Data General Corporation

Technical Manual

Nova 1220

DATA GENERAL TECHNICAL MANUAL

NOVA 1220 COMPUTER

MODELS

8151, 8152, 8153, 8154 8155, 8156, 8157, 8158

Ordering No. 015-000011-02
Copyright © 1972, Data General Corporation
All Rights Reserved.
rinted in the United States of America
Rev. 02 March 1973

INTRODUCTION	0
CENTRAL PROCESSOR	C
OPERATORS CONSOLE	K
POWER SUPPLY	P
MEMORY	M
INSTALLATION	1
MAINTENANCE	N
REFERENCE TABLES	T —

Data General Corporation (DGC) has prepared this manual for use by DGC personnel and customers as a guide to the proper installation, operation, and maintenance of DGC equipment and software. The drawings and specifications contained herein are the property of DGC and shall neither be reproduced in whole or in part without DGC's prior written approval nor be implied to grant any license to make, use, or sell equipment manufactured in accordance herewith.

NOTICE

DATA GENERAL CORPORATION (DGC) HAS PREPARED THIS MANUAL FOR INFORMATION PURPOSES ONLY. DGC RESERVES THE RIGHT TO MAKE CHANGES WITHOUT NOTICE IN THE SPECIFICATIONS AND MATERIALS CONTAINED HEREIN AND SHALL NOT BE RESPONSIBLE FOR ANY DAMAGES CAUSED BY RELIANCE ON THE MATERIALS PRESENTED, INCLUDING BUT NOT LIMITED TO TYPOGRAPHICAL OR ARITHMETIC ERRORS, COMPANY POLICY AND PRICING INFORMATION.

TABLE OF CONTENTS

SECTION O

INTRODUCTION

	Page
THE NOVA 1220 COMPUTER	O-1
THIS MANUAL	O-2
RELATED DOCUMENTS	0-2
SECTION C	
THE CENTRAL PROCESSOR UNIT	
INTRODUCTION	C-1
THE CONTROL UNIT	
Major States TS Cycles Timing Generator Cycles The Processor Timing Generator The Accumulator Timing Generator The Memory Timing Generator	C-2 C-2 C-2 C-2
CPU DATA PATHS	C-5
Registers Program Counter (PC). Instruction Register (IR and MBC). CPU Interface Register (MBO). Shift Buffer (ACB). Accumulators (AC0, AC1, AC2, AC3). Data Flow. Nibble Transfers. Instruction Overlapping. Data Buses.	.C-5 .C-5 .C-5 .C-5 .C-5 .C-5
THE FLOW AND TIMING DIAGRAMS	C-6
FETCH. ALC. EFA. I/O. DE FER. EXEC. DCH. PI. F COM.	. C-10 . C-12 . C-15 . C-16 . C-20 . C-26 . C-30 . C-33
REFERENCES	.C-6

SECTION K

THE OPERATOR'S CONSOLE

Page INTRODUCTION......K-1 CONSOLE LIGHTS AND SWITCHES..... K-1 The Console ADDRESS Lights..... K-1 The Console DATA Lights..... K-1 The Console Operational Indicators..... K-1 The Console Switch Register..... K-2 The Console Control Switches..... K-2 REFERENCES K-2 SECTION P THE POWER SUPPLY INTRODUCTION......P-1 POWER SUPPLY CIRCUITS......P-1 REFERENCES......P-1 SECTION M THE MEMORY The Memory Select Logic M-2

SECTION I

INSTALLING THE COMPUTER

Page INTRODUCTION..... I-1 Rack Mounting The Computer......I-5 Types of Cables......I-5 Device Cables......I-5 Internal Cables..... I-5 Interdevice Cables...... I-5 Adapter Cables...... I-5 Cabling The System..... I-8 SECTION N MAINTAINING THE COMPUTER On Call Service Contract......N-1 Hourly Service......N-1 TRAINING ORGANIZATION N-2 Fundamentals of Mini-Computer Programming......N-2 Advanced Programming......N-2 HOW TO TEST THE COMPUTER......N-7

REFERENCE TABLES

Page SIGNAL LIST......T1-1 ABBREVIATIONS......T2-1 LIST OF ILLUSTRATIONS Figure Title Page Exploded View of The Nova 1220 Computer With Central Processor and O-1Memory Cards Removed O-1 O-2O-3Nova 1220 Hardware Documentation......O-5 C-1 Timing For The Processor Timing Generator During All Major States Except C-2 C-3C-4C-5 C-6 C-7 C-8 C-9 C-10 C-11 C-12 C-13 C-14 C-15 C-16 C-17

LIST OF ILLUSTRATIONS (Continued)

<u>Figure</u>	<u>Title</u> P2	age
C-18	PI Timing Diagram	-48
C-19	Data Channel Increment Timing C-	-49
C-20	Data Channel In Timing	-49
C-21	Data Channel Out Timing	-50
C-22	Data Channel Out Followed By Data Channel In Timing	-50
K-1	The Console K-	-1
K-2	The CPU Key Sequence Timing Diagram	-2
K-3	Key, KEYM and Manual Flow Diagrams K-	-4
P-1	Simplified Schematic of The +5Vdc Series Switching Regulator P-	-3
P-2	Simplified Schematic of The +15Vdc Series Switching Regulator P-	-4
M-1	Simplified Schematic of a Memory Core	-1
M-2	Simplified Schematic of The Core Memory's Sense and Inhibit Lines	-2
M-3	Core Memory M-	-3
M-4	Wiring Up The Select Logic of 1K and 2K Boards M-	-4
M-5	Wiring Up The Select Logic of 4K and 8K Boards	-5
I-1	The Nova 1220 Shipping Kit I-	-2
I-2	Nova 1220 Board Slots	-3
I-3	Rack Mounting Hardware For The Nova 1220	-4
I-4	Sketch of The Nova 1220 Cabling SchemesI-	-6

Data General Corporation (DGC) has prepared this manual for use by DGC personnel and customers as a guide to the proper installation, operation, and maintenance of DGC equipment and software. The drawings and specifications contained herein are the property of DGC and shall neither be reproduced in whole or in part without DGC's prior written approval nor be implied to grant any license to make, use, or sell equipment manufactured in accordance herewith.

LIST OF TABLES

Number Title Page C-1 C-2 C-3 C-4 K-1 Control Switch Decoding To The Instruction Register......K-3 K-2 Backpanel Connections To The Console Through POA......K-5 P-1 Output Signals Of The Nova 1220 Power Fail Module...... P-2 P-2 M-1 The Nova 1220 Electrical, Mechanical and Environmental Specifications..... I-1 I-1 I -2 P3 Interconnections For Nova 1220......I-7 I-3N-1 N-2 Recommended Maintenance Tool Kit......N-4 The Nova 1220 Diagnostics..... N-5 N-3

SECTION O

INTRODUCTION

THE NOVA 1220 COMPUTER

The Nova 1220 computer shown in Figure O-1 consists of a power supply-backpanel assembly and a console assembly mounted on a chassis into which plug up to ten 15" by 15" PC boards. The chassis includes a frame, two fans, a filter, a power transformer and a power switch assembly; the power supply-backpanel includes the power supply and ten sets of edge connectors mounted on an

etched PC board. The console includes a frame, front panel and PC board which holds the switches, lights and associated logic. Each basic Nova 1220 includes a Central Processor module, and any one of four types of memory modules; 1K, 2K, 4K or 8K. A table top assembly is also available but not shown.

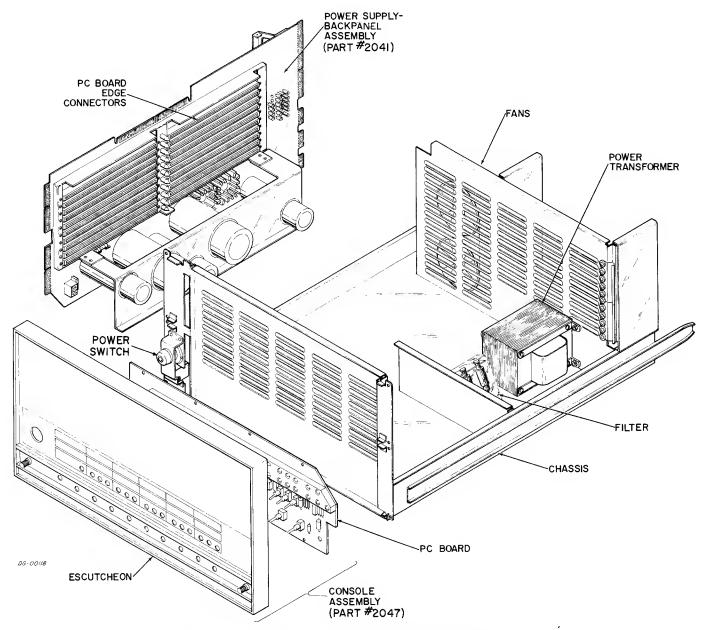


Figure O-1 Exploded View of The Nova 1220 Computer With Central Processor and Memory Cards Removed

The Central Processor, Console, Memories and Controllers communicate with each other along 16 bit buses called MEM, MBO and IN-OUT as shown in Figure O-2. MEM transfers information from Memory or the Console to the MBO or Instruction registers; MBO transfers information from the MBO register to the Console and Memories, and IN-OUT transfers information between the Memory's MB register and peripheral controllers. In the Nova 1220 proper all these data paths and their associated control signals travel along etched tracks on the backpanel to the board's edge connectors and to a plug in the console's PC board.

THIS MANUAL

This manual explains how the basic Nova 1220 works, how it is installed and how it is maintained. It is divided into 8 sections:

Section O introduces the machine and this manual;

Section C explains how the Central Processor works;

Section K explains how the operator's Console works;

Section P explains how the Power Supply works;

Section M explains how the Memories work;

Section I explains how to install the computer;

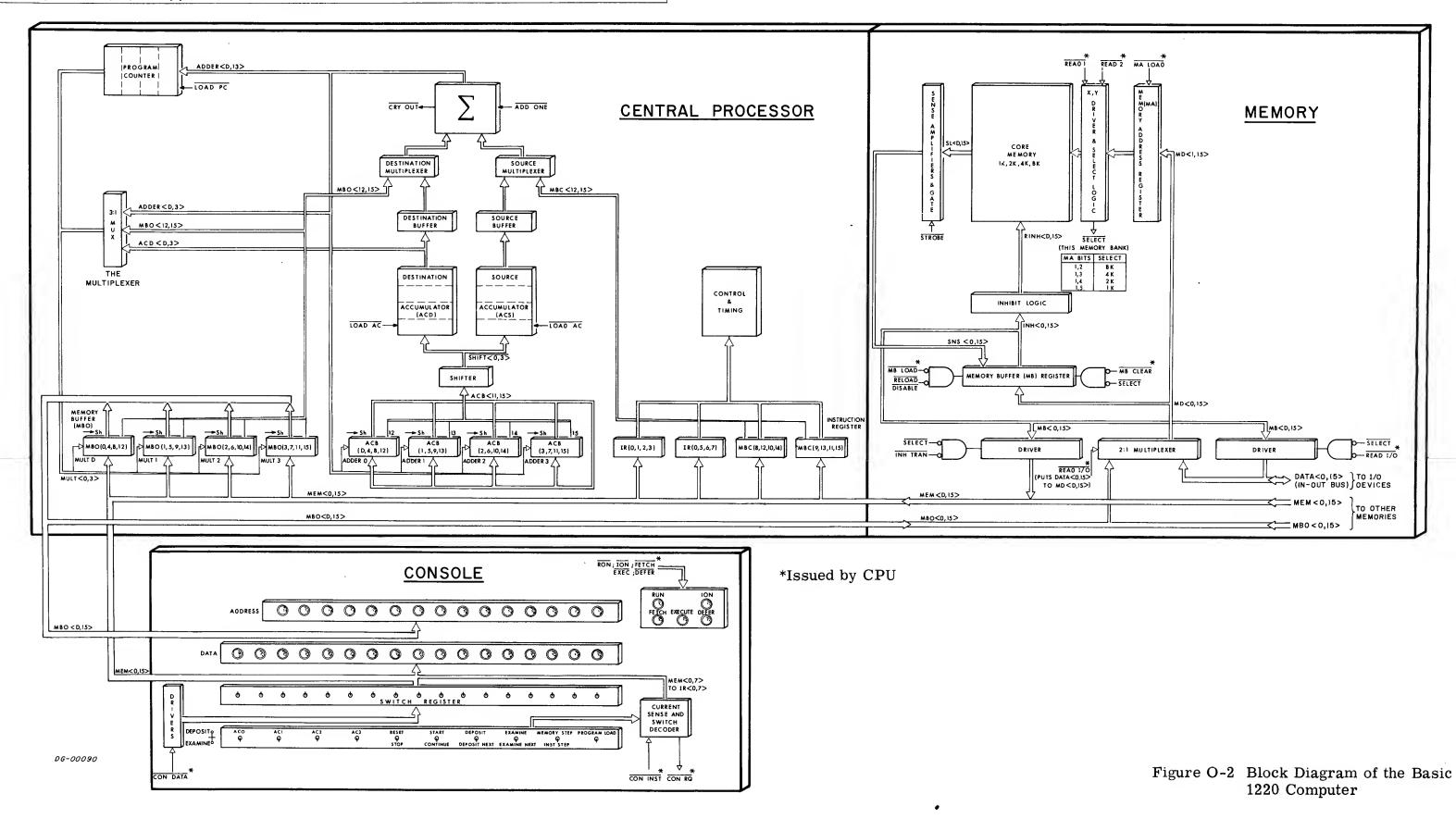
Section N explains how to maintain the computer;

Section T has two reference tables - a signal list and a list of expanded abbreviations. The signal list traces the source and destination of each signal in the Central Processor and the Memory. Source signals are listed alphanumerically by name. Each source signal originates at the output pin (PIN) of an integrated circuit (CHIP) which is called out on a drawing (DWG) at a grid reference (GRID). Each signal is wired to one or more ICs which themselves originate more signals, or (FUNCTIONS), whose names and locations are listed in the DESTINATION column beside their originating signal. Drawing numbers are identified by the last two numbers of the print followed by a hyphen followed by their sheet number(s).

RELATED DOCUMENTS

Figure O-3 lists the engineering prints and manuals which describe the basic computer. The manual "How To Use The Nova Computers" explains how to program the machine. The manual "The I.C. User's Guide" gives logic diagrams and truth tables for the I.C.s used in Data General's machines.

Data General Corporation (DGC) has prepared this manual for use by DGC personnel and customers as a guide to the proper installation, operation, and maintenance of DGC equipment and software. The drawings and specifications contained herein are the property of DGC and shall neither be reproduced in whole or in part without DGC's prior written approval nor be implied to grant any license to make, use, or sell equipment manufactured in accordance herewith.



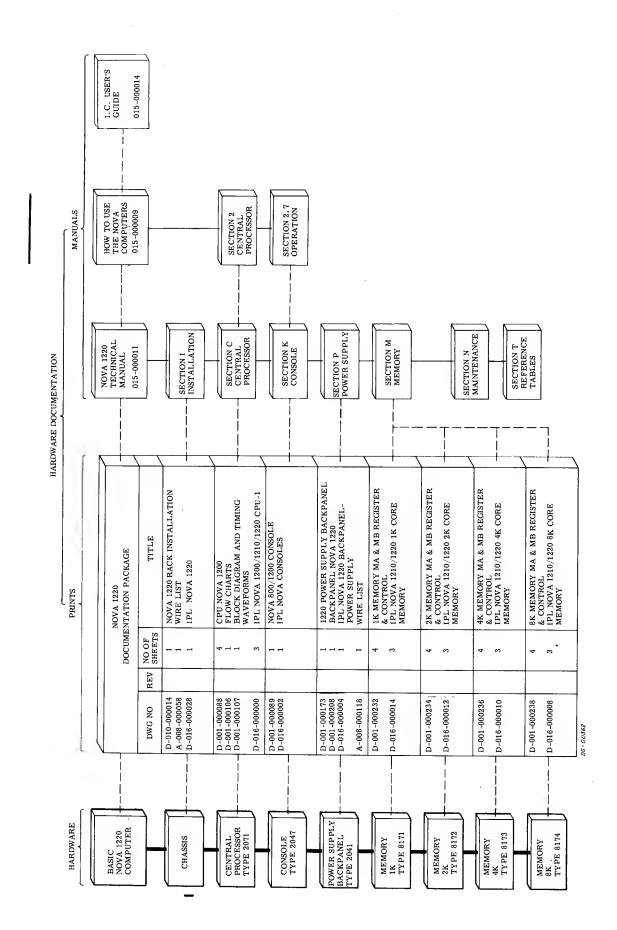


Figure O-3 Nova 1220 Hardware Documentation

This Page Left Blank
Intentionally

SECTION C

THE CENTRAL PROCESSOR UNIT

INTRODUCTION

The central processor unit (CPU) used in this computer is a binary, 2's complement, fixed word length, parallel/serial, digital, automatic processor. It takes up to 32K words of $1.2\mu \sec$ co-ordinate-addressed core memory of 16 bits per word. It has 7 sixteen bit hardware registers: four accumulators (AC0, AC1, AC2 and AC3); a program-transparent shift buffer (ACB); a program-transparent memory buffer (MBO); and one 15 bit program counter (PC). All internal data paths are four bits (or one "nibble") wide, so each internal transfer takes four steps; all three external data paths or buses, (MEM, MBO and IN-OUT) are 16 bits wide so each external transfer takes one step.

There are three classes of instructions; memory reference (EFA), input-output (I/O) and arithmetic and logic (ALC). There are three modes of addressing; absolute, index (to AC2 or AC3) and relative (to PC).

Peripheral devices can interrupt the processor and transfer data to or from its accumulators via the I/O instruction set, or simply use the processor's high speed data channel directly to memory.

The CPU is contained on a single 15" by 15" PC board which is inserted into the first slot of the computer's chassis. Power is supplied by the chassis' power supply.

THE CONTROL UNIT

The CPU is a synchronous processor for which time is broken up by two clocks into discrete, fixed periods. The two clocks are derived from a 13.333Mhz crystal oscillator which is divided by two. One clock, called MEM CLK is always running; the other, called CPU CLK is gated by three signals RUN, STUTTER and WHOA. RUN is a control flip-flop which stops the processor when it resets; STUTTER inhibits the clock for one cycle and WHOA is used by certain options like the multiply divide to slow the machine down. With these clocks the Control generates eight major states and two levels of minor states called timing state (TS) cycles and timing generator (TG) cycles.

Major States

Major states define what type of memory function is under way. The designated major state of the machine is set at the beginning of each memory cycle and remains set throughout that memory cycle. There are eight major states; Fetch, Defer, Execute, PI,DCH,Key, Keym, and a "dummy" state during which none of the other states are set.

- Fetch occurs when the next word to be read from memory is to be treated as an instruction.
- 2. Defer occurs when the next word from memory is to be treated as the address of an operandor instruction, i.e., during indirect addressing.
- 3. Execute occurs when the next word from memory is to be treated as an operand. Programmed I/O operations also set Execute, but the memory is not allowed to run.
- 4. PI occurs during a program interrupt when:
 - the contents of the PC are stored in location 0
 - the next major state is set to Defer
 - A JMP instruction is forced into the Instruction Register
 - the next address executed is in location 1, which should be set to the starting address of the service routine.
- 5. DCH occurs when the next memory cycle is to be a direct transfer between an I/O device and Memory.
- 6. Key occurs when a manual function is being requested from the Console. During Key, either all or part of the manual function is performed. The memory is not allowed to run during the Key cycle.
- 7. Keym occurs when the manual function requires a memory cycle, such as Examine or Program Load.
- 8. "Dummy" State occurs only when a machine stop is pending and the current instruction requires the skip conditions to be interrogated. During this state the machine increments the PC if the skip is successful in order that the address lights reflect the true next address.

TS Cycles

The TS cycles are four clock pulses long, and may be thought of as the time required to transfer a 16 bit word between two CPU registers at the rate of four bits per clock cycle. Each Major State consists of at least two complementary TS levels, called TS0 and TS3. TS0 occurs during the first half of the Major State, and TS3 occurs during the second half. Certain operations require more time than that provided by the two TS cycles, so a flip-flop called Loop is set to force the TS0 cycle to repeat and give the Major State three TS time intervals. During TS0 of this operation the data is fetched from the memory and loaded into the MBO; then Loop is set, TS0 is repeated, and the data in the MBO is shifted through the Adder. Finally, TS3 is set and the data is transferred from the MBO to the Memory and re-written.

Timing Generator Cycles

There are three timing generators, called the processor timing generator (PTG); the accumulator timing generator (ACTG) and the memory timing generator (MTG). These timing generators effectively designate the clock pulses for specific functions in the processor, accumulator and memory respectively.

The Processor Timing Generator. This two bit counter, designated, PTG0 and PTG1, cycles every four clock pulses. PTGO is set during the two middle clock cycles of a TS cycle, and PTG1 is set during the last two cycles of a TS cycle. These two levels are decoded into two others called PTG2 and PTG5. PTG2 is the last clock interval during TSO, and PTG5 is the last clock interval during TS3. PTG5 is used, for example, to enable the major state flip-flops. PTG0 "anded" with TS0 to form PTG0. TS0, the first clock interval during TSO, is used to increment the Adder as the least significant four bit nibble is passed through it. Figures C-1 and C-2 show the timing for the PTG during FETCH or KEY major states, and all other states.

The Accumulator Timing Generator. This two bit counter, designated ACTG0 and ACTG1, is always one clock state ahead of the PTG counter. Its two signals are used to drive the accumulator chips. Their timing is given in Figure C-3.

The Memory Timing Generator. This four bit counter, designated MTG0, MTG2, MTG3, is used to form the control signals for memory. Its timing is given in Figure C-4.

NEXT MAJOR STATE

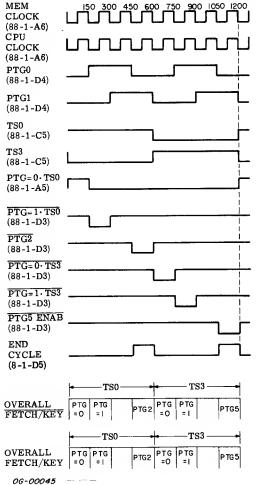


Figure C-1 Timing
For The Processor Timing
Generator During All
Major States Except
Fetch or Key

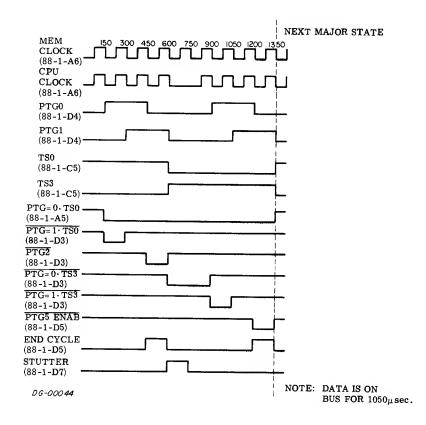


Figure C-2 Timing For The Processor Timing Generator During Fetch or Key

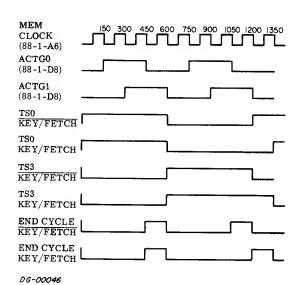
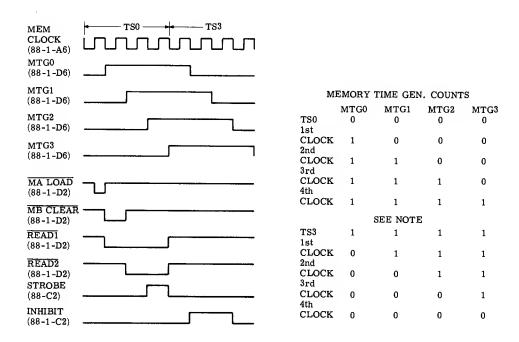


Figure C-3 Timing For The Accumulator Timing Generator

ACCUMULATOR TRUTH TABLE (88-4-B6 & B7 U124 & U123)

ACTG0	ACTG1		
0	0	BITS	12-15
1	0	BITS	8-11
1	1	BITS	4-7
0	1	BITS	0-3



NOTE - IF LOOPING TS0, CLOCK FREEZES WITH ALL ONES UNTIL FIRST CLOCK IN TS3.

DG-00047

Figure C-4 Timing For The Memory Timing Generator

CPU DATA PATHS

Registers

The CPU is organized around eight hardware registers as shown in Figure C-5; a shift buffer (ACB); a program counter (PC); a CPU interface register (MBO); an instruction register (IR and MBC); and four accumulators, (AC0, AC1, AC2, AC3). These eight registers are all 16 bits long except for the PC which is 15 bits. All internal data paths are four bits wide, so it takes four separate operations to perform an add, or a register-to-register transfer.

Program Counter (PC). The 15 bit address of the next instruction to be fetched is held in the PC. During the fetch of an instruction, the PC is incremented by one so that it points to the next sequential instruction. Certain instructions, such as JMP can change the contents of the PC. The PC consists of one 16 bit latch.

Instruction Register (IR and MBC). The Instruction Register stores the instruction currently being executed. The CPU decodes the data held in the Instruction Register in order to perform the instruction. The register is organized into two parts, the IR and MBC. The IR consists of the eight high order bits, and the MBC of the eight low order bits. During an effective address calculation, the MBC contains the displacement and shifts through the source multiplexer into the Adder and the IR bits remain static.

CPU Interface Register (MBO). The MBO is used in every operation the CPU performs. It acts as a parallel-to-serial converter for 16 bit data flowing into the machine from the MEM bus. This data is loaded from the MEM bus into the MBO in parallel, and shifted out four bits at a time into some other part of the machine. Conversely, data is shifted into the MBO from the Adder four bits at a time to be loaded into a Memory from the MBO bus. During effective address calculations, the MBO holds the present address used in relative addressing. During memory modify operations (such as ISZ) data is loaded into the MBO Memory. The MBO then modifies the data by recirculating it through the Adder and back into the MBO. The modified data is then loaded from the MBO back into Memory.

Shift Buffer (ACB). All data to be loaded into the Accumulators are passed through the ACB, where the results of an ALC instruction are assembled before they are loaded back into the Destination Accumulator.

Accumulators (AC0, AC1, AC2, AC3.) There are two identical sets of four - 16bit accumulators all of which can be logically and arithmetically manipulated under program control. Each set of accumulators is contained in a single 64 bit chip: (only one accumulator - nibble per chip can be addressed at any one time). Since it is necessary to be able to access two accumulators simultaneously. two sets are available, called source (S) and destination (D), each set containing the same information as the other. For example, two accumulators can be added together by simultaneously fetching the source data from one chip and the destination data from the other and then adding the two. The accumulators are buffered by four bit registers (source and destination) so that the next nibble can be selected while the current nibble is being processed. It takes 100 ns to access a nibble in the accumulator, and 100 ns to move a nibble through the Adder and Multiplexer, so by overlapping the two, the total time to process a nibble is 100 ns.

During the first nibble, the Adder is idle and a flag called STUTTER inhibits the clock until data is ready.

Data Flow

Nibble Transfers. When transferring data from one register to another, the lower order bits are always transferred first. The first clock interval would transfer bits 12-15, the second 8-11, the third 4-7, and the fourth 0-3. If an operation is to be performed upon a word, two things must be specified; the bit position inside the nibble, and the nibble to be acted upon. For example, to increment a word during FETCH TS0 time when the MBO is incremented, a carry is inserted into the low order bit of the Adder during the first clock interval, PTG=0. TS0, so a "one" is added to that first nibble. If a carry resulted from that first addition, it is stored in a flip-flop for the next clock interval where it is inserted into the Adder as a carry into the low order bit. This continues until all four nibbles have passed through the Adder. During JSR it is necessary to force bit 0 to be zero as it is stored into AC3. A gate in the high order position of the nibble forces the output of the multiplexer/shifter gate high (to load zero) during JSR and the fourth clock interval during the time state in which the PC is being loaded into AC3.

Instruction Overlapping. Certain instructions are carried out at the same time as parts of other instructions. For example, any operation which loads an accumulator is overlapped with the next major state. Such is the case with the ALC instruction when the CPU first operates upon the accumulator(s), loads the result into the ACB register while memory is re-writing the instruction, and then waits until the next state to transfer the result from the ACB back into the accumulator. The next state could be FETCH, PI, DCH or even KEY. Another operation that is overlapped with the next Major State is the interrogation of skip conditions for ALC and ISZ/DSZ instructions. The results of these instructions are loaded into the ACB, which shifts through the multiplexer/shifter during TSO of the next major state, after which the data may or may not be loaded into the accumulators. The output of the multiplexer/shifter is checked for all zeroes to see if it fulfills the skip conditions. If it does, the SKIP flip-flop is set at the end of TSO. If the next major state was FETCH, the execution of that instruction is inhibited, effectively skipping it, even though it was fetched from memory and loaded into the instruction register. If the next major state is PI, the PC that is loaded into address zero is incremented to reflect the skip before it is stored. If the next state is DCH and the SKIP flip-flop is left in the set state, appropriate action will be taken on the next FETCH or PI cycle. If the machine is about to be stopped from the Console by STOP, ISTP, or MSTP, a "Dummy State" is entered in which the skip conditions are interrogated, and the PC incremented as required to permit the ADDRESS lights on the Console to show the correct next address when the machine is stopped.

Data Buses

Data is transferred between memory and the central processor or an I/O device along three data buses called:

$\overline{ ext{MEM}}$	which transfers data from memory to
	the Central Processor;

MBO which transfers data from the Central Processor to Memory;

DATA which transfers data in either direction between memory and I/O devices.

During an output I/O instruction, data moves from the source AC into the MBO and on to the MBO bus. From the bus it is strobed into the memory MB register and on through the IN-OUT bus to the destination device. During an output I/O instruction the destination device outputs to the IN-OUT bus into the memory's MB register, which dumps into the MEM bus. The MEM bus is strobed into the MBO which moves it through the Adder to the ACB and into the destination AC.

THE FLOW AND TIMING DIAGRAMS

The following diagrams illustrate each step in the sequence of functions carried out by the central processor and memory. Each block of a flow diagram describes an operation, its data path and the location of critical logic. For example, this block means that the ACB register was transferred to an AC register via the

shifter (ACB) which is located on print 001-000088, sheet 4, in grid A7. The symbol Σ means Adder, M means Multiplexer, and S means Shifter. Supporting notes near the blocks give the current time state, relevant figures and the status of important signals.

