Advanced Operating Systems

MS degree in Computer Engineering
University of Rome Tor Vergata

Lecturer: Francesco Quaglia

Kernel level memory management

- 1. The very base on boot vs memory management
- 2. Memory 'Nodes' (UMA vs NUMA)
- 3. x86 paging support
- 4. Boot and steady state behavior of the memory management system in the Linux kernel

Basic terminology

- firmware: a program coded on a ROM device, which can be executed when powering a processor on
- **bootsector**: predefined device (e.g. disk) sector keeping executable code for system startup
- bootloader: the actual executable code loaded and launched right before giving control to the target operating system
 - ➤ this code is partially kept within the bootsector, and partially kept into other sectors
 - ➤It can be used to parameterize the actual operating system boot

Startup tasks

- The firmware gets executed, which loads in memory and launches the bootsector content
- The loaded bootsector code gets launched, which may load other bootloader portions
- The bootloader ultimately loads the actual operating system kernel and gives it control
- The kernel performs its own startup actions, which may entail architecture setup, data structures and software setup, and process activations
- To emulate a steady state unique scenario, at least one process is derived from the boot thread (namely the IDLE PROCESS)

Where is memory management there?

- All the previously listed steps lead to change the image of data that we have in memory
- These changes need to happen just based on various memory handling policies/mechanisms, operating at:
 - Kernel load time
 - ✓ Kernel initialization (including kernel level memory management initialization)
 - ✓ Kernel common operations (which make large usage of kernel level memory management services that have been setup along the boot phase)

An initially loaded kernel memory-image is not the same as the one that common applications ``see'' when they are activated

Traditional firmware on x86

- It is called BIOS (Basic I/O System)
- Interactive mode can be activated via proper interrupts (e.g. the F1 key)
- Interactive mode can be used to parameterize firmware execution (the parameterization is typically kept via CMOS rewritable memory devices powered by apposite temporary power suppliers)
- The BIOS parameterization can determine the order for searching the boot sector on different devices
- A device boot sector will be searched for only if the device is registered in the BIOS list

Bios boot sector

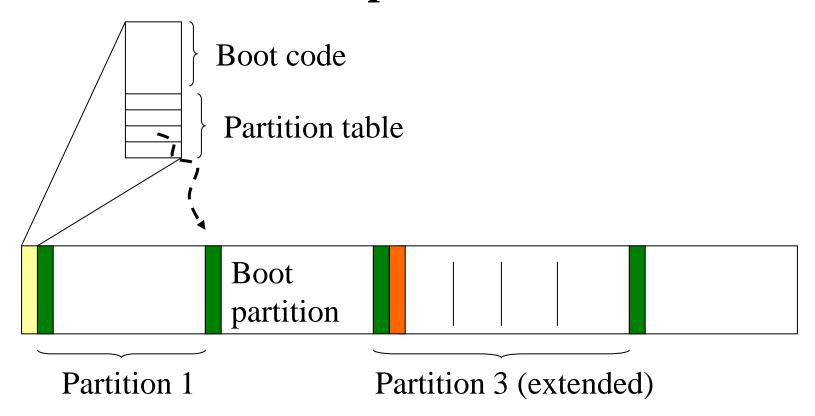
- The first device sector keeps the so called <u>master boot</u> record (MBR)
- This sector keeps executable code and a <u>4-entry tables</u>, each one identifying a different device partition (in terms of its positioning on the device)
- The first sector in each partition can operate as the partition boot sector (BS)
- In case the partition is extended, then it can additionally keep up to 4 sub-partitions (hence the partition boot sector can be structured to keep an additional partitioning table)
- Each sub-partition can keep its own boot sector

RAM image of the MBR

Offset	Size (bytes)	Description
0	436 (to 446, if you need a little extra	MBR Bootstrap (flat binary executable code)
0x1b4	10	Optional "unique" disk ID1
0x1be	64	MBR Partition Table, with 4 entries (below)
0x1be	16	First partition table entry
0x1ce	16	Second partition table entry
0x1de	16	Third partition table entry
0x1ee	16	Fourth partition table entry
0x1fe	2	(0x55, 0xAA) "Valid bootsector" signature bytes

Grub (if you use it) or others

An example scheme with Bios



- Boot sector
- Extended partition boot record

Nowadays huge limitation: the maximum size of manageable disks is 2TB

UEFI – Unified Extended Firmware Interface

- It is the new standard for basic system support (e.g. boot management)
- It removes several limitations of Bios:
 - We can (theoretically) handle disks up to 9 zettabytes
 - It has a more advanced visual interface
 - It is able to run EFI executables, rather than simply running the MBR code
 - It offers interfaces to the OS for being configured (rather than being exclusively configurable by triggering its interface with Fn keys at machine startup)

UEFI device partitioning

- Based on GPT (GUID Partition Table)
- GUID = Globally Unique Identifier Theoretically all over the world (if the GPT has in its turn a unique identifier)
- Theoretically unbounded number of partitions kept in this table No longer we nee extended partitions for enlarging the partitions' set
- GPT are replicated so that if a copy is corrupted then another one will work this breaks the single point of failure represented by MBR and its partition table

Bios/UEFI tasks upon booting the OS kernel

- The bootloader/EFI-loader, e.g., GRUB loads in memory the initial image of the operating system kernel
- This includes a ``machine setup code'' that needs to run before the actual kernel code takes control
- This happens since a kernel configuration needs given setup in the hardware upon being launched
- The machine setup code ultimately passes control to the initial kernel image
- In Linux, this kernel image executes starting from the start kernel() in the init/main.c
- This kernel image is way different, both in size and structure, from the one that will operate at steady state
- Just to name one reason, boot is typically highly configurable!

What about boot on multi-core machines

- The start_kernel() function is executed along a single CPU-core (the master)
- All the other cores (the slaves) only keep waiting that the master has finished
- The kernel internal function smp_processor_id() can be used for retrieving the ID of the current core
- This function is based on ASM instructions implementing a hardware specific ID detection protocol
- This function operates correctly either at kernel boot or at steady state

The actual support for CPU-core identification

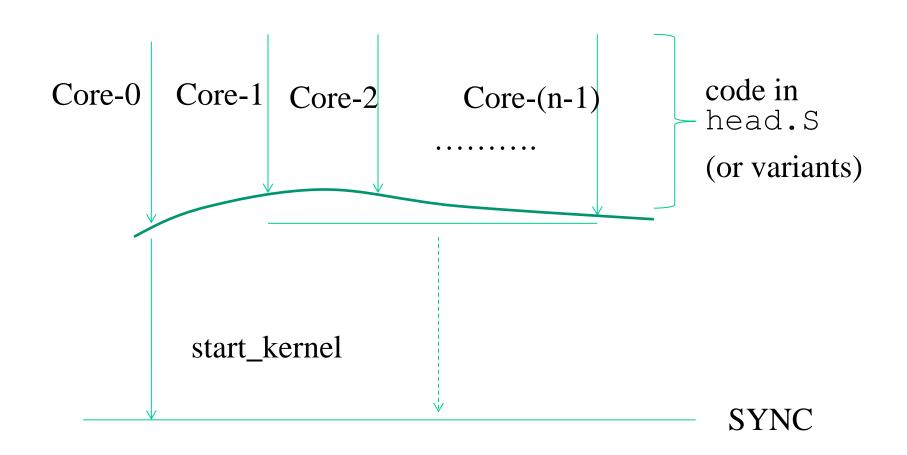
x86 Instruction Set Reference

CPUID

CPU Identification

	Opcode	Mnemonic	Description	
6	F A2	CPUID	Returns processor identification and feature information to the EAX, EBX, ECX, and EDX registers, according to the input value	
			entered initially in the EAX register.	

