

# **GPU Programming**

Lecture 3
UniTS Advance HPC Course 2024/2025

### Agenda



- OpenMP for GPUs
- Advanced Scheduling
- Data Movement
- Modular programming
- Examples and Exercises

But not everything today....

### Multi-level Parallelism



Tile the loop into an outer loop and an inner loop.

Create nteams "teams".

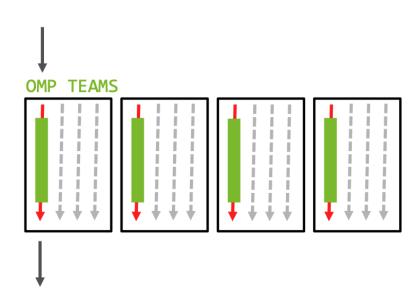


## **OpenMP Teams**

#### teams directive

To better utilize the GPU resources, use many thread teams via the TEAMS directive.

- Spawns 1 or more thread teams with the same number of threads
- Execution continues on the master threads of each team (redundantly)
- No synchronization between teams



### Multi-level Parallelism



Tile the loop into an outer loop and an inner loop.

Create nteams "teams".

Assign the outer loop to "teams".

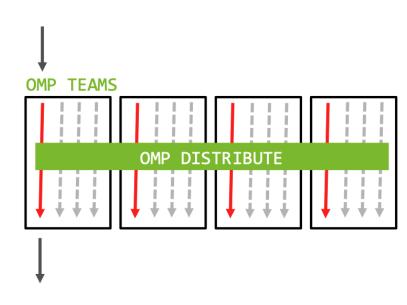


## **OpenMP Teams**

#### distribute directive

The distribute clause splits the loop iterations into chunks and assigns each chunk to a team.

- A team corresponds to a group of threads that work together (similar to a **CUDA block**).
- Each team works independently on its assigned chunk of the loop.
- Enables **team-level parallelism**, distributing work across multiple Streaming Multiprocessors (SMs).



### Multi-level Parallelism



Tile the loop into an outer loop and an inner loop.

Create nteams "teams".

Assign the outer loop to "teams".

Assign the inner loop to the "threads".

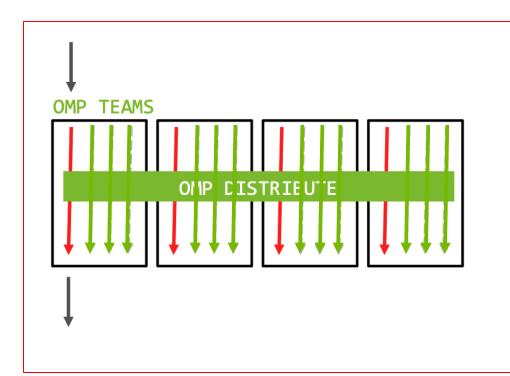
### OpenMP threads



### parallel for directive

The parallel for clause takes the chunk of iterations assigned to each team (by distribute) and further parallelizes it across the threads within that team.

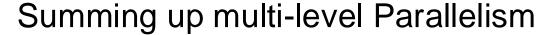
- Threads in the team work on individual loop iterations, dividing the chunk of work among themselves.
- Threads within a team map to CUDA threads (within a CUDA block).
- Enables thread-level parallelism, distributing the workload among the threads of a team.



### Multi-level Parallelism



For convenience, OpenMP defines composite constructs to implement the required code transformations

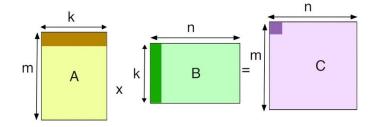




- 1. Teams: create multiple independent teams of threads
- 2. Distribute: Splits the loop into chunks, assigning chunks to teams. Each team works **independently** on a specific subset of the loop iterations.
- 3. parallel for: Splits the team's assigned chunk of iterations among threads within the team.
- 4. Hierarchy:
  - distribute controls team-level parallelism.
  - parallel for controls thread-level parallelism within each team.



#### **DGEMM** $C = \alpha A \times B$



```
void __attribute__ ((noinline)) mm_mul(TYPE *MA, TYPE *MB, TYPE *MCPU, TYPE alpha, int Ndim, int Mdim, int Kdim){
    for (int i = 0; i < Mdim; i++) {
        for (int j = 0; j < Ndim; j++) {
            | for (int kk = 0; kk < Kdim; kk++) {
            | MC[i * Ndim + j] = MA [i * Kdim + kk] * MB [kk * Ndim + j] + MC[i * Ndim + j];
        }
        MC[i * Ndim + j] *= alpha;
    }
}</pre>
```



#### Step 1: Offload:

#pragma omp target sends the loop to the GPU.