REFERENCES

1.	Nova 1200 CPU	Print D-001-000088-13
2.	Flow Charts	Print D-001-000106-00
3.	Waveforms	Print D-001-000107-00

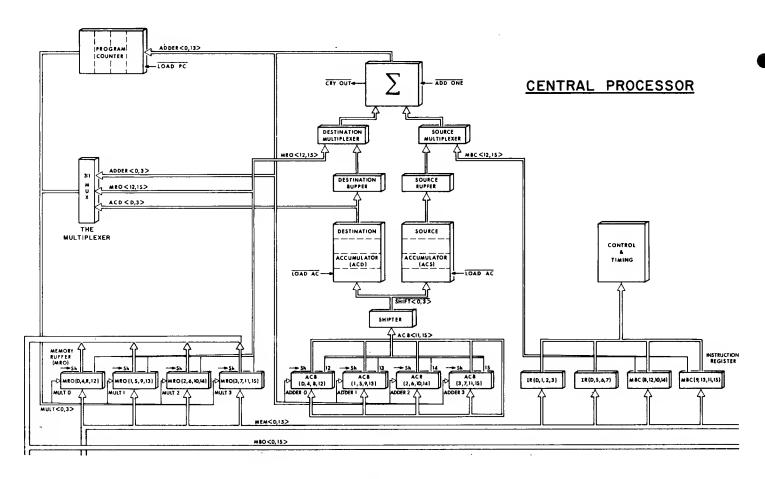
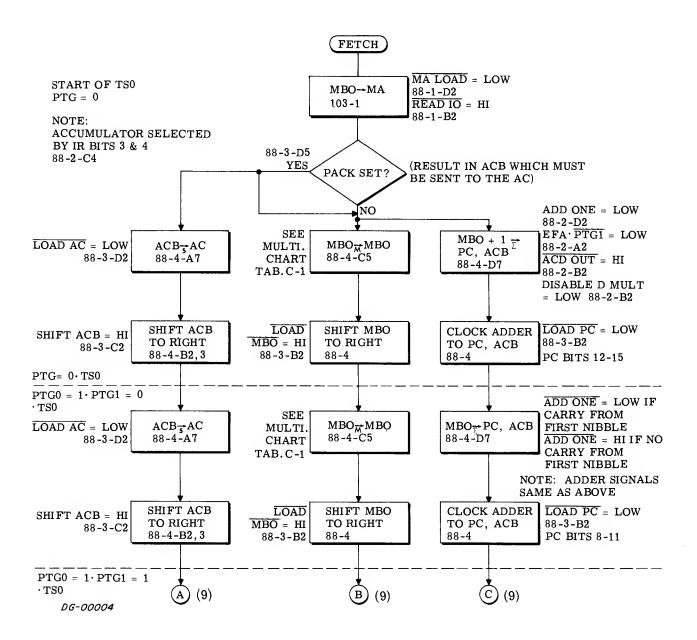
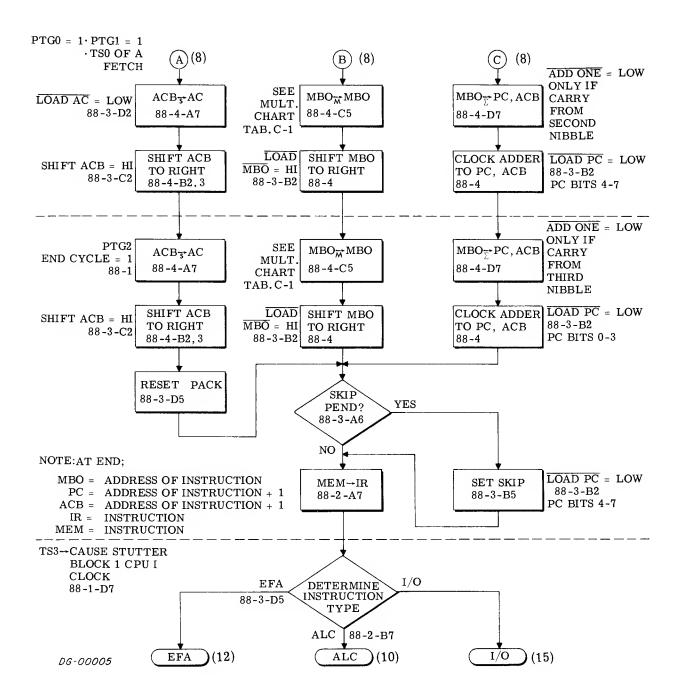
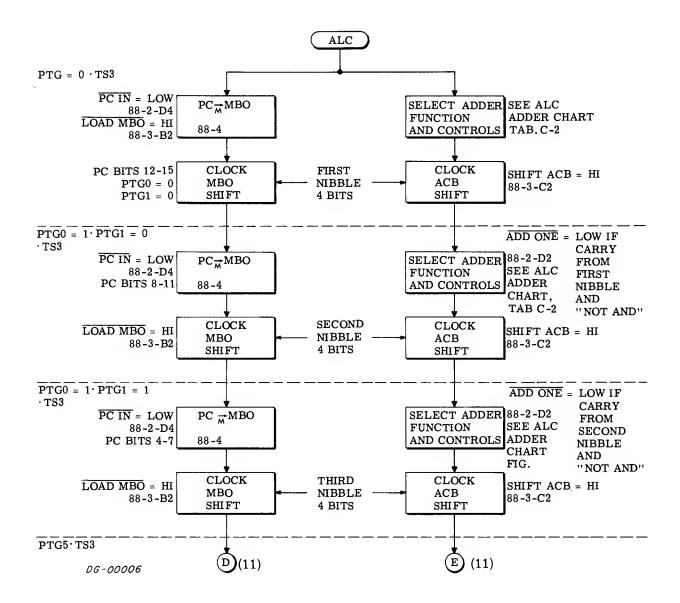
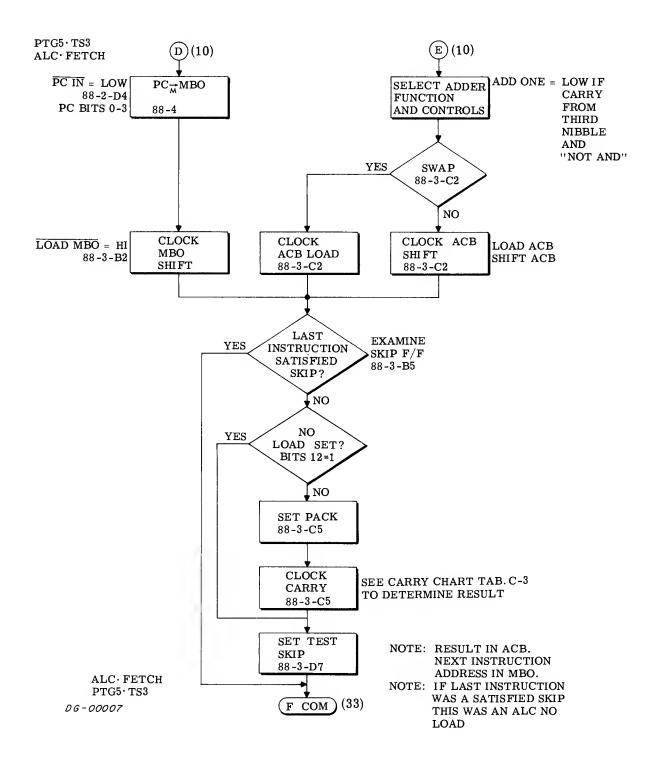


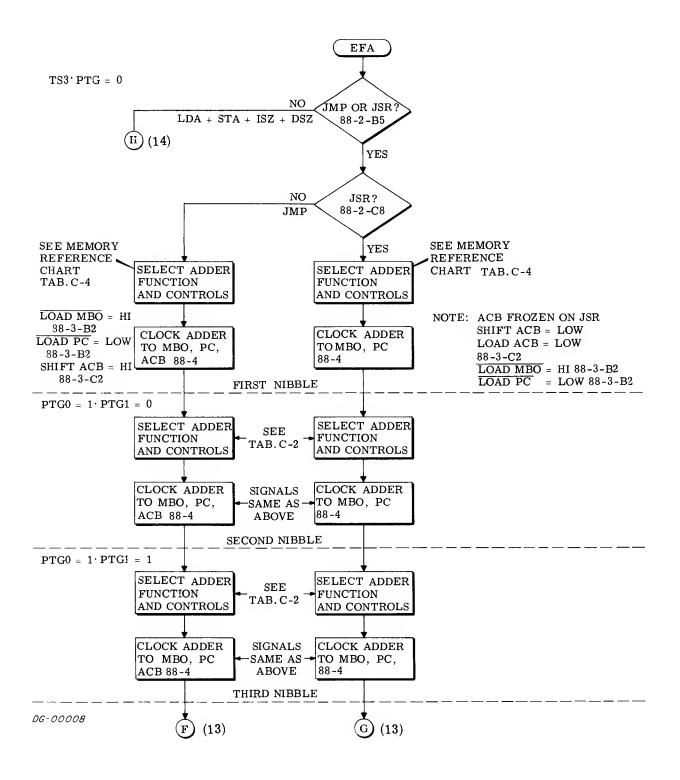
Figure C-5 The Nova 1220 Central Processor

