view\_frames Result Recorded at time: 48.209 odom Broadcaster: /gazebo Average rate: 30.418 Hz Most recent transform: 48.199 (0.010 sec old) Buffer length: 2.367 sec base\_footprint Broadcaster: /tf\_broadcaster Average rate: 100.422 Hz Most recent transform: 48.207 (0.002 sec old) Buffer length: 2.370 sec base\_scan Broadcaster: /tf\_broadcaster Average rate: 100.422 Hz Most recent transform: 48.207 (0.002 sec old) Buffer length: 2.370 sec robot/laser Broadcaster: /nav\_node Average rate: 84.429 Hz Most recent transform: 48.199 (0.010 sec old) Buffer length: 2.357 sec robot/base\_footprint Broadcaster: /nav\_node Average rate: 84.394 Hz Most recent transform: 48.200 (0.009 sec old) Buffer length: 2.358 sec

map