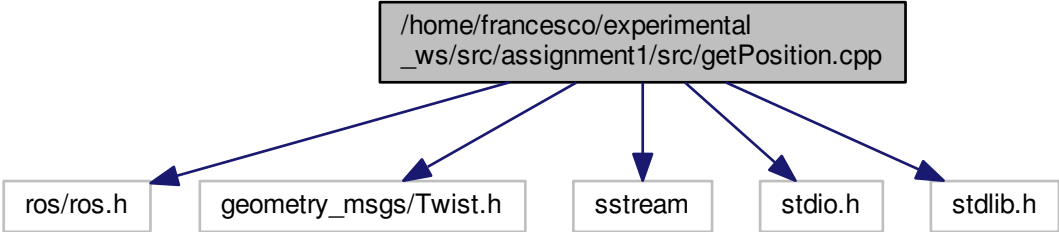


/home/francesco/experimental
_ws/src/assignment1/src/getPosition.cpp



```
graph TD; A["/home/francesco/experimental_ws/src/assignment1/src/getPosition.cpp"] --> B["ros/ros.h"]; A --> C["geometry_msgs/Twist.h"]; A --> D["sstream"]; A --> E["stdio.h"]; A --> F["stdlib.h"];
```

The diagram illustrates the dependencies of the file `/home/francesco/experimental_ws/src/assignment1/src/getPosition.cpp`. It is represented as a central gray box at the top. Five dark blue arrows point downwards from this box to five separate white boxes below it, each representing a dependency. The dependencies are: `ros/ros.h`, `geometry_msgs/Twist.h`, `sstream`, `stdio.h`, and `stdlib.h`.

ros/ros.h

geometry_msgs/Twist.h

sstream

stdio.h

stdlib.h