# FRANCESCO FABIANO

## Curriculum Vitae

## PERSONAL INFORMATION

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AFFILIATIONS Oxford University • Kellogg College
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PERSONAL E-MAIL fabianofrancesco.cs@gmail.com
ttps://francescofabiano.github.io

#### Research Interests

Artificial Intelligence • Hybrid AI Systems • Multi-agent Systems • Automated Planning • Logic/Constraint Programming • Epistemic/Doxastic Reasoning • Knowledge Representation • Belief Manipulation • Belief Update

#### LANGUAGES

Italian native speaker

English highly proficient in both spoken and written language

Spanish basic knowledge



## Work Experience

01/2025- Associate Researcher ongoing

Employer: University of Oxford, Oxford, United Kingdom

Description: Part of the Erlangen AI Hub, at the University of Oxford, focused on investigating the

Computational Foundations of AI and particularly on Understanding Decision Making.

10/2025— Lecturer in Computer Science 09/2026

Employer: Trinity College – University of Oxford, Oxford, United Kingdom

Description: Lecturer at Trinity College, providing tutorial support to Computer Science students for

the course "Imperative Programming".

08/2024- Affiliated Faculty Member ongoing

Employer: New Mexico State University, Las Cruces (NM), USA

Description: Affiliated Faculty at the Computer Science Department of New Mexico State University

to conduct research on Multi-Agent Epistemic Planning.

04/2020- **Joint Researcher** (telecommuting due to COVID-19 pandemic) ongoing

Employer

Employers: International Business Machines (IBM) Corporation, Yorktown Heights (NY), USA

Description: Participated at the IBM exploratory challenge #2106. The project, coordinated by

Francesca Rossi, aimed to develop a general and robust Artificial Intelligence paradigm starting from cognitive theories such as the one proposed by D. Kahneman in his book

"Thinking Fast and Slow".

08/2023- Assistant Professor

08/2024

Employer: New Mexico State University, Las Cruces (NM), USA

Description: Structured and taught undergraduate and graduate courses at the Computer Science De-

partment. Furthermore, I focused on research in neuro-symbolic AI, automated planning,

multi-agent epistemic reasoning, and computational logic.

SUMMER 2024 "Applied Machine Learning I" (CS 487/519).

Spring 2024 "Analysis of Algorithms" (CS 570); "Applied Machine Learning I"

Courses: (CS 487/519); and "Python Programming I" (CS 153/453).

Fall 2023 "Parallel Programming" (CS 491/521); "Python Programming I"

(CS 153/453); and "C++ Programming" (CS 151/451).

01/2023- Adjunct Professor 07/2023

Employer: Saint Joseph's University, Philadelphia (PA), USA

Description: Structured and taught the undergraduate and graduate courses offered by the "Decision

& System Sciences" curriculum at the Erivan K. Haub School of Business. Moreover, I focused on research in neuro-symbolic AI, automated planning, and computational logic

Summer 2023 "Advanced Python Programming" (DSS 770).

Courses: Spring 2023 "BIA: Concepts & Practices" (DSS 315); "Python Programming"

(DSS 615); "Advanced Python Programming" (DSS 693).

10/2022− Adjunct Professor - "Typing in LATEX" 09/2023

Employer: University of Parma, Parma, Italy

Description: Structured and taught the undergraduate course "Typing in LATEX", open to all the

students of the University. The course was designed to help the students acquire the necessary capabilities to realize documents using the typesetting language LATEX. The teaching was comprised of 24 hours (equivalent to 3 Italian credits) of frontal lectures

and exercises. Finally, the evaluation was based on a project.

01/2021- Research Associate - "Artificial Intelligence for packaging production lines"

12/2022

Employers: University of Parma, Parma, Italy &

ACMI S.P.A., Fornovo Taro (PR), Italy

Description: Implemented an automated reasoning tool that makes use of innovative techniques (e.g.,

constraint programming, planning, etc.) to model production processes and that returns an optimized and safe plan that controls the robotic components in the production line.

