


Advanced Operating Systems
MS degree in Computer Engineering
University of Rome Tor Vergata 
Lecturer: Francesco Quaglia

Kernel level memory management

1. The very base on boot vs memory management
2. Memory ‘Nodes’ (UMA vs NUMA)
3. x86 paging support
4. Boot and steady state behavior of the memory management system in the Linux kernel

Basic terminology

- **firmware**: a program coded on a ROM device, which can be executed when powering a processor on
- **bootsector**: predefined device (e.g. disk) sector keeping executable code for system startup
- **bootloader**: the actual executable code loaded and launched right before giving control to the target operating system
 - this code is partially kept within the bootsector, and partially kept into other sectors
 - It can be used to parameterize the actual operating system boot

Startup tasks

- The firmware gets executed, which loads in memory and launches the bootsector content
- The loaded bootsector code gets launched, which may load other bootloader portions
- The bootloader ultimately loads the actual operating system kernel and gives it control
- The kernel performs its own startup actions, which may entail architecture setup, data structures and software setup, and process activations
- To emulate a steady state unique scenario, at least one process is derived from the boot thread (namely the IDLE PROCESS)

Where is memory management there?

- All the previously listed steps lead to change the image of data that we have in memory
- These changes need to happen just based on various memory handling policies/mechanisms, operating at:

- ✓ Kernel load time
- ✓ Kernel initialization (including kernel level memory management initialization)
- ✓ Kernel common operations (which make large usage of kernel level memory management services that have been setup along the boot phase)

An initially loaded kernel memory-image is not the same as the one that common applications ``see'' when they are activated

Traditional firmware on x86

- It is called BIOS (Basic I/O System)
- Interactive mode can be activated via proper interrupts (e.g. the F1 key)
- Interactive mode can be used to parameterize firmware execution (the parameterization is typically kept via CMOS rewritable memory devices powered by apposite temporary power suppliers)
- The BIOS parameterization can determine the order for searching the boot sector on different devices
- A device boot sector will be searched for only if the device is registered in the BIOS list

Bios bootsector

- The first device sector keeps the so called **master boot record** (MBR)
- This sector keeps executable code and a 4-entry tables, each one identifying a different device partition (in terms of its positioning on the device)
- The first sector in each partition can operate as the partition boot sector (BS)
- In case the partition is extended, then it can additionally keep up to 4 sub-partitions (hence the partition boot sector can be structured to keep an additional partitioning table)
- Each sub-partition can keep its own boot sector

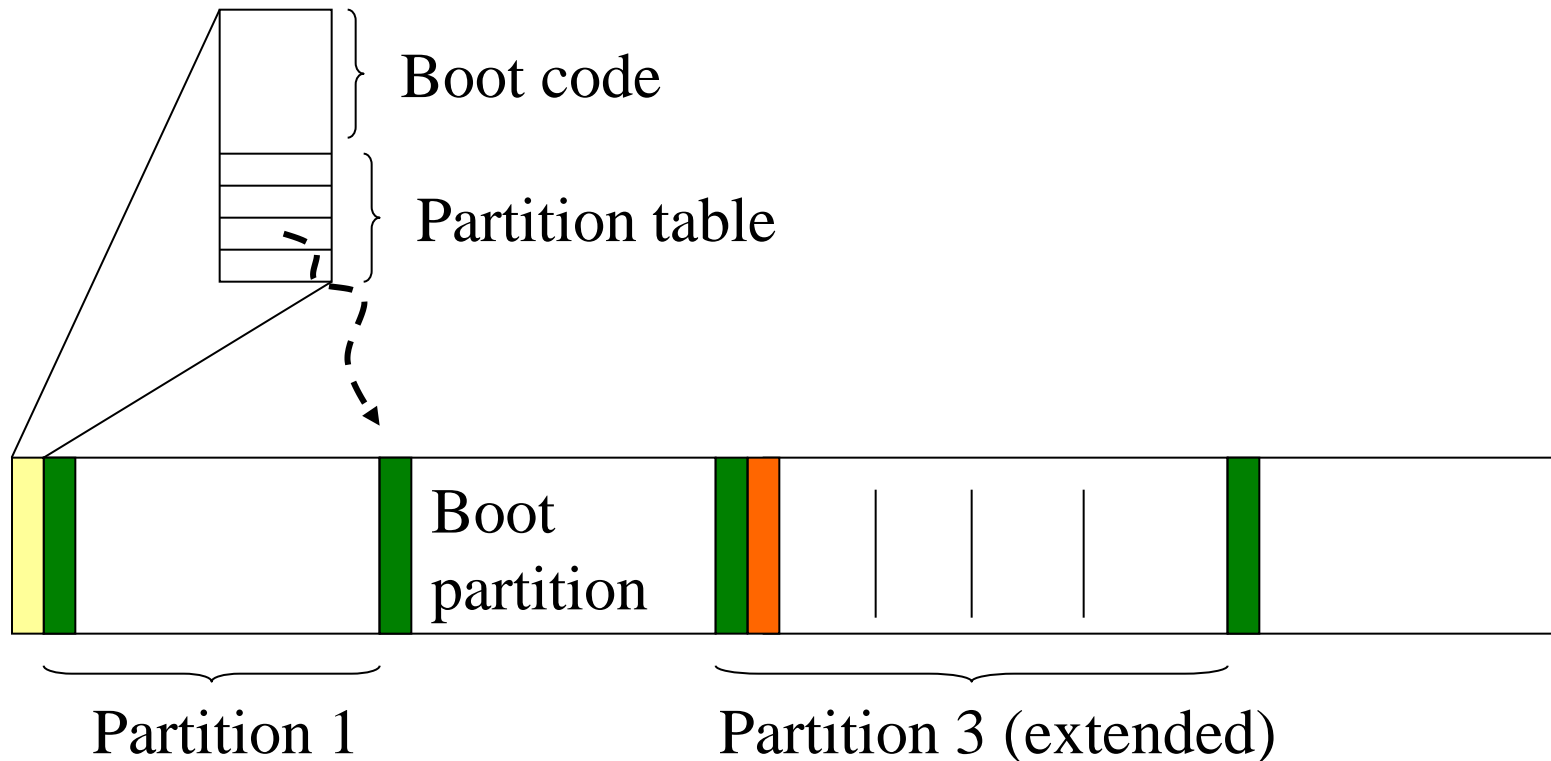
RAM image of the MBR

Offset	Size (bytes)	Description
0	436 (to 446, if you need a little extra)	MBR Bootstrap (flat binary executable code)
0x1b4	10	Optional "unique" disk ID ¹
0x1be	64	MBR Partition Table , with 4 entries (below)
0x1be	16	First partition table entry
0x1ce	16	Second partition table entry
0x1de	16	Third partition table entry
0x1ee	16	Fourth partition table entry
0x1fe	2	(0x55, 0xAA) "Valid bootsector" signature bytes



Grub (if you use it) or others

An example scheme with Bios



Boot sector



Extended partition boot record

Nowadays huge limitation:
the maximum size of
manageable disks is 2TB

UEFI – Unified Extended Firmware Interface

- It is the new standard for basic system support (e.g. boot management)
- It removes several limitations of Bios:
 - We can (theoretically) handle disks up to 9 zettabytes
 - It has a more advanced visual interface
 - It is able to run EFI executables, rather than simply running the MBR code
 - It offers interfaces to the OS for being configured (rather than being exclusively configurable by triggering its interface with Fn keys at machine startup)

UEFI device partitioning

- Based on GPT (GUID Partition Table)
- GUID = Globally Unique Identifier Theoretically all over the world (if the GPT has in its turn a unique identifier)
- Theoretically unbounded number of partitions kept in this table – No longer we need extended partitions for enlarging the partitions' set
- GPT are replicated so that if a copy is corrupted then another one will work – this breaks the single point of failure represented by MBR and its partition table

Bios/UEFI tasks upon booting the OS kernel

- The bootloader/EFI-loader, e.g., GRUB loads in memory the initial image of the operating system kernel
- This includes a ``machine setup code'' that needs to run before the actual kernel code takes control
- This happens since a kernel configuration needs given setup in the hardware upon being launched
- The machine setup code ultimately passes control to the initial kernel image
- In Linux, this kernel image executes starting from the `start_kernel()` in the `init/main.c`
- This kernel image is way different, both in size and structure, from the one that will operate at steady state
- Just to name one reason, boot is typically highly configurable!

What about boot on multi-core machines

- The `start_kernel()` function is executed along a single CPU-core (the master)
- All the other cores (the slaves) only keep waiting that the master has finished
- The kernel internal function `smp_processor_id()` can be used for retrieving the ID of the current core
- This function is based on ASM instructions implementing a hardware specific ID detection protocol
- This function operates correctly either at kernel boot or at steady state

The actual support for CPU-core identification

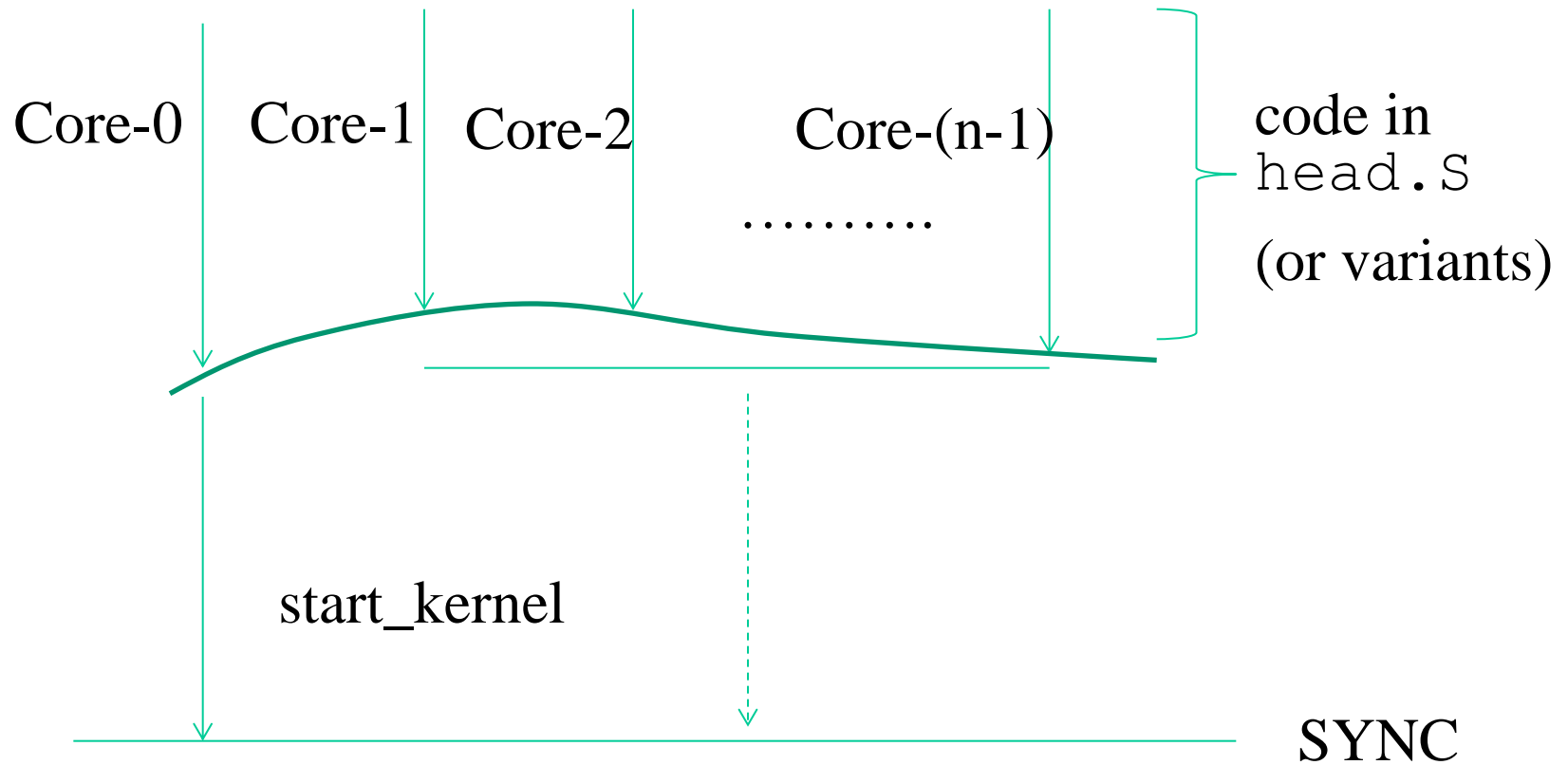
x86 Instruction Set Reference

CPUID

CPU Identification

Opcode	Mnemonic	Description
0F A2	CPUID	Returns processor identification and feature information to the EAX, EBX, ECX, and EDX registers, according to the input value entered initially in the EAX register.

