

ZMOD4450 API Documentation

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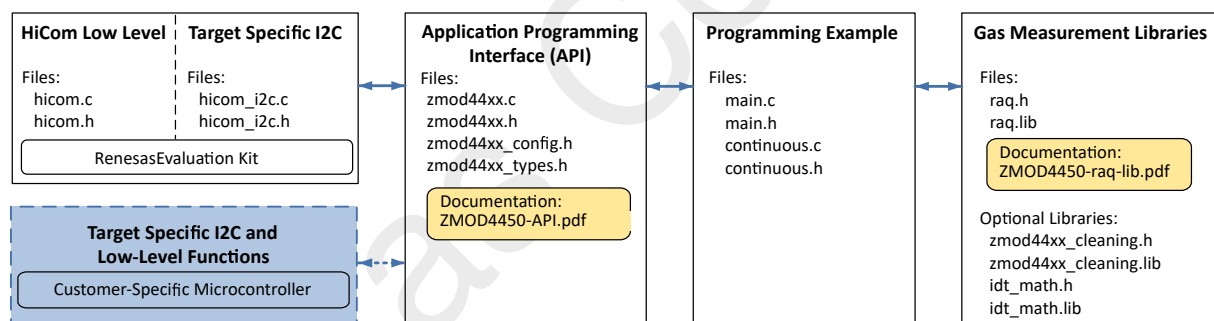
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Chapter 1

ZMOD4450 Application Programming Interface Overview

This document refers to the IDT document *ZMOD4450 Programming Manual - Read Me*. The figure below shows an overview of the ZMOD4450 API, programming example and libraries. Custom microcontrollers can be used to establish I2C communication. Using the user's own microcontroller requires implementing the user's own target-specific I2C and low-level functions (highlighted in light blue). The following describes in detail the Application Programming Interface (API) of the ZMOD4450.



Chapter 2

Module Index

2.1 Modules

Here is a list of all modules:

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Chapter 3

Data Structure Index

3.1 Data Structures

Here are the data structures with brief descriptions:

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Chapter 4

File Index

4.1 File List

Here is a list of all documented files with brief descriptions:

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Chapter 5

Module Documentation

5.1 Gas sensor IDs

Macros

- `#define ZMOD4450_PID (0x7310)`

5.1.1 Detailed Description

The gas sensor product IDs.

5.2 Error codes

Macros

- #define `ERROR_INIT_OUT_OF_RANGE` (1)
- #define `ERROR_GAS_TIMEOUT` (2)
- #define `ERROR_I2C` (3)
- #define `ERROR_SENSOR_UNSUPPORTED` (4)
- #define `ERROR_CONFIG_MISSING` (5)
- #define `ERROR_SENSOR` (6)
- #define `ERROR_ACCESS_CONFLICT` (7)
- #define `ERROR_POR_EVENT` (8)

5.2.1 Detailed Description

The gas sensor and API error codes.

5.2.2 Macro Definition Documentation

5.2.2.1 #define `ERROR_ACCESS_CONFLICT` (7)

AccessConflict.

5.2.2.2 #define `ERROR_CONFIG_MISSING` (5)

There is no pointer to a valid configuration.

5.2.2.3 #define `ERROR_GAS_TIMEOUT` (2)

The operation took too long.

5.2.2.4 #define `ERROR_I2C` (3)

Failure in i2c communication.

5.2.2.5 #define `ERROR_INIT_OUT_OF_RANGE` (1)

The initialize value is out of range.

5.2.2.6 #define `ERROR_POR_EVENT` (8)

POR_event.

5.2.2.7 #define `ERROR_SENSOR` (6)

Sensor malfunction.

5.2.2.8 #define `ERROR_SENSOR_UNSUPPORTED` (4)

Sensor is not supported with this firmware.

Chapter 6

Data Structure Documentation

6.1 zmod44xx_conf Struct Reference

Structure to hold the gas sensor module configuration.

```
#include <zmod44xx_types.h>
```

Data Fields

- `uint8_t start`
- [zmod44xx_conf_str h](#)
- [zmod44xx_conf_str d](#)
- [zmod44xx_conf_str m](#)
- [zmod44xx_conf_str s](#)
- [zmod44xx_conf_str r](#)

6.1.1 Detailed Description

Structure to hold the gas sensor module configuration.

The documentation for this struct was generated from the following file:

- [zmod44xx_types.h](#)

6.2 zmod44xx_conf_str Struct Reference

A single data set for the configuration.

```
#include <zmod44xx_types.h>
```

Data Fields

- `uint8_t addr`
- `uint8_t len`
- `const uint8_t * data`

6.2.1 Detailed Description

A single data set for the configuration.

