

A connection between Tempering and Entropic Mirror Descent

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- **Aim 1:** sample from a probability distribution π on \mathbb{R}^d and approximate expectations w.r.t. $\pi(x) = \eta(x)/\mathcal{Z}$ whose normalising constant might be unknown

$$\int f(x)\pi(x)dx$$

- **Motivation:** compute posterior expectations in Bayesian inference
- **Aim 2:** estimate the unknown normalising constant \mathcal{Z}
- **Motivation:** model selection/parameter inference

Sampling as optimisation over distributions

$$\min_{\mu \in \mathcal{P}(\mathbb{R}^d)} \text{KL}(\mu|\pi)$$

where $\text{KL}(\mu|\pi) = \int_{\mathbb{R}^d} \log(\mu/\pi) d\mu$ denotes the Kullback–Leibler divergence.

- Variational Inference ([Blei et al., 2017](#))
- Algorithms based on the Langevin diffusion ([Jordan et al., 1998](#))
- Stein Variational Gradient Descent (SVGD; [Liu \(2017\)](#))
- Algorithms based on tempering (this work and [Domingo-Enrich and Pooladian \(2023\)](#))

Why tempering?

1. can tackle multimodal targets
2. normalising constant estimated for free
3. used as alternatives to poorly mixing MCMC algorithms

Gradient descent in **Euclidean space** amounts to solving

$$\dot{x}_t = -\nabla \mathcal{F}(x_t)$$

Gradient descent in the **space of distributions** amounts to solving

$$\partial_t \mu_t = \operatorname{div}(\mu_t \nabla \operatorname{KL}(\mu_t | \pi))$$

Algorithms based on the Langevin diffusion (ULA, MALA, HMC, etc.), SVGD and continuous time tempering all implement gradient for the KL in different geometries.

Gradient Descent

Langevin diffusion $dX_t = \nabla \log \pi(X_t)dt + \sqrt{2}dB_t$

Geometry: Wasserstein-2

Gradient: $\nabla_{W_2} \text{KL}(\mu_t|\pi) = \nabla \log \left(\frac{\mu_t}{\pi} \right)$

Stein Variational Gradient Descent

$dX_t^i = 1/N \sum_{j=1}^N \left[k(X_t^i, X_t^j) \nabla \log \pi(X_t^j) - \nabla_1 k(X_t^j, X_t^i) \right]$

Geometry: Stein

Gradient: $\nabla_{\text{Stein}} \text{KL}(\mu_t|\pi) = \int k(x, \cdot) \nabla \log \left(\frac{\mu_t}{\pi}(x) \right) d\mu_t(x)$

Tempering $\mu_t \propto \mu_0^{e^{-t}} \pi^{1-e^{-t}}$

Geometry: Wasserstein-Fisher-Rao

Gradient: $\nabla_{\text{WFR}} \text{KL}(\mu_t|\pi) = \nabla_{W_2} \text{KL}(\mu_t|\pi) + \nabla_{\text{FR}} \text{KL}(\mu_t|\pi)$

Mirror Descent

Let $\mathcal{F} : \mathcal{P}(\mathbb{R}^d) \rightarrow \mathbb{R}^+$ be a functional on $\mathcal{P}(\mathbb{R}^d)$. **Mirror Descent** proceeds iteratively solving ([Aubin-Frankowski et al., 2022](#))

$$\mu_{n+1} = \operatorname{argmin}_{\mu \in \mathcal{P}(\mathbb{R}^d)} \{ \mathcal{F}(\mu_n) + \langle \nabla \mathcal{F}(\mu_n), \mu - \mu_n \rangle + (\gamma_{n+1})^{-1} B_\phi(\mu | \mu_n) \}. \quad (1)$$

- $(\gamma_n)_{n \geq 0}$ is a sequence of step-sizes
- $B_\phi(\nu | \mu) = \phi(\nu) - \phi(\mu) - \langle \nabla \phi(\mu), \nu - \mu \rangle$ for some positive and convex ϕ is the **Bregman divergence**
- $\lim_{\epsilon \rightarrow 0} \frac{1}{\epsilon} (\mathcal{F}(\nu + \epsilon \xi) - \mathcal{F}(\nu))$ is the **first variation** of \mathcal{F}

