

AI-Based Detection of Jamming Attacks In 6G Drone Networks

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Keywords: keyword 1; keyword 2; keyword 3 (List three to ten pertinent keywords specific to the article; yet reasonably common within the subject discipline.)

1. Introduction

The shift from 4G to 5G has been a generational leap has revolutionized connectivity around the world. Despite 5G being still in its early adoption rate at the time of writing [1], the research community is already working on the next generation of wireless communication technologies, 6G. 6G technology is expected to enable a wide variety of new use cases, thanks to the increases in both data rates and latency but this in turn will also bring forth new security challenges, specific to those applications.

One of the main differences between 5G and 6G technology will be the focus of the 6G standard in regards to AI integration. While Software Defined Networks (SDN) have played a key role in improving the efficiency and security of 5G networks, 6G is expected to take this a step further, by integrating artificial intelligence and machine learning directly into the network. This is what the authors of [2] define as the shift from *Softwarization* to *Intelligentization*.

AI integration in 6G networks will greatly strengthen the security of the network against security threats. By leveraging Diagnostic Analytics, a collection of insights into the status of the networks, security teams will be able to train specific AI models to detect and respond to security threats in real-time.

In this paper we will focus on a specific aspect of the security of 6G networks, namely we will provide a machine learning based approach for the detection of jamming attacks in networks of drones.

The paper is divided in 5 sections:

1. **Topic overview:** In this section we will discuss how drones can benefit from integration in 6G network, analyze jamming attacks, their types, mitigation and detection. Finally we will discuss the advantages of an edge AI approach for jamming detection.
2. **Materials and methods:** In this section we will define the scenario that we decided to analyze as well as the dataset, algorithm and evaluation metrics we chose for our tests.

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3. **Numerical Results:** In this section we will present the testing methodology as well as the numerical results that we obtained.
4. **Discussion:** In this section we will discuss the results obtained in the previous section and highlight notable trends.
5. **Conclusions:** In this section we will summarize the results and discuss possible future research directions.

2. Related Works

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3. Topic Overview

3.1. Drones in 6G Networks

Drones, also known as Unmanned Aerial Vehicles (UAVs) are defined as *all aircraft designed to fly without a pilot on board* [3]. This technology has experienced rapid growth in

recent years and is expected to keep growing in both the consumer sector as well as the commercial and military sectors [4].

In report 22.886 [5] 3GPP, the organ responsible for the development and maintenance of the 5G standard, identifies some of the envisioned use cases for 5G V2X (Vehicle-to-Everything) communication services. Among these use cases, the report identifies vehicle platooning, advanced and remote driving end extended situational awareness as some of the main benefits of V2V communication. All these use cases can be leveraged by a 6G drone network to achieve fast and reliable drone-to-drone communication, that, with the integration of artificial intelligence would allow the drones to act autonomously in a coordinated manner.

This would prove useful in a variety of fields: from autonomous soil and crop health assessment as well as irrigation in agriculture, delivery of life saving supplies and locating of survivors in disaster response, in the delivery sector as a more eco friendly alternative to traditional delivery options and possibly in the mobility sector as a complement to traditional taxis and public transportation [6].

The effectiveness of drones in the military sector is widely recognized, both for high and low end models. For example, in the Ukraine war even cheap FPV drones mounted with explosives were successfully used to destroy much more expensive equipment [7].

Security against Jamming attacks is crucial in all these applications, especially in a safety critical environment.

3.2. Understanding Jamming Attacks

Jamming attacks are a type of Denial of Service (DoS) attack that aims at disrupting the communication between two or more devices. This is achieved by transmitting a powerful signal on the same frequency as the one used by the devices to communicate. If the jamming signal is strong enough, it is able to overwhelm the legitimate signal, effectively blocking the communication between the devices [6]. Since the ability to communicate is affected, Jamming attacks falls under the umbrella of attacks that target the *Availability* of the service in the CIA triad classification [8]. Jamming attacks can be classified into 5 main categories, based on the attack pattern of the jammer:

- **Constant Jamming:** The jammer continuously transmits a strong signal on the same frequency as the devices it wants to disrupt.
- **Periodic Jamming:** The jammer simply transmits a strong signal on the same frequency as the devices it wants to disrupt for a certain period of time t_a , then stops transmitting for another period of time t_b . This type of jamming attack is particularly effective against devices that are not able to change their frequency and has the ability to disrupt the transmission of a sequence of consecutive packets. [9]
- **Random Jamming:** In random jamming, the jammer is active at random intervals, giving each transmitted packet a probability p of being jammed [9].
- **Reactive Jamming:** A reactive jammer starts transmitting its jamming signal only when it senses energy in the communication channel, indicating that a legitimate transmission is taking place. This type of jamming attack is more power efficient compared to other operation types, as it only transmits its signal when it is needed[16].
- **Smart Jamming:** A smart jammer is a more sophisticated type of jammer that is able to adapt its jamming signal to maximize the disruption of the communication between the devices. Smart jammers are able to modify their attack pattern based on the transmission specifics of the devices they are targeting and are able to adapt to changes in the communication channel[11].