Actual kernel startup scheme in Linux



An example head. S code snippet: triggering Linux paging (IA32 case)

```
/* * Enable paging */ 3:
movl $swapper_pg_dir-__PAGE_OFFSET,%eax
movl %eax,%cr3 /* set the page table
pointer.. */
movl %cr0,%eax
orl $0x80000000,%eax
movl %eax,%cr0 /* ..and set paging (PG) bit
*/
```

Hints on the signature of the start kernel function (as well as others)

..... __init start_kernel(void)

This only lives in memory during kernel boot (or startup)

The reason for this is to recover main memory storage which is relevant because of both:

- Reduced available RAM (older configurations)
- Increasingly complex (and hence large in size) startup code

Recall that the kernel image is not subject to swap out (conventional kernels are always resident in RAM)

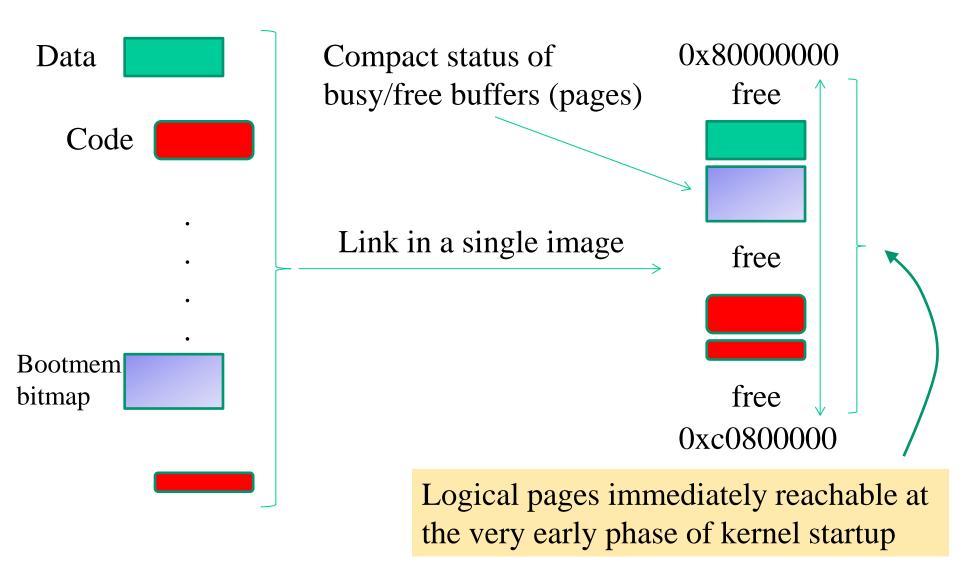
Management of init functions

- The kernel linking stage locates these functions on specific logical pages (recall what we told about the fixed positioning of specific kernel level stuff in the kernel layout!!)
- These logical pages are identified within a "bootmem" subsystem that is used for managing memory when the kernel is not yet at steady state of its memory management operations
- Essentially the bootmem subsystem keeps a bitmask with one bit indicating whether a given page has been used (at compile time) for specific stuff

... still on bootmem

- The bootmem subsystem also allows for memory allocation upon the very initial phase of the kernel startup
- In fact, the data structures (e.g. the bitmaps) it keeps not only indicate if some page has been used for specific data/code
- They also indicate if some page which is actually reachable at the very early phase of boot is not used for any stuff
- These are clearly "free buffers" exploitable upon the very early phase of boot

An exemplified picture of bootmem



The meaning of reachable page

- The kernel software can access the actual content of the page (in RAM) by simply expressing an address falling into that page
- The point is that the expressed address is typically a virtual one (since kernel code is commonly written using `pointer' abstractions)
- So the only way we have to make a virtual address correspond to a given page frame in RAM is to rely on at least a page table that makes the translation (even at the very early stage of kernel boot)
- The initial kernel image has a page table, with a minimum number of pages mapped in RAM, those handled by the bootmem subsystem

How is RAM memory organized on modern (large scale/parallel) machines?

- In modern chipsets, the CPU-core count continuously increases
- However, it is increasingly difficult to build architectures with a flat-latency memory access (historically referred to as UMA)
- Current machines are typically NUMA
- Each CPU-core has some RAM banks that are close and other that are far
- Generally speaking, each memory bank is associated with a so called NUMA-node
- Modern operating systems are designed to handle NUMA machines (hence UMA as a special case)

Looking at the Linux NUMA setup via Operating System facilities

- A very simple way is the numactl command
- It allows to discover
 - ✓ How many NUMA nodes are present
 - ✓ What are the nodes close/far to/from any CPU-core
 - ✓ What is the actual distance of the nodes (from the CPU-cores)

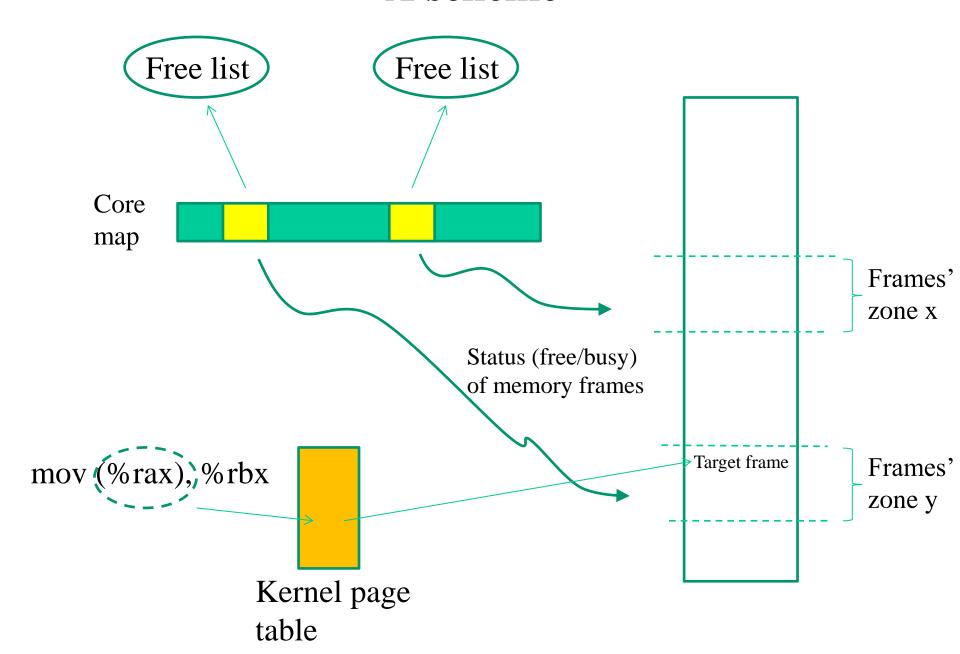
Let's see a few 'live' examples

Actual kernel data structures for managing memory

- Kernel Page table
 - This is a kind of 'ancestral' page table (all the others are somehow derived from this one)
 - ➤ It keeps the memory mapping for kernel level code and data (thread stack included)
- Core map
 - The map that keeps status information for any frame (page) of physical memory, and for any NUMA node
- Free list of physical memory frames, for any NUMA node

