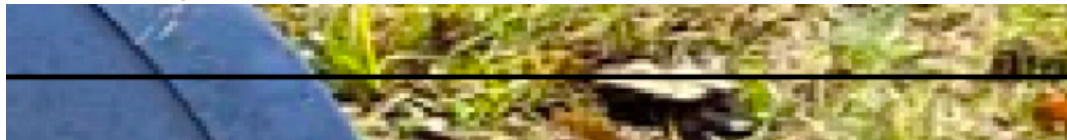


(a) right camera



(b) left camera



(c) local evidence



(d) left to right messages



(e) right to left messages



(f) marginalized posterior probability

