

	Requirement	C2-270 version 2.85
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## 4.12.3 AfterMarket\_Ext

### 4.12.3.1 RQEXT2\_1

Protocol name is:"AfterMarket\_extended"

### 4.12.3.2 RQEXT2\_2

The protocol broadcast via CAN1 in baud rate 500 Kbytes

The CAN message is transmitted every 100 ms.

### 4.12.3.3 CAN Message 0x669 Details - Lane

The message contains the Lane information and measurements.

	7 (MSB)	6	5	4	3	2	1	0 (LSB)
Byte 0	<a href="#">Lane type left</a>				<a href="#">Undocumented</a>	<a href="#">LDW available left</a>	<a href="#">Lane confidence left</a>	
Byte 1	<a href="#">Distance to left lane (LSB)</a>				<a href="#">Reserved</a>			
Byte 2	<a href="#">Distance to left lane (MSB)</a>							
Byte 3	<a href="#">Reserved</a>							
Byte 4								
Byte 5	<a href="#">Lane type right</a>				<a href="#">Undocumented</a>	<a href="#">LDW available right</a>	<a href="#">Lane confidence right</a>	
Byte 6	<a href="#">Distance to right lane (LSB)</a>				<a href="#">Reserved</a>			
Byte 7	<a href="#">Distance to right lane (MSB)</a>							

#### 4.12.3.4 Distance to lane (left and right)

Type: signed integer

Unit: meter

Range: -40 : 40 [m]

Conversion: (HEX)\*0.02

Invalid value: 800h

Note: The Offset (c) parameter in the equation:  $y = ax^2 + bx + c$

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#### 4.12.3.5 Lane Confidence (left right)

Confidence grade about the right lane information

Type: 2 bits, unsigned integer

Range 0 : 3

Invalid value: none

0 is the lowest confidence and 3 is the highest.

##### 4.12.3.5.1 LDW Availability

Should be on whenever the system detects lanes.at confidence  $\geq 2$

And speed is  $>55\text{km/h}$  +hysteresis, and configuration of the LDW is  $\geq 1$

#### 4.12.3.6 Lane Type

Type: int

Unit: Enum

0	Dashed
1	Solid
2	None
3	Road Edge
4	Double Lane Mark
5	Bott's Dots
6	Invalid

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