

Examples: Subspaces

Let S and T be two sets. By $S \cap T$, we mean the intersection of S and T , the set of all elements common to S and T . By $S \cup T$, we mean the union of S and T , the set of all elements which are in at least one of S and T .

Theorem: The intersection of two subspaces S and T of a vector space V is also a subspace of V .

Proof: Since S and T are subspaces of V , they are non-empty and clearly $0 \in S$ and $0 \in T$. Therefore, $0 \in S \cap T$ and hence $S \cap T \neq \emptyset$.

Now let $u, v \in S \cap T$ then $u, v \in S$ and $u, v \in T$. Since S and T are subspaces of V , $u, v \in S$ implies that $\alpha u + \beta v \in S$ where $\alpha, \beta \in F$. Similarly $u, v \in T$ implies that $\alpha u + \beta v \in T$ where $\alpha, \beta \in F$.

Hence, $u, v \in S \cap T$ implies that $\alpha u + \beta v \in S \cap T$ for $\alpha, \beta \in F$.

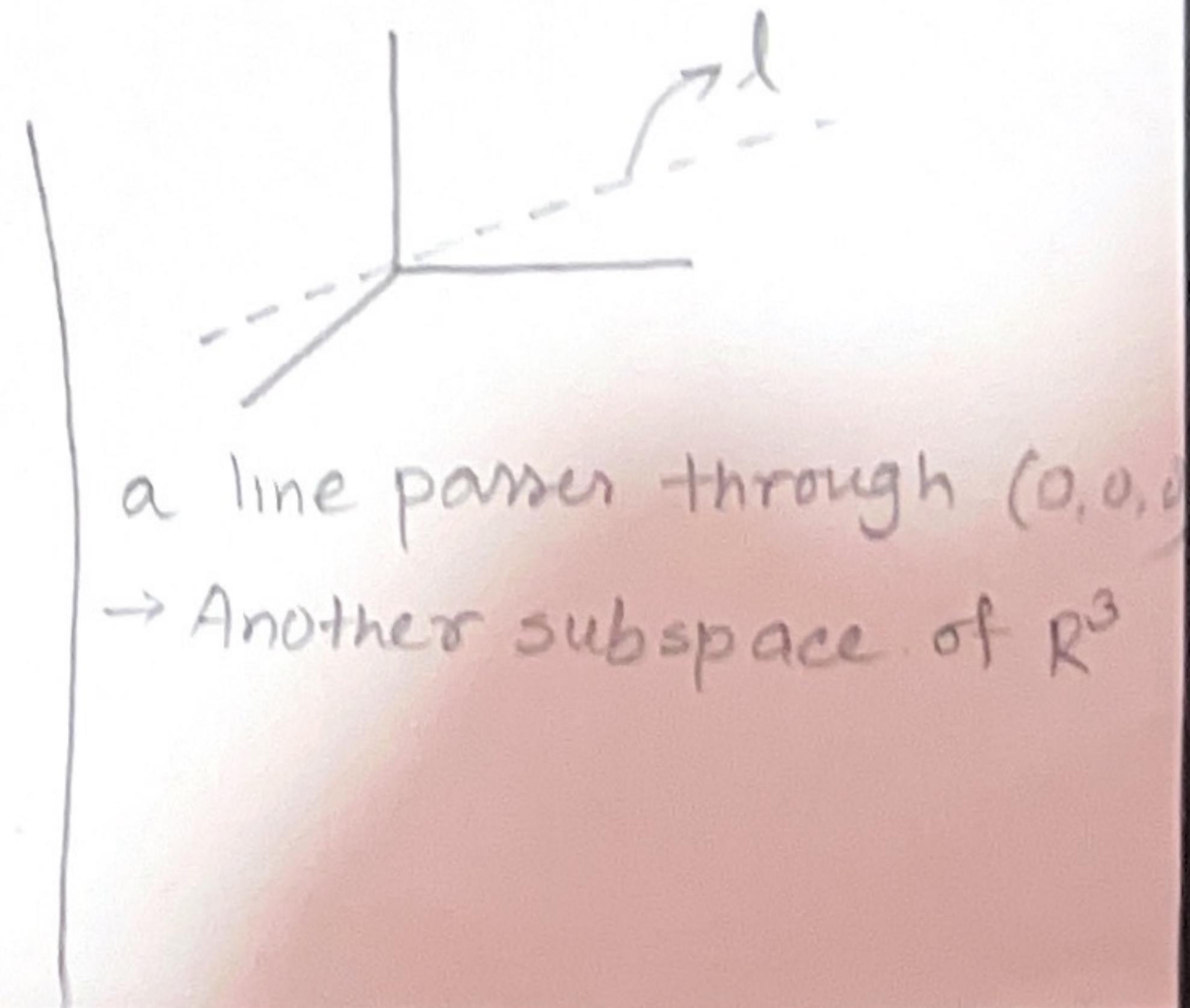
Therefore, $S \cap T$ is a subspace of the vector space V .