Actual kernel startup scheme in Linux



An example head.S code snippet: triggering Linux paging (IA32 case)

```
/* * Enable paging */ 3:  
movl $swapper_pg_dir-__PAGE_OFFSET,%eax  
movl %eax,%cr3 /* set the page table  
pointer.. */  
movl %cr0,%eax  
orl $0x80000000,%eax  
movl %eax,%cr0 /* ..and set paging (PG) bit  
*/
```

Hints on the signature of the `start_kernel` function (as well as others)

..... `__init start_kernel(void)`



This only lives in memory during kernel boot (or startup)

The reason for this is to recover main memory storage which is relevant because of both:

- Reduced available RAM (older configurations)
- Increasingly complex (and hence large in size) startup code

Recall that the kernel image is not subject to swap out (conventional kernels are always resident in RAM)

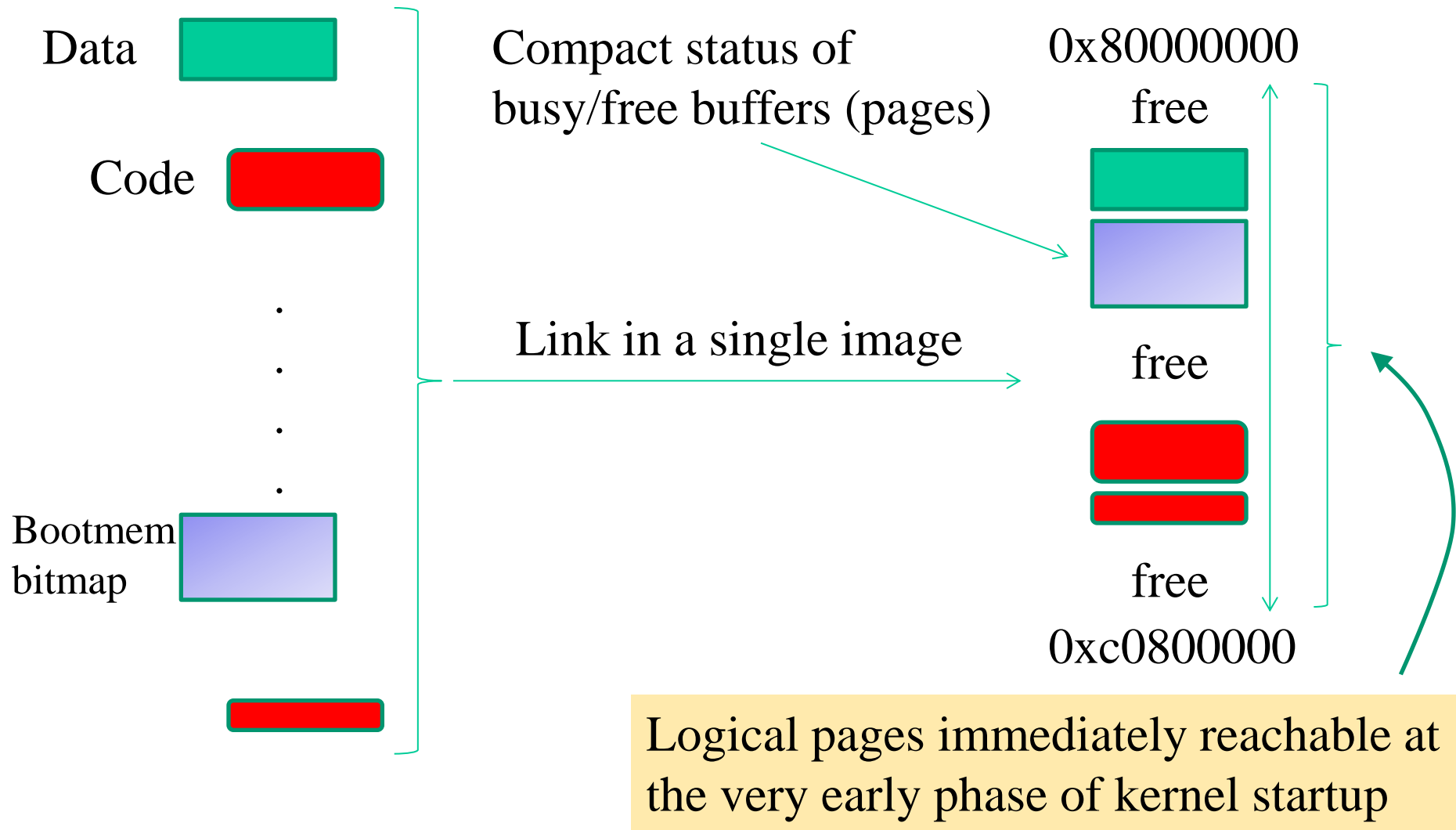
Management of `__init` functions

- The kernel linking stage locates these functions on specific logical pages (recall what we told about the fixed positioning of specific kernel level stuff in the kernel layout!!)
- These logical pages are identified within a “bootmem” subsystem that is used for managing memory when the kernel is not yet at steady state of its memory management operations
- Essentially the bootmem subsystem keeps a bitmask with one bit indicating whether a given page has been used (at compile time) for specific stuff

... still on bootmem

- The bootmem subsystem also allows for memory allocation upon the very initial phase of the kernel startup
- In fact, the data structures (e.g. the bitmaps) it keeps not only indicate if some page has been used for specific data/code
- They also indicate if some page which is actually reachable at the very early phase of boot is **not used for any stuff**
- These are clearly “free buffers” exploitable upon the very early phase of boot

An exemplified picture of bootmem



The meaning of ``reachable page''

- The kernel software can access the actual content of the page (in RAM) by simply expressing an address falling into that page
- The point is that the expressed address is typically a virtual one (since kernel code is commonly written using ``pointer'' abstractions)
- So the only way we have to make a virtual address correspond to a given page frame in RAM is to rely on at least a page table that makes the translation (even at the very early stage of kernel boot)
- The initial kernel image has a page table, with a minimum number of pages mapped in RAM, those handled by the bootmem subsystem

How is RAM memory organized on modern (large scale/parallel) machines?

- In modern chipsets, the CPU-core count continuously increases
- However, it is increasingly difficult to build architectures with a flat-latency memory access (historically referred to as UMA)
- Current machines are typically NUMA
- Each CPU-core has some RAM banks that are close and other that are far
- Generally speaking, each memory bank is associated with a so called NUMA-node
- Modern operating systems are designed to handle NUMA machines (hence UMA as a special case)

Looking at the Linux NUMA setup via Operating System facilities

- A very simple way is the `numactl` command
- It allows to discover
 - ✓ How many NUMA nodes are present
 - ✓ What are the nodes close/far to/from any CPU-core
 - ✓ What is the actual distance of the nodes (from the CPU-cores)

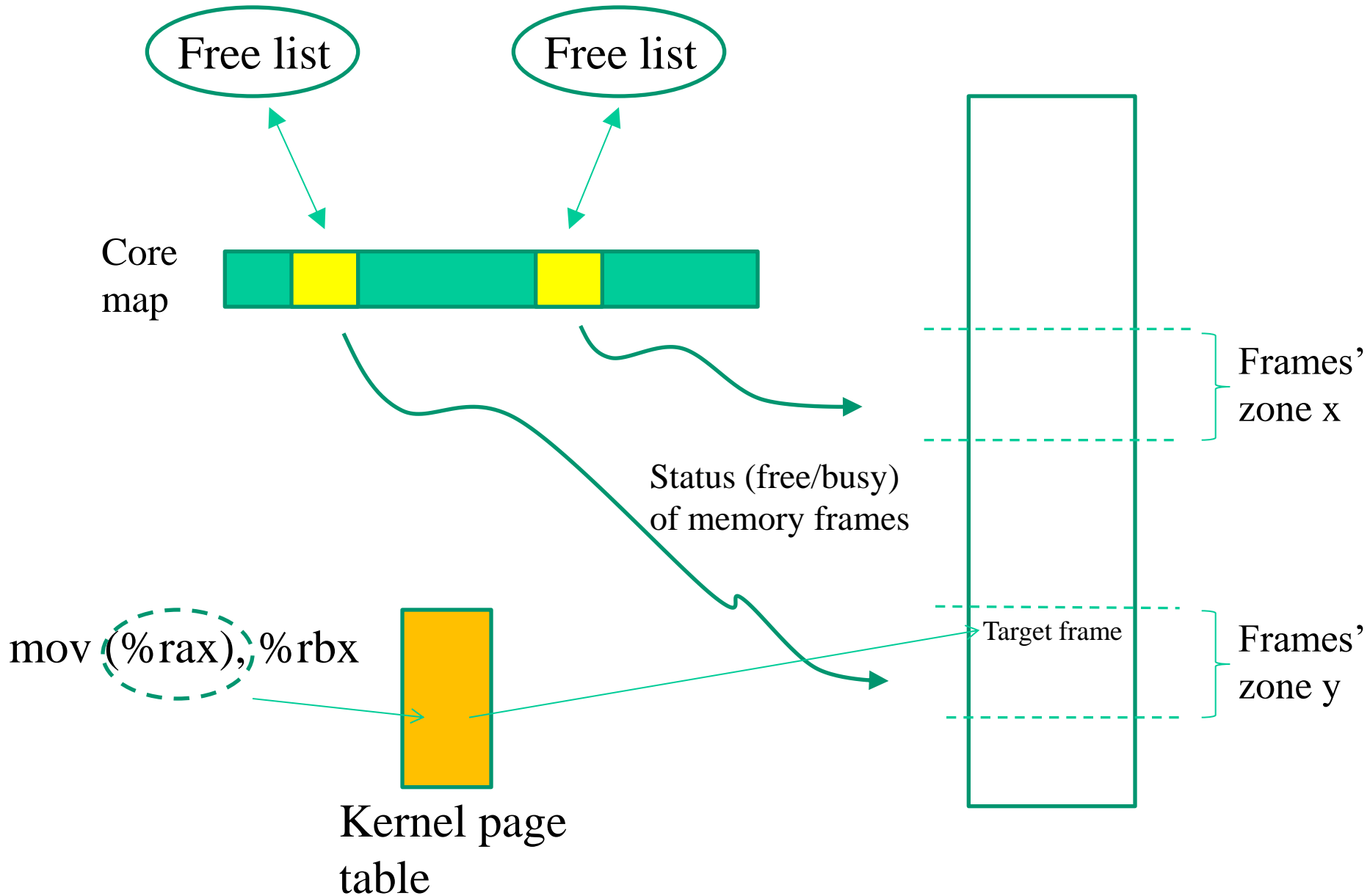
Let's see a few 'live' examples

Actual kernel data structures for managing memory

- Kernel Page table
 - This is a kind of ‘ancestral’ page table (all the others are somehow derived from this one)
 - It keeps the memory mapping for kernel level code and data (thread stack included)
- Core map
 - The map that keeps status information for any frame (page) of physical memory, and for any NUMA node
- Free list of physical memory frames, for any NUMA node

None of them is already finalized when we startup the kernel

A scheme



Objectives of the kernel page table setup

- These are basically two:
 - ✓ Allowing the kernel software to use virtual addressed while executing (either at startup or at steady state)
 - ✓ Allowing the kernel software (and consequently the application software) to reach (in read and/or write mode) the maximum admissible (for the specific machine) or available RAM storage
- The finalized shape of the kernel page table is therefore typically not setup into the original image of the kernel loaded in memory, e.g., given that the available RAM to drive can be parameterized

