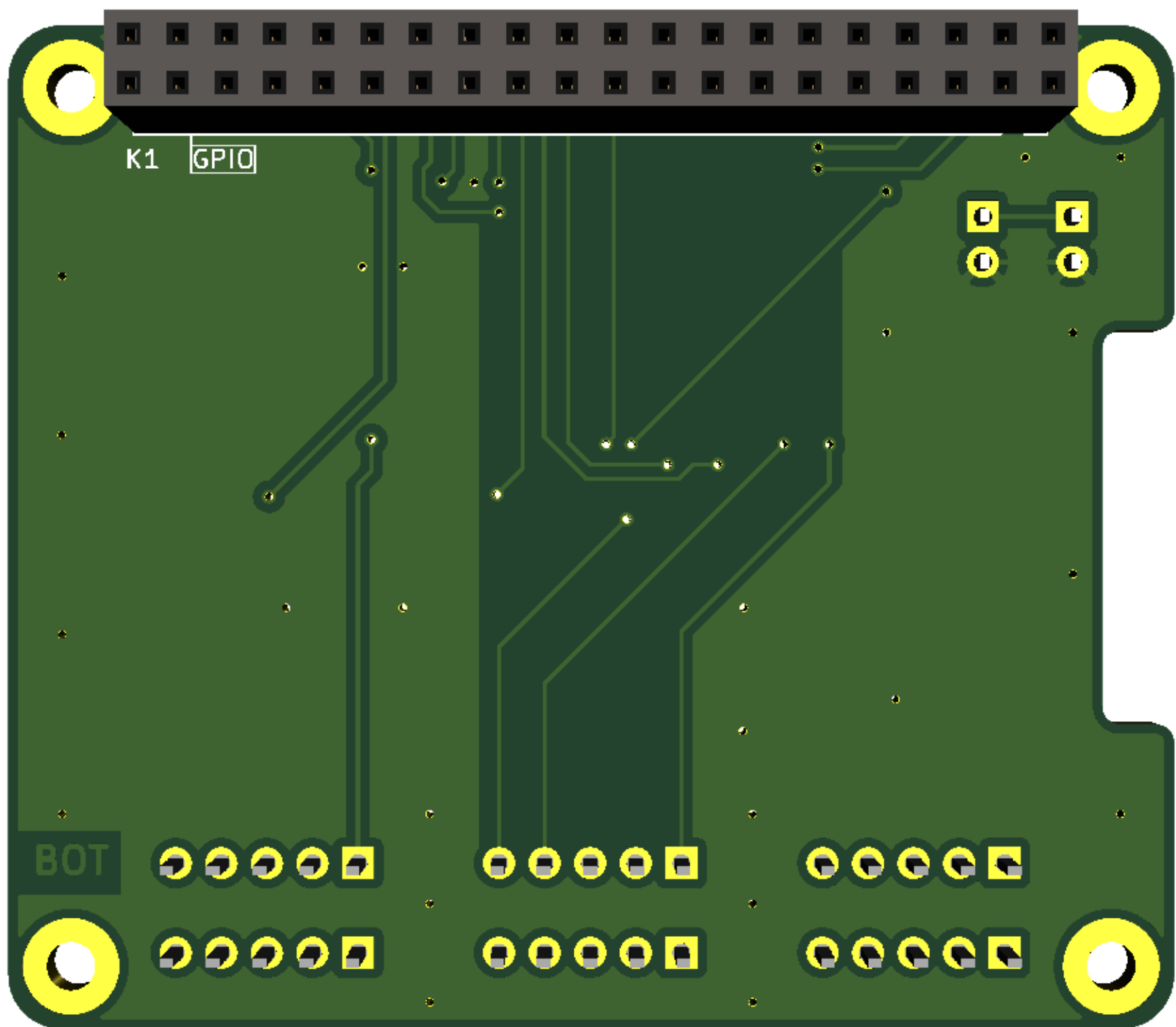
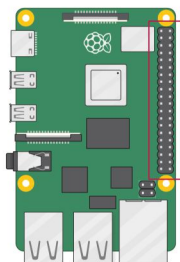