Note that the union of S and T is not a subspace of V unless $S \subseteq T$ or $T \subseteq S$.

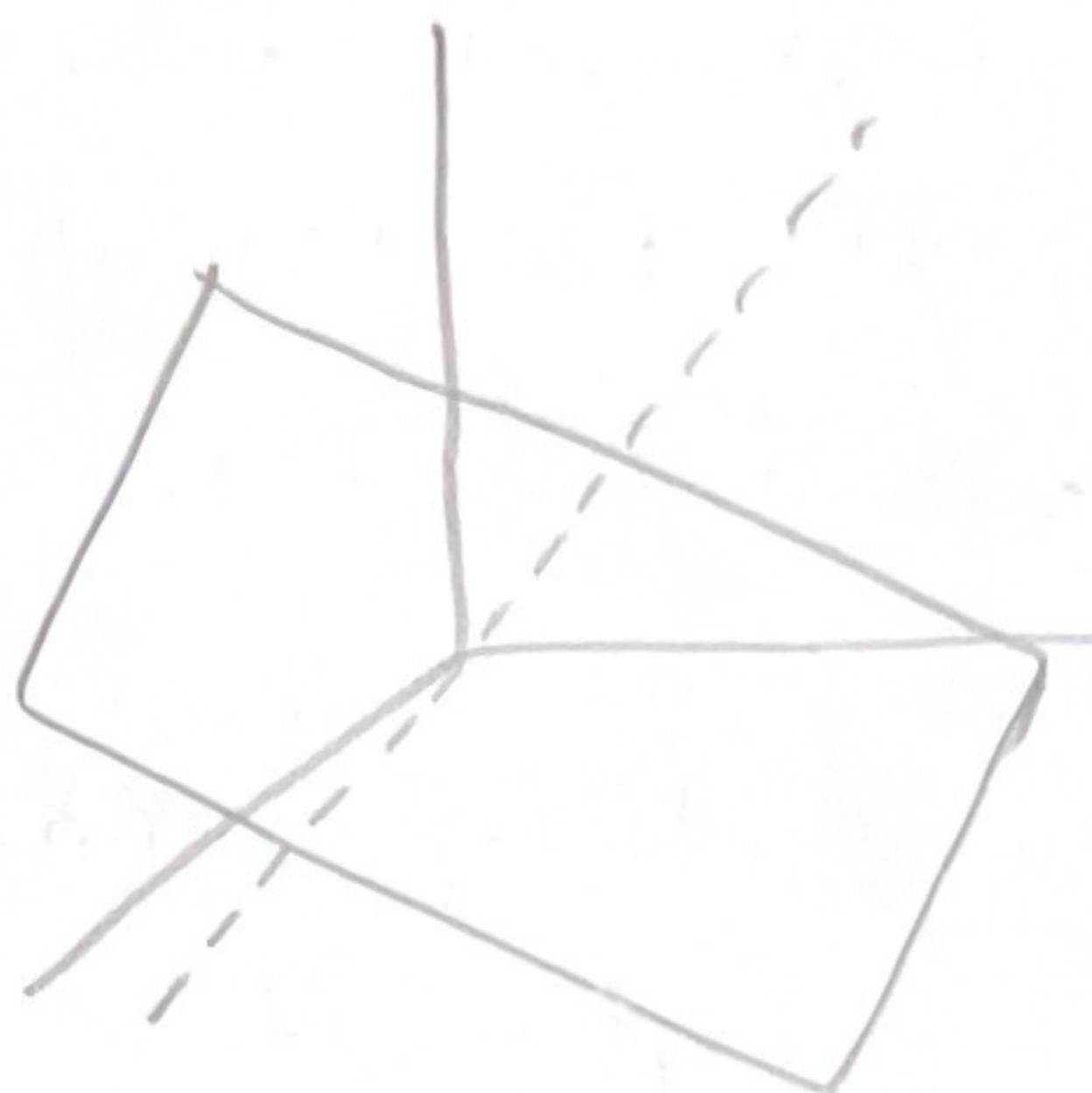


Plane passes through the origin \Rightarrow is a subspace of \mathbb{R}^3

- ① two vectors on the plane, result is on the plane
- ② multiplied by a negative of a vector is on the plane



Take two subspaces and put them together. Take union.



