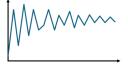


Coupled Markov chains with applications to Approximate Bayesian Computation for model based clustering

E. Bertoni, M. Caldarini, F. Di Filippo, G. Gabrielli, E. Musiari 11 november 2021

A complex problem





likelihood



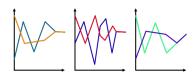


A complex problem





Unbiased Markov chain Monte Carlo methods with couplings

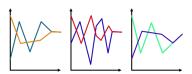






Aggiungere frecce che vanno in giù

Unbiased Markov chain Monte Carlo methods with couplings



Approximate Bayesian Computation

Unbiased Markov chain Monte Carlo methods with couplings

The road to parallelization: coupling of Markov chains

2/17

Faster MCMC ⇒ Parallelization

The road to parallelization: coupling of Markov chains

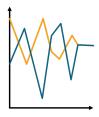
2/17

Faster MCMC ⇒ Parallelization ⇔ Unbiased estimator

Faster MCMC → Parallelization ← Unbiased estimator

Ridurre

P. Glynn and C. Rhee proposed in 2018 the class of exact estimations algorithms using coupling of Markov chain.



The goal is to estimate

$$\mathbb{E}_{\pi}[h(X)] = \int h(x)\pi(dx).$$

The estimator we are going to construct is based on a coupled pair of Markov chains, $(X_t)_{t\geq 0}$ and $(Y_t)_{t\geq 1}$, which marginally start from π_0 and evolve accordingly to P.

We consider some assumptions:

 $oldsymbol{1}$ as $t \to \infty$,

$$\mathbb{E}[h(X_t)] \to \mathbb{E}_{\pi}[h(X)];$$

and there exists $\eta > 0$ and $D < \infty$ such that $\mathbb{E}[|h(X_t)|^{2+\eta}] \le D$ for all t > 0;

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2 the chains are such that the meeting time

$$\tau = \inf\{t \ge 1 : X_t = Y_{t-1}\}$$

satisfies $\mathbb{P}(\tau > t) \leq C\delta^t$ for all $t \geq 0$, for some constants $C < \infty$ and $\delta \in (0,1)$;

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3 the chains stay together after meeting:

$$X_t = Y_{t-1}$$
 for all $t \ge \tau$.

Thanks to the previous assumptions we can prove that:

$$\mathbb{E}_{\pi}[h(X)] = \mathbb{E}[h(X_k) + \sum_{t=k+1}^{\tau-1} \{h(X_t) - h(Y_{t-1})\}];$$

Thanks to the previous assumptions we can prove that:

$$\mathbb{E}_{\pi}[h(\mathbf{X})] = \mathbb{E}[h(\mathbf{X}_k) + \sum_{t=k+1}^{\tau-1} \{h(\mathbf{X}_t) - h(\mathbf{Y}_{t-1})\}];$$

and we define the Rhee–Glynn estimator as:

$$H_k(X, Y) = h(X_k) + \sum_{t=k+1}^{\tau-1} \{h(X_t) - h(Y_{t-1})\}$$

which is unbiased by construction.

$$H_{k:m}(X,Y) = \frac{1}{m-k+1} \sum_{l=k}^{m} h(X_l) + \sum_{l=k+1}^{\tau-1} \min(1, \frac{l-k}{m-k+1}) \{h(X_l) - h(Y_{l-1})\}$$

Sistemare formula

$$H_{k:m}(X,Y) = \underbrace{\frac{1}{m-k+1} \sum_{l=k}^{m} h(X_l)}_{MCMC_{k:m}} + \sum_{l=k+1}^{\tau-1} \min(1, \frac{l-k}{m-k+1}) \{h(X_l) - h(Y_{l-1})\}$$

■ $MCMC_{k:m}$ is the standard MCMC average;

$$H_{k:m}(X,Y) = \underbrace{\frac{1}{m-k+1} \sum_{l=k}^{m} h(X_l)}_{MCMC_{k:m}} + \underbrace{\sum_{l=k+1}^{\tau-1} \min(1, \frac{l-k}{m-k+1}) \{h(X_l) - h(Y_{l-1})\}}_{BC_{k:m}}$$

- $MCMC_{k:m}$ is the standard MCMC average;
- $BC_{k:m}$ is the bias correction;

The MH algorithm adapted with couplings:

- **1** draw X_0 and Y_0 from an initial distribution π_0 and draw $X_1 \sim P(X_0, \cdot)$;
- 2 set t = 1: while $t < \max\{m, \tau\}$ and:
 - a draw $(\mathbf{X}_{t+1}, \mathbf{Y}_t) \sim \bar{P}\{(\mathbf{X}_t, \mathbf{Y}_{t-1}), \cdot\};$
 - b set $t \leftarrow t + 1$;
- 3 compute

$$H_{k:m}(X, Y)$$

with the time-averaged estimator.