08/2017- Web Master

05/2018

Employer: New Mexico State University, Las Cruces (NM), USA

Description: Migrated the website of the College of Arts and Sciences to a user-friendly platform to

simplify the College's staff work. After the migration, support and maintenance for the

website was provided.

01/2017- Research Assistant

07/2017

Employer: New Mexico State University, Las Cruces (NM), USA

Description: Studied, under Prof. Enrico Pontelli, the design of an epistemic forward planner with par-

ticular attention to heuristics for the solving process and optimizations for the underlying

knowledge representation.

EDUCATION

11/2018- Ph.D. in Computer Science, cum Laude

06/2022 University of Udine, Udine, Italy

Award: Best Ph.D. Thesis Award by GULP, 2022 (500 €)

Advisors: Profs. Agostino Dovier, Alessandro Dal Palù and Enrico Pontelli

Thesis title: "Planning while Believing to Know"

## 01/2017- Master's Degree in Computer Science

05/2018 New Mexico State University, Las Cruces (NM), USA

Advisor: Prof. Enrico Pontelli

Thesis title: "EFP and PG-EFP: Epistemic Forward Planners in multi-agent domains"

## 10/2013- Bachelor's Degree in Computer Science

12/2016 University of Parma, Parma, Italy

Award: Best UniPR Computer Science Student Award by UNICT & Cisita, 2015

Advisor: Prof. Alessandro Dal Palù

Thesis title: "Load distribution analysis in an MPI framework"

## 09/2008- Liceo Scientifico G. Marconi

06/2013 Parma, Italy

## Fellowships & Awards

UNICT & Cisita	Best UniPR Computer Science Student Award		2015
University of Udine	Ph.D. Scholarship	€ 15 343 p.a.	2018/2021
University of Parma & ACMI S.P.A.	Research Fellowship	€ 27 088 p.a.	2021/2022
Gruppo ricercatori e Utenti Logic Programming	Ph.D. Thesis Award	€ 500	2022
USA National Institute of Standards and Technology	Research Grant (sub-contract)	\$ 1000	2023
USA National Institute of Standards and Technology	Research Grant (sub-contract)	\$ 10 000	2024
The Pedro Arrupe, S.J., Center for Bussiness Ethics	PRME/SDG Dashboard Research Fellow	\$ 5000 p.a.	2023–2025
University of Oxford, Department of Computer Science	Research grant at UKRI AI Hub Project	£ 41 636 p.a.	2025/2026
UK Visas and Immigration	Global Talent Visa — Unrestricted right to work in	n the UK	2025/2028
OpenAl	OpenAI API Researcher Access Program	\$ 1000	2025/2026
Kellogg College	(non-stipendiary) Junior Research Fellowship		2025/2027

## TEACHING/DIVULGATION

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"Imperative Programming"	Trinity Colleg, Univ. of Oxford	2024/2025
CS 570 "Analysis of Algorithms"	New Mexico State University	2024
CS 487/519 "Applied Machine Learning I"	New Mexico State University	2024
CS 153/453 "Python Programming I"	New Mexico State University	2024
CS 491/521 "Parallel Programming"	New Mexico State University	2023
CS 151/451 "C++ Programming"	New Mexico State University	2023
DSS 770 "Advanced Python Programming"	Saint Joseph's University	2023
DSS 693 "Advanced Python Programming"	Saint Joseph's University	2023
DSS 615 "Python Programming"	Saint Joseph's University	2023
DSS 315 "Business Intelligence & Analytics: Concepts & Practices"	Saint Joseph's University	2023
"Typing in LaTEX"	University of Parma	2022/2023