$P \cup L$ = all vectors in P or L or both.

Take the vectors in the plane and also the vectors on that line, put them together \Rightarrow addition goes somewhere else
(Remember: most of the vectors are not on the line or in that plane) \Rightarrow not in plane or not on the line \Rightarrow not a subspace. $P \cup L$.

$P \cap L$ = all vectors in P and L : In picture, it's only zero vector \Rightarrow subspace because zero vector by itself is a subspace.

Remark: Vector space requirements.

- ① $v+w$ and $c v$ are in the space.

* Show that $V = \{(a, b, c, d) \in \mathbb{R}^4 : 2a - 3b + 5c - d = 0\}$ is a subspace of \mathbb{R}^4 .

Solution: For $\underline{0} \in \mathbb{R}^4$, $\underline{0} = (0, 0, 0, 0) \in V$ since $2 \cdot 0 - 3 \cdot 0 + 5 \cdot 0 - 0 = 0$

Hence V is non-empty.

Let $\underline{u} = (a, b, c, d)$ and $\underline{v} = (a_1, b_1, c_1, d_1) \in V$

so, $2a - 3b + 5c - d = 0$ and $2a_1 - 3b_1 + 5c_1 - d_1 = 0$

For any scalars $\alpha, \beta \in \mathbb{R}$

$$\begin{aligned}\alpha \underline{u} + \beta \underline{v} &= \alpha(a, b, c, d) + \beta(a_1, b_1, c_1, d_1) \\ &= (\alpha a + \beta a_1, \alpha b + \beta b_1, \alpha c + \beta c_1, \alpha d + \beta d_1)\end{aligned}$$

$$\begin{aligned}\text{Also, } 2(\alpha a + \beta a_1) - 3(\alpha b + \beta b_1) + 5(\alpha c + \beta c_1) - (\alpha d + \beta d_1) \\ &= (2\alpha a - 3\alpha b + 5\alpha c - \alpha d) + (2\beta a_1 - 3\beta b_1 + 5\beta c_1 - \beta d_1) \\ &= \alpha \cdot 0 + \beta \cdot 0 \\ &= 0\end{aligned}$$

Therefore, $\alpha \underline{u} + \beta \underline{v} \in V$ and so V is a subspace of \mathbb{R}^4 .

* $V = \{(a, b, c) | a, b, c \in \mathbb{R} \text{ and } a - 2b + 3c = 5\}$ is not a subspace of \mathbb{R}^3 .

Solution: $\underline{0} \in \mathbb{R}^3$, $\underline{0} = (0, 0, 0) \notin V$, since $0 - 2 \cdot 0 + 3 \cdot 0 = 0 \neq 5$.
So, V is not a subspace of \mathbb{R}^3 .

* Let V be a vector space of all 2×2 matrices over the real field \mathbb{R} . Show that W is not a subspace of V where

- (i) W consists of all matrices with zero determinant
- (ii) W consists of all matrices A for which $A^2 = A$.

Solution: Take $A = \begin{pmatrix} 0 & 0 \\ 1 & 0 \end{pmatrix}$, $B = \begin{pmatrix} 0 & 1 \\ 0 & 0 \end{pmatrix}$

Since, $|A| = |B| = 0$, $\therefore A, B \in W$.

Now, $A+B = \begin{pmatrix} 0 & 1 \\ 1 & 0 \end{pmatrix}$; $|A+B| = -1 \neq 0 \notin W$.

Hence, W is not a subspace of V .

(ii) Take $A = \begin{pmatrix} 1 & 0 \\ 0 & 1 \end{pmatrix}$ where $A^2 = \begin{pmatrix} 1 & 0 \\ 0 & 1 \end{pmatrix} \cdot \begin{pmatrix} 1 & 0 \\ 0 & 1 \end{pmatrix} = \begin{pmatrix} 1 & 0 \\ 0 & 1 \end{pmatrix}$

$\therefore A^2 = A$, $A \in W$.

Now, $2A = \begin{pmatrix} 2 & 0 \\ 0 & 2 \end{pmatrix}$ so, $(2A)^2 = \begin{pmatrix} 2 & 0 \\ 0 & 2 \end{pmatrix} \begin{pmatrix} 2 & 0 \\ 0 & 2 \end{pmatrix} = \begin{pmatrix} 4 & 0 \\ 0 & 4 \end{pmatrix} \neq 2A$.

Hence, W is not a subspace of V .

Example: The vector space R^2 is not a subspace of R^3 because R^2 is not even a subset of R^3 .

The vectors in R^3 all have three entries, whereas the vectors in R^2 have only two.

