```
from google.colab import drive

drive.mount('/content/drive/')

#poc_DATASET
#zip_ref = zipfile.ZipFile("/content/drive/My Drive/sg_ff_filtered_red.zip", 'r')

#ISGI_20000_200gray_DATASET
# zip_ref = zipfile.ZipFile("/content/drive/My Drive/ISGI_dataset_200g.zip", 'r')

#ISGI_20000_200rgb_DATASET
zip_ref = zipfile.ZipFile("/content/drive/My Drive/ISGI_dataset_200rgb.zip", 'r')

zip_ref.extractall("/tmp/")
zip_ref.close()

[]: import os
base_dir = '/tmp/ISGI_dataset_200rgb'
train_dir = os.path.join(base_dir, 'train')
validation_dir = os.path.join(base_dir, 'valid') #valid or validations

# Directory with our training FlickerFaces pictures
```

[]: import zipfile

```
train_ff_dir = os.path.join(train_dir, 'ff')
     # Directory with our training StyleGAN pictures
     train_sg_dir = os.path.join(train_dir, 'sg')
     # Directory with our validation FlickerFaces pictures
     validation_ff_dir = os.path.join(validation_dir, 'ff')
     # Directory with our validation StyleGAN pictures
     validation_sg_dir = os.path.join(validation_dir, 'sg')
[]: train_ff_fnames = os.listdir(train_ff_dir)
     train_ff_fnames.sort()
     print(train_ff_fnames[:10])
     train_sg_fnames = os.listdir(train_sg_dir)
     train_sg_fnames.sort()
     print(train_sg_fnames[:10])
[]: print('Training_FlickerFaces images total: \t', len(os.listdir(train_ff_dir)))
     print('Training_StyleGAN images total: \t', len(os.listdir(train_sg_dir)))
     print('Validation_FlickerFaces images total: \t', len(os.
      →listdir(validation_ff_dir)))
     print('Validation_StyleGAN images total: \t', len(os.listdir(validation_sg_dir)))
[]: %matplotlib inline
     import matplotlib.pyplot as plt
     import matplotlib.image as mpimg
     import random
     #params for graph
     nrows = 4
     ncols = 4
     #index for iteration
     pic_index = random.randint(0, 990)
[]: fig = plt.gcf()
     fig.set_size_inches(ncols * 4, nrows * 4)
     pic_index += 8
     next_ff_pix =
                    [os.path.join(train_ff_dir, fname)
                     for fname in train_ff_fnames[pic_index-8:pic_index]]
                    [os.path.join(train_sg_dir, fname)
     next_sg_pix =
                     for fname in train_sg_fnames[pic_index-8:pic_index]]
```

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for i, img_path in enumerate(next_ff_pix+next_sg_pix):
       sp = plt.subplot(nrows, ncols, i + 1)
       sp.axis('Off')
       img = mpimg.imread(img_path)
       plt.imshow(img)
       plt.show
[]: from tensorflow.keras import layers
     from tensorflow.keras import Model
     from tensorflow.keras.layers import BatchNormalization, Dropout
[]: input_layer = layers.Input(shape=(200, 200, 3))
     x = layers.Conv2D(16, 3, activation='relu')(input_layer)
     x = layers.MaxPooling2D(2)(x)
     x = Dropout(rate = 0.2)(x)
     x = layers.Conv2D(32, 3, activation='relu')(x)
     x = layers.MaxPooling2D(2)(x)
     x = Dropout(rate = 0.3)(x)
     x = layers.Conv2D(64, 3, activation='relu')(x)
     x = layers.MaxPooling2D(2)(x)
     x = Dropout(rate = 0.4)(x)
     x = layers.Conv2D(64, 3, activation='relu')(x)
     x = layers.MaxPooling2D(2)(x)
     x = Dropout(rate = 0.5)(x)
     x = layers.Conv2D(128, 3, activation='relu')(x)
     x = layers.MaxPooling2D(2)(x)
     x = Dropout(rate = 0.5)(x)
     x = layers.Conv2D(128, 3, activation='relu')(x)
     x = layers.MaxPooling2D(2)(x)
     x = Dropout(rate = 0.5)(x)
     x = layers.Flatten()(x)
     x = layers.Dense(200, activation='relu')(x)
     x = Dropout(rate = 0.5)(x)
     output_layer = layers.Dense(1, activation='sigmoid')(x)
     model = Model(input_layer, output_layer)
```

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model.summary()
[]: input_layer = layers.Input(shape=(200, 200, 3))
     x = layers.Conv2D(16, 3, activation='relu')(input_layer)
     x = layers.MaxPooling2D(2)(x)
     x = layers.Conv2D(32, 3, activation='relu')(x)
     x = layers.MaxPooling2D(2)(x)
     x = layers.Conv2D(64, 3, activation='relu')(x)
     x = layers.MaxPooling2D(2)(x)
     x = layers.Flatten()(x)
     x = layers.Dense(512, activation='relu')(x)
     output_layer = layers.Dense(1, activation='sigmoid')(x)
     model = Model(input_layer, output_layer)
     model.summary()
[]: from tensorflow.keras.optimizers import RMSprop
     model.compile(loss='binary_crossentropy',
                   optimizer=RMSprop(learning_rate=0.001),
                   metrics=['acc'])
[]: from tensorflow.keras.preprocessing.image import ImageDataGenerator
     train_datagen = ImageDataGenerator(rescale=1./255,
                                        zoom_range = 0.2,
                                        horizontal_flip = True,
                                        vertical_flip = True)
     val_datagen = ImageDataGenerator(rescale=1./255)
     # Flow training images in batches of 20 using train_datagen generator
     train_generator = train_datagen.flow_from_directory(
             train_dir, # This is the source directory for training images
             target_size=(200, 200),
             batch_size=20,
             # Since we use binary_crossentropy loss, we need binary labels
             class_mode='binary')
```

