

COMP0118-Coursework1-Figures

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1 Parametric models

1.1 Parameter estimation and mapping

1.1.1

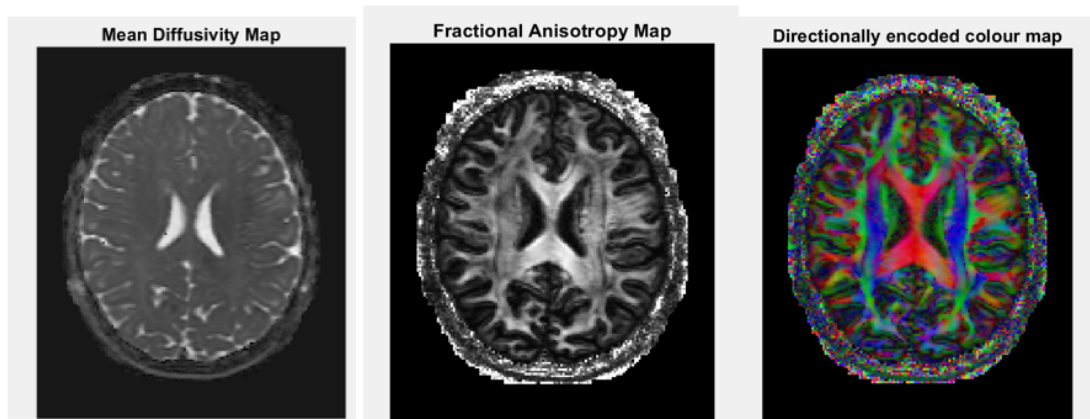


Figure 1: Maps of MRI scans computed using a Linear Diffusion Tensor estimator. Mean Diffusivity Map (left); Fractional Anisotropy Map (middle); Colour-coded Principal Direction Map(right)

1.1.2

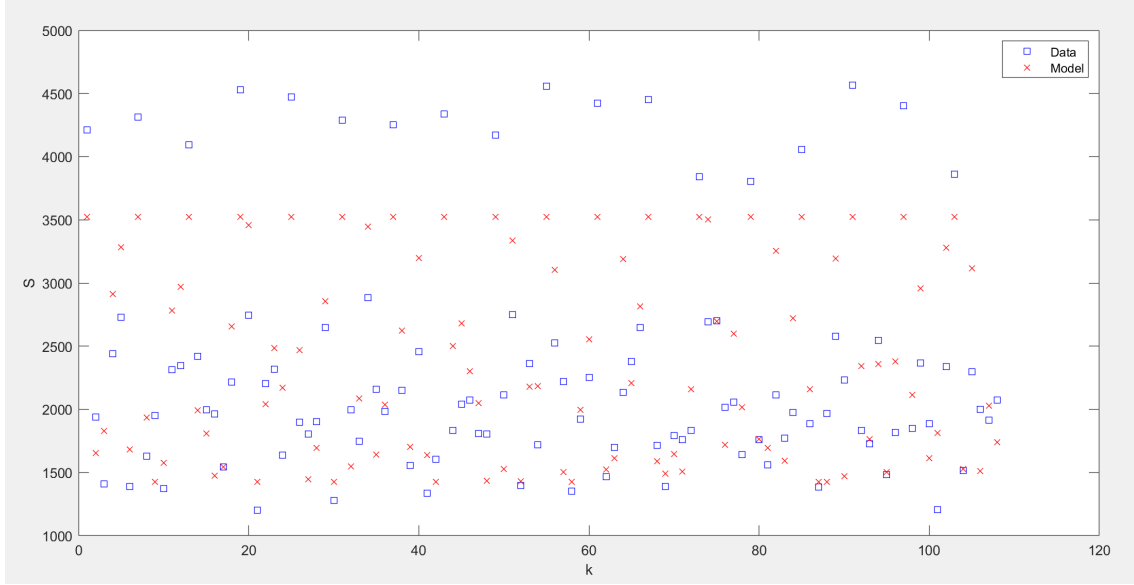


Figure 2: Comparison between the data and the estimated model. The model is the Ball-and-Stick without any constraints on the parameters

1.1.3

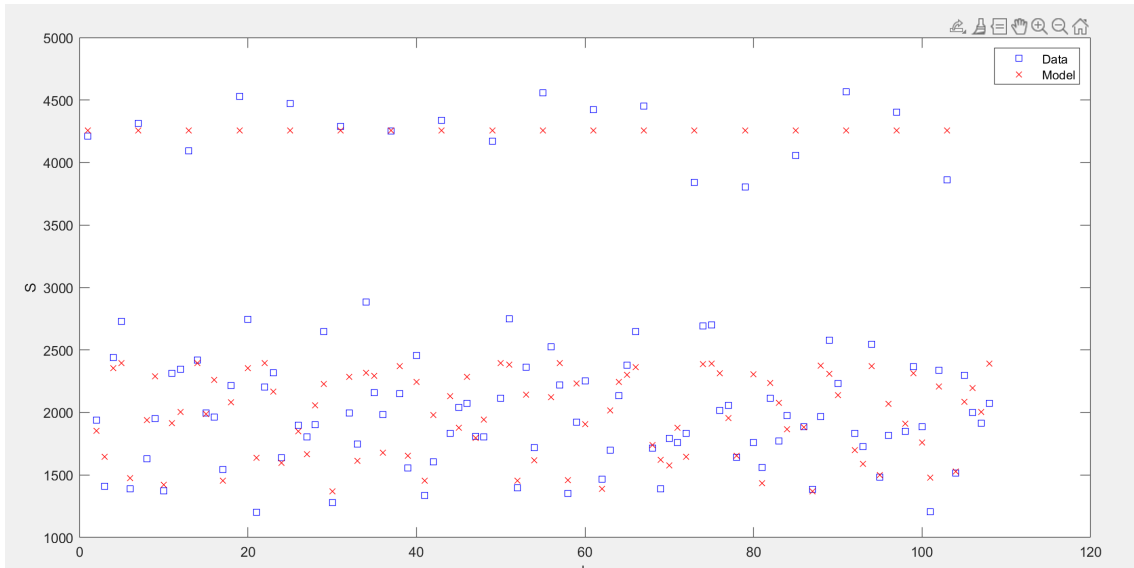


Figure 3: Comparison between the data and the estimated model. The model is the Ball-and-Stick constraints on the $S_{0,d}$ and f parameters

