

$\hat{\theta}_{MAP} := \underset{\theta \in \Theta_0}{\operatorname{argmax}} \left\{ P(\theta|x) \right\}$ is one of three Bayesian point estimates we will study in this class

maximum a posteriori

after data

$\mathcal{X} = \text{iid Bern}(\theta), n=3, x = \langle 0, 1, 1 \rangle, \Theta_0 = \{0.5, 0.75\}$

$$x \in \mathcal{X} = \{0, 1\} \times \{0, 1\} \times \{0, 1\}$$

	\mathcal{X}							
$\theta = 0.75$	$\langle 1, 1, 1 \rangle$	$\langle 1, 1, 0 \rangle$	$\langle 1, 0, 1 \rangle$	$\langle 0, 1, 1 \rangle$	$\langle 1, 0, 0 \rangle$	$\langle 0, 1, 0 \rangle$	$\langle 0, 0, 1 \rangle$	0.5
$\theta = 0.5$	1, 1, 1	1, 1, 0	1, 0, 1	0, 1, 1	1, 0, 0	0, 1, 0	0, 0, 1	0.5

principle of indifference

$$P(X = \langle 1, 1, 1 \rangle | \theta = 0.75) = 0.75^3 = 0.422$$

$$P(X = \langle 1, 1, 0 \rangle | \theta = 0.75) = 0.75^2 \cdot 0.25 = 0.141$$

$$P(X = \langle 1, 0, 1 \rangle | \theta = 0.75) = 0.75 \cdot 0.25^2 = 0.047$$

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$$P(X = \langle 0, 0, 0 \rangle | \theta = 0.75) = 0.25^3 = 0.016$$

$$P(X = \langle 1, 0, 0 \rangle | \theta = 0.75) P(\theta = 0.75) + P(X = \langle 1, 0, 0 \rangle | \theta = 0.5) P(\theta = 0.5) = 0.047 \cdot 0.75 + 0.125 \cdot 0.5 = 0.125$$

$$P(X = \langle 1, 0, 0 \rangle) = P(X = \langle 1, 0, 0 \rangle, \theta = 0.75) + P(X = \langle 1, 0, 0 \rangle, \theta = 0.5) = 0.125$$

$$P(\theta = 0.5 | X = \langle 1, 0, 0 \rangle) = \frac{P(\theta = 0.5, X = \langle 1, 0, 0 \rangle)}{P(X = \langle 1, 0, 0 \rangle)} = \frac{0.125 \cdot 0.5}{(0.047 + 0.125) \cdot 0.5} = \frac{0.125}{0.172} = 0.727$$

For discrete parameter spaces,

$$\sum_{\theta \in \Theta} P(\theta) = 1, \quad \sum_{\theta \in \Theta} P(\theta|x) = 1, \quad \sum_{\theta \in \Theta} P(x|\theta) = \text{could be anything}$$

$$P(\theta|x) = \frac{P(x, \theta)}{P(x)} \propto P(x, \theta) \propto P(x|\theta) P(\theta) \propto P(x|\theta) \quad \text{is constant (Laplace's idea)}$$

$$\hat{\theta}_{MAP} = \underset{\theta \in \Theta_0}{\operatorname{argmax}} \left\{ P(\theta|x) \right\} = \underset{\theta \in \Theta_0}{\operatorname{argmax}} \left\{ P(x|\theta) P(\theta) \right\} = \underset{\theta \in \Theta_0}{\operatorname{argmax}} \left\{ P(x|\theta) \right\} = \hat{\theta}_{MLE}$$

Let $\Theta_0 = \{0.1, 0.25, 0.5, 0.75, 0.9\}$, Laplace Prior

$$x = \langle 1, 1, 0 \rangle$$

$$P(X|\theta = 0.1) = 0.1^2 \cdot 0.9 = 0.009$$

$$P(X|\theta = 0.25) = 0.25^2 \cdot 0.75 = 0.047$$

$$P(X|\theta = 0.5) = 0.125$$

$$P(X|\theta = 0.75) = 0.141$$

$$P(X|\theta = 0.9) = 0.081$$

	\mathcal{X}			
0.1				
0.25	0.009			
0.5		0.125		
0.75			0.141	
0.9		0.081		

Θ_0

$$\hat{\theta}_{MAP} = 0.75$$

$$\hat{\theta}_{MLE} \notin \Theta_0$$

$$P(\theta = 0.75 | X = \langle 1, 1, 0 \rangle) = \frac{0.141}{0.009 + 0.047 + 0.125 + 0.141 + 0.081} = \frac{0.141}{0.383} = 0.368$$

