

ProblemStatement:

IoT-BasedIndustry-specificintelligentfire  
managementsystem

Domain:

InternetofThings

Assignment1:

Circuit design Homeautomation system in  
TinkerCad

By,

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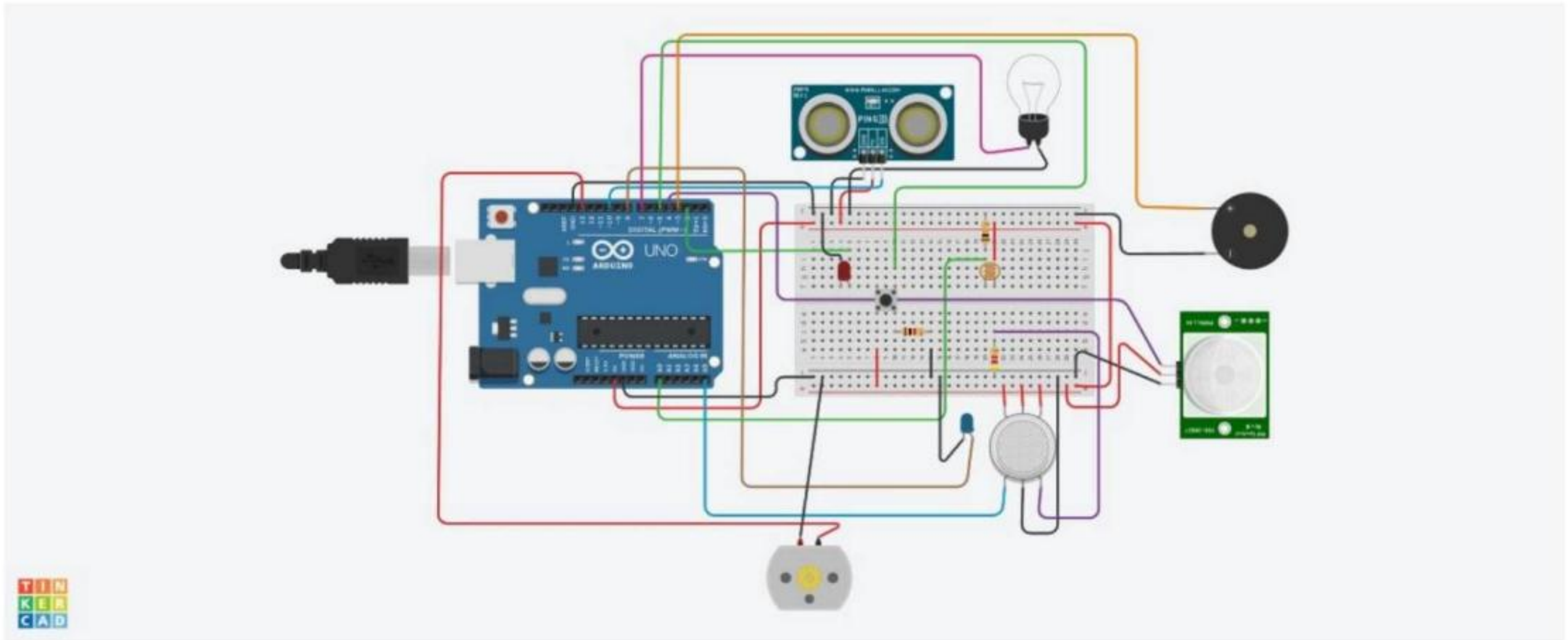
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Link:

Circuitdiagram:





## ArduinoUnoCode:

```

const int pingPin=10;

const int ledUS=2; const int light=7;

const int pir=4;

#define photoSensorA0
#define buzzer3

int const PINO_SGAS=A5;

int const ledGas=8;

int const button=5;

int const motor=13; void setup()
{
    pinMode(ledUS,OUTPUT);
    pinMode(light,OUTPUT);
    pinMode(buzzer,OUTPUT);
    pinMode(ledGas,OUTPUT);
    pinMode(motor,OUTPUT);
    pinMode(pir,INPUT);
    pinMode(button,INPUT);
    pinMode(photoSensor,INPUT);

```



```

Serial.begin(9600);
}
void loop()
{
    long duration, cm; int valLight = analogRead(photoSensor);
    int valPIR = digitalRead(pir);
    int valGAS = analogRead(PINO_SGAS);
    valGAS = map(valGAS, 300, 750, 0, 100);
    int valBt = digitalRead(button); pinMode(pingPin, OUTPUT);
    digitalWrite(pingPin, LOW); delayMicroseconds(2);
    digitalWrite(pingPin, HIGH); delayMicroseconds(5);
    digitalWrite(pingPin, LOW); pinMode(pingPin, INPUT);
    duration = pulseIn(pingPin, HIGH);
    cm = microsecondsToCentimeters(duration); if (cm < 336) {
        digitalWrite(ledUS, HIGH);
    } else { digitalWrite(ledUS, LOW);
    }
    if (valLight < 890) {
        digitalWrite(light, HIGH);
    } else { digitalWrite(light, LOW);
    }
    if (valPIR == 1) {
        digitalWrite(buzzer, HIGH);
    } else { digitalWrite(buzzer, LOW);
    }
    if (valBt == 1) {
        digitalWrite(motor, HIGH);
    } else { digitalWrite(motor, LOW);
    }
}

```



```
if(valGAS>20){  
    digitalWrite(ledGas,HIGH);  
}else{ digitalWrite(ledGas,LOW);  
}  
Serial.print(valPIR);  
Serial.println();  
}  
longmicrosecondsToCentimeters(longmicroseconds){  
    returnmicroseconds/29/2;  
}
```