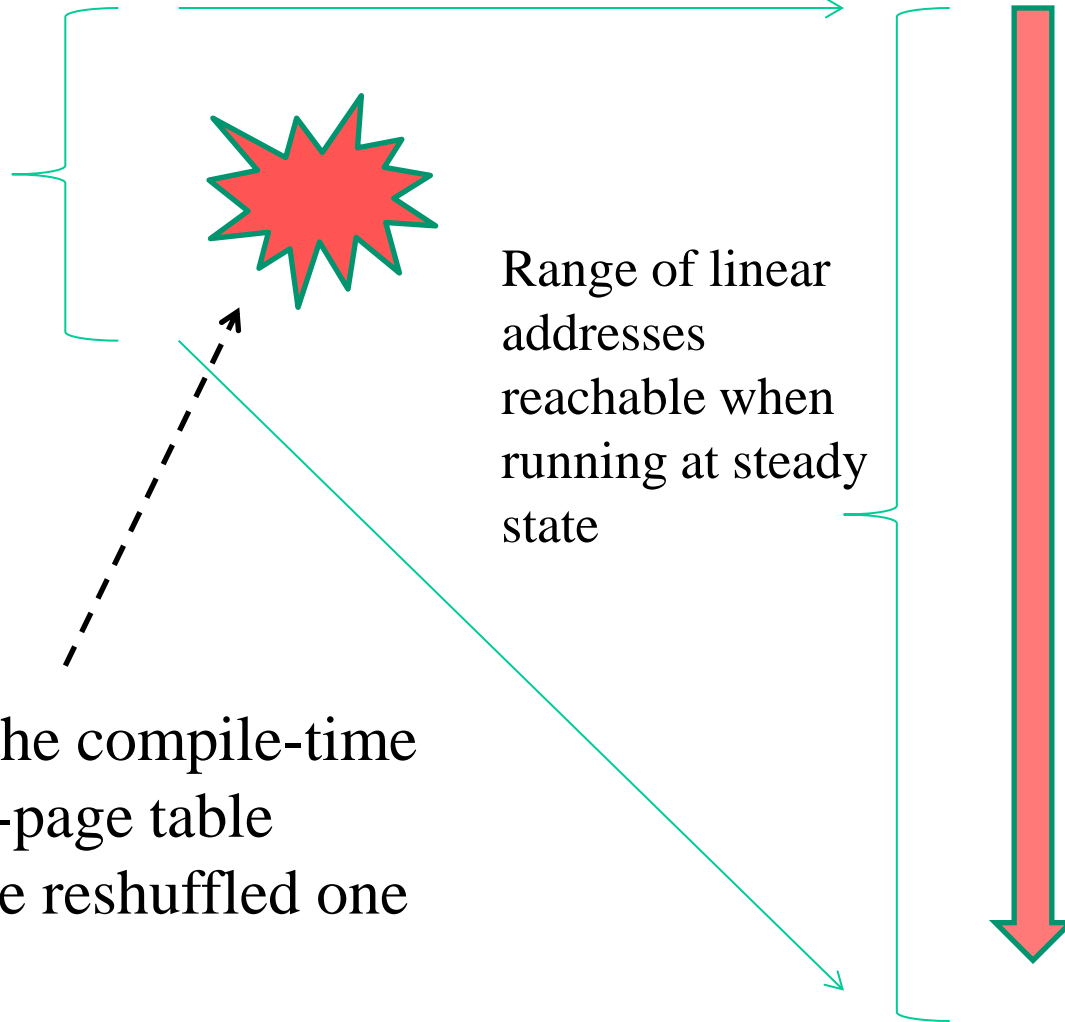
A scheme

Range of linear
addresses
reachable when
switching to
protected mode
plus paging

Range of linear
addresses
reachable when
running at steady
state

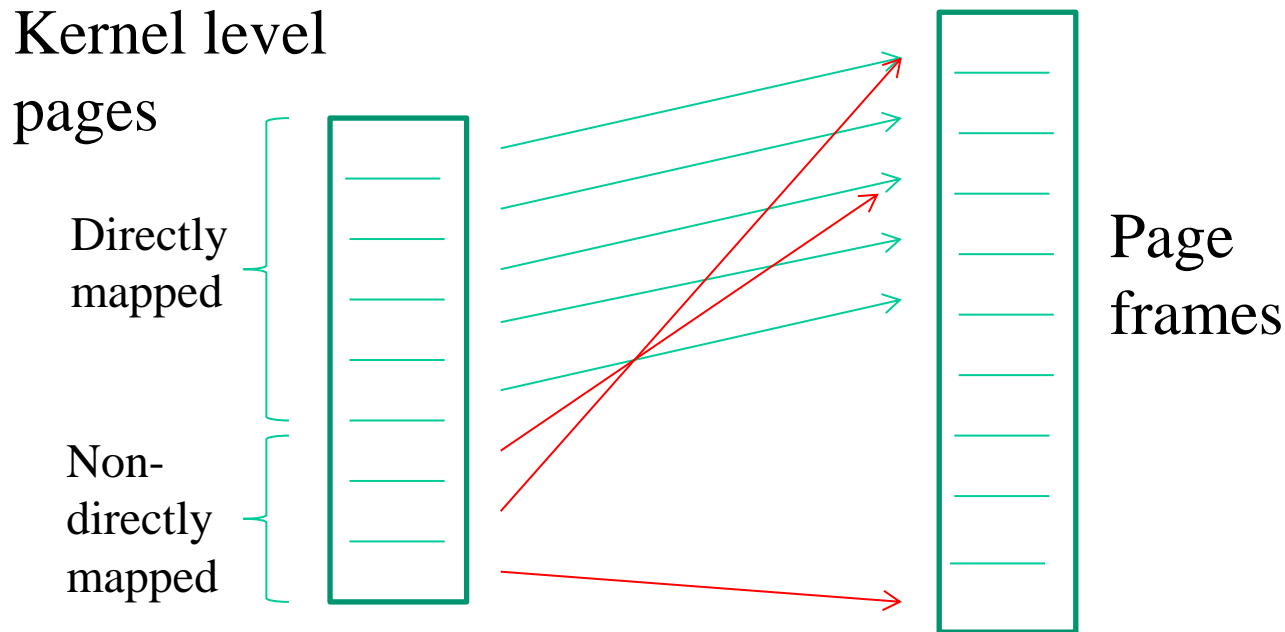
Increase
of the size
of reachable
RAM locations

Passage from the compile-time
defined kernel-page table
to the boot time reshuffled one



Directly mapped memory pages

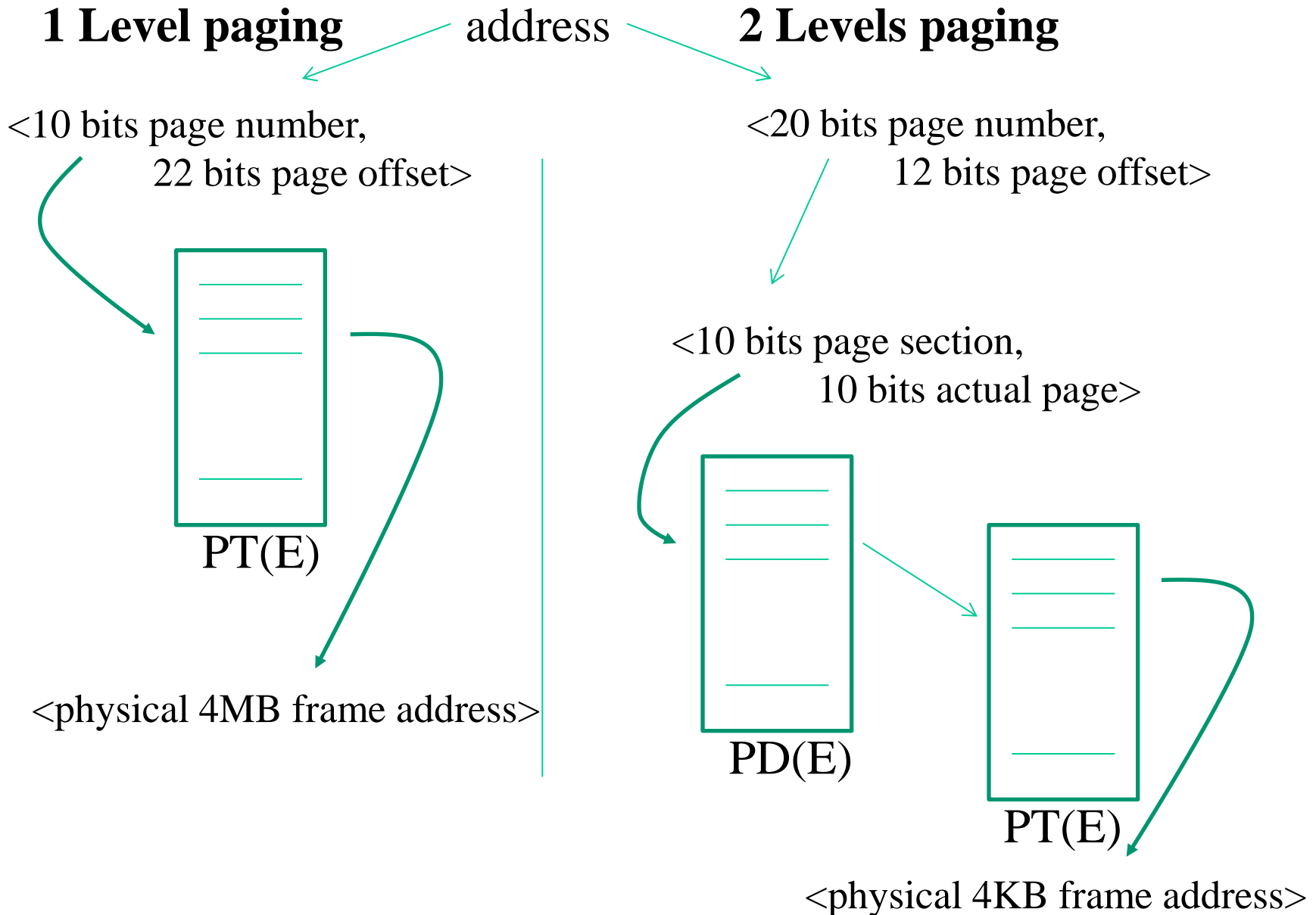
- They are kernel level pages whose mapping onto physical memory (frames) is based on a simple shift between virtual and physical address
 - ✓ $PA = \psi(VA)$ where ψ is (typically) a simple function subtracting a predetermined constant value to VA
- Not all the kernel level virtual pages are directly mapped



Virtual memory vs boot sequence (IA32 example)

- Upon kernel startup addressing relies on a simple single level paging mechanism that only maps 2 pages (each of 4 MB) up to 8 MB physical addresses
- The actual paging rule (namely the page granularity and the number of paging levels – up to 2 in i386) is identified via proper bits within the entries of the page table
- The physical address of the setup page table is kept within the CR3 register
- The steady state paging scheme used by LINUX will be activated during the kernel boot procedure
- The max size of the address space for LINUX processes on i386 machines (or protected mode) is 4 GB
 - 3 GB are within user level segments
 - 1 GB is within kernel level segments

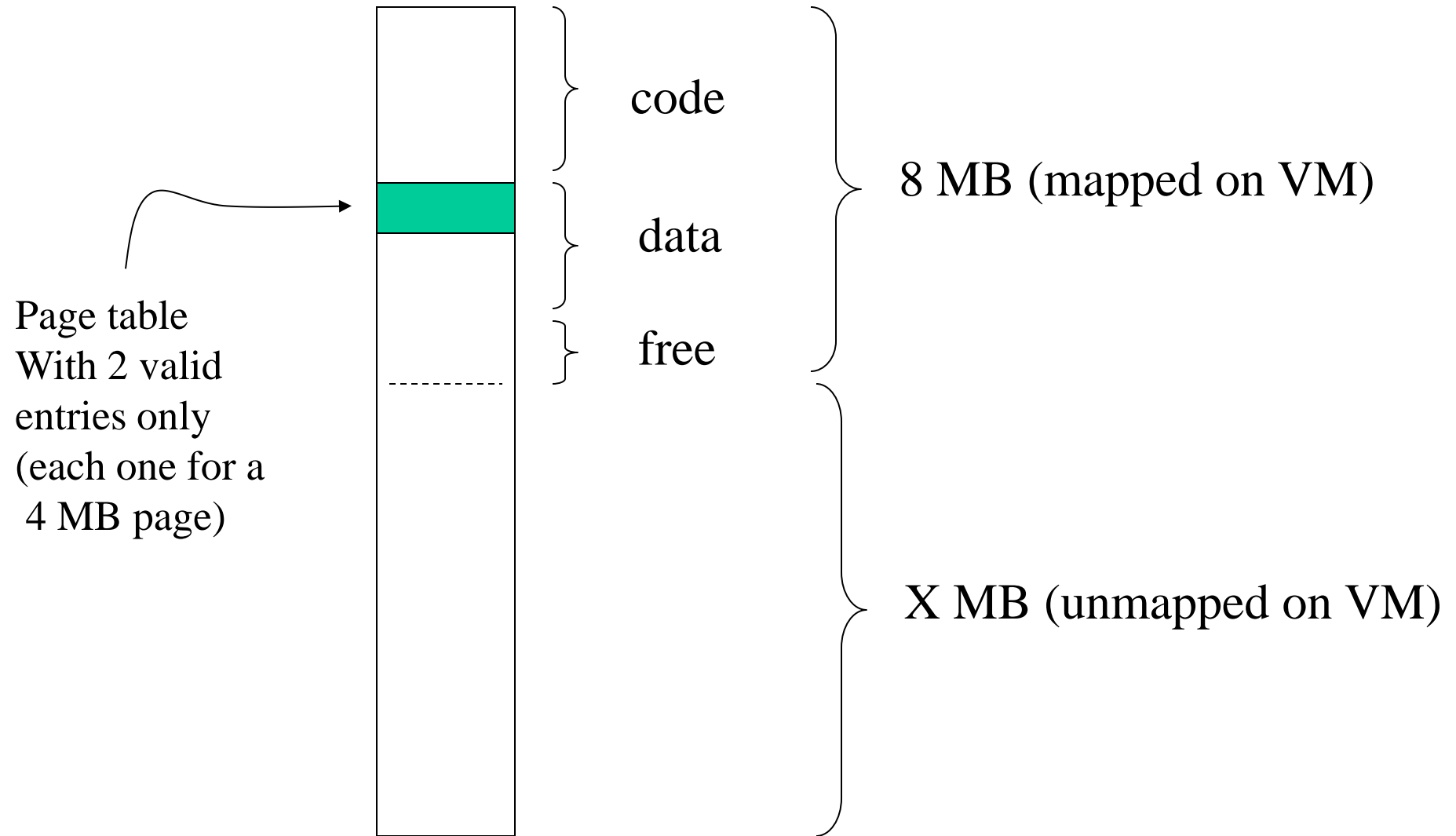
Details on the page table structure in i386 (i)



Details on the page table structure in i386 (ii)