Let's examine Laplace's prior under many different parameter spaces approaching the full space.

$$\Theta_{0,3} = \left\{ \frac{1}{4}, \frac{1}{2}, \frac{3}{4} \right\} \Rightarrow P(\theta) = U(\Theta_0) = \left\{ \frac{1}{3} \quad \forall \theta \right\}$$

$$\Theta_{0,4} = \left\{ \frac{1}{10}, \frac{2}{10}, \dots, \frac{9}{10} \right\} \Rightarrow P(\theta) = U(\Theta_0) = \left\{ \frac{1}{9} \quad \forall \theta \right\}$$

$$\Theta_{0,n} = \left\{ \frac{1}{n+1}, \frac{2}{n+1}, \dots, \frac{n}{n+1} \right\} \Rightarrow P(\theta) = U(\Theta_0) = \left\{ \frac{1}{n} \quad \forall \theta \right\}$$

$$\Theta_{0,1} = \lim_{n \rightarrow \infty} \Theta_{0,n} \Rightarrow P(\theta) = 0 \quad \forall \theta \quad \text{not a PMF!}$$

$$\lim_{n \rightarrow \infty} F_n(\theta) = F(\theta) = \theta \Rightarrow P(\theta) = F'(\theta) = 1 \Rightarrow P(\theta) = U(0,1) \quad \text{ie. Continuous}$$

$$\mathcal{X} = \text{iid Bern}(\theta), x = \langle 1, 1, 0 \rangle, P(\theta) = U(0,1)$$

$$P(\theta|x) = \frac{P(x|\theta) P(\theta)}{P(x)} = \frac{P(x|\theta)}{P(x)} = \frac{P(x|\theta)}{\int_{\Theta} P(x|\theta) d\theta} = \frac{P(x|\theta)}{\int_0^1 P(x|\theta) d\theta} = \frac{\theta^2(1-\theta)}{\int_0^1 \theta^2(1-\theta) d\theta}$$

$$= \frac{\theta^2(1-\theta)}{\left[\frac{\theta^3}{3} - \frac{\theta^4}{4} \right]_0^1} = 12 \theta^2(1-\theta)$$

$$\hat{\theta}_{MAP} = \underset{\theta \in \Theta_0}{\operatorname{argmax}} \left\{ 12 \theta^2(1-\theta) \right\} = \underset{\theta \in \Theta_0}{\operatorname{argmax}} \left\{ \theta^2(1-\theta) \right\}$$

$$= \underset{\theta \in \Theta_0}{\operatorname{argmax}} \left\{ 2 \theta(1-\theta) \right\} = \frac{2}{3}$$

$$P(\theta) \xrightarrow{x} P(\theta|x)$$

$$P(\theta > 0.5 | x) = \int_{0.5}^1 12 \theta^2(1-\theta) d\theta = 12 \left[\frac{\theta^3}{3} - \frac{\theta^4}{4} \right]_{0.5}^1 = 12 \left(\frac{1}{12} - \left(\frac{1}{24} - \frac{1}{64} \right) \right) = 0.688$$

We talked about the MAP Bayesian point estimate. Are there other measures of "best guess of θ " if you have the posterior distribution $P(\theta | X)$?

$$\hat{\theta}_{MSE} := E[\theta|x] = \underset{\theta \in \Theta_0}{\operatorname{argmin}} \left\{ E[\theta - \hat{\theta}]^2 | x \right\}$$

The minimum mean squared error Bayesian point estimate is the posterior mean (expectation). This is the default estimator.

In our case:

$$\hat{\theta}_{MSE} = \int_{\Theta} \theta P(\theta|x) d\theta = \int_0^1 \theta 12 \theta^2(1-\theta) d\theta = 12 \left[\frac{\theta^4}{4} - \frac{\theta^5}{5} \right]_0^1 = \frac{12}{20} = 0.6$$