Topic 5

Priority Queue and Heap. Heap Sort

Aim

- Presentation of an efficient implementation of the model Priority Queue
- Representation of the data with an array: Binary Heap
- Design of the generic sorting method Heap Sort

Contents

- 1. Introduction
- 2. Binary Heap
 - Characteristics
 - Properties
 - Array representation of a complete binary tree
- 3. The class *MonticuloBinario* (Heap)
- 4. Fast sorting with *Heap Sort*

1. Introduction

The model Priority Queue

 The Priority Queue (Cola de Prioridad) is a model for a data collection that allows to access to the element of highest priority:

```
public interface ColaPrioridad<E extends Comparable<E>>> {
    // Insert x in the queue
    void insertar(E x);
    // IFF !esVacia(): if not empty return the element with highest
priority
    E recuperarMin();
    // IFF !esVacia(): return and delete the element with highest
priority
    E eliminarMin();
    // Return true if the queue is empty
    boolean esVacia();
```

Characterisics

- Implementation based on an array
- The average cost of *insertar* is constant and logarithmic (worst case)
- The average cost of *eliminarMin* is logarithmic (also in the worst case)
- The cost of recuperarMin is constant

Properties

Structural property: a heap is a complete binary tree

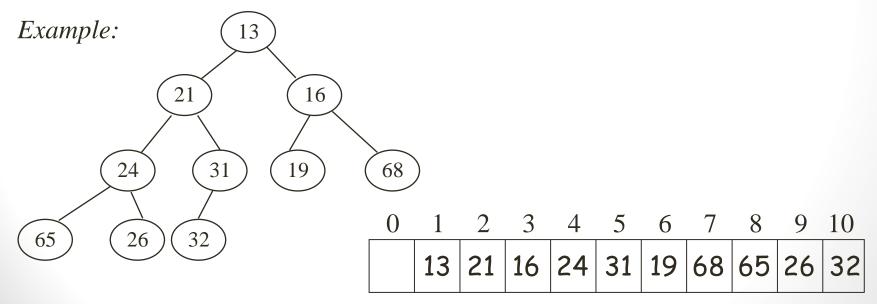
- o Its height is maximum: Llog₂N J
- The cost of the algorithms is in the worst case logarithmic
- The complete binary trees allow for an array representation

Sort property:

 In a min-heap, the element of a node is always smaller or equal than its children

Array representation of a complete binary tree

- Data stored in an array following the traversal by level
- The root is in the position 1

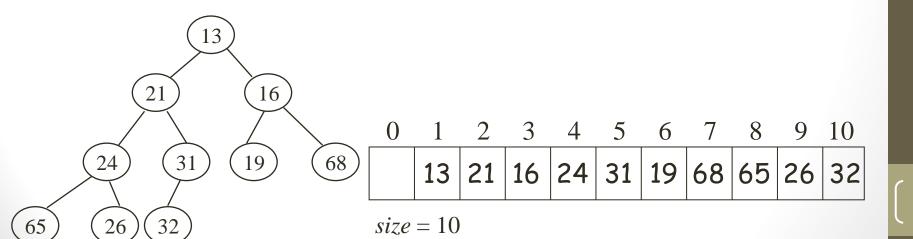


size = 10

7

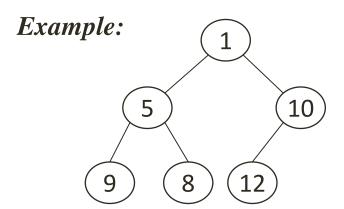
Implicit representation

- O Give the i-th node:
 - Position of its left child: 2*i (if 2*i ≤ size)
 - Position of its right child: 2*i+1 (if 2*i+1 ≤ size)
 - Position of its father: i/2 (if $i \neq 1$)



Properties

- Every path from the root to a leaf is sorted sequence:
 - **1**, 5, 9
 - **1**, 5, 8
 - **1**, 10, 12
- The root is the node with the smallest element (or greatest in a Max-Heap)
- Each subtree of a Heap is also an Heap



0	1	2	3	4	5	6	7	
	1	5	10	9	8	12		•••

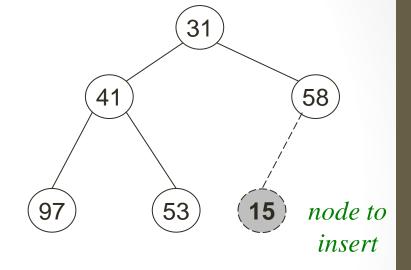
$$size = 6$$

Attributes and constructor

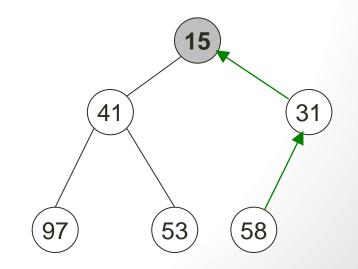
```
public class MonticuloBinario<E extends Comparable<E>>
       implements ColaPrioridad<E> {
  // Attributes
  protected static final int CAPACIDAD INICIAL = 50;
  protected E elArray[];
  protected int talla;
  // Constructor of an empty min-heap
 @SuppressWarnings("unchecked")
  public MonticuloBinario() {
    talla = 0;
    elArray = (E[]) new Comparable[CAPACIDAD_INICIAL];
```

The method insertar (1/3)

• Step 1: the new element is inserted in the first available position of the array:
elArray[talla + 1]



 Step 2: the new element is compared with its predecessors and moved in order to have the sort property accomplished