The documentation for this struct was generated from the following file:

- [zmod44xx_types.h](#)

6.3 zmod44xx_dev_t Struct Reference

Device structure ZMOD44xx.

```
#include <zmod44xx_types.h>
```

Data Fields

- `uint8_t i2c_addr`
- `uint8_t config [6]`
- `uint8_t prod_data [5]`
- `uint16_t mox_lr`
- `uint16_t mox_er`
- `uint16_t pid`
- `zmod44xx_i2c_ptr_t read`
- `zmod44xx_i2c_ptr_t write`
- `zmod44xx_delay_ptr_p delay_ms`
- `const zmod44xx_conf * init_conf`
- `const zmod44xx_conf * meas_conf`

6.3.1 Detailed Description

Device structure ZMOD44xx.

6.3.2 Field Documentation

6.3.2.1 `uint8_t config[6]`

configuration parameter set

6.3.2.2 `zmod44xx_delay_ptr_p` delay_ms

function pointer to delay function

6.3.2.3 `uint8_t` i2c_addr

i2c address of the sensor

6.3.2.4 `const zmod44xx_conf*` init_conf

pointer to the initialize configuration

6.3.2.5 `const zmod44xx_conf*` meas_conf

pointer to the measurement configuration

6.3.2.6 `uint16_t` mox_er

sensor specific parameter

6.3.2.7 `uint16_t` mox_lr

sensor specific parameter

6.3.2.8 `uint16_t` pid

product id of the sensor

6.3.2.9 `uint8_t` prod_data[5]

production data

6.3.2.10 `zmod44xx_i2c_ptr_t` read

function pointer to i2c read

6.3.2.11 `zmod44xx_i2c_ptr_t` write

function pointer to i2c write

The documentation for this struct was generated from the following file:

- [zmod44xx_types.h](#)

Chapter 7

File Documentation

7.1 zmod44xx.c File Reference

ZMOD44xx functions.

```
#include "zmod44xx.h"
#include "zmod44xx_config.h"
```

Functions

- `int8_t zmod44xx_read_sensor_info (zmod44xx_dev_t *dev)`
Read sensor parameter.
- `int8_t zmod44xx_init_sensor (zmod44xx_dev_t *dev)`
Initialize the sensor after power on.
- `int8_t zmod44xx_init_measurement (zmod44xx_dev_t *dev)`
Initialize the sensor for zmod4450 measurement.
- `int8_t zmod44xx_start_measurement (zmod44xx_dev_t *dev)`
Start the measurement.
- `int8_t zmod44xx_read_status (zmod44xx_dev_t *dev, uint8_t *status)`
Read the status of the device.
- `int8_t zmod44xx_read_rmx (zmod44xx_dev_t *dev, float *rmx)`
Read adc values from sensor and calculate RMX.

7.1.1 Detailed Description

ZMOD44xx functions.

Author

IDT

7.1.2 Function Documentation

7.1.2.1 `int8_t zmod44xx_init_measurement (zmod44xx_dev_t * dev)`

Initialize the sensor for zmod4450 measurement.

Parameters

in	<i>dev</i>	pointer to the device
----	------------	-----------------------

Returns

error code

Return values

0	success
$\neq 0$	error

7.1.2.2 `int8_t zmod44xx_init_sensor (zmod44xx_dev_t * dev)`

Initialize the sensor after power on.

Parameters

in	<i>dev</i>	pointer to the device
----	------------	-----------------------

Returns

error code

Return values

0	success
$\neq 0$	error

7.1.2.3 `int8_t zmod44xx_read_rmx (zmod44xx_dev_t * dev, float * rmx)`

Read adc values from sensor and calculate RMOX.

Parameters

in	<i>dev</i>	pointer to the device
in, out	<i>rmx</i>	pointer to the resulting Rmx value

Returns

error code

Return values

0	success
!= 0	error

7.1.2.4 int8_t zmod44xx_read_sensor_info (zmod44xx_dev_t * dev)

Read sensor parameter.

Parameters

in	dev	pointer to the device
----	-----	-----------------------

Returns

error code

Return values

0	success
!= 0	error

Note

This function must be called once before running other sensor functions.

7.1.2.5 int8_t zmod44xx_read_status (zmod44xx_dev_t * dev, uint8_t * status)

Read the status of the device.

Parameters

in	dev	pointer to the device
in, out	status	pointer to the status variable

Returns

error code

Return values

0	success
!= 0	error

7.1.2.6 int8_t zmod44xx_start_measurement (zmod44xx_dev_t * dev)

Start the measurement.

