PUC-Rio ACM-ICPC Reference

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1 Combinatória

1.1 Somatórios

```
\begin{array}{l} \sum_{k=0}^{n} k = n(n+1)/2 \\ \sum_{k=0}^{n} k^2 = n(n+1)(2n+1)/6 \\ \sum_{k=0}^{n} k^3 = n^2(n+1)^2/4 \\ \sum_{k=0}^{n} k^4 = (6n^5 + 15n^4 + 10n^3 - n)/30 \end{array}
```

1.2 Binômio de Newton

Total de multisets de tamanho k a partir de n elems: $\binom{n+k-1}{k}$ Total de n-tuplas com elementos não negativos com soma = s: $\binom{s+n-1}{n-1}$ Total de n-tuplas com elementos positivos com soma = s: $\binom{s-1}{n-1}$ Numero de caminhos de lattice restritos de (0,0)-(a,b): $\binom{a+b}{n}$

1.3 Numeros de Catalão

 $C_n=1/n+1*\binom{2n}{n}, C_0=1, C_n=\sum_{i=0}^{n-1}C_iC_{n-1-i}, C_{n+1}=C_n\frac{4n+2}{n+2}$ C_n representa: numero de sequencias válidas com n pares de parenteses triangulações de um (n+2)-gono

2 Template

```
#include <bits/stdc++.h>
using namespace std;
#define INF 0x3F3F3F3F
#define INFLL 0x3F3F3F3F3F3F3F3FLL
#define pb push_back
#define mp make_pair
#define fi first
#define se second
#define sz(x) int((x).size())
#define all(x) (x).begin(), (x).end()
#define contOnes __builtin_popcountl
#define logLow(X) (X <= 0 ? 0 : 31 - _builtin_clz(X))
#define logUpper(X) (X <= 1 ? 0 : 32 - __builtin_clz(X-1))</pre>
#define pow2(X) ((X)*(X))
#define watch(x) cout << (#x) << " is " << (x) << endl
#define mod(x, m) ((((x) % (m)) + (m)) % (m))
#define max3(a, b, c) max(a, max(b, c))
#define min3(a, b, c) min(a, min(b, c))
#define unico(x) x.erase(unique(all(x)), (x).end())
typedef long long 11;
typedef unsigned long long ull;
typedef pair<int,int> ii;
typedef pair<int,ii> iii;
typedef vector<int> vi;
typedef vector<vi> vvi;
typedef vector<ii> vii;
typedef vector<vii> vvii;
typedef vector<iii> viii;
typedef vector<ll> vll;
typedef vector<double> vd;
typedef vector<vd> vvd;
const double inf = 1.0/0.0;
const double pi = 2 * acos(0.0);
// Retorna -1 se a < b, 0 se a = b e 1 se a > b.
int cmp_double(double a, double b = 0, double eps = 1e-9) {
 return a + eps > b ? b + eps > a ? 0 : 1 : -1;
```

```
int main() {
  ios_base::sync_with_stdio(false);
  int n = numeric_limits<int>::max();
  return 0;
}
```

3 Ad-Hoc

3.1 Casamento estável $O(n^2)$

```
vi stable_marriage(vvi& men, vvi& women)
 int n = sz(men);
 vi ans(n, -1), prop(n, 0), match(n, -1);
 queue<int> q;
 for(int i = 0; i < n; ++i)</pre>
   q.push(i);
 while(!q.empty()){
   int m = q.front(), w = men[m][prop[m]++];
   if(match[w] == -1){
     ans[m] = w;
     match[w] = m:
     q.pop();
   } else{
     int m2 = match[w], mfirst = 0;
     for(int i = 0; i < n && women[w][i] != m2; ++i){</pre>
       if(women[w][i] == m){
         mfirst = 1;
         break;
     if(mfirst){
       q.pop();
       ans[m] = w;
       match[w] = m;
       ans[m2] = -1;
       q.push(m2);
   }
 return ans;
```

3.2 Maioria área em um histograma O(n)

```
ll maxAreaHist(vll& v){
    ll maxArea = 0, area;
    v.pb(0);
    int n = sz(v), top;
    stack<int> st;
    for(int i = 0; i < n; ++i){
        while(!st.empty() && v[i] < v[st.top()]){
            top = st.top(); st.pop();
            if(st.empty()) area = v[top]*i;
            else area = v[top] * (i - st.top() - 1);
            maxArea = max(maxArea, area);
    }
    st.push(i);
}
v.pop_back();
return maxArea;
}</pre>
```

3.3 Algoritmo de MoO(sqrt(n) * n)

```
/* Responde quantos elementos no intervalo [1, r]
   Aparecem pelo menos duas vezes */
struct Query {
   int 1, r, i;
} query[MAXQ];
int answer:
int cnt[MAXN], v[MAXN], ans[MAXQ];
void add(int idx) {
   cnt[v[idx]]++:
   if (cnt[v[idx]] == 2)
       answer += 2;
   else if (cnt[v[idx]] > 2)
       answer++;
void remove(int idx) {
   cnt[v[idx]]--;
   if (cnt[v[idx]] == 1)
       answer -= 2;
```

```
else if (cnt[v[idx]] > 1)
       answer--;
}
int main() {
    sort(query, query+q, [] (Query a, Query b) {
       if (a.1/SQRTN != b.1/SQRTN)
           return a.l < b.l;</pre>
       return a.r < b.r;</pre>
   });
    for (int i = 0, curl = 0, curr = -1; i < q; i++) {
       while (curl > query[i].1)
           add(--curl);
       while (curr < query[i].r)</pre>
           add(++curr);
       while (curl < query[i].1)</pre>
           remove(curl++);
       while (curr > query[i].r)
           remove(curr--);
       ans[query[i].i] = answer;
    }
```

4 Estruturas de Dados

4.1 BIT < O(log N), O(log N) >

```
struct BIT {
   int n;
   vi bit;
   BIT(int _n) : n(_n+1) {
      bit.resize(n+1, 0);
   }
   void update(int x, int val) {
      x++;
      for (; x <= n; x += x & -x)
           bit[x] += val;
   }
   int query(int x) {
      x++;
      int ret = 0;
      for (; x > 0; x -= x & -x)
```

```
ret += bit[x];
    return ret;
}
int query(int l, int r) {
    return query(r)-query(1-1);
}
```

4.2 BIT-2D

```
int bit[M][M], n;
int sum( int x, int y ){
   int ret = 0;
   while( x > 0 ){
      int yy = y; while( yy > 0 ) ret += bit[x][yy], yy -= yy & -yy;
      x -= (x & -x);
   }
   return ret;
}

void update(int x , int y , int val){
   int y1;
   while (x <= n){
      y1 = y;
      while (y1 <= n){ bit[x][y1] += val; y1 += (y1 & -y1); }
      x += (x & -x);
   }
}</pre>
```

4.3 Segment Tree < O(n), O(logN), O(logN)) >

```
#define LC 2*node+1
#define RC 2*node+2
#define REC int node = 0, int L = 0, int R = -1
template <typename T>
struct segtree {
    T op(const T& a, const T& b) {
        // This is THE function you want to change.
        return a+b;
    }
    int N;
    vector<T> tree;
```

```
segtree(int _N) : N(_N) {
       int e = 32 - __builtin_clz(N-1);
       if (N == 1) e = 0;
       N = 1 << e;
       tree.resize(1<<(e+1));
   }
   // Vector to be in the leaves
   void setup(vector<T>& V, REC) {
       if (R == -1) R = N;
       if (L >= sz(V)) return;
       if (R - L == 1) {
           tree[node] = V[L];
           return;
       int m = (L + R)/2;
       setup(V, LC, L, m);
       setup(V, RC, m, R);
       tree[node] = op(tree[LC], tree[RC]);
   }
   // Does "V[i] = nv"
   T update(int i, const T& nv, REC) {
       if (R == -1) R = N;
       if (i < L || i >= R) return tree[node];
       if (R - L == 1) return tree[node] = nv;
       int m = (L + R)/2;
       return tree[node] = op( update(i, nv, LC, L, m),
           update(i, nv, RC, m, R));
   }
   // queries the CLOSED interval [i,j]
   T query(int i, int j) {
       return _query(i, j+1);
   }
   T _query(int i, int j, REC) {
       if (R == -1) R = N:
       if (i <= L && R <= j) return tree[node];</pre>
       int m = (L + R)/2;
       if (i >= m) return _query(i, j, RC, m, R);
       else if (j <= m) return _query(i, j, LC, L, m);</pre>
       return op(_query(i, j, LC, L, m), _query(i, j, RC, m, R));
   }
};
#undef LC
#undef RC
#undef REC
```