#### **Step 2: Thread-Level Parallelism:**

#pragma omp parallel for creates threads on the GPU.

If the runtime decides to use 128 threads, for example, the loop's 1,000 iterations are split across these threads.

#### Step 3: simd Vectorization

Each thread processes multiple iterations at once using SIMD vectorization.





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#### Step 3: simd Vectorization

Each thread processes multiple iterations at once using SIMD vectorization.

#### Step 4: collapse () Merge loops

Enables to merge all the iterations of several associated loops into a single large iteration loop.

```
#pragma omp target teams dsistribute parallel for simd collapse(3)
for (int i=0;i<nx;i++)
    for (int i=0;i<nx;i++)
        for (int i=0;i<nx;i++)</pre>
```



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```
void __attribute__ ((noinline)) mm_mul(TYPE *MA, TYPE *MB, TYPE *MC, TYPE *MCPU, TYPE alpha, int Ndim, int Mdim, int Kdim){
    #pragma omp target teams distribute parallel for simd | collapse(2) | map(to: MA[0:Mdim*Kdim],MB[0:Kdim*Ndim],alpha) | map(tofrom: MC[0:Ndim*Mdim])
    for (int i = 0; i < Mdim; i++) {
        for (int j = 0; j < Ndim; j++) {
            | for (int kk = 0; kk < Kdim; kk++) {
            | MC[i * Ndim + j] = MA [i * Kdim + kk] * MB [kk * Ndim + j] + MC[i * Ndim + j];
        }
        MC[i * Ndim + j] *= alpha;
    }
}</pre>
```



#### Step 4: collapse () Merge loops

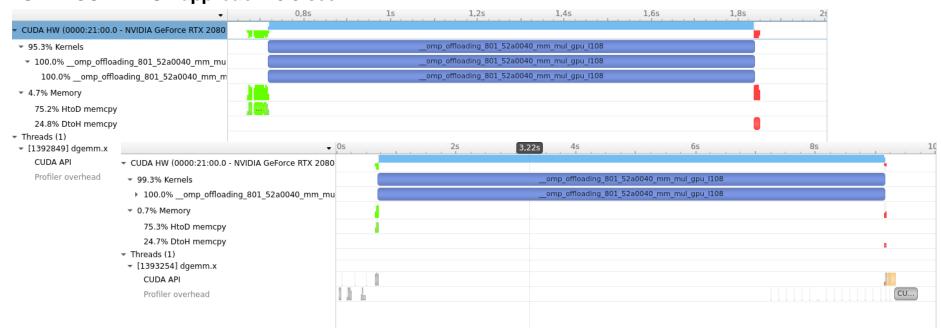
Enables to merge all the iterations of several associated loops into a single large iteration loop.





SIMD approach: ~11 sec

SIMD COLLAPSE approach: 3.8 sec





#### NSYS NVPROF

examples\$ nsys nvprof -o dgemm\_simd ./dgemm.x

Time(%)	Total Time (ns)	Num Calls	Average	Minimum	Maximum	StdDev	Name
69,0	168.399.236	2	84.199.618,0	72.070.694	96.328.542	17.152.888,0	cuDevicePrimaryCtxRelease_v2
17,0	42.764.492	8	5.345.561,0	11.968	24.790.348	8.214.495,0	cuMemcpyHtoDAsync_v2
