Lab 1: Modeling Packet Losses

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1 Hidden Markov Model

Gilbert-Elliott Model is packet loss model which is based on two-state Hidden Markov Model. In other words, Gilbert-Elliott Model is a simply version of Hidden Markov Model. Therefore, It's necessary to learn more about Hidden Markov Model to understand Gilbert-Elliott Model completely.

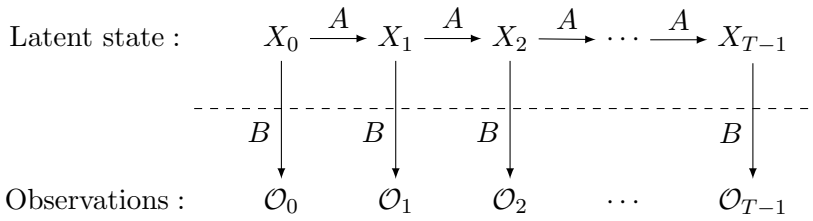

Figure 1: Hidden Markov Model

Hidden Markov Model introduce two random variable - Latent state and Observations. Latent state is a variable that we can't see. Observations is a variable that we can observe at the experiment. Furtheremore, HMM also has three parameters - initial probability vector π, transition probability matrix A, emission probability matrix B. So if we can compute three parameters $\{A, B, \pi\}$, we will reconstruct HMM. Researchers have developed numerous approaches to estimate parameters of Hidden Markov Model (HMM) such as Forward/Backward Algorithm.

Markov Model simplifies the Hidden Markov Model (HMM). It only uses two parameters $\{A, \pi\}$ and removes the Latent state. Maximum likelihood estimation (MLE) is a good way to estimate these parameters. The relationship between Hidden Markov Model and Markov Model is similar to the relation between Gilbert-Elliott Model (GM) and Simple Gilbert-Elliott Model (SGM). Section two of this article will demonstrate the reason.

2 Gilbert-Elliott Model

Gilbert-Elliott Model resembles Hidden Markov Model. To be specific, Gilbert-Elliott Model has two state - $\{Good, Bad\}$, transition matrix $\boldsymbol{P} = \begin{bmatrix} (1-p) & q \\ p & (1-q) \end{bmatrix}$ and emission probability vector $\begin{bmatrix} 1-k & 1-h \end{bmatrix}^T$.

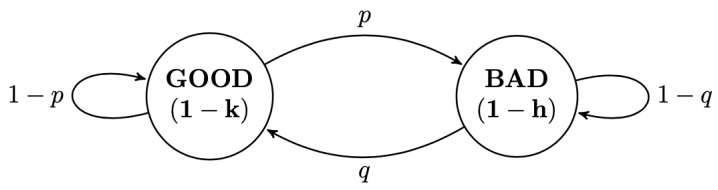

Figure 2: Gilbert-Elliott Model

Furtheremore, we can obtain the other parameters of Gilbert-Elliott Model such as the steady state probability vector π, packet loss probability p_L and the probability distribution of loss run length p_k. The steady state probability vector $\boldsymbol{\pi}$ satisfies the following conditions:

$$\boldsymbol{\pi} = \boldsymbol{P}\boldsymbol{\pi}, \mathbf{1}^T\boldsymbol{\pi} \tag{1}$$

where

$$\boldsymbol{\pi} = \begin{bmatrix} \pi_G \\ \pi_B \end{bmatrix} \tag{2}$$

The steady state probabilities exist for $0 < p,\ q < 1$ and are given by

$$\pi_G = \frac{q}{p+q}, \pi_B = \frac{p}{p+q} \tag{3}$$

From equation (3), we can get packet loss probability p_L as follows:

$$p_L = (1-k)\pi_G + (1-h)\pi_B \tag{4}$$

The special cases of $k = 1$ and $k = 1, h = 0$ are called a Gilbert Model (GM) and a simple Gilbert Model (SGM), respectively. Note that in case of the SGM, the probability distribution of loss run length has a geometric distribution, i.e.,

$$p_k \triangleq \text{ Prob } \{ \text{ loss run length } = k\} = q(1-q)^{k-1} \text{ for } k = 1, 2, \ldots, \infty \tag{5}$$

3 Estimation of parameters

3.1 Simple Gilbert Model (SGM)

Because $0, 1$ represent $\{Good, Bad\}$ respectively. The probabilities from *Good to Bad* is equal to $P(1|0)$ and the probabilities from *Bad to Good* is equal to $P(0|1)$. According to *Bayes theorem*,

$$\begin{aligned} p = P(1|0) = \frac{P(01)}{P(0)} = \frac{n_{01}}{n_0} \\ q = P(0|1) = \frac{P(10)}{P(1)} = \frac{n_{10}}{n_1} \end{aligned} \tag{6}$$

n_{10} means the times 0 follows 1 . n_{01} means the times 1 follows 0. n_0 represents the times of 0. n_1 represents the times of 1.