4.4 RMQ-DP < O(nLogn), O(1) >

```
#define better(a,b) A[a]<A[b]?(a):(b)
int make_dp(int n) { // N log N
    for(int i = 0; i < n; ++i) H[i][0]=i;
    for(int l=0,k; (k=1<<1) < n; l++) for(int i=0;i+k<n;i++)
        H[i][l+1] = better(H[i][l], H[i+k][l]);
}
int query_dp(int a, int b) {
    int l = __lg(b-a);
    return better(H[a][l], H[b-(1<<l)+1][l]);
}</pre>
```

4.5 Segment Tree com Lazy Propagation < O(n), O(logN), O(logN)) >

```
#define LC 2*node+1
#define RC 2*node+2
#define REC int node = 0, int L = 0, int R = -1
template <typename T, typename T2>
struct segtree_lazy {
   T op(const T& a, const T& b) {
       // This is THE function you want to change.
       return a + b;
   void recompute(int node, int L, int R, const T2& upd) {
       // Change this also. This is an example for the pirate.
       if (!islazy[node]) lazy[node] = 0;
       islazv[node] = true;
       if (upd == 1) { // 1 means flip
          lazv[node] ^= 1;
          tree[node] = (R - L) - tree[node];
       else if (upd != 0) { // 2 means set to 0, 3 means set to 1
          lazy[node] = upd;
          tree[node] = (upd - 2)*(R-L);
       }
   }
   int N;
   vector<T> tree;
   vector<T2> lazy;
   vector<bool> islazy;
```

```
segtree_lazy(int _N) : N(_N) {
   int e = 32 - __builtin_clz(N-1);
   if (N == 1) e = 0;
   N = 1 << e;
   tree.resize(1<<(e+1));
   lazy.resize(1<<(e+1));</pre>
   islazy.resize(1<<(e+1), false);</pre>
}
// Vector to be in the leaves
void setup(vector<T>& V, REC) {
   if (R == -1) R = N:
   if (L >= sz(V)) return;
   if (R - L == 1) {
       tree[node] = V[L];
       return;
   }
   int m = (L + R)/2;
   setup(V, LC, L, m);
   setup(V, RC, m, R);
   tree[node] = op(tree[LC], tree[RC]);
}
void push(int node, int L, int R) {
   if (!islazy[node]) return;
   islazy[node] = false;
   int m = (L+R)/2;
   recompute(LC, L, m, lazy[node]);
   recompute(RC, m, R, lazy[node]);
}
void update(int i, int j, const T2& upd) {
   _update(i, j+1, upd);
}
T _update(int i, int j, const T2& upd, REC) {
   if (R == -1) R = N;
   if (j <= L || i >= R) return tree[node];
   if (i <= L && R <= j) {
       recompute(node, L, R, upd);
       return tree[node];
   push(node, L, R);
   int m = (L + R)/2;
   return tree[node] = op( _update(i, j, upd, LC, L, m),
       _update(i, j, upd, RC, m, R));
}
// queries the CLOSED interval [i,j]
T query(int i, int j) {
```

```
return _query(i, j+1);
}
T _query(int i, int j, REC) {
    if (R == -1) R = N;
    if (i <= L && R <= j) return tree[node];
    push(node, L, R);
    int m = (L + R)/2;
    if (i >= m) return _query(i, j, RC, m, R);
    else if (j <= m) return _query(i, j, LC, L, m);
    return op(_query(i, j, LC, L, m), _query(i, j, RC, m, R));
}
};
#undef LC
#undef RC
#undef REC</pre>
```

4.6 Union Find

```
struct UnionFind {
   int nsize;
   vi parent, size;
   UnionFind(int n) : nsize(n) {
       size.resize(n, 1);
       parent.resize(n);
       iota(all(parent), 0);
   int unions(int u, int v) {
       if (finds(u) == finds(v))
           return 0;
       size[parent[v]] += size[parent[u]];
       parent[parent[u]] = parent[v];
       nsize--;
       return 1;
   }
   int finds(int u) {
       if (u == parent[u])
           return u:
       return parent[u] = finds(parent[u]);
   }
};
```

5 Geometria

5.1 Template

```
struct Point {
   double x, y;
   Point() {}
   Point(double x, double y) : x(x), y(y) {}
   Point operator+ (const Point &o) const { return Point(x + o.x, y +
        o.v); }
   Point operator- (const Point &o) const { return Point(x - o.x, y -
   Point operator* (const double &o) const { return Point(x * o, y * o);
   Point operator/ (const double &o) const { return Point(x / o, y / o);
   double operator* (const Point &o) const { return x * o.x + y * o.y; }
   double operator% (const Point &o) const { return x * o.y - o.x * y; }
   bool operator== (const Point &o) const {
       return cmp_double(x, o.x) == 0 && cmp_double(y, o.y) == 0;
   }
   bool operator< (const Point &o) const {</pre>
       return x != o.x ? x < o.x : y < o.y;</pre>
   }
   void read() {
       scanf("%lf %lf", &x, &y);
   }
   void print() {
       printf("(%lf,%lf)\n", x, y);
   }
};
typedef Point Vector;
double abs(Point p) {
   return sqrt(p * p);
Vector norm(Vector v) {
   return v / abs(v);
double ccw(Point p, Point q, Point r) {
   return cmp_double((q - p) % (r - p));
// angulo pqr
inline double angle(Point p, Point q, Point r) {
   Point u = p - q, v = r - q;
```

```
return atan2(u % v, u * v);
}
// retorna true se q esta no segmento [p,r]
bool between(Point p, Point q, Point r) {
   return ccw(p, q, r) == 0 && cmp_double((p - q) * (r - q)) <= 0;
}
struct Segment {
   Point p, q;
   Segment() {}
   Segment(Point p, Point q) : p(p), q(q) {}
}:
bool in_segment(Point p, Segment s) {
   double t;
   Vector v = s.q - s.p;
   if (cmp_double(v.x, 0) != 0)
       t = (p.x - s.p.x) / v.x;
   else
       t = (p.y - s.p.y) / v.y;
   return cmp_double(t, 0) >= 0 && cmp_double(t, 1) <= 0 && s.p + v * t
struct Line {
   Vector v;
   Point p;
   // implementar init() se quiser eq da reta na forma ax + by = c
   int a, b, c;
   void init() {
       a = -v.v;
       b = v.x;
       c = a * p.x + b * p.y;
       int d = abs(__gcd(a, __gcd(b, c)));
       if (d != 1)
           a /= d, b /= d, c /= d;
       if (a < 0)
           a = -a, b = -b, c = -c;
       else if (a == 0 \&\& b < 0)
           b = -b, c = -c;
   Line() {}
   Line(Point p, Point q) : v(q-p), p(p) {
       init();
   Line(Segment s) : v(s.q-s.p), p(s.p) {
       init();
```

```
Point operator() (double t) const { return p + v * t; }
   Vector normal() {
       return Vector(-v.y, v.x);
   }
};
pair<double, double> line_intersection(Line a, Line b) {
   double den = a.v % b.v;
   if (den == 0)
       return make_pair(inf, inf);
   double t = -(b.v \% (b.p - a.p)) / den;
   double s = -(a.v \% (b.p - a.p)) / den;
   return make_pair(t, s);
}
Point segment_intersection(Segment a, Segment b) {
   Line la = Line(a), lb = Line(b);
   pair<double, double> pdd = line_intersection(la, lb);
   double t = pdd.first, s = pdd.second;
   if (t == inf) {
       if (in_segment(b.p, a))
           return b.p;
       if (in_segment(b.q, a))
           return b.q;
       if (in_segment(a.p, b))
           return a.p;
       if (in_segment(a.q, b))
           return a.q;
       return Point(inf, inf);
   }
   if (cmp\_double(t, 0) < 0 \mid | cmp\_double(t, 1) > 0)
       return Point(inf, inf);
   if (cmp\_double(s, 0) < 0 \mid | cmp\_double(s, 1) > 0)
       return Point(inf, inf);
   return la(t);
}
double distPointToLine(Point p, Line 1) {
   Vector n = 1.normal();
   return (1.p - p) * n / abs(n);
}
struct Circle {
   Point p;
   double r;
   Circle() {}
   Circle(Point p, double r) : p(p), r(r) {}
```

```
};
bool in_circle(const Circle &c, const Point &p) {
   return cmp_double(abs(c.p - p), c.r) <= 0;</pre>
}
Point circumcenter(Point p, Point q, Point r) {
   Point a = p - r, b = q - r, c = Point(a*(p+r)/2, b*(q+r)/2);
   return Point(c % Point(a.y, b.y), Point(a.x, b.x) % c)/(a % b);
}
Point incenter(Point p, Point q, Point r) {
   double a = abs(r - q), b = abs(r - p), c = abs(q - p);
   return (p * a + q * b + r * c) / (a + b + c);
}
// Poligono p[]
int n;
Point p[MAX];
// area de p
double poly_area() {
   double s = 0;
   for (int i = 0; i < n; i++)</pre>
       s += p[i] \% p[(i+1) \% n];
   return abs(s/2);
}
// O(n): retorna -1 se q esta na borda, 1 se esta no interior ou 0 no
    exterior.
int in_poly(Point q) {
   double a = 0:
   for (int i = 0; i < n; i++) {</pre>
       if (between(p[i], q, p[(i+1) % n])) return -1;
       a += angle(p[i], q, p[(i+1) % n]);
   return cmp_double(a) != 0;
// O(log N): retorna 1 se q esta na borda ou no interior e O caso
    contrario.
int in_poly(Point q) {
   int 1 = 0, r = n;
   while (l+1 < r) {
```

```
int m = (1+r)/2;
if (ccw(p[m], p[0], q) == 0)
    return between(h[0], q, h[m]);
if (ccw(p[m], p[0], q) < 0) l = m;
else r = m;
}
return cmp_double(angle(p[0], q, p[1]) + angle(p[1], q, p[r]) +
    angle(p[r], q, p[0])) != 0;</pre>
```