"Algorithms and Data Structures" (Teaching Assistant)	Unive	rsity of Udine	2020/2021
Advising			
College Advisor to 5 students	Kellogg C	college (Univ. of Oxford)	2025-2026
Co-Advisor of 4 Master Theses	University		2019–2022
Co-Advisor of 18 Bachelor Theses	•	es of Udine & Parma	2019-2024
Conference Presentations			
"Building Neurosymbolic Systems with Metacognitive Con	atrol"	Lab @ AAAI 2025	26/02/2025
"H-EFP: Bridging Efficiency in Multi-Agent Epistemic Planning with Heuristic		PRIMA 2024	20/11/2024
"An Explainable Multilingual Framework for Data Analys		ICLP 2024	17/10/2024
"Multi-agent Epistemic Planning with Inconsistent Beliefs		PRICAI 2021	09/11/2021
"Comprehensive Multi-Agent Epistemic Planning"		DC @ ICLP 2021	22/09/2021
"E-PDDL: A Standardized Way of Defining Epistemic Pla	anning Problems"	KEPS @ ICAPS 2021	05/08/2021
"EFP 2.0: A Multi-Agent Epistemic Solver with Multiple e-State	e Representations"	ICAPS 2020	27/10/2020
"An ASP approach for arteries classification in CT-scans	,"	CILC 2020	15/10/2020
"Towards a Complete Characterization of Epistemic Reasoning"		CILC 2020	13/10/2020
"Design of a Solver for Multi-Agent Epistemic Planning"		ICLP 2019	24/09/2019
"Design of a Solver for Multi-Agent Epistemic Planning"		DC @ ICLP 2019	22/09/2019
"Non-Well-Founded Set Based Multi-Agent Action Langu	age"	CILC 2019	27/08/2019
Seminars and Talks			
"Thinking Fast and Slow in AI"	Erlangen Al Meet	ting @ Univ. of Oxford	20/05/2025
"Planning while Believing to Know"	_	nar @ Univ. of Oxford	23/04/2025
"Planning while Believing to Know"  OXCAV Seminar @ Univ. of Oxford		06/02/2025	
"Modeling Multi-Agent Epistemic Planning in ASP" Declarative Programming class @ UniPR		16/12/2024	
"Planning while Believing to Know" Haub Innovation Speaker @ SJU		17/02/2023	
"Modeling Multi-Agent Epistemic Planning in ASP" Declarative Programming class @ UniPR		30/11/2022	
"Thinking Fast and Slow in AI" Al4HRC workshop @ UniUD		28/03/2022	
"Planning while Believing to Know" ES seminar @ FBK		14/02/2020	
"Modeling Multi-Agent Epistemic Planning in ASP" Automated Reasoning class @ UniUD		12/12/2020	
"Epistemic Reasoning in Crime Reconstruction" COST Action 17124 meeting		09/12/2019	
"A Study on Fingerprint Inheritance through AI"			09/11/2019
$"Ill-Founded \ Multi-Agent \ Epistemic \ Action \ Language"$	"Ill-Founded Multi-Agent Epistemic Action Language" iFM <sup>2</sup> seminar @ UniUD		11/06/2019
"Inheritance in Fingerprints"	"Inheritance in Fingerprints" GNCS-2019 workshop @ UniPR		04/06/2019
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#### SCIENTIFIC CONTRIBUTIONS

"Epistemic Planning"

## **Projects Participation**

GNCS-2023	"ARICSxAI: Automated Reasoning Interpretation of CT-Scans and xAI"
GNCS-2022	"InSANE: Investigating Sparse Algorithms in the post von Neumann Era"
GNCS-2020	"NoRMA: Automazione del Ragionamento Non-Monotono su Moderne Architetture Parallele"
GNCS-2019	"Logic Programming for Early Detection of Pancreatic Cancer"
PRID-ENCASE 2019	"Efforts in the Understanding of Complex Interacting Systems"

GNCS-2019 workshop @ UniPR

03/06/2019

#### Research Proposal/Grants Reviewer

Toulouse Initiative for Research's Impact on Society (TIRIS), 2025 – Junior Fellowship Program • Dutch Research Council (NWO), 2024 – Research Proposal

## Chair

PRIMA, 2024 – Session Chair • SYNERGY @KR, 2024 – Organizer & Chair • ICLP & LPNMR, 2024 – Autumn School on Logic Programming Organizer • ICLP & LPNMR, 2024 – Doctoral Consortium Organizer & Chair • ICLP, 2023 – Doctoral Consortium Organizer & Chair • ICLP 2023, Session Chair