* The set $H = \left\{ \begin{bmatrix} s \\ t \\ 0 \end{bmatrix} : s, t \in R \right\}$ is a subset of R^3 . Show that H is a subspace of R^3 .

Solution: The zero vector is in H , H is closed under vector addition and scalar multiplication because these operations on vectors in H always produce vectors whose third entries are zero (and so belong to H). Thus H is a subspace of R^3 .

Linear combination

* Let $\underline{u} = (1, 2, -1)$ and $\underline{v} = (6, 4, 2)$. Show that $\underline{w} = (9, 2, 7)$ is a linear combination of \underline{u} and \underline{v} .

Solution: For any two scalars k_1 and k_2 , we get

$$(9, 2, 7) = k_1 \underline{u} + k_2 \underline{v} = k_1(1, 2, -1) + k_2(6, 4, 2)$$

$$\Rightarrow (9, 2, 7) = (k_1, 2k_1, -k_1) + (6k_2, 4k_2, 2k_2)$$

$$\Rightarrow (9, 2, 7) = (k_1 + 6k_2, 2k_1 + 4k_2, -k_1 + 2k_2)$$

$$\therefore k_1 + 6k_2 = 9$$

$$2k_1 + 4k_2 = 2$$

$$-k_1 + 2k_2 = 7$$

The augmented matrix is,

$$\left[\begin{array}{ccc|c} 1 & 6 & 9 \\ 2 & 4 & 2 \\ -1 & 2 & 7 \end{array} \right] \rightsquigarrow \left[\begin{array}{ccc|c} 1 & 6 & 9 \\ 0 & -8 & -16 \\ 0 & 8 & 16 \end{array} \right] \quad R'_2 = R_2 - 2R_1, \quad R'_3 = R_1 + R_3$$

$$\begin{aligned} R'_2 &= -\frac{1}{8} \times R_2 \\ R'_3 &\stackrel{\leftrightarrow}{=} \frac{1}{8} \times R_3 \end{aligned} \quad \left[\begin{array}{ccc|c} 1 & 6 & 9 \\ 0 & 1 & 2 \\ 0 & 1 & 2 \end{array} \right] \rightsquigarrow \left[\begin{array}{ccc|c} 1 & 6 & 9 \\ 0 & 1 & 2 \\ 0 & 0 & 0 \end{array} \right] \quad R'_3 = R_3 - R_2$$

$$\text{So we get, } k_1 + 6k_2 = 9 \Rightarrow k_1 = 9 - 6 \times 2 = -10 - 3.$$

$$k_2 = 2$$

$$\text{So, } (9, 2, 7) = -3\underline{u} + 2\underline{v}. \quad (\text{showed})$$

$$\begin{aligned} \text{check: } -3\underline{u} + 2\underline{v} &= -3(1, 2, -1) + 2(6, 4, 2) \\ &= (-3, -6, 3) + (12, 8, 4) = (-3+12, -6+8, 3+4) \\ &= (9, 2, 7) \end{aligned}$$

Linear span

* Given \underline{v}_1 and \underline{v}_2 in a vector space V , let $H = \text{Span}\{\underline{v}_1, \underline{v}_2\}$. Show that H is a subspace of V .

Solution: The zero vector is in H since $0 = 0 \cdot \underline{v}_1 + 0 \cdot \underline{v}_2$. To show that H is closed under vector addition, take two arbitrary vectors in H , say

$$\underline{u} = s_1 \underline{v}_1 + s_2 \underline{v}_2 \text{ and } \underline{w} = t_1 \underline{v}_1 + t_2 \underline{v}_2$$

By axioms, for the vector space V

$$\begin{aligned}\underline{u} + \underline{w} &= (s_1 \underline{v}_1 + s_2 \underline{v}_2) + (t_1 \underline{v}_1 + t_2 \underline{v}_2) \\ &= (s_1 + t_1) \underline{v}_1 + (s_2 + t_2) \underline{v}_2\end{aligned}$$

So, $\underline{u} + \underline{w}$ is in H . Furthermore, if c is any scalar, then

$$c\underline{u} = c(s_1 \underline{v}_1 + t_1 \underline{v}_2) = (cs_1) \underline{v}_1 + (ct_1) \underline{v}_2.$$

which shows that $c\underline{u}$ is in H is closed under scalar multiplication. Thus H is a subspace of V .

Theorem: If $\underline{v}_1, \underline{v}_2, \dots, \underline{v}_p$ are in a vector space V , then $\text{Span}\{\underline{v}_1, \underline{v}_2, \dots, \underline{v}_p\}$ is a subspace of V .