5,0	13.775.236	1	13.775.236,0	13.775.236	13.775.236	0,0	cuMemcpyDtoHAsync_v2
2,0	5.712.936	1	5.712.936,0	5.712.936	5.712.936	0,0	cuModuleLoadDataEx
1,0	4.300.121	7	614.303,0	218.654	1.047.211	346.622,0	cuMemFree_v2
1,0	2.773.178	7	396.168,0	199.229	921.751	255.089,0	cuMemAlloc_v2
1,0	2.405.621	1	2.405.621,0	2.405.621	2.405.621	0,0	cuMemAllocHost_v2
0,0	1.907.163	1	1.907.163,0	1.907.163	1.907.163	0,0	cuMemFreeHost
0,0	524.696	1	524.696,0	524.696	524.696	0,0	cuModuleUnload
0,0	257.307	1	257.307,0	257.307	257.307	0,0	cuLaunchKernel
0,0	39.136	7	5.590,0	2.913	7.326	1.639,0	cuEventRecord
0,0	19.833	2	9.916,0	9.686	10.147	326,0	cuStreamCreate
0,0	18.163	2	9.081,0	7.738	10.425	1.900,0	cuStreamDestroy_v2
0,0	11.791	2	5.895,0	5.312	6.479	825,0	cuStreamSynchronize
0,0	10.689	5	2.137,0	966	3.696	1.182,0	cuEventCreate
0,0	8.821	5	1.764,0	888	3.702	1.231,0	cuEventDestroy
0,0	2.569	1	2.569,0	2.569	2.569	0,0	cuStreamWaitEvent
0,0	860	2	430,0	398	462	45,0	cuDevicePrimaryCtxSetFlags_v2

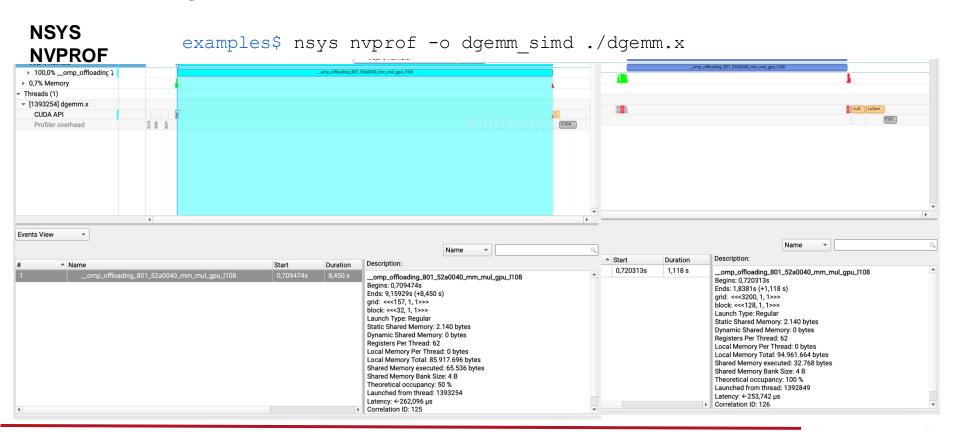


#### NSYS NVPROF

examples\$ nsys nvprof -o dgemm\_simd ./dgemm.x

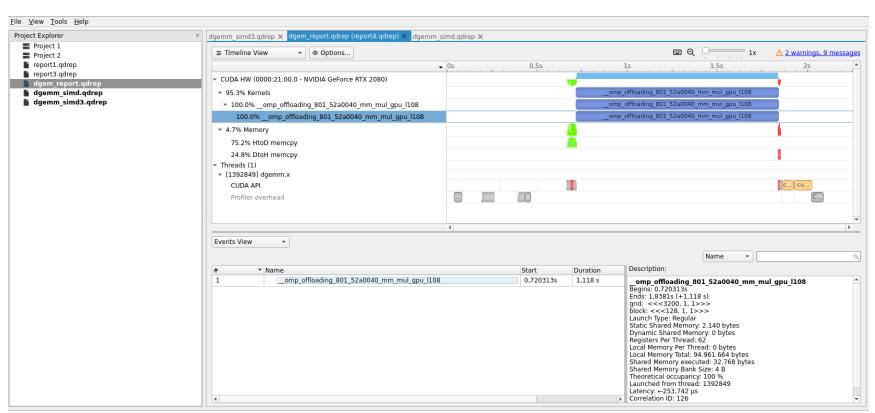
Time(%)	Total Time (ns)	Instances	Average	Minimur	m Max	imum Std[	Dev	Name
100,0	8.360.894.356	1	8.360.894.356,0	0 8.360.894	.356 8.360.	894.356	0,0omp_off	loading_801_52a0040_mm_mul_gpu_l10
JDA Memo	ry Operation Stat	istics (by t	cime):					
Time(%)	Total Time (ns)	Operations	Average	Minimum	Maximum	StdDev	Operatio	on
73,0	41.441.054	8	5.180.131,0	1.056	23.829.764	7.898.339,0	[CUDA memcpy	/ HtoD]
26,0	14.973.110	1	14.973.110,0	14.973.110	14.973.110	0,0	[CUDA memcpy	DtoH]
DA Memo	ry Operation Stat	istics (by s	size in KiB):					
JDA Memo Total		istics (by s	size in KiB): Minimum	Maximum	StdDev	Operatio	on	
	Operations		Minimum			Operatio		











### OpenMP Reduction



"The reduction clauses are **data-sharing attribute** clauses that can be used to perform some forms of recurrence calculations in parallel."