1.1.4

parameters	STD noise
$S0$	10^3
d	10^{-3}
f	10^{-1}
θ	10^{-1}
ϕ	10^{-1}

Table 1: Chosen STD noise values for each parameter of the Ball-and-Stick model

Voxel	Percentage	Num_runs
Avox = dwis(:, 92, 65, 72);	9.6400×10^{-1}	9.0118×10^{-1}
Avox = dwis(:, 115, 50, 72);	4.9000×10^{-1}	4.4490
Avox = dwis(:, 70, 90, 72);	6.8700×10^{-1}	2.5791
Avox = dwis(:, 112, 33, 72);	3.3700×10^{-1}	7.2892
Avox = dwis(:, 37, 44, 72);	6.1200×10^{-1}	3.1642
Avox = dwis(:, 100,100,72);	5.6100×10^{-1}	3.6389
Avox = dwis(:, 40, 100, 72);	9.3100×10^{-1}	1.1205
Avox = dwis(:, 90, 50, 72);	9.7900×10^{-1}	7.7545×10^{-1}
Avox = dwis(:, 77, 95, 72);	2.6400×10^{-1}	9.7732
Avox = dwis(:, 85, 70, 72);	7.5400×10^{-1}	2.1361

Table 2: Percentage of times the minimum *RESNORM* value was found across all runs from different starting points and number of runs required to be 95% confident in finding the global minimum for 10 different voxels.

1.1.5

option	value
MaxFunctionEvaluations	20000
Algorithm	sqp
MaxIter	2000
TolX	1×10^{-10}
TolFun	1×10^{-10}
lb	$[0 \ 0 \ 0 \ -inf \ -inf]$
ub	$[inf \ inf \ 1 \ inf \ inf]$

Table 3: Options used for *fmincon* function

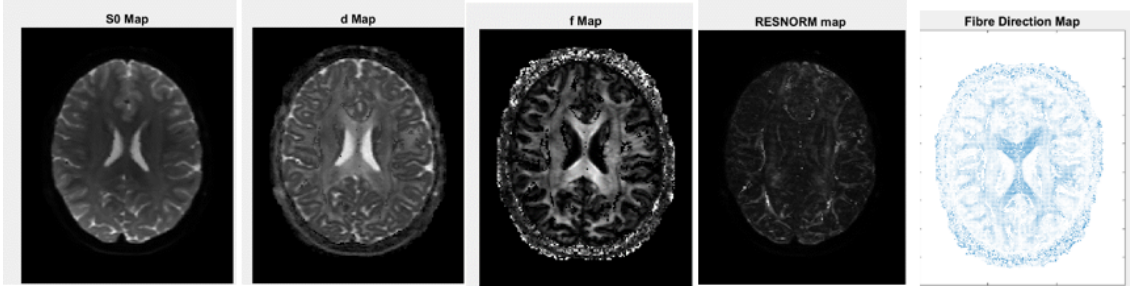


Figure 4: Maps of MRI scans computed using a Ball-and-Stick model estimation over all the voxel in the 72nd slice. *S0* Map (left-left); Diffusivity (*d*) Map (left); Volume Fraction (*f*) Map (middle); Residual Error (*RESNORM*) Map(right); Fibre Direction Map (right-right).

1.1.6

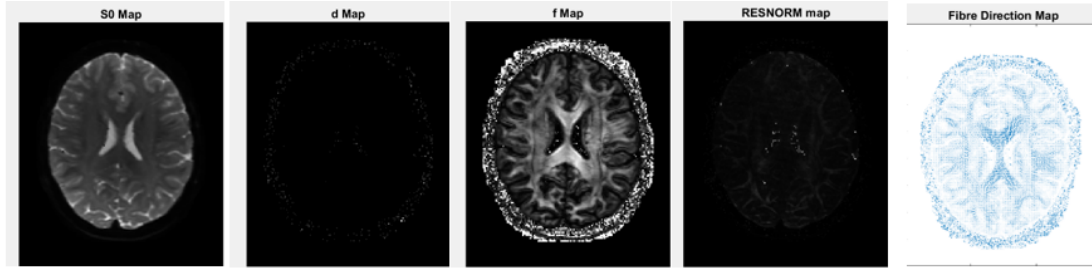


Figure 5: Maps of MRI scans computed using a Ball-and-Stick model estimation over all the voxel in the 72nd slice using the *fmincon* function to impose constraints to the parameters. *S0* Map (left-left); Diffusivity (*d*) Map (left); Volume Fraction (*f*) Map (middle); Residual Error (*RESNORM*) Map(right); Fibre Direction Map (right-right).

