

# Křivky

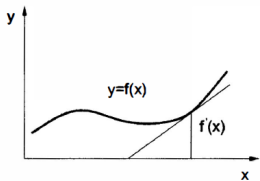
## Křivky

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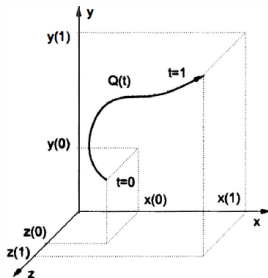
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**Explicitní**  $y = f(x)$

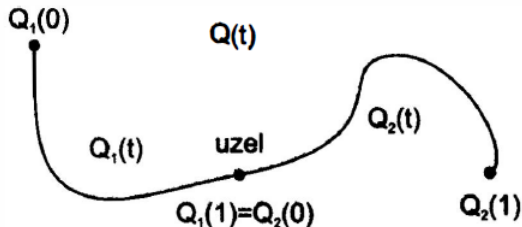


**Implicitní**  $f(x, y) = 0$

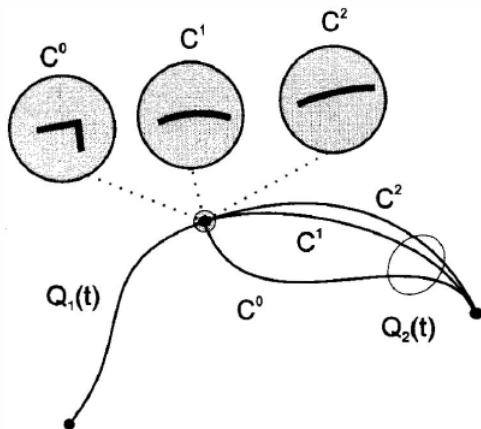
**Parametrické**  $x = x(t)$ ,  $y = y(t)$ ,  $z = z(t)$



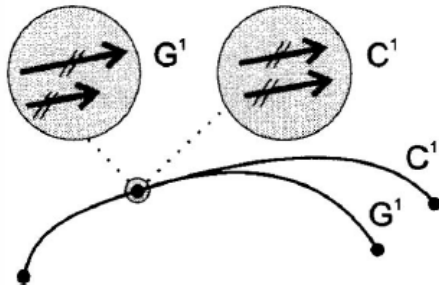
- **Bodová rovnice**  $Q(t) = [x(t), y(t), z(t)]$
- **Vektorová rovnice**  $\vec{q}(t) = [x(t), y(t), z(t)]$
- **Polohový vektor**  $\vec{q}(t) = Q(t) - [0, 0, 0]$
- **Tečný vektor**  $\vec{q}'(t_0) = (x'(t_0), y'(t_0), z'(t_0))$
- **Rovnice tečny**  $P(u) = Q(t_0) + u\vec{q}'(t_0) = (x'(t_0), y'(t_0), z'(t_0))$
- části křivky – segmenty



stupně  $n - C^n$



stupně  $n - G^n$



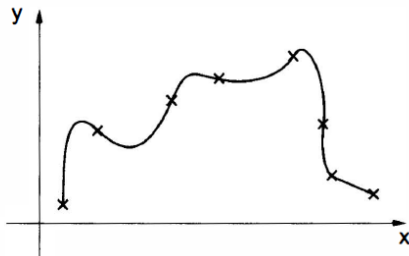
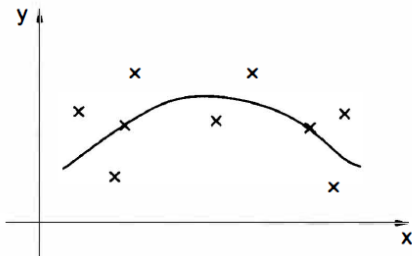
## polynomiální křivky:

$$Q_n(t) = a_0 + a_1t + a_2t^2 + \dots + a_nt^n$$

## Kubiky

řídící body

- aproximace
- interpolace



## parametricky:

$$x(t) = a_x t^3 + b_x t^2 + c_x t + d_x$$

$$y(t) = a_y t^3 + b_y t^2 + c_y t + d_y$$

$$z(t) = a_z t^3 + b_z t^2 + c_z t + d_z$$

## maticově:

$$Q(t) = TC = \begin{bmatrix} t^3 & t^2 & t & 1 \end{bmatrix} \begin{bmatrix} a_x & a_y & a_z \\ b_x & b_y & b_z \\ c_x & c_y & c_z \\ d_x & d_y & d_z \end{bmatrix}$$