- It is allocated in physical memory into 4KB blocks, which can be non-contiguous
- In typical LINUX configurations, once set-up it maps 4 GB addresses, of which 3 GB at null reference and (almost) 1 GB onto actual physical memory
- Such a mapped 1 GB corresponds to kernel level virtual addressing and allows the kernel to span over 1 GB of physical addresses
- To drive more physical memory, additional configuration mechanisms need to be activated, or more recent processors needs to be exploited as we shall see

i386 memory layout at kernel startup for 2.4 kernels



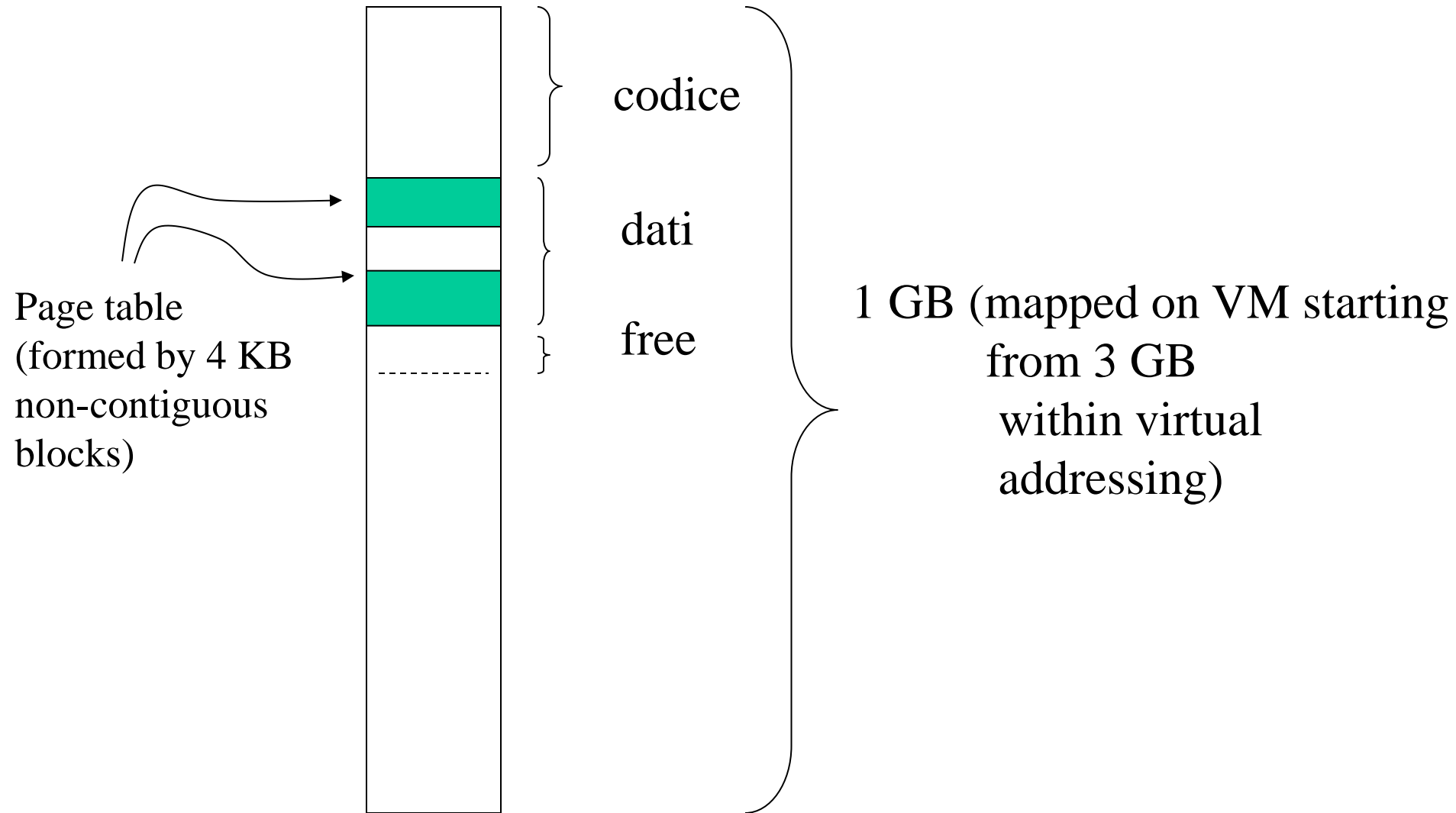
Actual issues to be tackled

1. We need to reach the correct granularity for paging (4KB rather than 4MB)
2. We need to span logical to physical address across the whole 1GB of kernel-manageable physical memory
3. We need to re-organize the page table in two separate levels
4. So we need to determine ‘free buffers’ within the already reachable memory segment to initially expand the page table
5. We cannot use memory management facilities other than paging (since core maps and free lists are not yet at steady state)

Back to the concept of *bootmem*

1. Memory occupancy and location of the initial kernel image is determined by the compile/link process
2. A compile/link time memory manager is embedded into the kernel image, which is called bootmem manager
3. It relies on bitmaps telling if any 4KB page in the currently reachable memory image is busy or free
4. It also offers API (to be employed at boot time) in order to get free buffers
5. These buffers are sets of contiguous (or single) page aligned areas
6. As hinted, this subsystem is in charge of handling `_init` marked functions in terms of final release of the corresponding buffers

Kernel page table collocation within physical memory

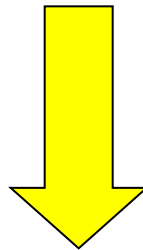
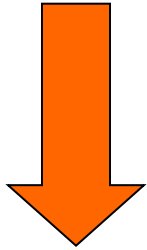


Low level “pages”

Load undersized page table
(kernel page size not finalized: 4MB)
- 4 KB (1K entry)

Finalize kernel handled
page size (4KB)

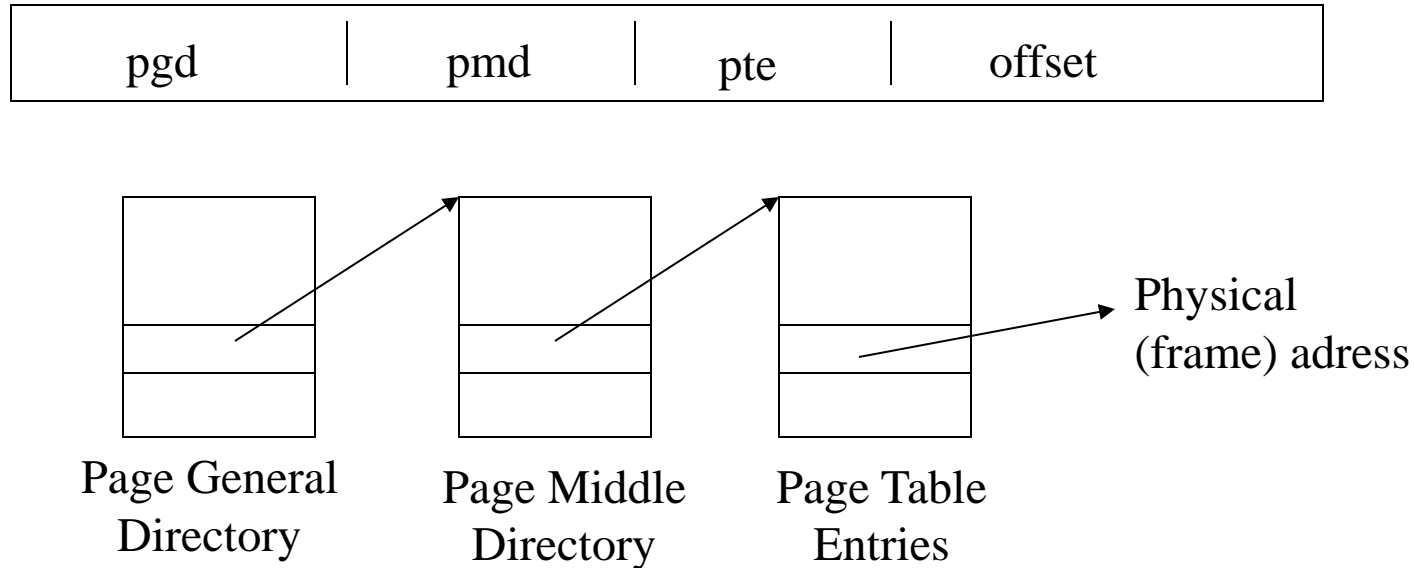
Expand page table via
boot mem low pages
(not marked in the page table)
- compile time identification



Kernel boot

LINUX paging vs i386

- LINUX virtual addresses exhibit (at least) 3 indirection levels



- On i386 machines, paging is supported limitedly to 2 levels (pde, page directory entry – pte, page table entry)
- **Such a dicotomy is solved by setting null** the pmd field, which is proper of LINUX, and mapping
 - pgd LINUX on pde i386
 - pte LINUX on pte i386

i386 page table size

- Both levels entail 4 KB memory blocks
- Each block is an array of 4-byte entries
- Hence we can map **1 K x 1K pages**
- Since each page is 4 KB in size, we get a 4 GB virtual addressing space
- The following macros define the size of the page tables blocks (they can be found in the file `include/asm-i386/pgtable-2level.h`)
 - `#define PTRS_PER_PGD 1024`
 - `#define PTRS_PER_PMD 1`
 - `#define PTRS_PER_PTE 1024`
- the value 1 for `PTRS_PER_PMD` is used **to simulate the existence of the intermediate level** such in a way to keep the 3-level oriented software structure to be compliant with the 2-level architectural support

Page table data structures

- A core structure is represented by the symbol `swapper_pg_dir` which is defined within the file `arch/i386/kernel/head.S`
- This symbol expresses the virtual memory address of the **PGD (PDE)** portion of the kernel page table
- This value is initialized at compile time, depending on the memory layout defined for the kernel bootable image
- Any entry within the PGD is accessed via displacement starting from the initial PGD address
- **The C types for the definition of the content of the page table entries on i386** are defined in `include/asm-i386/page.h`
- They are

```
typedef struct { unsigned long pte_low; } pte_t;  
typedef struct { unsigned long pmd; } pmd_t;  
typedef struct { unsigned long pgd; } pgd_t;
```

Debugging

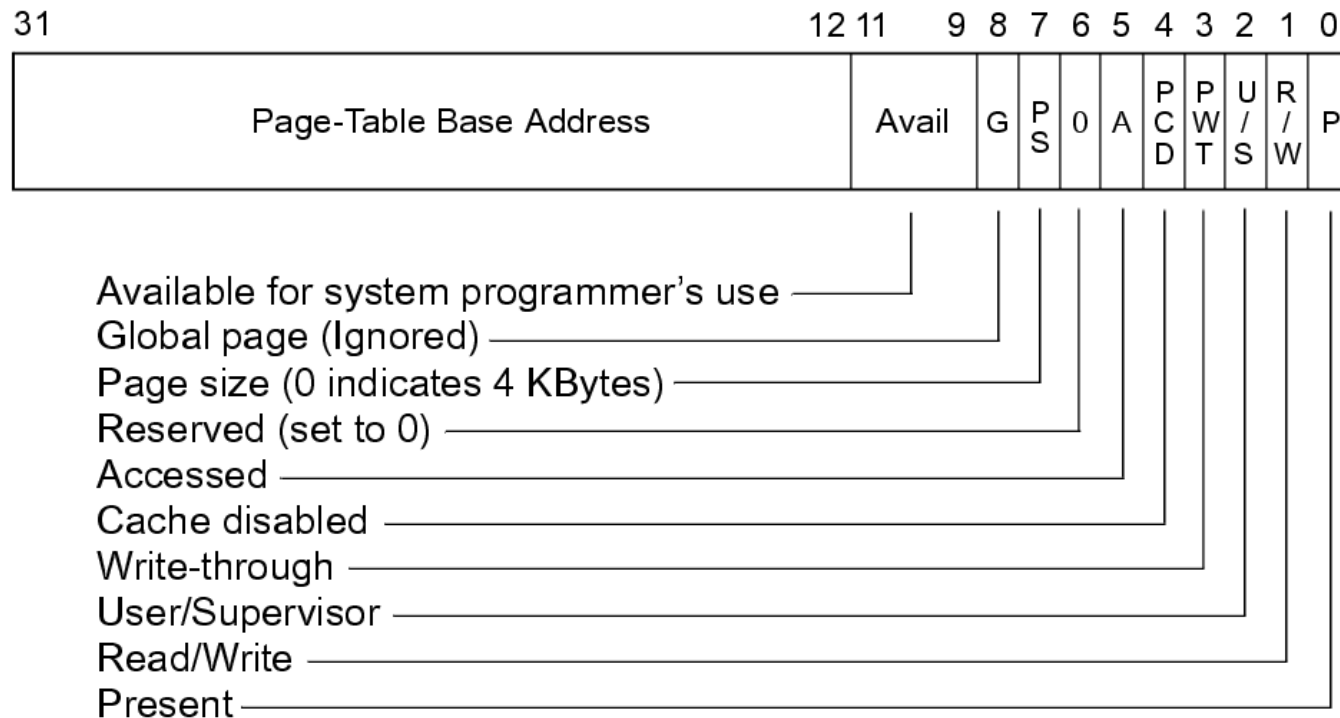
- The redefinition of different structured types, which are identical in size and equal to an `unsigned long`, is done for debugging purposes
- Specifically, in C technology, **different aliases for the same type are considered as identical types**
- For instance, if we define

```
typedef unsigned long pgd_t;
typedef unsigned long pte_t;
pgd_t x; pte_t y;
```

the compiler enables assignments such as `x=y` and `y=x`
- Hence, there is the need for defining different structured types which simulate the base types that would otherwise give rise to compiler equivalent aliases

i386 PDE entries

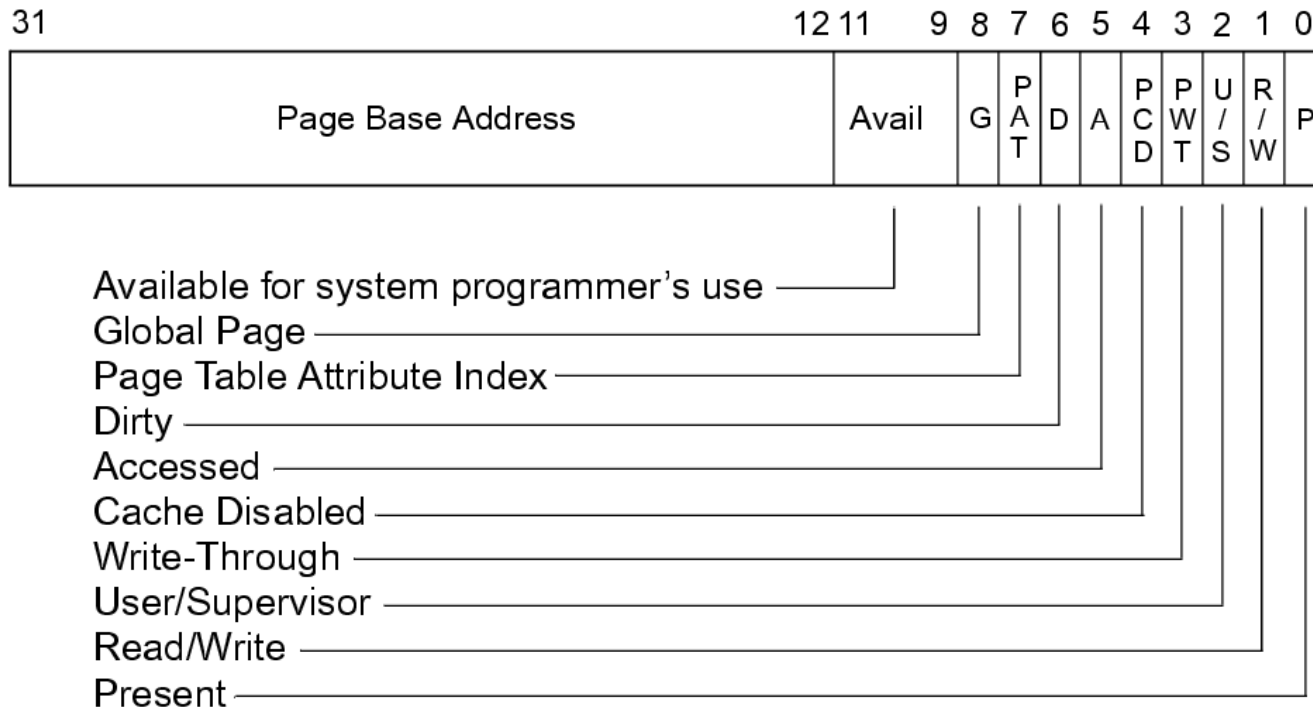
Page-Directory Entry (4-KByte Page Table)