Voxel	Percentage	Num_runs
$A_{vox} = \text{dwis}(:, 92, 65, 72);$	4.8000×10^{-1}	4.5811
$A_{vox} = \text{dwis}(:, 115, 50, 72);$	7.4000×10^{-1}	2.2239
$A_{vox} = \text{dwis}(:, 70, 90, 72);$	4.2600×10^{-1}	5.3965
$A_{vox} = \text{dwis}(:, 112, 33, 72);$	8.3800×10^{-1}	1.6459
$A_{vox} = \text{dwis}(:, 37, 44, 72);$	6.8700×10^{-1}	2.5791
$A_{vox} = \text{dwis}(:, 100, 100, 72);$	4.8400×10^{-1}	4.5277
$A_{vox} = \text{dwis}(:, 40, 100, 72);$	4.3200×10^{-1}	5.2962
$A_{vox} = \text{dwis}(:, 90, 50, 72);$	4.6000×10^{-1}	4.8617
$A_{vox} = \text{dwis}(:, 77, 95, 72);$	4.9700×10^{-1}	4.3596
$A_{vox} = \text{dwis}(:, 85, 70, 72);$	4.9100×10^{-1}	4.4361

Table 4: Percentage of times the minimum *RESNORM* value was found using *fmincon* to constraints the parameters across all runs from different starting points and number of runs required to be 95% confident in finding the global minimum for 10 different voxels.

1.2 Uncertainty estimation

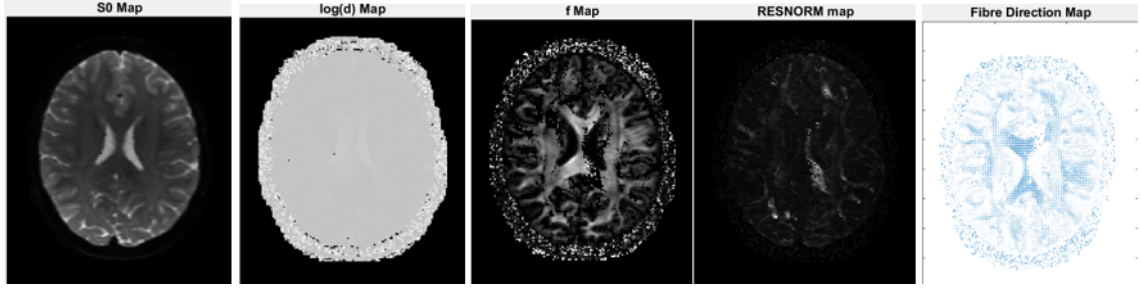


Figure 6: Maps of MRI scans computed using a Ball-and-Stick model estimation over all the voxel in the 72nd slice using the result of the Linear Diffusion Tensor as a starting point for the optimization process. *S0* Map (left-left); Log of the Diffusivity (*d*) Map (left); Volume Fraction (*f*) Map (middle); Residual Error (*RESNORM*) Map(right); Fibre Direction Map (right-right).

1.2.1

<i>parameter</i>	$2 - \sigma$	95% range
<i>S0</i>	[4136.0206099 4373.15407004]	[4131.31772944 4370.79343194]
<i>f</i>	[0.00088345174 0.0013340582]	[0.00075187509 0.00119869186]
<i>d</i>	[0.11173601735 0.5424787294]	$[6.3570069 \times 10^{-12} \quad 0.4075320969]$

Table 5: $2 - \sigma$ range and 95% confidence interval for the parameters *S0*, *d*, and *f* in the *Ball-and-Stick* model for the $Avox = dwis(:, 92, 65, 72)$ obtained with the *Classic Bootstrap* algorithm

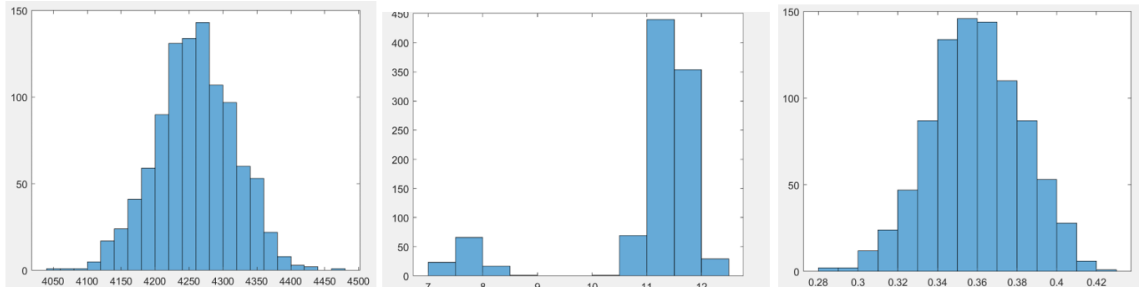


Figure 7: Posterior distributions for the *Classical Bootstrap* method for the parameters *S0* (left); *d* (middle); *f* (right).