5.2 Convex Hull O(nlogn)

```
int n, k;
Point p[MAXN], h[MAXN];
void convex_hull() {
   sort(p, p+n);
   k = 0:
   h[k++] = p[0];
   for (int i = 1; i < n; i++) {</pre>
       if (i != n-1 \&\& ccw(p[0], p[n-1], p[i]) >= 0) continue;
       while (k > 1 \&\& ccw(h[k-2], h[k-1], p[i]) \le 0) k--;
       h[k++] = p[i];
   }
   for (int i = n-2, lim = k; i >= 0; i--) {
       if (i != 0 && ccw(p[n-1], p[0], p[i]) >= 0) continue;
       while (k > lim \&\& ccw(h[k-2], h[k-1], p[i]) \le 0) k--;
       h[k++] = p[i];
   }
   k--;
```

5.3 Smallest Enclosing Circle

```
int n;
Point p[MAXN];

Circle spanning_circle() {
   random_shuffle(p, p+n);
   Circle c(Point(), -1);
   for (int i = 0; i < n; i++) if (!in_circle(c, p[i])) {</pre>
```

```
c = Circle(p[i], 0);
for (int j = 0; j < i; j++) if (!in_circle(c, p[j])) {
    c = Circle((p[i] + p[j])/2, abs(p[i] - p[j])/2);
    for (int k = 0; k < j; k++) if (!in_circle(c, p[k])) {
        Point o = circumcenter(p[i], p[j], p[k]);
        c = Circle(o, abs(o - p[k]));
    }
    }
}
return c;
}</pre>
```

5.4 Closest Pair of Points O(nlogn)

```
struct Point {
   int x, y, i;
   Point(int x = 0, int y = 0, int i = 0) : x(x), y(y), i(i) {}
   Point operator- (const Point &o) const { return Point(x - o.x, y -
   int operator* (const Point &o) const { return x * o.x + y * o.y; }
   bool operator< (const Point &o) const {</pre>
       return y != o.y ? y < o.y : x < o.x;
   void read() {
       scanf("%d %d", &x, &y);
};
double abs(const Point &p) {
   return sqrt(p * p);
int main() {
   int n:
   Point pnts[MAXN];
   set<Point> box;
   set<Point>::iterator it;
   scanf("%d", &n);
   for (int i = 0; i < n; i++) {</pre>
       pnts[i].read();
       pnts[i].i = i;
   sort(pnts, pnts+n, [] (const Point &p, const Point &g) {
```

```
return p.x != q.x ? p.x < q.x : p.y < q.y;</pre>
});
double best = inf;
int u, v;
box.insert(pnts[0]);
for (int i = 1, j = 0; i < n; i++) {
   while (j < i && pnts[i].x - pnts[j].x > best)
       box.erase(pnts[j++]);
   for (it = box.lower_bound(Point(pnts[i].x-best, pnts[i].y-best));
           it != box.end() && it->y <= pnts[i].y + best; it++) {</pre>
       double tmp = abs(pnts[i] - *it);
       if (tmp < best) {</pre>
           best = tmp;
           u = pnts[i].i, v = it->i;
       }
   }
   box.insert(pnts[i]);
}
if (u > v) swap(u,v);
printf("%d %d %.6lf\n", u, v, best);
```

5.5 Interseção de Polígonos Convexos O(|P| + |Q|)

```
// Utilizar implementacoes das funcoes abaixo, mesmo que ja definidas
    anteriormente

typedef vector<Point> Polygon;

inline int ccw(Point p, Point q, Point r) {
    return cmp_double((p - r) % (q - r));
}

bool between(Point p, Point q, Point r) {
    return ccw(p, q, r) == 0 && cmp_double((p - q) * (r - q)) <= 0;
}

// Do segments [p,q] and [r,s] have an intersection?

bool seg_intersect(Point p, Point q, Point r, Point s) {
    Point A = q - p, B = s - r, C = r - p, D = s - q;
    int a = cmp_double(A % C) + 2 * cmp_double(A % D);
    int b = cmp_double(B % C) + 2 * cmp_double(B % D);
    if (a == 3 || a == -3 || b == 3 || b == -3) return false;</pre>
```

```
if (a | | b | | p == r | | p == s | | q == r | | q == s) return true;
   int t = (p < r) + (p < s) + (q < r) + (q < s);
   return t != 0 && t != 4;
}
// Finds intersection between lines (p,q) and (r,s)
// (Warning: Divides by zero if parallel! Will return NaN or INF in this
Point line_intersect(Point p, Point q, Point r, Point s) {
   Point a = q - p, b = s - r, c = Point(p % q, r % s);
   return Point(Point(a.x, b.x) % c, Point(a.y, b.y) % c) / (a % b);
}
int in_poly(Point p, Polygon& T) {
   double a = 0; int N = T.size();
   for (int i = 0; i < N; i++) {</pre>
       if (between(T[i], p, T[(i+1) % N])) return -1;
       a += angle(T[i], p, T[(i+1) % N]);
   return cmp_double(a) != 0;
}
Polygon poly_intersect(Polygon& P, Polygon& Q) {
   int m = Q.size(), n = P.size();
   if (m == 0 || n == 0) return Polygon();
   int a = 0, b = 0, aa = 0, ba = 0, inflag = 0;
   Polvgon R:
   while ((aa < n || ba < m) && aa < 2*n && ba < 2*m) {
       Point p1 = P[a], p2 = P[(a+1) \% n], q1 = Q[b], q2 = Q[(b+1) \% m];
       Point A = p2 - p1, B = q2 - q1;
       int cross = cmp_double(A % B), ha = ccw(p2, q2, p1), hb = ccw(q2,
       if (cross == 0 \&\& ccw(p1, q1, p2) == 0 \&\& cmp_double(A * B) < 0) {
           if (between(p1, q1, p2)) R.push_back(q1);
           if (between(p1, q2, p2)) R.push_back(q2);
           if (between(q1, p1, q2)) R.push_back(p1);
           if (between(q1, p2, q2)) R.push_back(p2);
           if (R.size() < 2) return Polygon();</pre>
           inflag = 1; break;
       } else if (cross != 0 && seg_intersect(p1, p2, q1, q2)) {
           if (inflag == 0) aa = ba = 0;
           R.push_back(line_intersect(p1, p2, q1, q2));
           inflag = (hb > 0) ? 1 : -1;
       if (cross == 0 && hb < 0 && ha < 0) return R;
```

```
bool t = cross == 0 && hb == 0 && ha == 0;
       if (t ? (inflag == 1) : (cross >= 0) ? (ha <= 0) : (hb > 0)) {
           if (inflag == -1) R.push_back(q2);
           ba++; b++; b %= m;
       } else {
           if (inflag == 1) R.push_back(p2);
           aa++; a++; a %= n;
       }
   }
   if (inflag == 0) {
       if (in_poly(P[0], Q)) return P;
       if (in_poly(Q[0], P)) return Q;
   }
   unico(R);
   if (R.size() > 1 && R.front() == R.back()) R.pop_back();
   return R:
}
int main(int argc, char const *argv[]) {
   int n, m;
   scanf("%d %d", &n, &m);
   Polygon P(n), Q(m);
   for (int i = 0; i < n; i++)</pre>
       P[i].read():
   for (int i = 0; i < m; i++)</pre>
       Q[i].read();
   Polygon R = poly_intersect(P, Q);
   for (auto &x: R) x.print();
   return 0;
```