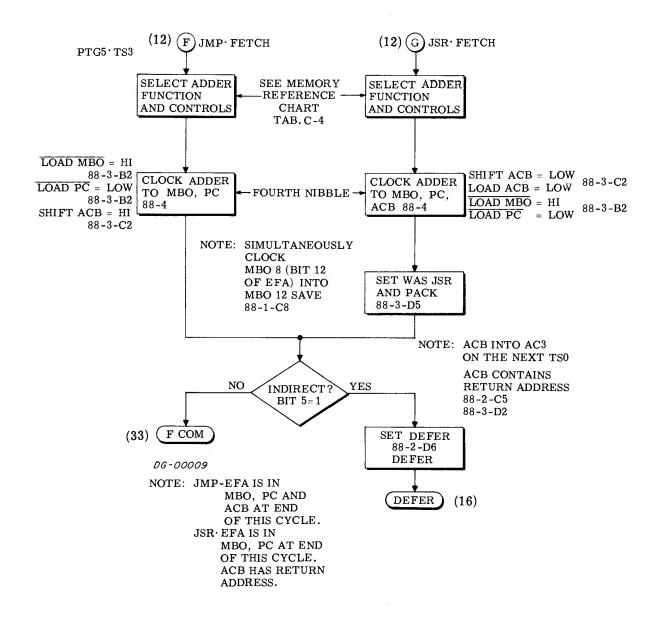


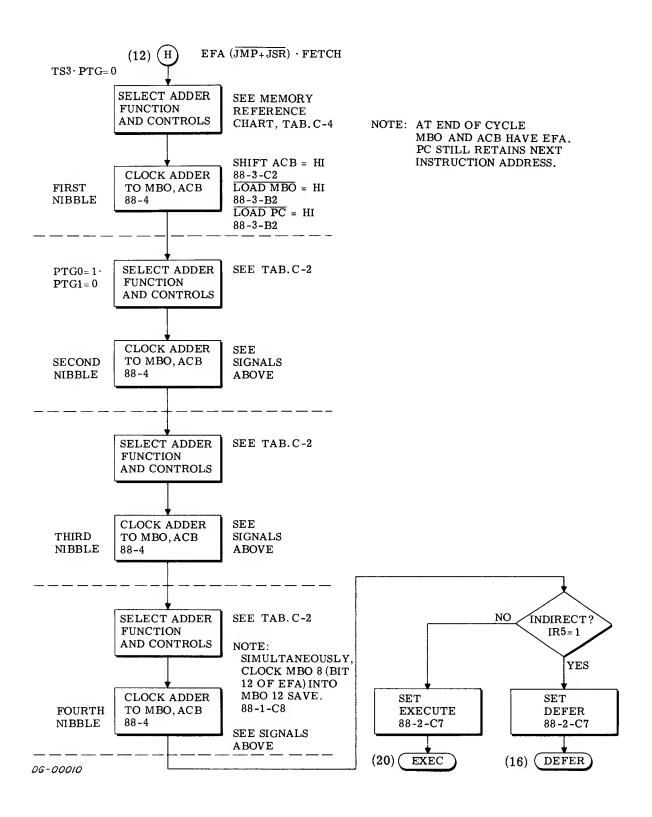


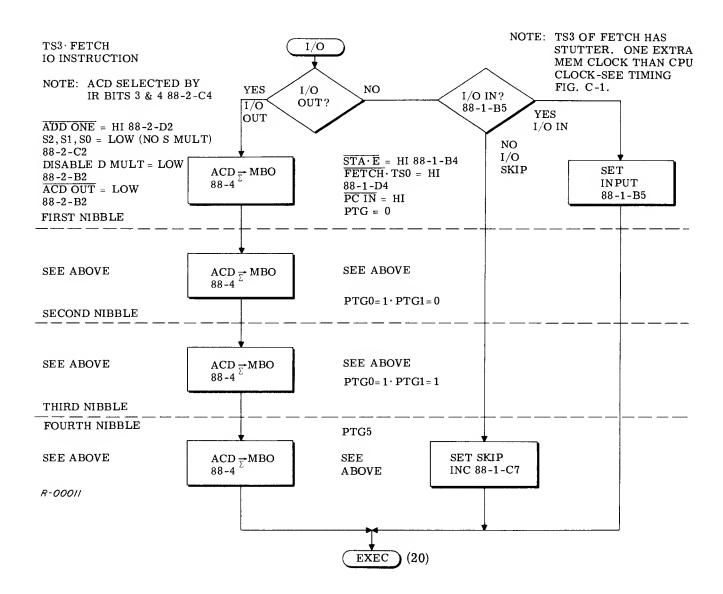


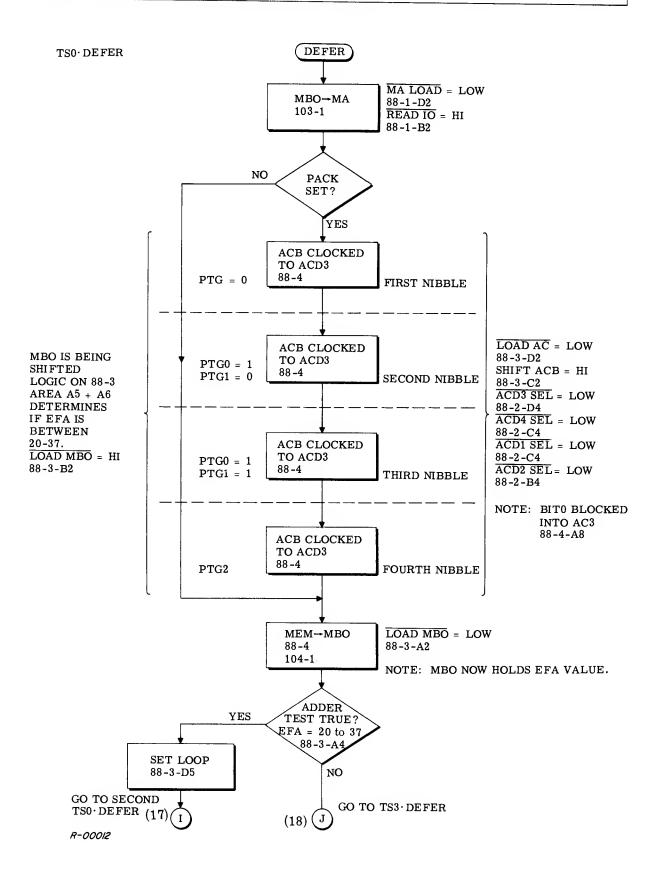


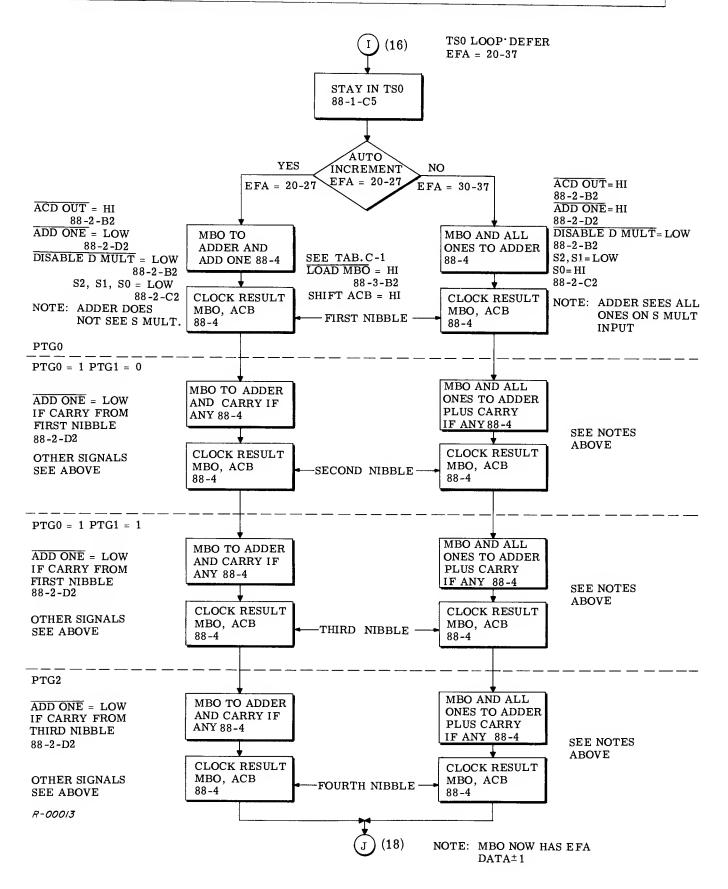


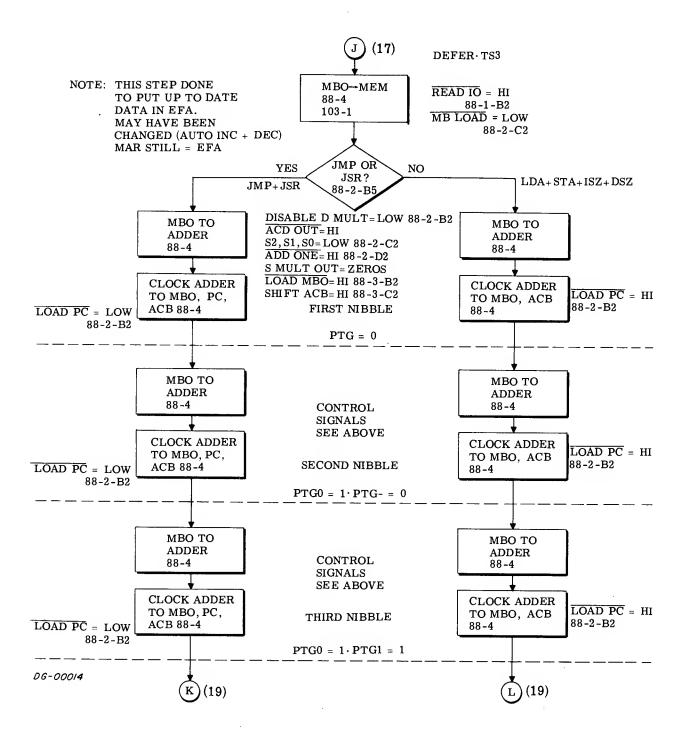


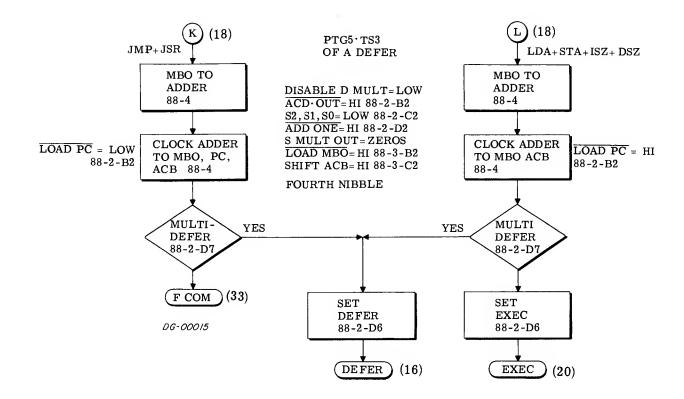


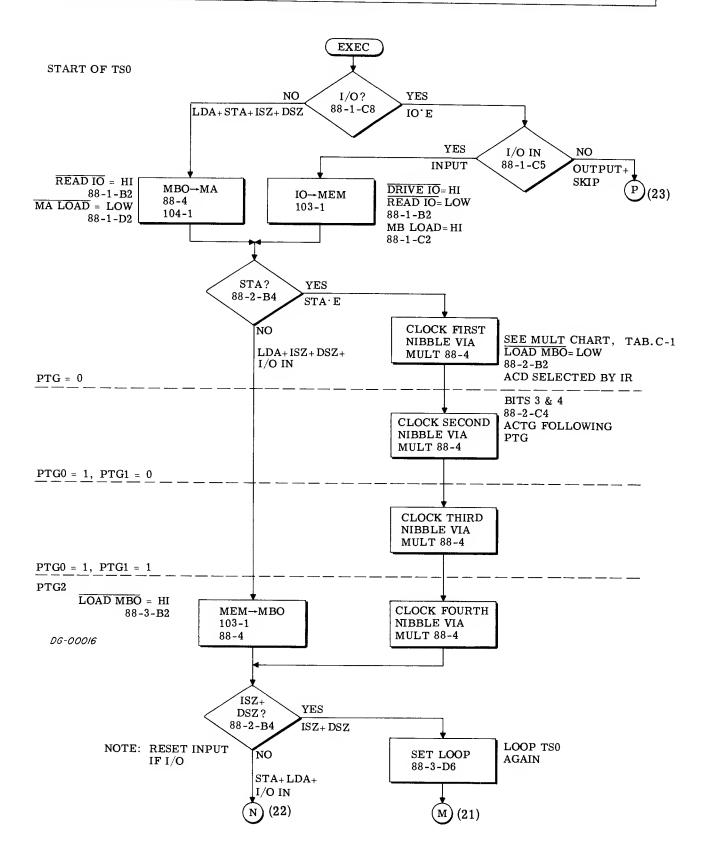


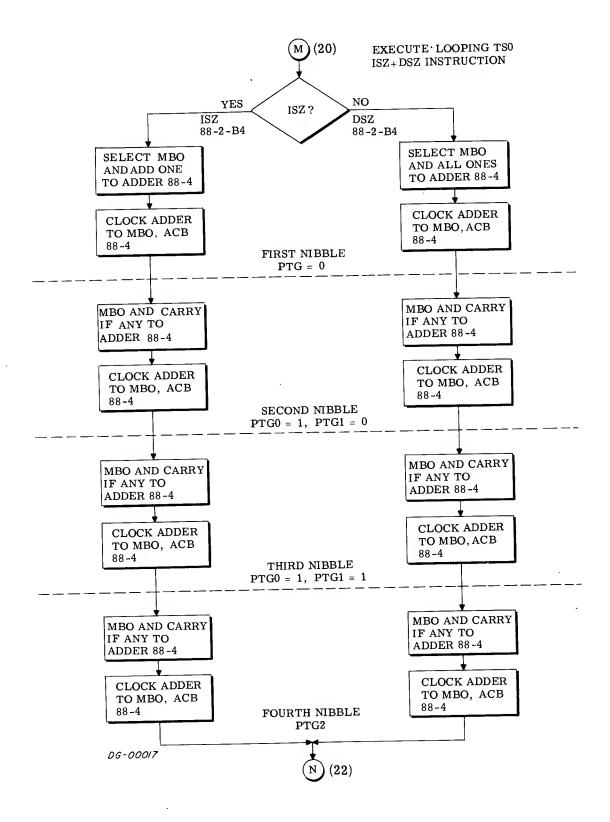


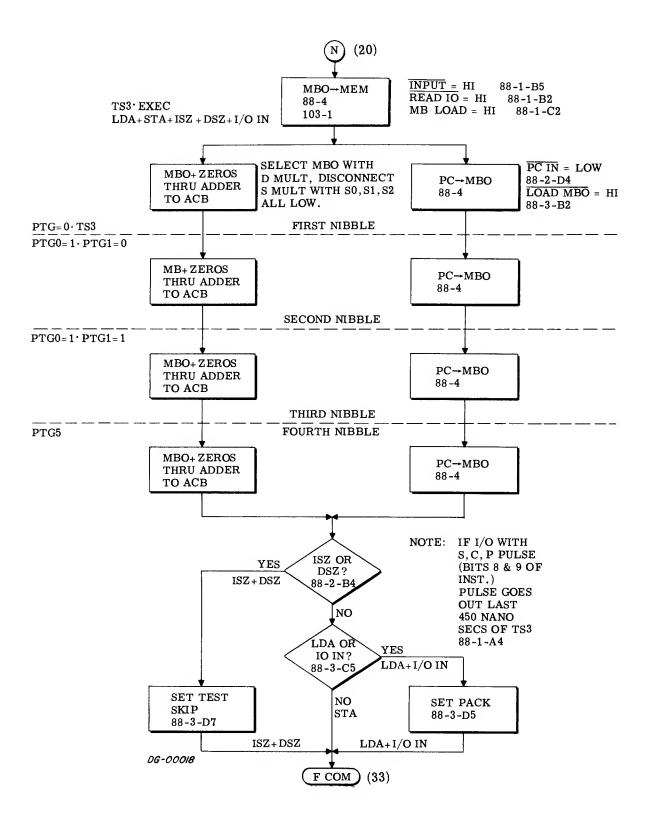


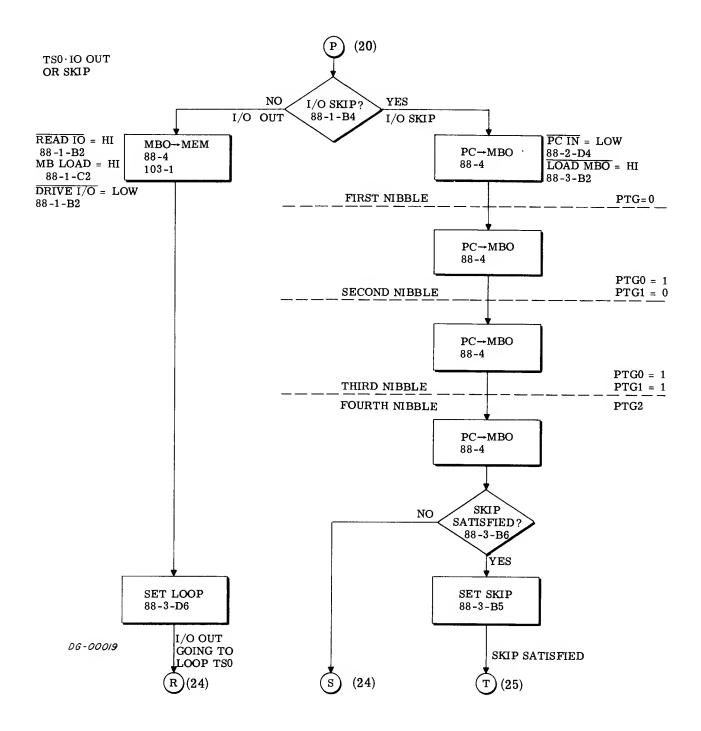


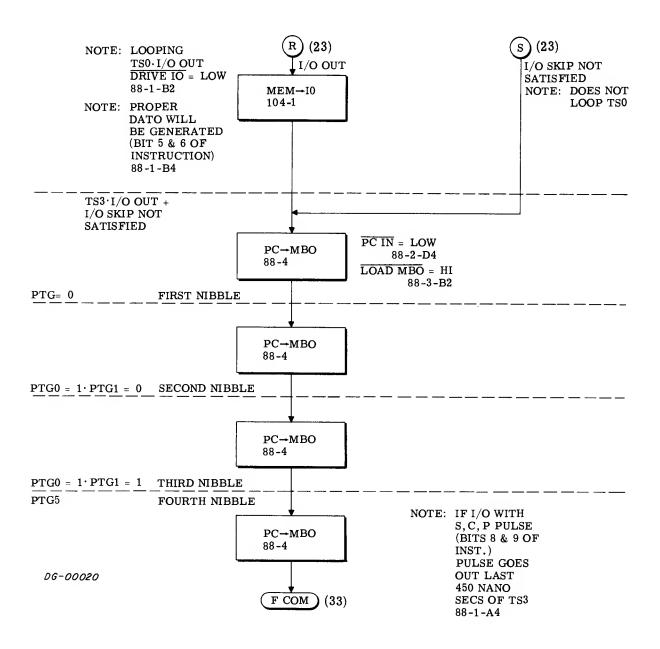


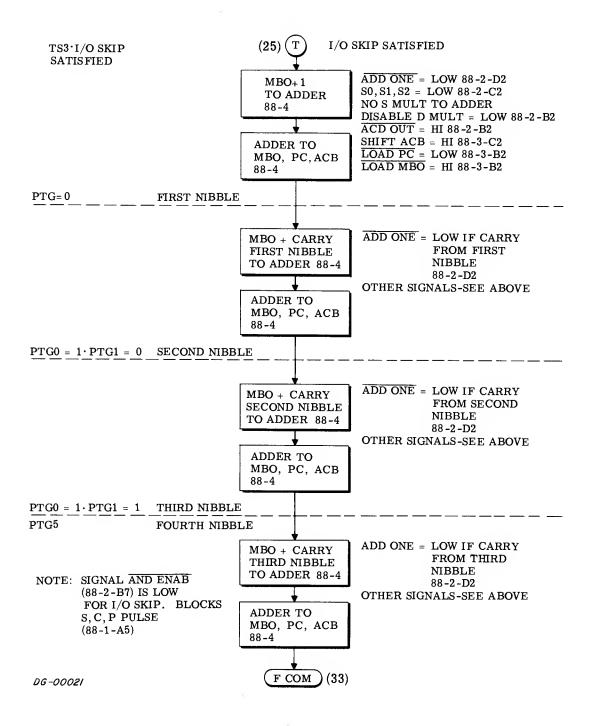


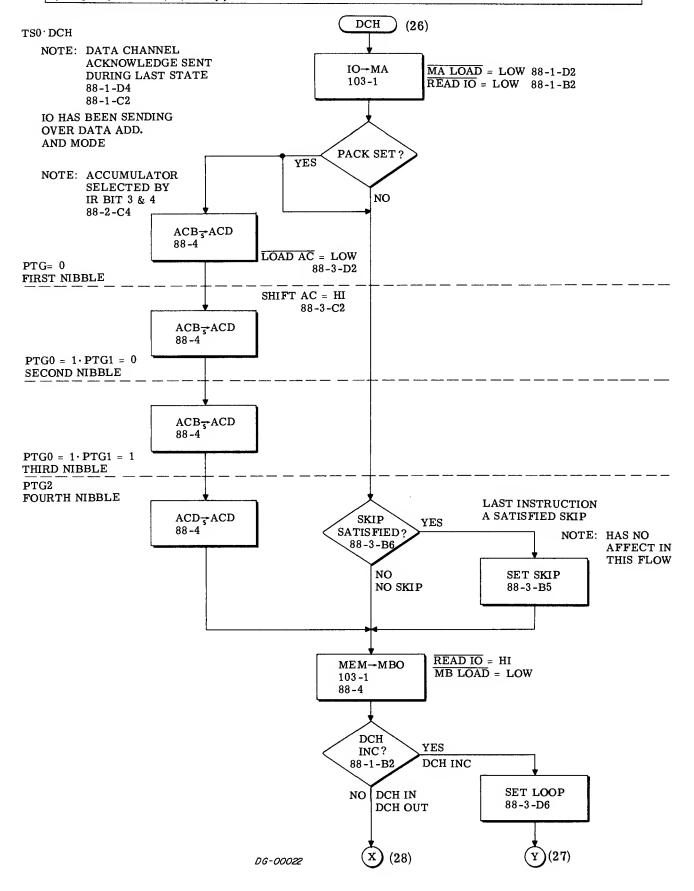


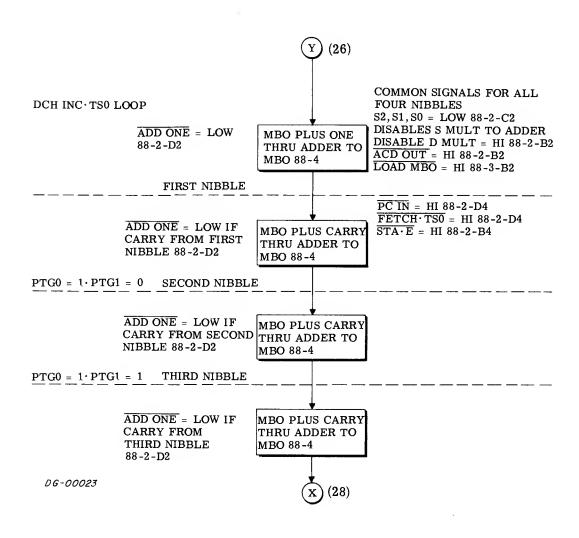


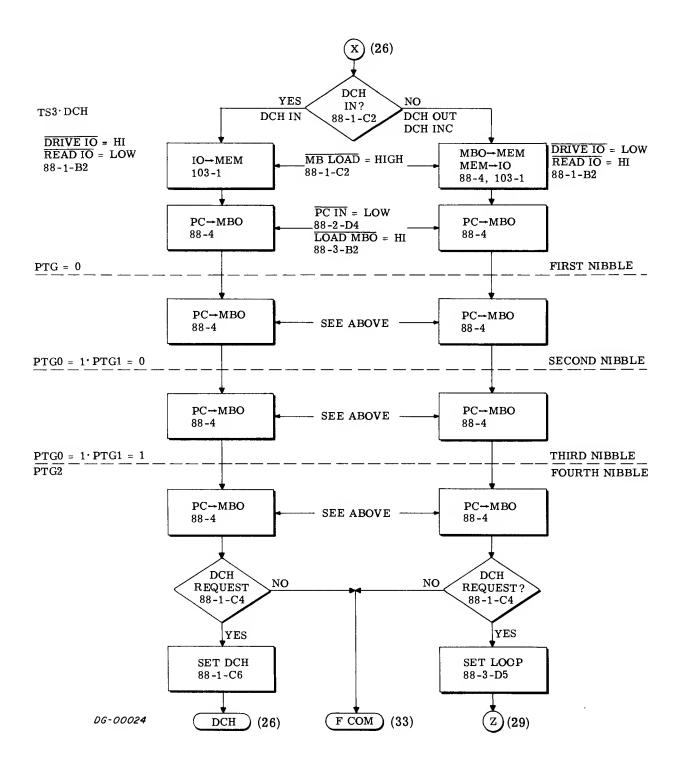


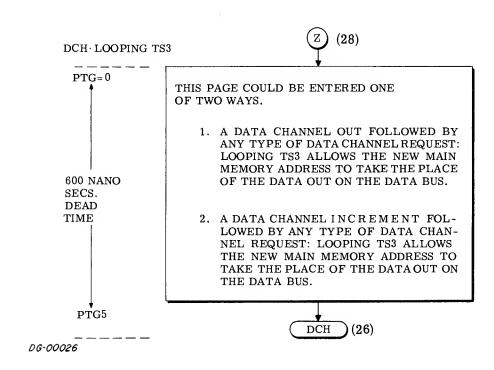




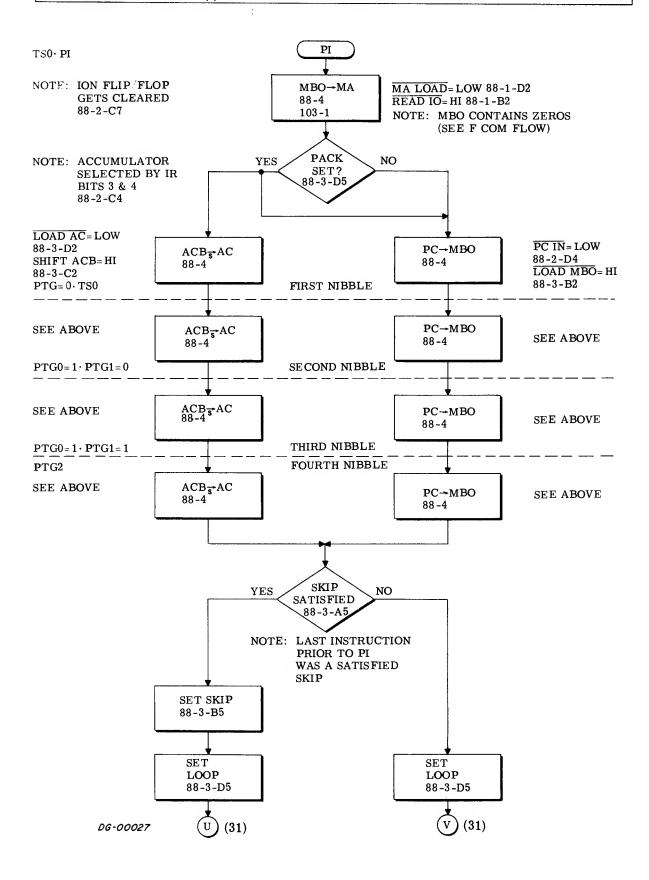


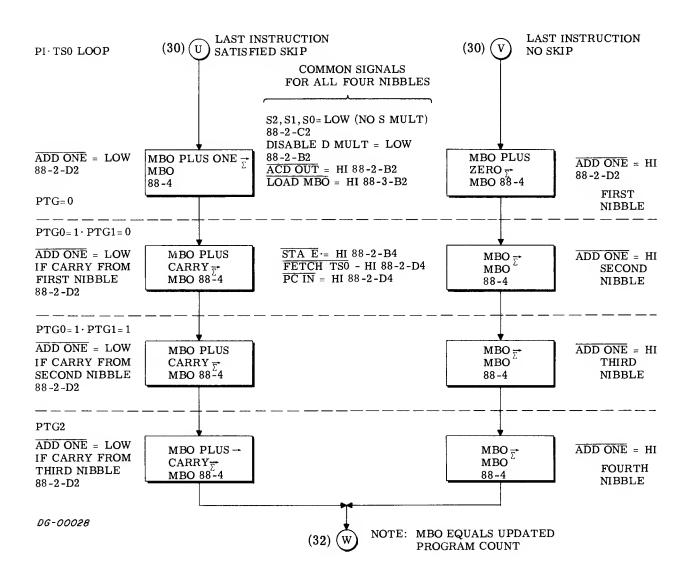


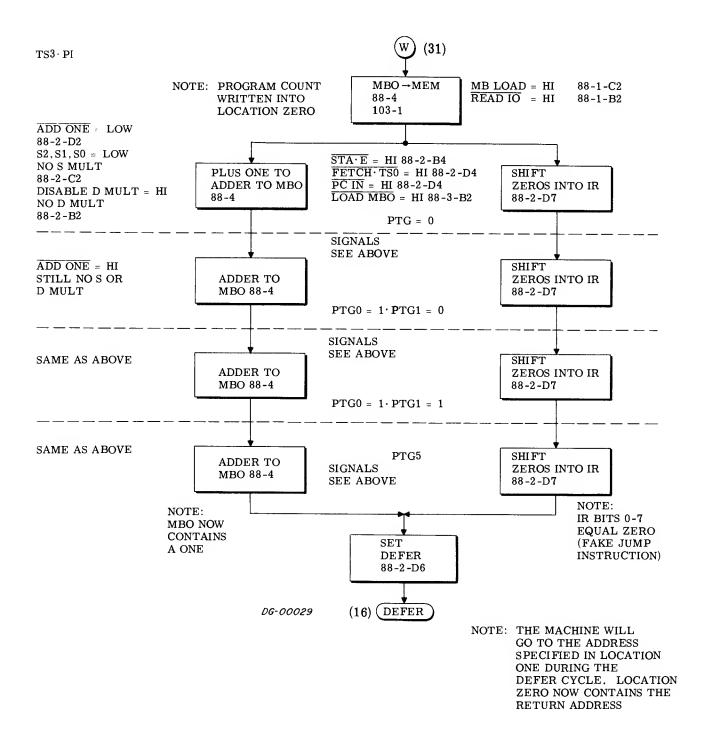


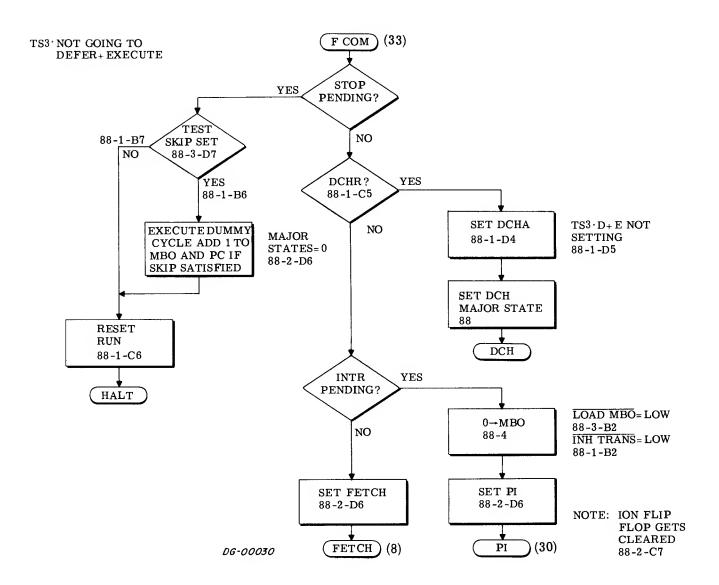


 \odot









 ${\bf Table~C-1}$ Adder and Multiplexer Control Signals During EFA Instructions

	*				*		
	S0	S1	S2	DISABLE D MULT	EFA· PTG1	ACD OUT	
REL·+(P6)	H/L	L	L	L	H/L	Н	
REL(P6)	н/н	L	L	L	H/L	Н	
(AC2) BASE +(AC3)	H/L	L	L	L	H/L	L	
(AC2) BASE -(AC3)	н/н	L	L	L	H/L	L	
PAGE ZERO	H/L	L	L	Н	H/L	H	DON'T CARE

* H for L for FIRST TWO LAST TWO NIBBLES NIBBLES

DG-00049

Table C-2
Adder Control Signals During ALC Instructions (TS3)

IR BITS 5 6 7	FUNCTION	IR5(1)=LOW DISABLE D MULT	ACD OUT	EFA · PTG1	IR6(1) = HI S0	S1	IR6(0) = HI S2	IR7(1) = LOW ADD ONE
0 0 0	COMPLEMENT	Н	L	L	L	Н	Н	Н
0 0 1	NEGATE	Н	L	L	L	Н	Н	L
0 1 0	MOVE	Н	L	L	Н	L	L	Н
0 1 1	INCREMENT	Н	L	L	Н	L	L	L
1 0 0	ADD COMPLEMENT	L	L	L	L	Н	Н	Н
1 0 1	SUBTRACT	L	L	L	L	Н	Н	L
1 1 0	ADD	L	L	L	Н	L	L	Н
1 1 1	AND	L	L	L	Н	Н	L	L
88-2 A7 & 6		88-2-B2	88-2 B2	88-2 A2	88-2 C2	88-2 C2	88 -2 C2	88-2 D2

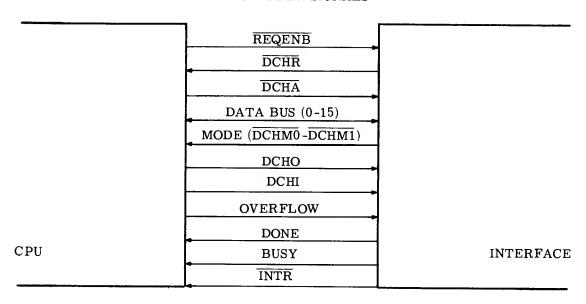
Table C-3
Carry Chart For ALC Instruction

PRIOR TO INSTRUCTION	IR 10	BITS 11	OVERFLOW OCCURRED?	CARRY AT COMPLETION
CARRY RESET	0	0	NO	RESET
CARRY RESET	0	0	YES	SET
CARRY SET	0	0	· NO	SET
CARRY SET	0	0	YES	RESET
CARRY RESET	0	1	NO	RESET
CARRY RESET	0	1	YES	SET
CARRY SET	0	1	NO	RESET
CARRY SET	0	1	YES	SET
CARRY RESET	1	0	NO	SET
CARRY RESET	1	0	YES	RESET
CARRY SET	1	0	NO	SET
CARRY SET	1	0	YES	RESET
CARRY RESET	1	1	NO	SET
CARRY RESET	1	1	YES	RESET
CARRY SET	1	1	NO	RESET
CARRY SET	1	1	YES	SET

Table C-4
Memory Reference Instruction Decoding Chart

IR	(0	1	2	3	4		
Í	0	0	0	0	0	JMP	SINGLE CYCLE(FETCH)
NO AC	0	0	0	0	1	JSR	EXCEPT DEFER(BIT5=1)
NO AC	0	0	0	1	0	ISZ]
į	0	0	0	1	1	DSZ	TWO CYCLE(FETCH & EXEC)
AC	0	0	1	AC	CD	LDA	EXCEPT DEFER(BIT5=1)
AC)	0	1	0	AC	CD	STA	J

DATA CHANNEL SIGNALS



SEQUENCE:

- 1. REQENB TO I/O
- 2. DCHR TO CPU
- 3. \overline{DCHA} TO I/O
- 4. a. MAIN MEMORY ADDRESS ON DATA BUS TO CPU
 - b. MODE BITS TO CPU (SEE TABLE)
- 5. DATA ON DATA BUS DIRECTION DETERMINED BY TYPE OF OPERATION.
- 6. DCHO OR DCHI TO INTERFACE
- A. OVERFLOW LINE APPLIES ON TO INCREMENT MODE
- B. DONE, BUSY AND INTR SAME AS NORMAL I/O

MODE BIT TABLE

DCHM0	DCHM1	FUNCTION					
H	H	OUT (WRITE)					
Н	L	INCREMENT					
L_L	Н	IN (READ)					
L	L	NOT USED					

Figure C-6 Data Channel Signals

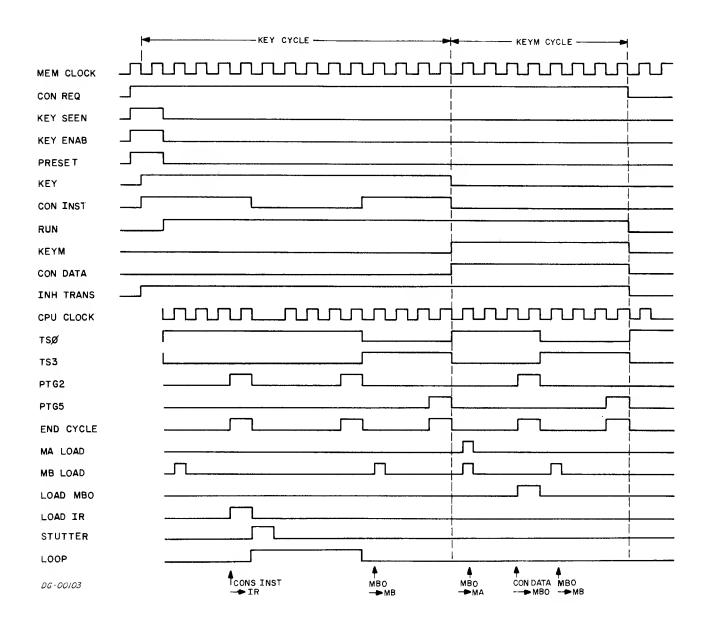


Figure C-7 Deposit Timing Diagram

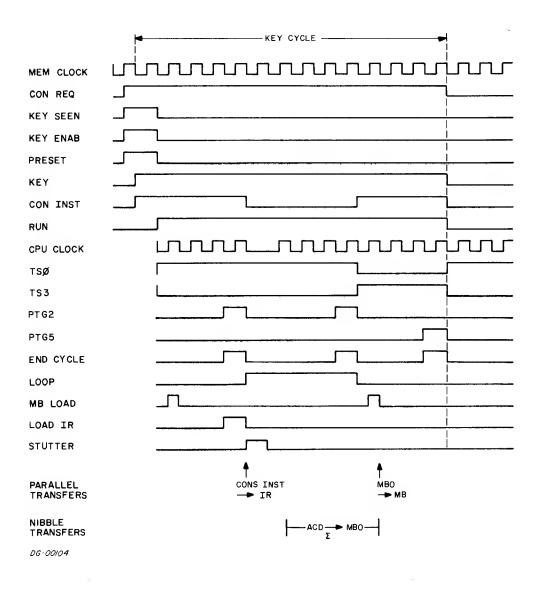


Figure C-8 Examine AC1 Timing Diagram

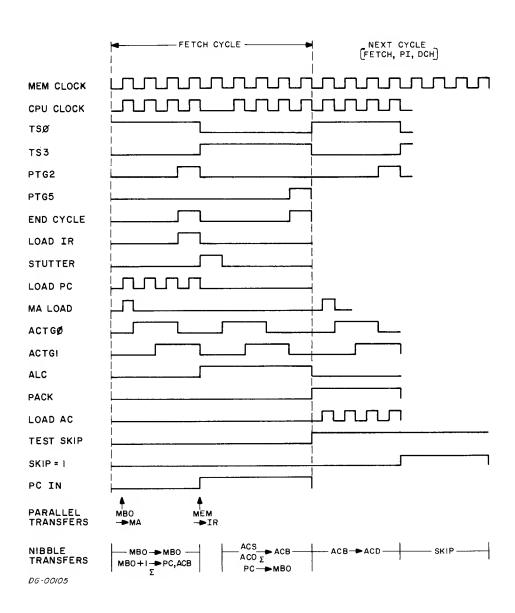


Figure C-9 ADD0, 1, SKP Timing Diagram

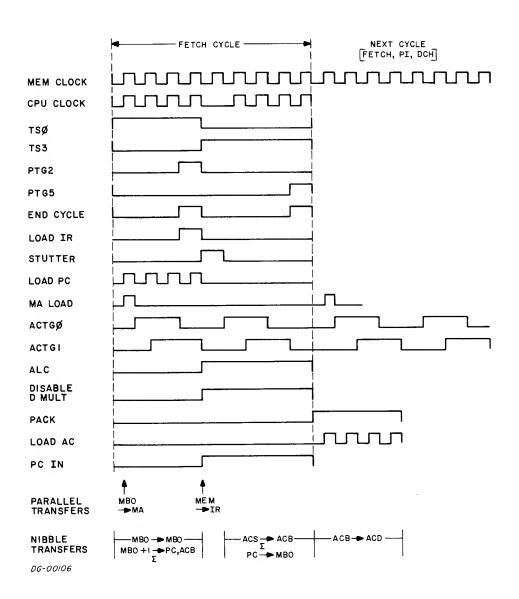


Figure C-10 MOV 0, 0 Timing Diagram

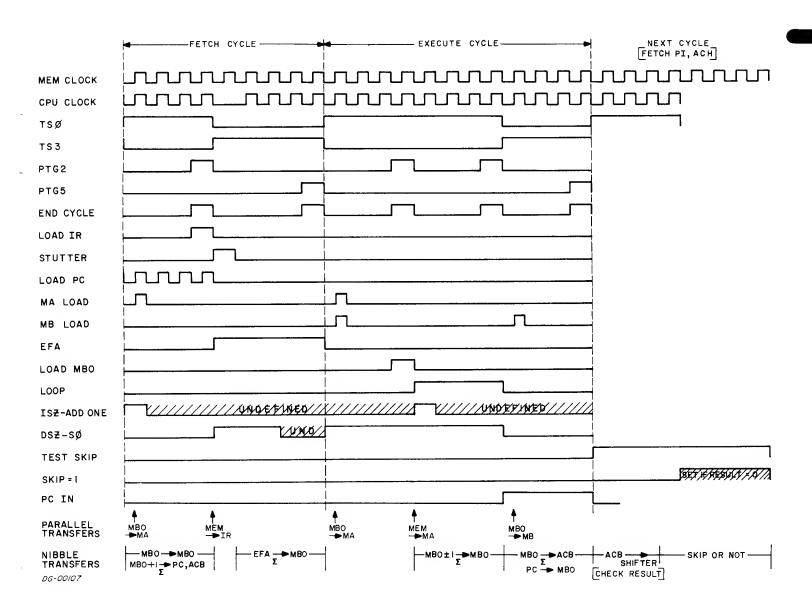


Figure C-11 Timing Diagram For Both The ISZ And DSZ Instructions

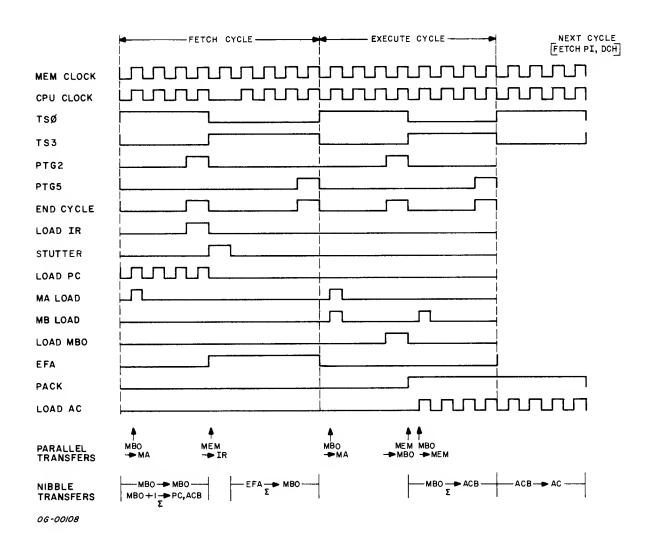


Figure C-12 LDA Timing Diagram

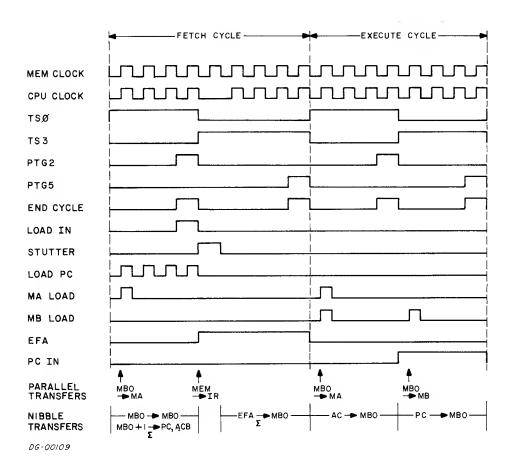


Figure C-13 STA Timing Diagram

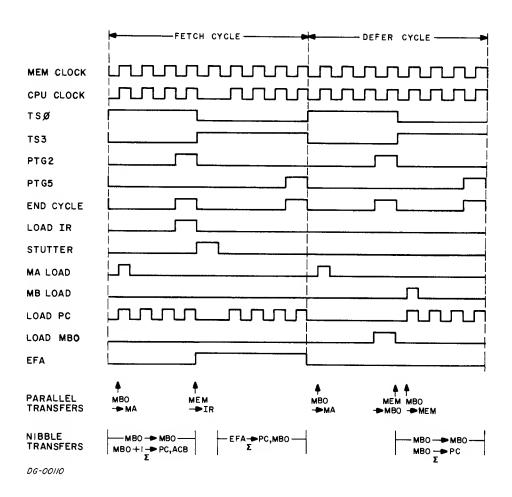


Figure C-14 JMP @ 100 Timing Diagram

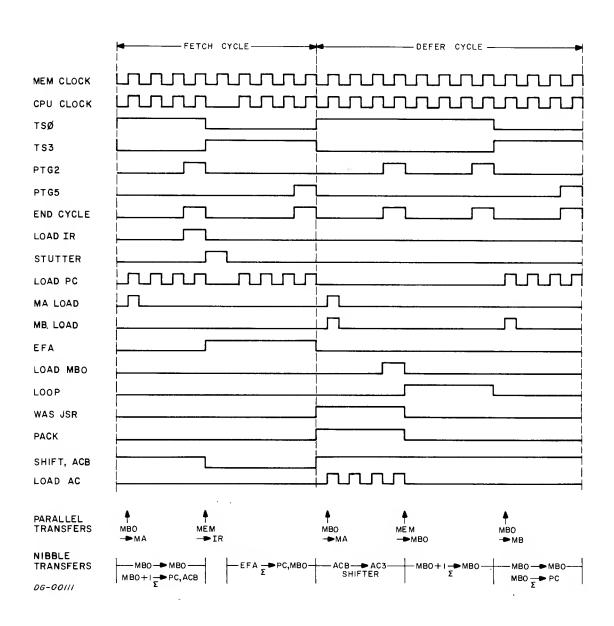


Figure C-15 JSR @ 20 Timing Diagram

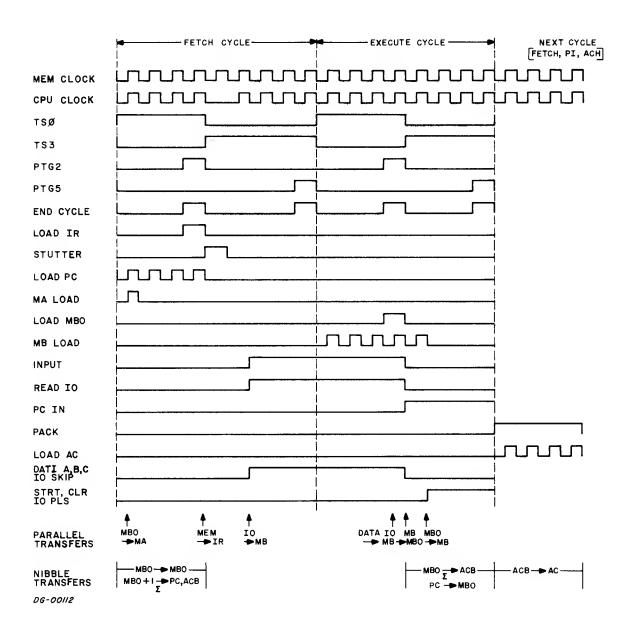


Figure C-16 I/O Input Timing Diagram

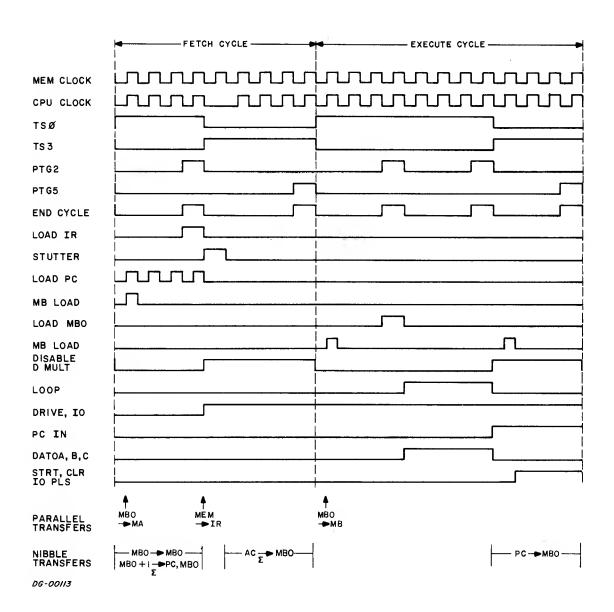


Figure C-17 I/O Output Timing Diagram

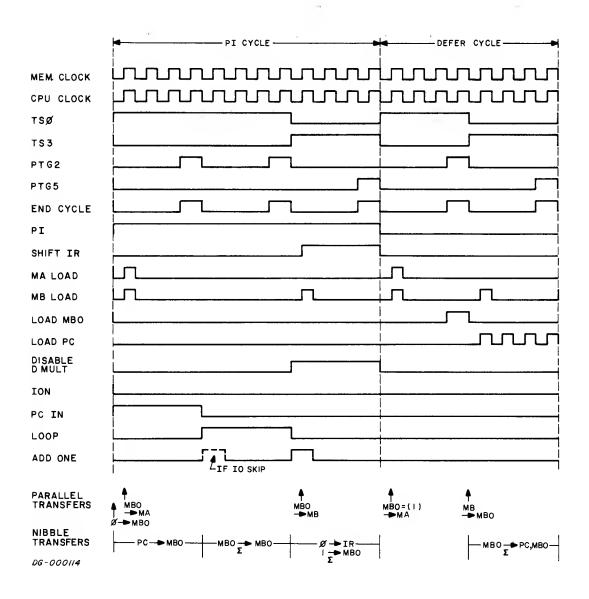


Figure C-18 PI Timing Diagram

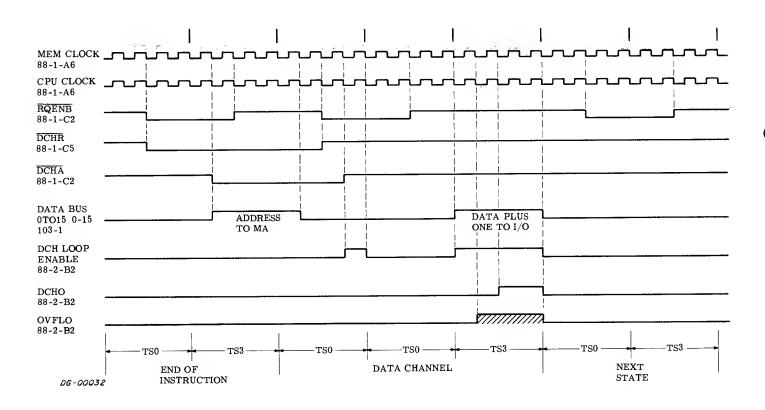


Figure C-19 Data Channel Increment Timing

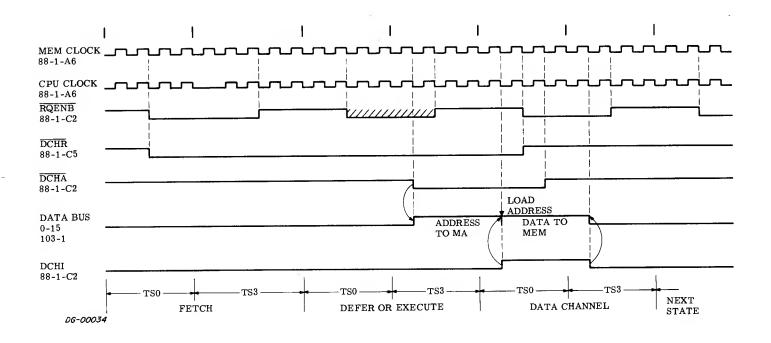


Figure C-20 Data Channel In Timing

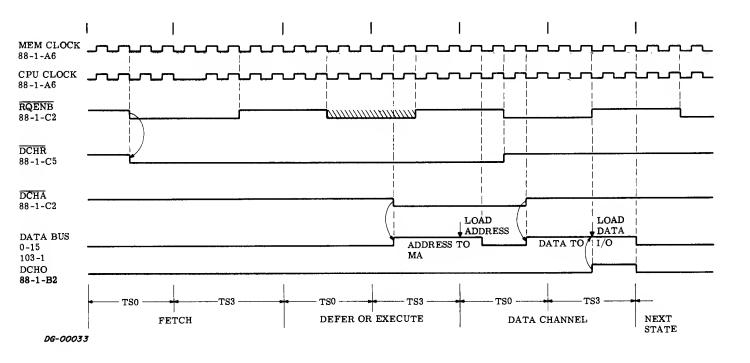


Figure C-21 Data Channel Out Timing

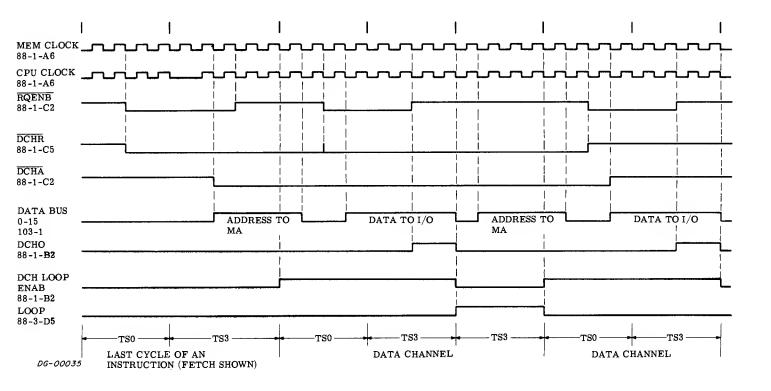


Figure C-22 Data Channel Out Followed By Data Channel In Timing

SECTION K

THE OPERATOR'S CONSOLE

INTRODUCTION

The console illustrated in Figure K-1, has a set of ADDRESS lights which display the contents of the MBO bus; a set of DATA lights which display the contents of the MEM bus; a register of toggle switches which will output to the MEM bus; a row of control switches at the bottom of the panel which instruct the computer on what to display in the lights, what to do with the information in the toggle switches, where to start or stop and how. The console also has a three position keyed rotary switch which turns power on and off and locks some of the operating switches.

CONSOLE LIGHTS AND SWITCHES

All the lights in the console are continually drawing about 10ma each through series resistors, so their filaments are always hot (but not glowing) and large surge currents are avoided when the filaments are driven on.

The Console ADDRESS Lights

These lights are always showing the state of the MBO bus which is driven directly from the MBO register. When the machine is running, the MBO register is continually shifting, so the display is meaningless; when the machine is stopped, the MBO register shows the contents of the PC, i.e., the next address.

The Console DATA Lights

These lights are always showing the state of the MEM bus. When the machine is running this bus carries data from memory to the instruction and MBO registers; when the machine is stopped this bus contains the contents of the memory buffer of the last memory selected.

The Console Operational Indicators

These lights are driven directly from their corresponding flip-flops in the central processor.

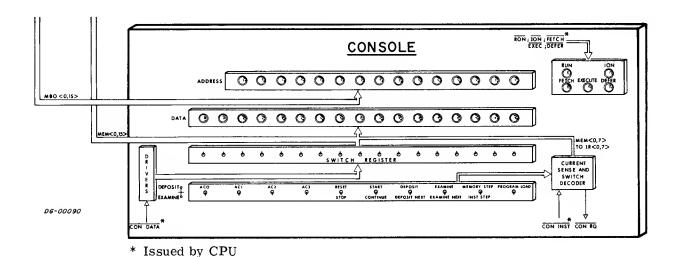


Figure K-1 The Console

The Console Switch Register

These switches connect non-inverting open collector buffers directly to the MEM bus. All Drivers go low when the $\overline{\text{CON DATA}}$ level goes low; $\overline{\text{CON DATA}}$ is issued by the CPU during the READS instruction or during a console operation that requires input from these switches, such as EXAMINE.

The Console Control Switches

All the control switches except STOP and RESET are wired through pull-up resistors to a common circuit which detects when current is flowing through a switch, initiates a delay to suppress contact bounce and then issues the signal $\overline{\text{CON REQ}}$ to the CPU. This signal forces the CPU into the key sequence shown in Figure K-2 which returns the signal $\overline{\text{CON}}$ $\overline{\text{INST}}$ to the console. $\overline{\text{CON INST}}$ connects switches AC0, AC1, AC2, AC3, DEPOSIT, DEPOSIT NEXT, EXAMINE and EXAMINE NEXT through a decoder to the MEM <0, 7> lines, which are input to the Instruction Register and interpreted as shown in Table K-1. The computer then goes into either the KEY or KEYM major state and follows the flows of Figure K-3.

The switches RESET, STOP, MEMORY STEP, IN-STRUCTION STEP and PROGRAM LOAD are wired separately to the CPU. RESET stops the computer at the end of the current cycle, issues the IORST pulse to all I/O devices, clears ION and sets the real time clock to the line frequency. STOP simply stops the computer at the end of the current instruction. MEMORY STEP takes the processor through the current state and then stops. INST STEP takes the processor through the current state and on to the end of the current instruction. Both signals force a $\overline{\text{CON}}$ $\overline{\text{RQ}}$ to the CPU and output $\overline{\text{MSTP}}$ and $\overline{\text{ISTP}}$ respectively. PROGRAM LOAD deposits the contents of the bootstrap ROM into locations 0-37 and the machine at location 0. It outputs the signal $\overline{\text{PL}}$ to the CPU.