Nothing tells whether we can fetch (so execute) from there

i386 PTE entries

Page-Table Entry (4-KByte Page)



Nothing tells whether we can fetch (so execute) from there

Field semantics

- **Present:** indicates whether the page or the pointed page table is loaded in physical memory. This flag is not set by firmware (rather by the kernel)
- **Read/Write:** define the access privilege for a given page or a set of pages (as for PDE) . Zero means read only access
- **User/Supervisor:** defines the privilege level for the page or for the group of pages (as for PDE). Zero means supervisor privilege
- **Write Through:** indicates the caching policy for the page or the set of pages (as for PDE). Zero means write-back, non-zero means write-through
- **Cache Disabled:** indicates whether caching is enabled or disabled for a page or a group of pages. Non-zero value means disabled caching (as for the case of memory mapped I/O)

- **Accessed:** indicates whether the page or the set of pages has been accessed. This is a sticky flag (no reset by firmware). Reset is controlled via software
- **Dirty:** indicates whether the page has been write-accessed. This is also a sticky flag
- **Page Size (PDE only):** if set indicates 4 MB paging otherwise 4 KB paging
- **Page Table Attribute Index:** Do not care
- **Page Global (PTE only):** defines the caching policy for TLB entries. Non-zero means that the corresponding TLB entry does not require reset upon loading a new value into the page table pointer CR3

Bit masking

- in `include/asm-i386/pgtable.h` there exist some macros defining the positioning of control bits within the entries of the PDE or PTE
- There also exist the following macros for masking and setting those bits

```
➤ #define __PAGE_PRESENT      0x001
➤ #define __PAGE_RW          0x002
➤ #define __PAGE_USER         0x004
➤ #define __PAGE_PWT          0x008
➤ #define __PAGE_PCD          0x010
➤ #define __PAGE_ACCESSED     0x020

➤ #define __PAGE_DIRTY        0x040 /* proper of PTE */
```

- These are all machine dependent macros

An example

```
pte_t x;
```

```
x = ...;
```

```
if ( (x.pte_low) & _PAGE_PRESENT) {  
    /* the page is loaded in a frame */  
}  
else{  
    /* the page is not loaded in any  
       frame */  
} ;
```

Relations with trap/interrupt events

- Upon a TLB miss, firmware accesses the page table
- The first checked bit is typically `_PAGE_PRESENT`
- If this bit is zero, a page fault occurs which gives rise to a trap (with a given displacement within the trap/interrupt table)
- Hence the instruction that gave rise to the trap can get finally re-executed
- **Re-execution might give rise to additional traps, depending on firmware checks on the page table**
- As an example, the attempt to access a read only page in write mode will give rise to a trap (which triggers the **segmentation fault handler**)

Run time detection of current page size on IA-32 processors and 2.4 Linux kernel

```
#include <kernel.h>
```

```
#define MASK 1<<7
```

```
unsigned long addr = 3<<30; // fixing a reference on the  
                           // kernel boundary
```

```
asmlinkage int sys_page_size(){
```

```
    //addr = (unsigned long)sys_page_size; // moving the reference  
    return(swapper_pg_dir[(int)((unsigned long)addr>>22)]&MASK?  
           4<<20:4<<10);
```

```
}
```

Kernel page table initialization details

- As said, the kernel PDE is accessible at the virtual address kept by `swapper_pg_dir` (now `init_level4_pgt` on x86-64/kernel 3 or `init_top_pgt` on x86-64/kernel4)
- The room for PTE tables gets reserved within the 8MB of RAM that are accessible via the initial paging scheme
- Reserving takes place via the macro `alloc_bootmem_low_pages()` which is defined in `include/linux/bootmem.h` (this macro returns a virtual address)
- Particularly, it returns the pointer to a 4KB (or 4KB x N) buffer which is page aligned
- This function belongs to the (already hinted) basic memory management subsystem upon which the LINUX memory system boot lies on

Kernel 2.4/i386 initialization algorithm

- we start by the PGD entry which maps the address 3 GB, namely the entry numbered 768
- cyclically
 1. We determine the virtual address to be memory mapped (this is kept within the `vaddr` variable)
 2. One page for the PTE table gets allocated which is used for mapping 4 MB of virtual addresses
 3. The table entries are populated
 4. The virtual address to be mapped gets updated by adding 4 MB
 5. We jump to step 1 unless no more virtual addresses or no more physical memory needs to be dealt with (the ending condition is recorded by the variable `end`)

Initialization function `pagetable_init()`

```
for (; i < PTRS_PER_PGD; pgd++, i++) {

    vaddr = i*PGDIR_SIZE; /* i is set to map from 3 GB */
    if (end && (vaddr >= end)) break;
    pmd = (pmd_t *)pgd; /* pgd initialized to (swapper_pg_dir+i) */

    .....

    for (j = 0; j < PTRS_PER_PMD; pmd++, j++) {
        .....

        pte_base = pte = (pte_t *) alloc_bootmem_low_pages(PAGE_SIZE);

        for (k = 0; k < PTRS_PER_PTE; pte++, k++) {
            vaddr = i*PGDIR_SIZE + j*PMD_SIZE + k*PAGE_SIZE;
            if (end && (vaddr >= end)) break;

            .....

            *pte = mk_pte_phys(__pa(vaddr), PAGE_KERNEL);
        }
        set_pmd(pmd, __pmd(_KERNPG_TABLE + __pa(pte_base)));
        .....

    }

}
```

Note!!!

- **The final PDE buffer coincides with the initial page table that maps 4 MB pages**
- 4KB paging gets activated upon filling the entry of the PDE table (since the Page Size bit gets updated)
- For this reason the PDE entry is set only after having populated the corresponding PTE table to be pointed
- **Otherwise memory mapping would be lost upon any TLB miss**

The `set_pmd` macro

```
#define set_pmd(pmdptr, pmdval) (*(pmdptr) = pmdval)
```

- This macro simply sets the value into one PMD entry
- Its input parameters are
 - the `pmdptr` pointer to an entry of PMD (the type is `pmd_t`)
 - The value to be loaded `pmdval` (of type `pmd_t`, defined via casting)
- While setting up the kernel page table, this macro is used in combination with `__pa()` (physical address) which returns an `unsigned long`
- **The latter macro returns the physical address corresponding to a given virtual address within kernel space (except for some particular virtual address ranges)**
- Such a mapping deals with [3,4] GB virtual addressing onto [0,1] GB physical addressing

The `mk_pte_phys ()` macro

`mk_pte_phys (physpage, pgprot)`

- The input parameters are
 - A frame physical address `physpage`, of type `unsigned long`
 - A bit string `pgprot` for a PTE, of type `pgprot_t`
- The macro builds a complete PTE entry, which includes the physical address of the target frame
- The result type is `pte_t`
- The result value can be then assigned to one PTE entry

PAE (Physical address extension)

- increase of the bits used for physical addressing
- offered by more recent x86 processors (e.g. Intel Pentium Pro) which provide up to 36 bits for physical addressing
- we can drive up to 64 GB of RAM memory
- paging gets operated at 3 levels (instead of 2)
- the traditional page tables get modified by extending the entries at 64-bits and reducing their number by a half (hence we can support $\frac{1}{4}$ of the address space)
- an additional top level table gets included called “page directory pointer table” which entails 4 entries, pointed by CR3
- CR4 indicates whether PAE mode is activated or not (which is done via bit 5 – PAE-bit)

x86-64 architectures

- They extend the PAE scheme via a so called “long addressing mode”
- Theoretically they allow addressing 2^{64} bytes of logical memory
- In actual implementations we reach up to 2^{48} canonical form addresses (lower/upper half within a total address space of 2^{48})
- The total allows addressing to span over 256 TB
- Not all operating systems allow exploiting the whole range up to 256 TB of logical/physical memory
- LINUX currently allows for 128 TB for logical addressing of individual processes and 64 TB for physical addressing