None of them is already finalized when we startup the kernel

A scheme

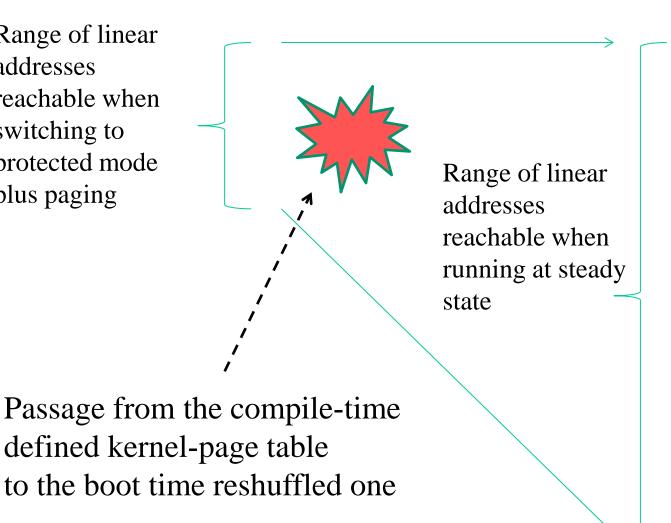


Objectives of the kernel page table setup

- These are basically two:
 - ✓ Allowing the kernel software to use virtual addressed while executing (either at startup or at steady state)
 - ✓ Allowing the kernel software (and consequently the application software) to reach (in read and/or write mode) the maximum admissible (for the specific machine) or available RAM storage
- The finalized shape of the kernel page table is therefore typically not setup into the original image of the kernel loaded in memory, e.g., given that the available RAM to drive can be parameterized

A scheme

Range of linear addresses reachable when switching to protected mode plus paging

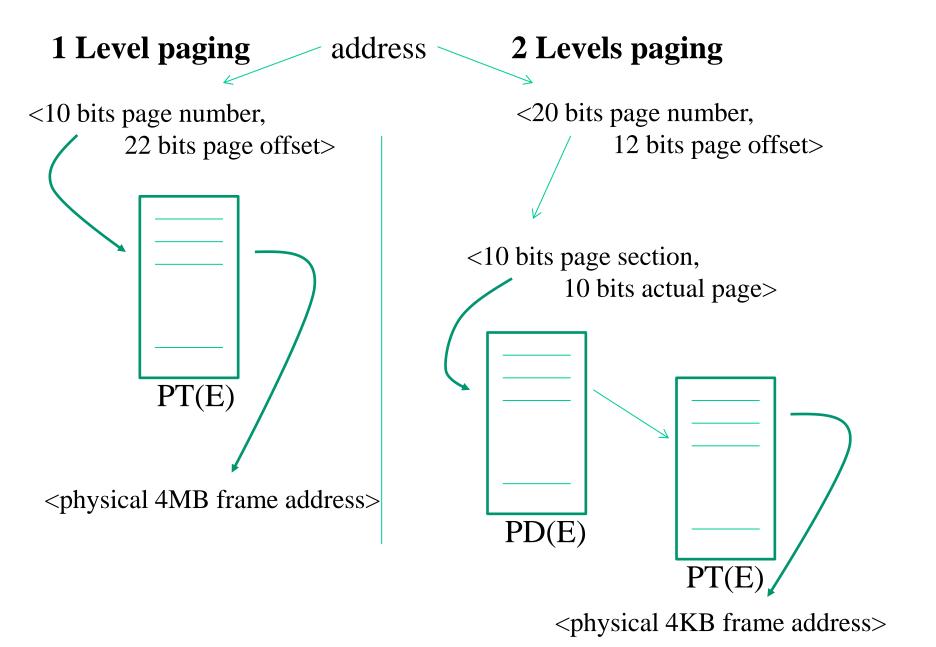


Increase of the size of reachable RAM locations

Virtual memory vs boot sequence (IA32 example)

- Upon kernel startup addressing relies on a simple single level paging mechanism that only maps 2 pages (each of 4 MB) up to 8 MB physical addresses
- The actual paging rule (namely the page granularity and the number of paging levels up to 2 in i386) is identified via proper bits within the entries of the page table
- The physical address of the setup page table is kept within the CR3 register
- The steady state paging scheme used by LINUX will be activated during the kernel boot procedure
- The max size of the address space for LINUX processes on i386 machines (or protected mode) is 4 GB
 - > 3 GB are within user level segments
 - ➤ 1 GB is within kernel level segments

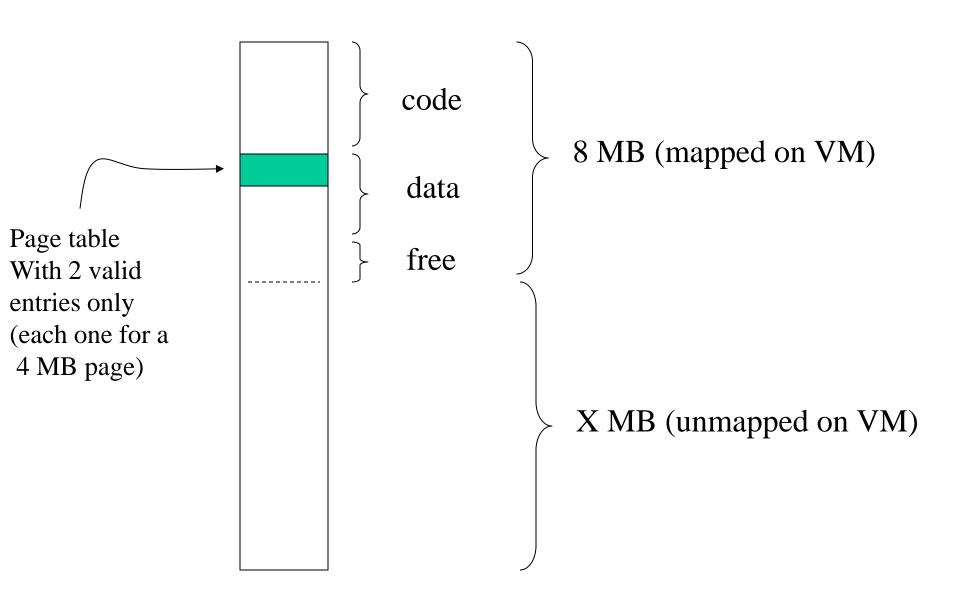
Details on the page table structure in i386 (i)



Details on the page table structure in i386 (ii)

- It is allocated in physical memory into 4KB blocks, which can be non-contiguous
- In typical LINUX configurations, once set-up it maps 4 GB addresses, of which 3 GB at null reference and (almost) 1 GB onto actual physical memory
- Such a mapped 1 GB corresponds to kernel level virtual addressing and allows the kernel to span over 1 GB of physical addresses
- To drive more physical memory, additional configuration mechanisms need to be activated, or more recent processors needs to be exploited as we shall see

i386 memory layout at kernel startup for 2.4 kernels



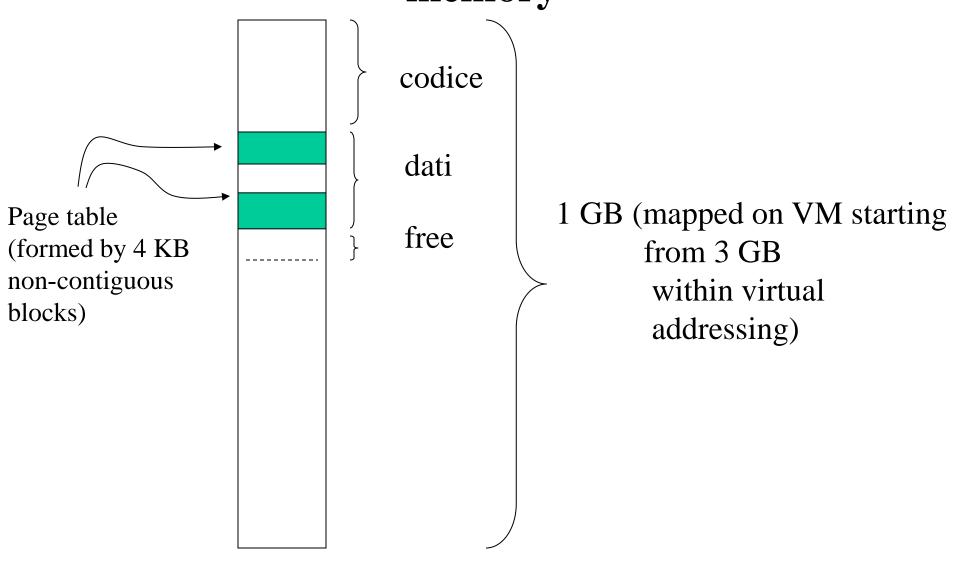
Actual issues to be tackled

- 1. We need to reach the correct granularity for paging (4KB rather than 4MB)
- 2. We need to span logical to physical address across the whole 1GB of kernel-manageable physical memory
- 3. We need to re-organize the page table in two separate levels
- 4. So we need to determine 'free buffers' within the already reachable memory segment to initially expand the page table
- 5. We cannot use memory management facilities other than paging (since core maps and free lists are not yet at steady state)