* We call $\text{Span}\{\underline{v}_1, \underline{v}_2, \dots, \underline{v}_p\}$ the subspace generated or spanned by $\{\underline{v}_1, \underline{v}_2, \dots, \underline{v}_p\}$

Example: Let H be the set of all vectors of the form $(a-3b, b-a, a, b)$ where a and b are arbitrary scalars. That is, let $H = \{(a-3b, b-a, a, b) : a, b \in \mathbb{R}\}$. Show that H is a subspace of \mathbb{R}^4 .

Solution: Write the vectors in H as column vectors. Then an arbitrary vector in H has the form

$$\begin{bmatrix} a-3b \\ b-a \\ a \\ b \end{bmatrix} = a \begin{bmatrix} 1 \\ -1 \\ 1 \\ 0 \end{bmatrix} + b \begin{bmatrix} -3 \\ 1 \\ 0 \\ 1 \end{bmatrix}$$

\uparrow \uparrow
 \underline{v}_1 \underline{v}_2

This calculation shows that $H = \text{span}\{\underline{v}_1, \underline{v}_2\}$ where \underline{v}_1 & \underline{v}_2 are the vectors indicated above. Thus H is a subspace of \mathbb{R}^4 by the theorem.

* For what values of h will \underline{y} be in the subspace of \mathbb{R}^3 spanned by $\underline{v}_1, \underline{v}_2, \underline{v}_3$ if

$$\underline{v}_1 = \begin{pmatrix} 1 \\ -1 \\ -2 \end{pmatrix}, \quad \underline{v}_2 = \begin{pmatrix} 5 \\ -4 \\ -7 \end{pmatrix}, \quad \underline{v}_3 = \begin{pmatrix} -3 \\ 1 \\ 0 \end{pmatrix} \text{ and } \underline{y} = \begin{pmatrix} -4 \\ 3 \\ h \end{pmatrix}$$

Hint: The solution shows that \underline{y} is in $\text{span}\{\underline{v}_1, \underline{v}_2, \underline{v}_3\}$ iff $h=5$.

Ans: $h=5$

* Determine whether vectors $\underline{v}_1 = (2, -1, 3)$, $\underline{v}_2 = (4, 1, 2)$ and $\underline{v}_3 = (8, -1, 8)$ span \mathbb{R}^3 .

Solution: We must determine whether an arbitrary vector $\underline{v} = (a, b, c)$ in \mathbb{R}^3 can be expressed as a linear combination.

$$\text{so, } (a, b, c) = k_1 \underline{v}_1 + k_2 \underline{v}_2 + k_3 \underline{v}_3.$$

$$\Rightarrow (a, b, c) = k_1(2, -1, 3) + k_2(4, 1, 2) + k_3(8, -1, 8)$$

which implies,

$$2k_1 + 4k_2 + 8k_3 = a$$

$$-k_1 + k_2 - 8k_3 = b$$

$$3k_1 + 2k_2 + 8k_3 = c$$

This problem thus reduces to determining whether or not the system is consistent for all values of a , b , and c . And the system will be consistent if the coefficient matrix is invertible or the determinant is non-zero.

$$\text{Here, } A = \begin{pmatrix} 2 & 4 & 8 \\ -1 & 1 & -1 \\ 3 & 2 & 8 \end{pmatrix}$$

$|A| = 0$, so, $\underline{v}_1, \underline{v}_2, \underline{v}_3$ do not span \mathbb{R}^3 .

* Show that the vectors $\underline{u} = (1, 2, 3)$, $\underline{v} = (0, 1, 2)$ and $\underline{w} = (0, 0, 1)$ generate \mathbb{R}^3 .

Solution: We must determine whether an arbitrary vector $\underline{v}' = (a, b, c)$ in \mathbb{R}^3 can be expressed as a linear combination

$$\text{so, } (a, b, c) = k_1 \underline{u} + k_2 \underline{v} + k_3 \underline{w}.$$

$$\Rightarrow (a, b, c) = k_1(1, 2, 3) + k_2(0, 1, 2) + k_3(0, 0, 1)$$

$$\therefore k_1 + 0 \cdot k_2 + 0 \cdot k_3 = a \Rightarrow k_1 = a$$

$$\text{and } 2k_1 + k_2 = b$$

$$\text{and } 3k_1 + 2k_2 + k_3 = c.$$

$$\text{Now, } \left(\begin{array}{ccc|c} 1 & 2 & 3 & a \\ 0 & 1 & 2 & b \\ 0 & 0 & 1 & c \end{array} \right) \left(\begin{array}{c} k_3 \\ k_2 \\ k_1 \end{array} \right) = \left(\begin{array}{c} c \\ b \\ a \end{array} \right)$$

which is in echelon form. We have, $k_1 = a$, $k_2 = b - 2a$,

$$k_3 = b - b + 2a - c - 3a - 2(b - 2a) = c - 2b + a.$$

Thus $\underline{u}, \underline{v}, \underline{w}$ generate (span) \mathbb{R}^3 .