5.6 Retângulos

```
struct Rect {
    // Ponto superior esquerdo.
    int x1, y1;
    // Ponto inferior direito.
    int x2, y2;
    Rect() {
        x1 = y2 = -INF;
        y1 = x2 = INF;
    }
    Rect(int a, int b, int c, int d) : x1(a), y1(b), x2(c), y2(d) {}
```

```
void read() {
    scanf("%d %d %d %d", &x1, &y1, &x2, &y2);
}
void print() {
    printf("%d %d %d %d\n", x1, y1, x2, y2);
}
Rect intersection(Rect a) {
    Rect intersect = *this;
    if (a.x1 > intersect.x1) intersect.x1 = a.x1;
    if (a.y1 < intersect.y1) intersect.y1 = a.y1;
    if (a.x2 < intersect.x2) intersect.x2 = a.x2;
    if (a.y2 > intersect.y2) intersect.y2 = a.y2;
    return intersect;
}
};
```

6 Grafos

6.1 Dijkstra O(ElogV)

```
/* Entrada: Grafo g e vertice fonte s
   Saida: Dijktra: vetor d[] com menor distancia de s ate todo v */
vi dijkstra(vvii& g, int s) {
   // comentar linha abaixo se ja tiver o tamanho n global
   int n = sz(g);
   set<ii> h;
   vi d(n, INF), vis(n, 0);
   d[s] = 0;
   vis[s] = 1;
   h.insert(mp(0, s));
   while (!h.empty()) {
       int u = h.begin()->se;
       h.erase(h.begin());
       vis[u] = 1;
       for (auto& x: g[u]) {
           int v = x.fi, w = x.se;
           if (!vis[v] \text{ and } d[u] + w < d[v]) {
              h.erase(mp(d[v], v));
              d[v] = d[u] + w;
              h.insert(mp(d[v], v));
          }
```

```
}
return d;
}
```

6.2 Kruskal O(ElogV)

```
// Vertices de 0 a n-1
int kruskal(viii &edges, int n) {
    sort(edges.begin(), edges.end());

    UnionFind ds(n);

    int cost = 0;
    for (int i = 0; i < sz(edges); i++)
         cost += edges[i].fi * ds.unions(edges[i].se.fi, edges[i].se.se);

    return cost;
}</pre>
```

6.3 TarjanO(V+E)

```
int n, m;
vector<int> g[MAX];
int lbl[MAX], low[MAX], idx, cnt_scc;
stack<int> st;
bool inSt[MAX];
void dfs(int u) {
   lbl[u] = low[u] = idx++;
   st.push(u);
   inSt[u] = 1;
   for (int i = 0; i < g[u].size(); i++) {</pre>
       int v = g[u][i];
       if (lbl[v] == -1) {
           dfs(v);
           low[u] = min(low[u], low[v]);
       } else if (inSt[v]) {
           low[u] = min(low[u], lbl[v]);
   }
```

```
if (low[u] == lbl[u]) {
       printf("%d -> ", ++cnt_scc);
       int v:
       do {
           v = st.top();
           st.pop();
           inSt[v] = 0;
           printf("%d; ", v);
       } while (v != u);
       putchar('\n');
   }
}
void tarjan() {
   for (int i = 1; i <= n; i++) {</pre>
       lbl[i] = -1;
       inSt[i] = 0:
   idx = cnt_scc = 0;
   for (int i = 1: i <= n: i++)
       if (lbl[i] == -1)
           dfs(i);
```

6.4 Articulações O(V + E)

```
int n, m;
vector<int> g[MAXN];//lista de adjacencia, notacao horrorosa
int lbl[MAXN], low[MAXN], parent[MAXN], idx;
bool art[MAXN], has_art;
void dfs(int u) {
   int cnt = 0;
   lbl[u] = low[u] = idx++;
   for (int i = 0; i < g[u].size(); i++) {</pre>
       int v = g[u][i];
       if (lbl[v] == -1) {
          parent[v] = u;
          dfs(v);
          low[u] = min(low[u], low[v]);
          if (low[v] >= lbl[u])
              cnt++:
       } else if (v != parent[u]) {
          low[u] = min(low[u], lbl[v]);
```

```
}
    }
    if (cnt > 1 || (lbl[u] != 0 && cnt > 0)) {
       art[u] = 1;
       has_art = 1;
    }
}
void articulation() {
    for (int i = 1; i <= n; i++) {</pre>
       lbl[i] = -1;
       art[i] = 0;
   }
    for (int i = 1; i <= n; i++) {</pre>
       if (lbl[i] == -1) {
           idx = 0;
           parent[i] = i;
           dfs(i);
       }
   }
```

6.5 Pontes O(V + E)

```
int n, m;
vector<int> g[MAXN]; // lista de adjacencia, notacao horrorosa
int lbl[MAXN], low[MAXN], parent[MAXN], idx;
bool has_bridge;
void dfs(int u) {
   lbl[u] = low[u] = idx++;
   bool parent_found = 0;
   for (int i = 0; i < g[u].size(); i++) {</pre>
       int v = g[u][i];
       if (lbl[v] == -1) {
          parent[v] = u;
          dfs(v);
          low[u] = min(low[u], low[v]);
          if (low[v] == lbl[v]) {
              printf("%d -> %d\n", u, v);
              has_bridge = 1;
          }
```

```
} else if (!parent_found && v == parent[u]) {
           parent_found = 1;
       } else {
           low[u] = min(low[u], lbl[v]);
       }
    }
}
void bridge() {
   for (int i = 1; i <= n; i++)</pre>
       lbl[i] = -1:
    for (int i = 1; i <= n; i++) {</pre>
       if (lbl[i] == -1) {
           idx = 0;
           parent[i] = i;
           dfs(i);
       }
    }
}
```

6.6 Lowest Common Ancestor < O(VlogV), O(logV) >

```
int n, m, u, v, w;
int anc[MAXN][LOGMAXN], dad[MAXN], lvl[MAXN], dist[MAXN];
vii g[MAXN];
void dfs(int u) {
    for (int i = 0; i < g[u].size(); i++) {</pre>
       int v = g[u][i].st, w = g[u][i].nd;
       if (v != dad[u]) {
           dad[v] = u;
           lvl[v] = lvl[u] + 1;
           dist[v] = dist[u] + w;
           dfs(v);
       }
    }
}
void pre() {
    dad[0] = lvl[0] = dist[0] = 0;
    dfs(0);
    for (int i = 0; i < n; i++)</pre>
```

```
anc[i][0] = dad[i];
    for (int j = 1; 1<<j < n; j++)
        for (int i = 0; i < n; i++)</pre>
           anc[i][j] = anc[anc[i][j-1]][j-1];
}
int lca(int u, int v) {
    if (lvl[u] < lvl[v])</pre>
        swap(u, v);
    int log;
    for (log = 1; (1<<log) <= lvl[u]; log++);</pre>
    log--;
    for (int i = log; i >= 0; i--)
        if (lvl[u] - lvl[v] >= (1<<i))</pre>
           u = anc[u][i];
    if (u == v)
        return u;
    for (int i = log; i >= 0; i--)
        if (anc[u][i] != anc[v][i])
           u = anc[u][i], v = anc[v][i];
    return dad[u];
}
```

6.7 Dinic O(V + E)

```
struct Edge {
    int v, c, f, next;
    Edge() {}
    Edge(int v, int c, int f, int next) : v(v), c(c), f(f), next(next) {}
};

int n, m, head[MAXN], lvl[MAXN], src, snk, work[MAXN];
Edge e[MAXM];

void init(int _n, int _src, int _snk) {
    n = _n;
    m = 0;
    src = _src;
    snk = _snk;
    memset(head, -1, sizeof(head));
}

void addEdge(int u, int v, int c) {
```

```
e[m] = Edge(v, c, 0, head[u]);
   head[u] = m++;
   e[m] = Edge(u, 0, 0, head[v]);
   head[v] = m++;
}
bool bfs() {
   queue<int> q;
   memset(lvl, -1, n * sizeof(int));
   lvl[src] = 0;
   q.push(src);
   while (!q.empty()) {
       int u = q.front(); q.pop();
       for (int i = head[u]; i != -1; i = e[i].next) {
           if (e[i].f < e[i].c && lvl[e[i].v] == -1) {</pre>
              lvl[e[i].v] = lvl[u] + 1;
              q.push(e[i].v);
              if (e[i].v == snk)
                  return 1:
          }
       }
   }
   return 0;
}
int dfs(int u, int f) {
   if (u == snk)
       return f;
   for (int &i = work[u]; i != -1; i = e[i].next) {
       if (e[i].f < e[i].c && lvl[u] + 1 == lvl[e[i].v]) {</pre>
           int minf = dfs(e[i].v, min(f, e[i].c - e[i].f));
           if (minf > 0) {
              e[i].f += minf;
              e[i^1].f -= minf;
              return minf;
           }
       }
   return 0;
//Atencao para integer overflow
int dinic() {
   int f, ret = 0;
   while (bfs()) {
       memcpy(work, head, n * sizeof(int));
```

```
while (f = dfs(src, INF))
    ret += f;
}
return ret;
}
```

