Cost function

* Centralized pool can get a trajectory (a size N array) from navigation stack
* The centralized pool will give robot a task with lowest cost and cost is less than 1000

When we take task dependency into account:

* Centralized pool can get a trajectory (a size N array) from navigation stack

|  |  |  |
| --- | --- | --- |
| Task id | dependency | Cost |
| 1 | 0 |  |
| 2 | 1 |  |
| 3 | 2 |  |

Task execute oder 1 -> 2 -> 3