Voxel	2-sigma range	95% range
$A_{\text{vox}} = \text{dwis}(:, 92, 65, 72);$	$[4.136\,020\,6 \times 10^3, 4.373\,154\,1 \times 10^3]$ $[8.835 \times 10^{-4}, 1.3341 \times 10^{-3}]$ $[1.117\,360 \times 10^{-1}, 5.424\,787 \times 10^{-1}]$	$[4.131\,317\,7 \times 10^3, 4.370\,793\,4 \times 10^3]$ $[7.519 \times 10^{-4}, 1.1987 \times 10^{-3}]$ $[6.3570 \times 10^{-12}, 4.075\,321 \times 10^{-1}]$
$A_{\text{vox}} = \text{dwis}(:, 100, 100, 72);$	$[2.382\,795\,9 \times 10^3, 3.038\,275\,4 \times 10^3]$ $[3.581 \times 10^{-4}, 1.1574 \times 10^{-3}]$ $[-1.100\,992 \times 10^{-1}, 8.292\,790 \times 10^{-1}]$	$[1.834\,553\,3 \times 10^3, 2.823\,978\,4 \times 10^3]$ $[2.4133 \times 10^{-18}, 9.559 \times 10^{-4}]$ $[1.4701 \times 10^{-16}, 6.082\,507 \times 10^{-1}]$
$A_{\text{vox}} = \text{dwis}(:, 40, 100, 72);$	$[3.594\,558\,8 \times 10^3, 3.719\,879\,9 \times 10^3]$ $[8.161 \times 10^{-4}, 1.4039 \times 10^{-3}]$ $[1.422\,03 \times 10^{-2}, 5.577\,154 \times 10^{-1}]$	$[3.595\,613\,0 \times 10^3, 3.717\,932\,7 \times 10^3]$ $[7.755 \times 10^{-4}, 1.2340 \times 10^{-3}]$ $[1.2618 \times 10^{-12}, 3.812\,613 \times 10^{-1}]$
$A_{\text{vox}} = \text{dwis}(:, 77, 95, 72);$	$[8.881\,617\,2 \times 10^3, 9.308\,816\,9 \times 10^3]$ $[3.925\,619 \times 10^2, 2.491\,169\,0 \times 10^3]$ $[-1.854\,952 \times 10^{-1}, 8.549\,589 \times 10^{-1}]$	$[8.884\,371\,4 \times 10^3, 9.300\,580\,9 \times 10^3]$ $[5.570\,198 \times 10^2, 2.645\,003\,5 \times 10^3]$ $[1.582\,78 \times 10^{-2}, 9.016\,526 \times 10^{-1}]$
$A_{\text{vox}} = \text{dwis}(:, 85, 70, 72);$	$[3.038\,514\,0 \times 10^3, 3.211\,936\,7 \times 10^3]$ $[7.177 \times 10^{-4}, 1.5054 \times 10^{-3}]$ $[1.261\,494 \times 10^{-1}, 9.400\,686 \times 10^{-1}]$	$[3.036\,623\,0 \times 10^3, 3.211\,707\,3 \times 10^3]$ $[5.801 \times 10^{-4}, 1.2732 \times 10^{-3}]$ $[6.9531 \times 10^{-12}, 6.744\,089 \times 10^{-1}]$

Table 6: $2 - \sigma$ range and 95% confidence interval for different voxels for the parameters S_0 , d , and f in the *Ball-and-Stick* model for the $A_{\text{vox}} = \text{dwis}(:, 92, 65, 72)$ obtained with the *Classic Bootstrap* algorithm

1.2.2

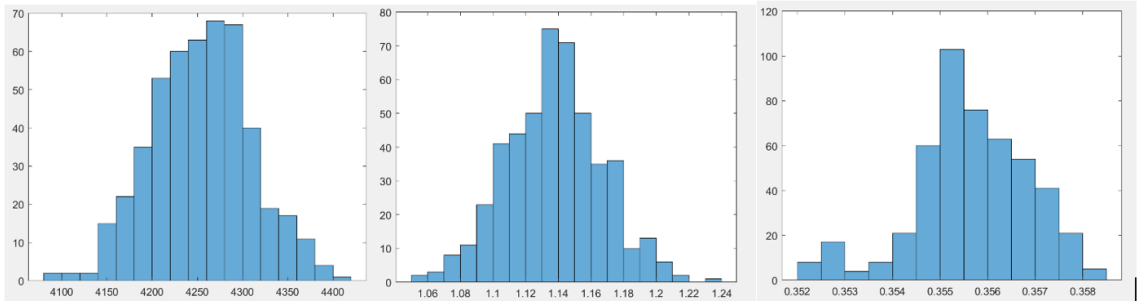


Figure 8: Posterior distributions for the *Metropolis-Hastings MCMC* method for the parameters S_0 (left); d (middle); f (right).

Specification	Value
Number of samples (T)	1000000
Burn in samples	20000
Sampling interval	2000

Table 7: Specifications for the Metropolis-Hastings MCMC algorithm

<i>parameter</i>	$2 - \sigma$	95% <i>range</i>
S_0	[4136.9534103 4363.5615563]	[4100.39516493 4353.303826223]
f	[0.0010846100 0.0012125074]	[0.0010705101 0.0012058503677]
d	[0.3562016184 0.3737022973]	[0.35620452269 0.370940663224]

Table 8: $2 - \sigma$ range and 95% confidence interval for the parameters S_0 , d , and f in the *Ball-and-Stick* model for the $Avox = dwis(:, 92, 65, 72)$ obtained with the *Metropolis-Hastings* algorithm

1.2.3

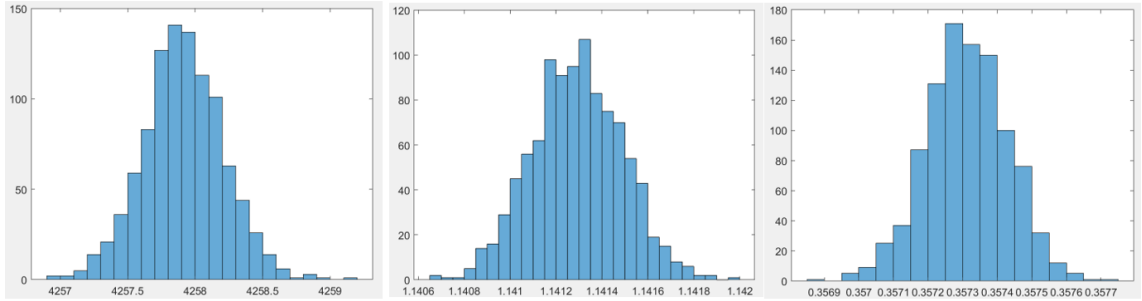


Figure 9: Posterior distributions for the *Parametric Bootstrap* method for the parameters S_0 (left); d (middle); f (right).

1.3

<i>Parameter</i>	$2 - \sigma$	95% range
$S0$	[4257.31 4258.52]	[4257.34 4258.53]
f	[0.001141 0.001142]	[0.001141 0.001142]
d	[0.35707 0.35756]	[0.35708 0.35755]

Table 9: $2 - \sigma$ range and 95% confidence interval for the parameters $S0$, d , and f in the *Ball-and-Stick* model for the $Avox = dwis(:, 92, 65, 72)$ obtained with the *Parametric Bootstrap* method.

