

# Open*DRIVE*

*managing the road ahead*

goes

rail*ML*.org

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*VIRES Simulationstechnologie GmbH*

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# Summary

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## OpenDRIVE®

*is designed for **driving simulation***







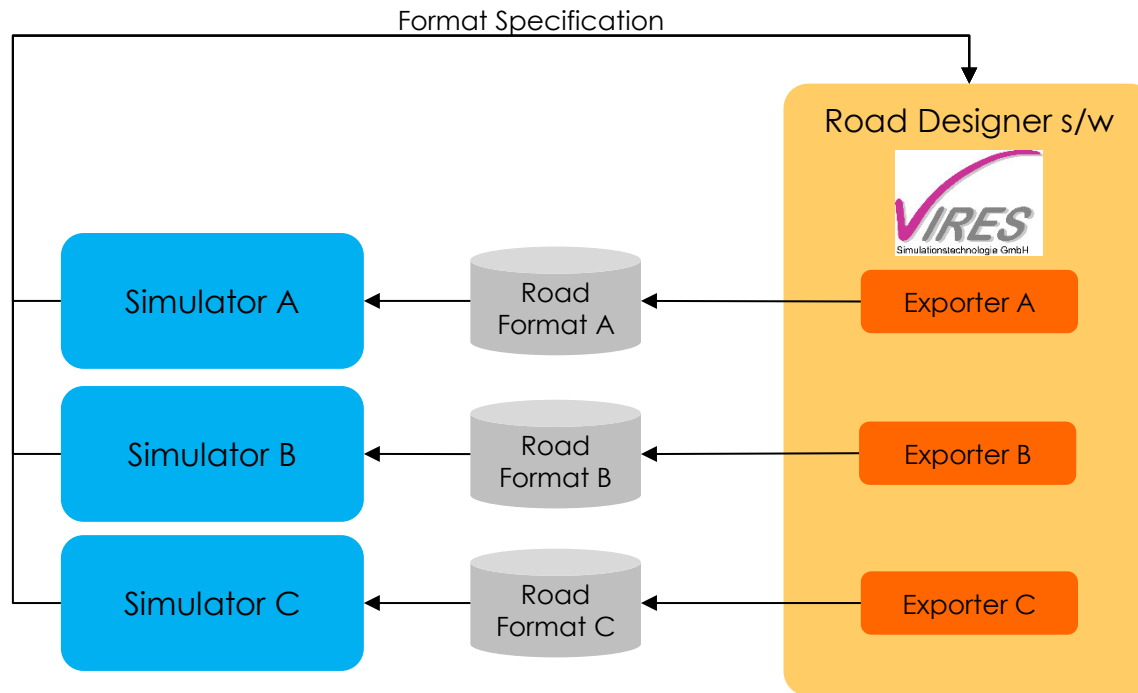




# History

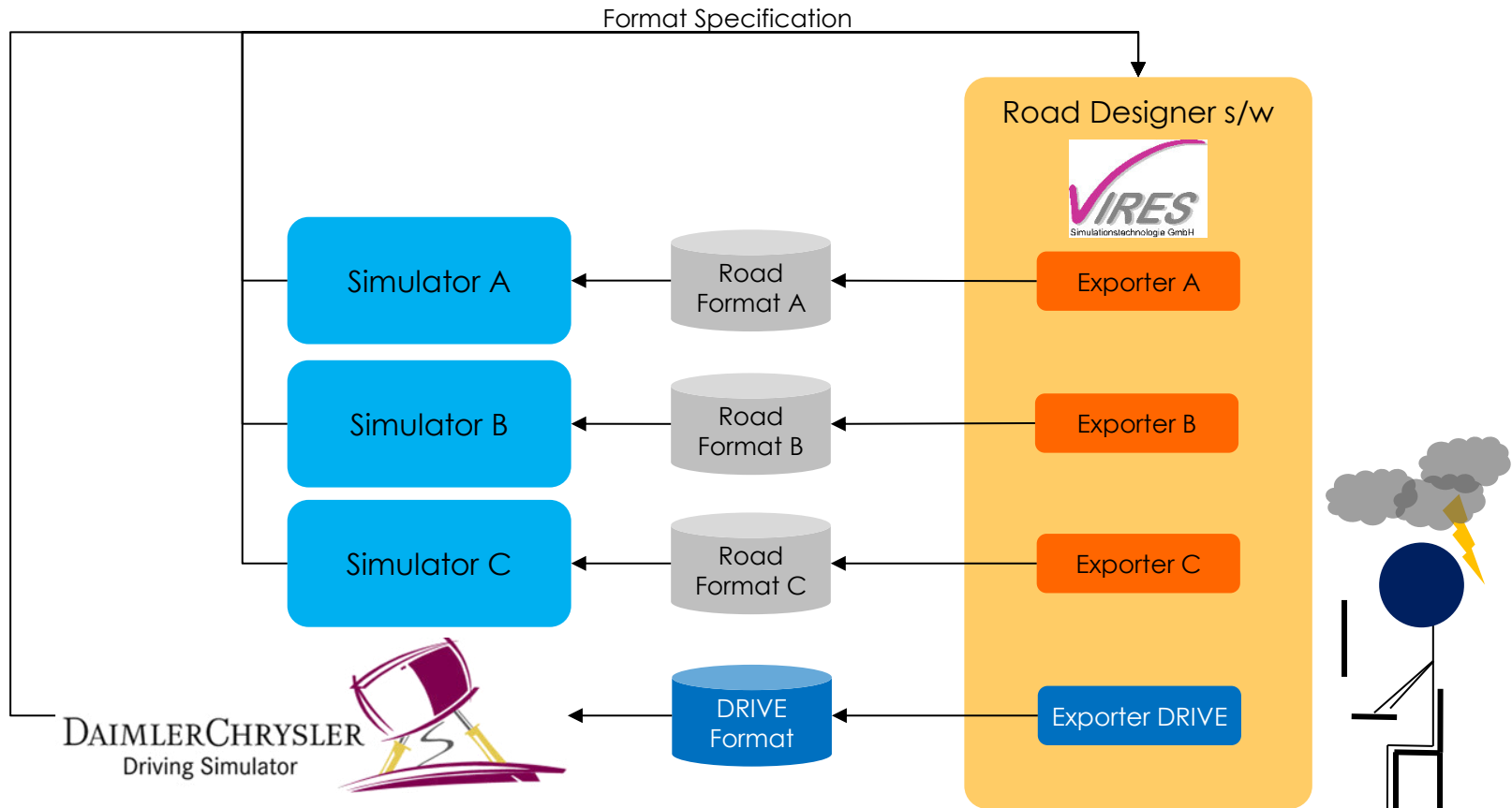


## Before 2004...

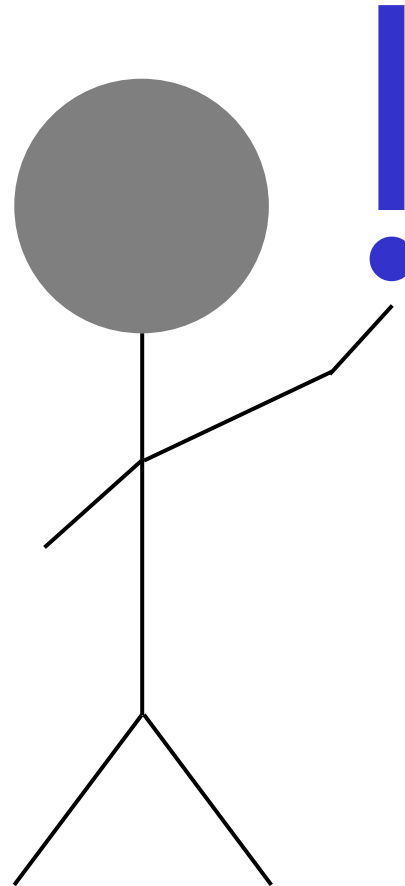


→ n ways to describe the same thing!