## PC Member

AAAI-AIA, 2026 • AAAI, 2026 • AIES, 2025 • ECAI, 2025 • ICLP, 2025 • IJCAI, 2025 • AAAI, 2025 • AIES, 2024 • ICLP, 2024 • IJCAI, 2024 • AAAI, 2024 • ICLP, 2023 • CILC, 2023 • IEEE ICTAI, 2022 • ACAIN, 2022 • OVERLAY, 2022 • CILC, 2022 • IJCAI, 2022 • IEEE ICTAI, 2021 • IJCAI, 2021

## Journal Reviews

International Journal of Computer Theory and Engineering (IJCTE), 2024 • Journal of Artificial Intelligence Research (JAIR), 2024 • Journal of Computer Languages (COLA), 2024 • The Journal of Supercomputing, 2024 • Journal of Logic and Computation (JLC), 2023 • Journal of Artificial Intelligence (AIJ), 2019

#### Conference Reviews and Sub-Reviews

PADL, 2024 • AAMAS, 2023 • AIxIA, 2022 • CP, 2022 • IJCAI, 2022 • IEEE ICTAI, 2021 • IJCAI, 2021 • ECAI, 2020 • ICLP, 2020 • IEEE ICTAI, 2020 • IJCAI, 2020 • AIIA, 2019 • LPNMR, 2019

## SCIENTIFIC PUBLICATIONS

A complete list of my publications can be found on my DBLP and Google Scholar pages, as well as in the lists below.

#### Editor

- [E1] Pedro Cabalar et al., eds. Proceedings 40th International Conference on Logic Programming, ICLP 2024, University of Texas at Dallas, Dallas Texas, USA, October 14-17 2024. Vol. 416. EPTCS. 2025. DOI: 10.4204/EPTCS.416.
- [E2] Lucía Gómez Álvarez et al., eds. Joint Proceedings of the Joint Workshop on Knowledge Diversity and Cognitive Aspects of KR and the Workshop on Symbolic and Neuro-Symbolic Architectures for Intelligent Robotics Technology (KoDis-CAKR-SYNERGY 2024) co-located with the 21st International Conference on Principles of Knowledge Representation and Reasoning (KR 2024), Hanoi, Vietnam, November 2-8, 2024. Vol. 3876. CEUR Workshop Proceedings. CEUR-WS.org, 2024. URL: https://nbn-resolving.org/urn:nbn:de:0074-3876-8.
- [E3] Enrico Pontelli et al., eds. Proceedings 39th International Conference on Logic Programming, ICLP 2023, Imperial College London, UK, 9th July 2023 15th July 2023. Vol. 385. EPTCS. 2023. DOI: 10.4204/EPTCS.385.

#### Journal Articles

- [J1] M. Bergamaschi Ganapini et al. "Fast, slow, and metacognitive thinking in AI". In: npj Artificial Intelligence 1.1 (Oct. 2025), p. 27. ISSN: 3005-1460. DOI: 10.1038/s44387-025-00027-5.
- [J2] Francesco Fabiano et al. "Thinking Fast and Slow in Human and Machine Intelligence". In: Commun. ACM 68.8 (July 2025), pp. 72–79. ISSN: 0001-0782. DOI: 10.1145/3715709.
- [J3] Davide Soldà, Francesco Fabiano, and Agostino Dovier. "ECHO: A hierarchical combination of classical and multi-agent epistemic planning problems." In: *J. Log. Comput.* 33.8 (2023), pp. 1804–1831. DOI: 10.1093/LOGCOM/EXADO36.
- [J4] Francesco Fabiano and Alessandro Dal Palù. "An ASP approach for arteries classification in CT scans." In: *J. Log. Comput.* 32.2 (2022), pp. 331–346. DOI: 10.1093/LOGCOM/EXAB087.
- [J5] Alessandro Burigana et al. "Modelling Multi-Agent Epistemic Planning in ASP." In: Theory Pract. Log. Program. 20.5 (2020), pp. 593–608. DOI: 10.1017/S1471068420000289.