Linear dependence and Independence.

* Show that the vectors $(2, -1, 4)$, $(3, 6, 2)$ and $(2, 10, -4)$ are linearly independent.

Solution: Form the matrix whose rows are the given vectors.

$$\begin{pmatrix} 2 & -1 & 4 \\ 3 & 6 & 2 \\ 2 & 10 & -4 \end{pmatrix} \rightsquigarrow \begin{pmatrix} 20 & 10 & -4 \\ 3 & 6 & 2 \\ 2 & -1 & 4 \end{pmatrix} \xrightarrow{R_1' = \frac{1}{2}R_1} \begin{pmatrix} 1 & 5 & -2 \\ 3 & 6 & 2 \\ 2 & -1 & 4 \end{pmatrix}$$

$$\begin{matrix} R_2' = R_3 - 3R_1 \\ R_3' = R_3 - 2R_1 \end{matrix} \begin{pmatrix} 1 & 5 & -2 \\ 0 & -9 & 8 \\ 0 & -11 & 8 \end{pmatrix} \rightsquigarrow \begin{pmatrix} 1 & 5 & -2 \\ 0 & -9 & 8 \\ 0 & 0 & -\frac{16}{9} \end{pmatrix} \text{ which is in row echelon form.}$$

Since the echelon form has no zero rows, the vectors are linearly independent.

* Show that the set of vectors $\{(3, 0, 1, -1), (2, -1, 0, 1), (1, 1, 1, -2)\}$ is linearly dependent.

Solution: Form the matrix whose rows are the given vectors.

$$\begin{pmatrix} 3 & 0 & 1 & -1 \\ 2 & -1 & 0 & 1 \\ 1 & 1 & 1 & -2 \end{pmatrix} \xrightarrow{\text{Reduce it}} \begin{pmatrix} 1 & 1 & 1 & -2 \\ 3 & 0 & 1 & -1 \\ 2 & -1 & 0 & 1 \end{pmatrix} \rightsquigarrow \begin{pmatrix} 1 & 1 & 1 & -2 \\ 0 & -3 & -2 & 5 \\ 0 & 0 & 0 & 0 \end{pmatrix}$$

This matrix is in row echelon form and has a zero row, hence the given vectors are linearly dependent.

Alternative process: set the linear combination of the given vectors equal to the zero vectors using unknown scalars. If the homogeneous system gives non-zero solution to the system, then linearly dependent, if not then linearly independent.

Basis and Dimension

* If V is a vector space of dimension m (equal to the max^m number of linearly independent vectors), every basis of V contains exactly m linearly independent vectors.

* Prove that the vectors $(1, 2, 0)$, $(0, 5, 7)$, and $(-1, 1, 3)$ form a basis for \mathbb{R}^3 .

Solution: The given vectors will be a basis of \mathbb{R}^3 iff they are linearly independent and every vector in \mathbb{R}^3 can be written as a linear combination of the given vectors.

For any scalars k_1, k_2, k_3 , we have

$$k_1(1, 2, 0) + k_2(0, 5, 7) + k_3(-1, 1, 3) = (0, 0, 0)$$

$$\Rightarrow k_1 - k_3 = 0$$

$$2k_1 + 5k_2 + k_3 = 0$$

$$7k_2 + 3k_3 = 0$$

We get,

$$\left(\begin{array}{ccc} 1 & 0 & -1 \\ 2 & 5 & 1 \\ 0 & 7 & 3 \end{array} \right) \xrightarrow{\substack{R_2 \leftarrow R_2 - 2R_1 \\ R_3 \leftarrow R_3 - \frac{3}{7}R_1}} \left(\begin{array}{ccc} 1 & 0 & -1 \\ 0 & 5 & 3 \\ 0 & 7 & 3 \end{array} \right) \xrightarrow{\substack{R_3 \leftarrow R_3 - \frac{7}{5}R_2}} \left(\begin{array}{ccc} 1 & 0 & -1 \\ 0 & 1 & \frac{3}{5} \\ 0 & 1 & \frac{3}{5} \end{array} \right)$$

$$\xrightarrow{\substack{R_3 \leftarrow R_3 - R_2}} \left(\begin{array}{ccc} 1 & 0 & -1 \\ 0 & 1 & \frac{3}{5} \\ 0 & 0 & \frac{3}{7} - \frac{3}{5} \end{array} \right) \xrightarrow{\substack{R_3 \leftarrow R_3 - \frac{6}{35}R_2}} \left(\begin{array}{ccc} 1 & 0 & -1 \\ 0 & 1 & \frac{3}{5} \\ 0 & 0 & -\frac{6}{35} \end{array} \right)$$

This matrix is in row echelon form and there is no zero row. Hence the given vectors are linearly independent.