The following is the **algorithm** to calculate the coupled kernel $\bar{P}\{(X_t, Y_{t-1}), \cdot\}$ via MH:

- **1** sample $(X^*, Y^*)|(X_t, Y_{t-1})$ from a maximal coupling of $q(X_t, \cdot)$ and $q(Y_{t-1}, \cdot)$;
- 2 sample $U \sim \mathcal{U}([0,1])$;
- 3 if

$$U \leq \min \left\{1, \frac{\pi(X^{\star})q(X^{\star}, X_t)}{\pi(X_t)q(X_t, X^{\star})}\right\}$$

then $X_{t+1} = X^*$; otherwise $X_t = X_{t-1}$;

evidenziare che la U è la stessa per entrambi i membri

4 if

$$U \leq \min \left\{ 1, \frac{\pi(Y^*)q(Y^*, Y_t)}{\pi(Y_t)q(Y_t, Y^*)} \right\}$$
 della coppia

then $Y_{t+1} = Y^*$; otherwise $Y_t = Y_{t-1}$.

Approximate Bayesian Computation

- a target posterior density $\pi(\theta|y_{obs}) \propto p(y_{obs}|\theta)\pi(\theta)$, consisting of a prior distribution $\pi(\theta)$ and a procedure of generating data under the model $p(y_{obs}|\theta)$;
- a proposal density $g(\theta)$, with $g(\theta) > 0$ if $\pi(\theta|y_{obs}) > 0$;
- \blacksquare an integer N > 0.

- a target posterior density $\pi(\theta|y_{obs}) \propto p(y_{obs}|\theta)\pi(\theta)$, consisting of a prior distribution $\pi(\theta)$ and a procedure of generating data under the model $p(y_{obs}|\theta)$;
- lacksquare a proposal density $g(\theta)$, with $g(\theta)>0$ if $\pi(\theta|\mathbf{y}_{\mathrm{obs}})>0$;
- \blacksquare an integer N > 0.

Sampling for i = 1, ..., N:

- **1** generate $\theta^{(i)} \sim g(\theta)$ from sampling density g;
- **2** generate $y \sim p(y|\theta^{(i)})$ from the likelihood;
- 3 if $y = y_{obs}$, then accept $\theta^{(i)}$ with probability $\frac{\pi(\theta^{(i)})}{\kappa g(\theta^{(i)})}$, where $\kappa \geq \max_{\theta} \frac{\pi(\theta)}{g(\theta)}$; else go to 1.

- a target posterior density $\pi(\theta|y_{obs}) \propto p(y_{obs}|\theta)\pi(\theta)$, consisting of a prior distribution $\pi(\theta)$ and a procedure of generating data under the model $p(y_{obs}|\theta)$;
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Output:

■ a set of parameter vectors $\theta^{(1)},...,\theta^{(N)}$ which are samples from $\pi(\theta|\mathbf{y_{obs}}).$

Likelihood-free rejection sampling algorithm II

10/17

Is this an efficient method for complex analysis?

Is this an efficient method for complex analysis?

3 If $\|y-y_{obs}\| \le h$, then accept $\theta^{(i)}$ with probability $\frac{\pi(\theta^{(i)})}{\mathsf{Kg}(\theta^{(i)})}$, where

$$K \ge \max_{\theta} \frac{\pi(\theta)}{g(\theta)}$$
; else go to 1.