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# Flow validation images in batches of 20 using val_datagen generator
     validation_generator = val_datagen.flow_from_directory(
             validation dir,
             target_size=(200, 200),
             batch_size=20,
             class_mode='binary')
[]: history = model.fit(
           train_generator,
           steps_per_epoch=800, # 2000 images = batch_size * steps
           epochs=15,
           validation_data=validation_generator,
           validation_steps=100, # 1000 images = batch_size * steps
           verbose=2)
[]: scores = model.evaluate(validation_generator, verbose=0)
     print("Accuracy: %.2f%%" % (scores[1]*100))
[]: import numpy as np
     import random
     from tensorflow.keras.preprocessing.image import img_to_array, load_img
     # define a new Model that will take an image as input, and will output
     # intermediate representations for all layers in the previous model after
     # the first.
     successive_outputs = [layer.output for layer in model.layers[1:]]
     visualization_model = Model(input_layer, successive_outputs)
     # prepare a random input image of a FlickerFaces or StyleGAN from the training
     \hookrightarrowset.
     ff_img_files = [os.path.join(train_ff_dir, f) for f in train_ff_fnames]
     sg_img_files = [os.path.join(train_sg_dir, f) for f in train_sg_fnames]
     img_path = random.choice(ff_img_files + sg_img_files)
     img = load_img(img_path, target_size=(200, 200)) # this is a PIL image
     x = img_to_array(img) # Numpy array with shape (150, 150, 3)
     x = x.reshape((1,) + x.shape) # Numpy array with shape (1, 150, 150, 3)
     # Rescale by 1/255
     x /= 255
     # run our image through our network, thus obtaining all
     # intermediate representations for this image.
     successive_feature_maps = visualization_model.predict(x)
     # These are the names of the layers, so can have them as part of our plot
     layer_names = [layer.name for layer in model.layers[1:]]
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# Now display our representations
    for layer_name, feature_map in zip(layer_names, successive_feature_maps):
      if len(feature_map.shape) == 4:
         # Just do this for the conv / maxpool layers, not the fully-connected layers
         n_features = feature_map.shape[-1] # number of features in feature map
         # The feature map has shape (1, size, size, n_features)
         size = feature_map.shape[1]
         # We will tile our images in this matrix
         display_grid = np.zeros((size, size * n_features))
         for i in range(n_features):
           # Postprocess the feature to make it visually palatable
          x = feature_map[0, :, :, i]
          x = x.mean()
          x /= x.std()
          x *= 64
          x += 128
           x = np.clip(x, 0, 255).astype('uint8')
           # We'll tile each filter into this big horizontal grid
           display_grid[:, i * size : (i + 1) * size] = x
         # Display the grid
         scale = 20. / n_features
         plt.figure(figsize=(scale * n_features, scale))
         plt.title(layer_name)
         plt.grid(False)
         plt.imshow(display_grid, aspect='auto', cmap='viridis')
[]: # Retrieve a list of accuracy results on training and validation data
     # sets for each training epoch
    acc = history.history['acc']
    val_acc = history.history['val_acc']
     # Retrieve a list of list results on training and validation data
     # sets for each training epoch
    loss = history.history['loss']
    val_loss = history.history['val_loss']
```

Get number of epochs
epochs = range(len(acc))

plt.plot(epochs, acc)
plt.plot(epochs, val_acc)

plt.figure()

Plot training and validation accuracy per epoch

plt.title('Training and validation accuracy')

```
# Plot training and validation loss per epoch
plt.plot(epochs, loss)
plt.plot(epochs, val_loss)
plt.title('Training and validation loss')

[]: model.save('placeholderm2.h5')

[]: !zip -r /content/model_1 /content/model
```