Addressing scheme

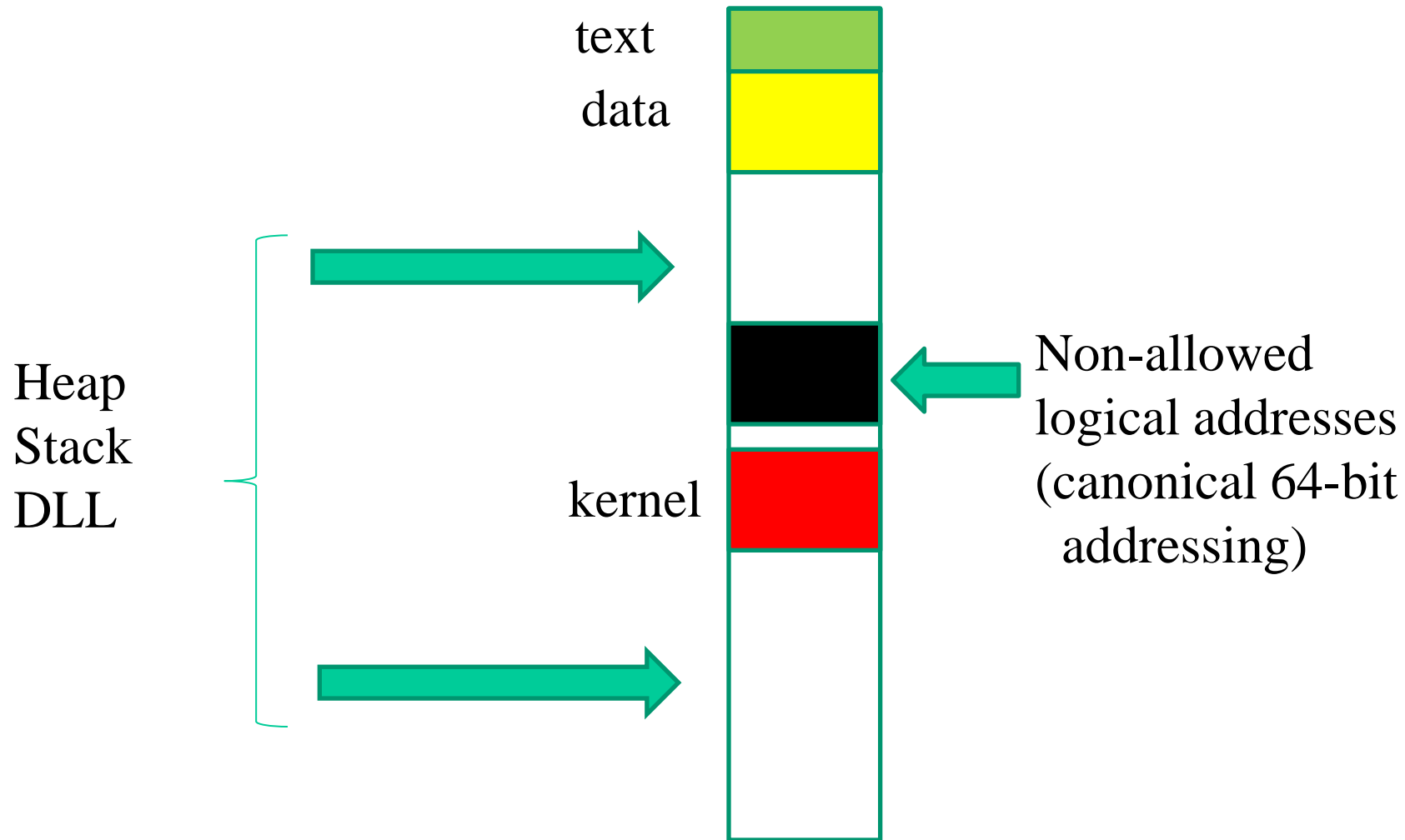
64-bit



48 out of 64-bit

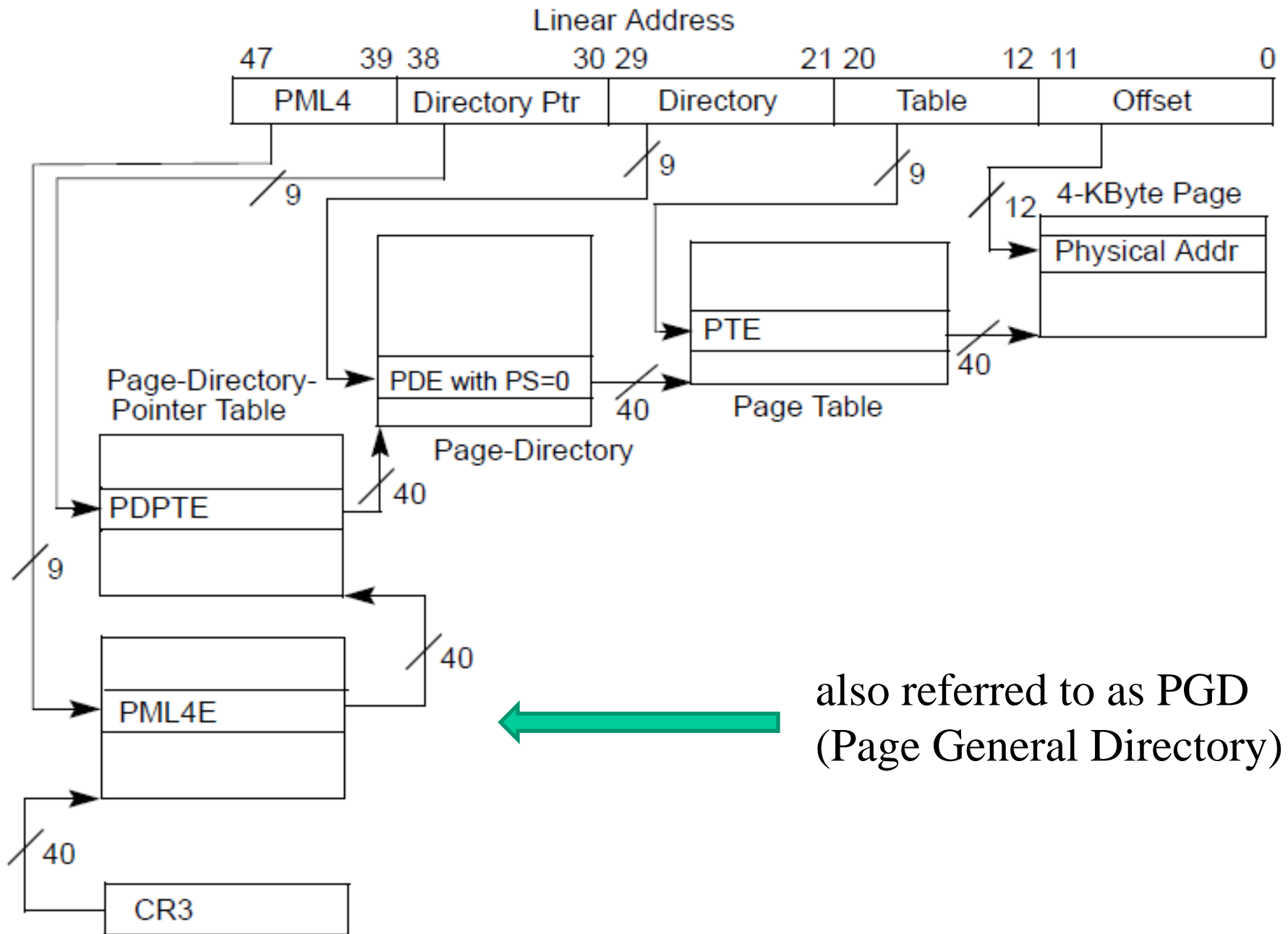


Linux address space on x86-64 processors



48-bit addressing: page tables

- Page directory pointer has been expanded from 4 to 512 entries
- An additional paging level has been added thus reaching 4 levels, this is called “Page-Map level”
- Each Page-Map level table has 512 entries
- Hence we get 512^4 pages of size 4 KB that are addressable (namely, a total of 256 TB)



6	6	6	6	5	5	5	5	5	5	5	5	5	5		M ¹	M-1			3	3	3	2	2	2	2	2	2	2	2	1	1	1	1	1	1	1	1	0	9	8	7	6	5	4	3	2	1	0	
Reserved ²															Address of PML4 table															Ignored			P C D	P W T	Ign.	CR3													
X D 3	Ignored														Rsvd.	Address of page-directory-pointer table															Ign.	R s v d	I g n	A	P C D	P W T	U / S	R / W	1	PML4E: present									
Ignored																											0	PML4E: not present																					
X D	Ignored														Rsvd.	Address of 1GB page frame					Reserved										P A T	Ign.	G	1	D	A	P C D	P W T	U / S	R / W	1	PDPTE: 1GB page							
X D	Ignored														Rsvd.	Address of page directory															Ign.	0	I g n	A	P C D	P W T	U / S	R / W	1	PDPTE: page directory									
Ignored																											0	PDPTE: not present																					
X D	Ignored														Rsvd.	Address of 2MB page frame										Reserved										P A T	Ign.	G	1	D	A	P C D	P W T	U / S	R / W	1	PDE: 2MB page		
X D	Ignored														Rsvd.	Address of page table															Ign.	0	I g n	A	P C D	P W T	U / S	R / W	1	PDE: page table									
Ignored																											0	PDE: not present																					
X D	Ignored														Rsvd.	Address of 4KB page frame															Ign.	G	P A T	D	A	P C D	P W T	U / S	R / W	1	PTE: 4KB page								
Ignored																											0	PTE: not present																					

Figure 4-11. Formats of CR3 and Paging-Structure Entries with IA-32e Paging

Table 4-19. Format of an IA-32e Page-Table Entry that Maps a 4-KByte Page

Bit Position(s)	Contents
0 (P)	Present; must be 1 to map a 4-KByte page
1 (R/W)	Read/write; if 0, writes may not be allowed to the 4-KByte page referenced by this entry (see Section 4.6)
2 (U/S)	User/supervisor; if 0, user-mode accesses are not allowed to the 4-KByte page referenced by this entry (see Section 4.6)
3 (PWT)	Page-level write-through; indirectly determines the memory type used to access the 4-KByte page referenced by this entry (see Section 4.9.2)
4 (PCD)	Page-level cache disable; indirectly determines the memory type used to access the 4-KByte page referenced by this entry (see Section 4.9.2)
5 (A)	Accessed; indicates whether software has accessed the 4-KByte page referenced by this entry (see Section 4.8)
6 (D)	Dirty; indicates whether software has written to the 4-KByte page referenced by this entry (see Section 4.8)
7 (PAT)	Indirectly determines the memory type used to access the 4-KByte page referenced by this entry (see Section 4.9.2)
8 (G)	Global; if CR4.PGE = 1, determines whether the translation is global (see Section 4.10); ignored otherwise
11:9	Ignored
(M-1):12	Physical address of the 4-KByte page referenced by this entry
51:M	Reserved (must be 0)
62:52	Ignored
63 (XD)	If IA32_EFER.NXE = 1, execute-disable (if 1, instruction fetches are not allowed from the 4-KByte page controlled by this entry; see Section 4.6); otherwise, reserved (must be 0)

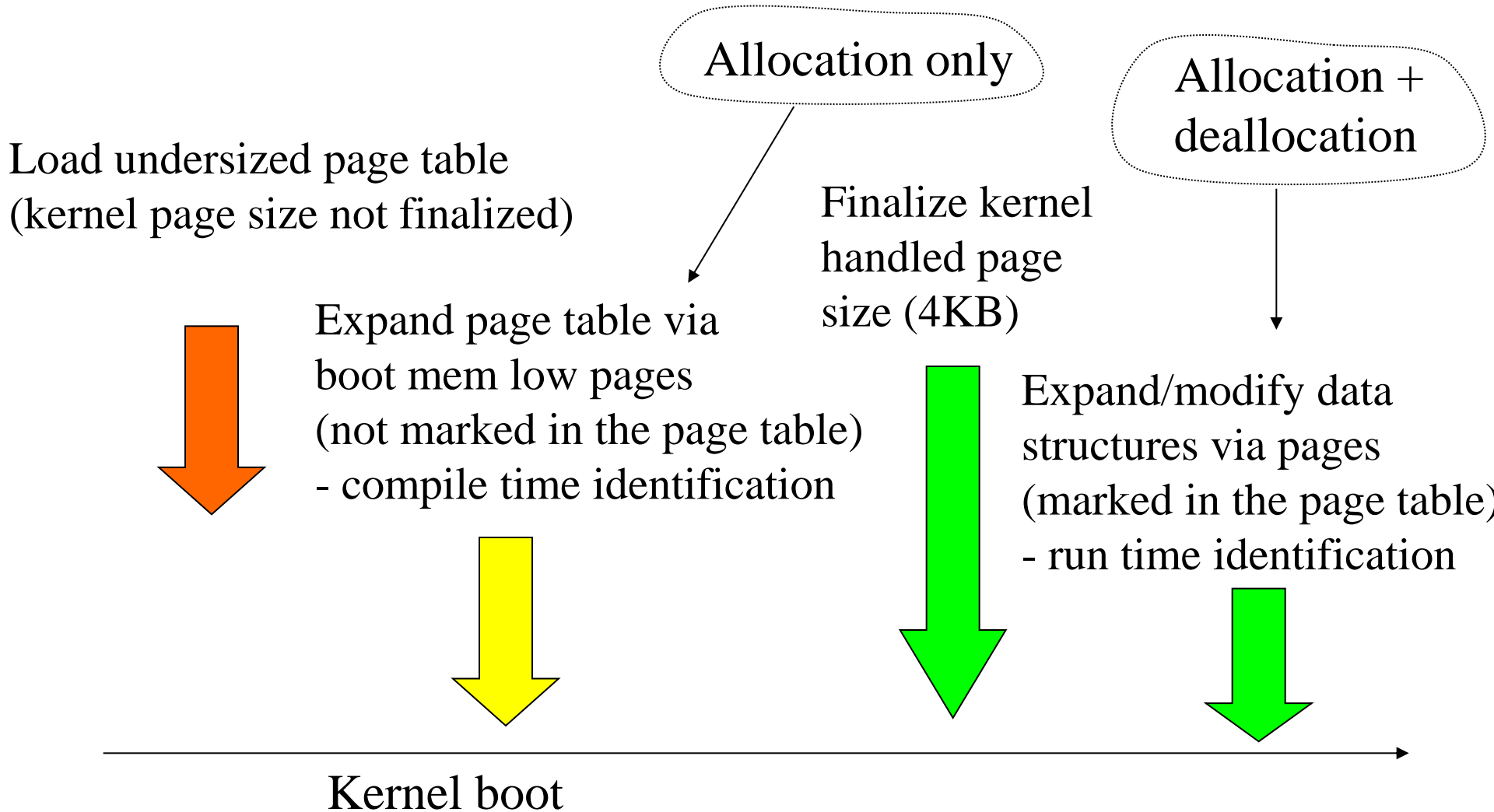
Direct vs non-direct page mapping

- In long mode x86 processors allow one entry of the PML\$ to be associated with 2^{27} frames
- This amounts to 2^{29} KB = 2^9 GB = 512 GB
- Clearly, we have plenty of room on virtual addressing for directly mapping all the available RAM into kernel pages on most common chipsets
- This is the typical approach taken by Linux, where we directly map all the RAM memory
- However we also remap the same RAM memory in non-direct manner whenever required

Huge pages

- Ideally x86-64 processors support them starting from PDPT
- Linux typically offers the support for huge pages pointed to by the PDE (page size 512*4KB)
- See: `/proc/meminfo` and `/proc/sys/vm/nr_hugepages`
- These can be “mmaped” via file descriptors and/or `mmap` parameters (e.g. `MAP_HUGETLB` flag)
- They can also be requested via the `madvise(void*, size_t, int)` system call (with `MADV_HUGEPAGE` flag)

Reaching vs allocating/deallocating memory



Core map

- It is an array of `mem_map_t` (also known as `struct page`) structures defined in `include/linux/mm.h`
- The actual type definition is as follows (or similar along kernel advancement):

```
typedef struct page {
    struct list_head list;                /* ->mapping has some page lists. */
    struct address_space *mapping;         /* The inode (or ...) we belong to. */
    unsigned long index;                  /* Our offset within mapping. */
    struct page *next_hash;               /* Next page sharing our hash bucket in
                                           the pagecache hash table. */

    atomic_t count;                      /* Usage count, see below. */
    unsigned long flags;                 /* atomic flags, some possibly
                                           updated asynchronously */

    struct list_head lru;                 /* Pageout list, eg. active_list;
                                           protected by pagemap_lru_lock !! */

    struct page **pprev_hash; /* Complement to *next_hash. */
    struct buffer_head * buffers;        /* Buffer maps us to a disk block. */

#ifdef CONFIG_HIGHMEM || defined(WANT_PAGE_VIRTUAL)
    void *virtual;                       /* Kernel virtual address (NULL if
                                           not kmapped, ie. highmem) */
#endif /* CONFIG_HIGMEM || WANT_PAGE_VIRTUAL */
} mem_map_t;
```

Fields

- Most of the fields are used to keep track of the interactions between memory management and other kernel sub-systems (such as I/O)
- Memory management proper fields are
 - `struct list_head list` (whose type is defined in `include/linux/lvm.h`), which is used to organize the frames into free lists
 - `atomic_t count`, which counts the virtual references mapped onto the frame (it is managed via atomic updates, such as with `LOCK` directives)
 - `unsigned long flags`, this field keeps the status bits for the frame, such as:

```
#define PG_locked      0
#define PG_referenced  2
#define PG_uptodate    3
#define PG_dirty       4
#define PG_lru         6
#define PG_reserved   14
```

Core map initialization (i386/kernel 2.4)

- Initially we only have the core map pointer
- This is `mem_map` and is declared in `mm/memory.c`
- Pointer initialization and corresponding memory allocation occur within `free_area_init()`
- After initializing, each entry will keep the value 0 within the `count` field and the value 1 into the `PG_reserved` flag within the `flags` field
- Hence no virtual reference exists for that frame and the frame is reserved
- Frame un-reserving will take place later via the function `mem_init()` in `arch/i386/mm/init.c` (by resetting the bit `PG_reserved`)

Free list organization: single NUMA zone – or NUMA unaware – protected mode case (e.g. kernel 2.4)

- we have 3 free lists of frames, depending on the frame positioning within the following zones: DMA (DMA ISA operations), NORMAL (room where the kernel can reside), HIGHMEM (room for user data)
- The corresponding defines are in `include/linux/mmzone.h`:

```
#define ZONE_DMA                0
#define ZONE_NORMAL             1
#define ZONE_HIGHMEM            2
#define MAX_NR_ZONES            3
```