## Back in 2004...

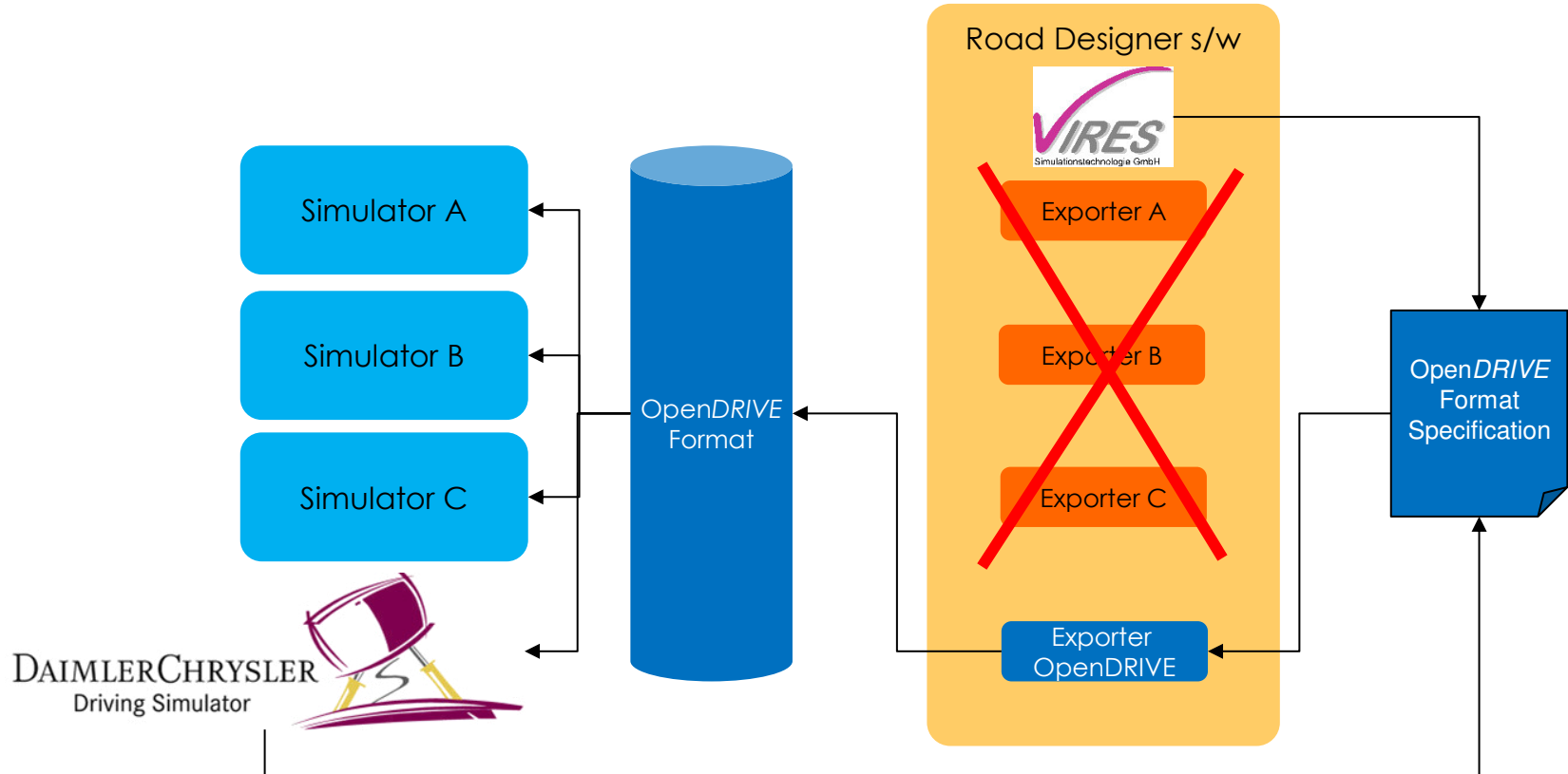


Starting 2005...