The Console Rotary Switch

This switch controls the primary power to the power supply. It has three positions:

OFF

- the primary power is removed from the power supply
ON

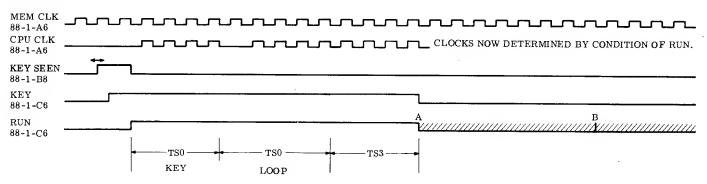
- the primary power is applied to the power supply

LOCK

- the primary power is applied to the power supply but the STOP RESET switch is disabled

REFERENCES

- 1. "How To Use The Nova Computers" 015-000009-00.
- 2. Nova 800/1200 Console Print D-001-000089-05.



- A. RUN RESETS IF KEY WAS AC EXAMINE OR AC DEPOSIT.
 NEXT STATE IF RUN DOES NOT RESET;
 KEYM-IF KEY WAS DEPOSIT, DEPOSIT NEXT, EXAMINE, EXAMINE NEXT OR PROGRAM LOAD.
 FETCH-IF KEY WAS START
- B. RUN RESETS IF KEY WAS DEPOSIT, DEPOSIT NEXT, EXAMINE OR EXAMINE NEXT.

NOTE: IF KEY WAS CONTINUE, INSTRUCTION STOP OR MEMORY STOP



Figure K-2 The CPU Key Sequence Timing Diagram

CONSOL	E									,
INSTRUCT	ION	IR0	IR1	IR2	IR3	IR4	IR5	IR6	IR7	IR8 TO 15
	AC0	0	0	1	0	0	0	1	1	0
AC	AC1	0	0	1	0	1	0	1	1	0
DEP.	AC2	0	0	1	1	0	0	1	1	0
	AC3	0	0	1	1	1	0	1	1	0
	AC0	0	1	1	0	0	1	1	1	0
AC	AC1	0	1	1	0	1	1	1	1	0
EXAM.	AC2	0	1	1	1	0	1	1	1	0
	AC3	0	1	1	1	1	1	1	1	0
DEPOSIT		1	1	0	1	1	1	0	1	0
DEPOSIT NEX	T	1	1	0	1	1	1	0	0	0
EXAMINE		1	1	1	1	1	0	0	1	0
EXAMINE NEX	ζT	1	1	1	1	1	1	0	0	0
MEMORY STE	P	1	1	1	1	1	1	1	1	0
INSTRUCTION	STEP	1	1	1	1	1	1	1	1	0
PROGRAM LO	AD	1	1	1	1	1	1	0	1	0
START		1	1	1	1	1	0	1	1	0

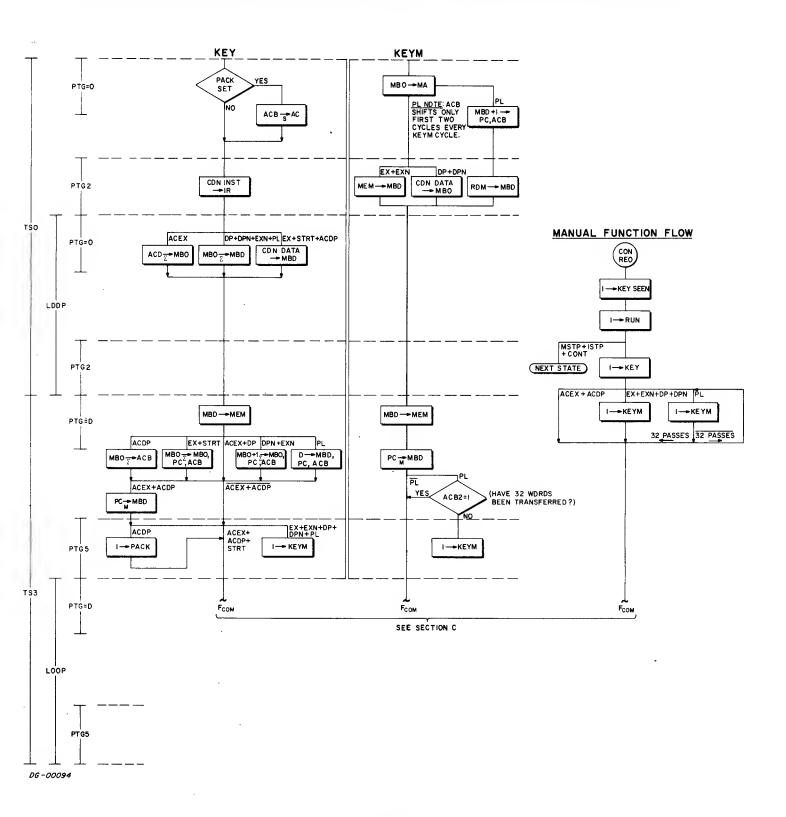


Figure K-3 Key, KEYM and Manual Flow Diagrams

Table K-2
Backpanel Connections To The Console
Through POA

POA PIN	SIGNAL	BACKPANEL PIN	POA PIN	SIGNAL	BACKPANEL PIN
1	GND	B1	27	+ 5	B4
2	MEM15	B18	28	MBO15	A41
3	MEM14	B76	29	MEM13	A35
4	MBO13	A37	30	MBO12	A39
5	MEM12	A36	31	MEM11	A51
6	MBO11	B5	32	MEM10	A45
7	MEM9	A53	33		N/A (BUS TO
'				+V _{LAMP}	POWER SUPPLY)
8	$\overline{\text{MBO9}}$	В9	34	MEM8	A55
9	MBO7	B14	35	MBO6	B16
10	MEM6	B22	36	MEM5	B26
11	MBO5	B32	37	MEM4	B28
12	MBO14	A43	38	MBO3	B43
13	$\overline{\text{MEM2}}$	B47	39	MEMO	B71
14	MBO1	B77	40	LAMP	GND
15	$\overline{ ext{MBO2}}$	B44	41	MEM1	B70
16	MBO4	B42	42	MEM7	B24
17	GND	B2	43	MEM3	B68
18	$\overline{\text{MBO8}}$	B12	44	MBO10	B8
19	RESTART				
i	ENABLE	A32	45	STOP	A31
20	RST	A30	46	CONT DATA	A28
21	CON RQ	A27	47	CONT+ISTP+	
]				MSTP	A25
22	CON INST	A22	48	MSTP	A20
23	$\overline{ ext{PL}}$	A19	49	CARRY	A15
24	<u>IST</u> P	A17	50	FETCH	A13
25	ION	A16	51	EXEC	A11
26	RUN	A14	52	DEFER	A12

This Page Left Blank
Intentionally

SECTION P

POWER SUPPLY

INTRODUCTION

The Nova 1220 power supply is mounted on the backpanel below the circuit boards where it converts either 110Vac at 60Hz or 220Vac at 50Hz to regulated, current limited 5Vdc, -5Vdc, +15Vdc for the logic and memories, and to unregulated 6.3Vac for the real time clock. With the power monitor and restart option, the power supply interrupts the computer when it detects a line voltage failure (less than 90% of nominal) stops the computer when the voltage gets too low for reliable operation, and issues a start pulse to the computer when the line voltage recovers.

POWER SUPPLY CIRCUITS

The 30V Unregulated Supply

110Vac or 220Vac are input through the power cord to a switch on the console S1, then on to transformer T1. The two primaries of T1 are wired in parallel for 110Vac, and in series for 220Vac. Note that the cooling fan operates on 110Vac only.

The secondary of the transformer is wired to two full wave bridge rectifiers which output approximately 30V and -15V into RC filters. The 30V is applied to two series pass switching regulators which supply the regulated +5Vdc and +15Vdc. The 15V is applied to a simple linear regulator for the -5Vdc.

The Series Pass Switching Regulators

A series pass switching regulator acts like a multivibrator which sets when it detects a low output voltage and resets when it detects a high output voltage. When the regulator is set, it gates current from the 30V supply into an LC circuit and the load; when the regulator is reset, the load draws all of its power from the LC circuit until the circuit is sufficiently exhausted to be recharged by the regulator. The frequency at which the regulator sets and resets varies from 0 to 25KHz depending on the load.

There are two such regulators in the 1220 power supply, one for the +15 Vdc (Figure P-1) and the other for the +5 Vdc (Figure P-2). The -5 Vdc is controlled by a linear regulator.

Note that the outputs of these circuits are DC levels with about .15V ripple at frequencies which vary with the loads.

The Fuses

The 1220 power supply has two fuses, a 10 amp between the power cord and the switch S1, and a 15 amp just after the bridge rectifier. The 10 amp will blow if there is a short in the cabling to S1, or if the convenience receptacle is overdrawing; the 15 amp will blow if the +15Vdc or +5Vds levels rise high enough to trigger an SCR, which then creates a short between the 30V supply and ground.

The Power Fail Module

This module detects a line voltage failure and outputs the signals shown in Table 2.

REFERENCES:

- 1. Fairchild Semiconductor Integrated Circuit
 Data Catalog Fairchild Semiconductor 1970
- Backpanel Nova 1220 print No. D-001-000208-00
- Backpanel 1220 Power Supply print No. D-001-000173-02.

Table P-1

Nova 1220 Power Supply Specifications

Output Voltage Level Name	Output Voltage	Maximum Current	Used On	Remarks
+ 15V	14.5-15.1Vdc (.15V ripple)	9A	XY Drivers	Full wave rectified; Short Circuit & Over- voltage Protection Regulated
5 V	-5 7V dc	1A	Sense Amplifiers	Full wave rectified; Current limited by a resistor, regulated
+ 5 V	5.2-5.4Vdc	20A	IC Logic	Full wave rectified; Short Circuit & Over- voltage Protection Regulated
TTY	-5→-7Vdc (.15V ripple)		Teletypewriter	Full wave rectified; Current limited by a resistor, regulated
RINH<0,15>	14.5-15.1Vdc	760mA each	Inhibit Driver	Full wave rectified; Short Circuit & Over- voltage Protection, Regulated
60Hz	6.3Vac	500mAc	Real Time Clock	This signal has the same frequency as the line (input) voltage
A10(VINH)	14.5-15.1Vdc (.15V ripple)	6Adc	Memory In- hibit Logic	Current Limited
B84(VINH)	14.5-15.1Vdc (.15V ripple)		Memory Drivers	Turns off memory drivers at about +12Vdc
^{+ V} LAMP	≈14-16Vdc	2Adc	Console Lamps	Unfiltered, Unregu- lated

Table P-2
Output Signals of the Nova 1220 Power Fail Module

SIGNAL NAME	SIGNAL FUNCTION
PWR FAIL	-sets the PWR LOW flag in the processor when the line voltage drops to 90% of nominal voltage.
MEM OK	-resets the RUN flag and stops the com- puter when the + Vmem (+15Vdc) voltage goes too low for the memory to function reliably.
+ 5OK	-sets the RUN flag and starts the com- puter when the +5Vdc has risen to 4.4 Vdc.

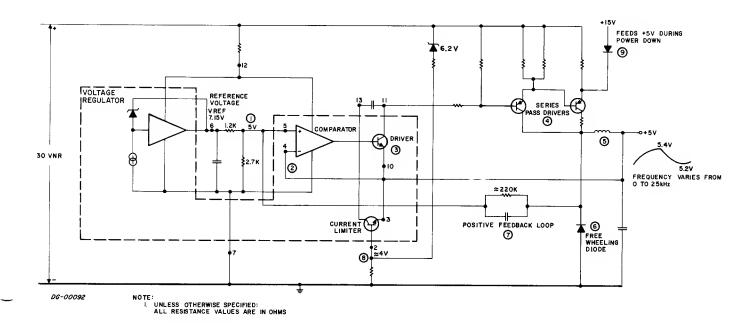


Figure P-1 Simplified Schematic of the +5Vdc Series Switching Regulator. When the comparator senses a difference between the (divided) reference voltage (1) and the output voltage (2) it switches, turning on the driver transistor (3) and consequently the series pass transistors (4). Current is shunted through the series pass transistors to the coil, output capacitor and load (5). The output voltage rises, reducing the error voltage to the comparator, which resets, turning off the driver (3) and consequently the series pass transistors. Now the load is supplied from power stored in the LC circuit. The back emf developed across the coil as a result of this switching is dropped across the free wheeling diode (6). Note that each time the comparator is forced to switch it is driven into saturation by the positive feedback loop which includes the 220K resistors (7).

The current limiter (8) turns on if the output voltage drops below about 4V, turning the driver (3) and subsequently the series pass transistors (4) off. The supply is latched in this state until power is removed and then returned.

The diode (9) feeds current from the 15V supply to +5V during power-down, driving the memory supply off early and the logic supply off later.

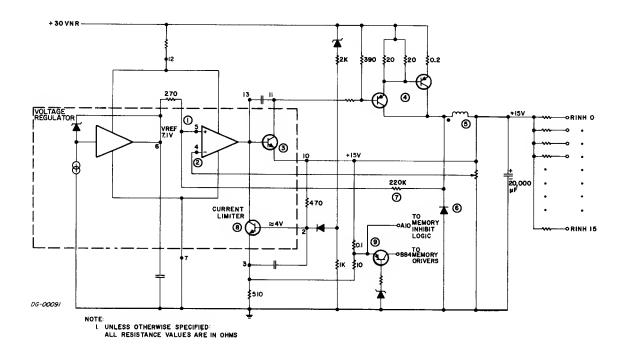


Figure P-2 Simplified Schematic of the +15Vdc Series Switching Regulator. When the comparator senses a difference between the reference voltage (1) and the divided output voltage (2), it switches, turning on the driver transistor (3) and consequently the series pass transistors (4). Current is shunted through the series pass transistors to the coil, output capacitor and load (5). The output voltage rises, reducing the error voltage to the comparator, which resets, turning off the driver (3) and consequently the series pass transistors. Now the load is supplied from power stored in the LC circuit. The back emf developed across the coil as a result of this switching is dropped across the free wheeling diode (6). Note that each time the comparator is forced to switch it is driven into saturation by the positive feedback loop which includes the 220K resistor (7).

The current limiter (8) turns on if the output voltage V MEM drops too low, or if the current at either terminal of (9) (memory inhibit and memory drive) is too high. When on, the current limiter turns off the driver and subsequently the series pass transistors, latching the supply into this mode until power is removed and then returned.

The transistor at (9) will switch off when the +15V drops too low for memory to function properly, thus removing power to the memory drivers.

SECTION M

THE MEMORY

A REVIEW OF CORE MEMORIES

A "bit" of information can be stored in a ferrite core by magnetizing the core in one of two possible directions or "states" and then calling one state a "1" and the other state a "0", similar to a flip-flop. Unlike a flip-flop, however, a core cannot be read simply by examining its output voltages; a core is read by forcing it into the "0" state and then watching for the current pulse which is always generated when a core changes state. If the pulse occurs, then the core must have been in the "1" state before it was excited; if no pulse occurs then the core must already have been in the "0" state because no transition took place.

Reading a core, then, always leaves it in the "0" state and although the information that it contained has probably been transferred to some register which was set by the current pulse, that information is no longer in the core, and it usually has to be restored with what is called a "write cycle". Writing means setting the core to a one or a zero, depending on the state of the memory register that usually contains core bound information.

Reading or writing into a core is a matter of sending current pulses along wires into the core; the direction of current relative to the core determines into which state the core will move.

Data General's core memories contain many thousands of these ferrite cores strung together like beads on wire. Each core has three wires passing through it, and these wires carry the currents to magnetize them and the pulses which occur when they change state. The memories are wired so that the computer can select any group of 16 bits at once, and read or write a complete 16 bit word "in parallel". A group of 16 cores, called an "address" is picked by passing current down two selected wires called X and Y, which are strung into the cores so that they both pass through only one address. The combined effect of current in these two wires is enough to flip the core into the zero state if it is not already there. Each core that flips sends a pulse down its own third wire called the sense wire which is then fed into one flip-flop of a 16 bit Memory Buffer. The flip-flop sets if it sees a pulse, and remains static if it does not. The register which selects the X Y wire or "lines" is called the Address Register.

Restoring the contents of the address involves resetting those core bits that set ones into the Memory Buffer. This is done by sending reverse currents down all the X and Y lines of that address, and inhibit currents to these bits which should remain in the "0" state. The contents of the memory buffer could be changed before this write-cycle so that new information is entered into the address.

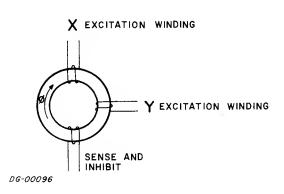


Figure M-1 Simplified Schematic of a Memory Core

A core will remain in the "one" state until currents pass through the X and Y excitation windings and force it into the "zero" state. The transition causes a pulse to travel down the sense winding to the detection logic. The core can be reset to the

"one" state by reversing the currents in the X and Y windings. The transition will still cause a pulse to be generated in the sense and inhibit winding, but the sense logic is disabled at this point.

SECTION N

MAINTAINING THE COMPUTER

INTRODUCTION

The Data General Corporation supports its equipment with a large field service organization, customer training programs and technical documentation. This section summarizes these services and includes tips on preventive maintenance, recommended tools and trouble shooting.

FIELD SERVICE ORGANIZATION

Field Service Programs

Data General's Field Service Organization currently offers its users a choice of three maintenance services. These services are subject to change without notice.

- 1. On Call Service Contract under which DGC will repair equipment at the installation when DGC is notified of a problem by the user. DGC also provides preventive maintenance on a regular schedule under this contract. Parts, labor and travel are included in the monthly payment schedule which is determined by the type and amount of equipment to be serviced and the distance between the installation and the nearest DGC service center.
- 2. Factory Service Contract under which DGC will:
 - (1) repair equipment when it is returned to the DGC factory in Southboro, Mass. The user assumes full responsibility for freight and insurance charges to and from the plant. Parts and labor are included in the monthly payment schedule.
 - (2) repair equipment at the installation when notified of a problem by the user. Parts are included in the monthly maintenance schedule, labor is charged at reduced rates and travel is charged at the prevailing standard rates.
- 3. Hourly Service under which parts, labor and travel are charged as needed at prevailing rates. No contract is signed for this service.

Field Service will also generate on request a complete spare parts list for any installation, and rent or sell replacement and loaner boards.

General Terms and Conditions (Subject to change without notice).

- 1. Equipment which is not under a DGC service contract or normal warranty is subject to an inspection by DGC Field Service before it is eligible for a service contract. All costs for this inspection are borne by the user.
- The user must bear all maintenance costs incurred as a result of unauthorized changes to DGC equipment. These costs will be charged as <u>Hourly Service</u>, regardless of the type of <u>service</u> contract existing between DGC and the user.
- 3. No additional service charge will be added for new (add-on) equipment until the warranty period of that equipment has expired.
- All services are offered between 9 a.m. and 5 p.m. Monday through Friday excluding DGC holidays.
- 5. The minimum contract period is 6 months.
- 6. Field Service price schedules are available on request from Data General Field Service, Southboro, Mass. 01772, Telephone 617-485-9100.

TRAINING ORGANIZATION

Data General's Training Organization currently offers its users four types of training courses. These courses are subject to change without notice.

Mainframe Maintenance Course. This course covers the logical structure of the central processor, memory, operator's console and power supply. Students must have experience with digital logic, integrated circuits and computer principles.

Fundamentals of Mini-Computer Programming.
This course covers number systems, logic, flow charts and computer architecture. Students should have an aptitude for mathematics.

Basic Programming. This course covers Data General's assembly language utility software including loaders, editors, debuggers and assemblers. Students should have experience in programming.

Advanced Programming. This course covers Data General's Operating Systems, DOS, RTOS and SOS. Students must have experience in programming.

Courses are scheduled regularly in the training department at Southboro, Mass., and occasionally in field offices. Special courses can be arranged.

For more information call or write

Training Department
Data General Corporation
Southboro, Mass. 01772

Tel. 617-485-9100

PREVENTIVE MAINTENANCE

Periodically carry out the checks listed in Table, N-1, and remember the following points:

- 1. It is very poor practice to use the equipment as a counter top, particularly for liquids like coffee or soft drinks.
- 2. Always check the line voltage before plugging an expensive piece of equipment into an unknown socket. (see Section I).
- 3. Be careful not to get metal filings into the equipment; for example never let the equipment room be cleaned with steel wool.
- 4. Never clean the equipment with a vacuum cleaner that has a metal (conducting) nozzle.
- 5. Always be aware that too much heat, moisture or contaminants can do much to harm the equipment (see Section I).
- 6. Be very careful how cables are routed; they should never be strained, cramped or crushed (underfoot).

Table N-1

Preventive Maintenance Check List							
Item	Check						
Mechanical Connections	1. that all screws are tight and that all mechanical assemblies are secure.						
	2. that all crimped lugs are secure and properly inserted onto their mating connectors.						
Wiring and Cables	1. all wiring and cables for breaks, cuts, frayed leads, or missing lugs.						
	2. wire wraps for broken or missing pins.						
	3. that no wires or cables are strained or cramped.						
	4. that cables do not interfere with doors, and that they do not chafe when doors are opened and closed.						
Air Filters	all air filters for cleanliness and for normal air movement through cabinets.						
Modules and Components	1. that all modules are properly seated. Look for areas of discoloration on all exposed surfaces.						
	2. all exposed capacitors for signs of discoloration, leakage, or corrosion.						
	3. power supply capacitors for bulges.						
Indicators and Switches	all indicators and switches for tightness; check for cracks, discoloration, or other visual defects.						
Fans	for broken fan blades.						
Diagnostics	Run all diagnostics periodically						

Table N-2

Recommended Maintenance Tool Kit							
ITEM	QTY	DESCRIPTION	MFG. & PART No.				
1	1	6" combination slip joint pliers	Utica # 5-6				
2	2	5 1/2" needle nose pliers	Utica # 654-5 1/2				
3	1	4" needle nose pliers	Utica # 23-4				
4	1	5" diagonal wire cutters	Utica # 44-5				
5	1	4" diagonal wire cutters	Utica # 347-4 CFJS				
6	1	5" ignition pliers	Utica # 517-5				
7	1	Screwdriver kit including handle, 3/16", 1/4", 5/16" slotted #1, #2 phillips blades, each 4" long	Xcelite # 99 PV-6				
8	1	3/32 slotter screwdriver with 2" blade	Xcelite # R3322				
9	1	1/8" #0 phillips screwdriver	Xcelite # P12S				
10	1	Magnetic pick up tool	Bonney # K26				
11	1	3/32 through 3/8, 10 pc nut driver set	Xcelite # PS120				
12	1	Xacto knife					
13	1	6" adjustable wrench	Utica # 91-6				
14	1	Ignition wrench	Bonney # N24R				
15	1	Set of 25 feeler gauges with 3" blades	Bonney # K53				
16	1	Set of 15 hex keys	Bonney # N6R				
17	1	Slotter 5" screw starter	Bonney # 5527				
18	1	Phillips 6 1/4" screw starter	Bonney # 556				
19	1 1	5" adjustable wire strippers	Utica # 110-5				
20	1	Set of 4 cut needle files	Hunter # F228A				
21	1	4 1/2" electrical tweezers	Hunter # B3M3				
22	1	flash light					
23	1	Can Quick Freez (circuit cooler)					

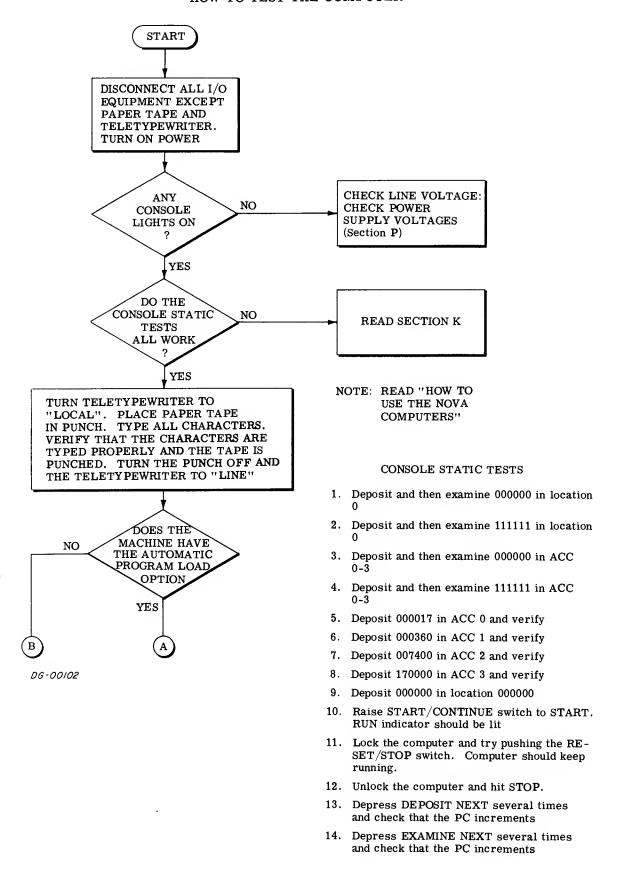
Table N-2 (Continued)

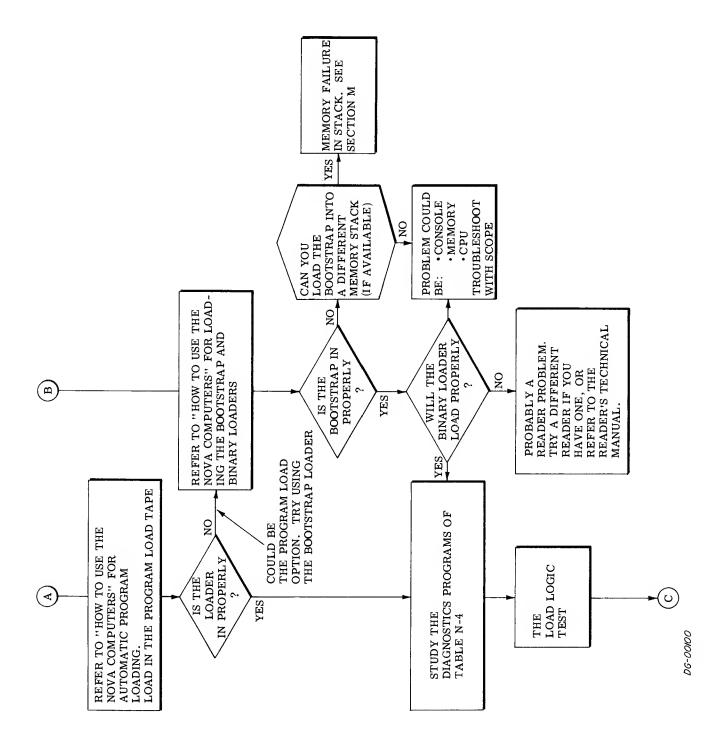
	Recommended Maintenance Tool Kit							
ITEM	QTY	DESCRIPTION	MFG & PART No.					
24	1	Can degreaser (flux remover)						
25	2	16P I/C test clip						
26	1	23 1/2 watt soldering iron with iron plated chisel tip	Ungar					
27	1	47 1/2 watt soldering iron element						
28	1	11b, 60/40 resin core solder	Kester					
29	3	Spools of solder wick						
30	2	Acid brushes						
31	1	Vacuum solder removal tool						
32	1	Multimeter	Simpson # 260					
33	1	Tool carrying case						
34	1	Oscilloscope	Tektronics # 453					
35	1	Current probes	Tektronics # P60-22					

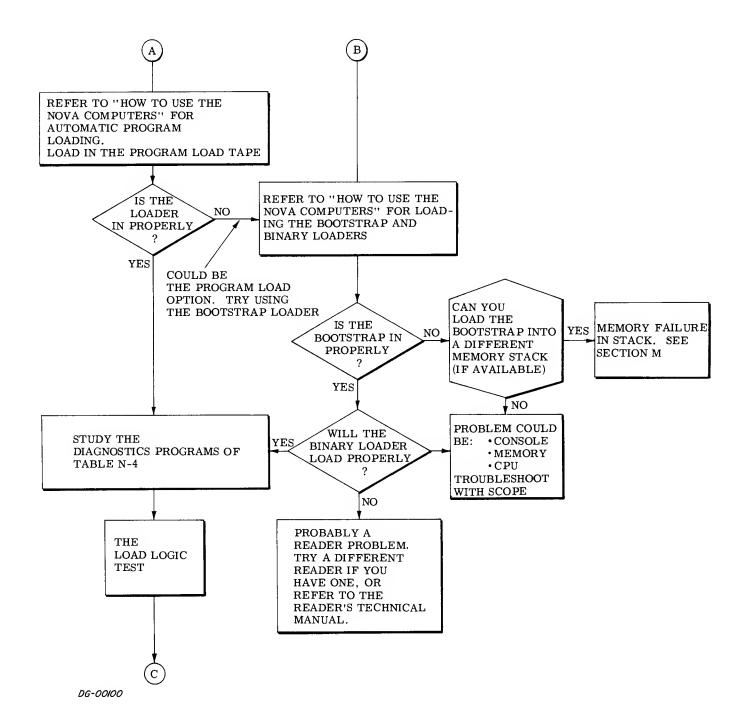
Table N-3

	The Nova 1220 Diagnostics									
Diagnostic	Part No.	Binary Tape No.	Description							
Address Test	097-000007	095-000005	checks memory address selection logic							
Checkerboard III	097-000014	095-000031	tests memory sense amplifiers and inhibit logic							
Nova 1220 Logic Test	097-000017	095-000036	tests CPU logic other than I/O							
Nova 1220 Instruction Timer	097-000019	095-000038	tests CPU clock logic and outputs time-to-complete for each instruction							
Exerciser	097-000004	095-000012	tests CPU logic, teletypewriter, reader, punch and real-time clock;							
Arithmetic Test	097-000018	095-000037	exercises arithmetic and logical instructions in CPU							

HOW TO TEST THE COMPUTER







SECTION M

THE MEMORY

A REVIEW OF CORE MEMORIES

A "bit" of information can be stored in a ferrite core by magnetizing the core in one of two possible directions or "states" and then calling one state a "1" and the other state a "0", similar to a flip-flop. Unlike a flip-flop, however, a core cannot be read simply by examining its output voltages; a core is read by forcing it into the "0" state and then watching for the current pulse which is always generated when a core changes state. If the pulse occurs, then the core must have been in the "1" state before it was excited; if no pulse occurs then the core must already have been in the "0" state because no transition took place.

Reading a core, then, always leaves it in the "0" state and although the information that it contained has probably been transferred to some register which was set by the current pulse, that information is no longer in the core, and it usually has to be restored with what is called a "write cycle". Writing means setting the core to a one or a zero, depending on the state of the memory register that usually contains core bound information.

Reading or writing into a core is a matter of sending current pulses along wires into the core; the direction of current relative to the core determines into which state the core will move.

Data General's core memories contain many thousands of these ferrite cores strung together like beads on wire. Each core has three wires passing through it, and these wires carry the currents to magnetize them and the pulses which occur when they change state. The memories are wired so that the computer can select any group of 16 bits at once, and read or write a complete 16 bit word "in parallel". A group of 16 cores, called an "address" is picked by passing current down two selected wires called X and Y, which are strung into the cores so that they both pass through only one address. The combined effect of current in these two wires is enough to flip the core into the zero state if it is not already there. Each core that flips sends a pulse down its own third wire called the sense wire which is then fed into one flip-flop of a 16 bit Memory Buffer. The flip-flop sets if it sees a pulse, and remains static if it does not. The register which selects the X Y wire or "lines" is called the Address Register.

Restoring the contents of the address involves resetting those core bits that set ones into the Memory Buffer. This is done by sending reverse currents down all the X and Y lines of that address, and inhibit currents to these bits which should remain in the "0" state. The contents of the memory buffer could be changed before this write-cycle so that new information is entered into the address.

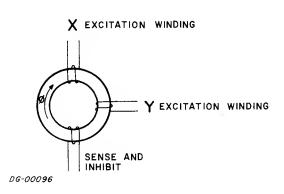


Figure M-1 Simplified Schematic of a Memory Core

A core will remain in the "one" state until currents pass through the X and Y excitation windings and force it into the "zero" state. The transition causes a pulse to travel down the sense winding to the detection logic. The core can be reset to the

"one" state by reversing the currents in the X and Y windings. The transition will still cause a pulse to be generated in the sense and inhibit winding, but the sense logic is disabled at this point.

DATA GENERAL'S CORE MEMORIES

The memories used on the basic computer consist of cores arranged in a three wire 3D scheme in which the sense and inhibit functions share the same wire. The cores are laid out in a single plane in mats, and wired together in the bow tie pattern shown in Figure M-2. There are four core planes available; 1K, 2K, 4K, and 8K. Each plane is assembled on a "daughter" board which is mounted on a 15" by 15" "mother" board, where most of the memory logic sits. Power is supplied by the chassis supply

The memory logic on any board consists of drivers, sense amplifiers, a Memory Address Register, a Memory Buffer Register, Multiplexers, and Memory select logic shown in Figure M-3.

