous model is non-convex -- solving as a MIP
Presolve time: 0.00s
Presolved: 6 rows, 4 columns, 18 nonzeros
Presolved model has 2 bilinear constraint(s)
Warning: Model contains variables with very large bounds participating
         in product terms.
         Presolve was not able to compute smaller bounds for these variables.
         Consider bounding these variables or reformulating the model.
Variable types: 4 continuous, 0 integer (0 binary)
Found heuristic solution: objective -51.9570140
Root relaxation: unbounded, 2 iterations, 0.00 seconds (0.00 work units)
            | Current Node | Objective Bounds
    Nodes
                                                                         Work
 Expl Unexpl | Obj Depth IntInf | Incumbent BestBd Gap | It/Node Time
          0 postponed 0 -51.95701
0 postponed 0 -51.95701
2 postponed 0 -51.95701
                                                                              0s
     0
     0
Explored 45 nodes (70 simplex iterations) in 0.06 seconds (0.00 work units)
Thread count was 12 (of 12 available processors)
Solution count 1: -51.957
Optimal solution found (tolerance 1.00e-04)
Best objective -5.195701399667e+01, best bound -5.195719131412e+01, gap 0.0003%
Optimal solution:
  x1 = -10.14600494474171
  x2 = 4.1641099413894915
  x3 = -3.756751649559144
```

Results Discussion

Optimal objective value = -51.95701399667372

The Gurobi Solver returns the global optima for the problems. As we stated in the previous questions, points xB and xD were global optima, and these Gurobi solutions directly correspond to them.

• Global Maximum:

```
x_1 = -97.16, \quad x_2 = 509.81, \quad x_3 = -0.01024
```

Global Minimum:

```
x_1 = -10.15, \quad x_2 = 4.164, \quad x_3 = -3.7568
```

This demonstrates the consistency of both approaches (symbolic analysis via MATLAB and numerical optimization via Gurobi) in identifying the correct optimal solutions. Nevertheless, in the Gurobi–Python approach, constraint qualifications are assumed to hold (or are enforced implicitly).

c) Gurobi-Python Problem 2

```
In [ ]: # Create a new model
model = Model("Problem_2_max")

# Define continuous variables
x1 = model.addVar(lb=-GRB.INFINITY, name="x1")
x2 = model.addVar(lb=-GRB.INFINITY, name="x2")
x3 = model.addVar(lb=-GRB.INFINITY, name="x3")

# Set the objective function: f(x) = 3*x1 + 5*x2 - 3*x3^2
```

```
model.setObjective(x1*x1 + x2*x2 - x3*x3, GRB.MAXIMIZE)
# Add equality constraints using addQConstr since they are quadratic:
# Constraint 1: 2*x1^2 - 37*x2^2 + 9*x3 == 18
model.addQConstr(8*x1*x1 + 24*x2 - 15*x3 <= 129, "c1")
# Constraint 2: 5*x1 + x2 + 5*x3^2 == 24
model.addQConstr(-x1*x1 - 2*x2*x2 - 4*x3*x3 <= -15, "c2")
# Optimize the model
model.optimize()