## Starting 2005...

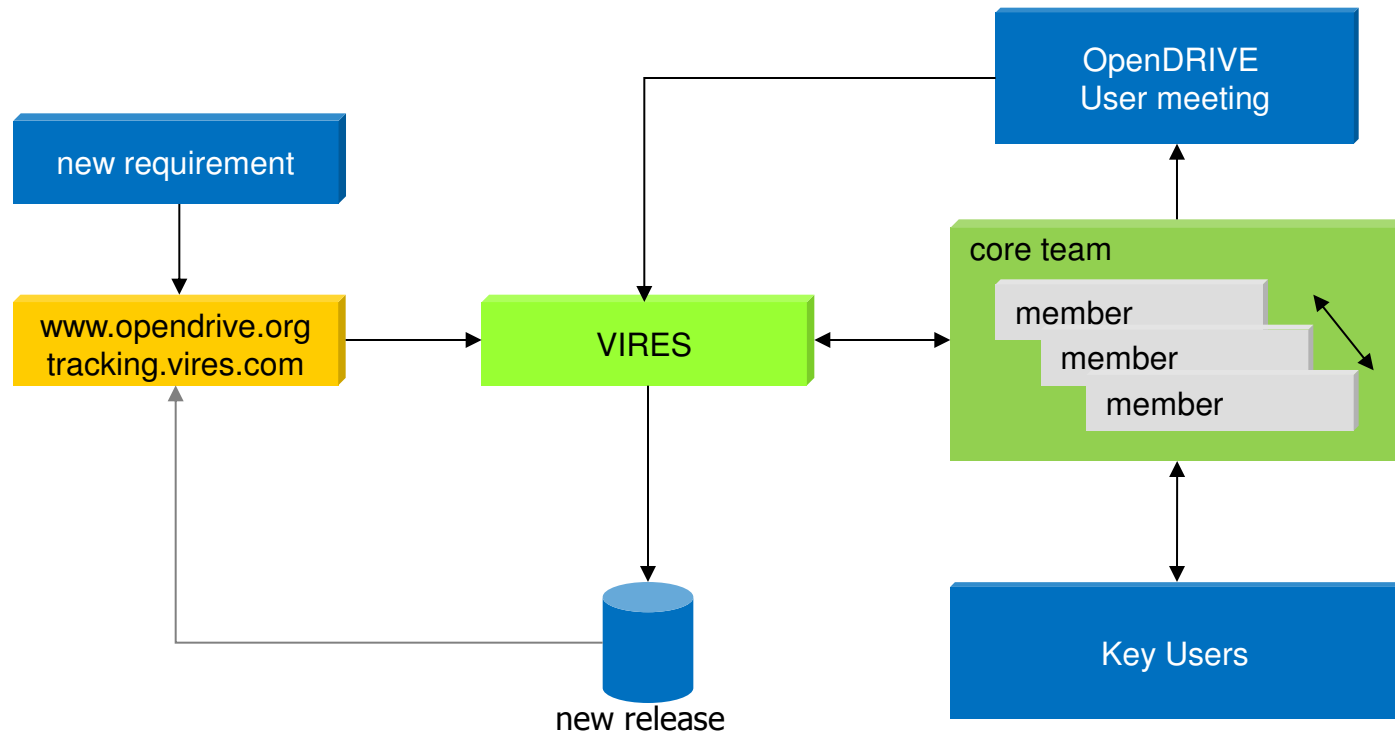


# Status

- **Website:** [www.opendrive.org](http://www.opendrive.org)
- **Newsletter:** [newsletter@opendrive.org](mailto:newsletter@opendrive.org)
- **Support:** [tracking.vires.com](http://tracking.vires.com) / [opendrive@opendrive.org](mailto:opendrive@opendrive.org)
- **Specification:** 1.4H (last stable)  
1.5 (draft)
- **Style Guide:** available on OpenDRIVE® website
- **Viewer:** available on OpenDRIVE® website
- **Validation:** OpenDRIVE® validator in ticket system
- **Core Team:**
  - **BMW:** Mohammad Bahram
  - **Daimler:** Hans Grezlikowski
  - **DLR:** Andreas Richter
  - **HERE:** Alex Goldberg
  - **KMWE:** Ekkehard Klärner
  - **Rheinmetall:** Dr. Bernhard Bock
  - **VIRE:** Marius Dupuis
  - **VTI:** Laban Källgren
  - **3D Mapping:** Philip Paulsteiner
- **Users:** uncounted (OEMs, Tier1s, tool suppliers, research institutes, universities, mapping companies...)



## Development Process



## How open is it?



- OpenDRIVE® is an open format, not a public format
- The specification of OpenDRIVE® is publicly available for free on [www.opendrive.org](http://www.opendrive.org)
- Use of the OpenDRIVE® format is free (no license fees apply) and only subject to the license agreement provided with the specification



- The trademark, website and data format are owned by VIRES Simulationstechnologie GmbH, Germany
- VIRES manages the data format, the website and the information exchange within the OpenDRIVE community