Data is transferred between memory and the central processor or an I/O device along three data buses called:

$\overline{ ext{MEM}}$	which transfers data from memory to
	the Central Processor;

which transfers data from the Central Processor to Memory

DATA which transfers data between memory and I/O devices in either direction.

The Memory Select Logic

When a memory board is plugged into a computer, its select logic must be wired to respond to the correct code in the MA register, since the MA registers of all boards are loaded with the same address at the same time. This wiring is done with a set of jumpers that connect either the 0 or 1 side of the high order MA bits to an "and" gate. The output of this "and" gate will be true only if the code for which it is wired is in the MA register, and only when this output is true can the memory respond. This code must be unique to that memory board.

The jumpers are forced into points on the board. These points are located on the logic side of the board at the lower right hand corner when its fingers are pointing at you. If there is a mixture of boards, i.e., 1K, 2K, 4K or 8K, it is a good policy to wire the largest board for low core, the second largest above it and so on. This way there will not be any gaps in the system's core map.

Figures M-4 and M-5 show how the select logic of the four types of boards are jumpered.

REFERENCES:

8K	Memory Prints	#001-000238-00
4K	Memory Prints	#001-000236-00
2K	Memory Prints	#001-000234-00
1K	Memory Prints	#001-000232-00

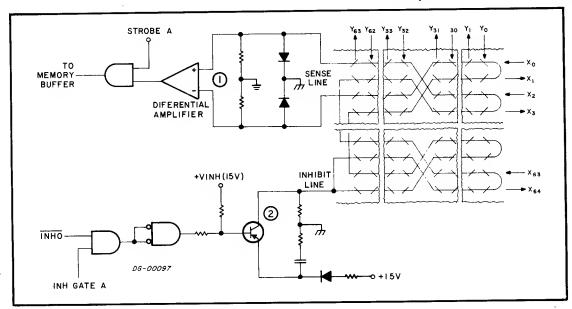


Figure M-2 Simplified Schematic of The Core Memory's Sense and Inhibit Lines

The sense and inhibit functions share the same wire. The sense circuitry, (1), sees both ends of the wire, and detects negative pulses with a differential amplifier. The output of this amplifier is examined at STROBE time.

The inhibit logic, (2), drives +15Vdc level into the middle of the same wire at INHIBIT time. The current is divided and passes through all cores to ground through the diodes at the other end.

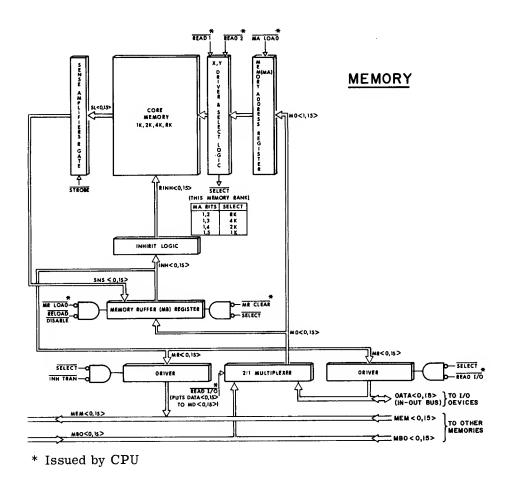


Figure M-3 Core Memory

During a typical FETCH instruction, the CPU outputs the memory address on the MBO <0, 15> data lines and then issues $\overline{\text{MA LOAD}}$. READ I/O is high, so the address is strobed into the Memory Address register and output to the driver select logic. Then, READ 1 and READ 2 are issued gating the X and Y currents to the selected address. A little later, STROBE is output by the CPU and it gates all core pulses into their corresponding Memory Buffer bits. The Memory Buffer is then re-read back into core by reversing all the driver currents and gating the INHIBIT signal issued by the CPU to those bits which are not to be reset. If the contents of the address are to change, the Memory Buffer is loaded with the new word before the address is re-written.

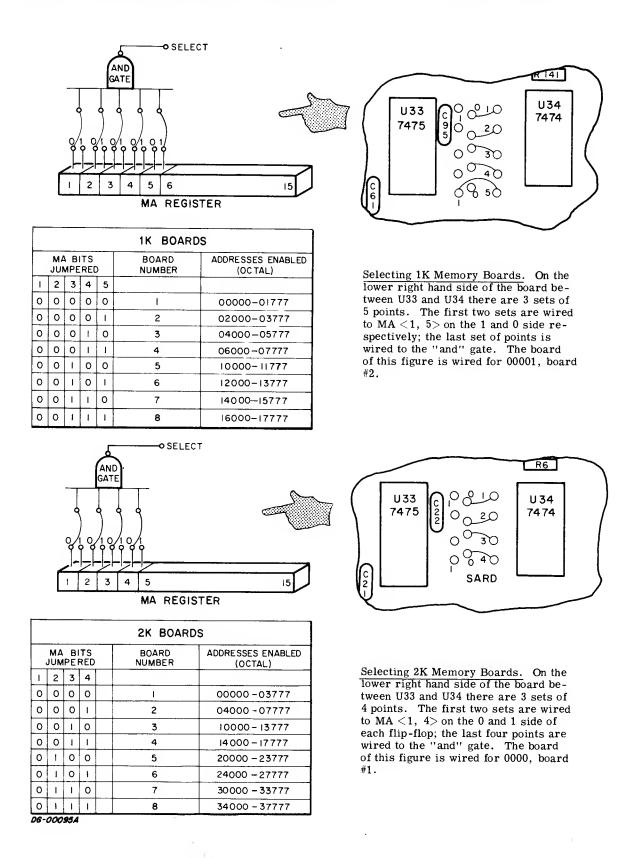
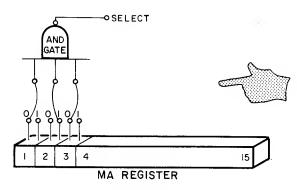


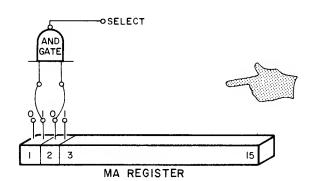
Figure M-4 Wiring Up The Select Logic of 1K and 2K Boards



			R6	
<u> </u>	U33 7475	0 2 0 2 0 3 0 0 4 0 SARD	U34 7474	
		- SAND		

	4K BOARDS							
	MA BITS JUMPERED)	80ARD NUMBER	ADDRESSES ENABLED (OCTAL)		
1	2	3						
0	0	0			1	00000-07777		
0	0	Ι			2	10000-17777		
0	1	0			3	20000-27777		
0		1 1			4	30000 37777		
.1	0 0			5	40000-47777			
1	0	ı			6	50000-57777		
I	1	0			7	60000-67777		
ı	I	Ι			8	70000~77777		

Selecting 4K Memory Boards. On the lower right hand side of the board between U33 and U34 there are 3 sets of 4 points. The first two sets are wired to MA <1, 3> on the 1 and 0 sides respectively, the last set is wired to the "and" gate. The board of this figure is wired for 010, board #3. Sard 4 should NOT be jumpered.



	U30 7475	00 0 R U31 9009	
		C88 0 C3	
_			منن

	8K BOARDS							
		BIT PER	-	BOARD NUMBER	ADDRESSES ENABLED (OCTAL)			
Т	1 2							
0	0			I	00000 - 17777			
0	0 1			2	20000 - 37777			
ı	1 0			3	40000-57777			
1	1			4	60000 - 77777			

lower right hand side of the board between U30 and U31 there are 2 sets of 6 points. The first set is wired to MA <1,3> on the 1 and 0 sides; the second set is wired to the "and" gate. The board of this figure is wired for 10, board #3. Position 3 should NOT be jumpered.

Selecting 8K Memory Boards. On the

DG-00095B

Figure M-5 Wiring Up The Select Logic of 4K and 8K Boards

Table M-1

External Memory Signals

SIGNAL NAME	FUNCTION
DATA <0, 15>	16 bidirectional lines which carry information to and from devices on the IN-OUT bus.
DRIVE I/O	Issued by CPU-1 to strobe the MB register onto DATA <0, 15> lines.
INH TRAN	Issued by CPU-1 to prevent the MB register from outputting to the MEM <0 , 15> bus during a data transfer from the console.
INHIBIT SELECT	Issued by CPU-1 to prevent the memory from being selected.
MA LOAD	Issued by CPU-1 to load the MA register.
MEM < 0, 15>	16 lines which carry information from the memory to CPU-1.
MB CLEAR	Issued by CPU-1 to clear the MB register.
MB LOAD	Issued by CPU-1 to load the MB register.
READ 1	Issued by CPU-1 to select the memory drivers.
READ 2	Issued by CPU-1 to select memory drivers.
READ I/O	Issued by CPU-1 to enable the DATA <0 , 15> lines into the MD <1 -15> lines.
RELOAD DISABLE	Issued by CPU-1 to inhibit MB Load.
STROBE	Issued by CPU-1 to strobe core pulses into the Memory Buffer.
MBO <0, 15>	16 lines which carry information from CPU-1 to memory.

SECTION I

NOVA 1220 INSTALLATION

INTRODUCTION

This section explains how to unpack, assemble and cable the computer.

PLACING THE COMPUTER

The computer room must be large enough to accommodate the equipment, operating personnel, tables and chairs, storage space (for tapes, manuals and listings), service clearances and possible future expansion. The room should be well lit and clean, with adequate primary power. The temperature and humidity must fall within acceptable tolerances of the most sensitive peripheral.

Overhead sprinklers should be "dry pipe" systems that remove primary power from the room and turn on a battery operated light source before opening the master valve. If power connections are made under the floor, use waterproof receptacles and connections. Any carpeting should be of the type that minimizes static electricity, and metal flooring should be well grounded.

UNPACKING THE COMPUTER

The computer is shipped in the kit shown in Figure I-1.

- 1. Open the top of the outer carton; remove all cables, manuals, packing filler, etc.
- 2. Remove the styrofoam container (it and contents weigh about 50 pounds) and place it on a flat surface right side up.
- 3. Unstrap the container and remove the cover and styrofoam spacers.
- 4. Carefully remove the styrofoam block from the back of the computer.
- 5. Remove the computer, placing your hands under the chassis front and back.
- 6. The computer is sometimes shipped with cardboard spacers in spare slots to keep the boards from vibrating during shipment. Remove these.

Table I-1

The Nova 1220 Electrical, Mechanical and Environmental Specifications

Voltage (AC)	NOMINAL @ 115V	Power Dissipotion (W)	Heot Dissipatian (Btu/hr)	Operating Temperature (min-mox F)	1 .	Humidity (Rel) (min-mox)	Moximum Wet Bulb	Moximum Coble Length	Dimensions (inches)	Service Clearance (inches)	Weight (Ibs)
110	9	1000	3400	32-130	-30-+160	20% 90%	78°F	IN-OUT 50FT	HEIGHT 10 1/2" WIDTH 17 1/2" LENGTH 22 1/4"	3" FRONT	PACKED 65 UN- PACKED 45

The Nova 1220 operates from a single-phase source at 115V 60Hz or ± 50 Hz all $\pm 20\%$. This device has a separate 4.5 foot power cord terminating in a standard 3 wire single-phase male connector. An earth ground connection must be supplied through the power cord.

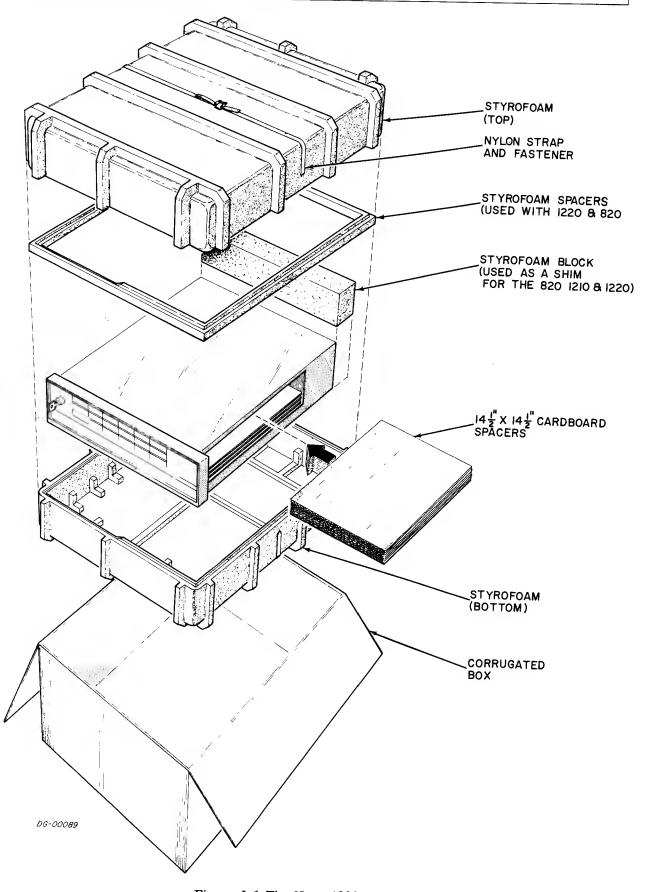


Figure I-1 The Nova 1220 Shipping Kit

PACKING THE COMPUTER

- Locate the original shipping container and packing material. If it is not available, order a shipping kit from Data General Corporation.
 DO NOT SHIP THE COMPUTER IN ANY OTHER CONTAINER.
- 2. Fill any large spaces inside the chassis with just enough cardboard spacers so the boards cannot vibrate.
- 3. Place the computer in the bottom half of styrofoam container "front justified" with the back
 end on top of the extra rib. Pack the power
 cord into the hollow area at the back. Fill in
 the space at the back with the styrofoam block
 to prevent the computer from moving during
 shipment.
- 4. Add the styrofoam spacers as needed.
- 5. Put on the cover of the styrofoam container and strap the pieces together.
- 6. Put the styrofoam container into the cardboard box. Place any odds and ends on top of the container, and fill in any empty spaces with cardboard or pieces of styrofoam.
- 7. Close and seal the cardboard box.
- 8. Call your local Field Service representative for the correct address if the equipment is to be shipped to Data General Corporation.

ASSEMBLING THE COMPUTER

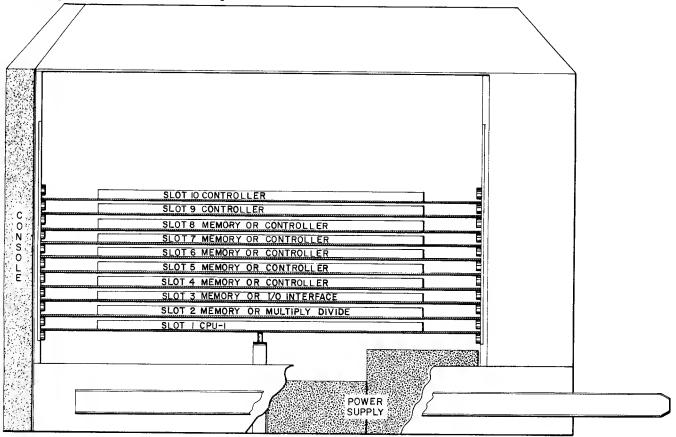
Assembling the computer outside the factory involves installing memory or controller boards or mounting the chassis into a 19" rack.

Installing or Removing Boards

The Nova 1220 computer has slots for ten 15×15 inch circuit boards which plug into ten sets of 100 pin connectors on the PC backpanel. The slots are numbered from the bottom up and assigned as follows:

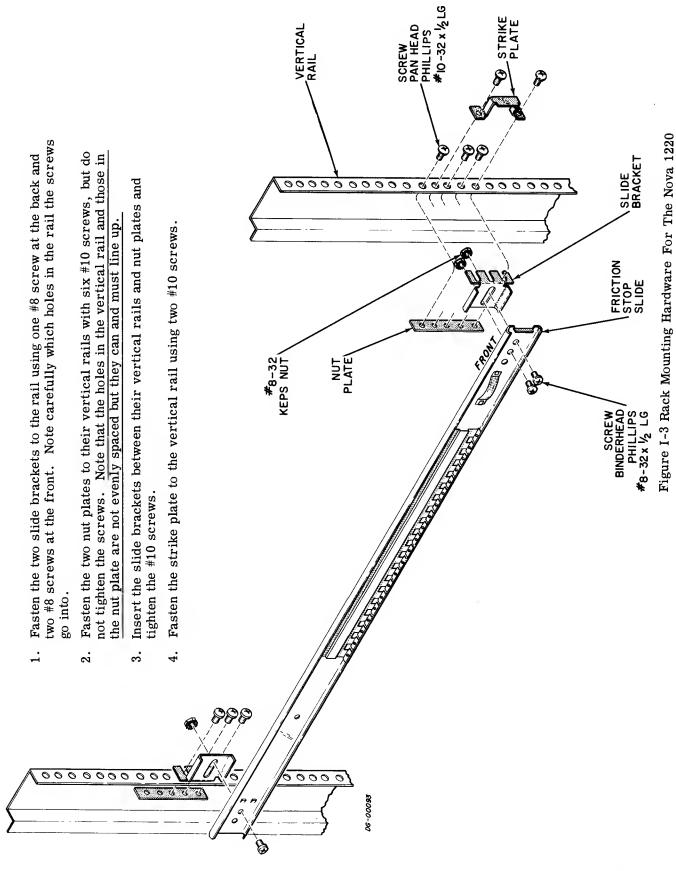
Slot Nu	mber	Boards Accepted
1		CPU-1 Only
2		Any 1220 Memory or the Multiply Divide option (8107)
3		Any 1220 Memory or the I/O Interface Assembly (4007)
4-8	3	Any 1220 Memory or Controller
9,1	.0	Any 1220 Controller

Note that slot 3 has special wiring for the 4007.



DG-00099

Figure I-2 Nova 1220 Board Slots



Note that if the Multiply Divide option 8107 is used, it must go into slot 2, and if the I/O Interface Assembly is used it must go into slot 3. If a new memory board is installed, check that the select logic jumpers are correct (See Section M).

If boards are installed or removed from the computer chassis, it is important that the integrity of the Program Interrupt and Data Channel priority systems be preserved. The Priority systems of the Program Interrupt and Data Channel facilities each use a scheme in which a wire is chained through every controller, one after the other, in such a way that only when there is an enabling level on that wire can a controller effectively request service of the facility. The enabling level on the wire will appear at any given controller only if all controllers closer to the computer on the chain are not requesting service themselves; i.e., whenever a controller requests service it removes the enabling level from all devices below it on the chain. There are two chains, one for the Program Interrupt and the other for the Data Chan-

The program interrupt chain enters a board slot at pin A96 and leaves at pin A95; the data channel chain enters at pin A94 and leaves at pin A93. (See "How to Use the Nova Computers" for more details.)

Here are the rules:

- Memories take Data Channel and Program Interrupt signals and pass them through their slots.
- 2. All controllers that use the interrupt system must be included in the interrupt chain; all controllers that use the data channel must be included in the data channel chain.
- 3. The Data Channel and Program Interrupt chains are completely independent and must not cross. Each chain must run through the controllers in series, NEVER in parallel.
- 4. Controllers that use the Program Interrupt system but do not use the Data Channel system do not need a jumper for the unused line. The only jumpering required is on unused slots or the user's manufactured boards.

Rack Mounting The Computer

The Nova 1220 can be mounted in a standard 19 inch rack, so each unit is shipped with rack slides attached and all of the necessary mounting hardware included. Figure I-3 shows how the right side of the rack slide is assembled in a cabinet; the other side uses identical hardware.

Leave at least two inches open at the back for cables and about 36" open at the front for servicing.

The console protrudes 1 3/4 inches out of the front of the rack.

CABLING ASSEMBLIES TOGETHER

Types of Cables

There are five types of cables used on a typical installation; I/O cables, device cables, internal cables, interdevice cables, and adapter cables. The correct cables are supplied with the equipment unless otherwise specified in the price list.

I/O Cables which connect peripheral controllers mounted outside the computer chassis, to the computer IN-OUT bus. The cables form a daisy chain, from controller to controller and finally to the computer chassis, where the first cable must terminate in a female connector compatible with the 100 finger male called P3 shown in Figure I-4. Controllers mounted inside the chassis are connected to the IN-OUT bus through backpanel etching, and therefore do not need an I/O cable.

Device Cables which connect each peripheral controller to the device it is controlling. When such a controller is inserted into the Nova 1220 chassis, an internal cable is run from the appropriate backpanel pins to a male connector, such as P3 of Figure I-4. The device cable must then run between the male paddle board on the 1220 chassis and the device.

Internal Cables are added when the controller is added, whether in the factory or in the field, so each shipment includes a wire list for the internal cable, and the internal cable itself. Figure I-4 shows how the paddle boards are mounted on the chassis.

Interdevice Cables interconnect peripheral devices. Some controllers will drive more than one device of the same kind, such as industry compatible tape controllers. In this case the device cables are daisy chained from device to device in the same way that the I/O cables are chained between controllers. The cables which interconnect the devices are not always the same as the device cable that runs from the controller to the first device, however, so these cables are called "interdevice cables".

Adapter Cables reconcile different cabling schemes. The Nova, Supernova, Nova 1200 and Nova 800 series computers use Cannon connectors instead of paddle boards for their device and I/O cables, and Data General supplies adapters so that peripherals used on these machines can also be used on the new models, or the other way around.

Figure I-4 Sketch of the Nova 1220 Cabling Schemes

① ②

3

(5)

Signals from the backpanel pins are connected to edge connectors called P3-P12, which are mounted parallel to the backpanel. The fingers of P3 are permanently connected to the IN-OUT Bus signals according to Table I-2 via etched tracks on the backpanel PC board. The fingers of P4 are permanently connected to pins of slot 9 according to Table I-3. P5, P6 and P7 are all part of a three plug 60 finger paddle board which is permanently connected, but used only when the paper tape reader, the paper tape punch or the EAI options are installed in slot 3. P8-P12, 100 finger paddle boards which accept 48 signal wires and two ground wires, can be mounted on standoffs next to P4 or P5, P6, P7 and wire wrapped to backpanel pins as they are needed. The Teletypewriter cable is run from its backpanel pins (marked TTY) of slot 3, through a cable clamp to the teletypewriter. (13) TELETYPEWRITER INLET CABLE (SLOT 3) CABLE ITEM DESCRIPTION TIE P4 BACKPANEL SLOT 9 2 P5 PAPER TAPE READER OPTION 4011B P6 EIA OPTION 4023 STRAIN 4 P7 PAPER TAPE PUNCH OPTION 4012A RELIEF 5 P8 CLAMP 6 P9 7 PIO B PII (9) 9 PI2 DG-00002 IO P3 IN-OUT BUS POB CUSTOMER CONSOLE ш 12 POA CONSOLE 13 P2 TELETYPEWRITER INTERFACE CONNECTOR 14 TELETYPEWRITER CABLE CLAMP

15 1030B CABLE

Table I-2
P3 Interconnections for Nova 1220

Р3	
NUMBER SIDE	SIGNAL NAME
	GND PWR ON (+5V) MSKO INTA DATIB DATIA DATIA DS3 DATOC CLR STRT DATIC DATO B DATO A DCHA DS4 DS5 DS2 DS1 IORST DS0
	——————————————————————————————————————
	NUMBER SIDE

Table I-3
P4 Interconnections for Nova 1220

	BACKPANEL			
NUMBER SIDE	LETTER SIDE	SLOT-SIDE-PIN No.		
	A THRU AF GND			
1		——— GND		
2		9 A 92		
3		9 A 91		
4		9 A 78		
5 — — –		——— 9 A 77		
6		9 A 76		
7		9 A 75		
8		9 A 73		
9		9 A 71		
10		——— 9 A 69		
11		9 A 67		
12		9 A 65 9 A 63		
13				
14 15 — — –		9 A 61 		
16		9 A 57		
17		9 A 37		
18		9 A 49		
19		9 A 79		
20 — — —		9 A 81		
20 21		9 A 84		
22		9 A 83		
23		9 A 86		
24		9 A 85		
25 — — —	<u> </u>	——— 9 A 88		
26		9 A 87		
27		9 A 89		
2 8		9 A 90		
29		9 B 6		
30 ———		——— 9 B 11		
31		9 B 13		
32		9 B 15		
33		9 B 19		
34		9 B 23 9 B 25		
35 — — — 36		9 B 27		
37		9 B 31		
38		9 B 34		
39		9 B 36		
40		9 B 38		
41		9 B 40		
42		9 B 48		
43		9 B 49		
44		9 B 51		
45 — — -		9 в 52		
46		9 в 53		
47		9 B 54		
48		9 B 67		
49	,	9 B 69		
50 — — —	 	— — RESERVED		

Data General Corporation (DGC) has prepared this manual for use by DGC personnel and customers as a guide to the proper installation, operation, and maintenance of DGC equipment and software. The drawings and specifications contained herein are the property of DGC and shall neither be reproduced in whole or in part without DGC's prior written approval nor be implied to grant any license to make, use, or sell equipment manufactured in accordance herewith.

Cabling The System

Turn all systems off, do not plug in any power cords, then:

- 1. install all internal cables not factory installed, following the instructions in the appropriate controller's manual.
- 2. install all device cables, remembering not to exceed the maximum length in each case. Be careful to protect each cable from wear and tear.
- 3. install the teletypewriter cable as shown in Figure I-4.

- 4. measure the line voltage of each service outlet, and check that it is correct for the computer.
- 5. measure the voltage between the ac return line and the frame ground at each outlet.

 THIS MUST BE ZERO
- 6. plug the power cord of each device into its service outlet.

REFERENCES:

Nova 1220 Rack Installation Print D-010-000014-01.

This Page Left Blank

Intentionally

SECTION N

MAINTAINING THE COMPUTER

INTRODUCTION

The Data General Corporation supports its equipment with a large field service organization, customer training programs and technical documentation. This section summarizes these services and includes tips on preventive maintenance, recommended tools and trouble shooting.

FIELD SERVICE ORGANIZATION

Field Service Programs

Data General's Field Service Organization currently offers its users a choice of three maintenance services. These services are subject to change without notice.

- 1. On Call Service Contract under which DGC will repair equipment at the installation when DGC is notified of a problem by the user. DGC also provides preventive maintenance on a regular schedule under this contract. Parts, labor and travel are included in the monthly payment schedule which is determined by the type and amount of equipment to be serviced and the distance between the installation and the nearest DGC service center.
- 2. Factory Service Contract under which DGC will:
 - (1) repair equipment when it is returned to the DGC factory in Southboro, Mass. The user assumes full responsibility for freight and insurance charges to and from the plant. Parts and labor are included in the monthly payment schedule.
 - (2) repair equipment at the installation when notified of a problem by the user. Parts are included in the monthly maintenance schedule, labor is charged at reduced rates and travel is charged at the prevailing standard rates.
- 3. Hourly Service under which parts, labor and travel are charged as needed at prevailing rates. No contract is signed for this service.

Field Service will also generate on request a complete spare parts list for any installation, and rent or sell replacement and loaner boards.

General Terms and Conditions (Subject to change without notice).

- 1. Equipment which is not under a DGC service contract or normal warranty is subject to an inspection by DGC Field Service before it is eligible for a service contract. All costs for this inspection are borne by the user.
- The user must bear all maintenance costs incurred as a result of unauthorized changes to DGC equipment. These costs will be charged as <u>Hourly Service</u>, regardless of the type of <u>service</u> contract existing between DGC and the user.
- 3. No additional service charge will be added for new (add-on) equipment until the warranty period of that equipment has expired.
- All services are offered between 9 a.m. and 5 p.m. Monday through Friday excluding DGC holidays.
- 5. The minimum contract period is 6 months.
- 6. Field Service price schedules are available on request from Data General Field Service, Southboro, Mass. 01772, Telephone 617-485-9100.

TRAINING ORGANIZATION

Data General's Training Organization currently offers its users four types of training courses. These courses are subject to change without notice.

Mainframe Maintenance Course. This course covers the logical structure of the central processor, memory, operator's console and power supply. Students must have experience with digital logic, integrated circuits and computer principles.

Fundamentals of Mini-Computer Programming.
This course covers number systems, logic, flow charts and computer architecture. Students should have an aptitude for mathematics.

Basic Programming. This course covers Data General's assembly language utility software including loaders, editors, debuggers and assemblers. Students should have experience in programming.

Advanced Programming. This course covers Data General's Operating Systems, DOS, RTOS and SOS. Students must have experience in programming.

Courses are scheduled regularly in the training department at Southboro, Mass., and occasionally in field offices. Special courses can be arranged.

For more information call or write

Training Department
Data General Corporation
Southboro, Mass. 01772

Tel. 617-485-9100

PREVENTIVE MAINTENANCE

Periodically carry out the checks listed in Table, N-1, and remember the following points:

- 1. It is very poor practice to use the equipment as a counter top, particularly for liquids like coffee or soft drinks.
- 2. Always check the line voltage before plugging an expensive piece of equipment into an unknown socket. (see Section I).
- 3. Be careful not to get metal filings into the equipment; for example never let the equipment room be cleaned with steel wool.
- 4. Never clean the equipment with a vacuum cleaner that has a metal (conducting) nozzle.
- 5. Always be aware that too much heat, moisture or contaminants can do much to harm the equipment (see Section I).
- 6. Be very careful how cables are routed; they should never be strained, cramped or crushed (underfoot).

