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# Stochastic System: What and Why

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— Hong Wan, Fall 2022 —

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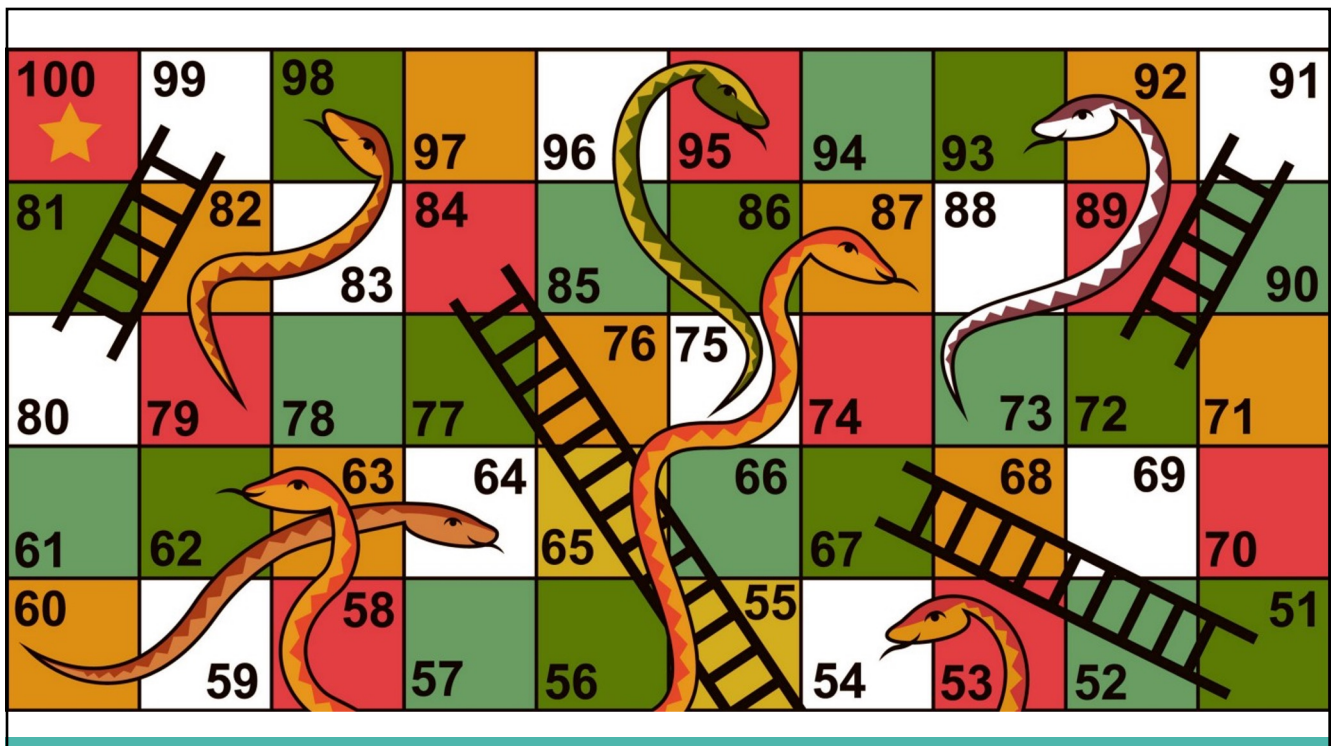
## Definition

A stochastic model represents a situation where **uncertainty** is present. In other words, it's a model for a process that has some kind of randomness.