```
#pragma omp target map(tofrom : conv)
#pragma omp teams distribute parallel for simd reduction(+ : conv)

for (int i = 0; i < Ndim; i++) {
    TYPE tmp = xnew[i] - xold[i];
    conv += tmp * tmp;
}
conv = sqrt((double)conv);</pre>
```

#pragma omp target parallel for reduction(operation:variable list)

### Multi-level Parallelism



For convenience, OpenMP defines composite constructs to implement the required code transformations

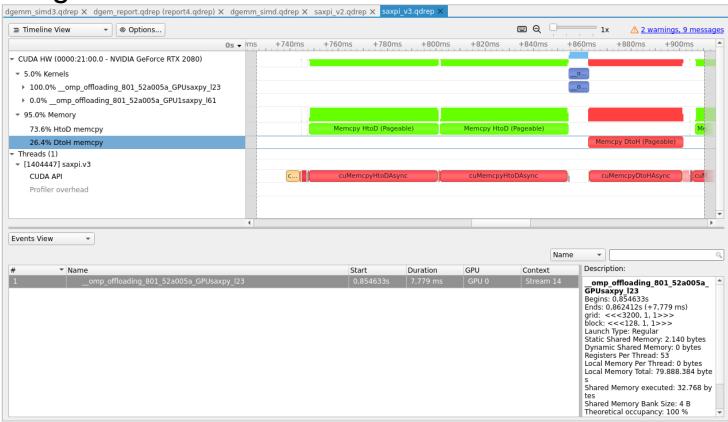
Block size = 16

```
Collecting data...
Available devices: 2
Running on device with 1 teams in total and 16 threads in each t
Block size= 4194304
Vector size = 67108864
Start: Initialization Kernel...Start: Computing Kernel with 6553
Time of kernel: 0.165576
```

```
int m = (n \gg 4);
#pragma omp target data device(0) \
 map(to:a, m, x[0:n]) map(tofrom:y[0:n])
#pragma omp target teams device(0) num teams(ial) \
 map(to:a, m, x[0:n]) map(tofrom:y[0:n]) \
 default(none) shared(a, m, x, y)shared(itr)
#pragma omp distribute parallel for num_threads(itr)\
   dist_schedule(static, itr) \
 default(none) shared(a, m, x, y) shared(x)
for (int i = 0; i < m; ++i) {
 v[i
              l = a * x[i]
                                   ] + v[i
             m] = a * x[i +
                                  m] + y[i +
 y[i + 0x2 * m] = a * x[i + 0x2 * m] + y[i + 0x2 * m];
 y[i + 0x3 * m] = a * x[i + 0x3 * m] + y[i + 0x3 * m];
 y[i + 0x4 * m] = a * x[i + 0x4 * m] + y[i + 0x4 * m];
 y[i + 0x5 * m] = a * x[i + 0x5 * m] + y[i + 0x5 * m];
 y[i + 0x6 * m] = a * x[i + 0x6 * m] + y[i + 0x6 * m];
 v[i + 0x7 * m] = a * x[i + 0x7 * m] + v[i + 0x7 * m];
 v[i + 0x8 * m] = a * x[i + 0x8 * m] + v[i + 0x8 * m];
 v[i + 0x9 * m] = a * x[i + 0x9 * m] + v[i + 0x9 * m];
 v[i + 0xa * m] = a * x[i + 0xa * m] + v[i + 0xa * m];
 v[i + 0xb * m] = a * x[i + 0xb * m] + v[i + 0xb * m];
 y[i + 0xc * m] = a * x[i + 0xc * m] + y[i + 0xc * m];
 y[i + 0xd * m] = a * x[i + 0xd * m] + y[i + 0xd * m];
 y[i + 0xe * m] = a * x[i + 0xe * m] + y[i + 0xe * m];
 y[i + 0xf * m] = a * x[i + 0xf * m] + y[i + 0xf * m];
```



### NSYS NVPROF





Create enough teams to fully utilize all Streaming Multiprocessors on the GPU.

Use the num\_teams clause to explicitly control the number of teams.

For example, on an NVIDIA A100 with 108 SMs:

- Set num teams to at least 108 to assign one team per SM.
- You can go higher (e.g., 512 teams) to saturate the GPU, as multiple teams can execute on the same SM.

```
#pragma omp target teams distribute parallel for num_teams(128)
for (int i = 0; i < N; i++) {
    // Your compute-intensive kernel here
}</pre>
```



Maximize the number of threads within each team to fully utilize the GPU cores.

Use the thread limit clause to control the number of threads per team.

For example, on an NVIDIA A100:

- Use a multiple of 32 (warp size) for thread limit to ensure warp efficiency.
- Common values are 256 or 512 threads per team.
- Avoid exceeding 1,024 threads per team, as this is the hardware limit.