Now, to show the three vectors span \mathbb{R}^3 , consider an

arbitrary vector $\vec{v} = (a, b, c)$ in \mathbb{R}^3 can be expressed as a linear combination of the given vectors.

$$(a, b, c) = \alpha(1, 2, 0) + \beta(0, 5, 7) + \gamma(-1, 1, 3); \text{ for scalars } \alpha, \beta, \gamma$$

$$\text{We have, } \alpha - \gamma = a$$

$$2\alpha + 5\beta + \gamma = b$$

$$7\beta + 3\gamma = c$$

The augmented matrix

$$\left(\begin{array}{ccc|c} 1 & 0 & -1 & a \\ 2 & 5 & 1 & b \\ 0 & 7 & 3 & c \end{array} \right) \sim \left(\begin{array}{ccc|c} 1 & 0 & -1 & a \\ 0 & 5 & 3 & b - 2a \\ 0 & 7 & 3 & c \end{array} \right)$$

$$\xrightarrow{R_3' = R_3 - \frac{7}{5}R_2} \left(\begin{array}{ccc|c} 1 & 0 & -1 & a \\ 0 & 5 & 3 & b - 2a \\ 0 & 0 & -\frac{6}{5} & c - \frac{7}{5}(b - 2a) \end{array} \right)$$

Therefore,

$$\alpha - \gamma = a$$

$$5\beta + \gamma = b - 2a$$

$$-\frac{6}{5}\gamma = c - \frac{7}{5}(b - 2a)$$

$$\therefore \gamma = -\frac{5}{6}\left(c - \frac{7}{5}(b - 2a)\right) = \frac{1}{6}(-5c + 7(b - 2a))$$

$$\therefore \gamma = \frac{1}{6}(7b - 5c - (-14a))$$

$$\text{Hence, } \beta = \frac{1}{2}(c - b + 2a) \text{ and } \alpha = \frac{1}{6}(7b - 5c - 8a).$$

$$\text{Therefore, } (a, b, c) = \alpha(1, 2, 0) + \beta(0, 5, 7) + \gamma(-1, 1, 3).$$

Thus every vector in \mathbb{R}^3 can be expressed as a linear combination of the vectors $(1, 2, 0), (0, 5, 7), (-1, 1, 3)$. Hence the given vectors form a basis of \mathbb{R}^3 .

* Determine a basis and the dimension for the solution space of the following homogeneous system.

$$x_4 - 3x_2 + x_3 = 0$$

$$2x_4 - 6x_2 + 2x_3 = 0$$

$$3x_4 - 9x_2 + 3x_3 = 0$$

Solution: The system becomes,

$$\begin{pmatrix} 1 & -3 & 1 \\ 2 & -6 & 2 \\ 3 & -9 & 3 \end{pmatrix} \begin{pmatrix} x_4 \\ x_2 \\ x_3 \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \\ 0 \end{pmatrix}$$

$$\text{Now, } \begin{pmatrix} 1 & -3 & 1 \\ 2 & -6 & 2 \\ 3 & -9 & 3 \end{pmatrix} \rightsquigarrow \begin{pmatrix} 1 & -3 & 1 \\ 1 & -3 & 1 \\ 1 & -3 & 1 \end{pmatrix} \rightsquigarrow \begin{pmatrix} 1 & -3 & 1 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{pmatrix}$$

$$\text{We have, } x_4 - 3x_2 + x_3 = 0$$

$$0 = 0$$

$$0 = 0$$

This system is in echelon form and has only one non-zero row in three unknowns. So we have $3-1=2$ free variables, which are x_2 and x_3 . Here x_1 is the basic variable.

∴ The dimension of the solution space is 2.

Setting $x_3 = 0$ and $x_2 = 1$, we get the special solution,

$$\text{and } x_4 = 3x_2 - x_3 = 3 - 0 = 3.$$

Again, setting $x_3 = 1$ and $x_2 = 0$, we get $x_4 = 3x_2 - x_3 = -1$.

