► Question 1. Write the initialization code.		
▶ Question 2. When are error messages appearing? Clue: look at the program return code, that is located at the end of the handler (there is a comment ## Return to program). Is the return to program code correct?		
▶ Question 3. Write the intruction line append to the program.		
► Question 4. Why so many asterisks appear when pressing a key?		
► Question 5. Write the instruction lines added to cancel the keyboard interrupt.		
, and the second		
► Question 6. Why the user program ends before expected when a key is pressed? Clue: The handler changes register \$t0 that is used inside the user program loops.asm.		

At the beginning of the handler code, where it says "save the user program context", write intructions that save the four register former mentioned into context, as shown igure 7. At the end of the handler code, where it says "restore the context", write the code the eads the context content and copies it back to the registers.
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▶ With the simulator: Check if the system works.

_	lestion 8. With the text editor open <i>keyboard.handler</i> and save it as <i>rd_and_clock.handler</i> .
•	In the starting code add the instructions that enable the clock interrupt.
•	Change the coprocessor state register to set the interrupt line <i>int2*</i> unmasked.
	the simulator: Check the system. If the clock interrupt has been enabled properly the will show asterisks without stopping.
_	stion 9. Explain why the system behaves as described previously. Clue: is the clock t cancelled somewhere on the hadler?
► Que	stion 10. With the text editor modify keyboard_and_clock.handler file.
•	Add a new tag (in figure 9 appears as retexc) that will mark the point on the handler that restores the context and gives the control back to the interrupted program. From now, jumping to this tag inside the handler will be the same as <i>ending</i> .
•	Add a new tag int0 to apply the handling that from steps 4 and 5 are applied to the keyboard interrupt. At the end of the interrupt handling we have to add a jump to <i>ending</i> .

•	Add a tag int2 followed by the clock interrupt handling that will be just cancelling the interrupt on the interface avoiding to unable the interrupt. Don't forget jumping to <i>ending</i> .
,	Add the instructions that will read and analyse the exception cause word from the exception coprocessor (the cause word explanation is on appendix 2) in the section marked with "## Identify and handle exceptions". If the cause is an interrupt the analysis will continue, otherwise a jump will be done to <i>ending</i> .
	Once it has been identified that the cause of a given exception is an interrupt, what remains is to add the instructions that will analyse bits <i>IPO</i> and <i>IP2</i> from the state word in the exception coprocessor followed by a jump to tags int0 e int2., respectively. If none of these bits is active then jump to <i>ending</i> .
k	e carea ll the time over the registers used by the handler. In step 5 we have written the code

- ▶ Take carea ll the time over the registers used by the handler. In step 5 we have written the code that saves and restores registers \$at, \$t0, \$v0 and \$a0. You can restrict yourself to use only those four registers on the handler, or you can use other registers like (like \$t1) if so you have to get aware that the context variable size should be increased to get space for those extra registers.
- ▶ With the simulator, check the system. If everything is fine, it will appear on the console one and only one "*" every time a key is pressed; the user program will smoothly end when the time comes.