Entropic Mirror Descent (MD)

Using the first order conditions of (1) we obtain the dual iteration

$$\nabla\phi(\mu_{n+1}) - \nabla\phi(\mu_n) = -\gamma_{n+1}\nabla\mathcal{F}(\mu_n).$$

In the case $B_\phi(\nu|\mu) = \text{KL}(\nu|\mu)$ we have the following multiplicative update named **entropic mirror descent**:

$$\mu_{n+1} \propto \mu_n e^{-\gamma_{n+1}\nabla\mathcal{F}(\mu_n)}.$$

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If $\mathcal{F}(\mu) = \text{KL}(\mu|\pi)$, $\nabla\mathcal{F}(\mu) = \log(\frac{\mu}{\pi})$ and we obtain entropic mirror descent on the KL:

$$\mu_{n+1} \propto \mu_n^{(1-\gamma_{n+1})} \pi^{\gamma_{n+1}}.$$

In the Monte Carlo literature, it is common to consider the following **tempering (or annealing)** sequence

$$\mu_{n+1} \propto \mu_0^{1-\lambda_{n+1}} \pi^{\lambda_{n+1}},$$

where $0 = \lambda_0 < \lambda_1 < \dots < \lambda_T = 1$.

- Parallel Tempering ([Geyer, 1991](#))
- Annealed Importance Sampling ([Neal, 2001](#))
- Sequential Monte Carlo samplers ([Del Moral et al., 2006](#))
- Thermodynamic Integration ([Gelman and Meng, 1998](#))

Connection between Tempering and MD

MD

$$\mu_{n+1} \propto \mu_n^{(1-\gamma_{n+1})} \pi^{\gamma_{n+1}}$$

Tempering

$$\mu_{n+1} \propto \mu_0^{1-\lambda_{n+1}} \pi^{\lambda_{n+1}}$$

are equivalent if

$$\lambda_n = 1 - \prod_{k=1}^n (1 - \gamma_k)$$

and can both be written in exponential family form

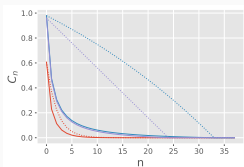
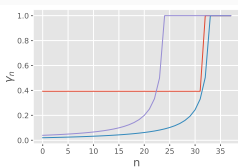
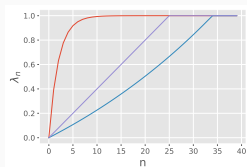
$$\mu_{n+1}(x) \equiv \mu_{\lambda_{n+1}}(x) \propto \mu_0 \exp \{ \lambda_{n+1} s(x) \}$$

where $s(x) := \log \pi(x) / \mu_0(x)$.

Convergence Rates

The connection between MD and tempering allows us to obtain explicit rates of convergence for the tempering iterates:

$$\text{KL}(\mu_n|\pi) \leq (\gamma_1)^{-1} \prod_{k=1}^n (1 - \gamma_k) \text{KL}(\pi|\mu_0) = (\lambda_1)^{-1} (1 - \lambda_n) \text{KL}(\pi|\mu_0)$$



— $\lambda_n = 1 - e^{-an}$ — $\lambda_n = e^{an} - 1$ — $\lambda_n = mn$

Connecting sampling and normalising constant estimation

- **Aim 1:** sample from a probability distribution π on \mathbb{R}^d
- **Objective Function:** $\text{KL}(\mu|\pi)$
- **Aim 2:** estimate the unknown normalising constant \mathcal{Z}
- **Objective Function:** $\text{Var}(\log \hat{\mathcal{Z}}) = \sum_{n=1}^T \text{KL}(\mu_{n-1}|\mu_n)$

The MD perspective allows us to link the two:

$$\text{KL}(\mu_{n-1}|\pi) - \text{KL}(\mu_n|\pi) \geq \text{KL}(\mu_{n-1}|\mu_n)$$

which gives

$$\text{Var}(\log \hat{\mathcal{Z}}) \leq \text{KL}(\mu_0|\pi) - \text{KL}(\mu_T|\pi).$$

$$\mu_{n+1} \propto q_n \exp(-\gamma_n g_n)$$

where g_n is an approximation of the gradient of the KL objective $\log(\mu_n/\pi)$; and q_n is an approximation of μ_n .