```
#pragma omp target teams distribute parallel for num_teams(128) thread_limit(256)
for (int i = 0; i < N; i++) {
    // Your compute-intensive kernel here
}</pre>
```



Achieve a good balance between the work assigned to teams (distribute) and the work assigned to threads (parallel for).

Ensure the **chunk size** assigned to each team is neither too large nor too small:

- If chunks are too large, some teams may idle while others are still working.
- If chunks are **too small**, the overhead of team creation may reduce performance.

```
#pragma omp target teams distribute parallel for schedule(static, chunk_size)
for (int i = 0; i < N; i++) {
    // Your compute-intensive kernel here
}</pre>
```

### Improving Parallelism: scheduling



Most OpenMP compilers will apply a **static** schedule to workshared loops, assigning iterations in (N/num threads) chunks.

- Each thread will execute contiguous loop iterations, which is very cache & SIMD friendly
- This is great on CPUs, but bad on GPUs

The SCHEDULE() clause can be used to adjust how loop iterations are scheduled.

#### Static Scheduling:

- Assigns fixed-size chunks to teams and threads.
- Good for balanced workloads.

#### **Dynamic Scheduling:**

- Dynamically assigns chunks to teams and threads.
- Useful for unbalanced workloads.

### Improving Parallelism: scheduling



Most OpenMP compilers will apply a **static** schedule to workshared loops, assigning iterations in (N/num threads) chunks.

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0 - (n/2-1)

This is great on CPUs, but bad on GPUs

The SCHEDULE() clause can be used to adjust how loop iterations are scheduled.

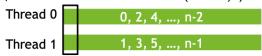
Thread 0

!\$OMP PARALLEL FOR SCHEDULE(STATIC)

Thread 1 (n/2) - n-1

Cache and vector friendly

!\$OMP PARALLEL FOR SCHEDULE(STATIC,1)\*



Memory coalescing friendly

\*There's no reason a compiler couldn't do this for you.



Achieve a good balance between the work assigned to teams (distribute) and the work assigned to threads (parallel for).

Ensure the **chunk size** assigned to each team is neither too large nor too small:

- If chunks are too large, some teams may idle while others are still working.
- If chunks are too small, the overhead of team creation may reduce performance.

```
#pragma omp target teams distribute parallel for num_teams(128) thread_limit(256) schedule(static, 16)
for (int i = 0; i < N; i++) {
    C[i] = A[i] + B[i];
}</pre>
```

- num\_teams(128): Launches 128 teams, targeting SMs on the GPU.
- thread limit(256): Each team uses 256 threads (8 warps).



• schedule(static, 16): Distributes chunks of 16 iterations to threads in each team, ensuring load balance.

## Improving Parallelism: scheduling



Schedule Type	Behavior	Use Case	Overhead
static	Fixed-size chunks, assigned in advance.	Balanced workloads.	Low
dynamic	Chunks assigned dynamically as threads finish.	Unbalanced workloads.	Medium
guided	Exponentially decreasing chunk sizes.	Unbalanced workloads with decreasing cost.	Medium
auto	Determined by runtime.	When unsure of the best strategy.	Varies
runtime	Controlled by OMP_SCHEDULE.	Experimenting with schedules.	Varies





Schedule	Description
static	The iterations of the loop are divided into chunks of fixed size (as specified in the chunk_size argument) and assigned to threads in a round-robin fashion.  If no chunk_size is specified, iterations are divided into chunks of approximately equal size.
dynamic	Iterations are divided into chunks of chunk_size, and chunks are assigned to threads dynamically as threads finish their previous chunks. Threads request new chunks from a queue, which introduces some scheduling overhead.
guided	Iterations are divided into chunks, but the size of each chunk decreases exponentially as the computation progresses.  •Chunks start large and gradually become smaller, aiming to reduce overhead while still balancing the workload.

### Multi-level Parallelism final considerations...