An effective Jamming detection AI model should achieve a high detection score against all the different types of jamming attacks.

3.3. Jamming attacks against drone networks

Jamming attacks are particularly effective against drone networks, as drones usually rely on external input to navigate and operate correctly. If a jammer were able to completely

block the communication between the drone and the base station, the drone would be left without any indication on how to behave and would need to activate an internal failsafe mechanism. This usually comes in the form of either a return to base procedure, a landing procedure or a hover in place procedure. All of these procedures leave the drone in a vulnerable position, as a bad actor could potentially capture the drone and use it for malicious purposes. This is especially true when jamming attacks are used in combination with other types of attacks, such as spoofing attacks.

One real world example of this is the capture of an American drone by Iran in 2011. In December 2011 a Lockheed Martin RQ-170 Sentinel drone operated by the United States Air Force was flying over Iran when its operators lost control of the vehicle. The US government initially claimed that the drone had crashed due to a technical malfunction, but later reports revealed that the drone had been captured by the Iranian military. Iranian electronic warfare specialists claimed to have brought it down using a Jamming attack, that forced the drone into a return to base procedure, in combination with a GPS spoofing attack, that made the drone land into a designated area [12]. After successfully capturing the drone, the Iranian government managed to reverse-engineer the drone and produce a working replica, which was then used in their military operations [13].

3.4. Centralized vs Edge approach for Jamming detection

When presenting a machine learning based approach in an IoT setting, the question of where the AI model should be placed often arises. By their nature, IoT devices, and in turn drones, are usually resource constrained, both in terms of computational power but also in terms of internal storage and battery capacity [14]. This means that complex AI models and algorithms are usually not feasible to be run on the device itself. A centralized approach offloads the computational burden to a central server, that returns the results of the AI model to the device. While this approach might be feasible in some cases, in a real-time situation such as a jamming attack, the latency introduced by the communication with the central server means less time to react to the attack. Also, as jamming attacks degrade or sometimes completely block the communication between the device and the base station, a centralized approach might not be feasible in this case. An lightweight edge approach on the other hand, while not as powerful as a centralized approach, would to provide real-time results to the device and would be able to operate even when the communication is disrupted.

3.5. Detection and Mitigation of Jamming Attacks

When attempting to mitigate jamming attacks, the first step is always to detect that an attack is taking place. This can be done by monitoring the communication channel for signs of jamming. The most common approaches involve the analysis of metrics such as the Signal to Noise Ration (SNR), the Received Signal Strength Indicator (RSSI) and the Packet Delivery Ratio (PDR) [15]. The most simple way to detect jamming attacks is to set a static threshold for these metrics and trigger an alarm when the threshold is crossed. While this approach easy to implement and might be effective in some cases, it is not able to adapt to changes in the communication channel and might be prone to false positives. Implementing a machine learning based approach for jamming detection would allow the system to adapt to the changes in the communication channel and would be able to provide a more accurate detection of jamming attacks [9]. This is especially useful in mobile scenarios like drone networks, where the environment is constantly changing and the signal strength can vary greatly.

Once an attack is successfully detected, state of the art jamming mitigation techniques, like Direct Sequence Spread Spectrum (DSSS), Frequency Hopping (FHSS) and advanced signal processing techniques can be put in place to mitigate the effects of the attack.

4. Materials and Methods

4.1. Scenario Definition and Attacker Classification

In the proposed scenario we have a flying drone that is subject to a jamming attack. The drone communicates with a ground station and periodically samples the Received Signal Strength (RSS) of the signal it receives. The drone implements a simple unsupervised machine learning algorithm module, trained on nominal traffic RSS values. The module takes the sampled RSS values and classifies them as either normal or anomalous. Thanks to this classification module, the drone is able to determine whether or not a jamming attack is taking place.

We assume that a jammer is deployed in the network and that it starts a jamming attack at a certain point in time by transmitting a strong signal on the same frequency as the one used by the drone to communicate with the ground station. We assume that the jammer is able to completely block the communication between the drone and the ground station, meaning the drone has to rely on its internal classification algorithm to determine if a jamming attack is taking place and react accordingly. We assume that the jammer type is unknown to the drone.

Figure 1 shows a diagram of the proposed scenario.