6.8 Hopcroft-Karp O(EsqrtV)

```
// Vertices em g1 de 1 a n. Vertices em g2 de n+1 a n+m.
int n, m, e;
vector<int> g1[MAXN];
int pair_g1[MAXN], pair_g2[MAXM], dist[MAXN];
bool bfs() {
   queue<int> q;
   for (int u = 1; u <= n; u++) {</pre>
       dist[u] = INF;
       if (pair_g1[u] == 0) {
           dist[u] = 0;
           q.push(u);
       }
   }
   dist[0] = INF;
   while (!q.empty()) {
       int u = q.front(); q.pop();
       for (int i = 0; i < g1[u].size(); i++) {</pre>
           int v = g1[u][i];
           if (dist[pair_g2[v]] == INF) {
               dist[pair_g2[v]] = dist[u] + 1;
               q.push(pair_g2[v]);
           }
       }
   }
   return dist[0] != INF;
bool dfs(int u) {
   if (u == 0)
       return 1;
   for (int i = 0; i < g1[u].size(); i++) {</pre>
       int v = g1[u][i];
       if (dist[pair_g2[v]] == dist[u] + 1 && dfs(pair_g2[v])) {
           pair_g1[u] = v;
           pair_g2[v] = u;
```

```
return 1;
       }
   dist[u] = INF;
   return 0;
}
int hk() {
   memset(pair_g1, 0, sizeof(pair_g1));
   memset(pair_g2, 0, sizeof(pair_g2));
   int matching = 0;
   while (bfs())
       for (int u = 1; u <= n; u++)</pre>
           if (pair_g1[u] == 0 && dfs(u))
              matching++;
   return matching;
}
int main() {
   scanf ("%d %d %d", &n, &m, &e);
   for (int i = 0, u, v; i < e; ++i) {
       scanf("%d %d", &u, &v);
       g1[u].push_back(n+v);
   printf("%d\n", hk());
   return 0;
```

6.9 Heavy-Light Decomposition $\langle O(logV), O(log^2V) \rangle$

```
// Chamar init() antes de tudo. Ler arestas e chamar addEdge() para cada
    uma delas. // Chamar hl_init() apos.

int op(int a, int b) {
    return a + b;
}

struct SegTree {
    vector<int> data, tree;
    int sz;
    SegTree(int tsz) : sz(1) {
        while (sz < tsz) sz *= 2;
        data.resize(sz);
        tree.resize(2*sz);
}</pre>
```

```
inline int left(int u) {
       return u << 1;
   }
   inline int right(int u) {
       return left(u) + 1;
   }
   void init(int u, int 1, int r) {
       if (1 == r) {
           tree[u] = data[1];
           return:
       int m = (1 + r) >> 1;
       init(left(u), 1, m);
       init(right(u), m+1, r);
       tree[u] = op(tree[left(u)], tree[right(u)]);
   }
   void init() {
       init(1, 0, sz-1);
   }
   int query(int u, int 1, int r, int a, int b) {
       if (a <= 1 && r <= b) return tree[u];</pre>
       int m = (1 + r) >> 1, ret = 0;
       if (a <= m) ret = query(left(u), 1, m, a, b);</pre>
       if (m < b) ret = op(ret, query(right(u), m+1, r, a, b));</pre>
       return ret;
   }
   int query(int a, int b) {
       return query(1, 0, sz-1, a, b);
   }
   void update(int u, int 1, int r, int pos, int val) {
       if (1 == r) {
           tree[u] = val:
           return;
       int m = (1 + r) >> 1;
       if (pos <= m) update(left(u), 1, m, pos, val);</pre>
       else update(right(u), m+1, r, pos, val);
       tree[u] = op(tree[left(u)], tree[right(u)]);
   }
   void update(int pos, int val) {
       update(1, 0, sz-1, pos, val);
   }
};
struct edge {
```

```
int u, v, w, next;
   edge() {}
   edge(int u, int v, int w, int next) : u(u), v(v), w(w), next(next) {}
};
int n, m, q, head[MAX];
edge e[2*MAX];
int dad[MAX], lvl[MAX], chd[MAX], sz[MAX], heavy[MAX];
int nump, psize[MAX], pfirst[MAX], path[MAX], offset[MAX];
vector<int> walk;
vector<SegTree> ptree;
void init() {
   m = 0:
   memset(head, -1, sizeof(head));
   memset(dad, 0, sizeof(dad));
void addEdge(int u, int v, int w, bool rev = false) {
   e[m] = edge(u, v, w, head[u]);
   head[u] = m++;
   if (!rev) addEdge(v, u, w, true);
void dfs(int u) {
   walk.push_back(u);
   sz[u] = 1:
   for (int i = head[u]: i != -1: i = e[i].next) {
       int v = e[i].v;
       if (!dad[v]) {
           dad[v] = u,lvl[v] = lvl[u] + 1, dfs(v);
           sz[u] += sz[v];
       }
   for (int i = head[u]; i != -1; i = e[i].next) {
       int v = e[i].v;
       if (dad[v] == u && 2*sz[v] >= sz[u]) {
          heavy[v] = 1;
           break;
       }
   heavy[u] = 0;
}
void hl_init() {
   walk.clear();
```

```
dad[1] = 1, lvl[1] = 0, dfs(1);
    nump = 0;
    for (int i = 0; i < n; i++) {</pre>
       int u = walk[i];
       if (!heavy[u]) {
           offset[u] = 0:
           path[u] = nump;
           pfirst[nump] = u;
           psize[nump++] = 1;
       }
       else {
           offset[u] = offset[dad[u]] + 1;
           path[u] = path[dad[u]];
           psize[path[u]]++;
    }
    ptree.clear();
    ptree.reserve(nump);
    for (int i = 0; i < nump; i++)</pre>
       ptree.push_back(SegTree(psize[i]));
   for (int i = 0; i < m; i += 2) {</pre>
       int u = e[i].u, v = e[i].v;
       if (u != dad[v]) swap(u, v);
       ptree[path[v]].data[offset[v]] = e[i].w;
    for (int i = 0; i < nump; i++)</pre>
       ptree[i].init():
}
int lca(int u, int v) {
    int fpu = pfirst[path[u]], fpv = pfirst[path[v]];
    while (fpu != fpv) {
       if (lvl[fpu] > lvl[fpv])
           u = dad[fpu], fpu = pfirst[path[u]];
       else
           v = dad[fpv], fpv = pfirst[path[v]];
    }
    return lvl[u] < lvl[v] ? u : v;</pre>
}
void update(int idx, int val) {
    int u = e[idx].u, v = e[idx].v;
    if (u != dad[v]) swap(u, v);
    ptree[path[v]].update(offset[v], val);
}
```

```
int query(int u, int v, bool up = false) {
    if (!up) {
        int w = lca(u, v);
        return op(query(u, w, true), query(v, w, true));
    }
    int ret = 0;
    int fpu = pfirst[path[u]], fpv = pfirst[path[v]];
    while (fpu != fpv) {
        ret = op(ret, ptree[path[u]].query(0, offset[u]));
        u = dad[fpu], fpu = pfirst[path[u]];
    }
    if (u != v)
        ret = op(ret, ptree[path[u]].query(offset[v]+1, offset[u]));
    return ret;
}
```