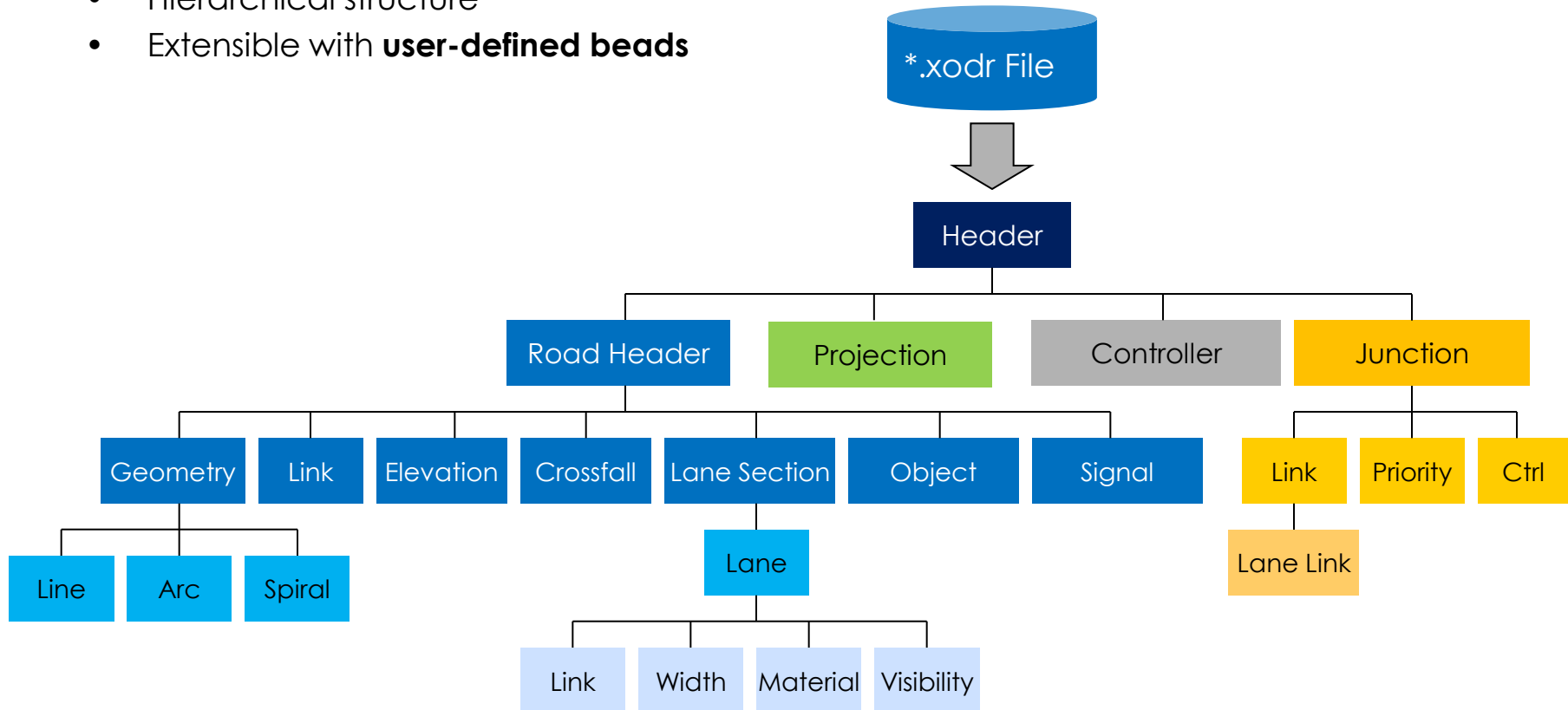
currently being  
discussed

# Technical Issues



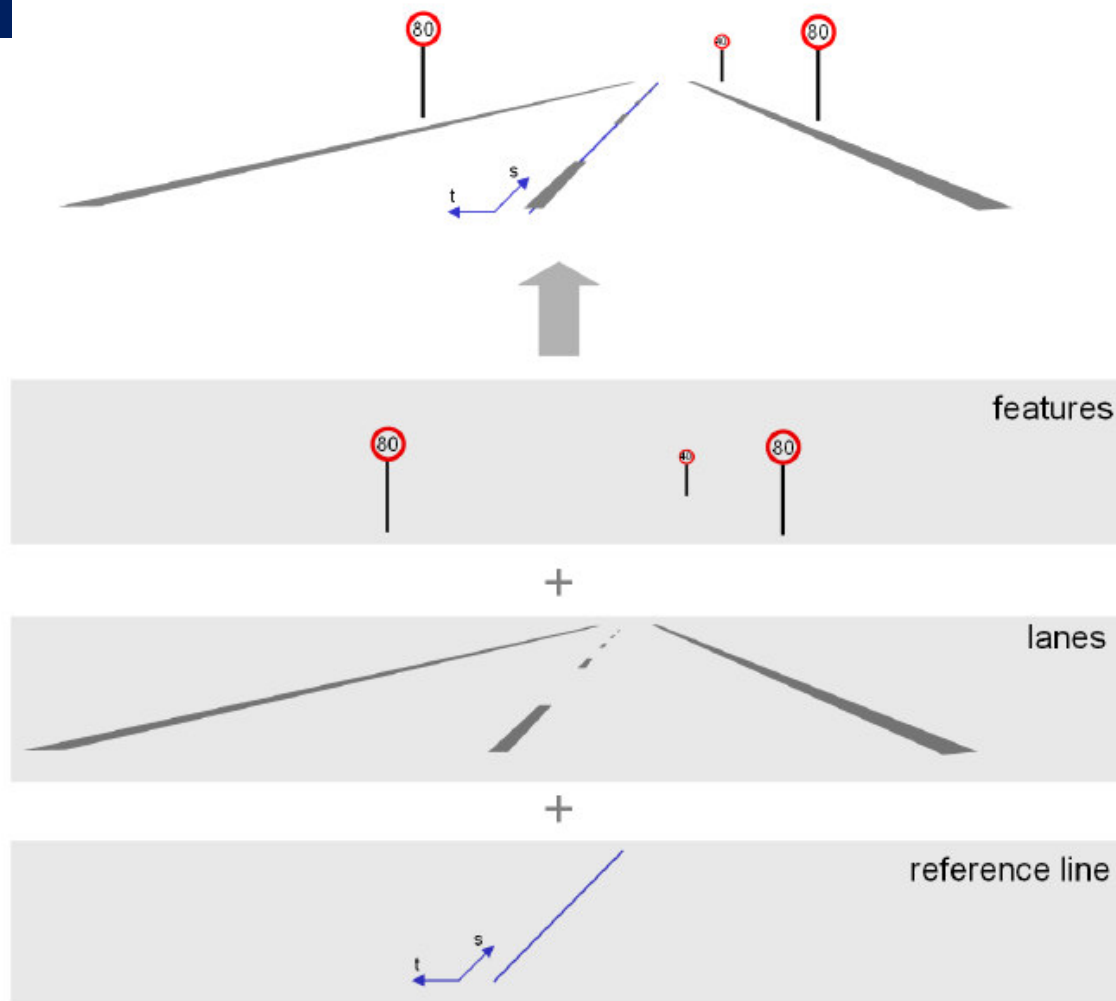
## File Format

- XML Format
- Hierarchical structure
- Extensible with **user-defined beads**



Note: the above figure is not complete and only shows a fraction of available beads

