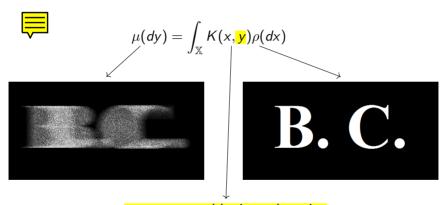
Solving Fredholm Integral Equations through Wasserstein Gradient Flows

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Fredholm Integral Equations of the First Kind (FIE)



constant speed horizontal motion

Fredholm Integral Equations of the First Kind (FIE)

- Applications: PDEs, indirect density estimation, signal reconstruction, causal inference, ...
- Inverse ill posed problems
- Solution methods often require discretisation/strong assumptions on f

FIE - Solution method

$$\mu(dy) = \int_{\mathbb{X}} \rho(dx) K(x, \mathbf{y}) \qquad \forall y \in \mathbb{Y},$$

Take ρ,μ probability measures and K a Markov transition density

$$\rho^{\star} := \operatorname{argmin} \mathsf{KL}(\mu, \rho \mathsf{K}) - \alpha \operatorname{ent}(\rho)$$

for some $\alpha > 0$.

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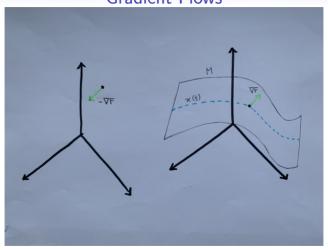
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for some $\alpha > 0$.

How?

 $\mathsf{minimisation} \longrightarrow \mathsf{PDE} \longrightarrow \mathsf{SDE}$

Gradient Flows



$$x'(t) = -\nabla F(x(t))$$

Wasserstein Gradient Flows (I)



Take the manifold

$$\mathcal{P}_2^{ac}(\mathbb{R}^d) = \left\{ \mu \in \mathcal{P}(\mathbb{R}^d) : \int \|x\|_2^2 \ d\mu(x) < \infty, \mu < < \mathcal{L} \right\}$$

with distance

$$W_2(\mu, \nu) := \left(\inf_{\pi \in \Pi(\mu, \nu)} \int \|x - y\|_2^2 \ d\pi(x, y)\right)^{1/2}$$

Wasserstein Gradient Flows (II)

Curves in $(\mathcal{P}_2^{ac}(\mathbb{R}^d), W_2)$ are geodetics

$$\mu_{\mathsf{s}} = ((1-\mathsf{s})\mathsf{Id} + \mathsf{st}_{\mu}^{\nu})_{\#}\mu$$

where t_{μ}^{ν} is the unique transport map between μ and ν and $T_{\#}\mu$ denotes the push-forward measure

$$T_{\#}\mu(A) = \mu(T^{-1}(A)).$$

Wasserstein Gradient Flows (III)

For $F: M \subset \mathbb{R}^d \mapsto \mathbb{R}$ the gradient flow equation is

$$x'(t) = -\nabla F(x(t)).$$

For $F: \mathcal{P}_2^{ac}(\mathbb{R}^d) \mapsto \mathbb{R}$ we have¹

$$\partial_t \rho_t = -\nabla \cdot \left(\rho_t \frac{\delta F}{\delta \rho_t} \right) \tag{1}$$

with
$$\frac{\delta F}{\delta \rho_t} := \frac{d}{d\epsilon} F(\rho + \epsilon \chi)_{|\epsilon=0}$$
.



¹Jordan, Kinderlehrer, Otto (1998)

When is (1) well-behaved?

We need:

- F continuous, $F(\rho) < +\infty$ for some ρ
- $F \lambda$ —convex: exists $\lambda \geq 0$ s.t.

$$F\left(((1-s)\mathit{Id}+\mathit{st}_{\mu}^{
u})_{\#}\mu
ight) \leq (1-s)F(\mu)+\mathit{sF}(
u)-rac{\lambda}{2}\mathit{s}(1-s)W_2^2(
u,\mu)$$

• F is coercive: exists r > 0 s.t.



$$\inf \left\{ F(\rho) : \rho \in \mathcal{P}_2^{ac}(\mathbb{R}^d), \int \|x\|_2^2 \ d\rho(x) \le r \right\} > -\infty$$

Then...

The gradient flow PDE (1) has a unique solution for a given initial condition ρ_0 .