Raspberry Pi

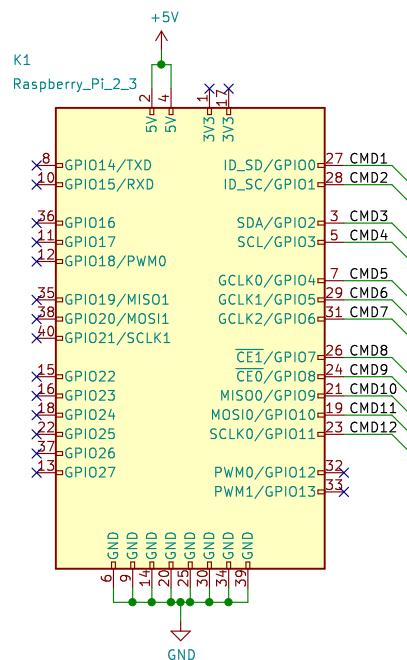
Conn	GPIO
X1	0 - 3
X2	4 - 7
X3	8 - 11

COM DRV9 DRV10 DRV11 DRV12 COM DRV5 DRV6 DRV7 DRV8 COM DRV1 DRV2 DRV3 DRV4

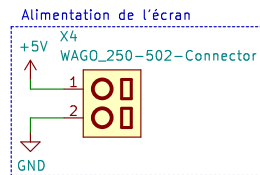
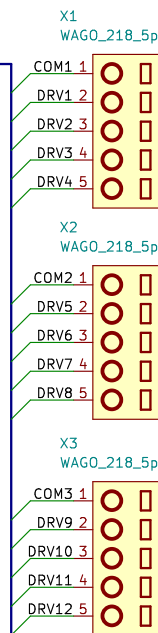
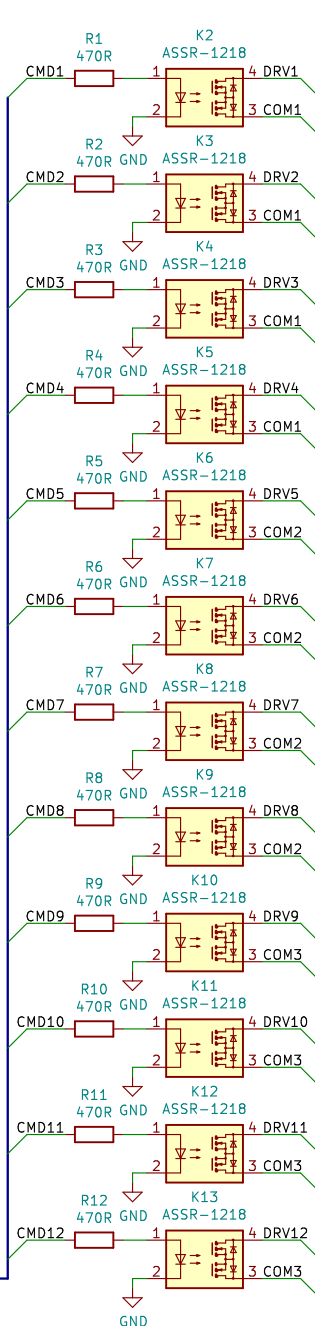




3V3 power	→	5V power
GPIO 2 (SDA)	→	5V power
GPIO 3 (SCL)	→	Ground
GPIO 4 (GCLK0)	→	GPIO 14 (TXD)
Ground	→	GPIO 15 (RXD)
GPIO 17	→	GPIO 18 (PCM_CLK)
GPIO 27	→	GPIO 23
GPIO 22	→	GPIO 24
3V3 power	→	Ground
GPIO 10 (MISO)	→	GPIO 25
GPIO 9 (MISO)	→	GPIO 8 (CE0)
GPIO 11 (SCLK)	→	GPIO 7 (CE1)
Ground	→	GPIO 1 (ID_SC)
GPIO 0 (ID_SD)	→	Ground
GPIO 5	→	Ground
GPIO 6	→	GPIO 12 (PWM0)
GPIO 13 (PWM1)	→	Ground
GPIO 19 (FS)	→	GPIO 16
GPIO 26	→	GPIO 20 (PCM_DIN)
Ground	→	GPIO 21 (PCM_DOUT)



Trous de fixation



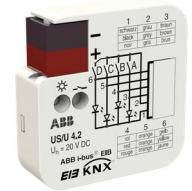
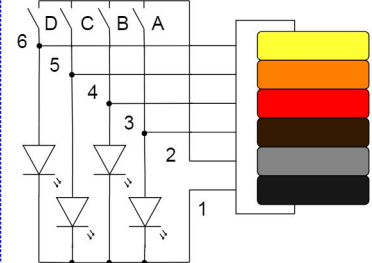
Dimensionnement R1 à R12

Pour $V_{cc} = 3.3V$
 $I_{min} = (V_{cc} - U_{fmax}) / R = 3.6 \text{ mA}$
 $I_{max} = (V_{cc} - U_{fmin}) / R = 4.7 \text{ mA}$

US/U 4.2

Connections

Gris : COM
 Brun : DRV1 --> A
 Rouge : DRV2 --> B
 Orange : DRV3 --> C
 Jaune : DRV4 --> D



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Sheet: /
 File: shield_octo.sch

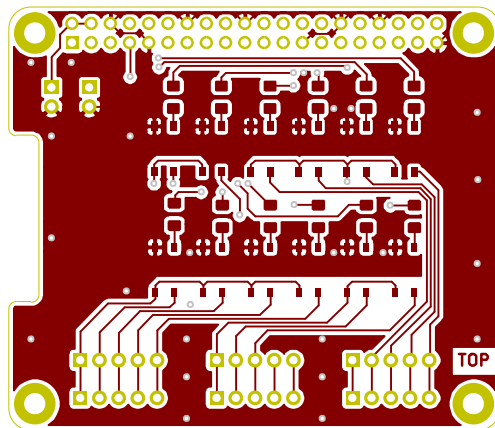
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Size: A4
 KiCad E.D.A. kicad (5.1.10)-1

Rev: 1
 Id: 1/1



TOP



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Center de formation, Force Aérienne, Base Aérienne, PAY

Sheet:

File: shield_octo.kicad_pcb

Title: shieLocto

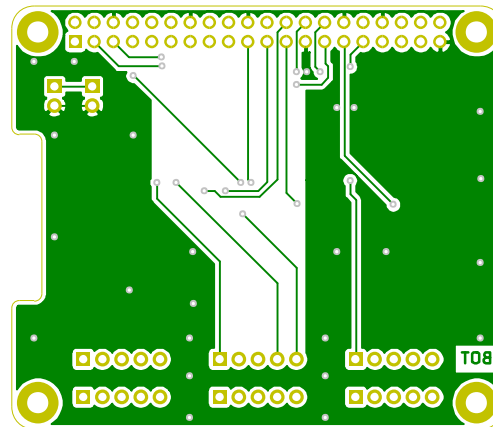
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KiCad E.D.A. kicad (5.1.10)-1