Table N-1

Preventive Maintenance Check List						
Item	Check					
Mechanical Connections	1. that all screws are tight and that all mechanical assemblies are secure.					
	2. that all crimped lugs are secure and properly inserted onto their mating connectors.					
Wiring and Cables	1. all wiring and cables for breaks, cuts, frayed leads, or missing lugs.					
	2. wire wraps for broken or missing pins.					
	3. that no wires or cables are strained or cramped.					
	4. that cables do not interfere with doors, and that they do not chafe when doors are opened and closed.					
Air Filters	all air filters for cleanliness and for normal air movement through cabinets.					
Modules and Components	1. that all modules are properly seated. Look for areas of discoloration on all exposed surfaces.					
	2. all exposed capacitors for signs of discoloration, leakage, or corrosion.					
	3. power supply capacitors for bulges.					
Indicators and Switches	all indicators and switches for tightness; check for cracks, discoloration, or other visual defects.					
Fans	for broken fan blades.					
Diagnostics	Run all diagnostics periodically					

Table N-2

		Recommended Maintenance Tool	Kit				
ITEM	QTY	DESCRIPTION	MFG. & PART No.				
1	1	6" combination slip joint pliers	Utica # 5-6				
2	2	5 1/2" needle nose pliers	Utica # 654-5 1/2				
3	1	4" needle nose pliers	Utica # 23-4				
4	1	5" diagonal wire cutters	Utica # 44-5				
5	1	4" diagonal wire cutters	Utica # 347-4 CFJS				
6	1	5" ignition pliers	Utica # 517-5				
7	1	Screwdriver kit including handle, 3/16", 1/4", 5/16" slotted #1, #2 phillips blades, each 4" long	Xcelite # 99 PV-6				
8	1	3/32 slotter screwdriver with 2" blade	Xcelite # R3322				
9	1	1/8" #0 phillips screwdriver	Xcelite # P12S				
10	1	Magnetic pick up tool	Bonney # K26				
11	1	3/32 through 3/8, 10 pc nut driver set	Xcelite # PS120				
12	1	Xacto knife					
13	1	6" adjustable wrench	Utica # 91-6				
14	1	Ignition wrench	Bonney # N24R				
15	1	Set of 25 feeler gauges with 3" blades	Bonney # K53				
16	1	Set of 15 hex keys	Bonney # N6R				
17	1	Slotter 5" screw starter	Bonney # 5527				
18	1	Phillips 6 1/4" screw starter	Bonney # 556				
19	1 1	5" adjustable wire strippers	Utica # 110-5				
20	1	Set of 4 cut needle files	Hunter # F228A				
21	1	4 1/2" electrical tweezers	Hunter # B3M3				
22	1	flash light					
23	1	Can Quick Freez (circuit cooler)					

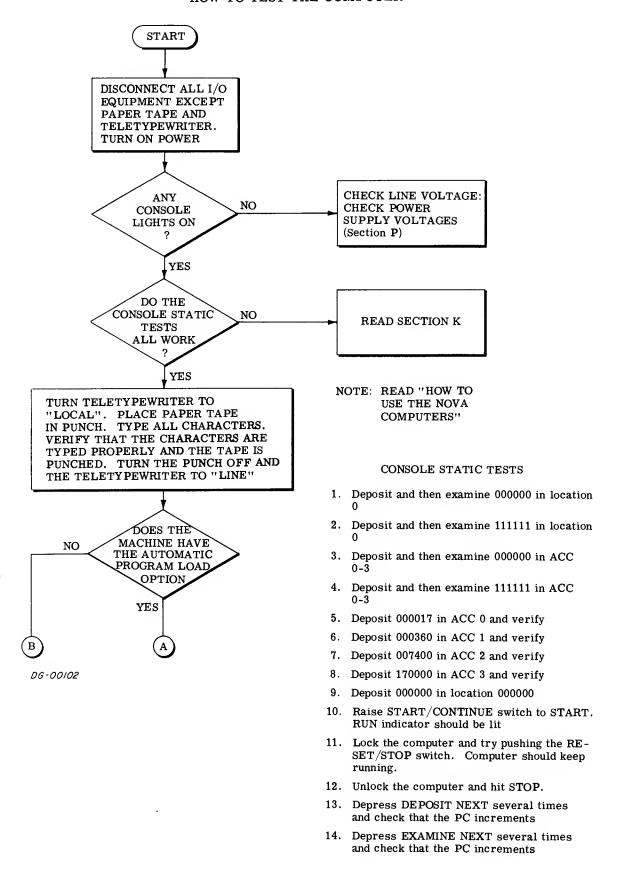
Table N-2 (Continued)

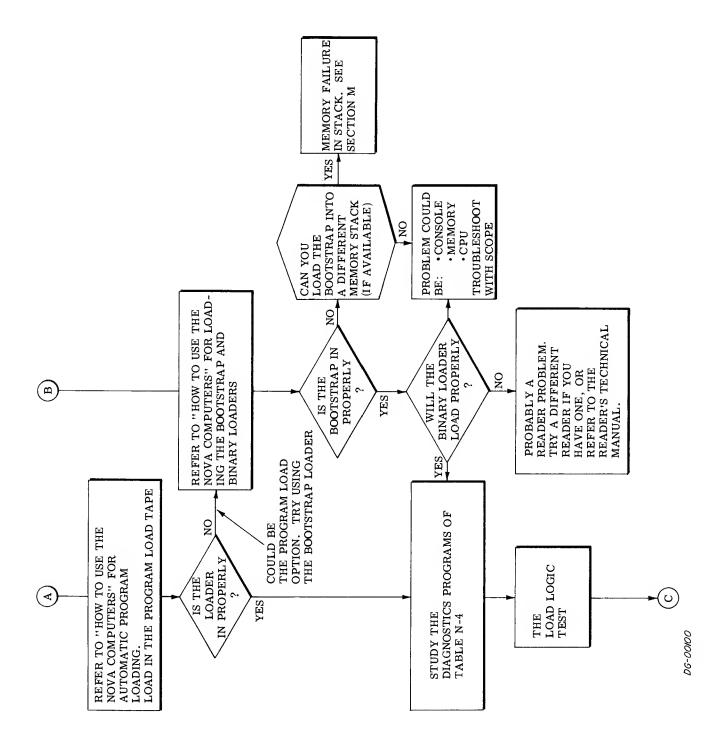
	Recommended Maintenance Tool Kit						
ITEM	QTY	DESCRIPTION	MFG & PART No.				
24	1	Can degreaser (flux remover)					
25	2	16P I/C test clip					
26	1	$23\ 1/2$ watt soldering iron with iron plated chisel tip	Ungar				
27	1	47 1/2 watt soldering iron element					
28	1	11b, 60/40 resin core solder	Kester				
29	3	Spools of solder wick	Spools of solder wick				
30	2	Acid brushes					
31	1	Vacuum solder removal tool					
32	1	Multimeter	Simpson # 260				
33	1	Tool carrying case					
34	1	Oscilloscope	Tektronics # 453				
35	1	Current probes	Tektronics # P60-22				

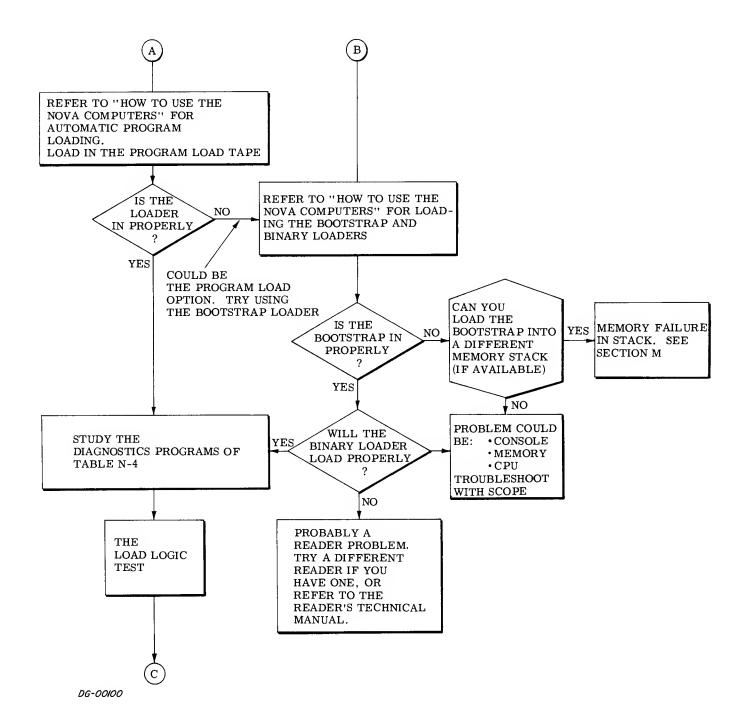
Table N-3

The Nova 1220 Diagnostics							
Diagnostic	Part No.	Binary Tape No.	Description				
Address Test	097-000007	095-000005	checks memory address selection logic				
Checkerboard III	097-000014	095-000031	tests memory sense amplifiers and inhibit logic				
Nova 1220 Logic Test	097-000017	095-000036	tests CPU logic other than I/O				
Nova 1220 Instruction Timer	097-000019	095-000038	tests CPU clock logic and outputs time-to-complete for each instruction				
Exerciser	097-000004	095-000012	tests CPU logic, teletypewriter, reader, punch and real-time clock;				
Arithmetic Test	097-000018	095-000037	exercises arithmetic and logical instructions in CPU				

HOW TO TEST THE COMPUTER







SIGNAL LIST
Table 1 - Nova 1210/1220

ORIGIN				DESTINATION					
SIGNAL	СШР	PIN	DWG	GRID	FUNCTION	CHIP	PIN	DWG	GRID
ACB0	105	5	88-4	B4	ACB12	105	14	88-4	В3
ACB1	106	5	**	В3	ACB13	106	14	**	B2
ACB2	107	5	**	A4	ACB14	107	14	''	A4
					LOAD MBO*	98	6	88-3	A3
				1	KEYM SET*	101	9	88-1	В7
ACB3	108	5	**	A3	ACB15	108	14	88-4	A2
ACB4	105	7	11	В4	ACB0	105	3	**	B4
ACB5	106	7	**	В3	ACB1	106	3	11	В3
ACB6	107	7	**	A4	ACB2	107	3	**	A4
ACB7	108	7	71	A3	ACB3	108	3	,,	A3
ACB8	105	9	11	B4	ACB4	105	2	",	B4 B3
ACB9	106	9	11	В3	ACB5	106	2	,,	
ACB10	107	9	"	A4	ACB6	107	2 13		A4 C6
ACB11	108	9	''	A3	CRY SET	81	2	88-3 88-4	A3
					ACB7	108	4	88-4	As
					SHIFTER	114	10	,,	A8
4.0710	105		,,	D4	Logic ACB12 SAVE	114 69	10	88-1	D5
ACB12	105	11	' '	В4	SHIFTER	09	3	00-1	טט
					Logic	109	9	88-4	A8
ACB12*	105	12	11	В3	SHI FTER	125	19	11	A7
ACB12** ACB13	105	11	11	В2	SHIFIER	120	10		A
ACB13*	106	$\frac{11}{12}$	11	D2	SHIFTER	125	2	,,	A7
ACDIS	100	1.2		i	SHIFTER	125	20	11	A7
ACB14	107	11	**	A4	DIII I Lit	120			11.
ACB14*	107	12	11	A3	SHI FTER	125	1	**	A7
ACDIT	101	12		710	SHI FTER	125	5	11	A6
					SHI FTER	125	18	**	A7
ACB15	108	11	**	A2					
ACB15*	108	12	**	A2	SHIFTER	125	3	11	A7
ACB12	100		:	12-					
SAVE	69	5	88-1	D4	SHI FTER				
		-			Logic	90	1	88-4	A7
AC CLR	20	9	**	A 6	IR(SH)	83	5	88 -2	B8
					SHIFTER	125	7	88-4	A 8
					LOAD AC*	111	3	88-3	D3
ACD0	123	5	88-4	B8	MULT	120	5	88-4	D5
					D BUFFR	122	3	11	C8
ACD1	123	7	11	B8	MULT	120	2	**	D5
*Indicates ''Not''									

SIGNAL LIST
Table 1 - Nova 1210/1220

ORIGIN DESTINATION SIGNAL CHIP PIN DWG GRID FUNCTION CHIP PIN DWG ACD2 123 9 88-4 B8 MULT 120 22 " ACD3 123 11 " B8 MULT 120 19 " ACD3 SEL* 50 6 88-2 D4 ACD 123 1 "	GRID C8 C5 C7 C5 C7 B8 B8 C8
ACD2 123 9 88-4 B8 MULT 120 22 " ACD3 123 11 " B8 MULT 120 19 " ACD3 SEL* 50 6 88-2 D4 ACD 123 1 "	C8 C5 C7 C5 C7 B8 B8
ACD2 123 9 88-4 B8 MULT 120 22 " ACD3 123 11 " B8 MULT 120 15 " ACD3 SEL* 50 6 88-2 D4 ACD 123 1 "	C5 C7 C5 C7 B8 B8
ACD3 123 11 '' B8 MULT 120 15 ''	C7 C5 C7 B8 B8
ACD3 123 11 '' B8 MULT 120 19 '' ACD3 SEL* 50 6 88-2 D4 ACD 123 1 ''	C5 C7 B8 B8
ACD3 SEL* 50 6 88-2 D4 ACD 123 1 "	C7 B8 B8
ACD3 SEL* 50 6 88-2 D4 ACD 123 1 "	B8 B8
	В8
ACD4 SEL* 44 8 '' C4 ACD 123 15 ''	C8 i
ACD OUT* 45 6 '' B3 D MULT(SEL) 121 1 ''	
[ACS0] 124 5 88-4 B7 S BUFFER 115 3 "	C7
[ACS1] 124 7 " B7 " 115 2 "	C7
[ACS2] 124 9 " B6 " 115 15 "	C6
[ACS3] 124 11 '' B6 '' 115 14 ''	C6
ACS1 SEL* 49 6,8 88-2 C4 ACS 124 1 "	B7
ACS2 SEL* 49 3,11 '' B4 ACS 124 15 ''	В7
ACTG0 54 5 88-1 D8 ACTG1 73 9 88-1	C8
IR(SH) LOGIC 111 2 88-2	B8
ACD 123 14 88-4	B8
ACS 124 14 ''	B7
ACTG1 54 7 88-1 D8 ACTG0 53 9 88-1	D8
IR(SH) LOGIC 111 9 88-2	A8
ACD 123 88-4	B8
ACS 124 13 "	B7
ADDER0 117 13 88-4 D7 CRY SET* 81 3 88-3	C6
ACB (DS) 105 4 88-4	B4
ACB8 105 15 ''	B4
PC LOGIC 118 5,4 "	B6
MULT 120 4 "	D5
ADDER1 117 11 88-4 D7 ACB(DS) 106 4 "	В3
ACB9 106 15 "	B3
PC LOGIC 118 1,2 "	B6
MULT 120 1 "	D5
ADDER2 117 10 88-4 D7 ACB(DS) 107 4 "	A4
ACB10 107 15 "	B2
PC LOGIC 118 12,	
13 "	A6
MULT 120 23 "	C5
ADDER3 117 9 88-4 D7 ACB(DS) 108 4 "	A3
Indicates '' Not'' ACB11 108 15 ''	A2

SIGNAL LIST
Table 1 - Nova 1210/1220

			·····		× 1			100	1	
O	RIGIN				DESTINATION					
SIGNAL	СНІР	PIN	DWG	GRID	FUNCTION	CHIP	PIN	DWG	GRID	
ADD ONE* ADDER	88	8	88 -2	D2	PC LOGIC MULT ADDER	118 120 117	9, 10 20 7	88 -4 ''	A6 C5 D6	
TEST ALC	58 94	3 6	88-3 88-2	A4 B7	LOOP SET* DISABLE D MULT S0 TEST SKIP	104 46 47	5 10 1	88-3 88-2		
ALC*	50	8	88 -2	В7	SET ADD ONE* AND E SET S2 ALC S BUFFER	86 44 65 74 91 94	5 2 5 1 12 5	88 -3 88 -2 ''	D3 B7 C7 C3 B7	
ALC· <u>SKIP</u> AND	83 65	10 6	88 -3 88 -2	D8 B7	(SH) LOAD CRY* CRY ENAP S1 ADDER	115 97 91 91 117	13 13 2 5 8	88 - 3 '' 88 - 2	C6 C3	
AND ENAB*	64	11	88-2	В7	IO DCDR AND PACK	62 65 89	13 4 2	88 - 4 88 - 1 88 - 2 88 - 3	A5 B7	
CARRY (F/F) CARRY*	76	8	88-3	C5	CRY ENAB	77	4	88-3	C7	
(F/F) CLK FLOP	76 20	9 5	88-1	C5	CON IND (A15, P49) CRY ENAB MA LOAD* CPU CLK	6 77 56 72	5 3 10 2, 12	89-1 88-3 88-1	C8 C7 D3	
Indicates ''Not''					MEM CLK LOAD AC	73 93	3 5	'' 88-3	A7 D3	

0	RIGIN				DESTINATION					
SIGNAL	СНІР	PIN	DWG	GRID	FUNCTION	СНІР		DWG	GRIE	
SIGNAL CLK FLOP* [CLR*] CLR CLR ION* CLR SKIP* [CON0*](S11) [CON1*](S12) [CON2*](S13) [CON3*](S14) [CON4*](S15) [CON5*](S16) [CON6*](S17) [CON7*](S18) [CON8*](S19) [CON9*](S20)	CHIP 20 63 7 63 99 6 6 6 3 3 3 3 3	6 5 2 11 8 4 2 8 12 8 10 6 4 2	88-1 88-3 89-1 89-1 89-1 89-1 89-1 89-1 89-1 89-1	A7 A4 A4 B4 B3 C8 C7 C7 C6 C6 C6 C6 C5 C5	FUNCTION CLK FLOP CLR (IO CLR PLS) ION SKIP LOAD MBO* MEM0* (CON IND) MEM1* (CON IND) MEM2* (CON IND) MEM3* (CON IND) MEM4* (CON IND) MEM5* (CON IND) MEM5* (CON IND) MEM6* (CON IND) MEM6* (CON IND) MEM7* (CON IND) MEM8* (CON IND)	CHIF 20 7 (A50) 84 79 98 (B71) 7 (B47) 7 (B68) 7 (B28) 8 (B26) 8 (B22) 8 (B24) 9 (A55) 9 (A53)	PIN 2 1 4 13, 10; (391) 9 P41, 13 (P13) 3 (P36) 3 (P10, 1 (P42) 13 (P34) 3 (P7) 1	DWG 88-1 90-1 88-2 88-3	A7 A4 C7 B5 B3 C8 C8 C7 C7 C7 C7 C7 C7 C6 C6 C6 C6 C6 C5 C5 C5 C5 C5	
[CON10*](S21)	4	8	89-1	C4		(A45) 10		11	C4 C4	
[CON11*](S22)	4	10	89-1	C4	` /	(A51) 10		"	C4 C4	
[CON12*](S23)	4	12	89-1	C3	MEM12* (CON IND)	(A36) 10	(P5) 1	"	C3 C3	
[CON13*](S24) *Indicates ''Not''	4	6	89-1	C3		(A35) 11	-	11	C3 C3	

SIGNAL LIST
Table 1 - Nova 1210/1220

OF	RIGIN				DESTINATION				
SIGNAL	СНІР	PIN	DWG	GRID	FUNCTION	СНІР	PIN	DWG	GRID
[CON14*](S25)	4	4	89-1	C3	MEM14*	(B76)	(P3)	89-1	C3
					(CON IND)	11	3	**	C3
[CON15*](S26)	4	2	89-1	C2	MEM15*	(B18)	B ` '	"	C2
CON DATA*	4	8	88 -1	A2	(CON IND)	12 (A28)	13 (P46		C2
CON DATA	4	0	00-1	AZ	[CON0*](S11)	6	3	' ,,	C8
					CON1* (S12)	6	1	,,	C7
					CON2* (S13)	6	9	* *	C7
'					[CON3*](S14)	6	13	**	C7
					[CON4*](S15)	3	9	""	C6
					[CON5*](S16)	3	11	",	C6
					[CON6*](S17)	3 3	5 3	<u>'</u> ',	C6 C5
					[CON7*](S18) [CON8*](S19)	3	ა 1	,,	C5
,					CON9*](S20)	3	13	77	C5
			1		[CON10*]				C4
					(S21)	4	9	"	C4
					[CON11*]				1 [
	l				(S22)	4	11	",	C4
					[CON12*]			,,	~ 0
					(S23)	4	13	l ''	C3
					[CON13*] (S24)	4	5	,,	C3
					[CON14*]	-	ľ		00
					(S25)	4	3	",	
					[CON15*]				C2
					(S26)	4	1	''	
CON INST*	36	8	88 -1	A2		(A22)	(P22		
	_				[CON INST]	5	9	''	A8
[CON INST]	5	8	89-1	l	MEM0*	1	2	,,	C8 C7
					MEM1* MEM2*	1 2	4 10	,,	C7
					MEM2* MEM3*	1	12	,,	C7
					MEM4*	1	10	,,	C6
1					MEM5*	2	12	**	C6
	l				MEM6*	2	2	"	C6
					MEM7*	2	4	"	C5
*Indicates ''Not''									

SIGNAL LIST
Table 1 - Nova 1210/1220

O	RIGIN				DESTINATION					
SIGNAL	СНІР	PIN	DWG	GRID	FUNCTION	T		DWG	GRID	
CON RQ*	5 A27)	6 (P21	89-1	C8	KEY SEEN	3	4	88-1	В8	
CONT+ISTP+ MSTP* CPU CLK	(A20) 72	6,8	89-1 88-1	B3 A6	KEY ENAB* MB LOAD	3 14	2 4	88 -1 ''	B8 C2	
					IR4-IR7 MBC MBC	28 32 33	6 6 6	88 -2	A6 A4 A5	
					MBO MBO	37 38	6 6	88-4	C4 C3	
					MBO MBO	39 40 42	6 6 6	,, 88 -1	D3 D4 C8	
				-	LOAD PC* MA LOAD* INPUT	57 60 66	10 10 13	88-3 88-1 ''	B3 D2 C 5	
					PTG SKIP MAJOR	69 78	6 13	'' 88-3	D4 B5	
					STATES CARRY F/F	95 0 5	6	88-2	D6	
					Logic LOOP/PACK	97 102	9 6	88-3	C5 D8	
					/EFA ACB ACB ACB	103 105 106 107	6 6 6	88-4 ''	D5 B4 B3 A4	
CPU INST	6	11	88-2	В7	ACB END CYCLE F/F INTA	108 113 6	6 13 5	88 -1	A3 D5 B5	
CPU INSI	O	11	00-2	ום	INTA IORST (SKIP Logic)	6 11 11	10 2 12	,, 88 -3	A4 B7 B7	
					CON DATA* (Reads)	24	4	88 -1	A3	
*Indicates ''Not''										

SIGNAL LIST
Table 1 - Nova 1210/1220

OF	RIGIN				DES	TINA	rion		
SIGNAL	СНІР	PIN	DWG	GRID	FUNCTION	CHIP	PIN	DWG	GRID
CPU INST*	10	6	88-2	B7	(IO OCDR) HALT* PACK Logic MSKO* CPU INST	64 71 87 4 6	2 2 4 13 12,	88-1 88-2 88-3 88-1	B5 C8 C6 A4
CRY ENAB	80	11	88-3	C6	CRY SET* CRY ENAB SAVE	81 102	13 4 15	88-2 88-3	B7 C6 D7
CRY ENAB SAVE	102	9	88-3		SHIFT Logic	90 114	10 13	88-4 '' 88-1	A7 A8 D7
CRY OUT* CRY SET*	117 81	16 8	88 - 4 88 - 3		SERIAL CRY CRY ENAB CRY SET SAVE	54 91 42	14 1 15	88-1 88-3	C6 C7
CRY SET SAVE	42	9	88-1	С7	CARRY F/F (SKIP Logic)	76 77	12 9	88-3	C5 B7
DATA0*	16 17 (B62)	11 1	103-1		Terminator			88-3	C8
DATA1*	16 17 (B65)	8	103-1	С	Terminator			88 - 3	C8
DATA2*	14 15 (B82)	11 1	103-1	С	Terminator			88 - 3	C8
DATA3*	14 15 (B73)	8	103-1		Terminator			88 - 3	C8
DATA4*	12 13 (B61)	11 1	103-1	С	Terminator			88 - 3	C8
*Indicates ''Not''			_						

SIGNAL LIST
Table 1 - Nova 1210/1220

O)	RIGIN				DESTINATION						
SIGNAL	СНІР	PIN	DWG	GRID	FUNCTION	СНІР	PIN	DWG	GRID		
DATA5*	12	8	103-1	С	Terminator			88-3	C8		
DATA6*	13 (B57) 10 11	3 11 1	103-1	С	Terminator			88-3	C8		
DATA7*	(B95) 10 11	8 3	** **	С	Terminator			88-3	C8		
DATA8*	(B55) 8 9	11 1	103-1	С	Terminator			88-3	C8		
DATA9*	(B60) 8 9	8	103-1	С	Terminator			88-3	В8		
DATA10*	(B63) 6 7	11 1	103-1	С	Terminator			88-3	В8		
DATA11*	(B75) 6 7	8 3	103-1	С	Terminator			88-3	В8		
DATA12*	(B58) 4 5	11 1	103-1	С	Terminator			88 - 3	В8		
DATA13*	(B59) 4 5	8	103-1	С	Terminator			88-3	B8		
DATA14*	(B64) 2 3	11 1	103-1	С	Terminator		1	88-3	В8		
DATA15*	(B56) 2 3	8	103-1	С	Terminator			88-3	В8		
[DATOA*] DATOA	(B66) 25 7	6	88 -1	В4	DATOA	7 (A58)	9	88-1 90-1	B4		
DATOB*	25	5	11	B4	DATOB MSKO*	7 4	13 12	88 <i>-</i> 1	B4 B4		
DATOB *Indicates ''Not''	7	12	88 -1	В4		(A56)		90-1			

SIGNAL LIST
Table 1 - Nova 1210/1220

OF	RIGIN				DESTINATION					
SIGNAL	СНІР	PIN	DWG	GRID	FUNCTION	СНІР	PIN	DWG	GRID	
[DATOC*] DATOC	25 26	4 6	88-1	B4 B4	DATOC	26 (A48)		88-1 90-1	В4	
[DATIA*] DATIA	25 5	9 12	**	B4 B4	DATIA CON DATA*	5 24 (A44)	13 5	88 -1	B4 A3	
[DATIB*] DATIB	25 5	10 10	11	B4 B4	DATIB INTA	(A44) 5 6 (A42)	11 4	88-1	B4 A4	
[DATIC*] DATIC	25 7	11 6	**	В4 В4	DATIC IORST	(A42) 7 6 (A54)	5 9	88-1	B4 A4	
[D BUFFR0] [D BUFF1] [D BUFFR2] [D BUFFR3]	122 122 122 122	5 7 9 11	88-4	C8 C8 C8 C8	[D MULT0] [D MULT1] [D MULT2] [D MULT3]	121 121 121 121 121	2 5 14 11	88-4	C8 C8 C8 C8	
DCH	23	9	88-1	C6	DCHI DCH LOOP	14	9	88 -1	C2	
DCHA	69	7	88-1	D4	ENAB ADD ONE* DCHA* DRIVE IO* DCH	15 41 7 13 23	2 2 11 5 15	88-1 88-2 88-1	B3 D4 C2 B3 C6	
DCHA* DCHA SET*	7 71	10 8	88-2 88-1	C2 C4	[DCHA SET]	(A60) 67	3	90 -1 88 -1 88 -2	C4 D7	
[DCHA SET] DCHI	67 14	4 8	88-1 ''	C4 C2	FETCH DCHA	97 69 (B37)	1 2	88-1 90-1	C4	
DCH LOOP	15	6	88-1	B2	DRIVE IO* OVFLO	13 15	9	88-1 88-1	B3 B2	
ENAB	19	υ	00-1	D4	DCHO	18	12, 13	88 -1	B2	
					ACTG(LD) LOOP SET*	75 104	10 10, 13	88-3	D8 C6	
*Indicates ''Not''										

ORIGIN DESTINATION SIGNAL CHIP PIN DWG GRID FUNCTION CHIP PIN DW DCHM0* (B17) 88-1 B3 DCH LOOP ENAB 15 4,5 88- [DCHM0] 16 1 " 16 1 " DCHM1* (B21) " B3 " 14 12 " [DCHM1] 16 4 88-1 B3 OVFLO 15 10 88-	-1 B3
DCHM0*	·1 B3
[DCHM0] 16 2 88-1 B3 [DCHM0] 15 4,5 88-1 DCHM1* B3 DCHI 14 10 " [DCHM1* [DCHM1] 16 3 " [DCHM1] 16 3 " [DCHM1] 16 3 " [DCHM1] 16 3 " [DCHM1] 18-3 "	
[DCHM0] 16 (B21) 2 88-1 B3 DCHI 14 10 " [DCHM1* [DCHM1] 16 1 10 " [DCHM1] 16 3 " [DCHM1] 16 3 " [DCHM1] 16 3 "	
[DCHM0] 16 2 88-1 B3 DCHI 14 10 " DCHM1* [B21] " B3 " [DCHM1] 16 3 " LOOP SET* 34 12 88-	
DCHM1* (B21) " B3 " 14 12 " [DCHM1] 16 3 " LOOP SET* 34 12 88-	B3
[DCHM1] 16 3 " LOOP SET* 34 12 88-	B2
LOOP SET* 34 12 88-	B2
	B3
[DCIIMI	- 1
DCHO 18 8 " B2 (B33) 90-	
DCHR* (B35) " C5 DCHR PEND 13 2 88-	_
DCHR PEND 13 3 " C5 DCHA SET* 71 10 "	C5
LOOP SET* 104 9 88-	
DEFER 95 7 88-2 D6 DEFER	° D°
AGAIN 76 4 88-	2 C7
ADD ONE* 90 4 ''	D4
DEFER* 94 11 "	D6
LOOP SET* 104 6 88-	3 D6
DEFER* 94 10 88-2 D6 (CON IND) (A12) P52 89-	
S0 48 1 88-	2 C4
ADDER	
TEST 58 12 88-	3 A6
ADDER 7 59 10 "	ٔ مرا
TEST 59 10 "FETCH +	A6
DEFER 75 2 88-	2 C7
DEFER AGAIN* 76 5 88-2 C7 DEFER 74 9 "	2 C7
(D+E SET) +	
TS3 36 11 " D5 DCHR PEND 13 1 88-	1 C5
(RUN LOGIC) 24 13 "	B7
PC IN* 35 1 88-	
D+E SET* 96 11 88-2 D7 (D+E SET)+	
TS3 36 13 88-	
(RUN LOGIC) 43 13 88 -	1 B7
FETCH	. '
LOGIC 97 5 88-	2 C7
*Indicates '' Not''	

SIGNAL LIST
Table 1 - Nova 1210/1220

OI	RIGIN				DES	TINA	ΓΙΟΝ	[
SIGNAL	СНІР	PIN	DWG	GRID	FUNCTION	СНІР	PIN	DWG	GRID
Disable D Mult DIV* [D MULT0] [D MULT1] [D MULT2] [D MULT3]	53 (A91) 121 121 121 121	3 4 7 12 9	88-4 ''	B2 C5 C7 C7 C7 C7	D Mult (Enab) Carry F/F ADDER " " "	121 76 117 117 117 117	15 10 19 21 23 2	88-4 88-3 88-4 ''	C8 C5 D7 D7 D7 D7
DRIVE IO*	12	8	88 -1	В2	READ IO* [DRIVE IO]	(B88) 12 18	4,5 1	90-1 88-1 103-1	B2 C8
[DRIVE IO]	18	2	103-1	C8	[Drive IO· Select]	26	9, 10, 12	103-1	C8
[DRIVE IO· Select]	26	8	103-1	C8	DATA0* DATA1* DATA2* DATA3* DATA4* DATA5* DATA6* DATA7* DATA8* DATA9* DATA10* DATA11* DATA12* DATA12* DATA13* DATA14* DATA15*	16 16 14 14 12 12 10 10 8 8 6 6 4 4 2 2	12 10 12 10 12 10 12 10 12 10 12 10 12 10 12 10 12	11 11 11 11 11 11 11 11 11 11 11 11	000000000000000
*Indicates ''Not''									

SIGNAL LIST
Table 1 - Nova 1210/1220

OI	RIGIN				DESTINATION					
SIGNAL	СНІР	PIN	DWG	GRID	FUNCTION	СНІР	PIN	DWG	GRID	
DS0* DS1* DS2* DS3* DS4* DS5* D SET	8 8 22 8 8 74	8 10 12 8 4 2	88-1 88-2	C4 C4 C4 C4 C4 C6	DEFER E SET D+ E SET*	(A72) (A68) (A66) (A46) (A62) (A64) 95 96 96	2 2 13	90-1	C6 C6 D7	
EFA* EFA* EFA·PTG1 End Cycle (F/F)	103 103 34 113	12 6 1	88-2 88-3 88-2 88-1	D5 D5 A2 D5	MBC(SH) MBC(SH) ACD4 SEL* ACD OUT* Disable D Mult S0 S0 D SET JSR · EFA EFA · PTG1 ACD4 SEL* ACD3 SEL* MBC (DS) S Mult (SEL) ACTG End Cycle(F/F) LOAD CRY* (LD) Test Skip (LD) Loop/	92 32 33 44 45 46 47 74 93 34 44 50 32 116 53 113 97 102	1 13 13 9 10 4 3 4 4 13 5 1 10, 12 12 10	88-2	C3 A5 A4 C5 B3 B3 C3 B3 C7 C8 A3 C5 C5 A4 C7 C8 C5 D8	
*Indicates ''Not''					Pack Shifter Logic	103 109 114	10 13 1	88-4 ''	D5 A8 A8	

SIGNAL LIST
Table 1 - Nova 1210/1220

OI	RIGIN				DESTINATION					
SIGNAL		PIN	DWG	GRID	FUNCTION	т —		DWG	GRID	
End Cycle*(F/F)	113	6	88-1	C5	Shifter Logic PTG0 TS0	114	9	88-4	A8	
E SET	96	3	88-2	C6	Logic EXEC D+E SET*	112 95 96	15 12	88-1 88-2	A6 D6 D7	
EXEC	95	9	88 -2	D6	EXEC* (INST DCDR)	73 92	11 19	11	D6 B5	
EXEC*	73	10	**	D6	(CON IND) (INST DCDR)	(A11) 52	(P51 15	89-1 88-2	C1 B5	
EXT LOAD*	(A47) (B49)			A3 A8	LOAD AC* Shifter (Enab)	111 125	4 8.9	88 - 3 88 - 4	D3 A8	
EXT Select*	(B80)				SELECT	35	9,	103-1		
FETCH FETCH*	95 94	5 12	88 -2 88 -2	D6	MB LOAD LOAD IR LOAD PC* FETCH·TSO* ALC* ION FETCH* CLR SKIP* (CON IND)	13 34 61 64 50 85 94 100 (A13)	13 9 10 9 1 13 4	88-1 88-2 88-3 88-2 "" "" 88-3)89-1	C3 A7 B4 D5 B8 C6 D6 B4 C2	
FEICH"	94	12	00-2	Бб	ACD OUT* FETCH+ DEFER ADD ONE*	75 89	1, 13 1 1	88-2	B4 C7 D3	
Fetch+Defer	75	3	88-2	C7	IR0+SKP E SET	50 74	1 13	11	B6 C7	
FETCH·TS0*	64	8	88-2	D4	EFA Mult (SEL)	85 120	12 16	,, 88 - 4	C5 C5	
Force Load IR*	(A85)		88-2	A8	IR(LD)	12	4	88-2	A8	
*Indicates ''Not''										