# Print the results
if model.status == GRB.OPTIMAL:
    print("Optimal solution:")
    print(f" x1 = {x1.x}")
    print(f" x2 = {x2.x}")
    print(f" x2 = {x2.x}")
    print(f" x3 = {x3.x}")
    print(f"Optimal objective value = {model.objVal}")
else:
    print("No optimal solution found.")</pre>
```

CPU model: Intel(R) Core(TM) i7-10750H CPU @ 2.60GHz, instruction set [SSE2|AVX|AVX2]

Thread count: 6 physical cores, 12 logical processors, using up to 12 threads

Optimize a model with 0 rows, 3 columns and 0 nonzeros

Model fingerprint: 0x2382531e Model has 3 quadratic objective terms Model has 2 quadratic constraints

Coefficient statistics:

Matrix range [0e+00, 0e+00] QMatrix range [1e+00, 8e+00] QLMatrix range [2e+01, 2e+01]

CPU model: Intel(R) Core(TM) i7-10750H CPU @ 2.60GHz, instruction set [SSE2|AVX|AVX2]

Thread count: 6 physical cores, 12 logical processors, using up to 12 threads

Optimize a model with 0 rows, 3 columns and 0 nonzeros

Model fingerprint: 0x2382531e Model has 3 quadratic objective terms Model has 2 quadratic constraints

Coefficient statistics:

[0e+00, 0e+00] Matrix range [1e+00, 8e+00] QMatrix range QLMatrix range [2e+01, 2e+01] Objective range [0e+00, 0e+00] QObjective range [2e+00, 2e+00] Bounds range [0e+00, 0e+00] RHS range [0e+00, 0e+00] QRHS range [2e+01, 1e+02]

Continuous model is non-convex -- solving as a $\ensuremath{\mathsf{MIP}}$

Presolve time: 0.00s

Presolved: 10 rows, 8 columns, 24 nonzeros Presolved model has 3 bilinear constraint(s)

Warning: Model contains variables with very large bounds participating

in product terms.

Presolve was not able to compute smaller bounds for these variables. Consider bounding these variables or reformulating the model.

Variable types: 8 continuous, 0 integer (0 binary) Found heuristic solution: objective 47.4102564

Root relaxation: unbounded, 7 iterations, 0.00 seconds (0.00 work units) | Current Node | Objective Bounds

1	Expl	Unexpl	Obj	Depth Ir	ntInf	Incumbent	BestBd	Gap	It/Node	Time
	0	0	postpoi	ned 0		47.41026	-	-	-	0s
	0	0	postpoi	ned 0		47.41026	-	-	-	0s
	0	2	postpoi	ned 0		47.41026	-	-	-	0s
*	3			2	62	5000.00000	-	-	4.7	0s
*	8			3	75	0000.00000	-	-	3.1	0s
*	9			3		25000.0000	-	-	2.8	0s
*	13			4		50000.0000	-	-	2.8	0s
*	19			5		50000.0000	-	-	1.9	0s
*	21			6		50000.0000	-	-	1.7	0s
*	26			6		25000.0000	-	-	1.4	0s
*	40			7		50000.0000	-	-	0.9	0s
*	42			8		625000e+07	-	-	0.9	0s
*	44 49			9		225000e+07	-	-	0.8	0s
*	49 67			10		412500e+07 425000e+07			0.8 0.6	0s 0s
*	69			11		282500e+07	-	-	0.5	0s
*	74			11		561250e+08	_	_	0.5	0s
*	106			12		562500e+08	_	_	0.4	0s
*	108			13		122500e+08	_	_	0.4	0s
*	110			14		024250e+09	_	_	0.4	0s
*	112			15		048250e+09	_	_	0.4	0s
*	114			16		096250e+09	_	_	0.4	0s
*	149			19		098000e+09	-	_	0.4	0s
*	165	40		19	8.	193000e+09	_	_	0.3	0s
*	193	38		24	8.	224000e+09	_	_	0.3	0s
*	195	38		25	1.	641600e+10	-	-	0.3	0s
*	230	38		22	3.	277000e+10	-	-	0.3	0s
*	232	38		23	6.	553800e+10	-	-	0.3	0s
*	234	38		24	1.	310740e+11	-	-	0.3	0s
*	236			25		621460e+11	-	-	0.3	0s
*	278	44		29	2.	621760e+11	-	-	0.2	0s
*	280			30		243200e+11	-	-	0.2	0s
*	282			31		048608e+12	-	-	0.2	0s
*	284			32		097184e+12	-	-	0.2	0s
*	359			33		097216e+12	-	-	0.3	0s
*	361			33		194336e+12	-	-	0.3	0s
*	363			34		388640e+12	-	-	0.3	0s
*	365			35		677725e+13	-	-	0.2	0s
*	367			36		355446e+13	-	-	0.2	0s
	369			37		710890e+13	-	-	0.2	0s
H *	371			4.4		551109e+14	-	-	0.2	0s
*	547 592			44 42		113881e+14 368710e+14	-	_	0.2 0.2	0s 0s
*	749			42		368710e+14 368719e+14	-	_	0.3	0s 0s
	1017			45		710886e+19	_	_	0.2	0s
111	TOT	40			0.	, 10000E+13	-	-	0.2	62

```
Explored 2249 nodes (235 simplex iterations) in 0.12 seconds (0.01 work units) Thread count was 12 (of 12 available processors)

Solution count 10: 6.71089e+19 5.36872e+14 5.36871e+14 ... 2.56125e+08

Optimal solution found (tolerance 1.00e-04)

Best objective 6.710886188749e+19, best bound 6.710886188749e+19, gap 0.0000\%

Optimal solution:

x1 = -32000.0

x2 = -8191999871.0

x3 = 0.0

Optimal objective value = 6.710886188748802e+19
```

Results Discussion

The enormous solution returned by Gurobi confirms what we observed in MATLAB. The problem is unbounded.

Our MATLAB analysis showed that there is no finite maximum since the objective can be increased without bound over the feasible set. There is no point at which all the 1st-order conditions (KKT) and 2nd-order conditions hold in such a way that a maximum is reached; rather, you can always find a feasible direction along which f(x) increases. Consequently, Gurobi, when solving the model without imposing artificial bounds, returns an enormous solution as it essentially drives the objective value toward infinity, thereby demonstrating that no finite optimal solution exists.