# Approximate Leave-One-Out with kernel SVM

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### 1 C-Support Vector Classification

Let K denote a positive-definite kernel matrix (hence invertible), with  $K_{i,j} = K(x_i, x_j)$ . The objective of a kernel SVC can be expressed in the "loss + penalty" variational form:

$$\min_{\rho,\alpha} \sum_{j=1}^{n} \max \left[ 0, 1 - y_j h(x_j) \right] + \frac{\lambda}{2} \alpha^{\top} K \alpha, \qquad h(x_j) = K_{\cdot,j}^{\top} \alpha + \rho.$$
 (1)

For simplicity we ignore the offset  $\rho$  for now. Let S and V be the smooth set and the set of singularities, respectively. For the j-th observation,  $j \in S$ , we have

$$\dot{\ell}(\boldsymbol{K}_{\cdot,j}^{\top}\boldsymbol{\alpha}) = -y_j \cdot \mathbf{1}\{y_j \boldsymbol{K}_{\cdot,j}^{\top}\boldsymbol{\alpha} < 1\}, \qquad \ddot{\ell}(\boldsymbol{K}_{\cdot,j}^{\top}\boldsymbol{\alpha}) = 0.$$

Additionally,

$$\nabla R(\alpha) = \lambda K \alpha, \qquad \nabla^2 R(\alpha) = \lambda K.$$

Substitute corresponding terms in Thm. 4.1, we deduce the ALO formula for kernel SVC:

$$\boldsymbol{K}_{\cdot,i}^{\top} \tilde{\boldsymbol{\alpha}}^{\setminus i} = \boldsymbol{K}_{\cdot,i}^{\top} \hat{\boldsymbol{\alpha}} + a_i g_{\ell,i},$$

where

$$a_{i} = \begin{cases} \frac{1}{\lambda} \boldsymbol{K}_{\cdot,i}^{\top} \left[ \boldsymbol{K}^{-1} - \boldsymbol{K}^{-1} \boldsymbol{K}_{\cdot,V} \left( \boldsymbol{K}_{\cdot,V}^{\top} \boldsymbol{K}^{-1} \boldsymbol{K}_{\cdot,V} \right)^{-1} \boldsymbol{K}_{\cdot,V}^{\top} \boldsymbol{K}^{-1} \right] \boldsymbol{K}_{\cdot,i} & i \in S, \\ \left[ \lambda \left( \boldsymbol{K}_{\cdot,V}^{\top} \boldsymbol{K}^{-1} \boldsymbol{K}_{\cdot,V} \right)_{ii}^{-1} \right]^{-1} & i \in V, \end{cases}$$

and

$$g_{\ell,S} = -y_S \odot \mathbf{1} \left\{ y_S \boldsymbol{K}_{\cdot,S}^{\top} \boldsymbol{\alpha} < 1 \right\}, \qquad g_{\ell,V} = \left( \boldsymbol{K}_{\cdot,V}^{\top} \boldsymbol{K}_{\cdot,V} \right)^{-1} \boldsymbol{K}_{\cdot,V}^{\top} \left[ \sum_{j \in S: y_j \boldsymbol{K}_{\cdot,j}^{\top} \boldsymbol{\alpha} < 1} y_j \boldsymbol{K}_{\cdot,j} - \lambda \boldsymbol{K} \boldsymbol{\alpha} \right].$$

## 2 $\varepsilon$ -Support Vector Regression

The  $\varepsilon$ -SVR is associated with the  $\varepsilon$ -insensitive loss function. Its objective function can be written as:

$$\min_{\rho,\alpha} \sum_{j=1}^{n} \max \left[ 0, |y_j - h(x_j)| - \varepsilon \right] + \frac{\lambda}{2} \alpha^{\top} K \alpha, \qquad h(x_j) = K_{\cdot,j}^{\top} \alpha + \rho.$$
 (2)