SIGNAL LIST

Table 1 - Nova 1210/1220

 					- M	-14 X	*,*/	4	
OF	RIGIN				DES	TINAT	ION		
SIGNAL	СНІР	PIN	DWG	GRID	FUNCTION	CHIP	PIN	DWG	GRID
HALT*	71	6	88-2	C7	MB LOAD (RUN LOGIC) DCHA	14 62 71	2 3 9	88-1	C2 B7 C5
INH0	34	9	103-1	В	MEM0* DATA0*	16 16	1 13	103-1 ''	C C
INH0* INH1	34 34	8 5	103-1	B B	(INHB0) (Q15) MEM1* DATA1*	68 16 16	12 5 9	103-2 103-1	7 C C
INH1* INH2	34 32	6 5	103-1	B B	(INHB1) (Q16) MEM2* DATA2*	68 14 14	2 1 13	103-2 103-1 ''	7 C C
INH2* INH3	32 32	6 9	103-1	B B	(INHB2) (Q13) MEM3* DATA3*	64 14 14	2 5 9	103-2 103-1	7 C C
INH3* INH4	32 31	8 9	103-1	B B	INHB3) (Q14) MEM4* DATA4*	64 12 12	1 13	103-2 103-1	7 C C
INH4* INH5	31 31	8 5	* * * * * * * * * * * * * * * * * * *	B B	(INHB4) (Q11) MEM5* DATA5*	58 12 12	5 9	103 -2 103 -1	7 C C
INH5* INH6	31 28	6 5	103-1	B B	(INHB5) (Q12) MEM6* DATA6*	58 10 10	2 1 13	103-2	7 C C
INH6* INH7	28 28	6 9	103-1	B B	(INHB6) (Q9) MEM7* DATA7*	55 10 10	2 5 9	103-2	7 C C
INH7* INH8	28 27	8 9	103-1	B B	(INHB7) (Q10) MEM8* DATA8*	55 8 8	12 1 13	103-2	7 C C
INH8* INH9	27 27	8 5	103-1	B B	(INHB8) (Q7) MEM9* DATA9*	48 8 8	12 5 9	103-2 103-1	4 C C
INH9* INH10	27 24	6 5	103-1	B B	(INHB9) (Q8) MEM10* DATA10*	48 6 6	2 1 13	103-2 103-1	4 C C
INH10*	24	6	103-1	В	(INHB10)(Q5)	45	2	103-2	4
*Indicates ''Not''						<u> </u>			

SIGNAL LIST
Table 1 - Nova 1210/1220

SIGNAL LIST
Table 1 - Nova 1210/1220

	DICIN				DEC	NITTA LA I	TION:		
<u></u>	RIGIN			1	DES	STINA'	HON	1	_
SIGNAL	СНІР	PIN	DWG	GRID	FUNCTION	CHIP	PIN	DWG	GRID
INH GATE B	26	6	103-1	D2	(INHB8) (Q7)	48	13	103-2	4
					(INHB9) (Q8)	48	1	17	4
					(INHB10) (Q5)	45	1	''	4
					(INHB11) (Q6)	45	13	**	4
					(INHB12) (Q3)	39	13	''	4
					(INHB13) (Q4)	39	1	11	4
					(INHB14) (Q1)	37	$\frac{1}{1}$	11	4
TATTITUTE	13	8	00 1	C2	(INHB15) (Q2)	37	13		D3
INHIBIT	13	Ø	88-1	CZ	INTL CAME A D	(B30)	_	103-1	D3
					INH GATE A, B		9	103-1	D3
INHIBIT					WRITE MEM	41	4	''	D3
SELECT*	(B85)		103-1	D8	SELECT	35	5	103-1	D8
INPUT*(F/F)	66	8	88-1	B5	DRIVE IO*	12	10	88-1	B3
111101 (1/1/	00		00-1	Бо	(IO INST	12	10	00-1	D
					DCDR)	25	15	11	в4
					MB LOAD	112	1,9	11	C3
[INTA*]	6	6	88-1	A4	INTA	5	9	11	A4
INTA	5	8	**	A4		(A40)	_	90-1	
INTR*	(B29)				PI SET	` 75 [°]	12	88 -2	C7
INH TRANS*	56	6	88-1	B2		(B45)		90-1	
Ì					INH TRANS.				
	ŀ				SEL]	36	2,5,		
							4	103-1	C8
[INH TRANS.						i			
SEL]	36	6	103-1	C8	MEM0*	16	2	103-1	C
	1				MEM1*	16	4	**	C
					MEM2*	14	2	**	C
		1			MEM3*	14	4	''	C
1	1				MEM4*	12	2	11	C
		ł			MEM5*	12	$\frac{4}{2}$	11	C
]	1				MEM6*	10 10	4	**	C
j j	l	1	ĺ	i	MEM7* MEM8*	8	$\overset{4}{2}$	**	Č
j	- 1	J	1	1	MEM9*	8	4	**	č
	- 1	İ	ł	ı	MEM10*	6	2	**	č
	j	1			MEM10*	6	4	11	č
	I	ł	i	1	MEM12*	4	$\stackrel{\scriptscriptstyle 1}{2}$	11	č
*Indicates ''Not''									

SIGNAL LIST
Table 1 - Nova 1210/1220

O	RIGIN				DES	TINA'	TION		
SIGNAL	СНІР	PIN	DWG	GRID	FUNCTION	I	Y	DWG	GRID
IO·E	42	5	88-1	C8	MEM13* MEM14* MEM15* IO·E* (IO Inst DCDR) (IO DCDR) HALT*	4 2 2 94 64 62 71	4 2 4 3 4 2 1	103-1 '' 88-1 '' 88-2	C C C7 D5 A5 C8
IO·E* [IO(F+D*] IO(F+D)	94 51 27	4 12 6	88-1 88-2	C7 B6 B5	LOOP SET* (Pack Logic) MA LOAD* IO(F+D) INPUT F/F Logic IO·E	86 89 60 27 9	9 4 13 5 12 3	88 - 3 88 - 3 88 - 1 88 - 2 88 - 1 88 - 1	C7 C5 D2 B6 C5 C8
ION	82	6	**	C7	(SKIP Logic)	11	13	88-3	В7
ION*	84	6	88-2	C7	ION* (CON IND) ION (ION LOGIC)	84 (A16) 82 85	5 (P26 5 5	88-2) 89-1 88-2	C7 D2 C7
[IO PLS*] IO PLS IORST IO SKIP* IO SKIP IR0*	63 26 10 25 26 28	4 4 8 12 2 5	88-1 "' "' 88-1 88-2	A7 A4 A4 B4 B4 A6	IO PLS IO SKIP SKIP INC* (Skip Logic) (RUN LOGIC) ACD OUT* SH/SWP DCDR	26 (A74) (A70) 26 87 59 43 45 50	1 1 5 10 3 13	88-1 90-1 90-1 88-1 " 88-3 88-1 88-2 88-2	C7 A4 B4 B8 B6 B7 B3 B6
IR5·IR6 IR0+SKIP *Indicates ''Not''	65 50	3 12	88 -2 88 -2	B8 B6	PC ENAB* (Pack Logic) AND ENAB* HALT* ALC* (SH/SWP DCDR)	51 53 92 64 71 50	1 4,5 4 12 4 11	88-3 88-3 88-2 "	B6 B4 C6 B8 D8 B8

SIGNAL LIST
Table 1 - Nova 1210/1220

OI	RIGIN	<u>'</u>			DES	TINA	ΓΙΟΝ		
SIGNAL	СНІР	PIN	DWG	GRID	FUNCTION	CHIP	PIN	DWG	GRID
ISTP* (ISZ+DSZ)E	(A17) 84	(P24 8	89-1 88-3	B8 D6	(RUN LOGIC) CRY SET*	24 81	9 9, 10	88 - 1 88 - 3	В7 С6
(ISZ+DSZ)E*	52	9	88-2	В4	LOOP SET* (INST DCDR) (ISZ+DSZ)E	104 52 84 86	2 1 13	88-2 88-3	D6 B5 D6 D8
ISZ·E·TS0*	52	5	88-2	В4	Test Skip Set ADD ONE*	89	9	88-2	D3
(JMP+JSE) (F+D)	48	11	**	В5	PC ENAB* JSR·EFA*	61 93	3 2	88 -3 88 -2	В4 С7
JSR.EFA	92	11	88-3	C3	SHIFT ACB WAS JSR	100 103	1	88-3	C3 D5
JSR·EFA*	93	12	88-2	C7	JSR·EFA (Pack Logic)	92 99	13 2	11	C3 C5
KEY	23	5	88-1	C6	KEY* LOAD IR	6 34	1 10	88-1 88-2	C7 A7
KEY*	6	3	88 -1	C6	CON INST* (RUN LOGIC) KEYM SET* Disable D Mult LOAD PC* KEY·LOOP (DS) ADD ONE* INH TRANS* MA LOAD* (Pack Logic) LOOP SET* CLR SKIP*	36 43 55 46 61 4 23 44 56 56 70 84 99	9 9 5 1 5 2 4 5 4 9 13 10	88-1 88-2 88-3 88-1 88-2 88-1 	A2 B7 B6 B3 B4 C6 C6 D3 B2 D3 C6 C6 B3
KEY ENAB*	3	3	88-1	В8	PRESET*	3 6	12 2	88-1 ''	B7 C7
KEY·LOOP	4	3	88-1	C6	CON DATA* ACD OUT* LOAD MBO*	4 45 98	10 2 13	88-2 88-3	A2 A3 B3
*Indicates ''Not''									

SIGNAL LIST
Table 1 - Nova 1210/1220

OF	RIGIN	,			DES	TINAT	TION		
SIGNAL	CHI P	₽IN	DWG	GRID	FUNCTION	СНІР	PIN	DWG	GRID
KEYM KEYM*	23 23	11 12	88-1 88-1	C6	CON DATA* (RUN LOGIC) ADD ONE*	24 43 41	3 2 1	88-1 '' 88-2	A3 B7 D4
KEYM• PL	41	8	88-1	C5	KEYM SET* KEYM·PL·TSO* JSR·EFA LOAD MBO*	55 57 93 98	3 2 9 5	88-1 88-3 ''	B6 C4 C4 A3
KEYM·PL· TS0*	57	3	88-3	С3	INH TRANS* LOAD PC*	56 57	5 4	88-1 88-3	B2 B3
KEYM SET*	55	6	88-1	В6	[KEY M SET] FETCH	22 97	1 2	88 - 1 88 - 2	B6 D7
[KEYM SET] KEY SEEN*	22	2	88-1	B6	KEYM	23	14	88-1	A6
(F/F)	2	6	**	B8	(RUN LOGIC) (MR) (MR)	21 54 102	1 1 1	;; 88 -3	B6 D8 D8
KEY SEEN (F/F)	2	5	88-1	В8	KEY ENAB* (SH)	3 23	1 13	88-1	D8 C6
LDA·E* LOAD AC*	52 93	10 6	88-2 88-3	B4 D2	(Pack Logic) ACD	99 (A77) 123	1 3	88-3 90-1 88-4	D5 B8
LOAD ACB	100	11	88-3	C3	ACS SHIFT ACB ACB(LD) ACB(LD) ACB(LD)	124 100 105 107 108	3 2 10 10 10	88-3 88-4	B7 C3 B4 B4 B4
LOAD CRY*	97	8	88-3	C5	CARRY (Pack Logic)	76 99	11 5	88-3	C5 C5
LOAD IR *Indicates '' Not''	34	3	88 -2	A6	IR(LD) IR(LD) Logic MBC(LD) MBC(LD) [STUTTER]	(A73) 28 8 32 33 54	10 5 10 10 15	90 -1 88 -2 '' '' '' 88 -1	A6 A8 A4 A5 D7

SIGNAL LIST
Table 1 - Nova 1210/1220

OI	RIGIN				MBO(SH) MSB-4 MBO(SH) MBO(SH) MSB-4 MSB-1 MBO(SH) MSB-4 MF MBO(SH) MSB-4 MF MBO(SH) MSB-4 MF MBO(SH) MSB-4 MSB-1 MBO(SH) MSB-4 MSB-1 MSB-3 MSB-1				
SIGNAL	СНІР	PIN	DWG	GRID	FUNCTION	СНІР	PIN	DWG	GRID
LOAD MBO*	98	8	88-3	A2	MBO(SH) MBO(SH)	38 39	13 13	**	C4 C4 C4 C4
LOAD PC* LOOP	57 103	8 7	88-3	A2 D5	PC MB LOAD LOOP* S0 (IO Inst DCDR)	119 13 22 47 64	12 12 5 9 5	88-1 88-3 88-2 88-1	A6 C3 D5 C3 B5
LOOP*	22	6	88-3	D5	PC IN* CON INST*	35 36	5 10	88-1	D5 A2 D3
LOOP SET	83	2	88-3	D5	$({ m TS3/TS0})$ PTG-5	65 70	9 10	11	C5 D5 D5
LOOP SET*	104	8	88-3	D5					C5 D5
MA1 MA1* MA2 MA2* MA3 MA3* MA4 MA4* MA4B*	33 33 33 33 33 29 67	14 10 11 9 8 16 1	103-1 103-4	C7 C7 C7 C7 C7 C7 C7 C7 D8	[SARD1] " [SARD2] " [SARD2] " [SARD2] " [SARD3] " MA4B* MA4B Y ADDR DCDR	35 35 35 35 67 67 52 66 54	4 1 2 2 3 11 5,4 5,4 5,4	103-4	D8 D8 D8 D8 D8 D8 7 7 7
MA5 MA5* MA5B	29 29 67	15 14 6	103-1 103-4	C6 C6 C8	MA5B MA5B*	67 67	5, 4 5 9	103-4	C8 C8

SIGNAL LIST
Table 1 - Nova 1210/1220

OI	RIGIN				DES	TINA	ΓΙΟΝ		
SIGNAL	СНІР	PIN	DWG	GRID	FUNCTION	CHIP	PIN	DWG	GRID
					Y ADDR DCDR	54	7	103-4	7
					11	62	7	11	7
					77	52	7	* *	7
					11	66	7	11	7
MA5B*	67	8	103-4	C8	Y ADDR DCDR	54		103-4	7
					11	62	1	* 1	7 7
					11	52	1	**	7
					""	66	1	**	B8
MA6	29		103-1	C5	MA6B*	67	1	, "	D0
MA6*	29	11	100 4	C5	MACD	C II	10	102 4	B8
MA6B*	67	2	103-4	B8	MA6B	67	13 6	103-4	7
					Y ADDR DCDR	62 66	6	.,	7
14.0D	C T	10	102 /	В8	11	54	6	,,	7
MA6B	67	12	103-4	ъ	**	52	6	,,	7
3.6.4.77	29	9	103-1	C5	MA7B*	44	11	,,	A8
MA7 MA7*	29 29	8	103-1	C5	MAID	27	11		
MA7B*	44	10	103-4	A8	MA7B	44	3	103-4	A8
MA (D"	44	10	103-4	110	Y ADDR DCDR		5,4		Α
					"	50	5, 4		Α
MA7B	44	4	103-4	A 8	11	57	5, 4		Α
WAID	11	1	100 1		11	47	5, 4		Α
MA8	25	16	103-1	C4	MA8B*	44	9	103-4	A 8
MA8*	25	1	11	C4		į .			ł
MA8B*	44	8	103-4	A 8	MA8B	44	5	103-4	A8
111111111111111111111111111111111111111					Y ADDR DCDR	60	7	**	Α
					7.7	50	7	**	Α
			l		11	57	7	''	Α
				i i	11	47	7	"	Α
MA8B	44	6	103-4	A8	11	60	1	''	A
					**	50	1	''	Α
			l	Ī	11	57	1	''	A
					11	47	1	"	A
MA9	25	15	103-1	C4	MA9B*	44	13	"	A8
MA9*	25	14	7.7	C4					
*Indicates ''Not''									

SIGNAL LIST
Table 1 - Nova 1210/1220

OI	RIGIN				DES	TINA	ΓΙΟΝ		
SIGNAL	СНІР	PIN	DWG	GRID	FUNCTION	СНІР	PIN	DWG	GRID
MA9B*	44	12	103-4	A 8	MA9B Y ADDR DCDR	44 60 57	1 6 6	103-4	A8 A A
мА9В	44	2	103-4	A 8	11	50 47	6 6	11	A A
MA10 MA10*	25 25	10 11	103-1	C4 C4	MA10B*	71	3	''	D8
MA10B*	71	4	103-3	D8	MA10B X ADDR DCDR	71 73 77	$ \begin{array}{c} 11 \\ 5, 4 \\ 5, 4 \end{array} $	103-3 ''	D8 7 7
MA10B	71	10	103-3	D8	11	72 76	5, 4 $5, 4$		7 7
MA11 MA11* MA11B	25 25 71	9 8 6	103-1 '' 103-3	C4 C4 C8	MA11B MA11B*	71 71 72	5 9 7	103-3	C8 C8 7
					X ADDR DCDR	76 73 77	777	** **	7 7 7
MA11B*	71	8	103-3	C8	;; ;;	77 72 76 73	1 1 1	**	7 7 7
MA12	22	16	103-1	С3	,, MA12B*	77 71	1 1 1	,, 103-3	7 B8
MA12* MA12B*	22 71	1 2	103-1	C3 B8	MA12B X ADDR DCDR	71 76	13 6	103-3	B8 7
MA12B	71	12	11	В8	11 11 11	77 72 73	6 6 6	,, ,,	7 7 7
MA13 MA13*	22 22	15 14	103-1 '' 103-3	C3 C3 A8	MA13B* MA13B	80 80	11 3	'' 103-3	A8 A8
MA13B*	80	10	109-9	Ao	X ADDR DCDR	79 74	$5, 4 \\ 5, 4$	**	A A
MA13B	80	4	103-3	A 8	X ADDR DCDR	78 75	$5, 4 \\ 5, 4$		A A
*Indicates ''Not''							<u> </u>		

SIGNAL LIST
Table 1 - Nova 1210/1220

O)	RIGIN				DES	STINA'	TION		
SIGNAL	СШР	PIN	DWG	GRID	FUNCTION	CHIP	PIN	DWG	GRID
MA14 MA14*	22 22	10 11	103-1	C2 C2	MA14B*	80	9	103-3	A8
MA14B*	80	8	103-3	A8	MA14B X ADDR DCDR	80 79	5 7	103-3	A8 A
					71 11	74 78	7 7	†† ††	A A
MA14B	80	6	103-3	A8	7 7	75 79	7	"	A A
WATE	00	Ü	100-0	110	11	74 78	1 1	"	A A
D4 A 1 5	22	9	103-1	C2	**	75 84	1 1 13	",	A A A8
MA15 MA15* MA15B*	22 22 80	8 12	103-1	C2 A8	MA15B*				A8
MAI5B*	80	12	103-3	Ao	MA15B X ADDR DCDR	80 79	1 6 6	103-3	A A A
MA15B	80	2	103-3	A8	11	78 74 75	6 6	**	A A A
MA LOAD*	60	8	88-1	D2	MTG(SH) [MA LOAD]	(B7) 35	11 9,10	90-1 88-1 103-1	C7 C8
					11	30	12, 13	,,	C8
[MA LOAD]	30	8	103-1		MA1-3	33 33	13 4	103-1	
					MA4-7	29 29	13 4	"	
					MA8-11	25 25	13 4	",	
мвс8*	33	5	88-2	A5	MA12-15 (SKIP LOGIC) MBC8 MBC(DS) (SH/SWP DCDR)	22 · 11 27 33 51	13 9 1 4 3	88-3 88-2 "	B7 A5 A5 B6
*Indicates ''Not''					(IO DCDR)	63 63	3 13	88-1	A4 A4

SIGNAL LIST
Table 1 - Nova 1210/1220

O	RIGIN				DES	STINA	ΓΙΟΝ	T	
SIGNAL	СНІР	PIN	DWG	GRID	FUNCTION	CHIP	PIN	DWG	GRID
мвс8	27	2	88-2	A4	(SKIP LOGIC) S0	11 47	5 5	88-3 88-2	B7 C3
MBC9*	32	5	88-2	A4	(SH/SWP DCDR) (IO DCDR)	51 63	2 2	,, 88-1	B6 A4
					MBC9	63 79	14 9,	"	A4
MBC9	79	8	88-2	A3	(SKIP LOGIC)	80	10 1	88-2 88-3	A4 B6
MBC10*	33	9	88-2	A5	MBC10	27	9	88-2	A4
				110	CRY ENAB	77	$\frac{3}{2}$	88-3	C7
MBC10	27	8	88-2	A4	CPU INST*	9	5	88-2	B8
					DS0*	8	9	88-1	C4
MBC11*	32	9	**	A4	MBC11	27	13	88-2	A3
MBC11	27	12	**	A3	DS1*	8	11	88 - 1	C4
					CPU INST*	9	4	88 -2	В8
					CRY ENAB	77	5	88 - 3	C7
MBC12*	33	7	88-2	A5	MBC12	27	11	88-2	A4
MBC12	27	10	88-2	A4	DS2*	8	13	88-1	C4
					CPU INST*	9	2	88-2	D8
		1			LOAD CRY*	101	1	88-3	C6
					S MULT	116	3	88-4	C7
MBC13*	32	7	88-2	A4	MBC13	27	3	88-2	A3
MBC13	27	4	11	A3	DS3*	22	9	88-1	C4
					CPU INST*	9	1	88-2	В8
	i				(SKIP LOGIC)	77	1	88-3	B7
Language Control	0.0				S MULT	116	6	88-4	C7
MBC14*	33	11	88-2						
(NOT USED)	00	4.0							
MBC14	33	12	88-2	A5	DS4*	8	3	88-1	C4
	ŀ	ĺ			CPU INST*	10	1	88-2	B8
	1				(SKIP LOGIC)	77	10	88 -3	B7
MBC15*	32		00.0		S MULT	116	13	88-4	C6
MBC15	32	11 12	88-2	A4	(SKIP LOGIC)	80	4	88 - 3	B6
MPC19	34	12		A3	DS5*	8	1	88-1	C4
					CPU INST* S MULT	10 116	2 10	88-2 88-4	B8 C6
*Indicates ''Not''									

SIGNAL LIST
Table 1 - Nova 1210/1220

RIGIN		·		DES	מתודא	TION		
СНІР	PIN	DWG	GRID	FUNCTION	T	_		GRID
19 18	6 8	88-1 103-1	D2 B8			$^{2,4},$	103-1	B8 B8
30	6	**	В8	INHO F/F INH1 F/F INH2 F/F INH3 F/F INH4 F/F INH5 F/F INH6 F/F INH7 F/F INH8 F/F INH9 F/F INH10 F/F INH11 F/F INH12 F/F INH13 F/F INH14 F/F	34 34 32 32 31 31 28 27 27 24 24 23 23	13 1 13 13 1 13 13 13 13 13 13 13 13 13	103-1	B B B B B B B B B B B B B B B B B B B
14	6	88-1	C2	INH15 F/F	(B74)	9	90-1	В В8
36	8	103-1	В8	INHO F/F INH1 F/F INH2 F/F INH3 F/F INH4 F/F INH5 F/F INH6 F/F INH7 F/F INH8 F/F INH9 F/F INH10 F/F INH11 F/F INH12 F/F INH13 F/F INH14 F/F	34 34 32 32 31 31 28 27 27 24 24 23 23	11 3 3 11 11 3 11 11 3 11 11 3 3	103-1	B B B B B B B B B B B B B B B B B B B
	19 18 30	CHI P PIN 19 6 8 30 6 14 6	CHIP PIN DWG 19 6 88-1 130 6 " 30 6 " 14 6 88-1	CHI P IN DWG GRID 19 8 88-1 B8 D2 B8 30 6 " B8 B8 4 6 88-1 C2 C2	CHIP PIN DWG GRID FUNCTION 19	CHIP PIN DWG GRID FUNCTION CHIP 19 6 88-1 D2 (B86) 18 8 103-1 B8 INH0 F/F 34 30 6 " B8 INH0 F/F 34 INH1 F/F 32 INH3 F/F 32 INH3 F/F 31 INH6 F/F 31 INH6 F/F 28 INH7 F/F 28 INH1 F/F 24 INH1 F/F 24 INH1 F/F 23 INH1 F/F 21 INH1 F/F 32 INH1 F/F 34 INH1 F/F 32 INH3 F/F 32 INH3 F/F 32 INH4 F/F 31 INH6 F/F 32 INH6 F/F 32 INH3 F/F 32 INH6 F/F 32 INH9 F/F 31 INH6 F/F 32 INH1 F/F 34 INH7 F/F 32 INH1 F/F 32 INH1 F/F 32 INH1 F/F	CHIP PIN DWG GRID FUNCTION CHIP PIN 19 6 88-1 D2 (B86) 18 8 103-1 B8 INH0 F/F 34 1 INH1 F/F 34 1 INH2 F/F 32 1 INH3 F/F 32 13 INH4 F/F 31 1 INH6 F/F 28 1 INH1 F/F 24 1 INH10 F/F 24 1 INH11 F/F 24 13 INH12 F/F 23 13 INH15 F/F 21 1 INH15 F/F 21 1 INH16 F/F 21 1 INH17 F/F 22 1 INH17 F/F 23 13 INH17 F/F 24 13 INH18 F/F 27 13 INH18 F/F 21 1 INH18 F/F 21 1 INH18 F/F 21 1 INH18 F/F 32 11 INH19 F/F 32 3 13 INH18 F/F 32 3 11 INH19 F/F 32 3 3	CHIP PIN DWG GRID FUNCTION CHIP PIN DWG 19 6 88-1 D2 (B86) 103-1 103-1 30 6 " B8 INH0 F/F 34 13 103-1 30 6 " B8 INH0 F/F 34 1 " INH1 F/F 34 1 " INH1 F/F 34 1 " INH2 F/F 32 1 " INH1 F/F 32 1 " INH3 F/F 32 13 " INH1 F/F 34 1 " INH6 F/F 28 1 " INH1 F/F 28 1 " INH1 F/F 28 1 " INH1 F/F 24 1 " INH1 F/F 24 1 " INH1 F/F 24 1 " INH1 F/F 24 1 " INH1 F/F 34 11 103-1

OI	RIGIN				DESTINATION				
SIGNAL	СНІР	PIN	DWG	GRID	FUNCTION	СНІР	PIN	DWG	GRID
Management	40	_	00.4	D.4	INH15 F/F	21 (B79)	11	103-1	В
MBO0*	40	5	88-4	D4	[MD0]	17	9	103-1	A7
MBO1*	39	5	88 -4	D3	MB1	(B77) 17	5	103-1	A7
MBO2*	37	5	88-4	C4	(CON IND) (P14)	7 (B44)	11	89-1	D7
WBO2**	31	J	00-4	C4	MD2	15	9	103-1	A7
MBO3*	38	5	88 -4	C3	(CON IND) (P15)	7 (B43)	5	89-1	D7
					MD3 (CON IND) (P38)	15 8	5 9	103-1 89-1	A6 D7
MBO4*	40	7	88 -4	D4	MD4	(B42) 13	9	103-1	A6
	:				(CON IND) (P16)	8	11	89-1	D6
MBO5*	39	7	88 -4	D3	MD5	(B32) 13	5	103-1	A6
MBO6*	37	7	88-4	C4	(CON IND) (P11)	8 (B16)	5	89-1	D6
MBOU	0,	ľ	00 1		MD6	11	9 9	103-1 89-1	A5 D6
MBO7*	38	7	88-4	C3	(CON IND) (P35)	(B14)			
					MD7 (CON IND) (P9)	11 9	5 11	103-1 89-1	A5 D5
MBO8*	40	9	88-4	D4	MBO12 SAVE*	(B12) 42	2	88-1	C8
					MD8 (CON IND) (P18)	9 9	9 5	103-1 89-1	A5 D5
MBO9*	39	9	88-4	D3		(B9)			
					MD9 (CON IND) (P8)	9 10	5 9	103-1 89-1	C4 D5
MBO10*	37	9	88-4	C4	MD10	7	9	103-1	C4
MDO11*	38	9	88-4	C3	(CON IND) (P44)	10 (B5)	11	89-1	D4
MBO11*	აგ	ฮ	00-4		MD11	7	5	103-1	C4
*Indicates '' Not''					(CON IND) (P6)	10	5	89-1	D4

SIGNAL LIST
Table 1 - Nova 1210/1220

OF	RIGIN				DESTINATION				
SIGNAL	СНІР	PIN	DWG	GRID	FUNCTION	CHIP	PIN	DWG	GRID
MBO12*	40	11	88-4	D4	MD12	(A39) 5	9	103-1	A3
мво12	40	12	88 -4	D3	(CON IND) (P30) D MULT MULT	11 121 120	9 3 6	89-1 88-4	D4 C8 D6
MBO13*	39	11	88-4	D2	ADDER TEST	57 (A37) 60 5	12 5 5	88-3 88-3 103-1	A4 A4 A3
мво13	39	12	88-4	D2	MD13 (CON IND) (P4) D MULT MULT	11 121 120	11 6 3		D3 C8 D6
MBO14*	37	11	88 -4	Ç4	ADDER TEST MD14	(A43) 60 3	4 9 5	88-3 103-1 89-1	A4 A3 D3
MBO14	37	12	88-4	C3	(CON IND) (P12) D MULT MULT	11 121 120	13 21	88-4	C7 C6
мво15*	38	11	88-4	C2	MD15	(A41) 3 11	5 1	103-1 89-1	A2 D3
MBO15	38	12	88 -4	C2	(CON IND) (P28) ADDER TEST D MULT MULT	84 120 121	9 10 18	88-3 88-4	A4 C7 C6
MBO12 SAVE*	42	7	88-1	C7	S0 ADD ONE*	48 90	2 5	88 -2	C4 D4
[MD0] MD1	17 17		103-1 103-1	B7 B7	INH0 INH1 MA1	34 34 33		103-1 103-1	B7 B7 C7
MD2	15	8	103-1	В7	INH2 MA2	32 33	6	",	В7 С7
MD3	15	6	103-1		INH3 MA3	32 33		''	B7 C7
MD4	13	8	103-1	В6	INH4 MA4	31 29		''	B7 C7
*Indicates ''Not''									

SIGNAL LIST
Table 1 - Nova 1210/1220

O	RIGIN				DESTINATION				
SIGNAL	СНІР	PIN	DWG	GRID	FUNCTION	CHIP	PIN	DWG	GRID
MD5	13	6	103-1	B6	INH5	31	2	103-1	B6
				775	MA5	39	3	11	C6
MD6	11	8	103-1	B5	INH6	28 29	2 6	,,	B5 C5
1505	11	6	103-1	В5	MA6 INH7	28	12	11	B5
MD7	11	O	103-1	D0	MA7	29	7	11	C5
MD8	9	8	103-1	В5	INH8	$\frac{27}{27}$	12	11	В5
MDO	ľ	Ů	100 1		MA8	25	2	11	C5
MD9	9	6	103-1	B4	INH9	27	2	11	В4
					MA9	25	3	11	C4
MD10	7	8	103-1	B4	INH10	24	2	**	B4
					MA10	25	6	11	C4
MD11	7	6	103-1	В4	INH11	24	12	11	B4
				720	MA11	25	7	""	C4
MD12	5	8	103-1	В3	INH12	23	$\begin{vmatrix} 12 \\ 2 \end{vmatrix}$,,	B3 C3
	_	_	400.4	В3	MA12	22 23	2	11	B3
MD13	5	6	-103-1	Бо	INH13 MA13	$\frac{23}{22}$	3	11	C3
3.4704.4	3	8	103-1	ВЗ	INH14	21	2	71	B3
MD14	٥	0	105-1	Do	MA14	22	6	11	C3
MD15	3	6	103-1	В2	INH15	21	12	"	B2
MIDIO	ľ				MA15	22	7	103-1	C2
MULTIPLY/									
DIVIDE	SEL			1					
MD SEL1*	(A87)		88 -2		ACS1 SEL*		6,8	88 -2	C4
MEM0*	16	3	103-1			(B71)	_		~~
(ACEX+ACDP)	1	3	89-1	A5	(CON IND) (P39)	7	9	89-1	C8
					IRO*	28	3	88-2	A6
				ł	MBO0*	40	3 2	88-4 88-2	D4 C7
				ľ	Defer Again	76 55	10,	00-4	Ci
					(EFA LOGIC)	ออ	10, 13	88-3	C6
3573514	10	e	103-1	В7		(B70)	10	00-0	
MEM1*	16 1	6	89-1	1	(CON IND) (P41)	7	13	89-1	C7
(ACDP)		Ů,	1 2		IR1*	29	2	88-2	A7
					MBO1*	39	3	88-4	D3
					(EFA LOGIC)	55	9	88-3	C6
*Indicates ''Not''	1 1		i		,	l]	