Parameters

in	dev	pointer to the device
----	-----	-----------------------

Returns

error code

Return values

0	success
!= 0	error

7.2 zmod44xx.h File Reference

ZMOD44xx functions.

```
#include "zmod44xx_types.h"
```

Macros

- #define **ZMOD4450_I2C_ADDRESS** (0x32)
- #define **ZMOD44XX_ADDR_PID** (0x00)
- #define **ZMOD44XX_ADDR_CONF** (0x20)
- #define **ZMOD44XX_ADDR_PROD_DATA** (0x26)
- #define **ZMOD44XX_ADDR_CMD** (0x93)
- #define **ZMOD44XX_ADDR_STATUS** (0x94)
- #define **ZMOD44XX_LEN_PID** (2)
- #define **ZMOD44XX_LEN_CONF** (6)
- #define **ZMOD44XX_LEN_PROD_DATA** (5)
- #define **STATUS_SEQUENCER_RUNNING_MASK** (0x80)
- #define **STATUS_SLEEP_TIMER_ENABLED_MASK** (0x40)
- #define **STATUS_ALARM_MASK** (0x20)
- #define **STATUS_LAST_SEQ_STEP_MASK** (0x1F)
- #define **STATUS_POR_EVENT_MASK** (0x80)
- #define **STATUS_ACCESS_CONFLICT_MASK** (0x40)

Functions

- `int8_t zmod44xx_read_sensor_info (zmod44xx_dev_t *dev)`
Read sensor parameter.
- `int8_t zmod44xx_init_sensor (zmod44xx_dev_t *dev)`
Initialize the sensor after power on.
- `int8_t zmod44xx_init_measurement (zmod44xx_dev_t *dev)`
Initialize the sensor for zmod4450 measurement.
- `int8_t zmod44xx_start_measurement (zmod44xx_dev_t *dev)`
Start the measurement.
- `int8_t zmod44xx_read_status (zmod44xx_dev_t *dev, uint8_t *status)`
Read the status of the device.
- `int8_t zmod44xx_read_rmox (zmod44xx_dev_t *dev, float *rmox)`
Read adc values from sensor and calculate RMOX.

7.2.1 Detailed Description

ZMOD44xx functions.

Author

IDT

7.2.2 Macro Definition Documentation

7.2.2.1 #define STATUS_ACCESS_CONFLICT_MASK (0x40)

AccessConflict

7.2.2.2 #define STATUS_ALARM_MASK (0x20)

Alarm

7.2.2.3 #define STATUS_LAST_SEQ_STEP_MASK (0x1F)

Last executed sequencer step

7.2.2.4 #define STATUS_POR_EVENT_MASK (0x80)

POR_event

7.2.2.5 #define STATUS_SEQUENCER_RUNNING_MASK (0x80)

Sequencer is running

7.2.2.6 #define STATUS_SLEEP_TIMER_ENABLED_MASK (0x40)

SleepTimer_enabled

7.2.3 Function Documentation

7.2.3.1 int8_t zmod44xx_init_measurement (zmod44xx_dev_t * dev)

Initialize the sensor for zmod4450 measurement.

Parameters

in	dev	pointer to the device
----	-----	-----------------------

Returns

error code

Return values

0	success
!= 0	error

7.2.3.2 int8_t zmod44xx_init_sensor (zmod44xx_dev_t * dev)

Initialize the sensor after power on.

Parameters

in	dev	pointer to the device
----	-----	-----------------------

Returns

error code

Return values

0	success
!= 0	error

7.2.3.3 `int8_t zmod44xx_read_rmx (zmod44xx_dev_t * dev, float * rmx)`

Read adc values from sensor and calculate RMOX.

Parameters

<code>in</code>	<code>dev</code>	pointer to the device
<code>in, out</code>	<code>rmx</code>	pointer to the resulting Rmx value

Returns

error code

Return values

<code>0</code>	success
<code>!= 0</code>	error

7.2.3.4 `int8_t zmod44xx_read_sensor_info (zmod44xx_dev_t * dev)`

Read sensor parameter.

Parameters

<code>in</code>	<code>dev</code>	pointer to the device
-----------------	------------------	-----------------------

Returns

error code

Return values

<code>0</code>	success
<code>!= 0</code>	error

Note

This function must be called once before running other sensor functions.

7.2.3.5 `int8_t zmod44xx_read_status (zmod44xx_dev_t * dev, uint8_t * status)`

Read the status of the device.

Parameters

<code>in</code>	<code>dev</code>	pointer to the device
<code>in, out</code>	<code>status</code>	pointer to the status variable

Returns

error code

Return values

<code>0</code>	success
<code>!= 0</code>	error

7.2.3.6 `int8_t zmod44xx_start_measurement (zmod44xx_dev_t * dev)`

Start the measurement.