Rev: 1

Id: 1/1

T08



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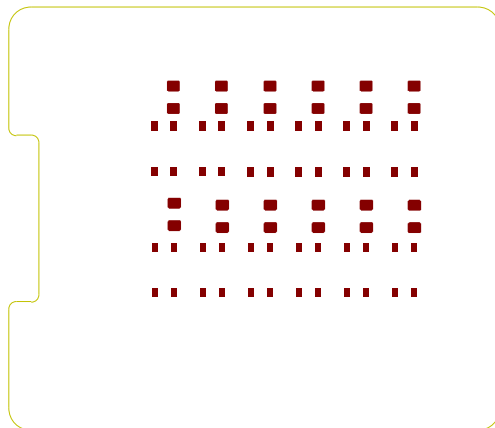
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KiCad E.D.A. kicad (5.1.10)-1

Rev: 1

Id: 1/1

TOP PASTE



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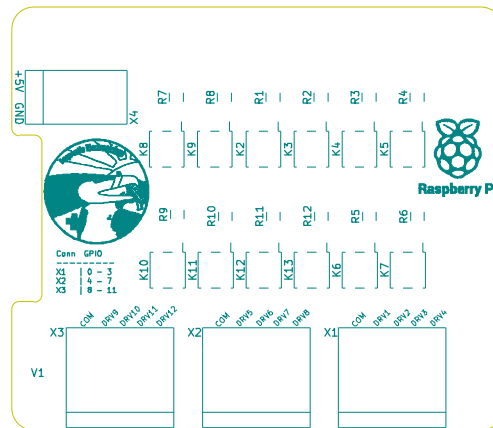
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KiCad E.D.A. kicad (5.1.10)-1

Rev: 1

Id: 1/1

TOP SILKSCREEN



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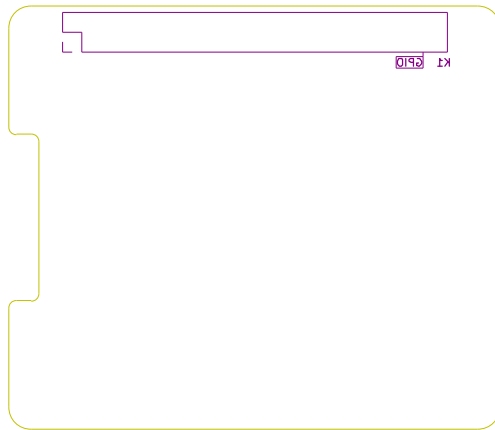
Size: A4 Date: 2021-12-01

KiCad E.D.A. kicad (5.1.10)-1

Rev: 1

Id: 1/1

BOT SILKSCREEN



Robin Forestier
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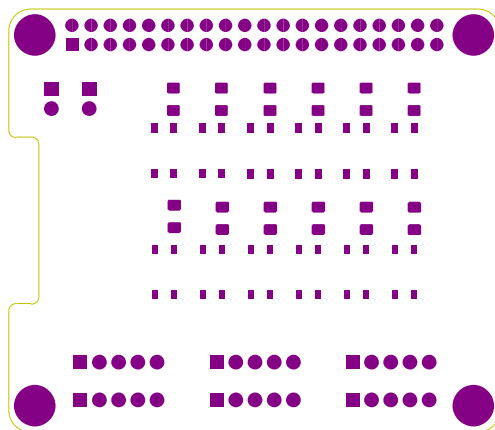
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KiCad E.D.A. kicad (5.1.10)-1

Rev: 1

Id: 1/1

TOP SOLDERMASK



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Sheet:

File: shield_octo.kicad_pcb

Title: shieLocto

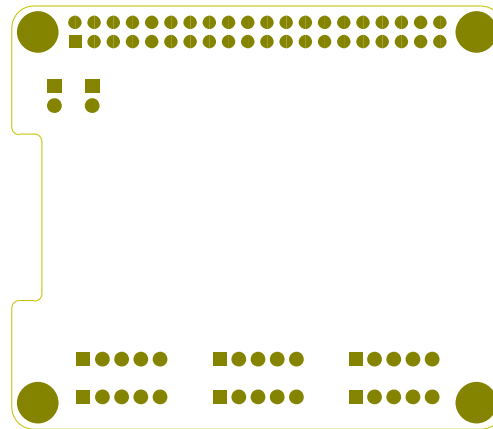
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KiCad E.D.A. kicad (5.1.10)-1

Rev: 1

Id: 1/1

BOT SOLDERMASK



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Sheet:

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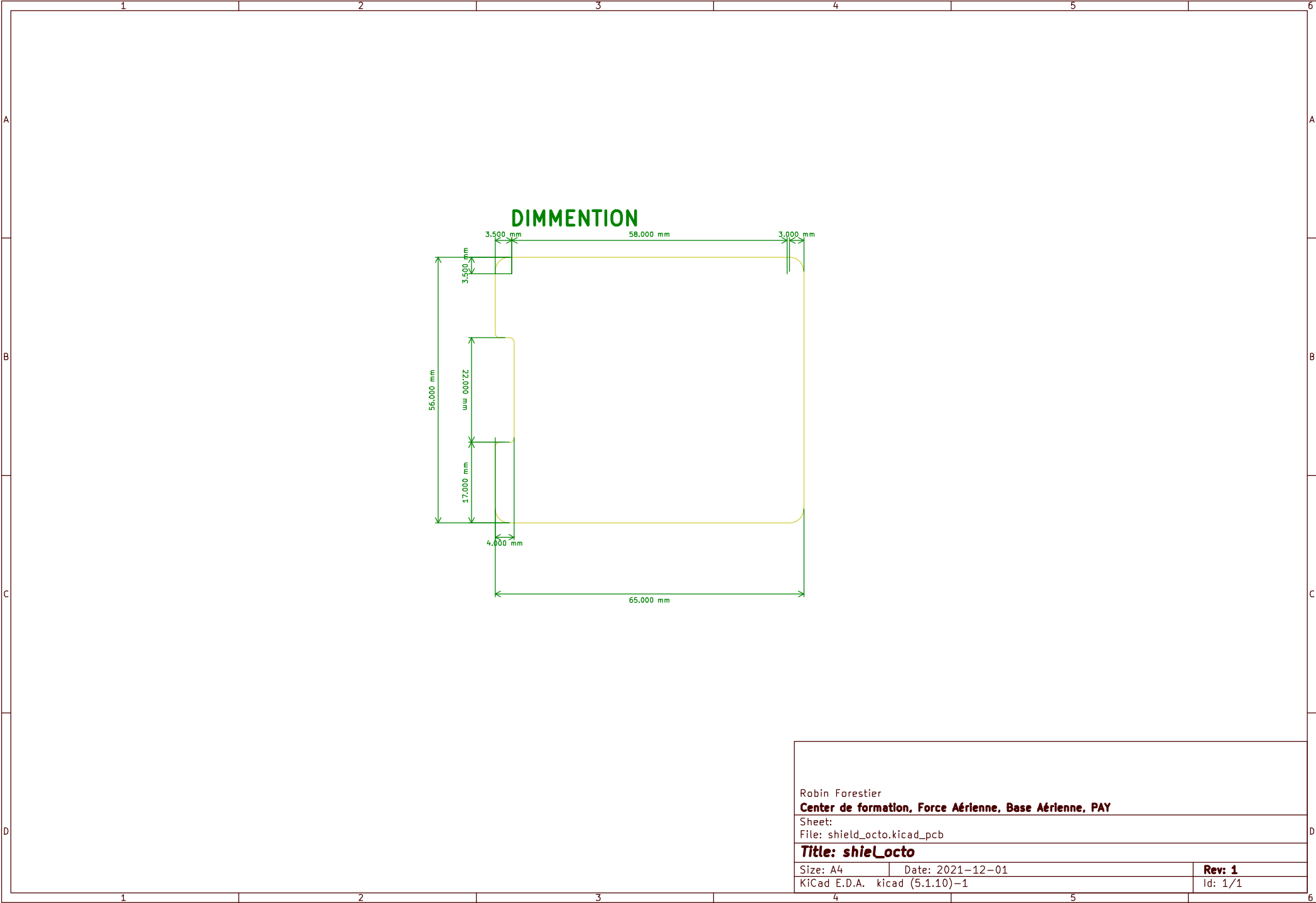
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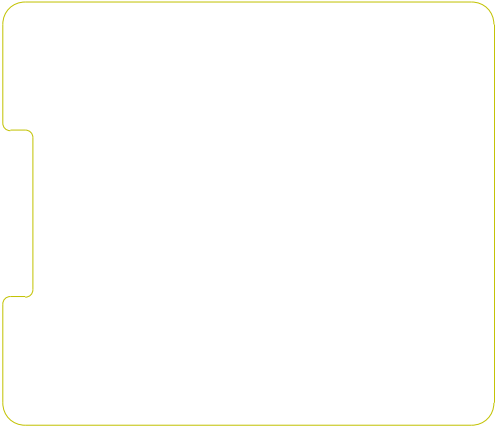
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Rev: 1

