

Explicit_Solution_Example

MLP Setting

We solve the following [PDE](#):

$$\frac{\partial u}{\partial t} + (\sigma^2 u(x, t) - \frac{1}{d} - \frac{\sigma^2}{2}) \operatorname{div}_x u(x, t) + \frac{\sigma^2}{2} \Delta_x u(x, t) = 0, t \in [s, T], x \in D \in \mathbb{R}^d \quad (19)$$

whose terminal condition is given by

$$u(x, T) = g(x) := \frac{\exp\left(T + \sum_{i=1}^d x_i\right)}{1 + \exp\left(T + \sum_{i=1}^d x_i\right)} \quad (20)$$

without any boundary constraints.

Then nonlinear term is given by

$$F(u, z)(x, t) = (\sigma u - \frac{1}{d\sigma} - \frac{\sigma}{2}) \sum_i z \quad (21)$$

This PDE has an explicit solution at time t :

$$u(x, t) = \frac{\exp\left(t + \sum_{i=1}^d x_i\right)}{1 + \exp\left(t + \sum_{i=1}^d x_i\right)} \quad (22)$$

which is our target in this section.

GP Setting

Rewrite the PDE as

$$\frac{\partial u}{\partial t} + (\sigma^2 u(x, t) - \frac{1}{d} - \frac{\sigma^2}{2}) \operatorname{div}_x u(x, t) + \frac{\sigma^2}{2} \Delta_x u(x, t) = 0, t \in [s, T], x \in D \in \mathbb{R}^d \quad (23)$$

Let the nonlinear term be

$$\vec{y}_{domain} = 0_{M_\Omega} \quad (24)$$

Define operators

$$L_1(u) : u \rightarrow \Delta_x u \quad (25)$$

$$L_2(u) : u \rightarrow \frac{\partial u}{\partial t} \quad (26)$$

$$L_3(u) : u \rightarrow \operatorname{div}_x u \quad (27)$$

We define feature functions

$$\phi_j^1(u) : u \rightarrow \delta_{x_\Omega^j} \circ u, 1 \leq j \leq M_\Omega \quad (28)$$

$$\phi_i^2(u) : u \rightarrow \delta_{x_i} \circ u, 1 \leq i \leq M_{\partial\Omega} \quad (29)$$

$$\phi_j^3(u) : u \rightarrow \delta_{x_\Omega^j} \circ L_1 \circ u, 1 \leq j \leq M_\Omega \quad (30)$$

$$\phi_j^4(u) : u \rightarrow \delta_{x_\Omega^j} \circ L_2 \circ u, 1 \leq j \leq M_\Omega \quad (31)$$

$$\phi_j^5(u) : u \rightarrow \delta_{x_\Omega^j} \circ L_3 \circ u, 1 \leq j \leq M_\Omega \quad (32)$$

Denote $\vec{z}_i = \phi_{1:M_\Omega}^i(u), i \in \{1, 3, 4, 5\}$ and $\vec{z}_i = \phi_{1:M_{\partial\Omega}}^i(u), i = 2$.

Let

$$\vec{z} = \begin{pmatrix} \vec{z}_1 \\ \vec{z}_2 \\ \vec{z}_3 \\ \vec{z}_4 \\ \vec{z}_5 \end{pmatrix} \quad (33)$$

We then derive

$$F(\vec{z}) = \begin{pmatrix} \vec{z}_4 + \sigma^2 \vec{z}_1 \odot \vec{z}_5 - \left(\frac{1}{d} + \frac{\sigma^2}{2}\right) \vec{z}_5 + \frac{\sigma^2}{2} \vec{z}_3 \\ \vec{z}_2 \end{pmatrix} \quad (34)$$

Thus $Q_\Omega = 4, Q = 5$.

Feature vector ϕ have $M = 4M_{\partial\Omega} + M_\Omega$ components, which is also the size of the kernel matrix.

Taking derivatives under linearization condition

$$DF(\vec{z}_k) = \begin{pmatrix} \sigma^2 \text{diag}(\vec{z}_5) & 0 & \frac{\sigma^2}{2} I_{M_\Omega} & I_{M_\Omega} & \sigma^2 \text{diag}(\vec{z}_1) - \left(\frac{1}{d} + \frac{\sigma^2}{2}\right) I_{M_\Omega} \\ 0 & I_{M_{\partial\Omega}} & 0 & 0 & 0 \end{pmatrix}$$

Parameters

Specifically, we consider the problem for

$$d = 100, \mu = 0, \sigma = 0.25, D = [-0.5, 0.5]^{100}, s = 0, T = 0.5 \quad (35)$$

and

$$d = 250, \mu = 0, \sigma = 0.25, D = [-0.5, 0.5]^{250}, s = 0, T = 0.5 \quad (36)$$