Parameters

<code>in</code>	<code>dev</code>	pointer to the device
-----------------	------------------	-----------------------

Returns

error code

Return values

<code>0</code>	success
<code>!= 0</code>	error

7.3 `zmod44xx_config.h` File Reference

ZMOD44xx configuration.

```
#include <stdint.h>
#include "zmod44xx_types.h"
```

Variables

- `const uint8_t data_set_4450_continuous []`

- `const uint8_t data_set_4450i []`
- `const zmod44xx_conf zmod4450_continuous`
ZMOD4450 configuration for continuous mode.
- `const zmod44xx_conf zmod44xxi`
ZMOD44XX sensor initialization configuration.

7.3.1 Detailed Description

ZMOD44xx configuration.

Author

IDT

7.3.2 Variable Documentation

7.3.2.1 `const uint8_t data_set_4450_continuous[]`

Initial value:

```
= {0x20, 0x04, 0x40, 0x09,
    0x03,
    0x00, 0x00, 0x80, 0x08}
```

7.3.2.2 `const uint8_t data_set_4450i[]`

Initial value:

```
= {0x00, 0x28, 0xC3, 0xE3,
    0x00, 0x00, 0x80, 0x40}
```

7.3.2.3 `const zmod44xx_conf zmod4450_continuous`

Initial value:

```
= {
    .start = 0xC0,
    .h = {.addr = 0x40, .len = 2},
    .d = {.addr = 0x50, .len = 4, .data = &data_set_4450_continuous[0]},
    .m = {.addr = 0x60, .len = 1, .data = &data_set_4450_continuous[4]},
    .s = {.addr = 0x68, .len = 4, .data = &data_set_4450_continuous[5]},
    .r = {.addr = 0x99, .len = 2}
}
```

ZMOD4450 configuration for continuous mode.

7.3.2.4 const zmod44xx_conf zmod44xxi

Initial value:

```
= {
    .start = 0x80,
    .h = {.addr = 0x40, .len = 2},
    .d = {.addr = 0x50, .len = 2, .data = &data_set_4450i[0]},
    .m = {.addr = 0x60, .len = 2, .data = &data_set_4450i[2]},
    .s = {.addr = 0x68, .len = 4, .data = &data_set_4450i[4]},
    .r = {.addr = 0x97, .len = 4}
}
```

ZMOD44XX sensor initialization configuration.

7.4 zmod44xx_types.h File Reference

ZMOD44xx types.

```
#include <stdint.h>
```

Data Structures

- struct [zmod44xx_conf_str](#)
A single data set for the configuration.
- struct [zmod44xx_conf](#)
Structure to hold the gas sensor module configuration.
- struct [zmod44xx_dev_t](#)
Device structure ZMOD44xx.

Macros

- #define [ZMOD4450_PID](#) (0x7310)
- #define [ZMOD44XX_OK](#) (0)
- #define [ERROR_INIT_OUT_OF_RANGE](#) (1)
- #define [ERROR_GAS_TIMEOUT](#) (2)
- #define [ERROR_I2C](#) (3)
- #define [ERROR_SENSOR_UNSUPPORTED](#) (4)
- #define [ERROR_CONFIG_MISSING](#) (5)
- #define [ERROR_SENSOR](#) (6)
- #define [ERROR_ACCESS_CONFLICT](#) (7)
- #define [ERROR_POR_EVENT](#) (8)

Typedefs

- typedef int8_t(* [zmod44xx_i2c_ptr_t](#)) (uint8_t addr, uint8_t reg_addr, const uint8_t *data, uint8_t len)
function pointer type for i2c access
- typedef void(* [zmod44xx_delay_ptr_p](#)) (uint32_t ms)
function pointer to hardware dependent delay function

7.4.1 Detailed Description

ZMOD44xx types.

Author

IDT

7.4.2 Macro Definition Documentation

7.4.2.1 #define ZMOD44XX_OK (0)

Return value if no fault has been found.

7.4.3 Typedef Documentation

7.4.3.1 typedef int8_t(* [zmod44xx_i2c_ptr_t](#)) (uint8_t addr, uint8_t reg_addr, const uint8_t *data, uint8_t len)

function pointer type for i2c access

Parameters

in	<i>addr</i>	7-bit I2C slave address of the ZMOD44xx
in	<i>reg_addr</i>	address of internal register to read/write
in, out	<i>data</i>	pointer to the read/write data value
in	<i>len</i>	number of bytes to read/write

Returns

error code

Return values

0	success
!= 0	error