Indicatrice con 1, e colorata come K

$$\pi(\theta, y|y_{obs}) \propto \mathbb{I}(\parallel y - y_{obs} \parallel \leq h)p(y|\theta)\pi(\theta)$$

$$\downarrow \qquad \qquad \qquad \downarrow$$

$$\pi_{ABC}(\theta, y|y_{obs}) \propto K_h(u)p(y|\theta)\pi(\theta)$$

Approximate Bayesian Computation

$$\pi(\theta, \mathbf{y}|\mathbf{y}_{obs}) \propto \mathbb{I}(\parallel \mathbf{y} - \mathbf{y}_{obs} \parallel \leq \mathbf{h}) \mathbf{p}(\mathbf{y}|\theta) \pi(\theta)$$

$$\downarrow \downarrow$$

$$\pi_{ABC}(\theta, \mathbf{y}|\mathbf{y}_{obs}) \propto \mathbf{K}_{\mathbf{h}}(\mathbf{u}) \mathbf{p}(\mathbf{y}|\theta) \pi(\theta)$$

Where we used a standard smoothing kernel function:

$$K_h(u) = \frac{1}{h}K(\frac{u}{h}), \quad \text{with } u = \parallel y - y_{\text{obs}} \parallel$$

Parentesi più grosse

Is this feasible in practice?

Is this feasible in practice?

No

Is this feasible in practice?

No it's difficult to have y ≈ yobs: we should use a large h, obtaining a poor posterior approximation!

 \implies use summary statistics s = S(y)

Summary statistics II

13/17

Critical decision: choice of summary statistics

Critical decision: choice of summary statistics

Rimettere le cose vecchie

⇒ choose sufficient statistics, such that:

$$\pi(\theta|\mathbf{s}_{\mathrm{obs}}) \equiv \pi(\theta|\mathbf{y}_{\mathrm{obs}})$$

Distance measure: substantial impact on ABC algorithm efficiency

$$\parallel \mathbf{s} - \mathbf{s}_{\text{obs}} \parallel = (\mathbf{s} - \mathbf{s}_{\text{obs}})^{\top} \Sigma^{-1} (\mathbf{s} - \mathbf{s}_{\text{obs}})$$

Distance measure: substantial impact on ABC algorithm efficiency

$$\parallel \mathbf{s} - \mathbf{s}_{\text{obs}} \parallel = (\mathbf{s} - \mathbf{s}_{\text{obs}})^{\top} \Sigma^{-1} (\mathbf{s} - \mathbf{s}_{\text{obs}})$$

- lacksquare $\Sigma = \mathrm{identity} \ \mathrm{matrix} o \mathrm{Euclidean} \ \mathrm{distance}$
- \blacksquare $\Sigma =$ diagonal matrix of non-zero weights \to Weighted Euclidean distance
- $f \Sigma = {\sf full}$ covariance matrix of ${\sf s} o {\sf Mahalanobis}$ distance

- a target posterior density $\pi(\theta|y_{obs}) \propto p(y_{obs}|\theta)\pi(\theta)$, consisting of a prior distribution $\pi(\theta)$ and a procedure of generating data under the model $p(y_{obs}|\theta)$;
- **a** proposal density $g(\theta)$, with $g(\theta) > 0$ if $\pi(\theta|y_{obs}) > 0$;
- \blacksquare an integer N > 0;
- a kernel function $K_h(u)$ and a scale parameter h > 0;
- **a** low dimensional vector of summary statistics s = S(y).

Sampling for i = 1, ..., N:

- **1** generate $\theta^{(i)} \sim g(\theta)$ from sampling density g;
- **2** generate $y \sim p(y|\theta^{(i)})$ from the likelihood;
- **3** compute summary statistic s = S(y);
- **4** accept $\theta^{(i)}$ with probability $\frac{K_h(\|\mathbf{s}-\mathbf{s}_{obs}\|)\pi(\theta^{(i)})}{Kg(\theta^{(i)})}$, where $K \geq K_h(0) \max_{\theta} \frac{\pi(\theta)}{g(\theta)}$; else go to 1.

Output:

■ a set of parameter vectors $\theta^{(1)},...,\theta^{(N)} \sim \pi_{ABC}(\theta|S_{obs})$.

Conclusions

Our focus till now was to understand the fundamental concepts and collect the missing information.

The next step will be a **simple and separate implementation** of both solution to be tested on simulated data.

Further steps will consider the **integration** of both solution into a single implementation and the testing on more complex data.

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