## Road Structure

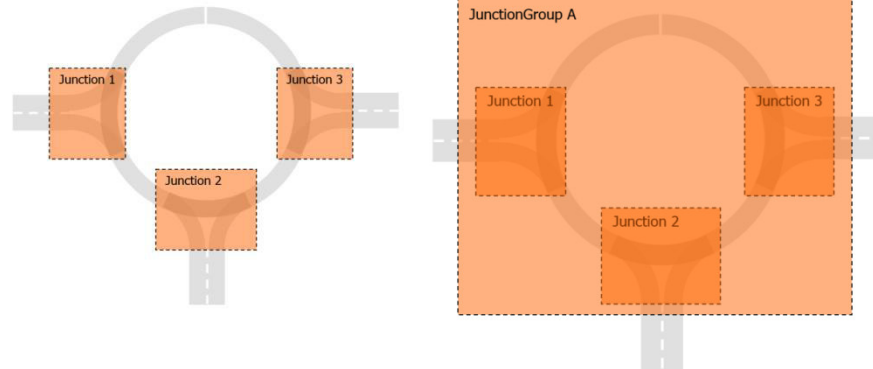


All features are described **relative** to a road's **reference line**.

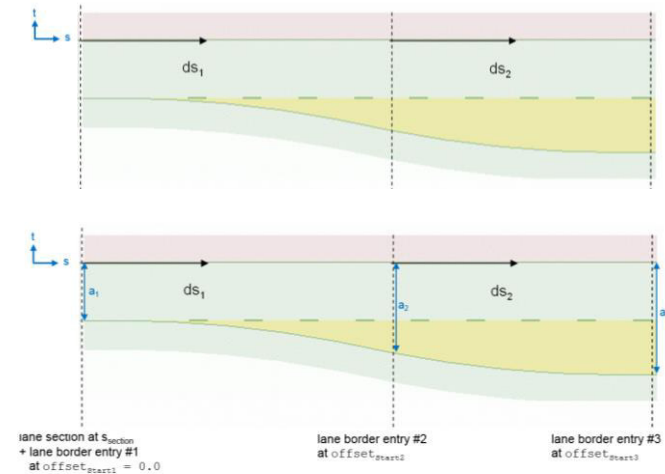
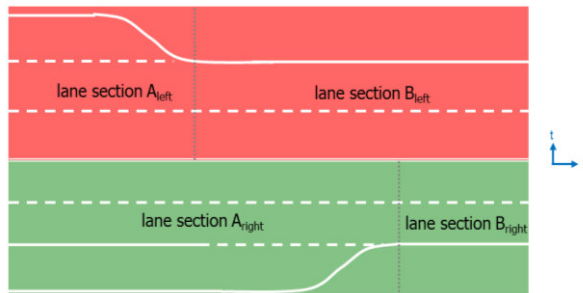
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## Flexible Concepts (Examples)



