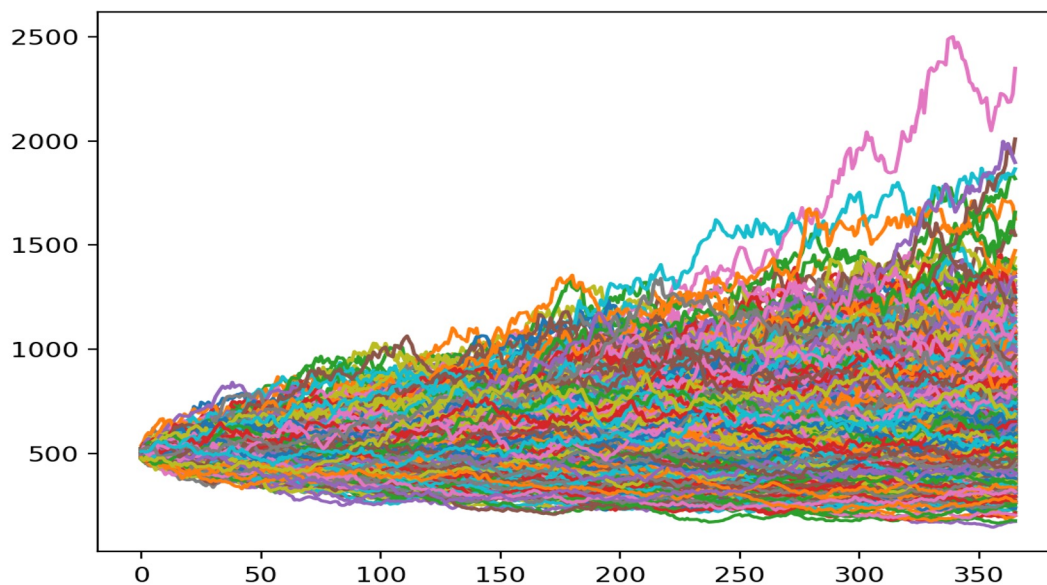
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<https://www.random.org/dice/>

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[Towards Data Science](#) Geometric Brownian Motion. A stochastic, non-linear process to... | by Roman Paolucci | [Towards Data Science](#)

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## A Simulation Example

- Two components work as an active and spare, so the system fails if both are failed simultaneously.
- The lifetime of a component is equally likely 1, 2, 3, 4, 5 or 6 days.
- Repair takes exactly 2.5 days (only one repair at a time); the repaired component becomes the spare.
- What can we say about the time to failure (TTF) for this system?
- Discrete-event simulation updates the **state** of the system when **events** happen.
  - The *state* of the system is the number of functional components.
  - The *events* are the failure of a component and the completion of a repair.

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Clock	System State	Next Failure	Next Repair
0	2	3	$\infty$
3	1	$3+5=8$	$3+2.5=5.5$
5.5	2	8	$\infty$
8	1	$8+3=11$	$8+2.5=10.5$
10.5	2	11	$\infty$
11	1	$11+1=12$	$11+2.5=13.5$
12	0	$\infty$	13.5

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Clock	System State	Next Failure	Next Repair
0	2		$\infty$

Your turn!

But let's do it with  
a spreadsheet &  
psuedorandom dice

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# Outputs

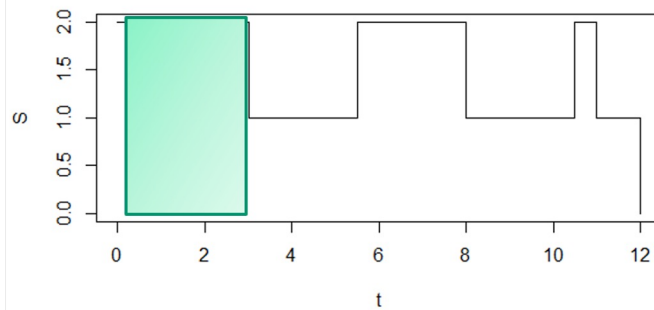
- *Replications* are statistically independent repetitions of the model.
- We distinguish between *within-replication* and *across-replication* output data.
  - Your time of system failure  $Y$  and the number of functional components  $\{S(t); t \geq 0\}$  are *within-replication* outputs.
  - Our times of system failure  $Y_1, Y_2, \dots, Y_n$ , and the average number of functional components,  $\bar{S}_1, \bar{S}_2, \dots, \bar{S}_n$  from  $n$  replications are *across-replication* outputs.
- Notice that  $\bar{S}$  is a *time-average* because  $S(t)$  is a continuous-time output variable.

$$\bar{S} = \frac{1}{Y} \int_0^Y S(t) dt$$

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## Time Averages

No calculus  
required!



$$\bar{S} = \frac{1}{Y} \int_0^Y S(t) dt$$

Average number of  
functional components

$$= \frac{1}{12} \left[ \boxed{2(3-0)} + 1(5.5-3) + 2(8-5.5) + \right. \\ \left. 1(10.5-8) + 2(11-10.5) + 1(12-11) \right] = \frac{17}{12}$$

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## Steady-State Simulation

- The “average number of functional components up to the first system failure” is not very meaningful.
- But if we let the simulation continue, then the system comes back up and starts functioning again.
- The “long-run average number of functional components” *is* a meaningful summary measure.
- But how do we let  $T \rightarrow \infty$  in a simulation?

$$\lim_{T \rightarrow \infty} \frac{1}{T} \int_0^T S(t) dt$$