Reinforcement Learning Hackathon

Team: Mesa-optimizers
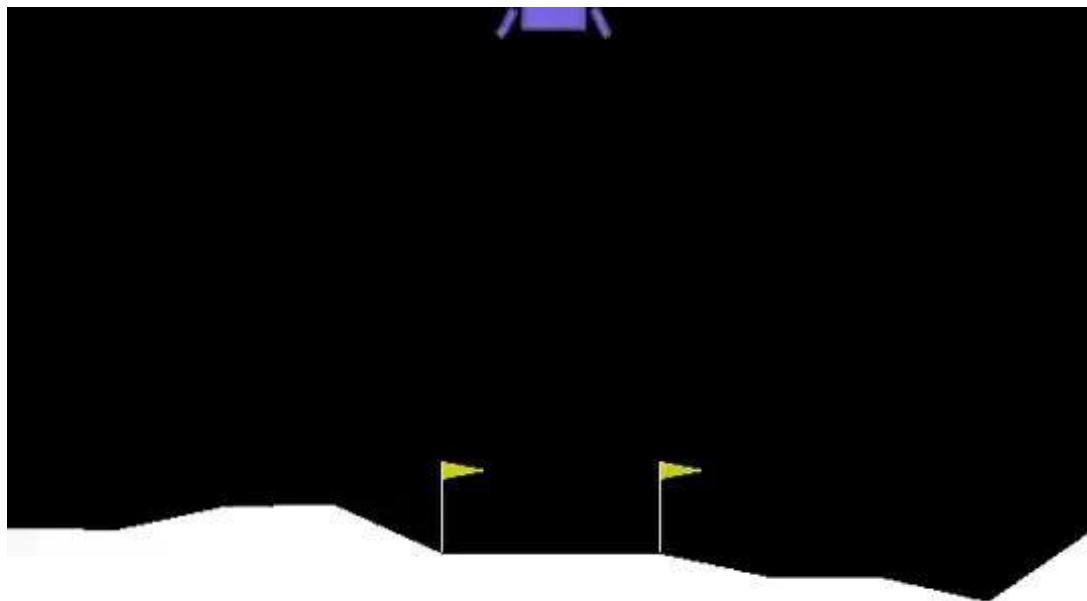
Francisco Enguix
Areg M. Sarvazyan

DEEP
LEARNING
LABS
by Nextgrid

DigitalOcean

NEXTGRID

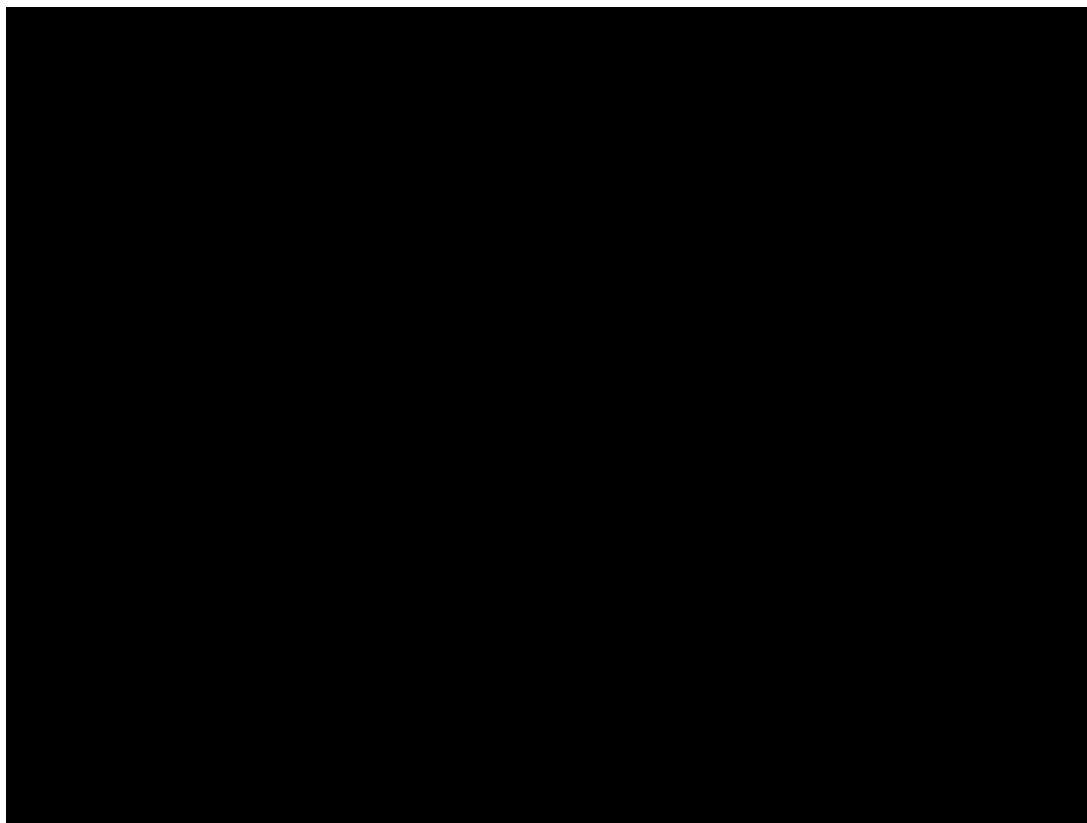# Lunar Lander

Experimented with:

- A2C

- DQN
    - Better performance

Cartpole

- Tried DQN
    - Based on
      Lunar
      Lander
      Results

Bipedal Walker

- TQC