6.10 Min-Cost Max-Flow O(VE + fElogV), f = maxflow

```
struct Edge {
   int u, v, cap, flow, cost, next;
   Edge() {}
   Edge(int u, int v, int cap, int flow, int cost, int next)
   : u(u), v(v), cap(cap), flow(flow), cost(cost), next(next) {}
};
int n, m, head[MAXN], src, snk;
Edge e[MAXM];
int pi[MAXN], dist[MAXN], path[MAXN], mincap[MAXN], vis[MAXN];
void init(int _n, int _src, int _snk) {
   n = _n;
   m = 0;
   src = _src;
   snk = snk:
   memset(head, -1, sizeof(head));
void addEdge(int u, int v, int cap, int cost) {
   e[m] = Edge(u, v, cap, 0, cost, head[u]);
   head[u] = m++:
   e[m] = Edge(v, u, 0, 0, -cost, head[v]);
   head[v] = m++:
}
int bellman_ford() {
```

```
memset(pi, INF, sizeof(pi));
    pi[src] = 0;
    int flag = 1;
    for (int i = 0; flag && i < n; i++) {</pre>
       flag = 0;
       for (int j = 0; j < m; j++) {
           if (e[j].cap == e[j].flow) continue;
           if (pi[e[j].u] + e[j].cost < pi[e[j].v]) {</pre>
               pi[e[j].v] = pi[e[j].u] + e[j].cost;
               flag = 1;
           }
       }
    }
    return flag;
}
int dijkstra() {
    priority_queue<pii, vector<pii>, greater<pii> > heap;
    memset(dist, INF, sizeof(dist));
    memset(vis, 0, sizeof(vis));
    dist[src] = 0;
    mincap[src] = INF;
    heap.push(mp(0, src));
    while (!heap.empty()) {
       int u = heap.top().se;
       heap.pop();
       if (vis[u]) continue;
       vis[u] = 1:
       for (int i = head[u]; i != -1; i = e[i].next) {
           int v = e[i].v;
           if (vis[v] || e[i].flow == e[i].cap) continue;
           int w = dist[u] + e[i].cost + pi[u] - pi[v];
           if (w < dist[v]) {</pre>
               dist[v] = w;
               path[v] = i;
               mincap[v] = min(mincap[u], e[i].cap - e[i].flow);
               heap.push(mp(dist[v], v));
           }
       }
    }
    // update potencials
    for (int i = 0; i < n; i++)</pre>
       pi[i] += dist[i];
    return dist[snk] < INF;</pre>
}
```

```
pii mcmf() {
   // set potencials
   if (bellman_ford())
       return mp(-1, -1);
   int cost = 0, flow = 0;
   while (dijkstra()) {
       // augment path and update cost
       int f = mincap[snk];
       for (int v = snk; v != src; ) {
           int idx = path[v];
           e[idx].flow += f;
           e[idx^1].flow -= f;
           cost += e[idx].cost * f;
           v = e[idx].u;
       }
       flow += f;
   return mp(cost, flow);
```

7 Matemática

7.1 LCM

```
11 lcm(11 a, 11 b) {
   if (a == 0 && b == 0) return 0;
   return a / __gcd(a,b) * b;
}
```

7.2 Algoritmo Estendido de Euclides

```
typedef pair<11, ll> pll;

pll egcd(ll a, ll b) {
    ll x = 0, lastx = 1, auxx;
    ll y = 1, lasty = 0, auxy;
    while (b) {
        ll q = a / b, r = a % b;
        a = b, b = r;
        auxx = x;
    }
}
```

```
x = lastx - q*x, lastx = auxx;
auxy = y;
y = lasty - q*y, lasty = auxy;
}
return mp(lastx, lasty);
```

7.3 Resto Chines para gcd(i, j) = 1

```
struct teq {
    int r, n; // x = r (mod n)
};
int qnt;
teq eqs[MAXN];
int chinese_remainder_algorithm() {
    int beta, sum = 0, n = 1;
    for (int i = 0; i < qnt; i++)</pre>
       n *= eqs[i].n;
    for (int i = 0; i < qnt; i++) {</pre>
       beta = egcd(eqs[i].n, n/eqs[i].n).second;
       while (beta < 0)</pre>
           beta += eqs[i].n;
       sum += (eqs[i].r * beta * n/eqs[i].n) % n;
    }
    return sum;
}
```

7.4 Resto Chines Generalizado

```
struct teq {
    ll r, n; // x = r (mod n)
};

ll inv(ll x, ll n) {
    ll ret = egcd(x, n).first;
    return mod(ret, n);
}

int qnt;
```

```
teq eqs[MAX];
pair<11, 11> chines() {
    11 n = eqs[0].n, r = mod(eqs[0].r, n), auxr, d;
    for (int i = 1; i < qnt; i++) {
        d = __gcd(n, eqs[i].n);
        auxr = mod(eqs[i].r - r, eqs[i].n);
        if (auxr % d) return mp(-1, -1);
        r += auxr / d * n * inv(n/d, eqs[i].n/d);
        n *= eqs[i].n/d;
        r = mod(r, n);
    }
    return mp(r, n);
}</pre>
```

7.5 Crivo de Eratosthenes O(n * loglogn)

7.6 Fatoração

```
int nf, f[MAXN], e[MAXN];
void factor(int n) {
   nf = 0;
   for (int i = 0; n != 1 && p[i]*p[i] <= n; i++) {</pre>
```

```
if (n % p[i] == 0) {
       f[nf] = p[i];
       e[nf] = 1;
       n /= p[i];
       while (n \% p[i] == 0) {
           e[nf]++;
          n /= p[i];
       }
       nf++;
   }
}
if (n != 1) {
   f[nf] = n;
   e[nf] = 1;
   nf++;
}
```

7.7 Totiente de Euler

```
//Cuidado com integer overflow
int phi(int n) {
   int ret = 1;
   for (int i = 0; n != 1 && p[i]*p[i] <= n; i++) {</pre>
       if (n % p[i] == 0) {
          int pk = p[i];
          n /= p[i];
           while (n % p[i] == 0) {
              pk *= p[i];
              n /= p[i];
          }
           ret *= pk - pk/p[i];
       }
   }
   if (n != 1)
       ret *= n-1;
   return ret;
```

7.8 Totiente de Euler $\forall x < n - \phi(x)$

```
int phi[MAXN];
void build_phi(int n) {
   for (int i = 0; i < n; i++)
      phi[i] = i;
   for (int i = 2; i < n; i++) if (phi[i] == i)
      for (int j = i; j < n; j += i)
            phi[j] = phi[j] / i * (i-1);
}</pre>
```

7.9 Exponenciação Rápida com Módulo

```
ll power(ll b, ll e, ll mod = numeric_limits<ll>::max()) {
   if (e == 0) return 1;
   b %= mod;
   11 a = power(b, e/2, mod);
   a = (a*a) \% mod;
   if (e&1) return (a*b) % mod;
   return a;
}
ll power(ll b, ll e, ll mod = numeric_limits<ll>::max()) {
   ll ret = 1;
   b = b \% mod:
   while (e > 0) {
       if (e & 1) ret = (ret * b) % mod;
       e >>= 1;
       b = (b * b) \% mod;
   return ret;
```

7.10 Fast Fourier Transform

```
typedef complex<long double> pt;
pt tmp[1<<20];

void fft(pt *in, int sz, bool inv) {
   if (sz == 1)
      return;
   for (int i = 0, j = 0, h = sz >> 1; i < sz; i += 2, j++) {
      in[j] = in[i];
   }
}</pre>
```

```
tmp[h+j] = in[i+1];
}
for (int i = sz >> 1; i < sz; i++)</pre>
    in[i] = tmp[i];
sz >>= 1;
pt *even = in, *odd = in + sz;
fft(even, sz, inv);
fft(odd, sz, inv);
long double p = (inv ? -1 : 1) * M_PI / sz;
pt w = pt(cosl(p), sinl(p)), w_i = 1;
for (int i = 0; i < sz; i++) {</pre>
    pt conv = w_i * odd[i];
    odd[i] = even[i] - conv;
    even[i] += conv;
    w_i *= w;
}
```