For two initial conditions ρ_0^1,ρ_0^2 we have the estimate

$$W_2(\rho_t^1, \rho_t^2) \le e^{-\lambda t} W_2(\rho_0^1, \rho_0^2).$$

Gradient Flow for FIE - Assumptions

$$\mu(dy) = \int_{\mathbb{X}} \rho(dx) K(x, \mathbf{y}) \qquad \forall y \in \mathbb{Y},$$

- 1. \mathbb{X} , \mathbb{Y} subsets of some Euclidean spaces with Borel σ -algebras; 2. μ , ρ ties with finite second moment;
- 3. K bounded and bounded away from 0. Lipschitz continuous with Lipschitz continuous gradient and λ -concave in x:

$$x \mapsto K(x,y) + \frac{\lambda}{2} ||x||_2^2$$

is concave for some $\lambda > 0$ for all $y \in \mathbb{Y}$.



Gradient Flow for FIE

$$F(\rho) := \mathsf{KL}(\mu, \rho K) - \alpha \operatorname{ent}(\rho)$$

is continuous, coercive and λ geodesically convex with $\lambda=0$ and has first variation

$$\frac{\delta F}{\delta \rho}(x) = -\int \mu(dy) \frac{K(x,y)}{\rho K(y)} + \alpha (1 + \log \rho(x)).$$

the gradient flow exist and is unique for each initial condition ho_0

Gradient Flow for FIE - PDE

$$\partial_{t}\rho_{t} = \nabla \cdot \left(\rho_{t} \nabla \frac{\delta F}{\delta \rho_{t}}\right)$$

$$= \nabla \cdot \left(\rho_{t} \left[-\int \mu \left(dy\right) \frac{\nabla K(x, y)}{\rho K(y)} + \alpha \nabla \log \rho \left(x\right)\right]\right)$$

$$= -\nabla \cdot \left(\rho_{t} \int \mu \left(dy\right) \frac{\nabla K(x, y)}{\rho_{t} K(y)}\right) + \alpha \triangle \rho_{t}$$

is a Fokker-Plank equation with corresponding SDE...

Gradient Flow for FIE - SDE

$$dX_t = \int \mu\left(dy\right) rac{
abla \mathcal{K}(X_t,y)}{
ho_t \mathcal{K}(y)} dt + \sqrt{2lpha} dW_t, \quad X_0 \sim
ho_0$$

- McKean-Vlasov SDE
- a strong solution exists and is unique
- requires discretisation in time and space

SDE - Implementation

 discretisation in space: take N copies of the SDE and use the resulting empirical measure instead of ρ_t



$$dX_t^{i,N} = \int \mu(dy) \frac{\nabla K(X_t^{i,N}, y)}{\rho_t^N K(y)} dt + \sqrt{2\alpha} dW_t^i, \quad \rho_t^N = \frac{1}{N} \sum_{i=1}^N \delta_{X_t^{i,N}}$$

discretisation in time: Euler scheme

$$X_{n+1}^{i,N} = X_n^{i,N} + \int \mu(dy) \frac{\nabla K(X_n^{i,N}, y)}{\rho_n^N K(y)} \Delta t + \sqrt{2\alpha} \Delta W^i,$$
$$\rho_n^N = \frac{1}{N} \sum_{i=1}^N \delta_{X_n^{i,N}}$$

Toy Example

$$\mu(dy) = \int_{\mathbb{X}} \rho(dx) K(x, \mathbf{y}),$$

with

$$\mu(y) = \mathcal{N}(y; m, \sigma_{\mu}^2 := \sigma_K^2 + \sigma_{\rho}^2)$$

$$K(x, y) = \mathcal{N}(y; x, \sigma_K^2)$$

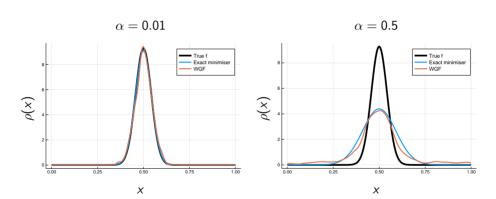
$$\rho(x) = \mathcal{N}(x; m, \sigma_{\rho}^2).$$

The unique minimiser of E is

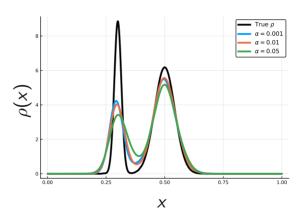
$$\rho: \alpha(x) = \mathcal{N}(x; m, \sigma_{\alpha}^2)$$

for $\alpha \in [0,1)$.

Toy Example



A second Toy Example

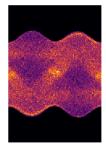


PET

The reconstruction of a cross-section of the brain (Figure (a)) from the data image provided by PET scanners (Figure (b)) is described by a 2D Fredholm integral equation of the first kind.



(a) 128-pixels Shepp-Logan phantom



(b) Sinogram + noise