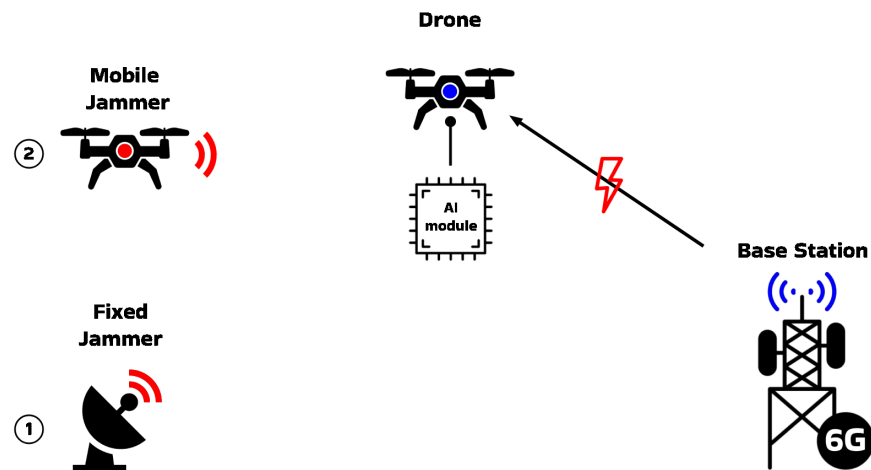


Figure 1. Proposed jamming scenario. The Drone communicates with the 6G base station and receives information about how to behave. The fixed jammer (1) and the mobile jammer (2) target the communication between the drone and the base station. The drone has an internal classification module that is able to detect jamming attacks.

In our scenario, the drone will be subject to two types of jamming attacks, a constant jamming attack and a periodic jamming attack. These types of attacks can be attributed to different types of jammers. The constant jamming attack could be caused by a ground jammer, as maintaining a constant jamming signal requires a large power source, while the periodic jamming attack could be caused by a drone jammer, as drones are usually battery powered and can only jam for a limited amount of time. Employing a periodic jamming attack could help the malicious drone conserve energy and reduce the chances of being detected.

Table 1 shows the attacker classification in the proposed scenario [16]:

Table 1. Attacker classification details.

Classification	Description
Active	The attacker is actively trying to disrupt network operation by transmitting a jamming signal
External	The attack takes place at level 1 of the OSI model, meaning that the attacker is not part of the network
Local	The attack is local, as it is targeted at a specific drone or drone cluster and not at the entire network
Malicious	Jamming attacks are considered malicious as their main goal is to disrupt correct network operation

4.2. Dataset Choice

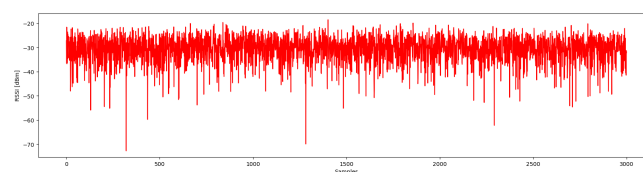
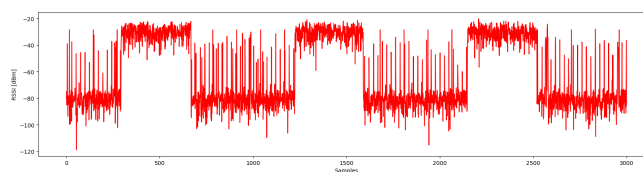
As 6G network traffic is not yet available, we chose an open-source dataset [17] that analyses the RSS values received by a Raspberry Pi 3 that is subject to periodic and constant jamming attacks.

The dataset was created using a software-defined radio (SDR) connected to a laptop that was programmed to transmit a jamming signal using the open source software *GNU Radio*. A second SDR radio was chosen to receive the jamming signal and the RSS values and was connected to a Raspberry Pi 3. The jamming radio operates at a frequency of 2.412 GHz with a Bandwidth of 40MHz, while the Raspberry Pi 3 was programmed to sample the RSS values with a frequency of 32K samples per second.

The dataset contains 3 different *.txt* files that store the RSS values sampled by the Raspberry Pi 3. The first file contains the RSS values sampled during a constant jamming attack, the second file contains the RSS values sampled during a periodic jamming attack and the third file contains the RSS values sampled during normal network operation. The samples are stored in a single column, with each row representing a single sample. The samples use the *dBm* (*decibel-milliwatts*) unit of measurement a logarithmic scale that measures the power of a signal in relation to 1 milliwatt. Conversion can be done using the formula [18] shown in equation 1:

$$P_{dBm} = 10 \cdot \log_{10} \left(\frac{P_{mW}}{1mW} \right) \quad (1)$$

Figures 2 and 3 show respectively plots of the RSS values sampled during a constant jamming attack and a periodic jamming attack.

