Deblurring Images with Neural Networks

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Deep Learning Course Project prof. Andrea Asperti

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Autoencoder

An autoencoder is an artificial neural network that learns to copy its input to its output

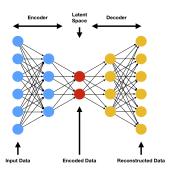


Figure: autoencoder model

Models:

- Plain Network
- Skip Connections
- ResNet

Plain Network

3 models:

$$C_{32}^{3,1} - C_{64}^{3,1} - C_{128}^{3,1} - D_{128}^{3,1} - D_{64}^{3,1} - D_{32}^{3,1} - D_{3,p}^{3,1}$$
 (1)

$$5C_8^{3,1} - 5C_{16}^{3,1} - 5C_{32}^{3,1} - 5D_{32}^{3,1} - 5D_{16}^{3,1} - 5D_8^{3,1} - D_{3,p}^{3,1}$$
 (2)

$$4C_{16}^{3,1} - 4C_{32}^{3,1} - 4C_{64}^{3,1} - 4D_{64}^{3,1} - 4D_{32}^{3,1} - 4D_{16}^{3,1} - D_{3,p}^{3,1}$$
 (3)

| | CNNBase_v1 | CNNBase_v2 | CNNBase_v3 | SkipConnections_v1 | SkipConnections_v2 | ResNet_v1 | ResNet_v2 |
|---------------|------------|------------|------------|--------------------|--------------------|-----------|-----------|
| Total Params. | 333955 | 118499 | 375011 | 370833 | 130099 | 2187715 | 236227 |

Figure: Table of the toltal number of parameters in each network

Skip Connections

2 models:

$$C1_{32}^{3,1} - C2_{64}^{3,1} - C3_{64}^{3,1} - C4_{128}^{3,1} - D5_{128}^{3,1} - D6_{64}^{3,1} - S7_{C2} - D8_{32}^{3,1} - S9_X - D10_{3,p}^{3,1}$$
(4)

$$5C_8^{3,1} - 10C_{16}^{3,1} - 5C_{32}^{3,1} - 5D_{32}^{3,1} - 5D_{16}^{3,1} - S_{C6} - 2D_8^{3,1} - S_{C4} - 2D_8^{3,1} - S_{C2} - D_8^{3,1} - S_{8X} - D_{3,p}^{3,1}$$
(5)

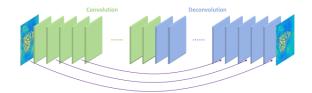


Figure: Skip Connections Model

Skip Connections

2 models:

$$C_{32}^{5,2} - R_{32}^5 - C_{64}^{5,2} - R_{64}^5 - C_{128}^{5,2} - R_{128}^3 - D_{128}^{3,2} - R_{128}^5 - D_{64}^{5,2} - R_{64}^5 - D_{32}^{8,2} - D_{3,p}^{3,1}$$

$$(6)$$

$$C_8^{5,2} - 2R_8^5 - C_{16}^{5,2} - 2R_{16}^5 - C_{16}^{5,2} - 2R_{16}^5 - C_{32}^{3,1} - 2R_{32}^3 - D_{32}^{3,1} - 2R_{32}^5 - D_{16}^{3,1} - 2R_{16}^5 - D_8^{8,1} - D_{3,p}^{3,1}$$

$$(7)$$

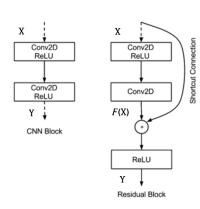


Figure: Residual block

CIFAR10 Results



Figure: Output examples

CIFAR10 Results

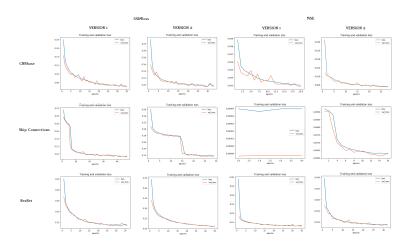


Figure: Loss Accuracy Comparison between different networks on CIFAR10

CIFAR10 Results

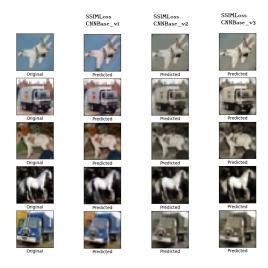


Figure: Outputs comparison with different version of CNNBase scheme

Kernel Motion Approach

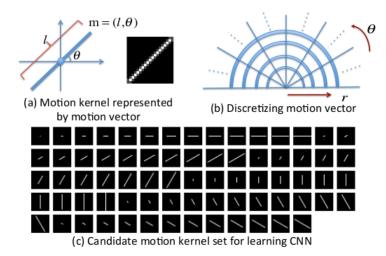


Figure: Representation of motion blur kernel by motion vector and generation of motion kernel candidates

Style Transfer Approach

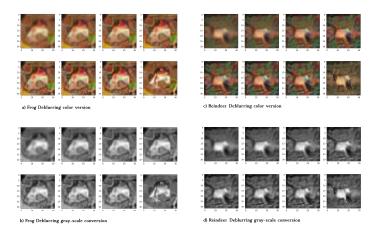


Figure: Style Transfer outputs on two images of CIFAR10. The last image in each group is the sharp image.