Complicated_HJB

MLP Setting

We solve the following PDE(labeled as Eq(100) in the original paper)

$$rac{\partial u}{\partial t} - rac{1}{d} div_x u(x,t) + 2 + \Delta_x u(x,t) = 0, t \in [s,T], x \in D \subset \mathbb{R}^d$$
 (15)

whose terminal condition is given by

$$u(x,T) = g(x) := \sum_{i=1}^{d} x_i,$$
 (16)

without any boundary constraints.

The nonlinear term is given by

$$F(u,z)(x,t) = 2 (17)$$

This PDE has an explicit solution at time t

$$u(x,t) = \sum_{i=1}^{d} x_i + (T-t).$$
 (18)

which is our target in this section.

GP Setting

Rewrite the PDE as

$$\frac{\partial u}{\partial t} - \frac{1}{d}div_x u(x,t) + \Delta_x u(x,t) = -2, t \in [s,T], x \in D \subset \mathbb{R}^d$$
 (19)

Let the nonlinear term be

$$y_{domain} = -2 - \frac{\partial u}{\partial t} + \frac{1}{d}div_x u = -2$$
 (20)

Define operators

$$L(u): u \to \Delta_x u$$
 (21)

We define feature functions

$$\phi_j^1(u): u o \delta_{x_\Omega^j} \circ u, 1 \le j \le M_\Omega$$
 (22)

$$\phi_j^2(u): u o \delta_{x_{\partial\Omega}^j} \circ u, 1 \le j \le M_{\partial\Omega}$$
 (23)

$$\phi_j^3(u): u o \delta_{x_\Omega^j} \circ L \circ u, 1 \le j \le M_\Omega$$
 (24)

Denote $ec{z}_i=\phi^i_{1:M_\Omega}(u), i\in\{1,3\}$ and $ec{z}_i=\phi^i_{1:M_{\partial\Omega}}(u), i=2.$

Let

$$ec{z} = egin{pmatrix} ec{z}_1 \ ec{z}_2 \ ec{z}_3 \end{pmatrix}$$
 (25)

We then derive

$$F(\vec{z}) = \begin{pmatrix} \vec{z}_3 \\ \vec{z}_2 \end{pmatrix} \tag{26}$$

Thus $Q_{\Omega}=2, Q=3$.

Feature vector ϕ have $M=M_\Omega+M_{\partial\Omega}+M_\Omega$ components, which is also the size of the kernel matrix.

Taking derivatives under linearization condition

$$DF(ec{z}_k) = egin{pmatrix} 0 & 0 & I_{M_\Omega} \ 0 & I_{M_{\partial\Omega}} & 0 \end{pmatrix}$$

Parameters

Specifically, we consider the problem for

$$d = 100, \mu = -1/d, \sigma = \sqrt{2}, D = [-0.5, 0.5]^{100}, s = 0, T = 0.5$$
 (27)

and

$$d = 250, \mu = -1/d, \sigma = \sqrt{2}, D = [-0.5, 0.5]^{250}, s = 0, T = 0.5$$
 (28)