7.11 Polinômios

```
struct Poly {
   int n;
   double a[MAXN];
   Poly(int n = 0): n(n) { memset(a, 0, sizeof(a)); }
   Poly(const Poly &o) : n(o.n) { memcpy(a, o.a, sizeof(a)); }
   const double& operator[] (int i) const { return a[i]; }
   double& operator[] (int i) { return a[i]; }
   double operator() (double x) const {
       double ret = 0;
       for (int i = n; i >= 0; i--)
          ret = ret * x + a[i];
       return ret;
   }
   Poly operator+ (const Poly &o) const {
       Poly ret = o;
       for (int i = 0; i <= n; i++)</pre>
          ret[i] += a[i];
       ret.n = max(n, o.n);
       return ret;
   Poly operator- (const Poly &o) const {
       Poly ret = o;
       for (int i = 0; i <= n; i++)</pre>
```

```
ret[i] -= a[i]:
       ret.n = max(n, o.n);
       return ret:
    Poly operator* (const Poly &o) const {
       Poly ret(n + o.n);
       for (int i = 0; i <= n; i++)</pre>
           for (int j = 0; j <= o.n; j++)
               ret[i+j] += a[i] * o[j];
       return ret;
    }
};
// Saida: produto p*q
Poly fastMult(const Poly &p, const Poly &q) {
    int sz = 1 << (32 - \_builtin_clz(p.n + q.n + 1));
    pt pin[sz], qin[sz];
    for (int i = 0; i < sz; i++) {</pre>
       if (i <= p.n)</pre>
           pin[i] = p[i];
       else
           pin[i] = 0;
       if (i <= q.n)</pre>
           qin[i] = q[i];
       else
           qin[i] = 0;
   fft(pin, sz, 0);
    fft(qin, sz, 0);
    for (int i = 0; i < sz; i++)</pre>
       pin[i] *= qin[i];
    fft(pin, sz, 1);
    Poly ret(p.n + q.n);
    for (int i = 0; i <= ret.n; i++)</pre>
       ret[i] = pin[i].real() / sz;
    while (ret.n > 0 \&\& cmp(ret[ret.n], 0) == 0)
       ret.n--;
    return ret;
}
// Saida: polinomio derivada de p
Poly diff(const Poly &p) {
    Poly ret(p.n-1);
    for (int i = 1; i <= p.n; i++)
       ret[i-1] = i * p[i];
```

```
return ret;
}
// Saida: quociente e resto da divisao de p por (p.x - x)
pair<Poly, double> ruffini(const Poly &p, double x) {
   if (p.n == 0)
       return make_pair(Poly(), 0);
   Poly ret(p.n-1);
   for (int i = p.n; i > 0; i--)
       ret[i-1] = ret[i] * x + p[i];
   return make_pair(ret, ret[0] * x + p[0]);
}
// Entrada: polinomio p e intervalo [lo,hi] com exatamente uma raiz
// Saida: pair::second := 0 se nao existe tal raiz, ou 1 se existe
          pair::first := raiz do polinomio dentro do intervalo [lo,hi]
pair<double, int> findRoot(const Poly &p, double lo, double hi) {
   if (cmp(p(lo), 0) == 0)
       return make_pair(lo, 1);
   if (cmp(p(hi), 0) == 0)
       return make_pair(hi, 1);
   if (cmp(p(lo), 0) == cmp(p(hi), 0))
       return make_pair(0, 0);
   if (cmp(p(lo), p(hi)) > 0)
       swap(lo, hi);
   while (cmp(lo, hi) != 0) {
       double mid = (lo + hi) / 2;
       double val = p(mid);
       if (cmp(val, 0) == 0)
          lo = hi = mid;
       else if (cmp(val, 0) < 0)
          lo = mid;
       else
          hi = mid;
   }
   return make_pair(lo, 1);
// Saida: vetor com raizes reais com suas multiplicidades em ordem
    crescente
vector<double> roots(const Poly &p) {
   vector<double> ret;
   if (p.n == 1) {
       ret.push_back(-p[0] / p[1]);
```

```
else {
    vector<double> r = roots(diff(p));
    r.push_back(-MAXX);
    r.push_back(MAXX);
    sort(r.begin(), r.end());
    for (int i = 0, j = 1; j < (int) r.size(); i++, j++) {
        pair<double, int> pr = findRoot(p, r[i], r[j]);
        if (pr.second)
            ret.push_back(pr.first);
    }
}
return ret;
}
```

7.12 Eliminação Gaussiana $O(n^3)$

```
// Entrada: Matriz aumentada do sistema Ax=b, ou seja, com o vetor b a
    direita de A
// Saida: O numero de solucoes do sistema (0, 1, INF). Se o retorno for
    1, as
// solucoes podem ser verificadas em ans.
typedef vector<double> vd;
typedef vector<vd> vvd;
int gauss(vvd a, vd &ans, double EPS = 1e-9) {
   int n = sz(a):
   int m = sz(a[0]) - 1;
   vi where (m, -1);
   for (int col = 0, row = 0; col < m && row < n; col++) {
       int sel = row;
       for (int i = row; i < n; i++)</pre>
           if (abs(a[i][col]) > abs(a[sel][col]))
              sel = i:
       if (abs(a[sel][col]) < EPS)</pre>
           continue:
       for (int i = col; i <= m; i++)</pre>
           swap(a[sel][i], a[row][i]);
       where[col] = row;
       for (int i = 0; i < n; i++)
```

```
if (i != row) {
           double c = a[i][col] / a[row][col];
           for (int j = col; j <= m; j++)</pre>
               a[i][j] -= a[row][j] * c;
       }
   row++;
ans.assign(m, 0);
for (int i = 0; i < m; i++)</pre>
   if (where[i] != -1)
       ans[i] = a[where[i]][m] / a[where[i]][i];
for (int i = 0; i < n; i++) {</pre>
   double sum = 0;
   for (int j = 0; j < m; j++)
       sum += ans[j] * a[i][j];
   if (abs(sum - a[i][m]) > EPS)
       return 0;
}
for (int i = 0; i < m; i++)</pre>
   if (where[i] == -1)
       return INF;
return 1;
```

7.13 Integração por Método de Simpson

```
double simpson(double a, double b, int n = 1e6) {
   double h = (b - a) / n;
   double s = f(a) + f(b);
   for (int i = 1; i < n; i += 2)
        s += 4 * f(a + h*i);
   for (int i = 2; i < n; i += 2)
        s += 2 * f(a + h*i);
   return s*h/3;
}</pre>
```

7.14 Exponenciação Rápida de Matrizes

```
vvd multMatrix(vvd& A, vvd& B) {
```

}

```
int n = sz(A), m = sz(A[0]), p = sz(B[0]);
    vvd ans(n, vd(p, 0.0));
    for (int i = 0; i < n; i++)</pre>
       for (int k = 0; k < m; k++)
           for (int j = 0; j < p; j++)
               ans[i][j] += A[i][k]*B[k][j];
    return ans;
}
vvd expMat(vvd& A, int e) {
    if (e == 0) {
       int n = sz(A);
       vvd ans(n, vd(n, 0));
       for (int i = 0; i < n; i++)</pre>
           ans[i][i] = 1.0;
       return ans;
    vvd x = expMat(A, e/2);
    x = multMatrix(x,x);
    if (e&1)
       x = multMatrix(x,A);
   return x;
```

8 Programação Dinâmica

8.1 Coin Change (menor qutd) O(nc)

8.2 Coin Change (total de formas) O(nc)

8.3 Knapsack Com Repetição O(nc)

8.4 Longest Common Subsequence O(nm)

```
//Entrada: strings a e b
//Saida: string com a maior subsequencia em comum entre a e b
string lcs(string a, string b) {
  int n = a.length();
  int m = b.length();
```

```
vvi dp(n+1, vi(m+1, 0));
for (int i = 1: i <= n: i++) {
   for (int j = 1; j \le m; j++) {
       if (a[i-1] == b[j-1]) dp[i][j] = dp[i-1][j-1] + 1;
       else dp[i][j] = max(dp[i-1][j], dp[i][j-1]);
   }
}
string answer = "";
int i = n;
int j = m;
while (i and j) {
   if (dp[i][j] == dp[i-1][j]) i--;
   else if (dp[i][j] == dp[i][j-1]) j--;
   else if (dp[i][j] == dp[i-1][j-1] + 1) answer.push_back(a[i-1]),
        i--, j--;
}
reverse(answer.begin(), answer.end());
return answer;
```

8.5 Longest Common Substring O(nm)

```
string lcs(string a, string b) {
   int n = a.length();
   int m = b.length();

   int maximum = 0;
   int ii = 0;
   int jj = 0;

   vvi dp(n+1, vi(m+1, 0));

   for (int i = 1; i <= n; i++) {
      for (int j = 1; j <= m; j++) {
        if (a[i-1] == b[j-1]) {
            dp[i][j] = dp[i-1][j-1] + 1;
      }
}</pre>
```

```
if (dp[i][j] > maximum) {
              maximum = dp[i][j];
              ii = i; jj = j;
          }
       } else {
          dp[i][j] = 0;
      }
   }
}
string answer = "";
while (ii and dp[ii][jj]) {
   answer.push_back(a[--ii]);
   jj--;
}
reverse(answer.begin(), answer.end());
return answer;
```

8.6 Longest Increasing Sequence O(nlogn)

```
//Saida: ans[i] := indice do i-esimo elemento da maior subsequencia
    crescente
vi find_lis(vi& v) {
   int n = sz(v), len = 0;
   vi tam(n), dad(n);
   for (int i = 0; i < n; i++) {</pre>
       int lo = 0, hi = len;
       while (lo < hi) {</pre>
           int mid = (lo+hi) / 2:
           if (v[tam[mid]] < v[i])</pre>
               lo = mid+1;
           else
               hi = mid;
       dad[i] = (lo > 0) ? tam[lo-1] : -1;
       tam[lo] = i:
       if (lo == len) len++;
   }
```

```
vi ans(len);
// se quiser a sequencia e nao apenas os indices, trocar u por v[u]
for (int u = tam[len-1], i = len-1; u != -1; u = dad[u], i--)
    ans[i] = u;
return ans;
}
```