So for the *j*-th observation,  $j \in S$ , we have

$$\dot{\ell}(\boldsymbol{K}_{\cdot,j}^{\top}\boldsymbol{\alpha}) = -\operatorname{sgn}\left(\boldsymbol{K}_{\cdot,j}^{\top}\boldsymbol{\alpha}\right) \cdot \mathbf{1} \left\{ \left| y_j - \boldsymbol{K}_{\cdot,j}^{\top}\boldsymbol{\alpha} \right| \ge \varepsilon \right\}, \qquad \ddot{\ell}(\boldsymbol{K}_{\cdot,j}^{\top}\boldsymbol{\alpha}) = 0.$$

Our ALO recipe will then be exactly the same as in C-SVC, except

$$g_{\ell,S} = -\operatorname{sgn}\left(\boldsymbol{K}_{\cdot,S}^{\top}\boldsymbol{\alpha}\right) \odot \mathbf{1}\left\{\left|y_{j} - \boldsymbol{K}_{\cdot,S}^{\top}\boldsymbol{\alpha}\right| \geq \varepsilon\right\},$$

and

$$g_{\ell,V} = \left(\boldsymbol{K}_{\cdot,V}^{\top} \boldsymbol{K}_{\cdot,V}\right)^{-1} \boldsymbol{K}_{\cdot,V}^{\top} \left[ \sum_{j \in S: \left| y_{j} - \boldsymbol{K}_{\cdot,j}^{\top} \boldsymbol{\alpha} \right| \geq \varepsilon} \operatorname{sgn} \left(\boldsymbol{K}_{\cdot,j}^{\top} \boldsymbol{\alpha}\right) \boldsymbol{K}_{\cdot,j} - \lambda \boldsymbol{K} \boldsymbol{\alpha} \right].$$

### 3 $\nu$ -SVC and $\nu$ -SVR

 $\nu$ -SVC and  $\nu$ -SVR are introduced in [Sch+00], with  $\nu \in (0,1]$  a new parameter that can control the number of support vectors. Notably,  $\nu$  replaces C in C-SVC and  $\varepsilon$  in  $\varepsilon$ -SVR, and in the latter case  $\varepsilon$  itself becomes an optimization argument.

Because of the following equivalencies, there is no need to figure out the variational problem in order to derive ALO for  $\nu$ -SVC and  $\nu$ -SVR:

- Let  $\alpha^*$  be the dual solution of  $\nu$ -SVC with parameters  $(C, \nu)$ , then  $\alpha^*/\rho^*$  is an optimal solution of C-SVC with  $C = 1/(n\rho^*)$ . See [CL01].
- Let  $\alpha^*$  be the dual solution of  $\nu$ -SVR with parameters  $(C, \nu)$ , then  $\alpha^*$  is also the solution of  $\varepsilon$ -SVR with parameters  $(C/n, \varepsilon^*)$ . See [CL02].

Here  $\rho^*$  and  $\varepsilon^*$  are the corresponding primal solutions, and can be worked out quickly from  $\alpha^*$  through equations derived from KKT conditions. See [CL11, Section 4.2].

#### 4 Multiclass-classifier

To handle the multinomial classification, LIBSVM adopts the one-versus-one strategy: for a dataset with  $y \in \mathcal{S}$ ,  $|\mathcal{S}| = K$ , LIBSVM will train K(K-1)/2 classifiers  $\hat{f}_{(u,v)}(x)$ , one for each 2-combination (u,v) of  $\mathcal{S}$ . The prediction for a new observation  $x_{\text{new}}$  is then obtained through voting:  $\hat{y}_{\text{new}} = \text{mode}\{\hat{f}_{(u,v)}(x_{\text{new}})\}$ , and the label with the lowest index will be chosen in case of ties.

