

Rules to be followed

There are two boxes entry box and exit box

The entry box should have the id of their respective room

The exit box should also have id for the same.

The box should be fully covered to the wall. we has to provide 3 points that will be converted into four points

- id: 0

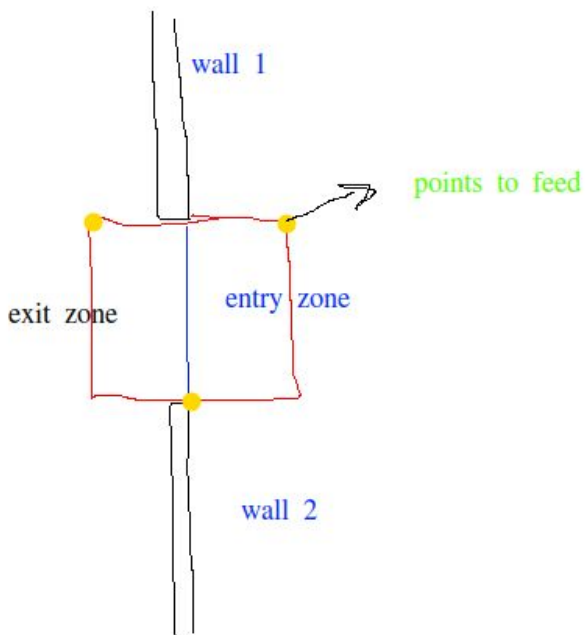
name: hall

floor: 0

pos: [ [[-4.320,-6.811],[-4.981,-7.416]], [[-4.223,1.616],[-4.851,0.584]],  
[[-4.4353,5.8762],[-4.975,4.747]], [[7.916,-0.249],[6.309,0.222]], [[3.017,-2.748],[3.605,-3.669]] ]

map\_location:

"/home/navaneeth/Documents/practice\_ws/ros\_navigation\_ws/src/diff\_wheeled\_robot\_gazebo/maps/fivemap/hall.yaml"



Path planning should have full map.