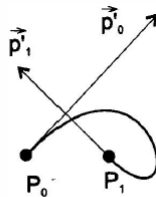
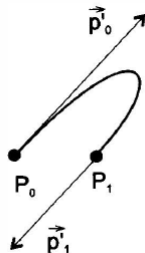
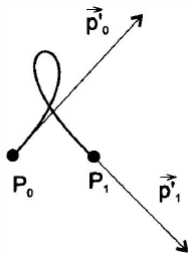
## s geometrickými podmínkami

$$Q(t) = TCG = \begin{bmatrix} t^3 & t^2 & t & 1 \end{bmatrix} \begin{bmatrix} m_{11} & m_{12} & m_{13} & m_{14} \\ m_{21} & m_{22} & m_{23} & m_{24} \\ m_{31} & m_{32} & m_{33} & m_{34} \\ m_{41} & m_{42} & m_{43} & m_{44} \end{bmatrix} \begin{bmatrix} G_1 \\ G_2 \\ G_3 \\ G_4 \end{bmatrix}$$



- Hermitovské kubiky





$$Q(t) = TCG = \begin{bmatrix} t^3 & t^2 & t & 1 \end{bmatrix} \begin{bmatrix} 2 & -2 & 1 & 1 \\ -3 & 3 & -2 & 1 \\ 0 & 0 & 1 & 0 \\ 1 & 0 & 0 & 0 \end{bmatrix} \begin{bmatrix} P_0 \\ P_1 \\ \vec{p}_0 \\ \vec{p}_1 \end{bmatrix}$$



- Beziérový kubiky
- Coonsovy kubiky
- Spline křivky

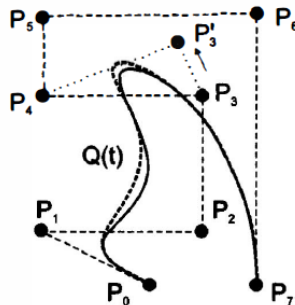
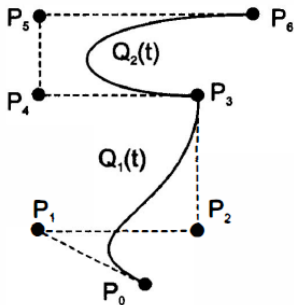
$$Q(t) = \sum_{i=1}^n P_i B_i^n(t)$$

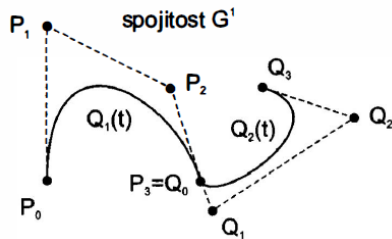
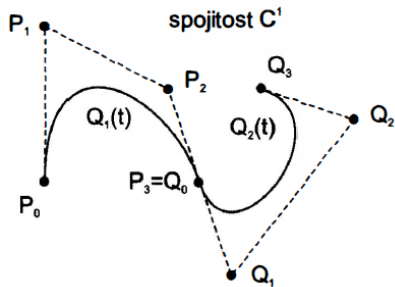
**Bernsteinovy polynomy n-tého stupně** –  $B_i^n$

$$B_i^n(t) = \binom{n}{i} t^i (1 - t)^{n-i}$$

$$t \in \langle 0, 1 \rangle$$

$$i = 0, \dots, n$$





- naivní (neadaptivní)
- rekurzivní algoritmus de Casteljau