```
void saxpy(float a, float* x, float* y, int sz) {
    #pragma omp target teams distribute parallel for simd \
    num_teams(128) thread_limit(256) schedule(static, 16) \
    map(to:x[0:sz]) map(tofrom:y[0:sz])
    for (int i = 0; i < sz; i++) {
        y[i] = a * x[i] + y[i];
    }
}</pre>
```

#### **Minimize Overhead**

- 1. Avoid Overloading Teams: Don't assign too many iterations to each team. This can create bottlenecks if threads within a team cannot efficiently distribute the work.
- 2. Coalesce Memory Accesses: Ensure that threads within a team access contiguous memory locations to maximize memory bandwidth. For example, structure data so that threads process adjacent elements of an array.
- 3. Avoid Warp Divergence: Minimize branching (e.g., **if statements**) within the loop to ensure all threads in a warp execute the same instructions.

### How OpenMP Leverages GPU Hardware



#### **SMs (Streaming Multiprocessors)**:

- Each team is assigned to one or more SMs.
- Multiple teams can share an SM depending on the workload and hardware capabilities.

#### Warp-Level Execution:

 Threads within a team are grouped into warps and execute SIMD-style instructions.

#### **Resource Sharing:**

 Teams and threads within an SM share the same hardware resources, such as L1 cache, registers, and shared memory.

### Key OpenMP Directives



- Offloading: #pragma omp target Specifies that the computation should run on the GPU.
- Teams Creation: #pragma omp teams
   Creates a grid of teams, each consisting of multiple threads.
- • Parallel Threads Within a Team: #pragma omp parallel Specifies parallel execution within a team.
- Combined Directive: #pragma omp target teams distribute parallel for Combines offloading, team creation, and thread-level parallelization.

#### **Key Mapping**

Teams are mapped to SMs.

Threads within a team are mapped to CUDA cores and grouped into warps.

## OpenMP vs CUDA: Key Differences

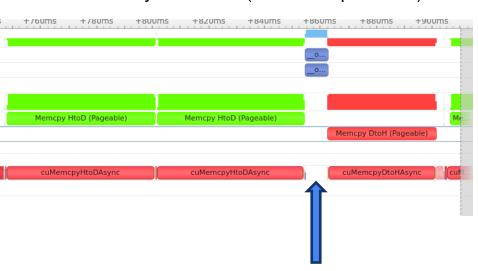


Aspect	OpenMP	CUDA
Grid/Block Management	Automatically handled by OpenMP runtime	Explicitly defined by the programmer
Thread Control	Threads are abstracted; programmer controls teams and loops	Fully controlled by the programmer
Ease of Use	High, suitable for quick GPU programming	Requires more detailed understanding of GPU hardware
Performance Tuning	May require effort to optimize (less low-level control)	Allows fine-tuning of hardware resources
Memory Management	Managed implicitly via OpenMP clauses	Explicitly managed by the programmer



#### Some considerations:

- The OMP implementation of memCopy is synchronous (and implies CPU operations)
- The OMP implementation of Kernel execution is synchronous (NO CPU operations)
- Copy data is expensive



CPU can process something here!!!!

#### OpenMP: optimizing data transfer



If you want to allocate the memory of some variables on the device at a given point of your program but it is not possible to free the memory within the same scope of the program, you can then use the enter data and exit data constructs.

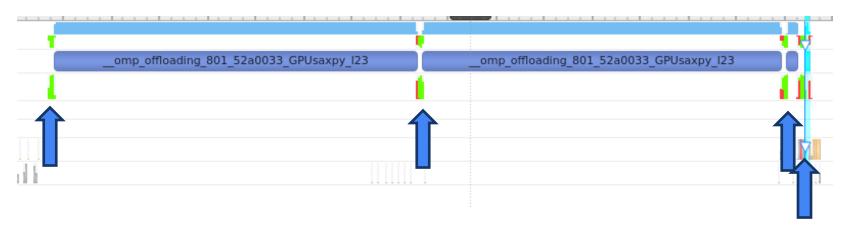
Memory is deallocated

## OpenMP: optimizing data transfer



If you want to allocate the memory of some variables on the device at a given point of your program but it is not possible to free the memory within the same scope of the program, you can then use the enter data and exit data constructs.

#### SAXPI.V2





```
void some_function_somewhere (void)
        double* A = (double*) malloc(nx*nv*sizeof(double));
        double* B = (double*) malloc(nx*ny*sizeof(double));
        #pragma omp target enter data map(to:A[0:nx*ny])
        #pragma omp target enter data map(alloc:B[0:nx*ny])
TYPE *A = (TYPE *) malloc(sizeof(TYPE *) * M * K);
TYPE *B = (TYPE *)malloc(sizeof(TYPE *) * K * N);
TYPE *C = (TYPE *) malloc(sizeof(TYPE *) * M * N);
TYPE *C2 = (TYPE *) malloc(sizeof(TYPE *) * M * N);
* Matrix initialization A=1., B=1. and C=0.
                                                              startTime = TCPU TIME:
mm_init(A,M,K, val);
mm_init(B,K,N,val);
                                                              mm_mul_gpu(A, B, C, alpha, N, M, K);
#pragma omp target enter data map(to:A[0:M*K], B[0:N*K])
                                                              mm_mul_gpu2(A, B, C, alpha, N, M, K);
//#pragma omp target enter data map(alloc:C[0:M*N])
mm_zero(C,M,N);
                                                              stopTime = TCPU_TIME;
mm_zero(C2,M,N);
                                                              wtime = stopTime - startTime;
                                                              printf("Execution Time on GPU = %e [sec]\n", wtime);
                                                              printf("-----
                                                          #pragma omp target exit data map(delete:A,B)
```