## Conference Papers

- [C1] Flavio Bertini et al. "Concept2Text: An Explainable Multilingual Rewriting of Concepts into Natural Language." In: Proceedings of the 39th Italian Conference on Computational Logic, Rome, Italy, June 26-28, 2024. 2024. URL: https://ceur-ws.org/Vol-3733/paper14.pdf.
- [C2] Flavio Bertini et al. "Data2Concept2Text: An Explainable Multilingual Framework for Data Analysis Narration." In: Proceedings 40th International Conference on Logic Programming, ICLP 2024, University of Texas at Dallas, Dallas Texas, USA, October 14-17 2024. 2024, pp. 139-152. DOI: 10.4204/EPTCS.416.13.
- [C3] David Buckingham et al. "Action Language mA\* with Higher-Order Action Observability." In: Proceedings of the 21st International Conference on Principles of Knowledge Representation and Reasoning, KR 2024, Hanoi, Vietnam. November 2-8, 2024. 2024. DOI: 10.24963/KR.2024/20.
- [C4] Francesco Fabiano et al. "H-EFP: Bridging Efficiency in Multi-agent Epistemic Planning with Heuristics." In: PRIMA 2024: Principles and Practice of Multi-Agent Systems 25th International Conference, Kyoto, Japan, November 18-24, 2024, Proceedings. 2024, pp. 81–86. DOI: 10.1007/978-3-031-77367-9\_7.
- [C5] Vishal Pallagani et al. "On the Prospects of Incorporating Large Language Models (LLMs) in Automated Planning and Scheduling (APS)." In: Proceedings of the Thirty-Fourth International Conference on Automated Planning and Scheduling, ICAPS 2024, Banff, Alberta, Canada, June 1-6, 2024. 2024, pp. 432–444. DOI: 10.1609/ICAPS.V34I1.31503.
- [C6] Marianna Bergamaschi Ganapini et al. "Value-based Fast and Slow AI Nudging." In: Proceedings of the Workshop on Ethics and Trust in Human-AI Collaboration: Socio-Technical Approaches (ETHAICS 2023) co-located with 32nd International Joint Conference on Artificial Intelligence (IJCAI 2023) Macao, August 21, 2023., Macao, August 21, 2023. 2023. URL: https://ceur-ws.org/Vol-3547/paper6.pdf.

