PC NO	PART NAME	QTY
27	L-bracket 20x20x14x2	2
26	M4x10 countersunk machine screw, M4 screw nut, washer	4, 4, 4
25	M4x15 machine screw, M4 screw nut	4, 4
24	M3x16 wood screw	4
23	M2x12 machine screw, M2 screw nut	4, 4
22	M3x10 machine screw, M3 screw nut, washer	3, 3, 6
21	M3x10 wood screw	12
20	M3x12 wood screw	6
19	LIDAR_TIM571	2
18	SUPPORT_FRONT	2
17	SUPPORT-6	2
16	SUPPORT_TOP	2
15	POWER_SUPPLY	1
14	PC_PLATFORM	1
13	PLATFORM-HOLES1	1
12	PLATFORM_EMPTY	1
11	STICKY_BIG	1
10	STICKY_SMALL	2
9	SIDE_R_FRONTLIDAR	2
8	FRONTLIDAR_BOTTOM	1
7	DLINK_ANDERESEITE	1
6	DLINK_HINTEN	1
5	DLINK_VORNE	1
4	DLINK_SEITE	1
3	BACKLIDAR_BOTTOM	1
2	PC_FRONTNBACK	2
1	PC_SIDE1	2

two additional parts complete the projekt: visensor_mount backring

Doublesided adhesive tapes is used to attach the parts "sticky_big", "sticky small" and "backring" on the Pepper robot

Aenderungsstand / change state			Werkstoff / material		
revision	date	name	–		
			Behandlung Werkstoff / material treatement	Mst. / scale	Format / size
			–	1:5	A3
			Oberflaechen Behandlung / surface treatement	Einheit / unit	Blatt / sheet
			–	mm	1/1
gezeichnet	02.10.2018	Kranz	Name / partname	Projekt / project	rev.
geprueft			platforms	asl_pepper	1-1
freigegeben			Zeichnungsnummer / partnumber	Dateiname / file name	
			0	platforms_dwg_1-1	