- The corresponding sizes are usually defined as

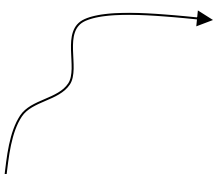
```
/* ZONE_DMA    < 16 MB    ISA DMA capable memory
ZONE_NORMAL    16-896 MB    direct mapped by the kernel
ZONE_HIGHMEM    > 896 MB    only page cache and user
processes */
```

Free list data structures

- Free lists information is kept within the `pg_data_t` data structure defined in `include/linux/mmzone.h`, and whose actual instance is `contig_page_data`, which is declared in `mm/numa.c`

Field of interest

```
typedef struct pglist_data {  
    zone_t node_zones[MAX_NR_ZONES];  
    zonelist_t node_zonelists[GFP_ZONEMASK+1];  
    int nr_zones;  
    struct page *node_mem_map;  
    unsigned long *valid_addr_bitmap;  
    struct bootmem_data *bdata;  
    unsigned long node_start_paddr;  
    unsigned long node_start_mapnr;  
    unsigned long node_size;  
    int node_id;  
    struct pglist_data *node_next;  
} pg_data_t;
```



- the `zone_t` type is defined in `include/linux/mmzone.h` as follows

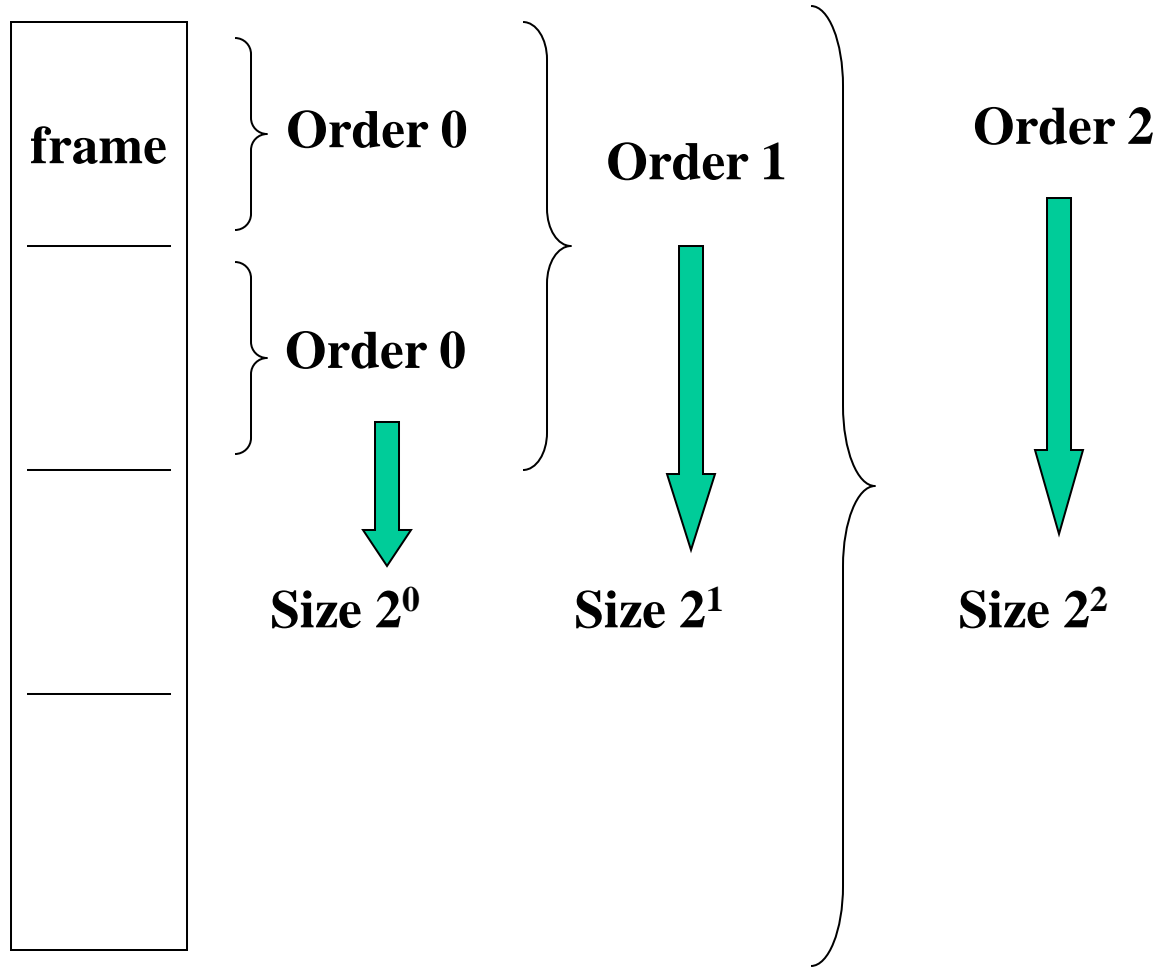
Beware this!

```
typedef struct zone_struct {  
    spinlock_t      lock;  
    unsigned long    free_pages;  
    zone_watermarks_t  watermarks[MAX_NR_ZONES];  
    unsigned long    need_balance;  
    unsigned long    nr_active_pages, nr_inactive_pages;  
    unsigned long    nr_cache_pages;  
    free_area_t      free_area[MAX_ORDER];  
    wait_queue_head_t * wait_table;  
    unsigned long    wait_table_size;  
    unsigned long    wait_table_shift;  
    struct pglist_data *zone_pgdat;  
    struct page      *zone_mem_map;  
    unsigned long    zone_start_paddr;  
    unsigned long    zone_start_mapnr;  
    char             *name;  
    unsigned long    size;  
    unsigned long    realsize;  
} zone_t;
```

Fields of
interest

Up to 11 in
recent
kernel versions
(it was typically
5 before)

Buddy system features



- `free_area_t` is defined in the same file as

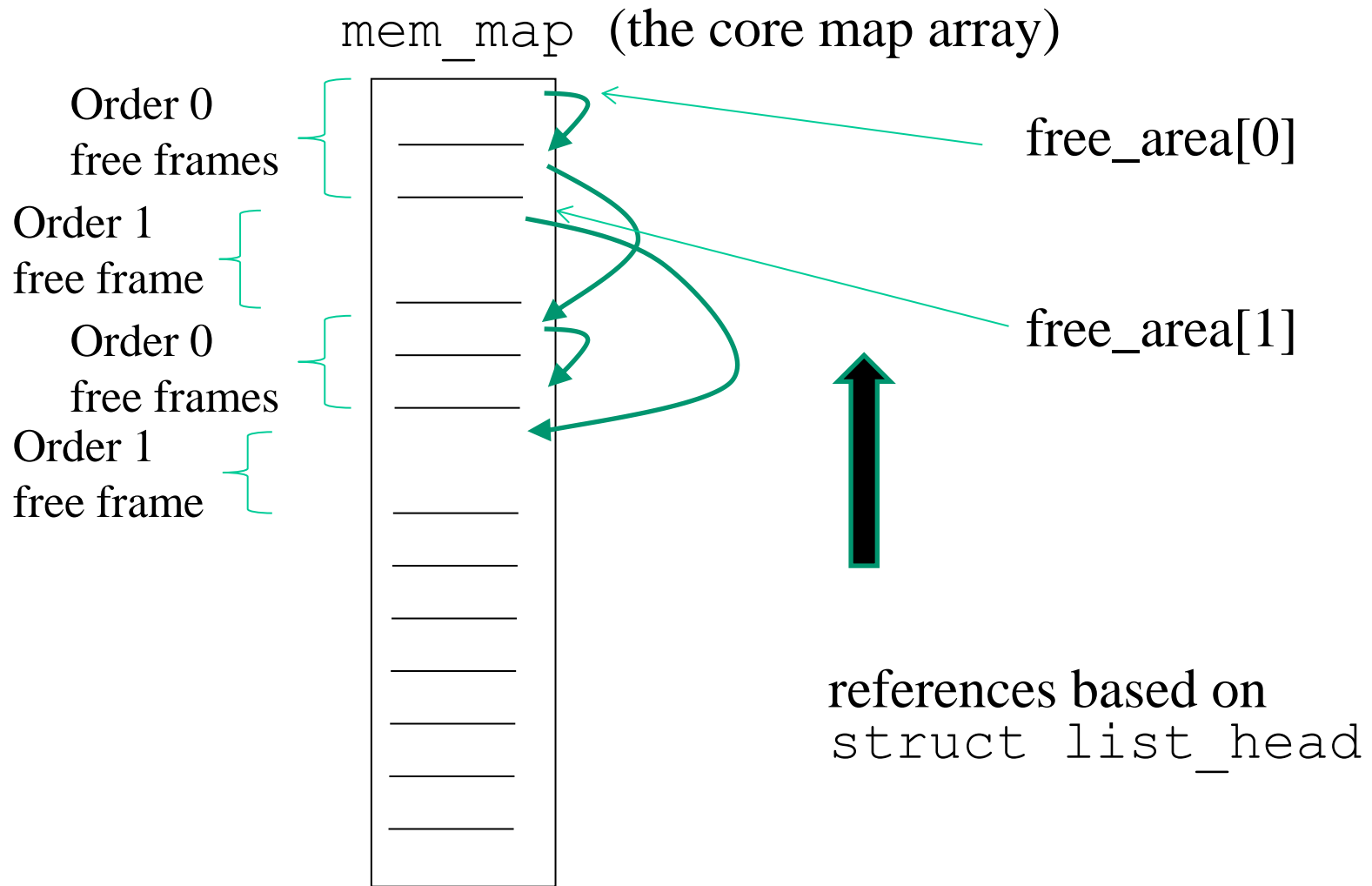
```
typedef struct free_area_struct {  
    struct list_head list;  
    unsigned int *map;  ←----- Buddies fragmentation  
} free_area_t          state
```

- where

```
struct list_head {  
    struct list_head *next, *prev;  
}
```

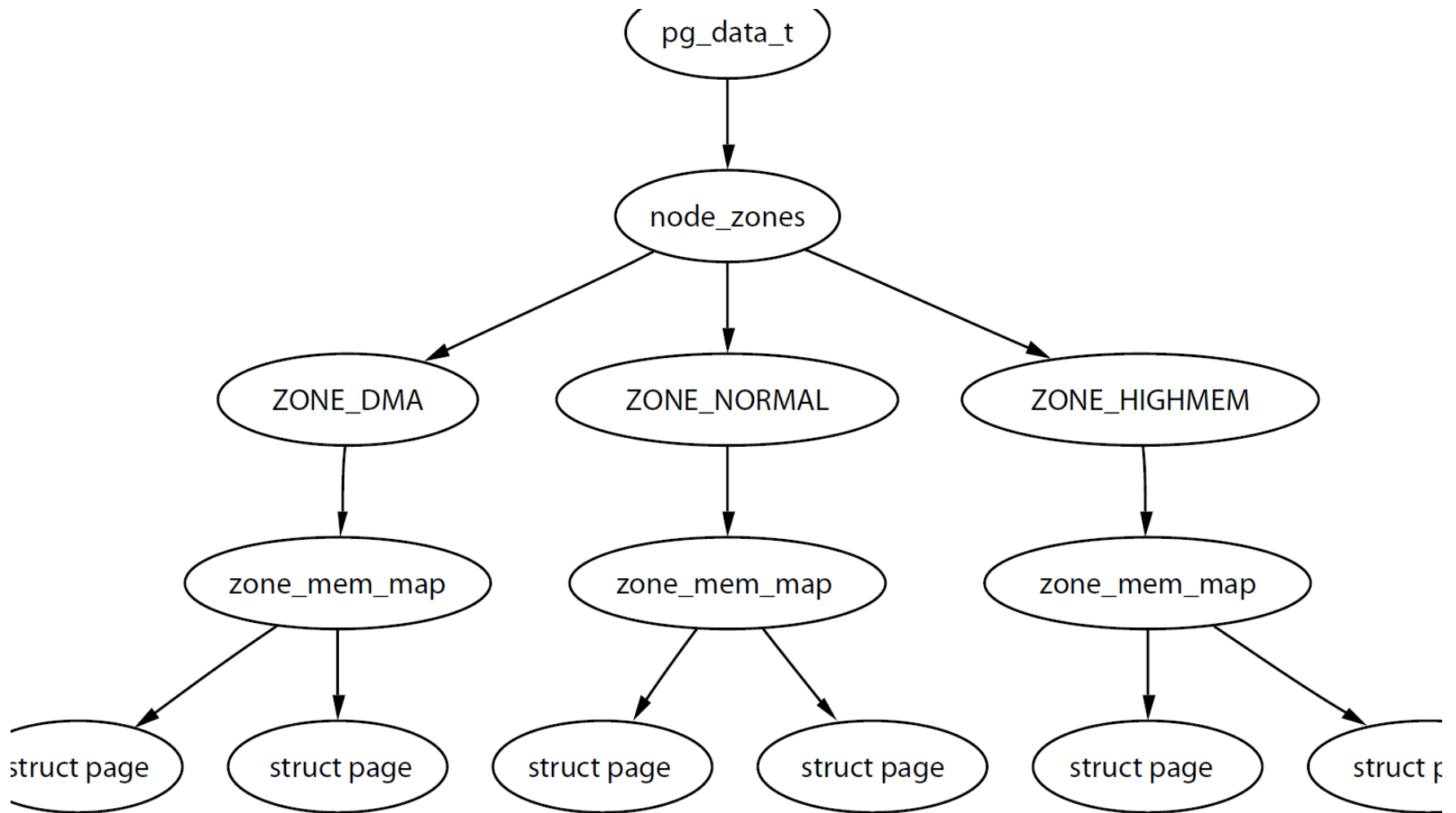
-
- overall, any element of the `free_area[]` array keeps
 - A pointer to the first free frame associated with blocks of a given order
 - A pointer to a bitmap that keeps fragmentation information according to the the “buddy system” organization