```
■ Timeline View

▲ 2 warnin

                                             ls 1,305s
CUDA HW (0000:21:00.0 - NVII
                                            omp offloading 80.
                                                                                                                    omp offloading 801 52a0066 mm mul gpu2 I107

    99.1% Kernels

                                                                                                                    omp offloading 801 52a0066 mm mul gpu2 I107
  ▼ 88.2% omp offloading 80
                                                                                                                    omp offloading 801 52a0066 mm mul gpu2 I107
      100.0% omp offloading
  ▼ 11.8% omp offloading 80
                                            omp offloading 80..
      100.0% omp offloading
                                            omp offloading 80.
 ▼ 0.9% Memory
    65.5% HtoD memcpy
    34.5% DtoH memcpy

    Threads (1)

 ▼ [1407541] dgemm.x
    CUDA API
    Profiler overhead
```

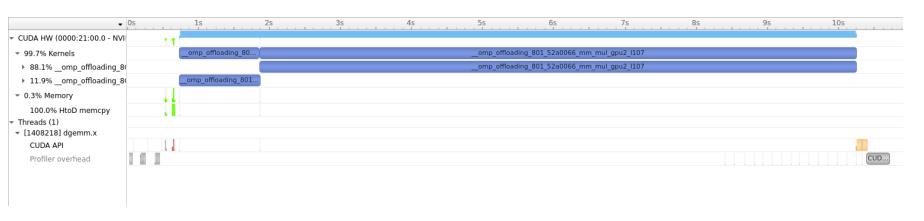


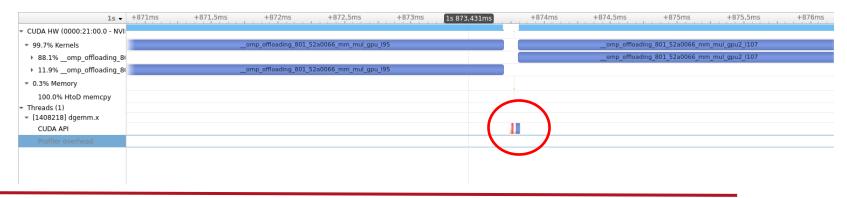
```
mm_init(A,M,K, val);
mm_init(B,K,N,val);
#pragma omp target enter data map(to:A[0:M*K], B[0:N*K])
mm_zero(C,M,N);
#pragma omp target enter data map(to:C[0:M*N])
mm_zero(C2,M,N);
```

Initialize one (copy one) use two times!!!

```
printf("Execution Time on GPU = %e [sec]\n", wtime);
printf("----\n");
#pragma omp target exit data map(delete:A,B,C)
printf("End Computation\n");
```







#### OpenMP optimizing data transfer



```
#pragma omp target data device(0) map(alloc:tmp[:N]) map(to:input[:N)) map(from:res)
#pragma omp target device(0)
#pragma omp parallel for
    for (i=0; i<N; i++)
      tmp[i] = some_computation(input[i], i);
    update_input_array_on_the_host(input);
#pragma omp target update device(0) to(input[:N])
#pragma omp target device(0)
#pragma omp parallel for reduction(+:res)
    for (i=0; i<N; i++)
      res += final_computation(input[i], tmp[i], i)
```

tan

rget

Sod

tarq

Tet

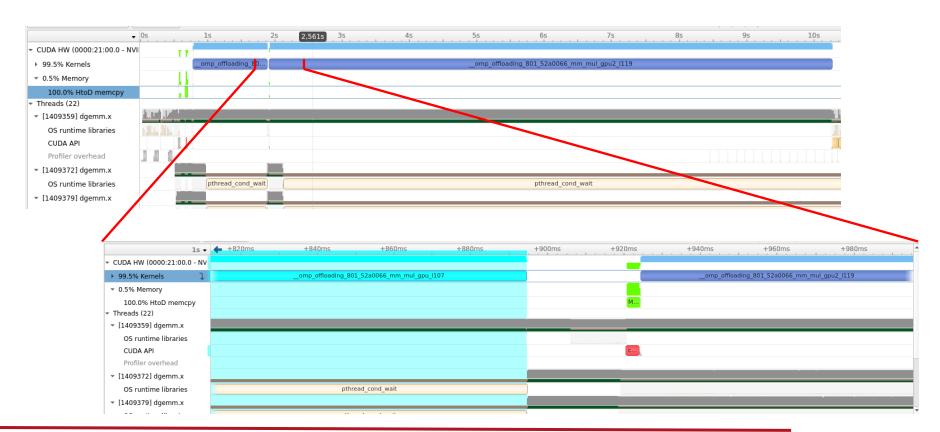