Back to the concept of bootmem

- 1. Memory occupancy and location of the initial kernel image is determined by the compile/link process
- 2. A compile/link time memory manager is embedded into the kernel image, which is called bootmem manager
- 3. It relies on bitmaps telling if any 4KB page in the currently reachable memory image is busy or free
- 4. It also offers API (to be employed at boot time) in order to get free buffers
- 5. These buffers are sets of contiguous (or single) page alligned areas
- 6. This subsystem is in charge of handling _init marked functions in terms of final release of the corresponding buffers

Kernel page table collocation within physical memory

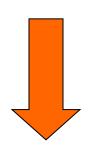


Low level "pages"

Load undersized page table (kernel page size not finalized: 4MB)

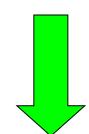
- 4 KB (1K entry)

Finalize kernel handled page size (4KB)



Expand page table via boot mem low pages (not marked in the page table)

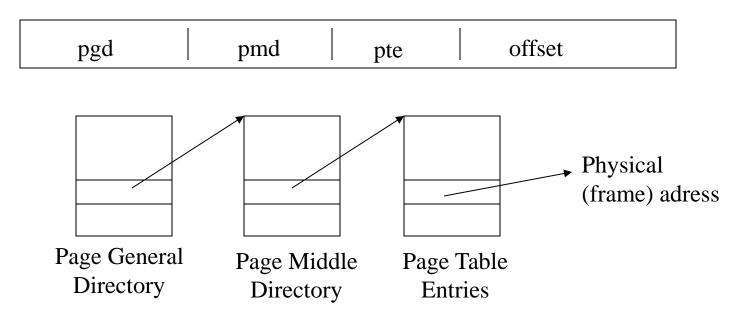
- compile time identification



Kernel boot

LINUX paging vs i386

• LINUX virtual addresses exhibit (at least) 3 indirection levels



- On i386 machines, paging is supported limitedly to 2 levels (pde, page directory entry pte, page table entry)
- Such a dicotomy is solved by setting null the pmd field, which is proper of LINUX, and mapping
 - ▶pgd LINUX on pde i386
 - >pte LINUX on pte i386

i386 page table size

- Both levels entail 4 KB memory blocks
- Each block is an array of 4-byte entries
- Hence we can map 1 K x 1K pages
- Since each page is 4 KB in sixe, we get a 4 GB virtual addressing space
- The following macros define the size of the page tables blocks (they can be found in the file include/asm-i386/pgtable-2level.h)

```
▶#define PTRS_PER_PGD 1024
▶#define PTRS_PER_PMD 1
▶#define PTRS_PER_PTE 1024
```

• the value1 for PTRS_PER_PMD is used to simulate the existence of the intermediate level such in a way to keep the 3-level oriented software structure to be compliant with the 2-level architectural support

Page table data structures

- A core structure is represented by the symbol swapper_pg_dir which is defined within the file arch/i386/kernel/head.S
- This symbol expresses the virtual memory address of the **PGD (PDE)** portion of the kernel page table
- This value is initialized at compile time, depending on the memory layout defined for the kernel bootable image
- Any entry within the PGD is accessed via displacement starting from the initial PGD address
- The C types for the definition of the content of the page table entries on i386 are defined in include/asm-i386/page.h
- They are

```
typedef struct { unsigned long pte_low; } pte_t;
typedef struct { unsigned long pmd; } pmd_t;
typedef struct { unsigned long pgd; } pgd t;
```

Debugging

- The redefinition of different structured types, which are identical in size and equal to an unsigned long, is done for debugging purposes
- Specifically, in C technology, <u>different aliases for the same type</u> are considered as identical types
- For instance, if we define typedef unsigned long pgd_t;

typedef unsigned long pte_t;

pgd_t x; pte_t y;

the compiler enables assignments such as x=y and y=x

• Hence, there is the need for defining different structured types which simulate the base types that would otherwise give rise to compiler equivalent aliases

i386 PDE entries

Page-Directory Entry (4-KByte Page Table)

31		12	11	9	8	7	6	5	4	3	2	1	0
	Page-Table Base Address		Ava	il	G	PS	0	Α	P C D	P W T	U / S	R / W	Р
	Available for system programmer's use Global page (Ignored) ————————————————————————————————————												

i386 PTE entries

Page-Table Entry (4-KByte Page)

31		12	11	9	8	7	6	5	4	3	2	1	0
	Page Base Address		Avai	l	G	P A T	D	А	P C D	P W T	U / S	R / W	Р
	Available for system programmer's use Global Page Page Table Attribute Index Dirty Accessed Cache Disabled Write-Through User/Supervisor Read/Write Present												

Field semantics

- **Present**: indicates whether the page or the pointed page table is loaded in physical memory. This flag is not set by firmware (rather by the kernel)
- **Read/Write**: define the access privilege for a given page or a set of pages (as for PDE). Zero means read only access
- User/Supervisor: defines the privilege level for the page or for the group of pages (as for PDE). Zero means supervisor privilege
- Write Through: indicates the caching policy for the page or the set of pages (as for PDE). Zero means write-back, non-zero means write-through
- Cache Disabled: indicates whether caching is enabled or disabled for a page or a group of pages. Non-zero value means disabled caching (as for the case of memory mapped I/O)

- Accessed: indicates whether the page or the set of pages has been accessed. This is a sticky flag (no reset by firmware). Reset is controlled via software
- **Dirty**: indicates whether the page has been write-accessed. This is also a sticky flag
- Page Size (PDE only): if set indicates 4 MB paging otherwise 4 KB paging
- Page Table Attribute Index: Do not care
- Page Global (PTE only): defines the caching policy for TLB entries.
 Non-zero means that the corresponding TLB entry does not require reset upon loading a new value into the page table pointer CR3

Bit masking

- in include/asm-i386/pgtable.h there exist some macros defining the positioning of control bits within the entries of the PDE or PTE
- There also exist the following macros for masking and setting those bits

• These are all machine dependent macros

An example

```
pte t x;
x = ...;
if ((x.pte low) & PAGE PRESENT) {
    /* the page is loaded in a frame */
else{
     /* the page is not loaded in any
         frame */
```

Relations with trap/interrupt events

- Upon a TLB miss, firmware accesses the page table
- The first checked bit is typically _PAGE_PRESENT
- If this bit is zero, a page fault occurs which gives rise to a trap (with a given displacement within the trap/interrupt table)
- Hence the instruction that gave rise to the trap can get finally re-executed
- Re-execution might give rise to additional traps, depending on firmware checks on the page table
- As an example, the attempt to access a read only page in write mode will give rise to a trap (which triggers the **segmentation fault handler**)

Run time detection of current page size on IA-32 processors and 2.4 Linux kernel

Kernel page table initialization details

- As said, the kernel PDE is accessible at the virtual address kept by swapper_pg_dir (now init_level4_pgt on x86-64/kernel 3 or init top pgt on x86-64/kernel4)
- The room for PTE tables gets reserved within the 8MB of RAM that are accessible via the initial paging scheme
- Reserving takes place via the macro alloc_bootmem_low_pages() which is defined in include/linux/bootmem.h (this macro returns a virtual address)
- Particularly, it returns the pointer to a 4KB (or 4KB x N) buffer which is page aligned
- This function belongs to the (already hinted) basic memory management subsystem upon which the LINUX memory system boot lies on