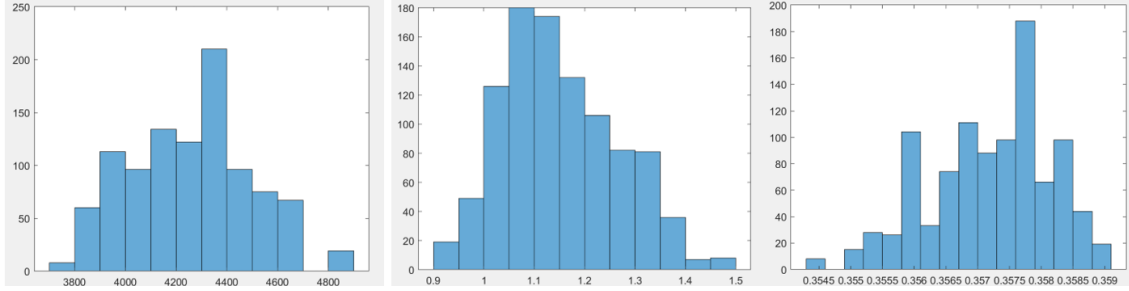


Figure 10: Posterior distributions for the *Residual Bootstrap* method for the parameters $S0$ (left); d (middle); f (right).

<i>Parameter</i>	$2 - \sigma$	95% range
$S0$	[3764.54 4736.79]	[3820.91 4677.33]
f	[0.000922 0.001392]	[0.000977 0.001392]
d	[0.35520 0.35912]	[0.35515 0.35862]

Table 10: $2 - \sigma$ range and 95% confidence interval for the parameters $S0$, d , and f in the *Ball-and-Stick* model for the $Avox = dwis(:, 92, 65, 72)$ obtained with the *Residual Bootstrap* method.

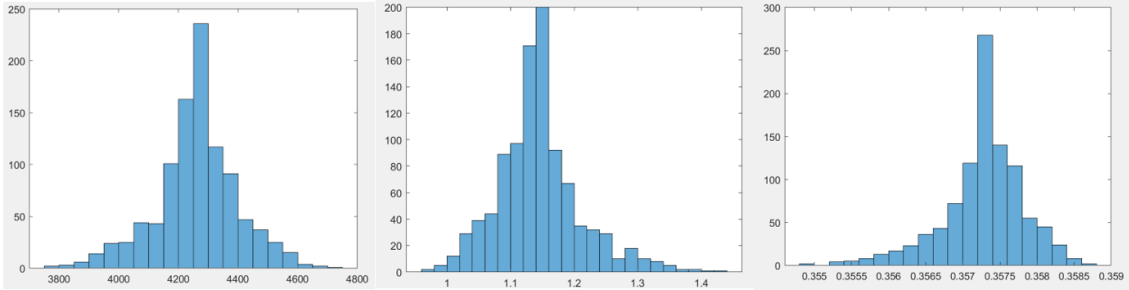


Figure 11: Posterior distributions for the *Wild Bootstrap* method for the parameters $S0$ (left); d (middle); f (right).

<i>Parameter</i>	$2 - \sigma$	95% range
$S0$	[3995.95 4546.48]	[3969.78 4577.72]
f	[0.001011 0.001267]	[0.001010 0.001293]
d	[0.35626 0.35838]	[0.35602 0.35835]

Table 11: $2 - \sigma$ range and 95% confidence interval for the parameters $S0$, d , and f in the *Ball-and-Stick* model for the $Avox = dwis(:, 92, 65, 72)$ obtained with the *Wild Bootstrap* method.

<i>Parameter</i>	$2 - \sigma$
$S0$	[4257.0637 4258.78434]
f	[4.8924×10^{-6} 0.0022874]
d	[0.29421423 0.420405484]

Table 12: $2 - \sigma$ range confidence interval for the parameters $S0$, d , and f in the *Ball-and-Stick* model for the $Avox = dwis(:, 92, 65, 72)$ obtained with the *Laplace Method*.

1.3.1

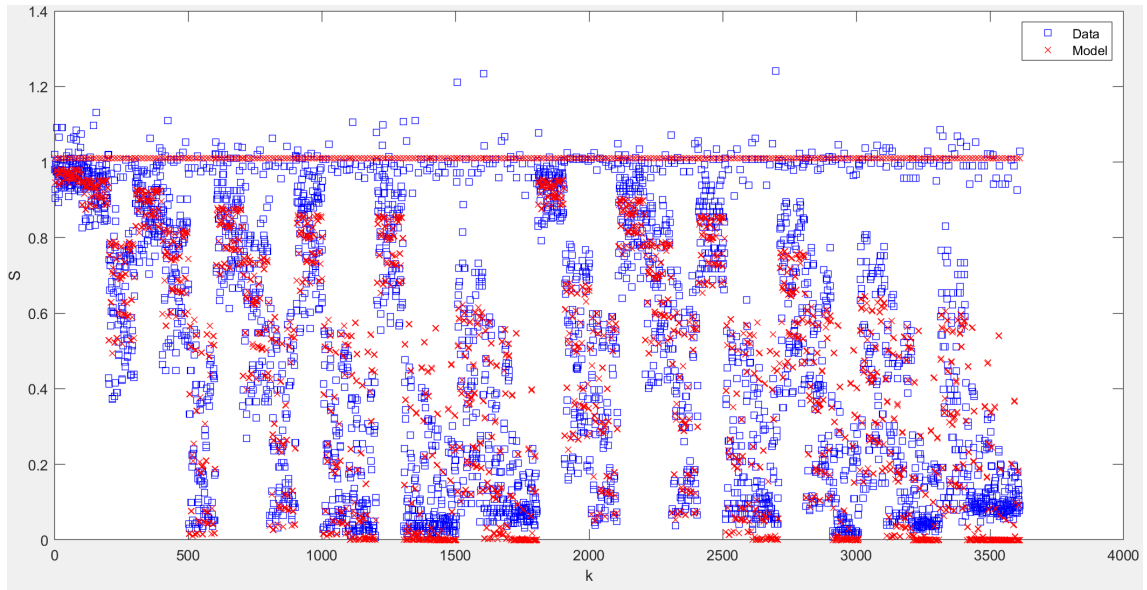


Figure 12: Comparison between the data and the estimated model. The model is the Ball-and-Stick applied to the new data set

parameters	STD noise
S_0	10^1
d	10^{-3}
f	10^{-1}
θ	10^{-1}
ϕ	10^{-1}

Table 13: Chosen STD noise values for each parameter of the Ball-and-Stick model for the new data set

