

Trabalho Final

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Tema - Alice no País das Maravilhas



Tema - Outras Ideias



Objetos

```
14 inds = []
15 objs = ['parede.obj', 'chao.obj', 'mesa.obj', 'xicara.obj', 'porta.obj', 'grama.obj', 'estrada.obj', 'carta.obj', 'cogumelo.obj', 'lagarta.obj', 'ceu.obj' ]
16 teks = ['parede_3.jpg', 'chao.png', 'mesa.png', 'xicara.jpg', 'porta.jpg', 'grama.jpg', 'estrada.jpg', 'carta.jpg', 'cogumelo.jpg', 'lagarta.jpg', 'ceu.jpg' ]
17 poss = [(0,0,0), (0,0,0), (15,0,0), (18.5,6.3,0), (0,30,0), (-30,30,0), (0,0,-90), (-5,0,-70), (10,40,1), (-15,35,1), (0,0,-45) ]
18 scas = [(30,30,30), (30,30,30), (4,4,4), (0.5,0.5,0.5), (0.01,0.01,0.01), (2,2,2), (5,5,5), (5,5,5), (1,1,1), (3,3,3), (30,30,30) ]
19 rots = [(0,1,0), (0,1,0), (0,1,0), (0,1,0), (-1,0,0), (-1,0,0), (0,1,0), (0,1,0), (0,1,0), (-1,0,0), (-1,0,0), (0,1,0), (0,1,0) ]
20 ang = [ 0, 0, 0, 0, 90, 90, 0, 0, 0, 90, 90, 0, 1 ]
21
22
```

```
164 for obj in objs:
165     m = load.load_model(obj)
166     inds.append( add_model(m))
167
168     i = 0
169     for t in teks:
170         load.load_texture(i,t)
171         i+=1
172
```

```
132 for i in range(len(objs)):
133     px,py,pz = poss[i]
134     rx,ry,rz = rots[i]
135     sx,sy,sz = scas[i]
136     ang = ang[i]
137     mat_model = matrix.model(ang,rx,ry,rz,px,py,pz,sx,sy,sz)
138     desenha_obj(mat_model,i,inds[i])
139
```


Movimentação

```
30 # aperta A
31 if key == 65:
32     ang -= math.pi/30
33 # aperta D
34 if key == 68:
35     ang += math.pi/30
36 cos = math.cos(ang)
37 sin = math.sin(ang)
38 matrix.cameraFront = glm.vec3(sin, 0.0, -cos);
39
40 # aperta W
41 if key == 87 and not collision(1):
42     matrix.cameraPos += matrix.cameraFront * speed
43 # aperta S
44 if key == 83 and not collision(-1):
45     matrix.cameraPos -= matrix.cameraFront * speed
46
```

```
17 def collision(direction):
18     x = matrix.cameraPos[0] + matrix.cameraFront[0]*direction
19     w = matrix.cameraPos[2] + matrix.cameraFront[2]*direction
20     if inside:
21         return x > 29 or x < -29 or w > 29 or w < -29
22     else:
23         return x > 4 or x < -4 or w < -70 or w > -31
24
```


Eventos

```
10 def close(x,z):
11     return (abs(cameraPos[0] - x) < 3) and (abs(cameraPos[2] - z) < 3)
12
```

```
47 #aperta Z
48 if key == 90 and not colision(5):
49     zoom_begin = time.time()
50     zoom_pos = matrix.cameraPos
51     zooming = True
52
```

```
53 # aperta espaço
54 # bebe chá
55 if key == 32 and matrix.close(18.5,0):
56     matrix.cameraPos[1] = 1
57     speed = 0.2
58     small = True
59 if action == 1:
60     # sair pela porta
61     if key == 32 and matrix.close(0,-28) and small and inside:
62         matrix.cameraPos[0] = 0
63         matrix.cameraPos[2] = -32
64         inside = False
65         return
66     # entrar pela porta
67     if key == 32 and matrix.close(0,-32) and small and not inside:
68         matrix.cameraPos[0] = 0
69         matrix.cameraPos[2] = -28
70         inside = True
71         return
```


Animação

```
14 inds = []
15 objs = ['parede.obj', 'chao.obj', 'mesa.obj', 'xicara.obj', 'porta.obj', 'grama.obj', 'estrada.obj', 'carta.obj', 'cogumelo.obj', 'lagarta.obj', 'ceu.obj']
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17 poss = [(0,0,0), (0,0,0), (15,0,0), (18.5,6.3,0), (0,30,0), (-30,30,0), (0,0,-90), (-5,0,-70), (10,40,1), (-15,35,1), (0,0,-45)]
18 scas = [(30,30,30), (30,30,30), (4,4,4), (0.5,0.5,0.5), (0.01,0.01,0.01), (2,2,2), (5,5,5), (5,5,5), (1,1,1), (3,3,3), (30,30,30)]
19 rots = [(0,1,0), (0,1,0), (0,1,0), (0,1,0), (-1,0,0), (-1,0,0), (0,1,0), (0,1,0), (-1,0,0), (-1,0,0), (0,1,0)]
20 angs = [0, 0, 0, 0, 90, 90, 0, 0, 90, 90, 1]
21
22
```

```
104 def animation():
105     t = time.time() - begin
106     ft = 1+0.3*math.cos(t)
107     scas[8] = (1,ft,ft)
108
109     if keys.zooming:
110         t = 2*(time.time() - keys.zoom_begin)
111         ft = math.sin(t)
112         matrix.camera_ang = 45 + ft*10
113         matrix.cameraPos = keys.zoom_pos + ft*5*matrix.cameraFront
114         if t >= (math.pi):
115             keys.zooming = False
116             matrix.camera_ang = 45
117             matrix.camera_pos = keys.zoom_pos
118
```


Obrigado!