Id: 1/1



EDGE CUT



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Title: shieLocto

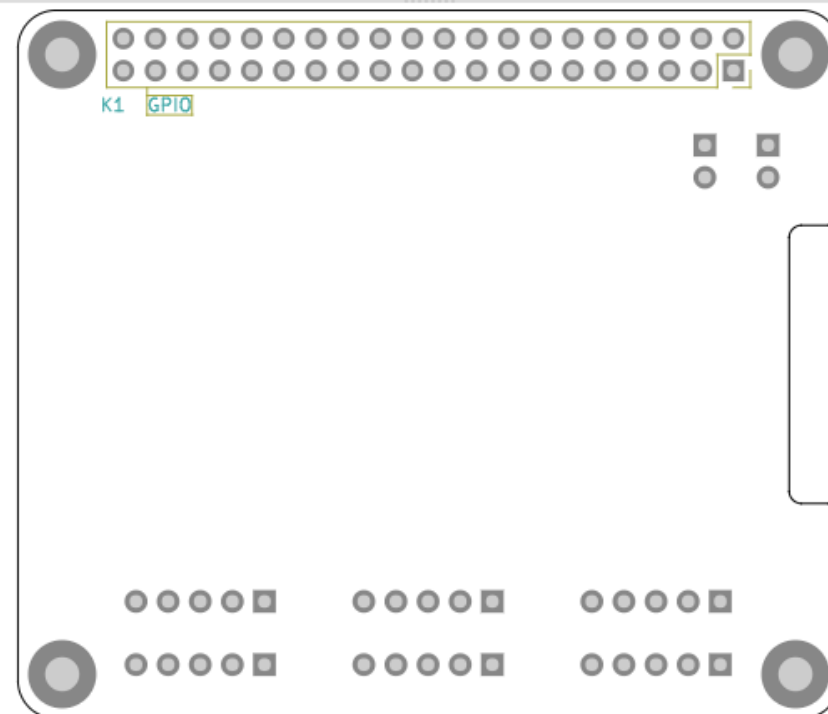
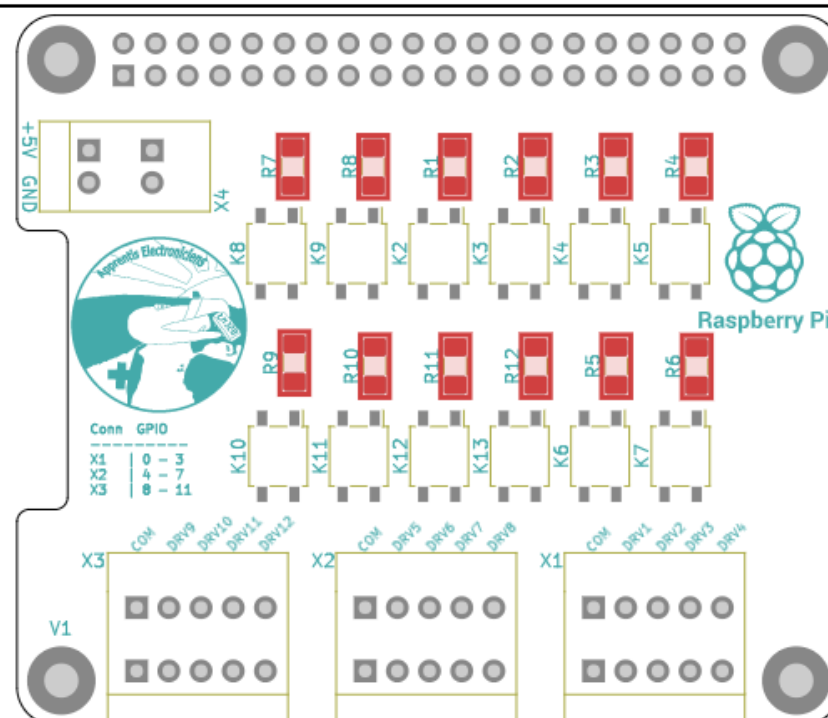
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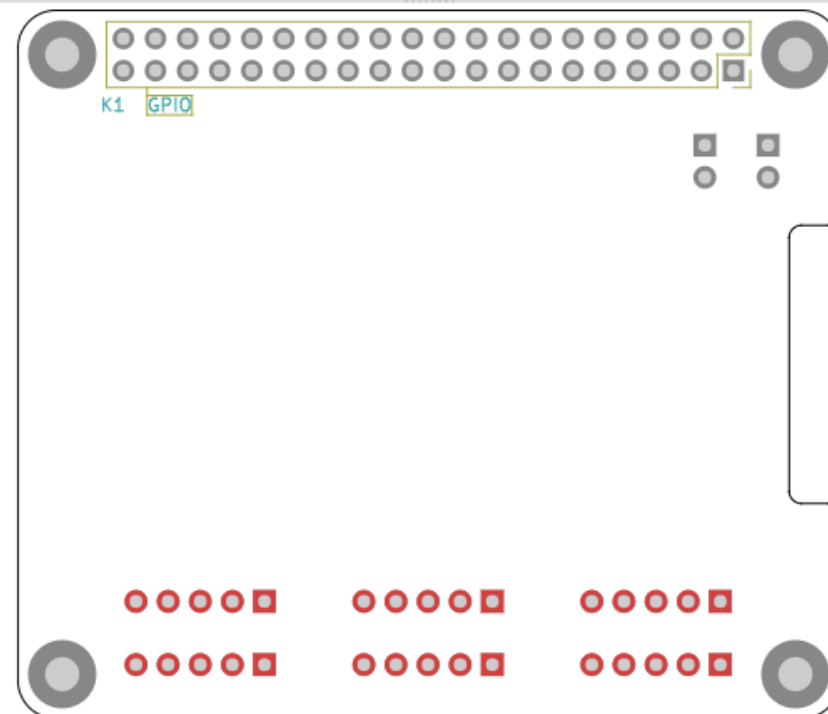
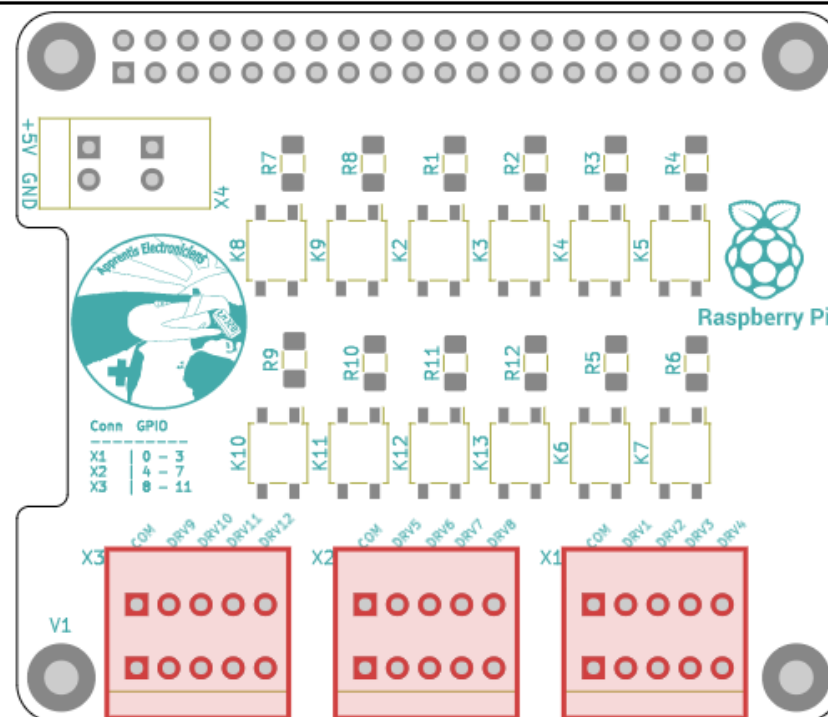


