

# Yifei Zhang

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## EDUCATION

<b>PhD Student at Carnegie Mellon University</b> <i>Machine Learning Department</i>	Sep 2025 - Est. May 2031
<b>Visiting Undergraduate Researcher at UC Berkeley</b>	Feb 2024 - Sep 2025
<b>University of Chinese Academy of Sciences (UCAS)</b> <i>Bachelor of Artificial Intelligence</i>	Sep 2021 - June 2025 Current GPA: 3.99/4.0 Ranking: 1/70

## RESEARCH INTEREST

I'm interested in building learning systems that are reliable in the real world—systems that can continuously learn from experience and adapt as the world changes. At a high level, my work is driven by a central question: *can we enable models to learn effectively from ongoing experience in a way that resembles how humans learn?*

## SELECTED PUBLICATIONS

- Qianqian Wang\*, **Yifei Zhang\***, Aleksander Holynski, Alexei A Efros, and Angjoo Kanazawa, “Continuous 3D Perception Model with Persistent State,” in *IEEE Computer Vision and Pattern Recognition (CVPR)*, 2025, **Oral**.
- Yixiao Wang\*, **Yifei Zhang\***, Mingxiao Huo\*, Ran Tian, Xiang Zhang, Yichen Xie, Chenfeng Xu, Pengliang Ji, Wei Zhan, Mingyu Ding, and Masayoshi Tomizuka, “Sparse Diffusion Policy: A Sparse, Reusable, and Flexible Policy for Robot Learning,” in *Conference on Robot Learning (CoRL)*, 2024.
- **Yifei Zhang**, Huan-ang Gao, Zhou Jiang, and Hao Zhao, “Dual-frame Fluid Motion Estimation with Test-time Optimization and Zero-divergence Loss,” in *Conference on Neural Information Processing Systems (NeurIPS)*, 2024.
- **Yifei Zhang**, Hao Zhao, Hongyang Li, and Siheng Chen, “FastMAC: Stochastic Spectral Sampling of Correspondence Graph,” in *IEEE Computer Vision and Pattern Recognition (CVPR)*, 2024.

## RESEARCH EXPERIENCES

<b>3D Perception Model</b>   <i>Instructed by Angjoo Kanazawa, Alexei A. Efros, UC Berkeley</i>	Aug. 2024 – Jan. 2025
<ul style="list-style-type: none"> <li>• Field: 3D Vision</li> <li>• Co-first author, <b>CVPR 2025 Oral</b>.</li> <li>• <b>Co-leading</b> the development process, including large-scale model training, and extensive experiments.</li> <li>• Developed a unified model for diverse 3D tasks, including 3D/4D reconstruction and novel geometry synthesis.</li> </ul>	
<b>Sparse Diffusion Policy</b>   <i>Instructed by Masayoshi Tomizuka, UC Berkeley</i>	Feb. 2024 – June. 2024
<ul style="list-style-type: none"> <li>• Field: Robotic Learning</li> <li>• <b>Co-First Authored</b> and achieved acceptance by <b>CoRL 2024</b>.</li> <li>• Expanding diffusion-policy to robot multi-task learning and continual learning.</li> <li>• <b>Co-led</b> task integration and exploration of continual learning capabilities within the framework.</li> </ul>	
<b>FastMAC</b>   <i>Instructed by Hao Zhao, Institute for AI Industry Research, Tsinghua University</i>	May. 2023 – Nov. 2023
<ul style="list-style-type: none"> <li>• Field: 3D Point Cloud Understanding</li> <li>• <b>First-Authored</b> and achieved acceptance by <b>CVPR 2024</b>.</li> <li>• Innovated the <i>FastMAC</i> algorithm, achieving real-time processing speeds with minimal performance degradation.</li> <li>• Spearheaded the research from conception to publication, leading a team of 4 in experiment design and managing the writing process, resulting in the paper's high praise and acceptance.</li> </ul>	
<b>DECROB</b>   <i>Instructed by Hao Zhao, Institute for AI Industry Research, Tsinghua University</i>	May. 2023 – Oct. 2023
<ul style="list-style-type: none"> <li>• Field: AI4Science, Physics, Point Tracking</li> <li>• Led the project as the <b>first-author</b> on a novel self-supervised framework for 3D Particle Tracking Velocimetry, currently <b>accepted by NeurIPS 2024</b>.</li> <li>• As the <b>first author</b>, led through the research progress, from initial concept to preprint submission, achieving groundbreaking results and recognition.</li> </ul>	