We focus on algorithms which use:

- importance weights corresponding to $\exp(-\gamma_n g_n)$
- mixtures corresponding to q_n

Particle Mirror Descent (PMD)

In PMD (Dai et al., 2016), the mirror descent iterate at time n is approximated by a kernel density estimator

$$q_n^{\text{PMD}}(x) := \sum_{i=1}^N V_n^i K_{h_n}(x - X_n^i)$$

- $\{X_n^i, V_n^i\}_{i=1}^N$ weighted particle set with

$$V_n(x) = \left(\frac{\pi(x)}{q_{n-1}^{\text{PMD}}(x)} \right)^{\gamma_n}.$$

- K_{h_n} a smoothing kernel with bandwidth h_n
- at each iteration a new N -particle set is resampled from q_n^{PMD}

Safe and Regularized Adaptive Importance Sampling (SRAIS)

In SRAIS ([Korba and Portier, 2022](#)), the mirror descent iterate at time n is approximated by a kernel density estimator

$$q_n^{\text{SRAIS}}(x) = \sum_{i=1}^n U_i K_{h_i}(x - X_i)$$

- $\{X_n^i, U_n^i\}_{i=1}^N$ weighted particle set with

$$U_n(x) = \left(\frac{\pi(x)}{q_{n-1}^{\text{SRAIS}}(x)} \right)^{\gamma_n}.$$

- K_{h_i} a smoothing kernel with bandwidth h_i
- at each iteration a new particle is added sampling from q_n^{SRAIS}

Sequential Monte Carlo (SMC) samplers

In SMC ([Del Moral et al., 2006](#)), the mirror descent iterate at time n is approximated by $q_n^{\text{SMC}}(x) = \sum_{i=1}^N W_n^i \delta_{X_n^i}(x)$

- $\{X_n^i, W_n^i\}_{i=1}^N$ weighted particle set with

$$W_n(x) = \left(\frac{\pi(x)}{\mu_0(x)} \right)^{\lambda_n - \lambda_{n-1}} = \left(\frac{\pi(x)}{\mu_{n-1}(x)} \right)^{\gamma_n}.$$

- at each iteration a new N -particle set is resampled using W_n^i and a μ_n -invariant Markov kernel

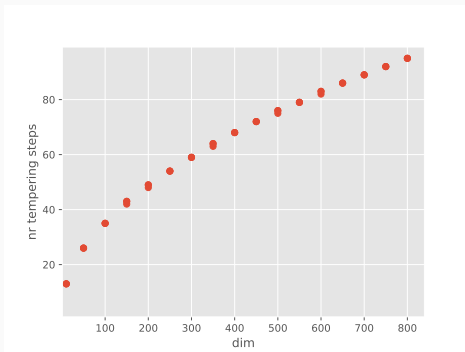
Which algorithm is better?

- **computational cost:** SMC is cheaper than PMD (no weight approximation)
- **approximation error:** SMC targets π exactly, PMD and SRAIS target a smoothed version of π
- PMD allows for minibatching while simple SMC does not (but a different version does)
- the convergence properties of SMC are very well studied

Adaptive strategies

The SMC literature offers an easy way to tune the stepsize/tempering sequence adaptively: aim for iterates which keep $\text{KL}(\mu_{n-1}|\mu_n)$ constant.

1. easy and inexpensive to approximate with particle cloud
2. can be linked to the effective sample size (i.e. variance of the weights)
3. guarantees $T = \mathcal{O}(\sqrt{d})$



Conclusions

- the connection between mirror descent (MD) and tempering justifies tempering from an optimisation point of view and provides the MD literature with a new class of algorithms (which is very well-studied!)
- opens the door to extensions of tempering through the use of other divergences
- clarifies when and in which case each algorithm should be used

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Thank you!

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