Kernel 2.4/i386 initialization algorithm

- we start by the PGD entry which maps the address 3 GB, namely the entry numbered 768
- cyclically
 - 1. We determine the virtual address to be memory mapped (this is kept within the vaddr variable)
 - 2. One page for the PTE table gets allocated which is used for mapping 4 MB of virtual addresses
 - 3. The table entries are populated
 - 4. The virtual address to be mapped gets updated by adding 4 MB
 - 5. We jump to step 1 unless no more virtual addresses or no more physical memory needs to be dealt with (the ending condition is recorded by the variable end)

Initialization function pagetable init()

```
for (; i < PTRS PER PGD; pgd++, i++) {
       vaddr = i*PGDIR SIZE; /* i is set to map from 3 GB */
       if (end && (vaddr >= end)) break;
       pmd = (pmd t *)pgd;/* pgd initialized to (swapper pg dir+i) */
       for (j = 0; j < PTRS PER PMD; pmd++, j++) {
       pte base = pte = (pte t *) alloc bootmem low pages(PAGE SIZE);
       for (k = 0; k < PTRS PER PTE; pte++, k++) {
              vaddr = i*PGDIR SIZE + j*PMD SIZE + k*PAGE SIZE;
              if (end && (vaddr >= end)) break;
                      *pte = mk pte phys( pa(vaddr), PAGE KERNEL);
       set pmd(pmd, pmd( KERNPG TABLE + pa(pte base)));
```

Note!!!

- The final PDE buffer coincides with the initial page table that maps 4 MB pages
- 4KB paging gets activated upon filling the entry of the PDE table (since the Page Size bit gets updated)
- For this reason the PDE entry is set only after having populated the corresponding PTE table to be pointed
- Otherwise memory mapping would be lost upon any TLB miss

The set_pmd macro

```
#define set pmd(pmdptr, pmdval) (*(pmdptr) = pmdval)
```

- Thia macro simply sets the value into one PMD entry
- Its input parameters are
 - > the pmdptr pointer to an entry of PMD (the type is pmd_t)
 - The value to be loaded pmdval (of type pmd_t, defined via casting)
- While setting up the kernel page table, this macro is used in combination with __pa() (physical address) which returns an unsigned long
- The latter macro returns the physical address corresponding to a given virtual address within kernel space (except for some particular virtual address ranges)
- Such a mapping deals with [3,4] GB virtual addressing onto [0,1] GB physical addressing

The mk_pte_phys() macro

```
mk_pte_phys(physpage, pgprot)
```

- The input parameters are
 - A frame physical address physpage, of type unsigned long
 - > A bit string paprot for a PTE, of type paprot t
- The macro builds a complete PTE entry, which includes the physical address of the target frame
- The result type is pte_t
- The result value can be then assigned to one PTE entry

PAE (Physical address extension)

- increase of the bits used for physical addressing
- offered by more recent x86 processors (e.g. Intel Pentium Pro) which provide up to 36 bits for physical addressing
- we can drive up to 64 GB of RAM memory
- paging gets operated at 3 levels (instead of 2)
- the traditional page tables get modified by extending the entries at 64-bits and reducing their number by a half (hence we can support 1/4 of the address space)
- an additional top level table gets included called "page directory pointer table" which entails 4 entries, pointed by CR3
- CR4 indicates whether PAE mode is activated or not (which is done via bit 5 PAE-bit)

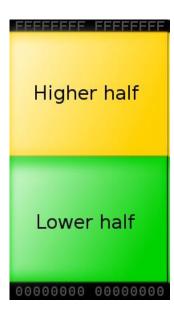
x86-64 architectures

- They extend the PAE scheme via a so called "long addressing mode"
- Theoretically they allow addressing 2^64 bytes of logical memory
- In actual implementations we reach up to 2^48 canonical form addresses (lower/upper half within a total address space of 2^48)
- The total allows addressing to span over 256 TB
- Not all operating systems allow exploiting the whole range up to 256 TB of logical/physical memory
- LINUX currently allows for 128 TB for logical addressing of individual processes and 64 TB for physical addressing

Addressing scheme

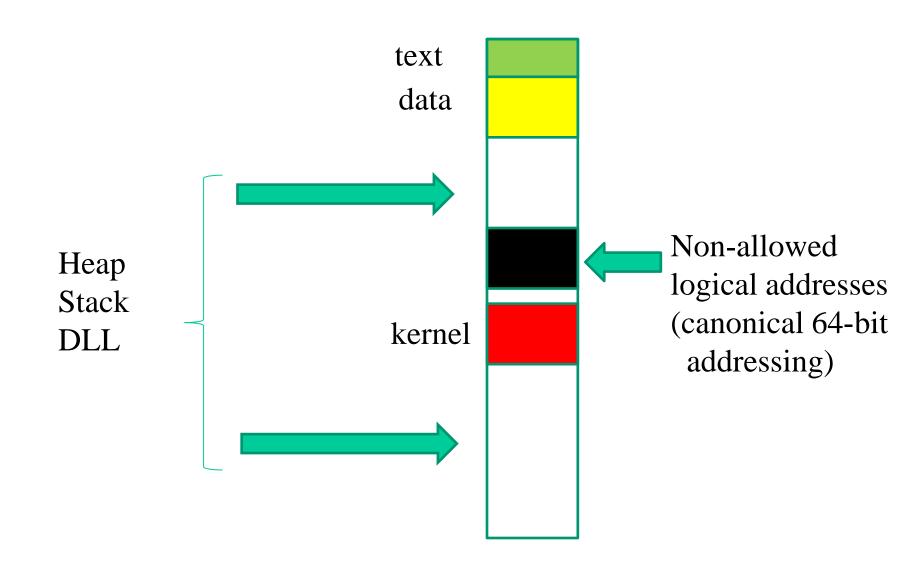
64-bit

48 out of 64-bit



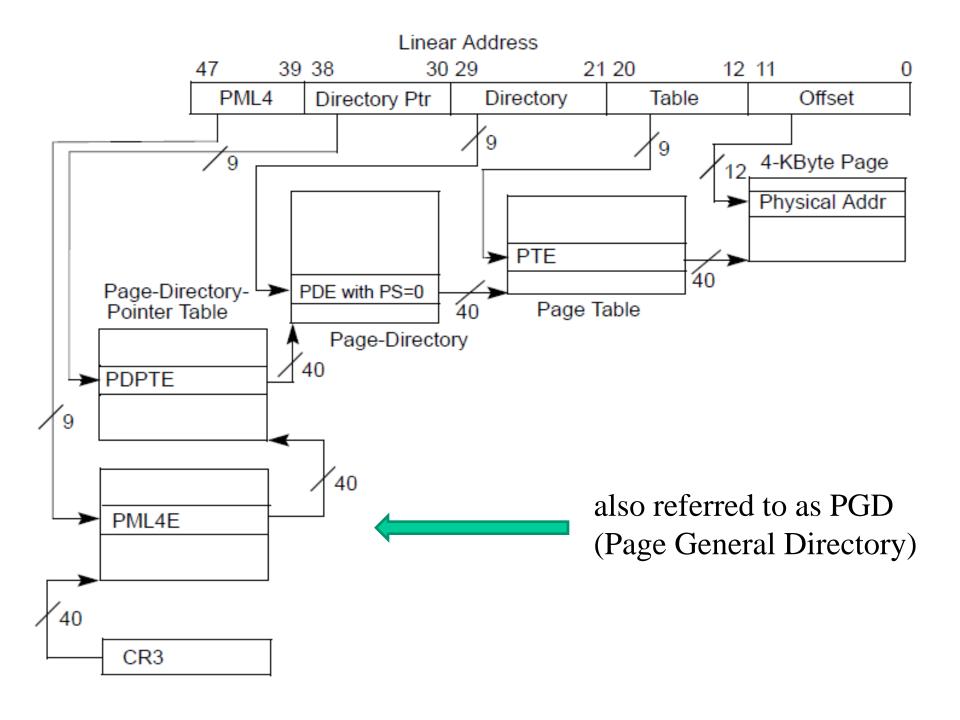


Linux address space on x86-64 processors



48-bit addressing: page tables

- Page directory pointer has been expanded from 4 to 512 entries
- An additional paging level has been added thus reaching 4 levels, this is called "Page-Map level"
- Each Page-Map level table has 512 entries
- Hence we get 512⁴ pages of size 4 KB that are addressable (namely, a total of 256 TB)