- [C7] Vishal Pallagani et al. "Plansformer Tool: Demonstrating Generation of Symbolic Plans Using Transformers." In: Proceedings of the Thirty-Second International Joint Conference on Artificial Intelligence, IJCAI 2023, 19th-25th August 2023, Macao, SAR, China. 2023, pp. 7158-7162. DOI: 10.24963/IJCAI.2023/839.
- [C8] Flavio Bertini et al. "CARING for xAI." In: Proceedings of the 37th Italian Conference on Computational Logic, Bologna, Italy, June 29 - July 1, 2022. 2022, pp. 47-60. URL: https://ceur-ws.org/Vol-3204/paper\_5.pdf.
- [C9] Alessandro Burigana and Francesco Fabiano. "The Epistemic Planning Domain Definition Language (Short Paper)." In: Proceedings of the 10th Italian workshop on Planning and Scheduling (IPS 2022), RCRA Incontri E Confronti (RiCeRcA 2022), and the workshop on Strategies, Prediction, Interaction, and Reasoning in Italy (SPIRIT 2022) co-located with 21st International Conference of the Italian Association for Artificial Intelligence (AIxIA 2022), November 28 December 2, 2022, University of Udine, Udine, Italy. 2022. URL: https://ceurws.org/Vol-3345/paper5\_2497.pdf.
- [C10] Marianna Bergamaschi Ganapini et al. "Combining Fast and Slow Thinking for Human-like and Efficient Decisions in Constrained Environments." In: Proceedings of the 16th International Workshop on Neural-Symbolic Learning and Reasoning as part of the 2nd International Joint Conference on Learning & Reasoning (IJCLR 2022), Cumberland Lodge, Windsor Great Park, UK, September 28-30, 2022. 2022, pp. 171–185. URL: https://ceur-ws.org/Vol-3212/paper12.pdf.
- [C11] Marianna Bergamaschi Ganapini et al. "Thinking Fast and Slow in AI: The Role of Metacognition." In: Machine Learning, Optimization, and Data Science - 8th International Workshop, LOD 2022, Certosa di Pontignano, Italy, September 19-22, 2022, Revised Selected Papers, Part II. 2022, pp. 502-509. DOI: 10.1007/978-3-031-25891-6\_38.
- [C12] Davide Soldà, Francesco Fabiano, and Agostino Dovier. "Epistemic Multiagent Reasoning with Collaborative Robots." In: Proceedings of the 37th Italian Conference on Computational Logic, Bologna, Italy, June 29 July 1, 2022. 2022, pp. 32-46. URL: https://ceur-ws.org/Vol-3204/paper\_4.pdf.
- [C13] Grady Booch et al. "Thinking Fast and Slow in AI." In: Thirty-Fifth AAAI Conference on Artificial Intelligence, AAAI 2021, Thirty-Third Conference on Innovative Applications of Artificial Intelligence, IAAI 2021, The Eleventh Symposium on Educational Advances in Artificial Intelligence, EAAI 2021, Virtual Event, February 2-9, 2021. 2021, pp. 15042–15046. DOI: 10.1609/AAAI.V35I17.17765.
- [C14] Francesco Fabiano. "Comprehensive Multi-Agent Epistemic Planning." In: Proceedings 37th International Conference on Logic Programming (Technical Communications), ICLP Technical Communications 2021, Porto (virtual event), 20-27th September 2021. 2021, pp. 248–257. DOI: 10.4204/EPTCS.345.41.
- [C15] Francesco Fabiano et al. "Epistemic Planning in a Fast and Slow Setting." In: Proceedings of the Thinking Fast and Slow and Other Cognitive Theories in AI, a AAAI 2022 Fall Symposium, Westin Arlington Gateway in Arlington, Virginia, November 17-19, 2022. 2021. URL: https://ceur-ws.org/Vol-3332/paper7.pdf.
- [C16] Francesco Fabiano et al. "Multi-agent Epistemic Planning with Inconsistent Beliefs, Trust and Lies." In: PRICAI 2021: Trends in Artificial Intelligence - 18th Pacific Rim International Conference on Artificial Intelligence, PRICAI 2021, Hanoi, Vietnam, November 8-12, 2021, Proceedings, Part I. 2021, pp. 586-597. DOI: 10.1007/978-3-030-89188-6\_44.
- [C17] Marianna Bergamaschi Ganapini et al. "Combining Fast and Slow Thinking for Human-like and Efficient Navigation in Constrained Environments." In: Proceedings of the Thinking Fast and Slow and Other Cognitive Theories in AI, a AAAI 2022 Fall Symposium, Westin Arlington Gateway in Arlington, Virginia, November 17-19, 2022. 2021. URL: https://ceur-ws.org/Vol-3332/paper10.pdf.
- [C18] Francesco Fabiano. "Towards a Complete Characterization of Epistemic Reasoning: the Notion of Trust." In: Proceedings of the 35th Italian Conference on Computational Logic CILC 2020, Rende, Italy, October 13-15, 2020. 2020, pp. 21-35. URL: https://ceur-ws.org/Vol-2710/paper2.pdf.
- [C19] Francesco Fabiano and Alessandro Dal Palù. "An ASP Approach for Arteries Classification in CT-scans." In: Proceedings of the 35th Italian Conference on Computational Logic CILC 2020, Rende, Italy, October 13-15, 2020. 2020, pp. 312-326. URL: https://ceur-ws.org/Vol-2710/paper20.pdf.
- [C20] Francesco Fabiano et al. "EFP 2.0: A Multi-Agent Epistemic Solver with Multiple E-State Representations." In: Proceedings of the Thirtieth International Conference on Automated Planning and Scheduling, Nancy, France, October 26-30, 2020. 2020, pp. 101-109. URL: https://ojs.aaai.org/index.php/ICAPS/article/view/6650.
- [C21] Francesco Fabiano. "Design of a Solver for Multi-Agent Epistemic Planning." In: Proceedings 35th International Conference on Logic Programming (Technical Communications), ICLP 2019 Technical Communications, Las Cruces, NM, USA, September 20-25, 2019. 2019, pp. 403-412. DOI: 10.4204/EPTCS.306.54.
- [C22] Francesco Fabiano et al. "Non-Well-Founded Set Based Multi-Agent Epistemic Action Language." In: Proceedings of the 34th Italian Conference on Computational Logic, Trieste, Italy, June 19-21, 2019. 2019, pp. 242-259. URL: https://ceur-ws.org/Vol-2396/paper38.pdf.
- [C23] Tiep Le et al. "EFP and PG-EFP: Epistemic Forward Search Planners in Multi-Agent Domains." In: Proceedings of the Twenty-Eighth International Conference on Automated Planning and Scheduling, ICAPS 2018, Delft, The Netherlands, June 24-29, 2018. 2018, pp. 161-170. URL: https://aaai.org/ocs/index.php/ICAPS/ICAPS18/ paper/view/17733.