Note that for a specific pair (u', v'), the leave-i-out prediction  $f_{(u',v')}^{\setminus i}(x_j)$  is exactly the full-data prediction  $f_{(u',v')}(x_j)$  when  $y_i$  is neither u' nor v', for  $x_i$  does not contribute to the training of

 $f_{(u',v')}(\cdot)$  in anyway. Therefore, to obtain the multiclass ALO prediction  $\tilde{y}_j^{\setminus i}$ , we first construct all K(K-1)/2 full-data predictions, then replace the K-1 ones whose training are affected by  $y_i$  with the corresponding binary ALO predictions, and finally ensemble the result through popular voting.

### 5 Computation

To compute ALO for SVM, we must perform a variety of operations with the kernel matrix  $K \in \mathbb{R}^{n \times n}$ . In practice n can often be quite large, therefore, naïvely implement the ALO formula will result in severe loss of efficiency. This issue can be, however, alleviated by exploiting the symmetry of K: consider the Cholesky decomposition  $K = LL^{\top}$ , then for an arbitrary index set  $E \subseteq \{1, \ldots, n\}$ , we have

$$\boldsymbol{L}^{-1}\boldsymbol{K}_{\cdot,E} = \boldsymbol{L}^{-1}\boldsymbol{L}\boldsymbol{L}_{E,\cdot}^{\top} = \boldsymbol{L}_{E,\cdot}^{\top}.$$

By further considering the thin QR factorization  $L_{V_r}^{\top} = Q_V R_V$ , where  $Q_V$  semi-orthogonal and  $R_V$  upper-triangular, we may expressed  $a_s$ ,  $s \in S$ , as a difference of two quadratic form:

$$\lambda a_{s} = K_{,s}^{\top} K^{-1} K_{,s} - K_{,s}^{\top} K^{-1} K_{,,V} \left( K_{,,V}^{\top} K^{-1} K_{,,V} \right)^{-1} K_{,V}^{\top} K^{-1} K_{,s}$$

$$= K_{,s}^{\top} (L L^{\top})^{-1} K_{,s} - K_{,s}^{\top} (L L^{\top})^{-1} K_{,,V} \left( K_{,,V}^{\top} (L L^{\top})^{-1} K_{,,V} \right)^{-1} K_{,,V}^{\top} (L L^{\top})^{-1} K_{,s}$$

$$= (L^{-1} K_{,s})^{\top} L^{-1} K_{,s} - (L^{-1} K_{,s})^{\top} (L^{-1} K_{,,V}) \left[ (L^{-1} K_{,,V})^{\top} (L^{-1} K_{,,V}) \right]^{-1} (L^{-1} K_{,,V})^{\top} (L^{-1} K_{,s})$$

$$= L_{s,\cdot} L_{s,\cdot}^{\top} - L_{s,\cdot} L_{V,\cdot}^{\top} \left( L_{V,\cdot} L_{V,\cdot}^{\top} \right)^{-1} L_{V,\cdot} L_{s,\cdot}^{\top}$$

$$= L_{s,\cdot} L_{s,\cdot}^{\top} - (Q_{V}^{\top} L_{s,\cdot})^{\top} (Q_{V}^{\top} L_{s,\cdot}).$$

Similarly,  $a_v$  with  $v \in V$  can be evaluated through the inner product of two vectors:

$$(\lambda a_v)^{-1} = \left(\boldsymbol{L}_{V,\cdot} \boldsymbol{L}_{V,\cdot}^{\top}\right)_{v,v}^{-1} = \left(\boldsymbol{R}_{V}^{\top} \boldsymbol{Q}_{V}^{\top} \boldsymbol{Q}_{V} \boldsymbol{R}_{V}\right)_{v,v}^{-1} = \boldsymbol{R}_{v,\cdot}^{-1} \boldsymbol{R}_{\cdot,v}^{-1}.$$

As a result, with L, and thus  $L_{S,\cdot}$ ,  $L_{V,\cdot}$  computed beforehand, we avoided direct multiplication of large matrices and reduced computational costs.

#### References

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