6 3	6 6 6 5 5 5 5 5 5 5 5 5 5 2 1 0 9 8 7 6 5 4 3 2	5 1 M ¹	M-1 3 3 3 2 1 0	2 2 2 2 2 2 2 2 2 2 9 8 7 6 5 4 3 2 1	2 1 1 1 1 1 1 1 1 0 9 8 7 6 5 4 3	1 1 1 2 1 0 9	8 7	6 5	4	3 2 1	0	
	Reserved ²			Address of PML4 ta			nore		P C D	P W Ign T		CR3
3 D	Ignored	Rsvd.	Address	of page-directory-p	ointer table	lgn.	Rs vo	g A n	P C D	P U R W/S / T	1	PML4E: present
				Ignored		•	•				<u>0</u>	PML4E: not present
X D	Ignored	Rsvd.	Address of 1GB page frame	Reser	ved	P A Ign. T	G <u>1</u>			P U R W/S W		PDPTE: 1GB page
X D	Ignored	Rsvd.	F	Address of page direc	ctory	lgn.	0	I g A n	D D	P U R W/S W	1	PDPTE: page directory
			•	Ignored		•	·				<u>0</u>	PDTPE: not present
X D	Ignored	Rsvd.		dress of age frame	Reserved	P A Ign. T	G <u>1</u>		- 1 - 1	P U R W/S / T		PDE: 2MB page
X D	Ignored	Rsvd.		Address of page tal	ble	lgn.	0	I g A n	P C D	P U R W/S W	1	PDE: page table
				Ignored							<u>0</u>	PDE: not present
X D	Ignored	Rsvd.	A	ddress of 4KB page t	frame	lgn.	G A T	D A	P C D	P U R W /S W	1	PTE: 4KB page
				Ignored					-		<u>0</u>	PTE: not present

Figure 4-11. Formats of CR3 and Paging-Structure Entries with IA-32e Paging

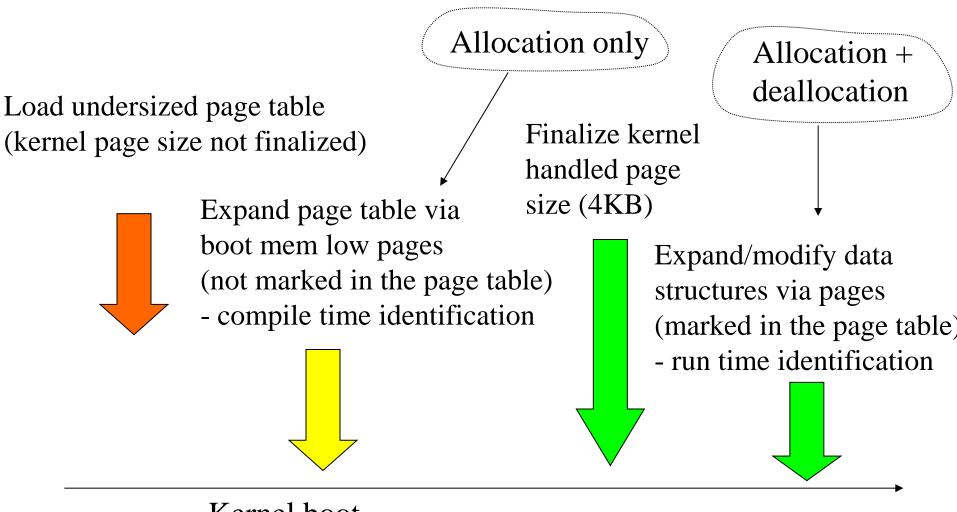
Table 4-19. Format of an IA-32e Page-Table Entry that Maps a 4-KByte Page

Bit Position(s)	Contents
0 (P)	Present; must be 1 to map a 4-KByte page
1 (R/W)	Read/write; if 0, writes may not be allowed to the 4-KByte page referenced by this entry (see Section 4.6)
2 (U/S)	User/supervisor; if 0, user-mode accesses are not allowed to the 4-KByte page referenced by this entry (see Section 4.6)
3 (PWT)	Page-level write-through; indirectly determines the memory type used to access the 4-KByte page referenced by this entry (see Section 4.9.2)
4 (PCD)	Page-level cache disable; indirectly determines the memory type used to access the 4-KByte page referenced by this entry (see Section 4.9.2)
5 (A)	Accessed; indicates whether software has accessed the 4-KByte page referenced by this entry (see Section 4.8)
6 (D)	Dirty; indicates whether software has written to the 4-KByte page referenced by this entry (see Section 4.8)
7 (PAT)	Indirectly determines the memory type used to access the 4-KByte page referenced by this entry (see Section 4.9.2)
8 (G)	Global; if CR4.PGE = 1, determines whether the translation is global (see Section 4.10); ignored otherwise
11:9	Ignored
(M-1):12	Physical address of the 4-KByte page referenced by this entry
51:M	Reserved (must be 0)
62:52	Ignored
63 (XD)	If IA32_EFER.NXE = 1, execute-disable (if 1, instruction fetches are not allowed from the 4-KByte page controlled by this entry; see Section 4.6); otherwise, reserved (must be 0)

Huge pages

- Ideally x86-64 processors support them starting from PDPT
- Linux typically offers the support for huge pages pointed to by the PDE (page size 512*4KB)
- See: /proc/meminfo and /proc/sys/vm/nr_hugepages
- These can be "mmaped" via file descriptors and/or mmap parameters (e.g. MAP_HUGETLB flag)
- They can also be requested via the madvise (void*, size_t, int) system call (with MADV_HUGEPAGE flag)

Reaching vs allocating/deallocating memory



Kernel boot

Core map

- It is an array of mem_map_t (also known as struct page) structures defined in include/linux/mm.h
- The actual type definition is as follows (or similar along kernel advancement):

```
typedef struct page {
                                      /* ->mapping has some page lists. */
    struct list head list;
                                      /* The inode (or ...) we belong to. */
    struct address space *mapping;
    unsigned long index;
                                      /* Our offset within mapping. */
    struct page *next hash;
                                      /* Next page sharing our hash bucket in
                                         the pagecache hash table. */
                                      /* Usage count, see below. */
    atomic t count;
                                      /* atomic flags, some possibly
    unsigned long flags;
                                         updated asynchronously */
                                      /* Pageout list, eq. active list;
    struct list head lru;
                                         protected by pagemap lru lock !! */
    struct page **pprev_hash; /* Complement to *next hash. */
    struct buffer head * buffers; /* Buffer maps us to a disk block. */
#if defined(CONFIG HIGHMEM) || defined(WANT PAGE VIRTUAL)
    void *virtual;
                                      /* Kernel virtual address (NULL if
                                         not kmapped, ie. highmem) */
#endif /* CONFIG HIGMEM || WANT PAGE VIRTUAL */
} mem map t;
```

Fields

- Most of the fields are used to keep track of the interactions between memory management and other kernel sub-systems (such as I/O)
- Memory management proper fields are
 - > struct list_head list (whose type is defined in include/linux/lvm.h), which is used to organize the frames into free lists
 - ➤ atomic_t count, which counts the virtual references mapped onto the frame (it is managed via atomic updates, such as with LOCK directives)
 - > unsigned long flags, this field keeps the status bits for the frame, such as:

```
#define PG_locked 0
#define PG_referenced 2
#define PG_uptodate 3
#define PG_dirty 4
#define PG_lru 6
#define PG_lru 6
```