### Road Connection



### Lanes



## Signals / Signs

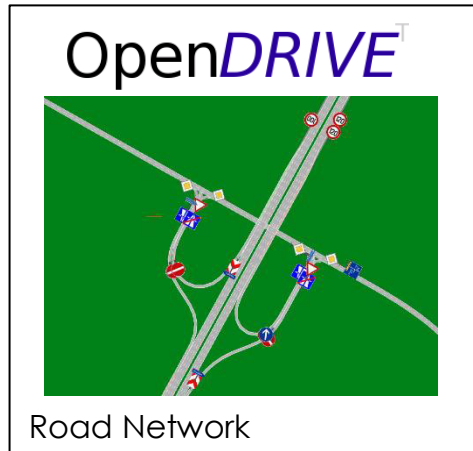
signal	type	subtype	signal	type	subtype	signal	type	subtype
	1.000.001	-		1.000.008	-		1.000.011	10
	1.000.002	-		1.000.008	10		1.000.011	20
	1.000.002	10		1.000.008	20		1.000.011	30
	1.000.007	-		1.000.009	10		1.000.011	40
	1.000.007	10		1.000.009	20		1.000.011	50
	1.000.007	20		1.000.010	10		1.000.012	10
	1.000.007	30		1.000.010	20		1.000.012	20
							1.000.013	-
							1.000.014	-



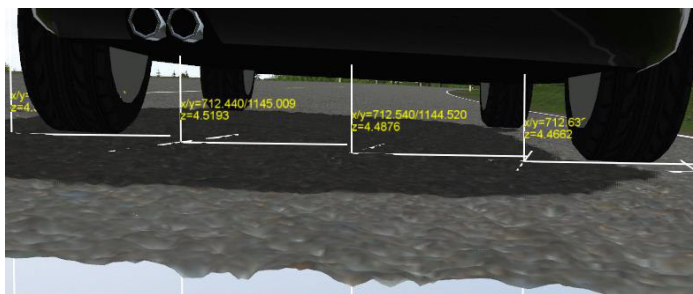
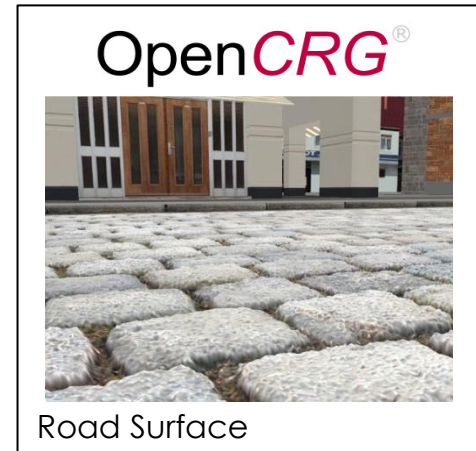


# Extended Scope

## Partnership: Road Surface



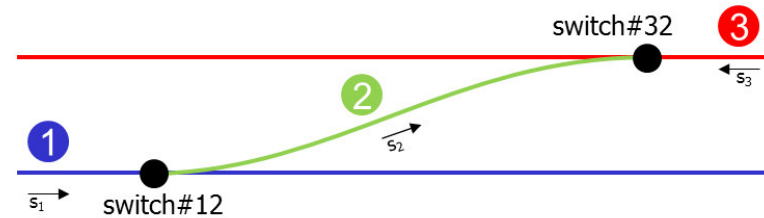
+



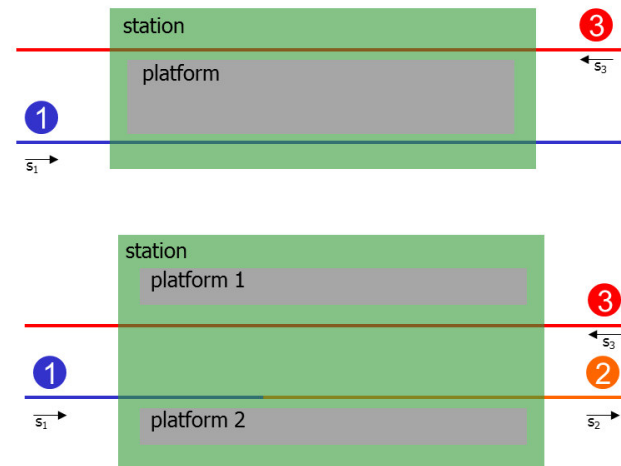
## Mixed Concepts



## Switches (vs. junctions)



## Stations



# Challenges

## Driving simulation has **changed**:

- virtual testing of ADAS etc. has become mandatory
- virtual tests have to be validated against real test rides
- localization data has to be included
- real sensor data has to be matched with virtual sensor data
- the focus is shifting from human learning to machine learning