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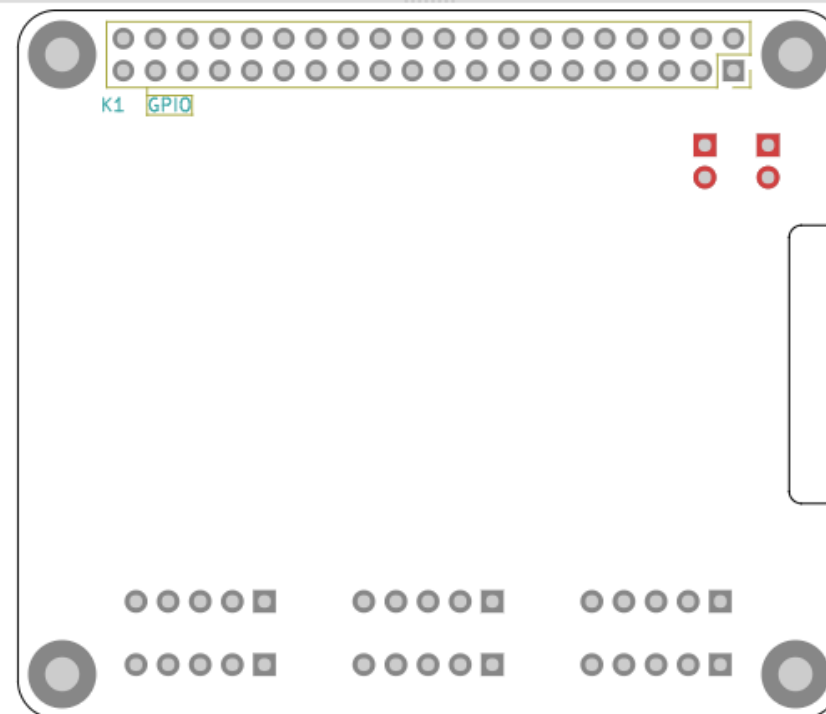
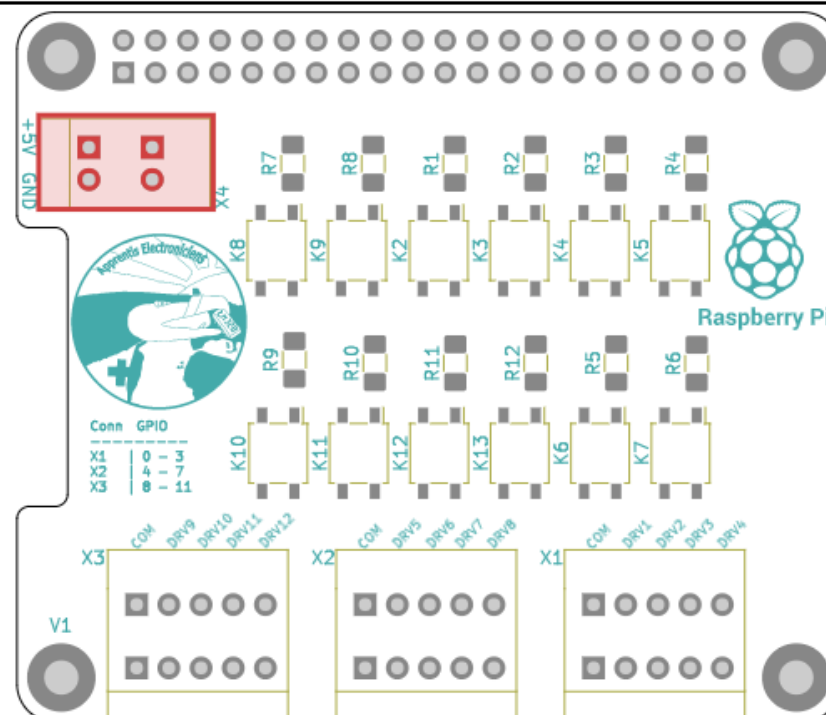