1.3.2

<i>Model</i>	Percentage	Num_runs
Zeppelin-and-Stick	0.993	0.60375
Zeppelin-and-Stick with Tortuosity	0.99800	0.48205

Table 14: Percentage of times the minimum *RESNORM* value was found across all runs from different starting points and number of runs required to be 95% confident in finding the global minimum for the two different models.

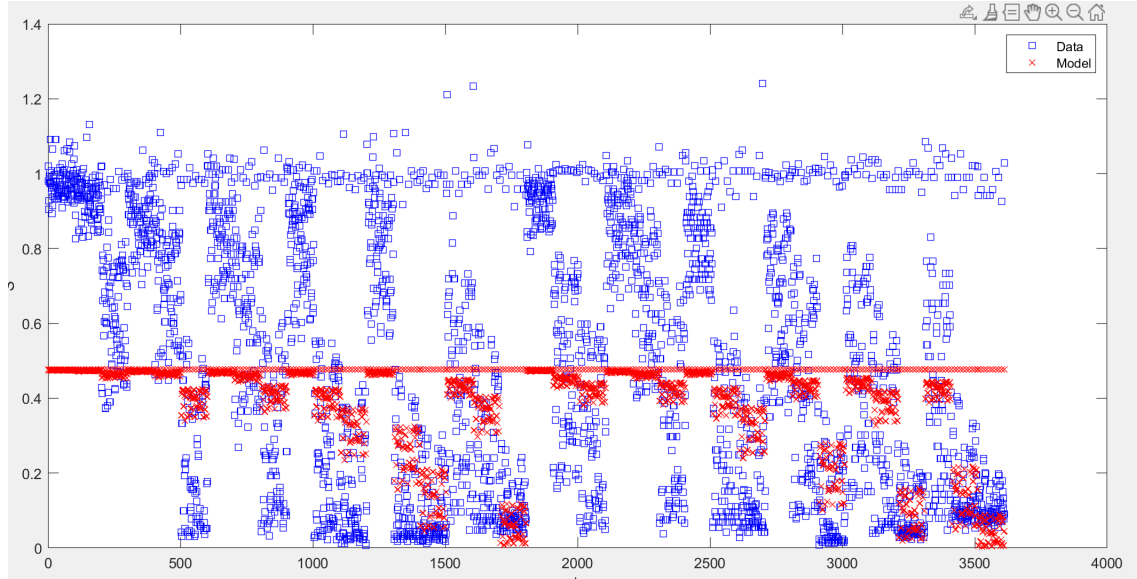


Figure 13: Comparison between the data and the estimated model. The model is the Linear Diffusion Tensor applied to the new data set

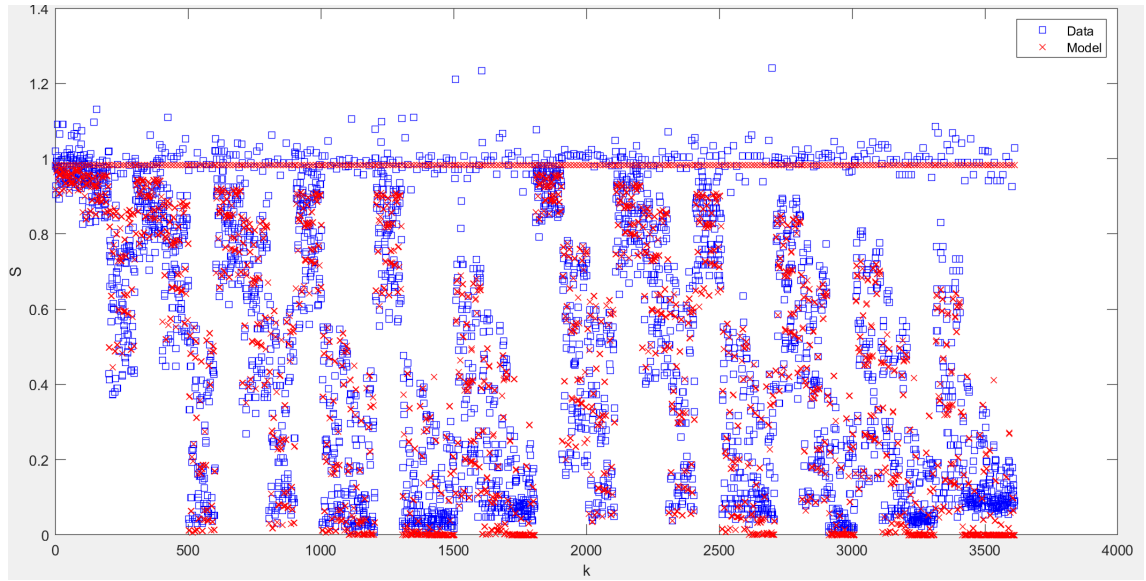


Figure 14: Comparison between the data and the estimated model. The model is the Zeppelin-and-Stick applied to the new data set