Core map initialization (i386/kernel 2.4)

- Initially we only have the core map pointer
- This is mem_map and is declared in mm/memory.c
- Pointer initialization and corresponding memory allocation occur within free area init()
- After initializing, each entry will keep the value 0 within the count field and the value 1 into the PG_reserved flag within the flags field
- Hence no virtual reference exists for that frame and the frame is reserved
- Frame un-reserving will take place later via the function mem_init() in arch/i386/mm/init.c (by resetting the bit PG reserved)

Free list organization: single NUMA zone – or NUMA unaware – protected mode case (e.g. kernel 2.4)

- we have 3 free lists of frames, depending on the frame positioning within the following zones: DMA (DMA ISA operations), NORMAL (room where the kernel can reside), HIGHMEM (room for user data)
- The corresponding defines are in include/linux/mmzone.h:

```
#define ZONE_DMA 0
#define ZONE_NORMAL 1
#define ZONE_HIGHMEM 2
#define MAX NR ZONES 3
```

• The corresponding sizes are usually defined as

Free list data structures

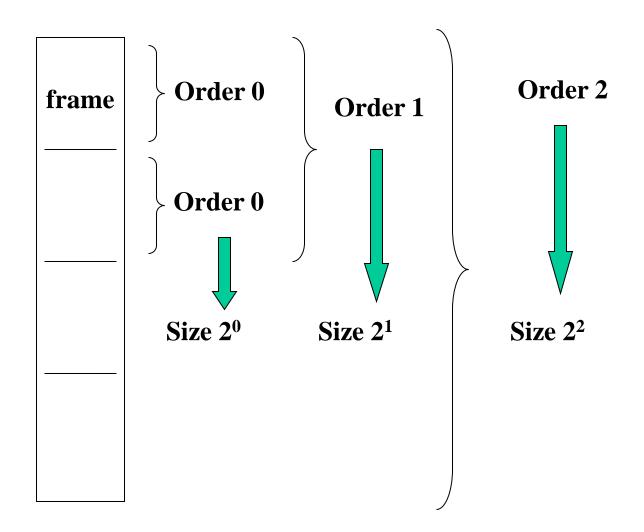
• Free lists information is kept within the pg_data_t data structure defined in include/linux/mmzone.h, and whose actual instance is contig_page_data, which is declared in mm/numa.c

```
typedef struct pglist data {
           zone t node zones[MAX NR ZONES];
           zonelist t node zonelists[GFP ZONEMASK+1];
           int nr zones;
Field of
           struct page *node mem map;
           unsigned long *valid addr bitmap;
interest
           struct bootmem data *bdata;
           unsigned long node start paddr;
           unsigned long node start mapnr;
           unsigned long node size;
           int node id;
           struct pglist data *node next;
       pg data t;
```

• the zone_t type is defined in include/linux/mmzone.h as follows

```
typedef struct zone struct {
            spinlock t
                                 lock;
            unsigned
                                 long
                                        free pages;
            zone watermarks t watermarks [MAX NR ZONES];
                                 need balance;
            unsigned long
            unsigned long nr active pages, nr_inactive_pages;
            unsigned long
                                 nr cache pages;
            free area t
                                 free area[MAX ORDER];
                                 * wait table;
            wait queue head t
            unsigned long
                                 wait table size;
                                wait table shift;
           unsigned long
                                                     Up to 11 in
Fields of
            struct pglist data
                                 *zone pgdat;
                                                     recent
interest
                                 *zone_mem_map;
           struct page
                                                      kernel versions
            unsigned long
                                 zone start paddr;
                                                      (it was typically
            unsigned long
                                 zone start mapnr;
                                                      5 before)
            char
                                 *name;
            unsigned long
                                 size;
            unsigned long
                                 realsize;
       zone t;
```

Buddy system features



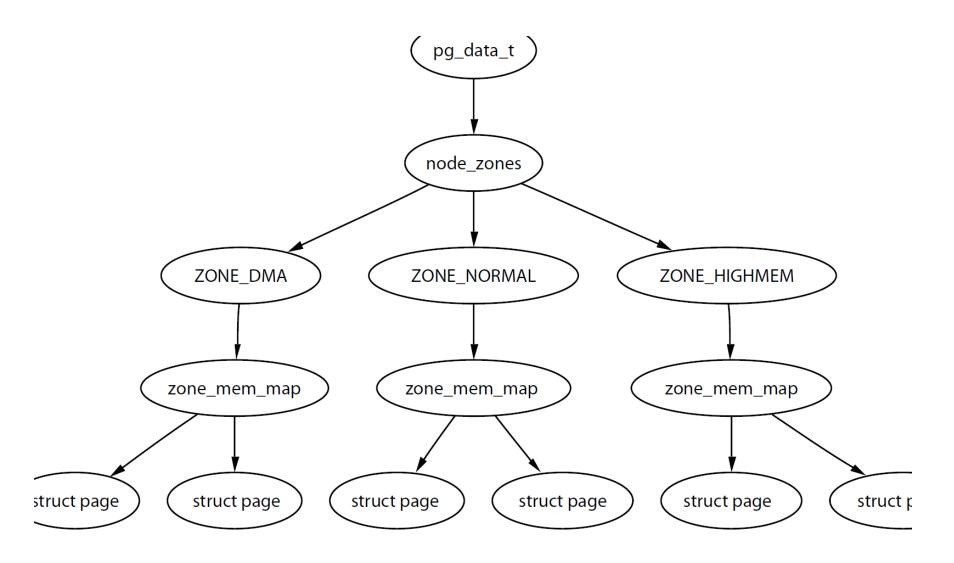
• free area t is defined in the same file as

where

```
struct list_head {
      struct list_head *next, *prev;
}
```

- overall, any element of the free_area[] array keeps
 - A pointer to the first free frame associated with blocks of a given order
 - A pointer to a bitmap that keeps fragmentation information according to the 'buddy system' organization

A scheme (picture from: Understanding the Linux Virtual Memory Manager – Mel Gorman)



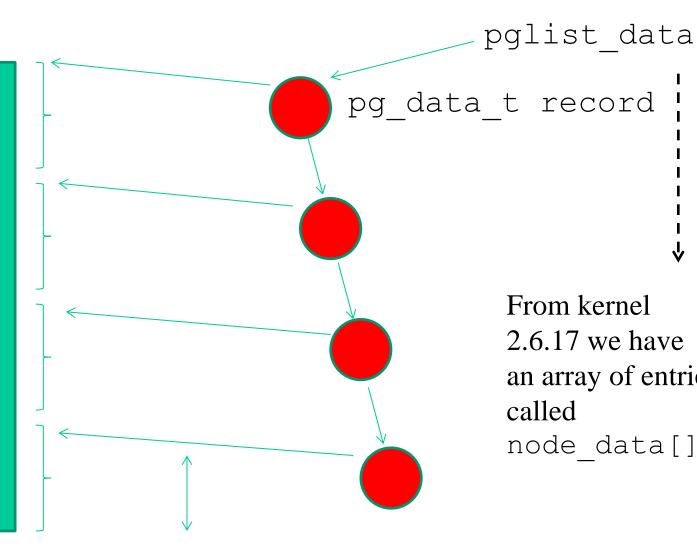
Jumping to more recent kernels for NUMA machines – kernel 2.6