Hence, the respective solutions are $\begin{pmatrix} x_1 \\ x_2 \\ x_3 \end{pmatrix} = \begin{pmatrix} 3 \\ 1 \\ 0 \end{pmatrix} = v_1$ and $\begin{pmatrix} -1 \\ 0 \\ 1 \end{pmatrix} = v_2$
so, $\{v_1, v_2\}$ is a basis of the solution space.

Bases for row space, column space & null space

* Find bases for the row space, column space and the null space of the matrix (REF) (REF) (RREF)

$$A = \begin{bmatrix} -2 & -5 & 8 & 0 & -17 \\ 1 & 3 & -5 & 1 & 5 \\ 3 & 11 & -19 & 7 & 1 \\ 1 & 7 & -13 & 5 & -3 \end{bmatrix}.$$

$$\rightsquigarrow \begin{bmatrix} 1 & 3 & -5 & 1 & 5 \\ -2 & -5 & 8 & 0 & -17 \\ 3 & 11 & -19 & 7 & 1 \\ 1 & 7 & -13 & 5 & -3 \end{bmatrix} \rightsquigarrow \begin{bmatrix} 1 & 3 & -5 & 1 & 5 \\ 0 & 1 & -2 & 2 & -7 \\ 0 & 2 & -4 & 4 & -14 \\ 0 & 4 & -8 & 4 & -8 \end{bmatrix}$$

$$\rightsquigarrow \begin{bmatrix} 1 & 3 & -5 & 1 & 5 \\ 0 & 1 & -2 & 2 & -7 \\ 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & -4 & 20 \end{bmatrix} \rightsquigarrow \begin{bmatrix} 1 & 3 & -5 & 1 & 5 \\ 0 & 1 & -2 & 2 & -7 \\ 0 & 0 & 0 & -4 & 20 \\ 0 & 0 & 0 & 0 & 0 \end{bmatrix} = B$$

The three non-zero rows form a basis for the row space of A.

Basis for Row A: $\{(1, 3, -5, 1, 5), (0, 1, -2, 2, -7), (0, 0, 0, -4, 20)\}$.

For the column space, observe from B that the pivots are in columns 1, 2 and 4. Hence columns 1, 2 and 4 of A (not B) form a basis for Col A.

Basis for Col A: $\left\{ \begin{bmatrix} -2 \\ 1 \\ 3 \\ 1 \end{bmatrix}, \begin{bmatrix} -5 \\ 3 \\ 11 \\ 7 \end{bmatrix}, \begin{bmatrix} 0 \\ 1 \\ 7 \\ 3 \end{bmatrix} \right\}$

$$B = \begin{bmatrix} 1 & 3 & -5 & 1 & 5 \\ 0 & 1 & -2 & 2 & -7 \\ 0 & 0 & 0 & -4 & 20 \\ 0 & 0 & 0 & 0 & 0 \end{bmatrix} \rightsquigarrow \begin{bmatrix} 1 & 0 & 1 & 0 & 1 \\ 0 & 1 & -2 & 0 & 3 \\ 0 & 0 & 0 & 1 & -5 \\ 0 & 0 & 0 & 0 & 0 \end{bmatrix} = C$$

The equation $A\bar{x} = \underline{0}$ is equivalent to $C\bar{x} = \underline{0}$

$$x_1 + x_3 + x_5 = 0$$

$$x_2 - 2x_3 + 3x_5 = 0$$

$$x_4 - 5x_5 = 0$$

so, $x_1 = -x_3 - x_5$, $x_2 = 2x_3 - 3x_5$, $x_4 = 5x_5$, with x_3 and x_5 free variables. The usual calculations are, setting $x_3 = 0$ and $x_5 = 1$,

$$\text{we get, } x_4 = 5x_5 = 5, x_2 = 2x_3 - 3x_5 = -3, x_1 = -x_3 - x_5 = -1$$

Again, $x_3 = 1$, and $x_5 = 0$, $x_4 = 5x_5 = 0$, $x_2 = 2x_3 - 3x_5 = 2$,
 $x_1 = -x_3 - x_5 = -1$.

Hence basis for Null A: $\left\{ \begin{bmatrix} -1 \\ -3 \\ 0 \\ 5 \\ 1 \end{bmatrix}, \begin{bmatrix} -1 \\ 2 \\ 1 \\ 0 \\ 0 \end{bmatrix} \right\}$

* the rank of A is the dimension of the column space of A.

Rank theorem: $\text{rank}(A) + \dim \text{Null}(A) = n$ (no. of column vectors)

\therefore Rank of A = 3, [A has three pivot columns]

Nullity of A = 2 [rank(A) + Null(A) = 5 (no. of total columns in A)].