```
mm_mul_gpu(A, B, C, alpha, N, M, K);
printf("Begin Update on CPU.\n");
mm_rand(B,K,N);
#pragma omp target update to(B[0:K*N])
printf("Begin second DGEMM on GPU.\n");
mm_mul_gpu2(A, B, C, alpha, N, M, K);
```

When you want to update the values of a given variable, or a set of variables, either on the GPU or on the CPU, you can use the target update construct to **avoid doing it by closing a data structure.** 

**Warning:** you can update the whole array or a part of it.







Functions that are call inside a kernel should be executed on the accelerator. You should use the declare construct to inform the compiler that it should produce such an executable.

```
#pragma omp target teams distribute parallel for simd map(from:mean_values[0:num_rows])

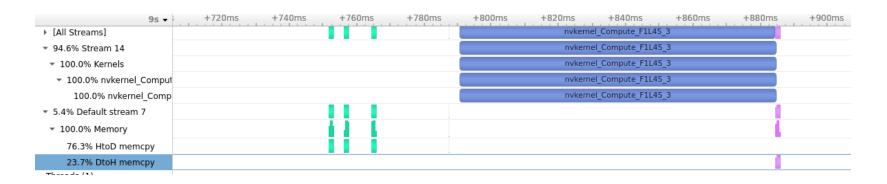
{
    for (size_t i=0; i<num_rows; ++i)
    mean_values[i] = mean_value(&(table[i*num_cols]), num_cols);
}

#pragma omp target exit data map(delete:table)

for (size_t i=0; i<10; ++i)
    printf("Mean value of row %6d=%10.5f\n", i, table[i]);
    printf("...\n");</pre>
```



Functions that are call inside a kernel should be executed on the accelerator. You should use the declare construct to inform the compiler that it should produce such an executable.





If you have multiple accelerators available, you can select the one on which you run the kernels with the device clause of the target construct. It includes both target data constructs and target teams/parallel constructs.

```
MPI_Comm_rank(MPI_COMM_WORLD, &rank);
int num_gpus = omp_get_num_devices();
int my_gpu = my_rank%num_gpus
#pragma omp target data map(...) device(my_gpu)
{
    ...
}
```

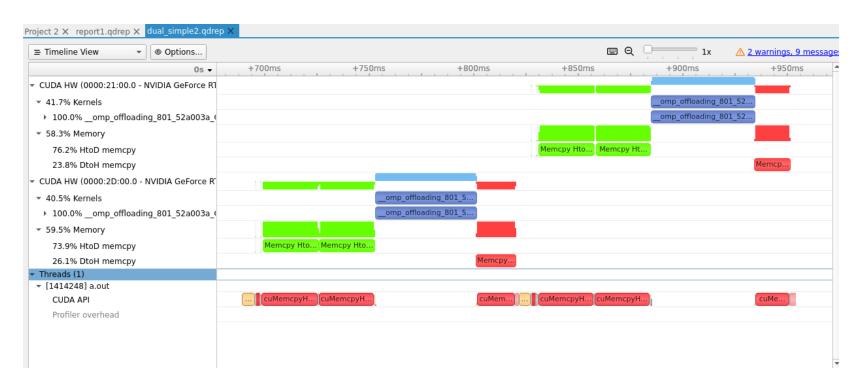
device number is 0, 1, 2, ...

On target data construct you can partition data between GPUs



```
\#pragma omp target data device(1) map(to:a, n, \times[0:n/2]) map(tofrom:y[0:n/2])
#pragma omp target device(1)
printf("Running on device: %d\n", omp_get_device_num());
#pragma omp target teams distribute parallel for simd device(1) map(to:a, n, x[0:n/2]) map(tofrom:y[0:n/2])
for (int i = 0; i < n/2; ++i) {
 y[i] = a * x[i] + y[i];
printf("second GPU\n");
#pragma omp target data device(0) map(to:a, n, x[n/2+1:n/2]) map(tofrom:y[n/2+1:n/2])
#pragma omp target teams distribute parallel for simd device(0) map(to:a, n, x[n/2+1:n/2]) map(tofrom:y[n/2+1:n/2])
for (int i = n/2+1; i < n; ++i) {
 y[i] = a * x[i] + y[i];
```







# THANK YOU.

# Now, it's your time QUESTIONS?

**GPU** programming with OpenMP