## **Technical Reports and Preprints**

- [T1] Alessandro Abate et al. "Best-Effort Policies for Robust Markov Decision Processes". In: CoRR abs/2508.07790 (2025). DOI: 10.48550/ARXIV.2508.07790. arXiv: 2508.07790.
- [T2] Giovanni Briglia, Francesco Fabiano, and Stefano Mariani. "Scaling Multi-Agent Epistemic Planning through GNN-Derived Heuristics". In: CoRR abs/2508.12840 (2025). DOI: 10.48550/ARXIV.2508.12840. arXiv: 2508. 12840.
- [T3] Frederik Baymler Mathiesen et al. "Certified Neural Approximations of Nonlinear Dynamics". In: CoRR abs/2505.15497 (2025). DOI: 10.48550/ARXIV.2505.15497. arXiv: 2505.15497.
- [T4] Vishal Pallagani et al. On the Prospects of Incorporating Large Language Models (LLMs) in Automated Planning and Scheduling (APS). 2024. DOI: 10.48550/ARXIV.2401.02500.
- [T5] Francesco Fabiano et al. Fast and Slow Planning. 2023. DOI: 10.48550/ARXIV.2303.04283.
- [T6] Marianna Bergamaschi Ganapini et al. Value-based Fast and Slow AI Nudging. 2023. DOI: 10.48550/ARXIV. 2307.07628.
- [T7] Vishal Pallagani et al. Understanding the Capabilities of Large Language Models for Automated Planning. 2023.

  DOI: 10.48550/ARXIV.2305.16151.
- [T8] Marianna Bergamaschi Ganapini et al. Combining Fast and Slow Thinking for Human-like and Efficient Navigation in Constrained Environments. 2022. URL: https://arxiv.org/abs/2201.07050.
- [T9] Vishal Pallagani et al. Plansformer: Generating Symbolic Plans using Transformers. 2022. DOI: 10.48550/ARXIV. 2212.08681.
- [T10] Francesco Fabiano et al. E-PDDL: A Standardized Way of Defining Epistemic Planning Problems. 2021. URL: https://arxiv.org/abs/2107.08739.
- [T11] Marianna Bergamaschi Ganapini et al. Thinking Fast and Slow in AI: the Role of Metacognition. 2021. URL: https://arxiv.org/abs/2110.01834.
- [T12] Grady Booch et al. Thinking Fast and Slow in AI. 2020. URL: https://arxiv.org/abs/2010.06002.
- [T13] Alessandro Burigana et al. Modelling Multi-Agent Epistemic Planning in ASP. 2020. URL: https://arxiv.org/abs/2008.03007.