3. The class *MonticuloBinario*The method insertar (2/3)

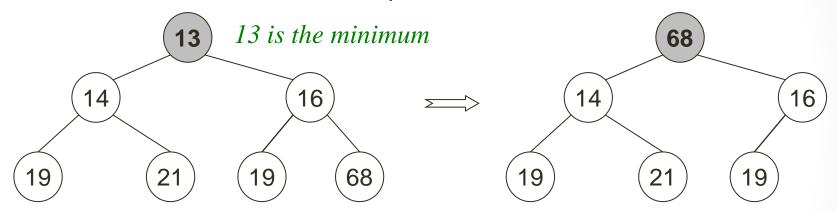
```
public void insertar(E x) {
  // do we have space in the array for another element?
  if (talla == elArray.length - 1) duplicarArray();
  // hole is the position where x will be inserted
  int hole = ++talla;
  // it is moved in order to have the sort property
 accomplished
  while (hole > 1 && x.compareTo(elArray[hole/2]) < 0) {</pre>
    elArray[hole] = elArray[hole/2];
    hole = hole/2;
  // now we know in what position to insert the new
 element
  elArray[hole] = x;
```

3. The class *MonticuloBinario*The method insertar (3/3)

- Worst case: the complexity is O(log₂N) if the added element is the new minimum
- Best case: when the element to insert is greater than its father (only one comparison)
- It has been empirically proofed that on average 2.6 comparisons are needed to insert a new element (constant complexity)

The method eliminarMin (1/3)

 Step 1: the minimum is in the root. The root is substituted by the last element of the Heap



Step 2: the new root is moved down via its children in order to accomplish the sort property:

The method eliminarMin – heapify (2/3)

• The method heapify (hundir):

```
private void heapify(int hole) {
  E aux = elArray[hole];
  int child = hole * 2;
  boolean isHeap = false;
  while (child <= talla && !isHeap) {</pre>
    if (child != talla &&
        elArray[child+1].compareTo(elArray[child]) < 0)
        child++; // We choose the smalles of the two children
    if (elArray[child].compareTo(aux) < 0) { // we move down</pre>
      elArray[hole] = elArray[child];
      hole = child;
      child = hole*2;
    } else isHeap = true; // The sort property is accomplished
  elArray[hole] = aux;
```

3. The class *MonticuloBinario*The method eliminarMin (3/3)

```
// IFF !esVacia(): delete and return the smallest element
public E eliminarMin() {
  E theMin = recuperarMin();
  // the root is substituted with the last element
  elArray[1] = elArray[talla--];
  // the new root is moved down (sort property)
  heapify(1);
  return theMin;
// IFF!esVacia(): return the smallest element
public E recuperarMin() {
  return elArray[1];
```

3. The class *MonticuloBinario*The method buildHeap (arreglarMonticulo)

- Given a complete binary tree it allows to accomplish the sort property
- It moves down all nodes in an inverse order wrt traversal by levels

```
private void buildHeap() //arreglarMonticulo
{
for (int i = talla / 2; i > 0; i--)
    heapify(i);
}
```

The method buildHeap (arreglarMonticulo)

It has linear time complexity:

Leaves have height 0 and the root height $\lfloor \log_2 n \rfloor$

There $ar e log_2 n - h$ nodes at height h

The cost of heapify a node at height h is $\Theta(h)$

$$\begin{split} &\mathsf{T}_{\mathsf{arreglarMonticulo}}(\mathsf{n}) = \sum_{h=0}^{\lfloor \log_2 n \rfloor} h \cdot 2^{\lfloor \log_2 n \rfloor - h} = \\ &\sum_{h=0}^{\lfloor \log_2 n \rfloor} h \cdot \frac{2^{\lfloor \log_2 n \rfloor}}{2^h} \leq \sum_{h=0}^{\lfloor \log_2 n \rfloor} h \cdot \frac{2^{\log_2 n}}{2^h} = \sum_{h=0}^{\lfloor \log_2 n \rfloor} h \cdot \frac{n}{2^h} = \\ &\mathsf{n} \cdot \sum_{h=0}^{\lfloor \log_2 n \rfloor} \frac{h}{2^h} \leq \mathsf{n} \cdot \sum_{h=0}^{\infty} \frac{h}{2^h} = 2 \cdot n \in \Theta(\mathsf{n}) \end{split}$$

4. HeapSort

Fast sorting with HeapSort

- The cost of HeapSort is O(N*log₂N)
 - QuickSort has a complexity O(N²) as worst case
 - MergeSort needs an auxiliar array
- This algorithm is based on the properties of a heap
 - First step: all the elements of an array to be sorted are stored in a heap
 - <u>Second step</u>: the smallest element is extracted (root) in an iterative way

4. HeapSort

Insertion of the data of an array in a Heap

 The most efficient way to insert the data of an array in a Heap is with the method arreglarMonticulo (buildHeap):

 The cost of the constructor is O(N), where N is the size of the array

4. HeapSort

Algorithm

```
public class Ordenacion {
   public static <E extends Comparable<E>> void heapSort(E v[]) {
      // Creating the heap from the array
      MonticuloBinario<E> heap = new MonticuloBinario<E>(v);
      // Extracting data from the heap in a sorted way
      for (int i = 0; i < v.length; i++)
      v[i] = heap.eliminarMin();
   }
}</pre>
```

Ocost HeapSort = cost constructor + N * cost of eliminarMin

```
T_{\text{heapSort}}(N) \in O(N) + N*O(log_2N) = O(N*log_2N)
```

Cost HeapSort to sort only the first k elements of the array:
 O(N + k*log₂N)

References

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