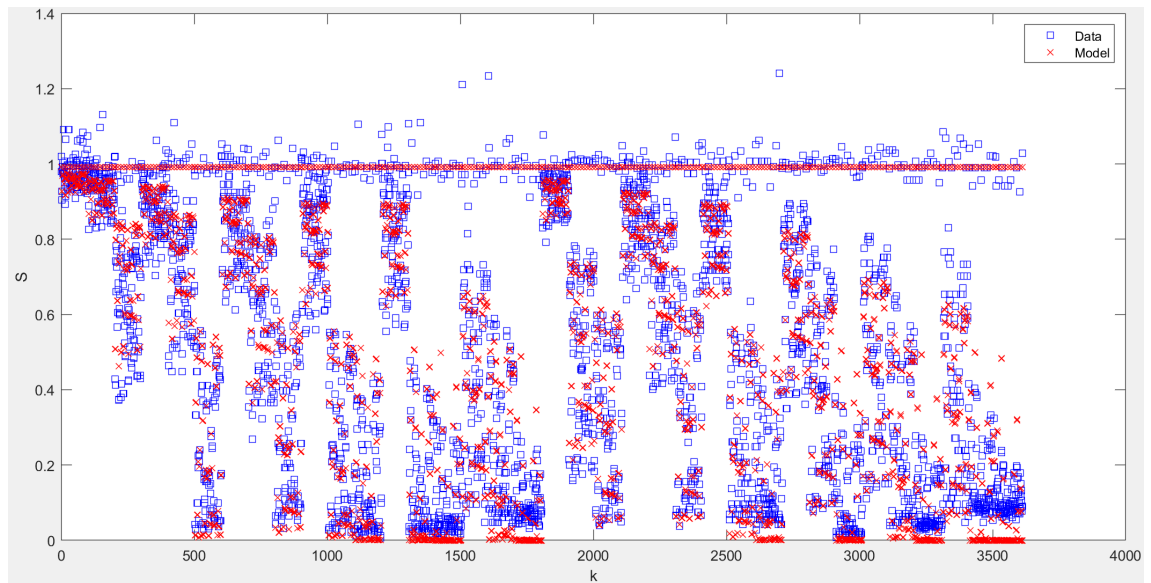


Figure 15: Comparison between the data and the estimated model. The model is the Zeppelin-and-Stick with Tortuosity applied to the new data set

1.3.3

MODEL	AIC	BIC
DT	-8660.48	-8824.21
BS	-19770.65	-19397.98
ZS	-20975.07	-20550.69
ZST	-20722.91	-20300.18

Table 15: AIC and BIC values for different models (DT, BS, ZS, ZST).

1.3.5

MODEL	AIC	BIC
DT	-8660.48	-8824.21
	-8470.49	-8685.83
	-8466.81	-8564.64
	-8610.95	-8774.67
	-8420.96	-8636.30
	-8417.27	-8515.10
BS	-19770.65	-19397.98
	-18768.89	-18387.46
	-19033.09	-19289.12
	-19733.50	-19360.83
	-18731.73	-18350.31
	-18995.93	-19251.97
ZS	-20975.07	-20550.69
	-20122.82	-19263.30
	-20405.68	-20783.56
	-20931.73	-20507.35
	-20079.48	-19219.96
	-20362.33	-20740.22
ZST	-20722.91	-20300.18
	-19743.23	-19048.18
	-19964.16	-20248.77
	-20685.76	-20263.03
	-19706.08	-19011.02
	-19927.01	-20211.62

Table 16: AIC and BIC values for different models (DT, BS, ZS, ZST) for all 6 voxel.

MODEL	VFCV	MCVC	L1OCV
BS constraints	0.1585	0.0811	0.0126
ZS	0.1124	0.0613	0.0090
ZST	0.1210	0.0688	0.0100

Table 17: VFCV, MCVC, and L1OCV values for different models.