Buddy allocation vs core map vs free list



Recall that spinlocks are used to manage this data structure

A scheme (picture from: Understanding the Linux Virtual Memory Manager – Mel Gorman)



Jumping to more recent kernels for NUMA machines – kernel 2.6

- The concept of multiple NUMA zones is represented by a `struct pglist_data` even if the architecture is Uniform Memory Access (UMA)
- This struct is always referenced by its typedef `pg_data_t`
- Every node in the system is kept on a NULL terminated list called `pgdat_list`, and each node is linked to the next with the field `pg_data_t→node_next`
- For UMA architectures like PC desktops, only one static `pg_data_t` structure, as already seen called `contig_page_data` is used

A scheme

mem_map

pglist_data

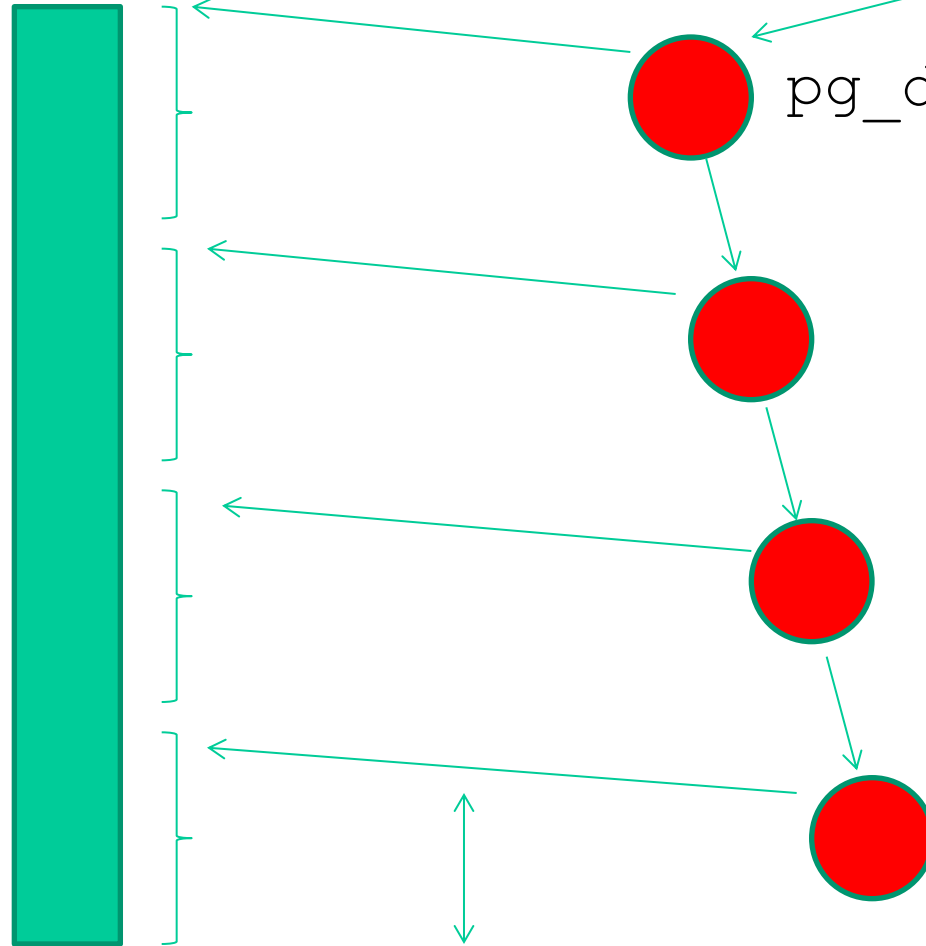
pg_data_t record



From kernel
2.6.17 we have
an array of entries
called
node_data[]

One buddy
allocator
per each
node

struct page *node_mem_map



Summarizing (still for 2.4 kernel)

- Architecture setup occurs via `setup_arch()` which will give rise to
 - a Core Map with all reserved frames
 - Free lists that look like if no frame is available (in fact they are all reserved at this stage)
- Most of the work is done by `free_area_init()`
- This relies on bitmaps allocation services based on `alloc_bootmem()`

Releasing boot used pages to the free lists

```
static unsigned long __init
free_all_bootmem_core(pg_data_t *pgdat)
{
    .....
    for (i = 0; i < idx; i++, page++) {
        if (!test_bit(i, bdata->node_bootmem_map)) {
            // il frame non deve restare riservato
            count++;
            ClearPageReserved(page);
            set_page_count(page, 1);
            __free_page(page);
        }
    }
    total += count;
    .....
    return total;
}
```

Allocation contexts (more generally, kernel level execution contexts)

- Process context
 - Allocation is caused by a system call
 - Not satisfiable → wait is experienced along the current execution trace
 - Priority based schemes
- Interrupt
 - Allocation requested by an interrupt handler
 - Not satisfiable → no-wait is experienced along the current execution trace
 - Priority independent schemes

Buddy-system API

- After booting, the memory management system can be accessed via proper APIs, which drive operations on the aforementioned data structures
- The prototypes are in `#include <linux/malloc.h>`
- The very base allocation APIs are (bare minimal – page aligned allocation)
 - `unsigned long get_zeroed_page(int flags)`
removes a frame from the free list, sets the content to zero and returns the virtual address
 - `unsigned long __get_free_page(int flags)`
removes a frame from the free list and returns the virtual address
 - `unsigned long __get_free_pages(int flags, unsigned long order)`
removes a block of contiguous frames with given `order` from the free list and returns the virtual address of the first frame

- `void free_page(unsigned long addr)`
puts a frame into the free list again, having a given initial virtual address
- `void free_pages(unsigned long addr, unsigned long order)`
puts a block of frames of given order into the free list again
Note!!!!!! Wrong order gives rise to kernel corruption in several kernel configurations

flags : used contexts

`GFP_ATOMIC` the call cannot lead to sleep (this is for interrupt contexts)

`GFP_USER` - `GFP_BUFFER` - `GFP_KERNEL` the call can lead to sleep

Buddy allocation vs direct mapping

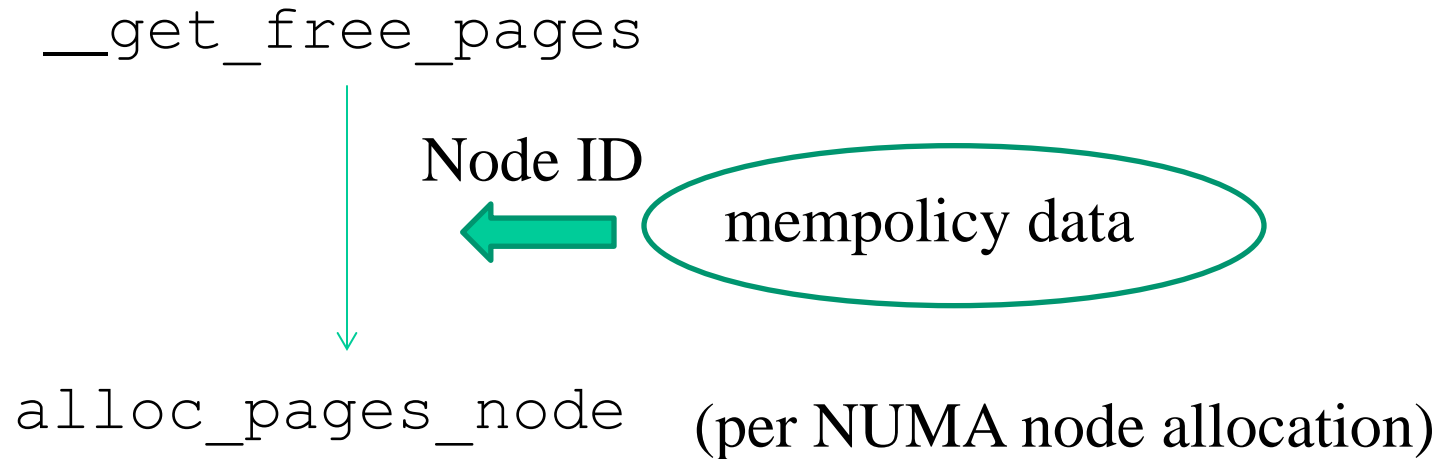
- All the buddy-system API functions return virtual addresses of direct mapped pages
- We can therefore directly discover the position in memory of the corresponding frames
- Also, memory contiguity is guaranteed for both virtual and physical addresses

Binding actual allocation to NUMA nodes

The real core of the Linux page allocator is the function

```
struct page *alloc_pages_node(int nid, unsigned  
    int flags, unsigned int order);
```

Hence the actual allocation chain is:



Mem-policy details

- Generally speaking, mem-policies determine what NUMA node needs to be involved in a specific allocation operation which is thread specific
- Starting from kernel 2.6.18, the determination of mempolicies can be configured by the application code via system calls

Synopsis

```
#include <numaif.h>

int set_mempolicy(int mode, unsigned long
                 *nodemask, unsigned long maxnode);
```

sets the NUMA memory policy of the calling process, which consists of a policy mode and zero or more nodes, to the values specified by the *mode*, *nodemask* and *maxnode* arguments

The *mode* argument must specify one of **MPOL_DEFAULT**, **MPOL_BIND**, **MPOL_INTERLEAVE** or **MPOL_PREFERRED**

... another example

Synopsis

```
#include <numaif.h>
```

```
int mbind(void *addr, unsigned long len, int  
mode, unsigned long *nodemask, unsigned long  
maxnode, unsigned flags);
```

sets the NUMA memory policy, which consists of a policy mode and zero or more nodes, for the memory range starting with *addr* and continuing for *len* bytes. The memory policy defines from which node memory is allocated.

... finally you can also move pages around

Synopsis

```
#include <numaif.h>
```

```
long move_pages(int pid, unsigned long count,  
void **pages, const int *nodes, int *status,  
int flags);
```

moves the specified *pages* of the process *pid* to the memory nodes specified by *nodes*. The result of the move is reflected in *status*. The *flags* indicate constraints on the pages to be moved.

The case of frequent allocation/deallocation of a target-specific data structures

- Here we are talking about allocation/deallocation operations of data structures
 1. that are used for a target-specific objective (e.g. in terms of data structures to be hosted)
 2. which are requested/released frequently
- The problem is that getting the actual buffers (pages) from the buddy system will lead to contention and consequent synchronization costs (does not scale)
- In fact the (per NUMA node) buddy system operates with spinlock synchronized critical sections
- Kernel design copes with this issue by using pre-reserved buffers with lightweight allocation/release logic

... a classical example

- The allocation and deletion of page tables, at any level, is a very frequent operation, so it is important the operation is as quick as possible
- Hence the pages used for the page tables are cached in a number of different lists called *quicklists*
- For 3 levels paging, PGDs, PMDs and PTEs have two sets of functions each for the allocation and freeing of page tables.
- The allocation functions are `pgd_alloc()`, `pmd_alloc()` and `pte_alloc()`, respectively the free functions are, predictably enough, called `pgd_free()`, `pmd_free()` and `pte_free()`
- Broadly speaking, these APIs implement caching

Actual quicklists

- Defined in `include/linux/quicklist.h`
- They are implemented as a list of per-core page lists
- There is no need for synchronization
- If allocation fails, they revert to
`__get_free_page()`

Quicklist API and algorithm

```
static inline void *quicklist_alloc(int nr, gfp_t flags, ...) {
    struct quicklist *q;
    void **p = NULL;

    q = &get_cpu_var(quicklist)[nr];
    p = q->page;
    if (likely(p)) {
        q->page = p[0];
        p[0] = NULL;
        q->nr_pages--;
    }
    put_cpu_var(quicklist);
    if (likely(p))
        return p;

    p = (void *)__get_free_page(flags | __GFP_ZERO);
    return p;
}
```

SLAB (or SLUB) allocator: a cache of ‘small’ size buffers

- The prototypes are in `#include <linux/malloc.h>`
- The main APIs are
 - `void *kmalloc(size_t size, int flags)`
allocation of contiguous memory **of a given size** - it returns the virtual address
 - `void kfree(void *obj)`
frees memory allocated via `kmalloc()`
- Main features:
 - Cache aligned delivery of memory chunks (performance optimal access of related data within the same chunk)
 - Fast allocation/deallocation support
- Clearly, we also can perform node-specific requests via
 - `void *kmalloc_node(size_t size, int flags, int node)`

What about large size allocations

- Classically employed while adding large size data structures to the kernel in a stable way
 - This is the case when, e.g., mounting external modules
 - **This time we are not guaranteed to get direct mapped pages**
 - The main APIs are:
 - `void * vmalloc(unsigned long size);`
allocates memory of a given size, which can be non-contiguous, **and returns the virtual address** (the corresponding frames are anyhow reserved)
 - `void vfree(void * addr)`
frees the above mentioned memory
-

Be careful of performance effects due to global TLB invalidations!!

Logical/Physical address translation for kernel directly mapped memory (not `vma1loc` one)

We can exploit the below macros for direct mapped pages

```
virt_to_phys(unsigned int addr)
```

```
(in include/asm-i386/io.h)
```

```
phys_to_virt(unsigned int addr)
```

```
(in include/asm-i386/io.h)
```

```
__pa()
```

```
__va()
```

In generic kernel versions

kmalloc vs vmalloc: an overall picture

- Allocation size:
 - 128 KB for kmalloc (cache aligned)
 - 64/128 MB for vmalloc
- Physical contiguousness
 - Yes for kmalloc
 - No for vmalloc
- Effects on TLB
 - None for kmalloc
 - Global for vmalloc (transparent to vmalloc users)