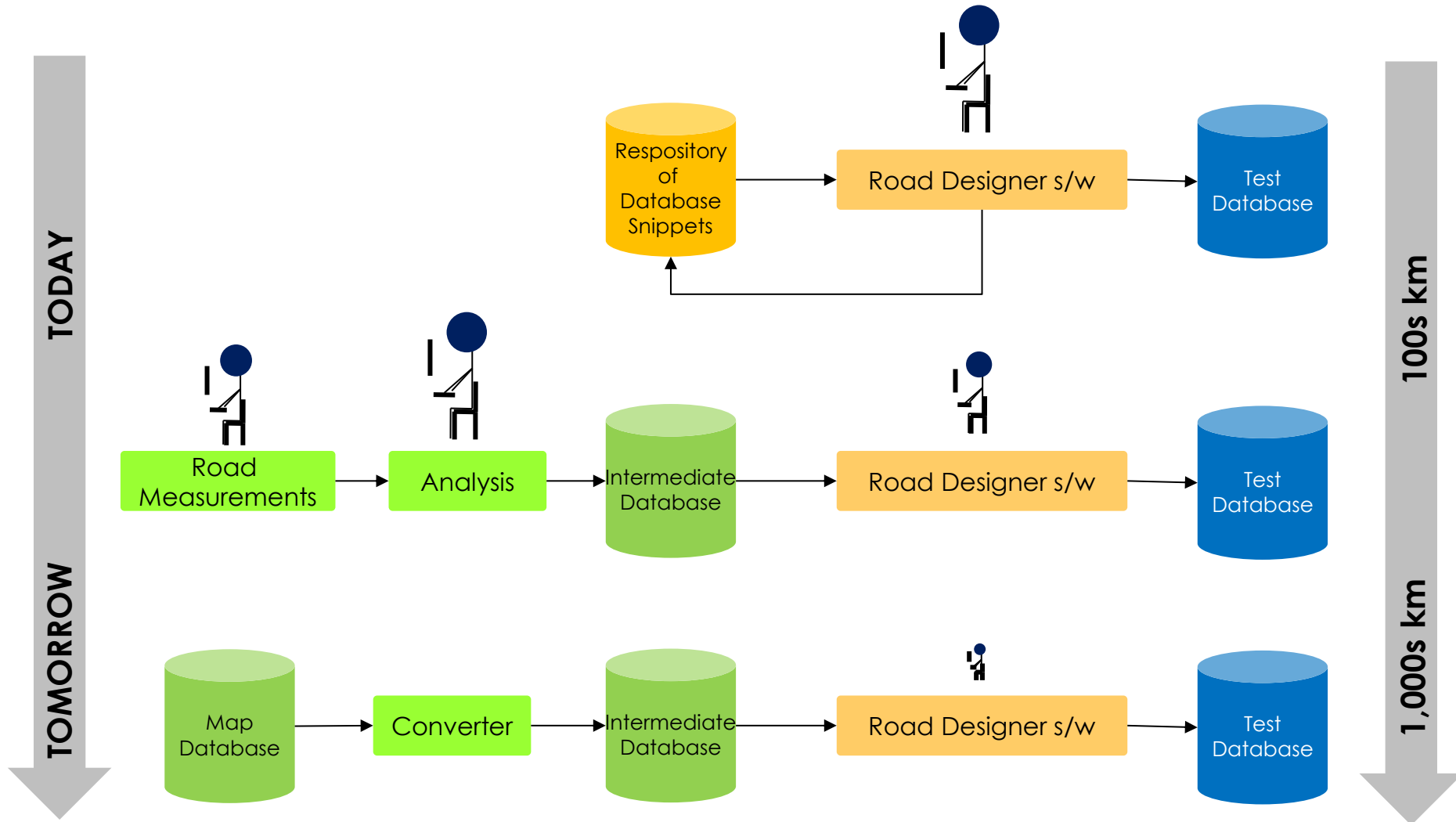
→ The need for describing **real road networks** in OpenDRIVE® has increased.





# Challenges – Data Sourcing

The **sourcing** of road network data has **changed**:



The **quality** of road network data has to **improve**

- support of localization features
- high level of details (e.g. traffic islands, traffic light and sign contours etc.)
- road surface features
- materials
- etc.

→ Sensor simulation should be able to work like the real stuff.



# Conclusion

- OpenDRIVE® is a **mature** format
  - in service since 2006
- OpenDRIVE® is a **living** format
  - recently adapted and permanently under review for new use cases
- OpenDRIVE® is an **open standard**
  - large user base
  - available for free without any strings attached
- OpenDRIVE® has to meet current and future **challenges**
  - availability of large road networks
  - highly detailed representation of the real world
  - processes and tools for sourcing from other available data

*That's it!*

*Thanks for your attention!*

**Questions?**

Join the team...

Open*DRIVE*<sup>T</sup>

Open*CRG*<sup>®</sup>

Open*SCENARIO*