3.2 Gilbert Model (GM)

Gilbert applied a method to decide the parameters of GM [1]. Firstly, the parameters of p, q, h can be estimated from another parameters of a, b, c. The expression equation of a, b, c is as follow:

$$a = P(1), b = P(1|1), c = \frac{P(111)}{P(101) + P(111)} \tag{7}$$

Finally, we can get parameters of Gilbert Model by the following relation between these variables.

$$1-q=\frac{ac-b^2}{2ac-b(a+c)}, h=1-\frac{b}{1-q}, p=\frac{aq}{1-h-a} \tag{8}$$

4 Experiment Task

In this experiment, we simulate the Simple Gilbert Model (SGM) and Gilbert Model (GM) separately.

4.1 Simple Gilbert Model (SGM)

4.1.1 Construct model

The script and detailed comments for Constructing Simple Gilbert Model is attached at the appendix A. The main implement is here.

```
# main loop
for i in range(len):
    # if the random sequence is large than the transition probability
    # we must change the state for example 0 -> 1 or 1 -> 0
    if statechange[i] > tr[state, state]:
        # transition into the other state
        state ^= 1
    # add a binary value to output
    seq[i] = state
```

As we can see from the code segment, if the sequence[i] is large than the transition probability, the start will flip from 0 to 1 or from 1 to 0.

4.1.2 Estimate model parameters

To determine the parameters of p, q, I write the script to count the number of times where binary sequence occurs.

4.1.3 Comparison and discussion

4.2 Gilbert Model (GM)

4.2.1 Construct model

4.2.2 Estimate model parameters

4.2.3 Comparison and discussion

Detailed Python Script Appendix

A Construct Simple Gilbert Model (SGM)

```
    #!/usr/bin/env python
# -*- coding: utf-8 -*-
##
# @file     sgm_generate.py
# @author   Kyeong Soo (Joseph) Kim <kyeongsoo.kim@gmail.com>
# @date     2020-03-25
#
# @brief    A function for generating loss pattern based on simple Guilbert model.
#

import numpy as np
import sys


def sgm_generate(len, tr):
    """
    Generates a binary sequence of 0 (GOOD) and 1 (BAD) of length
    len from an SGM specified by a 2x2 transition probability matrix
    tr; tr[i, j] is the probability of transition from state i to
    state j.

    This function always starts the model in GOOD (0) state.

    Examples:

    import numpy as np

    tr = np.array([[0.95, 0.10],
                   [0.05, 0.90]])
    seq = sgm_generate(100, tr)
    """

    seq = np.zeros(len)

    # tr must be 2x2 matrix
    tr = np.asarray(tr)  # make sure seq is numpy 2D array
    if tr.shape != (2, 2):
        sys.exit("size of transition matrix is not 2x2")

    # create a random sequence for state changes
    statechange = np.random.rand(len)

    # Assume that we start in GOOD state (0).
    state = 0

    # main loop
    for i in range(len):
        # if the random sequence is large than the transition probability
        # we must change the state for example 0 -> 1 or 1 -> 0
        if statechange[i] > tr[state, state]:
            # transition into the other state
            state ^= 1
        # add a binary value to output
        seq[i] = state

```

```
    return seq


if __name__ == "__main__":
    import argparse

    parser = argparse.ArgumentParser()
    parser.add_argument(
        "-L",
        "--length",
        help="the length of the loss pattern to be generated; default is 10",
        default=10,
        type=int)
    parser.add_argument(
        "-T",
        "--transition",
        help="transition matrix in row-major order; default is
    \"0.95,0.10,0.05,0.90\"",
        default="0.95,0.10,0.05,0.90",
        type=str)
    args = parser.parse_args()
    len = args.length
    tr = np.reshape(np.fromstring(args.transition, sep=','), (2, 2))
    print(sgm_generate(len, tr))
```

References

[1] E. N. Gilbert, "Capacity of a burst-noise channel," Bell System Technical Journal, vol. 39, no. 5, pp. 1253–1265, Sep. 1960.