1.3.6

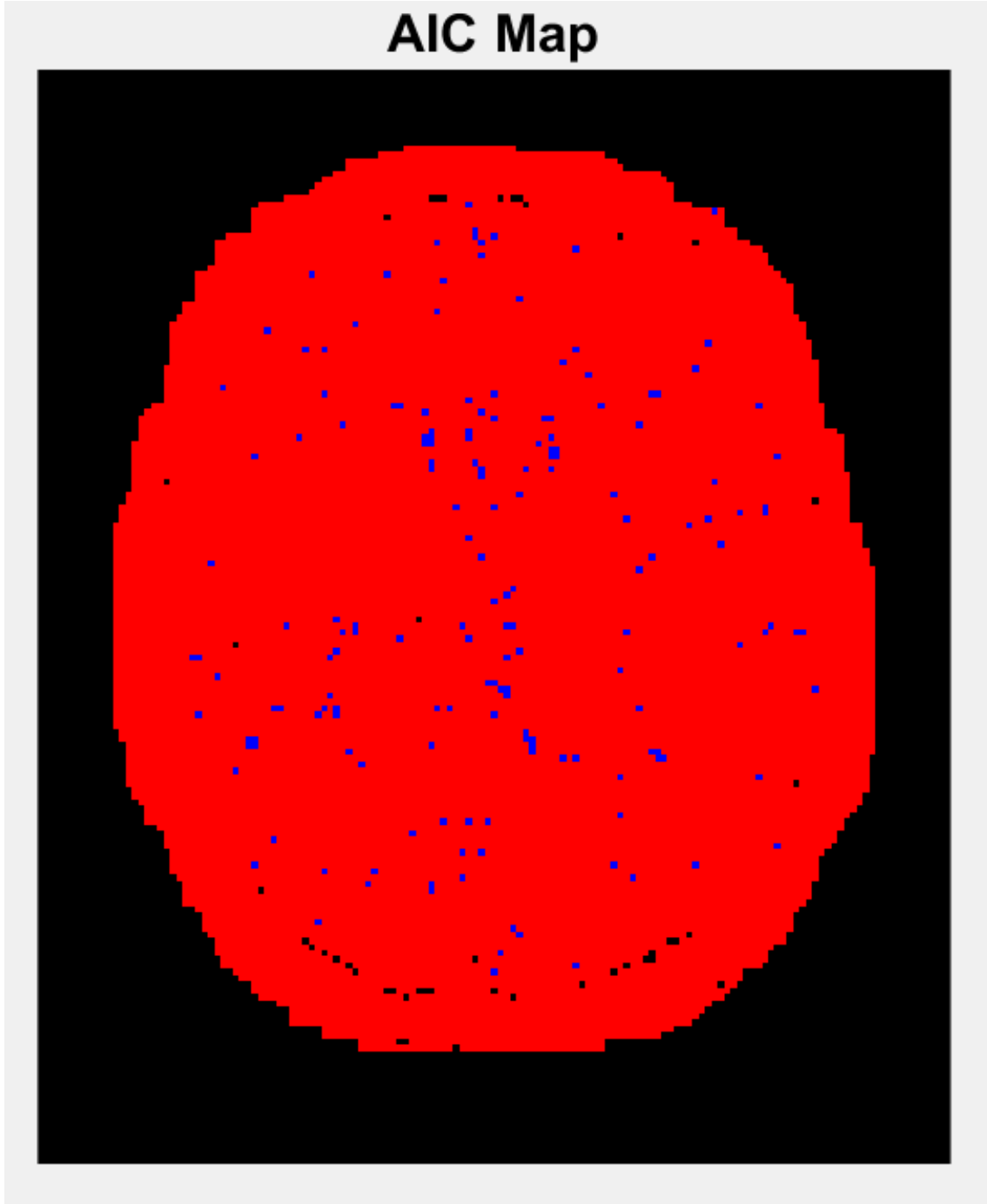


Figure 16: Map of the best model between *Zeppelin-and-Stick*, in blue, and *Zeppelin-and-Stick with Tortuosity*, in red for the 72nd slice of the data set used in sections 1.1 and 1.2

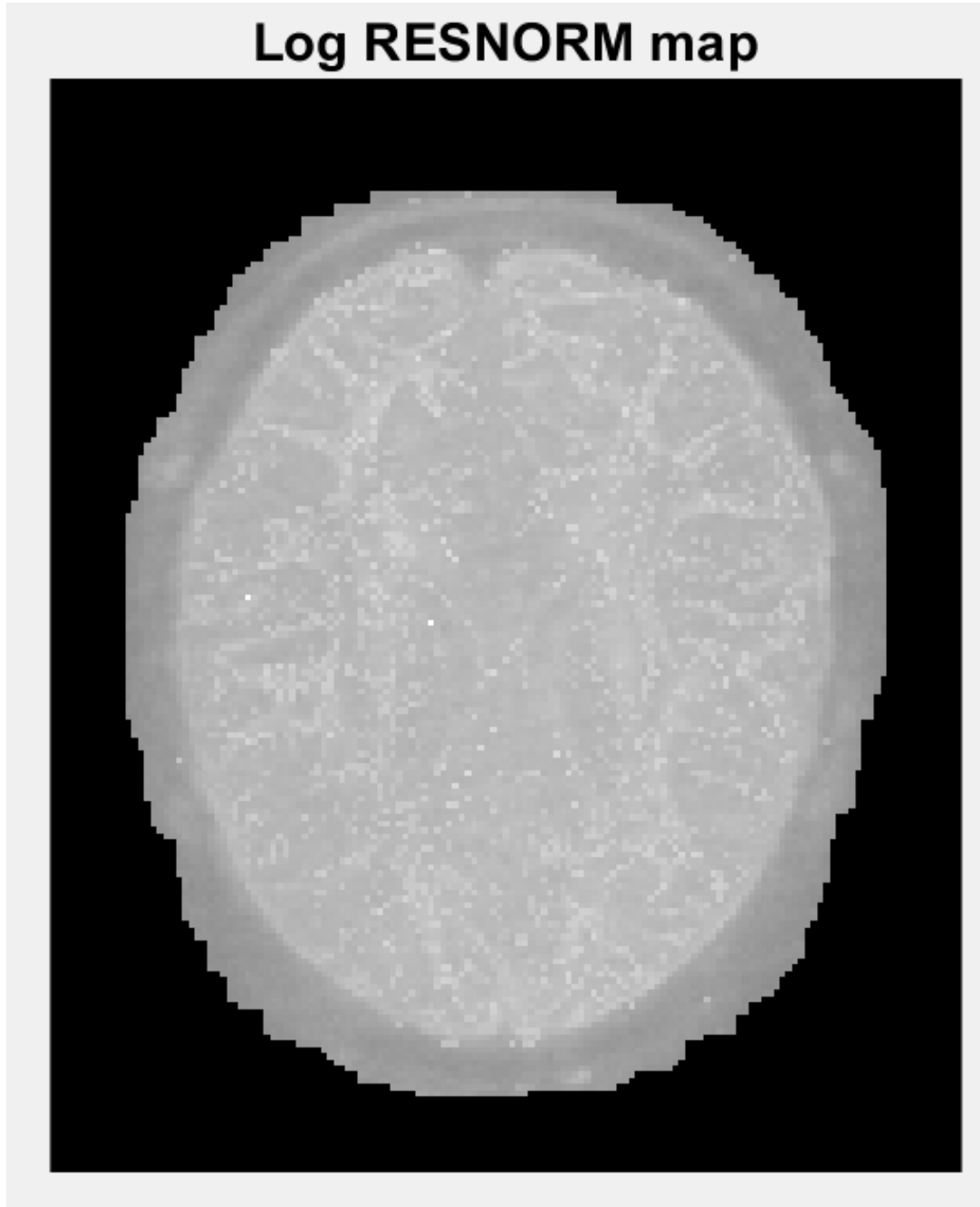


Figure 17: Log of the *RESNORM* map obtained by weighting the estimated signals obtained from different models with the Akaike weights