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2	<input type="checkbox"/>	<input type="checkbox"/>	X1, X2, X3	WAGO_218_5p	WAGO_218-505	3
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4	<input type="checkbox"/>	<input type="checkbox"/>	K1	Raspberry_Pi _2_3	PinSocket_2x20_P2.54 mm_Vertical	1
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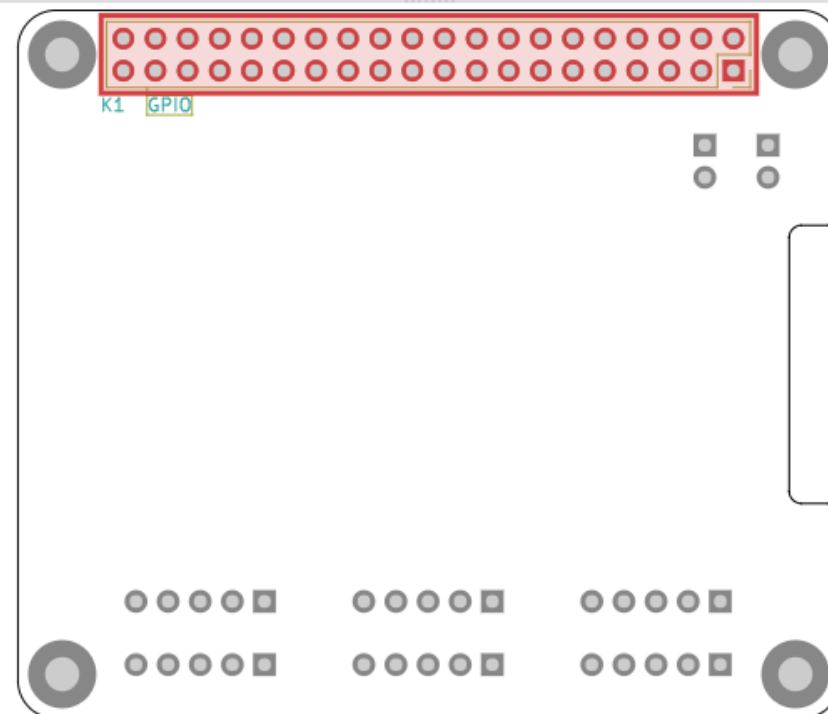
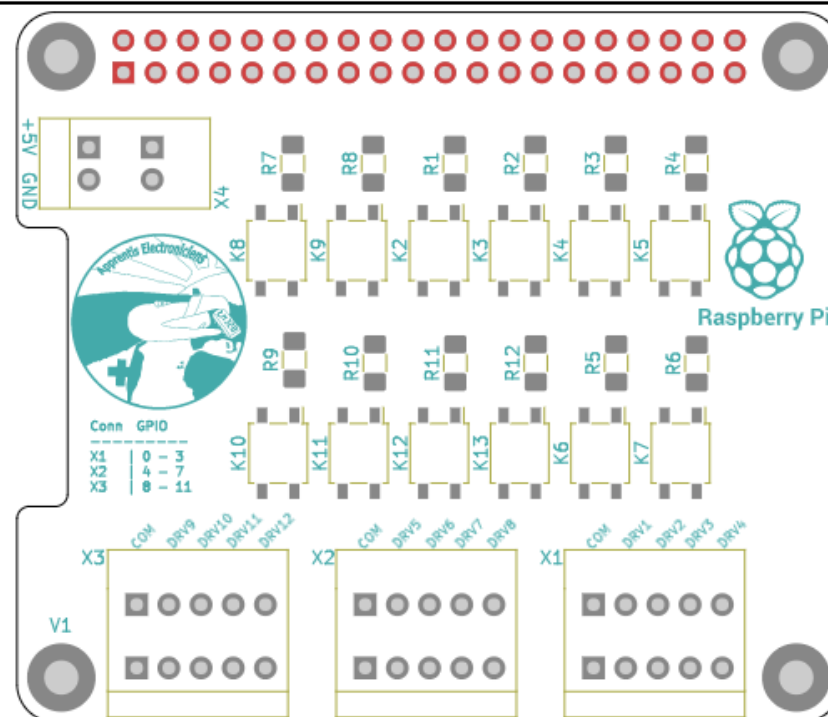


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2	<input type="checkbox"/>	<input type="checkbox"/>	X1, X2, X3	WAGO_218_5p	WAGO_218-505	3
3	<input type="checkbox"/>	<input type="checkbox"/>	X4	WAGO_250- 502- Connector	Wago_218-502_MOR	1
4	<input checked="" type="checkbox"/>	<input checked="" type="checkbox"/>	K1	Raspberry_Pi _2_3	PinSocket_2x20_P2.54 mm_Vertical	1
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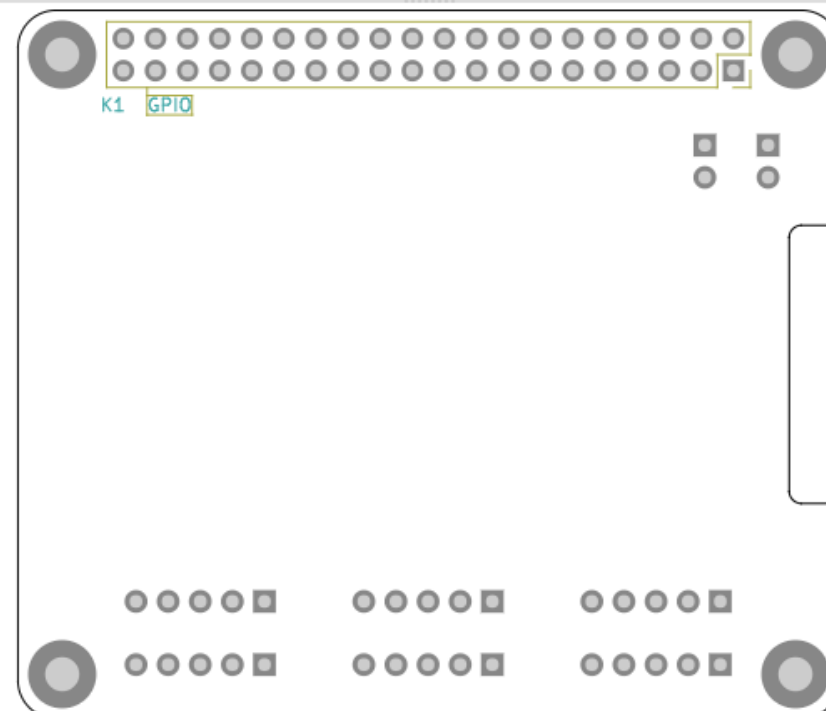
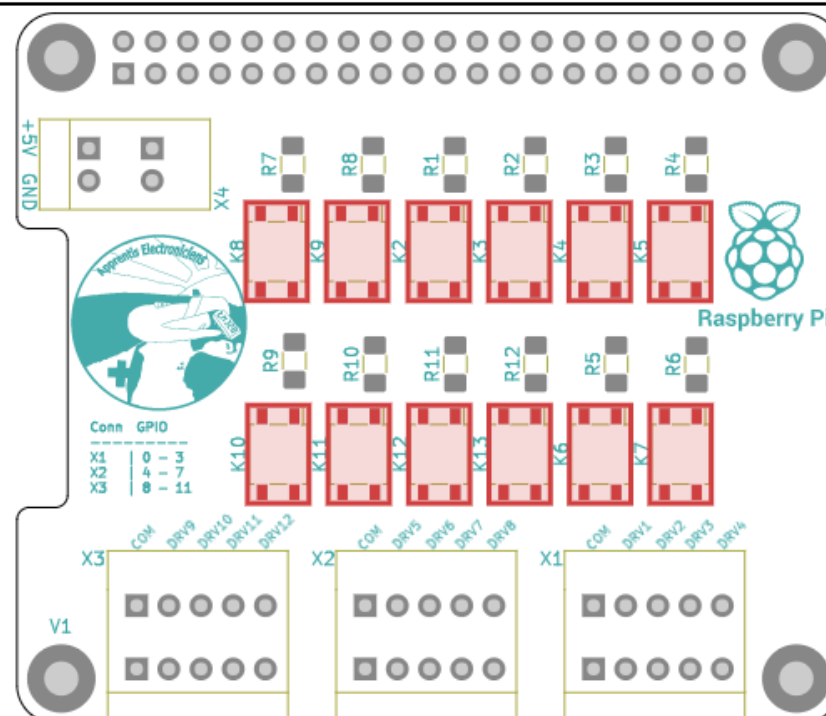