- The concept of multiple NUMA zones is represented by a struct pglist_data even if the architecture is Uniform Memory Access (UMA)
- This struct is always referenced by its typedef pg_data_t
- Every node in the system is kept on a NULL terminated list called pgdat_list, and each node is linked to the next with the field pg data t-node next
- For UMA architectures like PC desktops, only one static pg_data_t structure, as already seen called contig_page_data is used

mem map

A scheme

One buddy allocator per each node



From kernel 2.6.17 we have an array of entries called node data[]

struct page *node mem map

Summarizing (still for 2.4 kernel)

- Architecture setup occurs via setup_arch() which will give rise to
 - ➤ a Core Map with all reseved frames
 - Free lists that looks like if no frame is available (in fact they are all reserved at this stage)
- Most of the work is done by free_area_init()
- This relies on bitmaps allocation services based on alloc_bootmem()

Releasing boot used pages to the free lists

```
static unsigned long init
free all bootmem core(pg data t *pgdat)
      for (i = 0; i < idx; i++, page++) {
            if (!test bit(i, bdata->node bootmem map)) {
      // il frame non deve restare riservato
                  count++;
                  ClearPageReserved(page);
                  set page count (page, 1);
                   free page(page);
      total += count;
      return total;
```

Allocation contexts (more generally, kernel level execution contexts)

Process context

- Allocation is caused by a system call
 - Not satisfiable → wait is experienced along the current execution trace
 - Priority based schemes

• Interrupt

- Allocation requested by an interrupt handler
 - Not satisfiable → no-wait is experienced along the current execution trace
 - Priority independent schemes

Buddy-system API

- After booting, the memory management system can be accessed via proper APIs, which drive operations on the aforementioned data structures
- The prototypes are in #include nux/malloc.h>
- The very base allocation APIs are (bare minimal page aligned allocation)
 - unsigned long get_zeroed_page(int flags)
 removes a frame from the free list, sets the content to zero and returns
 the virtual address
 - unsigned long __get_free_page(int flags)
 removes a frame from the free list and returns the virtual address
 - unsigned long __get_free_pages(int flags, unsigned long order)
 - removes a block of contiguous frames with given order from the free list and returns the virtual address of the first frame

- void free_page (unsigned long addr)
 puts a frame into the free list again, having a given initial virtual
 address
- ➤ void free_pages (unsigned long addr, unsigned long order) puts a block of frames of given order into the free list again Note!!!!!! Wrong order gives rise to kernel corruption

flags: used contexts

GFP_ATOMIC the call cannot lead to sleep (this is for interrupt contexts)

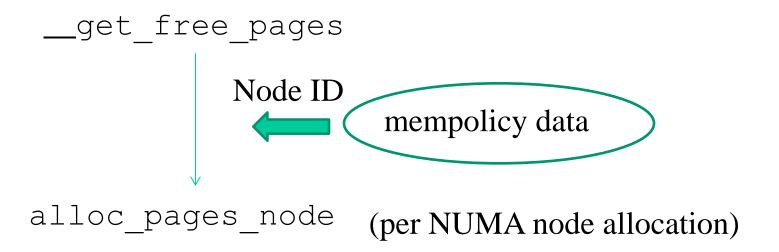
GFP_USER - GFP_BUFFER - GFP_KERNEL the call can lead to sleep

Binding actual allocation to NUMA nodes

The real core of the Linux page allocator is the function

```
struct page *alloc_pages_node(int nid, unsigned
  int flags, unsigned int order);
```

Hence the actual allocation chain is:



Mempolicy details

- Generally speaking, mempolicies determine what NUMA node needs to be involved in a specific allocation operation which is thread specific
- Starting from kernel 2.6.18, the determination of mempolicies can be configured by the application code via system calls

Synopsis

```
#include <numaif.h>
int set_mempolicy(int mode, unsigned long
    *nodemask, unsigned long maxnode);
```

sets the NUMA memory policy of the calling process, which consists of a policy mode and zero or more nodes, to the values specified by the *mode*, *nodemask* and *maxnode* arguments

The *mode* argument must specify one of MPOL_DEFAULT, MPOL_BIND, MPOL_INTERLEAVE or MPOL_PREFERRED

... another example

Synopsis

```
#include <numaif.h>
int mbind(void *addr, unsigned long len, int
mode, unsigned long *nodemask, unsigned long
maxnode, unsigned flags);
```

sets the NUMA memory policy, which consists of a policy mode and zero or more nodes, for the memory range starting with *addr* and continuing for *len* bytes. The memory policy defines from which node memory is allocated.

... finally you can also move pages around

Synopsis

```
#include <numaif.h>
long move_pages(int pid, unsigned long count,
void **pages, const int *nodes, int *status,
int flags);
```

moves the specified *pages* of the process *pid* to the memory nodes specified by *nodes*. The result of the move is reflected in *status*. The *flags* indicate constraints on the pages to be moved.

The case of frequent allocation/deallocation of a target-specific data structures

- Here we are talking about allocation/deallocation operations of data structures
 - 1. that are used for a target-specific objective (e.g. in terms of data structures to be hosted)
 - 2. which are requested/released frequently
- The problem is that getting the actual buffers (pages) from the buddy system will lead to contention and consequent synchronization costs (does not scale)
- In fact the (per NUMA node) buddy system operates with spinlock synchronized critical sections
- Kernel design copes with this issue by using pre-reserved buffers with lightweight allocation/release logic

... a classical example

- The allocation and deletion of page tables, at any level, is a very frequent operation, so it is important the operation is as quick as possible
- Hence the pages used for the page tables are cached in a number of different lists called *quicklists*
- For 3 levels paging, PGDs, PMDs and PTEs have two sets of functions each for the allocation and freeing of page tables.
- The allocation functions are pgd_alloc(), pmd_alloc() and pte_alloc(), respectively the free functions are, predictably enough, called pgd_free(), pmd_free() and pte_free()
- Broadly speaking, these APIs implement caching

Actual quicklists

- Defined in include/linux/quicklist.h
- They are implemented as a list of per-core page lists
- There is no need for synchronization
- If allocation fails, they revert to

```
__get_free_page()
```

Quicklist API and algorithm

```
static inline void *quicklist alloc(int nr, gfp t flags, ...) {
      struct quicklist *q;
      void **p = NULL;
      q = &get cpu var(quicklist)[nr];
      p = q->page;
      if (likely(p)) {
            q-page = p[0];
             p[0] = NULL;
             q->nr pages--;
      put_cpu_var(quicklist);
      if (likely(p))
             return p;
      p = (void *) get free page(flags | GFP ZERO);
      return p;
```

SLAB (or SLUB) allocator: a cache of 'small' size buffers

- The prototypes are in #include ux/malloc.h>
- The main APIs are
 - void *kmalloc(size_t size, int flags)
 allocation of contiguous memory of a given size it returns the virtual address
 - void kfree(void *obj)
 frees memory allocated via kmalloc()
- Main features:
 - Cache aligned delivery of memory chunks (performance optimal access of related data within the same chunk)
 - ➤ Fast allocation/deallocation support
- Clearly, we also can perform node-specific requests via

What about large size allocations

- Classically employed while adding large size data structures to the kernel in a stable way
- This is the case when, e.g., mounting external modules
- The main APIs are:
 - ➤ void * vmalloc(unsigned long size);
 allocates memory of a given size, which can be non-contiguous, and
 returns the virtual address (the corresponding frames are anyhow
 reserved)
 - F void vfree (void * addr)
 frees the above mentioned memory

Be careful of performance effects due to global TLB invalidations!!

Logical/Physical address translation for kernel directly mapped memory (not vmalloc one)

We can exploit the macros

__pa() __va()

In generic kernel versions

kmalloc vs vmalloc: an overall picture

- Allocation size:
 - > 128 KB for kmalloc (cache aligned)
 - ➤ 64/128 MB for vmalloc
- Physical contiguousness
 - > Yes for kmalloc
 - ➤ No for vmalloc
- Effects on TLB
 - ➤ None for kmalloc
 - ➤ Global for vmalloc (transparent to vmalloc users)