**Figure 2.** Constant jamming attack RSS values**Figure 3.** Periodic jamming attack RSS values

4.3. Algorithm Choice

When choosing the algorithm for the classification module, we first had to define the requirements that the algorithm had to meet. The algorithm had to be able to classify anomalous samples with a high degree of accuracy, while at the same time being lightweight enough to be run on a resource constrained device like a drone. The training phase should also be fast, as this would allow the drone to redetermine the normal transmission RSS values in a constantly changing environment. If the model didn't periodically redefine normal RSS values, it would be prone to false positives caused by the mobile nature of drones. The model should be also required a limited amount of storage to be run effectively, as drones are usually lacking in internal storage.

The algorithm that best fit these requirements was the *Isolation Forest* algorithm [19]. The Isolation Forest algorithm is a state-of-the-art unsupervised machine learning algorithm for anomaly detection, introduced by Liu et al. in 2008. Unlike traditional anomaly detection algorithms, which require the definition of a normal class, Isolation Forest is able to detect anomalies without explicitly defining This is achieved by leveraging the properties of anomalies themselves, i.e being few and separated from the majority of the data points.

5. Results

This section may be divided by subheadings. It should provide a concise and precise description of the experimental results, their interpretation as well as the experimental conclusions that can be drawn.

5.1. Subsection

5.1.1. Subsubsection

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5.2. Figures, Tables and Schemes

All figures and tables should be cited in the main text as Figure 4, Table 2, etc.



Figure 4. This is a figure. Schemes follow the same formatting. If there are multiple panels, they should be listed as: (a) Description of what is contained in the first panel. (b) Description of what is contained in the second panel. Figures should be placed in the main text near to the first time they are cited. A caption on a single line should be centered.

Table 2. This is a table caption. Tables should be placed in the main text near to the first time they are cited.

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¹ Tables may have a footer.

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Table 3. This is a wide table.

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Entry 4	Data	Data	Data
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* Tables may have a footer.

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5.3. *Formatting of Mathematical Components*

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This is the example 1 of equation:

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$$a = 1,$$

(2)

the text following an equation need not be a new paragraph. Please punctuate equations as regular text.

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This is the example 2 of equation:

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$$a = b + c + d + e + f + g + h + i + j + k + l + m + n + o + p + q + r + s + t + u + v + w + x + y + z$$

(3)

Please punctuate equations as regular text. Theorem-type environments (including propositions, lemmas, corollaries etc.) can be formatted as follows:

Theorem 1. *Example text of a theorem.*

The text continues here. Proofs must be formatted as follows:

Proof of Theorem 1. Text of the proof. Note that the phrase “of Theorem 1” is optional if it is clear which theorem is being referred to. □

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6. Discussion

Authors should discuss the results and how they can be interpreted from the perspective of previous studies and of the working hypotheses. The findings and their implications should be discussed in the broadest context possible. Future research directions may also be highlighted.

7. Conclusions

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Data Availability Statement: We encourage all authors of articles published in MDPI journals to share their research data. In this section, please provide details regarding where data supporting reported results can be found, including links to publicly archived datasets analyzed or generated during the study. Where no new data were created, or where data is unavailable due to privacy or ethical restrictions, a statement is still required. Suggested Data Availability Statements are available in section “MDPI Research Data Policies” at <https://www.mdpi.com/ethics>.

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Abbreviations

The following abbreviations are used in this manuscript:

- SDN Software Defined Networks
- UAVs Unmanned Aerial Vehicles
- 3GPP 3rd Generation Partnership Project
- V2X Vehicle to Everything
- FPV First Person View
- DOS Denial Of Service
- SNR Signal to Noise Ratio
- RSSI Received Signal Strength Indicator
- PDR Packet Delivery Ratio
- CIA Confidentiality, Integrity, Availability
- IoT Internet of Things
- AI Artificial Intelligence
- DSSS Direct Sequence Spread Spectrum
- FHSS Frequency Hopping Spread Spectrum
- OSI Open Systems Interconnection
- dBm Decibel-milliwatts

Appendix A

Appendix A.1

The appendix is an optional section that can contain details and data supplemental to the main text—for example, explanations of experimental details that would disrupt the flow of the main text but nonetheless remain crucial to understanding and reproducing the research shown; figures of replicates for experiments of which representative data are shown in the main text can be added here if brief, or as Supplementary Data. Mathematical proofs of results not central to the paper can be added as an appendix.

Table A1. This is a table caption.

Title 1	Title 2	Title 3
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Appendix B

All appendix sections must be cited in the main text. In the appendices, Figures, Tables, etc. should be labeled, starting with “A”—e.g., Figure A1, Figure A2, etc.

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