8.7 Weighted Activity Selection O(nloqn)

```
//Entrada: vetor v[] com atividades no formato
//Saida: soma maxima dos pesos de atividades nao sobrepostas
//Obs: v□ e 1-indexado
struct Event {
   int b, e, w;
   Event () {}
   Event (int b, int e, int w) : b(b), e(e), w(w) {}
   bool operator< (const Event& o) const {</pre>
       return e != o.e ? e < o.e : b < o.b;
   }
};
int was(vector<Event>& v) {
   int n = sz(v)-1;
   sort(v.begin()+1, v.end());
   vi dp(n+1);
   dp[0] = 0;
   for (int i = 1; i <= n; i++) {
       int lo = 0, hi = i-1;
       while (lo < hi) {</pre>
           int mid = (lo + hi + 1)/2;
           if (v[mid].e > v[i].b)
              hi = mid - 1;
           else
              lo = mid;
       }
       dp[i] = max(dp[i-1], v[i].w + dp[lo]);
   return dp[n];
```

8.8 Caixeiro Viajante $O(n^22^n)$

```
// Saida: menor custo para comecar no vertice 0, fazer um tour pelos
    vertices 1...n-1 e retornar ao vertice 0.
int n;
ii p[MAX];
double pd[(1<<MAX)][MAX];</pre>
double cost(int i, int j) {
    return sqrt(pow2(p[i].st-p[j].st)+pow2(p[i].nd-p[j].nd));
}
double tsp() {
    for (int i = 0; i < (1 << n); i++)
       for (int j = 0; j < n; j++)
           pd[i][j] = inf;
    pd[0][0] = 0.0;
    for (int i = 1; i < (1 << n); i += 2) {
       for (int j = 0; j < n; j++) {
           if (i & (1<<j)) continue;</pre>
           for (int k = 0; k < n; k++)
               if (k != j and (i & (1<<k)))</pre>
                  pd[i][j] = min(pd[i][j], pd[i^(1 << k)][k] + cost(k, j));
       }
    }
    double ans = inf;
    for (int k = 0; k < n; k++)
       ans = min(ans, pd[((1<<n)-1)-(1<<k)][k] + cost(k,0));
    return ans;
}
```

9 String

9.1 Suffix Array e Longest Common Prefix O(nlogn)

```
// Usar a partir da funcao initSA(string& _str)
// sa : array de sufixos
```

```
// pos: inverso do array de sufixos, ie, pos[i] := o indice do sufixo i
// suf[i] < suf[j] se e somente se pos[i] < pos[j]</pre>
int n;
string str;
int sa[MAX], pos[MAX], cnt[MAX], nxt[MAX], bh[MAX], b2h[MAX], lcp[MAX];
void suffix_array() {
   for (int i = 0; i < n; i++)</pre>
       sa[i] = i:
   sort(sa, sa + n, [] (int a, int b) {
       return str[a] < str[b];</pre>
   });
   for (int i = 0; i < n; i++) {</pre>
       bh[i] = (i == 0 || str[sa[i]] != str[sa[i-1]]);
       b2h[i] = 0;
   for (int h = 1; h < n; h <<= 1) {
       int buckets = 0;
       for (int i = 0, j; i < n; i = j) {
           j = i + 1;
           while (j < n \&\& !bh[j])
               j++;
           nxt[i] = j;
           buckets++;
       }
       if (buckets == n)
           break;
       for (int i = 0; i < n; i = nxt[i]) {</pre>
           cnt[i] = 0;
           for (int j = i; j < nxt[i]; j++)</pre>
               pos[sa[j]] = i;
       cnt[pos[n-h]]++;
       b2h[pos[n-h]] = 1;
       for (int i = 0; i < n; i = nxt[i]) {</pre>
           for (int j = i; j < nxt[i]; j++) {</pre>
               int s = sa[j] - h;
               if (s >= 0) {
                   int head = pos[s];
                   pos[s] = head + cnt[head]++;
                   b2h[pos[s]] = 1;
           }
```

```
for (int j = i; j < nxt[i]; j++) {</pre>
               int s = sa[i] - h;
               if (s >= 0 && b2h[pos[s]]) {
                   for (int k = pos[s] + 1; !bh[k] && b2h[k]; k++)
                      b2h[k] = 0;
               }
           }
       }
       for (int i = 0; i < n; i++) {</pre>
           sa[pos[i]] = i;
           bh[i] |= b2h[i];
    }
    for (int i = 0; i < n; i++)</pre>
       pos[sa[i]] = i;
}
void getlcp() {
    lcp[0] = 0;
    for (int i = 0, h = 0; i < n; i++) {
       if (pos[i] > 0) {
           int j = sa[pos[i] - 1];
           while (i + h < n \&\& j + h < n \&\& str[i+h] == str[j+h])
               h++;
           lcp[pos[i]] = h;
           if (h > 0)
               h--:
       }
    }
}
void initSA(string& _str) {
    str = _str;
    n = sz(str);
    suffix_array();
    getlcp();
```

9.2 Aho-Corasick

```
struct Node {
   map<char, int> adj;
   int fail;
   ii match;
   int next;
```

```
void init() {
       adj.clear();
       fail = -1;
       match = mp(-1, -1);
       next = -1;
   }
   int getChild(const char &c) {
       map<char, int>::iterator it = adj.find(c);
       if (it != adj.end())
           return it->nd;
       return -1:
};
int qntNodes, qntPatts;
Node trie[MAX];
void init() {
   trie[0].init();
   qntNodes = 1;
   qntPatts = 0;
}
void addWord(const char *word) {
   int node = 0, aux = -1;
   for (int i = 0; word[i]; i++) {
       aux = trie[node].getChild(word[i]);
       if (aux == -1) {
           trie[qntNodes].init();
           aux = qntNodes++;
           trie[node].adj[word[i]] = aux;
       }
       node = aux;
   trie[node].match = mp(qntPatts++, strlen(word));
}
void build() {
   queue<int> q;
   map<char, int>::iterator it;
   trie[0].fail = -1;
   q.push(0);
   while (!q.empty()) {
       int u = q.front();
       q.pop();
       for (it = trie[u].adj.begin(); it != trie[u].adj.end(); it++) {
           int v = it->nd;
           char c = it->st;
```

```
q.push(v);
          int f = trie[u].fail;
          while (f >= 0 && trie[f].getChild(c) == -1)
              f = trie[f].fail;
          f = f \ge 0 ? trie[f].getChild(c) : 0;
          trie[v].fail = f;
          trie[v].next = trie[f].match.st >= 0 ? f : trie[f].next;
       }
   }
void search(const char *text) {
   int node = 0;
   for (int i = 0; text[i]; i++) {
       while (node >= 0 && trie[node].getChild(text[i]) == -1)
          node = trie[node].fail;
       node = node >= 0 ? trie[node].getChild(text[i]) : 0;
       int aux = node;
       while (aux >= 0) {
           if (trie[aux].match.st >= 0) {
              // do something with the match
              printf("patt: %d, pos: %d\n",
                  trie[aux].match.st,
                 i - trie[aux].match.nd + 1);
          }
          aux = trie[aux].next;
       }
   }
```

9.3 KMP O(n+m)

```
vi kmp(string& txt, string& ptt) {
   vi matches;

// Calculo do vetor auxiliar lps (longest proper prefix
   // which is also suffix).
   vi lps(ptt.size() + 1, -1);

for (int i = 1; i <= ptt.size(); i++) {
   int pos = lps[i - 1];
   while (pos != -1 and ptt[pos] != ptt[i - 1])
      pos = lps[pos];
   lps[i] = pos + 1;</pre>
```

9.4 Z algorithm O(n)

```
//Saida: Z[i] := tamanho da maior string a partir do indice i que eh um
    prefixo de str

vi z_algo(string &str) {
    int n = sz(str);
    vi Z(n, 0);
    for (int i = 1, 1 = 0, r = 0; i < n; ++i) {
        if (i <= r)
            Z[i] = min (r - i + 1, Z[i - 1]);
        while (i + Z[i] < n && str[Z[i]] == str[i + Z[i]])
            ++Z[i];
        if (Z[i] > r - i + 1)
            1 = i, r = i + Z[i] - 1;
    }
    return Z;
}
```

9.5 String Hashing

```
#define B 33

llu powB[MAX];
void init() {
   powB[0] = 1;
```

9.6 Manacher O(n)

```
char s[MAXN];
int p[2*MAXN]; // length of the palindrome centered at position (i-1)/2;
void manacher() {
    int m = 0;
    char t[2*MAXN];
   for (int i = 0; s[i]; i++) {
       t[m++] = '#';
       t[m++] = s[i];
       p[i] = 0;
    t[m++] = '#';
    int c = 0, r = 0;
   for (int i = 0; i < m; i++) {</pre>
       int i_ = 2 * c - i;
       p[i] = r > i ? min(r-i, p[i_]) : i & 1;
       while (0 \le i-p[i]-1 \&\& i+p[i]+1 \le m \&\& t[i-p[i]-1] == t[i+p[i]+1])
           p[i] += 2;
       if (i + p[i] > r) {
           c = i;
           r = i + p[i];
       }
   }
}
```