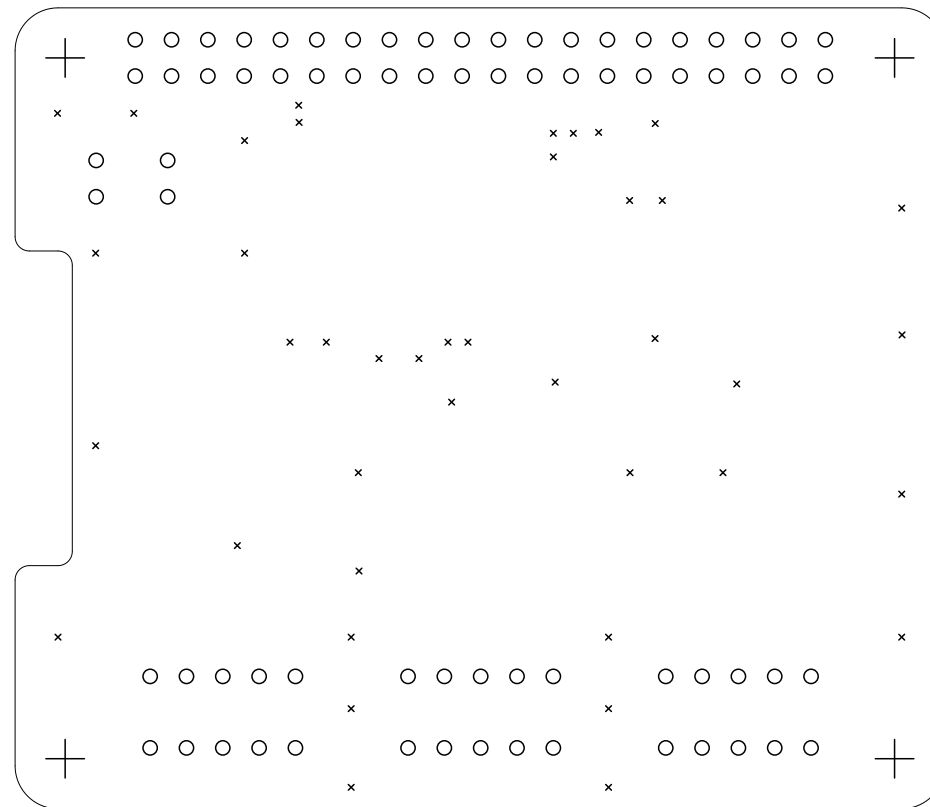


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2	<input type="checkbox"/>	<input type="checkbox"/>	X1, X2, X3	WAGO_218_5p	WAGO_218-505	3
3	<input type="checkbox"/>	<input type="checkbox"/>	X4	WAGO_250- 502- Connector	Wago_218-502_MOR	1
4	<input type="checkbox"/>	<input type="checkbox"/>	K1	Raspberry_Pi _2_3	PinSocket_2x20_P2.54 mm_Vertical	1
5	<input type="checkbox"/>	<input type="checkbox"/>	K2, K3, K4, K5, K6, K7, K8, K9, K10, K11, K12, K13	ASSR-1218	S0- 4_4.4x4.3mm_P2.54mm	12





Drill Map:

× 0.400mm / 0.0157" (41 holes)
 ○ 1.000mm / 0.0394" (74 holes)
 + 2.700mm / 0.1063" (4 holes)