## HONORS AND AWARDS

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SenseTime Scholarship ( <b>25 winners nationwide</b> )	July. 2024
China National Scholarship ( <b>Top 0.01%</b> )	Dec. 2023 & Dec. 2024
First-Level Scholarship of UCAS ( <b>Top 1% in UCAS</b> )	Every Year
National First Prize in APMCM ( <b>Top 5% in China</b> )	Dec. 2022
Honorable Mention in Mathematical Contest in Modeling ( <b>Top 10% around the world</b> )	Feb. 2023
3V3 National Second Prize in RoboMaster University League	April. 2023

## OTHER PROJECTS

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<b>Industrial Showroom Setup</b>   <i>Member</i>	Fall, 2023
In charge of display systems for Tsinghua University's showroom, enabling remote control of autonomous vehicles, resulting in improvement in system efficiency through advanced <b>Unity and ROS communications</b> .	
<b>iFLYTEK 10.24 Industrial Big Model Launch Event</b>   <i>Member</i>	Fall, 2023
Led debugging and optimization of robotic arm <b>hardware drivers</b> for the iFLYTEK 10.24 launch, contributing to a successful product demonstration.	
<b>Development of Robotic Arm &amp; Intelligent Vehicle System</b>   <i>Individual Project</i>	Fall, 2023
Designed and constructed a fully functional <b>robotic arm</b> mounted on a four-wheel vehicle for a Robotics Seminar course project, demonstrating innovative engineering solutions and automation capabilities.	
<b>Cognitive Behavioural Prediction</b>   <i>Leader</i>	Fall, 2023
Led a Cognitive Neuroscience course project focusing on <b>cognitive behavioral prediction</b> , developing multi-modal fusion algorithms that predict IQ patterns, detailed documentation available on Github.	
<b>Autonomous Driving</b>   <i>Member</i>	Summer, 2023
Constructed an autonomous robot capable of complex environment navigation for a summer project at Tsinghua University. Led the development and implementation of sophisticated <b>mapping and navigation</b> algorithms.	

## VOLUNTEER ACTIVITIES

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<b>Volunteer Academic Q&amp;A Counseling</b>   <i>Member</i>	2022 – 2023
Served as an Academic Peer Mentor, offering vital academic counseling for more than 1.5 years, significantly improving the younger students' understanding of complex subjects.	
<b>Covid-19 Hospital Volunteering</b>   <i>Member</i>	July, 2022
Volunteered at a local hospital during the COVID-19 epidemic, providing essential guidance and support to over 200 patients, facilitating efficient healthcare delivery and enhancing patient satisfaction during critical times.	

## SKILLS AND SELF-EVALUATION

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<b>Proficient in English</b> , evidenced by a TOEFL score of 106(R28, L30, S23, W25) tested on Sep 21, 2024.
<b>Expert in programming</b> with extensive experience in CUDA, C/C++, and Python.
<b>Abundant Experience in Deep Learning</b> , leveraging Pytorch for innovative projects and familiar with development tools including Git/GitHub, Ubuntu, VS Code, CLion/PyCharm.
<b>Good at Mathematics and Physics</b> .
Good Mathematic Grades: Linear Algebra(95), Advanced Algebra(96), Mathematical Analysis(96). Good Physic Grades: Mechanics(99), Thermal Physics(97), Electromagnetics(92), Optics(96), Atomic Physics(97). All courses are at the <b>most advanced</b> level.