O!	RIGIN	<u> </u>			DESTINATION				
SIGNAL	СНІР	PIN	DWG	GRID	FUNCTION	СНІР	PIN	DWG	GRID
MEM2* (DP+ DPN)	14 2	3 8	103 -1 89-1	B7 A4	(CON IND) (P13) IR2* MBO2*	(B47) 7 29 37	3 15 3	39-1 88-2 88-4	C7 A7 C4
MEM3* (ACEX+ ACDP)	14 1	6 11	103-1 89-1	B6 A7	(CON IND) (P43) IR3* MBO3*	55 (B68) 7 29 38	1 1 14 3	89-1 88-2 88-4	C6 C7 A7 C3
MEM4* (ACEX+ACDP)	12 1	3 8	103-1 89-1		(CON IND) (P37) IR4* MBO4*	(B28) 8 29 40	13 3 2	89-1 88-2 88-4	C6 A7 D4
MEM5* (EX+STRT+ ACDP)	12 2	6 11	103-1 89-1	B6 A3	(CON IND) (P36) IR5*	(B26) 8 28	3 2	89-1 88-2	C6 A6
MEM6* (EX+EXN+DP+	10	3	103-1	B5	MBO5*	39 (B22)	2	88-4	D3
(DPN)	2	3	89-1	A3	(CON IND) (P10) IR6* MBO6*	8 28 37	1 15 2	89-1 88-2 88-4	C6 A6 C4
MEM7* (EXN+DPN)	10 2	6 6	103-1 89-1		(CON IND) (P42) IR7* MBO7*	(B24) 9 28 38	13 14 2	89-1 88-2 88-4	C5 A6 C3
MEM8*	8	3	103-1	B5	(CON IND) (P34) MBC8* MBO8*	(A55) 9 33 40	3 3 15	89-1 88-2 88-4	C5 A5 D4
MEM9*	8	6	103-1	В4	(CON IND) (P7) MBC9* MBO9*	(A53) 9 32 39	1 3 15	89-1 88-2 88-4	C5 A4 C3
*Indicates ''Not''									

O	RIGIN			Ì	DESTINATION				
SIGNAL	СНІР	PIN	DWG	GRID	FUNCTION	СНІР	PIN	DWG	GRID
MEM10*	6	3	103-1	В4	(CON IND) (P32) MBC10* MBO10*	(A45) 10 33 37	13 15 15	89-1 88-2 88-4	C4 A5 C4
MEM11*	6	6	103-1	B4	(CON IND) (P31) MBC11* MBO11*	(A51) 10 32 38		89-1 88-2 88-4	C4 A4 C3
MEM12*	4	3	103-1	В3	(CON IND) (P5) MBC12* MBO12*	(A36) 10 33 40	1 2 14	89-1 88-2 88-4	C4 A5 D4
MEM13*	4	6	103-1	В3	(CON IND) (P29) MBC13* MBO13*	(A35) 11 32 39	13 2 14	89-1 88-2 88-4	C3 A4 D2
MEM14*	2	3	103-1	В2	(CON IND) (P3) MBC14* MBO14*	(B76) 11 33 37	3 14 14		C3 A5 C4
MEM15*	2	6	103-1	В2	(CON IND) (P2) MBC15* MBO15*	(B18) 12 32 38	13 14 14	88-2	C3 A4 C2
MEM CLK	73	6	88-1	A6	(MTG) (KEY/RUN/DCH) (ACTG) LOAD AC* S BUFF D BUFF IR4, IR1-3	(B48) 17	6 6 6 4 6 6	90-1 88-1 " 88-3 88-4 " 88-2	D6 C6 D8 D3 C7 C8
мем ок	(A9)		91	B2	RUN LOGIC	62	5	88-1	C7
*Indicates ''Not''									

SIGNAL LIST

Table 1 - Nova 1210/1220

O.	RIGIN				DESTINATION				
SIGNAL	СНІР	PIN	DWG	GRID	FUNCTION	CHIP	PIN	DWG	GRID
[MSKO] MSKO*	4 5	11 4	88-1	B4 A4	MSKO*	5 (A38)	3	88 -1 90 -1	A4
MSTP	(A20) 17	(P48 5) 89-1 88-1	D6	(RUN LOGIC) INHIBIT	24 13	1, 10 10	88-1	В7 С2
MTG0	17	υ	00-1	D0	DCHI MTG0*	14 16	13 13	**	C2 D6
					MTG	17	2, 15,		
					READ1*	19	14	**	D6 D2
MTG0* MTG1	16 17	12 7	88 -1 88 -1	D6 D6	MB CLR* MTG(SH)(Logic) RQENB*	19 36 16	4 5	11	D2 C7 C2
WITGI	11	•	00-1	Б	MTG1* READ2*	16 19	11 10	††	D6 D2
MTG1*	16	10	88-1	D6	MB CLR* DCHO	19 18	5 10	11 11	D2 B2
MTG3*	17	12	88-1	D6	MTG(SH)(Logic MTG(DS) STROBE	36 17 18	$5 \\ 4 \\ 1, 2,$	**	D6 D6
					READ1*	19	4 2	11	D2 D2
MULT0*	120	10	88 -4	CD 5	READ2* MBO(DS)	19 40	9	88 -4	D2 CD34
MULT1* MULT2* MULT3*	120 120 120	11 13 14	†† ††	-11 11 11	MBO(DS) MBO(DS) MBO(DS)	39 37 38	4 4 4	'' ''	11
OVFLO	15	8	88-1	B2		(B39)		90-1	
PACK	103	9	88 -3	D5	ACS1 SEL* ACS2 SEL*	49 49	10 12	11	C5 B5
PACK*	83	12	88-3	D5	PACK* ACS1 SEL* ACS2 SEL* LOAD AC*	83 49 49 111	13 4 2 5	88-3 88-2 " 88-3	D5 C5 B5 D3
*Indicates ''Not''					LOAD AC	111		00 0	20

SIGNAL LIST
Table 1 - Nova 1210/1220

0	RIGIN				DESTINATION				
SIGNAL	СНІР	PIN	DWG	GRID		Т	1	DWG	GRID
[PC0] [PC1]	119 119	10 9	88-4	A5 A5	MULTO* MULT1*	120 120	10		CD 5
PC2	119	7	,,	A5	MULT2*	120	11 13		CD 5
PC3	119	6	**	A5	MULT3*	120	13 14	**	CD 5 CD 5
PC ENAB*	61	8	88-3	B3	PC IN*	36	1	88-2	D5
	1				LOAD PC*	57	5		B3
	l				E SET	74	2	88-2	C7
PC IN*	36	3	88-2	D4	PC	119	11	88-4	A5
	Ĭ				Multiplexer	120	7, 8	00-1	۸۷
	l					120	9	88-4	C5
	ł				MULT(ENAB)	120	7,8,	00 1	~ ~
					,,		9	88-4	C5
PI	95	11	88-2	D6	PC IN*	35	4	88-2	D5
,		l j			ADD ONE*	90	3	**	D4
İ					CLR SKIP*	100	5	88-3	A4
					Disable D Mult	46	2,3	88-2	В3
PI*	95	12	88-2	D6	IR(SH)	114	2	88-2	A8
					IR(DS)	12	13	**	A8
					D SET	74	11	**	C7
					ADD ONE*	82	13	**	D3
		ŀ			ION*	84	1	11	C7
					LOOP SET*	84	12	88-3	D6
PI SET	96	6	88 -2	C6	PΙ	95	14	**	
			ı		FETCH	96	9	**	D6
77.0	(,			LOAD MBO*	98	2	88-3	A3
PL*	(A19)	(P23)	89-1	B2	KEYM· PL	41	9	88 - 1	C6
		Į			(RUN Logic)	43	3	"	В7
DD FIGURE	20				Disable D Mult	87	9	88-2	В4
PRESET*	22	10	88-1	B7	MTG(MR)	17	1	88 -1	D7
		-	ł		INPUT	66	1	**	B5
	1		1		PTG(MR)	69	1	**	D5
	į		•	Į	SKIP	78	1	88-3	В5
PTG0	69	g	88-1	- D.4	(Major States)	95	1	88-2	D7
FIGU	69	9	00-1	D4	PTG DCDR	68.	2	88-1	D3
1	1		1	l		68	14	''	D3
]			l		PTG PC	69	14	"	D4
	I		1	ı	PC PC	119	4	88-4	A5
*Indicates ''Not''					PC	119	13	· · · · · · · · · · · · · · · · · · ·	A5

SIGNAL LIST
Table 1 - Nova 1210/1220

QI.	RIGIN				DES	TINAT	ΓΙΟΝ		
SIGNAL	СНІР	PIN	DWG	GRID	FUNCTION	СНІР	PIN	DWG	GRID
PTG1	69	11	88 -1	D4	MB LOAD EFA·PTG1 PTG DCDR	112 34 68 68	13 4 3 13	88-1 88-2 88-1	C3 A3 D3 D3
			:		End Cycle F/F PC PC	113 119 119	3 5 14	88-4	D5 D5 A5 A5 C3
PTG1*	69	12	88-1	D4	MB LOAD SO PTG	112 47 69	10 2 15	88-1 88-2 88-1	C3 C3 D4
PTG2*	68	10	88-1	D4	ADDER Test TS0/TS3 PTG2 PTG2·LOOP	57 65 67	13 10 9 5	88-3 88-1	A6 C5 D3 D5
PTG2 PTG5	67 70	8 8	88-1 88-1	D3 D4	INPUT F/F Key/Run/DCH/	70 66	12	**	В5
					(LD) (LD) TS0/TS F/F Adder Test	23 42 66 78 79	10 10 2 12 4	88-1 '' 88-3	C6 C8 C5 A5 A5
					Major States (LD) LOAD MBO*	95 98	10 3	88-2 88-3	D7 A3
PTG5 ENAB*	68	6	88-1	D3	LOAD MBO* INH TRANS* PTG5 Pack Logic SKIP F/F	98 56 70 70 79	4 1 9 12 12	88-3 88-1 '' 88-3	A3 B2 D5 C6 B5
PTG=0∙TS0	113	9	88-1	A5	LOAD ACB Adder Test MA LOAD* ADD ONE*	100 58 60 88	12 12 13 12 9	88-1 88-2	C3 A6 D2 D3
PTG=0·TS0*	113	8	88-1	A5	Shifter Logic ADD ONE* Shifter Logic SHIFT ACB	90 88 90 93	9 4 13 10	88-4 88-2 88-4 88-3	A7 D3 A7 C4
*Indicates ''Not''									

SIGNAL LIST

Table 1 - Nova 1210/1220

QI.	RIGIN				DES	TINA	ΓΙΟΝ		
SIGNAL	СНІР	PIN	DWG	GRID	FUNCTION	СНІР	PIN	DWG	GRID
PTG= 0 · TS3*	68	4	88-1	D3	PTG=0·TS3	67	13	88-1	D3
			00.1		ADD ONE*	88	5	88-2	D3
PTG=0·TS3	67	12	88-1	D3	INPUT F/F	9	9, 10	88-1	C5
					MTG(LD)	17	10	"	D7
	1				ADD ONE*	88	1,2	88-2	D3
PTG=1.TS0*	68	11	88-1	D3	ADDER Test	80	10	88-3	A6
					SHIFT ACB	93	11	11	C4
$PTG=1 \cdot TS3*$	68	5	88-1	D3	(IO DCDR)	109	5	88 -1	A5
PTG2·LOOP	70	6	88-1	D4	PTG2+LOOP	73	13 9	88-1 88-3	D4 B3
			ļ		LOAD MBO* LOOP SET*	98 104	3, 4		D6
PTG2+LOOP	73	12	88-1	D4	LOOP SET	34	$1^{3, 4}$	88-2	A7
P1G2+LOOP	13	12	00-1	$D^{\frac{1}{4}}$	SKIP (F/F)	79	$\overline{2}$	88-3	B5
PULSE ENAB	109	6	88 - 1	A5	OVFLO	15	12	88-1	В2
1 0202 21112					IO DCDR	62	1	"	A5
PWR FAIL*	(A5)		91-1	C2	PWR LOW	86	12	88 -3	D8
					AC CLR	20	12	88 -1	A6
PWR LOW	102	11	88-3	D7	(SKIP Logic)	11	1	88 - 3	B1
PWR LOG*	102	12	''	D7	PI SET PWR LOW	75 86	13 13	88-2 88-3	C7 D8
DEAD1*	19	3	88-1	$_{ m D2}$	PWR LOW	(B87)	13	103-1	סם י
READ1*	19	э	00-1	172	MTG(SH)	35	10	88-1	D6
					READ 1B	18	13	103-1	D6
!	18	12	103-1	D6	71	19	5, 4	103-1	D6
					READ2B	19	12	103-1	D6
READ 1B	19	6	103-1	D5	• • • • • • • • • • • • • • • • • • • •	19	10	"	
					(X ADDR DCDR)	72	2	103-3	A7
					''	76 73	$\frac{2}{2}$,,	A7
					**	77	2	,,	A7 A7
					**	79	3	٠,	A7
					",	74	3	,,	A7
					11	78	3	''	A7
	i				11	75	3	i ''	A7
*Indicates ''Not''									

SIGNAL LIST
Table 1 - Nova 1210/1220

OI	RIGIN				DES	TINA	ΓΙΟΝ	T	
SIGNAL	СНІР	PIN	DWG	GRID	FUNCTION	Υ		DWG	GRID
READ 2*	19	8	88-1	D2		(B90)		103-1	D6
					READ 2B	18	11	• • • • • • • • • • • • • • • • • • • •	D6
	18	10	103-1	D6	11	19	9	11	D6
DEAD OD	10		100 0	5.5	(X ADDD DCDD)	19	13	100 4	D6
READ 2B	19	8	103-2	D5	(Y ADDR DCDR)	54 62	2 2	103-4	A7 A7
1					11	52	2	**	A7
					**	66	2	**	A7
					**	60	3	**	A7
				l	**	50	3	**	A7
					**	57	3	**	A7
					**	47	3	* *	A7
READ IO*	12	3	88 -1	B2		(B83)		103-1	A8
					[READ IO]	18	3	"	A8
	18	4	103-1	A8	[MD0]	17	13	**	Α
					MD1	17	2	* *	Α
					MD2	15	13	**	A
					MD3	15	2	17	A
					MD4 MD5	13 13	13 2	11	A A
					MD6	11	13	**	A
					MD7	11	2	11	A
					MD8	9	13	**	A
					MD9	9	2	11	A
					MD10	7	13	**	A
	l				MD11	7	2	11	Α
					MD12	5	13	11	Α
ł					MD13	5	2	103-1	Α
					MD14	3	13	**	Α
					MD15	3	2	''	Α
[READ IO]	18	6	103-1	A8		18	5	''	A8
					[MD0]	17	10	11	A
	ł				MD1	17	4	11	A
	ł				MD2 MD3	15 15	10	,,	A
					MD3 MD4	15 13	4 10	* **	A A
	l				MD4 MD5	13	4	,,	A
*Indicates ''Not''	l				MD6	11	10	""	A
1101									

SIGNAL LIST
Table 1 - Nova 1210/1220

C	RIGIN				DESTINATION				
SIGNĀL	СНІР	PIN	DWG	GRID	FUNCTION	CHIP	PIN	DWG	GRID
RESET*	22	4	88-1	В7	MD7 MD8 MD9 MD10 MD11 MD12 MD13 MD14 MD15 PRESET* IORST KEY/RUN/DCH (MR) (MR) ION* LOOP/PACK (MR)	11 9 9 7 7 5 5 3 3 3 10 21 23 42 84	4 10 4 10 4 10 4 10 4 13 13 9	103-1 '' '' '' '' 88-1 '' '' 88-2 88-3	A A A A A A A A B7 A4 B8 C6 C8 C7
RESTART* RELOAD Disable*	(B72)		88-1	A8	KEY SEEN F/F Disable D Mult	3 87 36	5 10 10,	88-1 88-2	B8 B4
RESTART Enable RINH0 RINH1 RINH2 RINH3 RINH4 RINH5 RINH6 RINH7 RINH8 RINH9 RINH10 RINH11 *Indicates '' Not''	(A32) (A5) (A7) (A9) (A11) (A13) (A15) (A18) (A17) (A19) (A24) (A23) (A21)) 89-1 103-2 ''' ''' '''	B7 7 7 7 7 7 7 7 4 4 4			12	103-1	В8

SIGNAL LIST
Table 1 - Nova 1210/1220

OI	RIGIN				DESTINATION					
SIGNAL	CHI P	PIN	DWG	GRID	FUNCTION	T		DWG	GRID	
RINH12 RINH13 RINH14 RIN15 RQENB* RST* RUN RUN* S0 S1 S2 [S BUFFR0] [S BUFFR1] [S BUFFR2] [S BUFFR3] SELB* SELB* SELD* SELECT	(A28) (A25) (A29) (A27) 16 (A30) 23 22 91 91 115 115 (A82) (A80) 35	6 (P20 7 12 3 8 11 5 7 9 11	103-2 '' '' 88-1	4 4 4 C2 B6 C6	RESET* RUN* CPU CLK (CON IND) (A14) KEY SEEN F/F ADDER '' S1 ADDER S MULT '' '' '' SKIP Logic '' STRB A, B, C, D '' READ 1B INH GATE A, B '' (DRIVE IO)	(B41) 21 22 72 12 2 117 117 116 116 116 116 11 1 1 1 1 26 41	12 13 4, 10 1 1,2 3,6 5 4 4 2 5 14 11 10 4 1,10 12,13 1,2 2,4,5 10,13 11,2	90-1 88-1 " 89-1 88-1 88-4 " " 88-2 88-4 " " 103-1	B8 C6 A7 D2 B8 D8 D8 C3 D8 C7 C7 C7 C7 C7 C7 C7 C7 C6 B6 B6 D4 D5 D6 D3 C8	
*Indicates ''Not'										

SIGNAL LIST
Table 1 - Nova 1210/1220

	ORIGIN						DESTINATION			
SIGNAL	СНІР	PIN	DWG	GRID	1	T	, 	DWG	GRID	
SERIAL CRY SET ION* SHIFT0*	54 63 125	12 10 13	88-1 ,, 88-4	D7 B8 A 678	ADD ONE* ION*	36 36 30 15 88 82 (B94)		103-1 "' 88-1 88-2	B8 B8 B8 B2 D3 C7	
SHIFT1*	125	14	88-4	***	SKIP Logic ACD ACS SKIP Logic ACD ACS	110 123 124 (B96) 110 123 124	12 4 4 10 6 6	88-3 88-4 '' 88-3 88-4	A6 A 678 '' A6 A 678	
SHI FT2*	125	11	88-4	11	SKIP Logic ACD ACS	(B93) 110 123 124	13 10 10	88-3 88-4	A6 A 678	
SHIFT3*	125	10	88 -4	11	SKIP Logic ACD ACS	110 123 124	9 12 12	88-3 88-4	A6 A 678 ''	
SHIFT ACB	100	3	88-3	C2	ACB(SH) ACB(SH) ACB(SH) ACB(SH)	105 106 107 108	13 13 13 13	11 11 11	B4 B4 B4 B4	
SHL*	51	6	88-2	В6	Carry F/F Logic [SHL] SHIFTER(SEL)	101 101 125	5 3 16	88-3 ,, 88-4	C6 C6 A8	
[SHL] SHR*	101 51	4 5	88-3 88-2	C6 B6		81 81 101 125	2 6 5	88-3 '' 88-4	C6 C6 C6 A8	
[SHR]	101	6	88-3	C6	CRY SET*	81	1	88-3	C6	

SIGNAL LIST
Table 1 - Nova 1210/1220

OF	DESTINATION								
SIGNAL	СНІР	PIN	DWG	GRID	FUNCTION	CHIP	PIN	DWG	GRID
SKIP SKIP*	78 78	5 6	88-3	B5 B5	ADD ONE* IR0+SKIP D SET ADD ONE* Test Skip Set	90 (B69) 50 74 82 86	2 3 12 4	88-2 90-1 88-2 " 88-3	D4 B6 C7 D3 A8
SKIP INC*	42	12	88-1	C7	PC IN* MA LOAD* PC ENAB* CLR SKIP*	99	13 12 4,5 12	88 - 2 88 - 1 88 - 3	D5 D3 B4 B3
+SL0 -SL0 +SL1 -SL1 +sl2 -SL2 +SL3 -SL3 +SL4 -SL4 +SL5 -SL5 +SL6 -SL6 +SL7 -SL7 +SL8 -SL8 +SL9 -SL9 +SL10 -SL10 +SL11			103-2	777777777777444444444444444444444444444	SNS0 SNS1 SNS2 SNS3 SNS4 SNS5 SNS6 SNS7 SNS8 SNS9 SNS10 SNS11	69 69 69 65 65 59 59 59 56 49 49 46 46 46	2 3 6 7 2 3 6 7 2 3 6 7 2 3 6 7 2 3 6 7	103-2	6 6 6 6 6 6 6 6 6 6 6 6 6 6 6 3 3 3 3 3
*Indicates ''Not''									

SIGNAL LIST
Table 1 - Nova 1210/1220

ORIGIN					DESTINATION				
SIGNAL	CHI P	PIN	DWG	GRID	FUNCTION	CHIP	PIN	DWG	GRID
+ SL12			103-2	4	SNS12	40	2	103-2	3
-SL12	1	i	11	4	**	40	3	11	3
+SL13			11	4	SNS13	40	6	11	3
-SL13			"	4	**	40	7	11	3
+SL14			"	4	SNS14	38	2	11	3
-SL14			**	4	**	38	3	11	3
+SL15			11	4	SNS15	38	6	11	3
-SL15			**	4	SNS15	38	7	**	3
[S MULTO]	116	4	88-4	C 6, 7	ADDER	117	18		D,78
S MULT1	116		11	11	ADDER	117	20	11	""
S MULT2	116	12	• • •	**	**	117	22	11	11
[S MULT3]	116	9	"	11	**	117	1	11	**
SNS0	69	14	103-2	6	SNS0*	68	9	103-2	
SNS0*	68	8	, ,,	6	INHO F/F	34	10		
SNS1	69	12	"	6	SNS1*	68	5	103-2	
SNS1*	68		11	6	INH1 F/F	34	4	103-1	
SNS2	65	14	**	6	SNS2*	64	5	103-2	
SNS2*	64	6	"1	6	INH2 F/F	32	4	103-1	
SNS3	65	12	"	6	SNS3*	64	9	103-2	
SNS3*	64	8	"	6	INH3 F/F	32	10		
SNS4	59	14		6	SNS4*	58	9	103-2	
SNS4*	58	8	**	6	INH4 F/F	31	10		
SNS5	59	12	''	6	SNS5*	58	5	103-2	
SNS5*	58	6	''	6	INH5 F/F	31	4	103-1	
SNS6	56	14		6	SNS6*	55	5	103-2	
SNS6*	55	6	''	6	INH6 F/F	28	4	103-1	
SNS7	56	12		6	SNS7*	55	9	103-2	
SNS7*	55	8	''	6	INH7 F/F	28	10		
SNS8	49	14		3	SNS8*	48	9	103-2	
SNS8*	48	8	''	3	INH8 F/F	27	10		
SNS9	49	12		3	SNS9*	48	5	103-2	
SNS9*	48	6	"	3	INH9 F/F	27	4	103-1	
SNS10	46	14		3	SNS10*	45		103-2	B4
SNS10*	45	6	11	3	INH10 F/F	24	4	103-1	54
*Indicates ''Not''									

SIGNAL LIST
Table 1 - Nova 1210/1220

ORIGIN					DESTINATION				
SIGNAL	СНІР	PIN	DWG	GRID	FUNCTION	CHIP	PIN	DWG	GRID
SNS11 SNS11*	46 45	12 8	103-2	3 3 3	SNS11* INH11 F/F	45 24		103-2 103-1	C3 B3 C3
SNS12 SNS12* SNS13	40 39 40	14 8 12	11 11 11	3 3	SNS12* INH12 F/F SNS13*	39 23 39	9 10 5	103-2 103-1 103-2	B3 B3
SNS13* SNS14	39 38	6 14	11	3 3 3	INH13 F/F SNS14*	23 37	4 5	103-1 103-2	B3 B3 B2
SNS14* SNS15 SNS15*	37 38 37	6 12 8	11 11	3	INH14 F/F SNS15* INH15 F/F	21 37 21	4 9 10	103 -1 103 -2 103 -1	A3 B2
STA·E*	52	11	88-2	B5	LOAD MBO* MULT (SEL)	99 120	9 17	88-3 88-4	в3
STOP* STOP INH*	(A31) 82	(P45) 8	89-1 88-1	B5 B6	STOP SYNC DCHA SET*	4 71	4, 5 13	88 - 3 88 - 1	D8 C5
STOP SYNC	102	5	88-3	D7	SKIP INC* FETCH RUN Logic	87 97 43	2 4 1	88 -2 88-1	C8 D7 B7
STROBE	18	6	88-1	C2	STRB A, B, C,	(B20)			D5
STRB A	1	6	103-1	D4	D SNS0* SNS1*	1 68 68	5 10 4	103-1 103-2 ''	C6 C6
STRB B	1	6	103-1	D4	SNS2* SNS3* SNS4*	64 64 58	4 10 10	11	C6 C6 A6
SIRBB	1	U	103-1	D-x	SNS5* SNS6*	58 55	4 4	11	A6 A6
STRB C	1	6	103-1	D4	SNS7* SNS8* SNS9*	55 48 48	10 10 4	11 11 11	A6 C3 C3
					SNS10* SNS11*	45 45	4 10	11	C3 C3 A3
STRB D	1	6	103-1	D4	SNS12* SNS13* SNS14*	39 39 37	10 4 4	103-2 ''	A3 A3
Indicates ''Not''					SNS15	37	10	"	A3

SIGNAL LIST
Table 1 - Nova 1210/1220

Q)	DESTINATION								
SIGNAL	СНІР	PIN	DWG	GRID	FUNCTION	CHIP	PIN	DWG	GRID
[STRT*] STRT [STUTTER] STUTTER* SWP*	63 7 54 73 51	6 4 9 2 4	88 -1 '' '' '' 88 -2	A4 A4 D7 D7 B6	STRT (IO STRT PLS) STUTTER* CPU CLK LOAD ACB	7 (A52) 73 72 100	3 1 1,13 13	88-1 90-1 88-1 88-1 88-3	A4 D7 A7 C3
TS0	66	5	88-1	C5	PC IN IR(SH) INST DCDR Disable D Mult KEYM·PL·TS0* PC ENAB* FETCH·TS0* PTG DCDR S1 LOOP SET* (D+E SET)+TS3 ACD OUT* ALC* PC ENAB* PC ENAB*	114 92 53 57 61 64 68 91 34 45 50 61 61	3 5 10 1 1 9 10 1 10 13 12 4 10 1 2,4	88-2 88-3 88-2 88-1 88-2 88-3 	D5 B8 B5 B3 C4 B4 D5 D3 C3 C6 D5 B3 B8 B4 B4
TS3 SET TEST* TEST SKIP Test Skip Set WAS JSR WAS JSR* WHOA* + 5 OK *Indicates ''Not''	65 (A92) 102 86 103 48 (B6) (A8)	8 7 3 5 8	88-1 90-1 88-3 " 88-3 88-2 90-1 91-1	C5 D7 D7 D5 C5 B2	IO DCDR Logic PTG DCDR ACTG(LD) Defer Again (F/F PTG=0·TS0 '' CARRY F/F SKIP F/F Logic RUN LOGIC STOP INH* TEST SKIP ACS1 SEL* SHIFTER Logic CPU CLK RESET*	68 75) 76 112 76 59 41 82 102	2 15 9 3 13 3 13 9 2 10 12 5,9	88-1 88-2 88-1 88-3 88-1 88-2 88-4 90-1 88-1 	A5 D3 D8 D7 A6 C5 B6 B6 D7 C5 A8

SIGNAL LIST
Table 1 - Nova 1210/1220

OI OI	ORIGIN						DESTINATION			
SIGNAL	СНІР	PIN	DWG	GRID	FUNCTION	CHIP	PIN	DWG	GRID	
WRITE MEM	41	6	103 -1	D2	X DRIVERS Y DRIVERS	72 76 73 77 79 74 78 75 54 62 52 66 60 50	3 3 3 3 2 2 2 2 3 3 3 3 2 2 2	103 -3 '' '' '' '' '' 103 -4 '' '' '' '' '' '' '' '' '' '' ''	A7 A7 A7 A7 A7 A7 A7 A7 A7 A7 A7	
xrs			103-3 103-3	B2	X DRIVERS " X DRIVERS " " "	72 76 73 77 75 78 74 79	11 11 11 11 11 11 11	103-3	B7 B7 B7 B7 B3 B3 B3 B3	
YRS			103-4	B2	Y DRIVERS " " " "	54 62 52 66	11 11 11 11	103-4	B7 B7 B7 B7	
YWS			103-4	B2	Y DRIVERS	47 57 50 60	11 11 11 11	17	B3 B3 B3	

This Page Left Blank
Intentionally

ABBREVIATIONS

CENTRAL PROCESSOR AND MEMORY

NOVA 1210/1220

		·	
ABC0 thru ACB15	Accumulator Buffer Register Outputs	DATIA	Data In A (I/O instruction)
ACD	0 thru 15 Destination Accumulator	DATIB	Data In B (I/O instruction)
ACD OUT	Destination Accumulator Out	DATIC	Data In C (I/O instruction)
ACDP	Accumulator Deposit	DATOA	Data Out A (I/O in- struction)
ACD 3 SEL	Destination Accumu- lator Select enable line	DATOB	Data Out B (I/O in-
ACD 4 SEL	Destination Accumu- lator Select enable line	DATOC	struction) Data Out C (I/O in-
AC EX	Accumulator Examine		struction)
ACS	Source Accumulator	DATA0 thru DATA15	I/O Data bus signals, 16 bits wide
ACS 1 SEL	Source Accumulator Select enable line	D BUFFER	Destination (Accumulator) Buffer
ACS 2 SEL	Source Accumulator Select enable line	INTA	Interrupt Acknowledge
ACTG0, ACTG1	Accumulator Timing Generator outputs 0 & 1	INTP IN	Interrupt Priority In (to Device)
ALC	Arithmetic Logic Class (instruction)	INTP OUT	Interrupt Priority Out (from Device)
AND ENAB	AND (instruction) Enable	INTR	Interrupt (Bus Signal from Device)
CLK	Clock	IO (F+D)	IO (instruction) (Fetch or Defer state)
CLR	Clear	IO or I/O	Input/Output
CLR ION	Clear Interrupt On	ION	Interrupt On
CON DATA	Console Data	IO PLS	Input/Output Pulse
CON INST	Console Instruction	IORST	Input/Output Reset
CON RQ	Console Request	IO SKIP	Input/Output Skip
CONT	Continue switch at Console		(instruction)
CPU	Central Processor Unit	IR0 thru IR7	Instruction Register outputs 0 thru 7
CPU CLK	Central Processor Unit Clock	ISTP	Instruction Step (Console switch)
CPU INST	Central Processor Unit Instruction	ISZ	Increment and Skip if Zero(instruction)
CRY ENAB	Carry Enable	JMP	Jump (instruction)
CRY OUT	Carry Out	JSR	Jump to Subroutine
CRY SET	Carry Set		(instruction)

ABBREVIATIONS (Continued)

KEYM	Key Memory (access	STRB A	Strobe A (Memory Stack)			
KE IW	cycle)	STRB B	Strobe B (Memory Stack)			
LOAD AC	Load Accumulator	STRB C	Strobe C (Memory Stack)			
LOAD ACB	Load Accumulator Buf- fer (Shifter)	STRB D	Strobe D (Memory Stack)			
TOAD ID	Load Instruction Regis-	STRT	Start (Console switch)			
LOAD IR	ter	SWP	Swap (bytes)			
LOAD MBO	Load Memory Bus Out-	TS0 thru TS3	Time State 0 thru 3			
	puts (CPU Interface Register)	TT	Teletype			
LOAD PC	Load Program Counter	TTI	Teletype In (Teletype Keyboard/Reader Buf-			
MA1 thru MA15	Memory Address Reg-		fer)			
	ister outputs 1 thru 15	TTO	Teletype Out (Teletype			
MA LOAD	Load Memory Address Register		Teleprinter/Punch (Buffer)			
MB CLEAR	Memory Buffer Clear	XRS	X (plane) Read Source (Memory Stack)			
MBC8 thru MBC15	Memory Buffer Com- puter outputs 8 thru 15	xws	X (plane) Write Source (Memory Stack)			
MB LOAD	Load Memory Buffer Register	YRS	Y (plane) Read Source (Memory Stack)			
MBO0 thru MBO15	Memory Bus Outputs (CPU Interface Regis- ter) 0 thru 15	YWS	Y (plane) Write Source (Memory Stack)			
MD SEL1	Multiply Divide Select 1	32 VNR	+ 32 Volts, Not			
MD1-MD15	Memory Data 1 thru 15	*******	Regulated			
SET ION	Set Interrupt On	+ VINH	+ (Memory) Inhibit Voltage			
SHIFT ACB	Shift Accumulator Buf- fer	+ V _{Lamp}	+ Lamp Voltage (Con- sole indicators)			
SHL	Shift Left	+ VMEM	+ Voltage Memory			
SHR	Shift Right	+ 5 OK	+ 5 Volt (power)			
SKIP INC	Skip Increment	ll V	operating properly			
SL0 thru SL15	Sense Lines (Memory Stack) 0 thru 15					
SMULT	Source Multiplexer					
SNS0 thru SNS15	Sense Amplifier Out- puts 0 thru 15					
S0 thru S2	(Adder function) Select Control Bits 0 thru 2					
STOP INH	(Processor) STOP INHIBIT					