

TUTORIAL - WEEK 8

Normal equation for linear regression: (a.k.a. standard form for least square problem)

Suppose we have an overdetermined system: $Ax = b$ with $A_{m \times n}$ ($m > n$), $x_{n \times 1}$ and $b_{m \times 1}$

$$\begin{bmatrix} a_{11} & a_{12} \\ a_{21} & a_{22} \\ a_{31} & a_{32} \end{bmatrix} \begin{pmatrix} x_1 \\ x_2 \end{pmatrix} = \begin{pmatrix} b_{11} \\ b_{21} \\ b_{31} \end{pmatrix} \quad \text{No exact solution}$$

If $S(x)$ is the set with all the possible solutions we want to find $\hat{x} \in S(x)$ such that:

$$\hat{x} = \underset{\uparrow}{\operatorname{argmin}} (S(x))$$

solution with the minimum square error

We can rewrite our system as $Ax - b = 0$. Since $S(x)$ is a set of solutions we can try to minimize it to find \bar{x} .

To do that in a least square sense, we can write the 2-norm for our system, then set the derivative of it to 0:

$$\|S(x)\|_2 = \sum_{i=1}^m \left| \sum_{j=1}^n A_{ij} x_j - b_i \right|^2 \equiv \|Ax - b\|^2 = (A^T x^T - b^T)(Ax - b)$$

↖ we want to take the derivative with respect to the vector x of this and then set it to zero

$$\frac{d(A^T x^T - b^T)(Ax - b)}{dx_j} = 0$$

↖ partial derivative with respect to each component of \bar{x}

$$\frac{d}{dx_j} \underbrace{(A^T x^T A x - A^T x^T b - b^T A x + b^T b)}_{\text{expanded the products}} = 0 \quad A^T x^T b = b^T A x \quad (\text{column vector, same dimension of } b)$$

$$\frac{d}{dx} (A^T A x - 2 A^T x^T b + \cancel{b^T b}) = 0 \quad \Leftrightarrow \quad 2 A^T A \hat{x} - 2 A^T b = 0$$

$$A^T A \hat{x} - A^T b = 0 \quad \Leftrightarrow \quad A^T A x = A^T b$$

$$\boxed{\hat{x} = (A^T A)^{-1} A^T b}$$

normal eq. for linear regression

Numerical example:

$$A x = b \quad \text{where:}$$

$$\begin{bmatrix} 1 & -1 \\ 1 & 1 \\ 2 & 1 \end{bmatrix} \begin{pmatrix} x_1 \\ x_2 \end{pmatrix} = \begin{pmatrix} 2 \\ 4 \\ 8 \end{pmatrix}$$

$$A \quad x \quad b$$

$$A_{m \times n} \quad m > n$$

$$x_{n \times 1}$$

$$b_{m \times 1}$$

To compute \hat{x} I need A^T :

$$A^T = \begin{bmatrix} 1 & 1 & 2 \\ -1 & 1 & 1 \end{bmatrix}$$

$$A^T A x = A^T b$$

$$\begin{bmatrix} 1 & 1 & 2 \\ -1 & 1 & 1 \end{bmatrix} \begin{bmatrix} 1 \\ -1 \end{bmatrix} \begin{pmatrix} x_1 \\ x_2 \end{pmatrix} = \begin{bmatrix} 1 & 1 & 2 \\ -1 & 1 & 1 \end{bmatrix} \begin{pmatrix} 2 \\ 4 \\ 8 \end{pmatrix} \Leftrightarrow$$

$$\begin{pmatrix} 6 & 2 \\ 2 & 3 \end{pmatrix} \begin{pmatrix} x_1 \\ x_2 \end{pmatrix} = \begin{pmatrix} 22 \\ 10 \end{pmatrix}$$

I can solve this using Gauss elimination:

$$\left(\begin{array}{cc|c} 6 & 2 & 22 \\ 2 & 3 & 10 \end{array} \right) \quad R_2 = -3R_2 + R_1 \quad \left(\begin{array}{cc|c} 6 & 2 & 22 \\ 0 & -7 & -8 \end{array} \right)$$

$$\begin{pmatrix} 6 & 2 \\ 0 & -7 \end{pmatrix} \begin{pmatrix} x_1 \\ x_2 \end{pmatrix} = \begin{pmatrix} 22 \\ -8 \end{pmatrix} \rightarrow \begin{matrix} x_2 = 8/7 \\ x_1 = 23/7 \end{matrix} \rightarrow \hat{x} = \begin{pmatrix} 23/7 \\ 8/7 \end{pmatrix}$$

Taylor polynomials

If $f(x)$ is a function, and $f^{(n)}$ is continuous in $[a, b]$ and $f^{(n+1)}$ exists, the n^{th} Taylor polynomial for $f(x)$ is:

$$T_n(x) = \sum_{i=0}^n \frac{f^{(i)}(c)}{i!} (x-c)^i$$

c is where I evaluate my polynomial.

If $c=0 \rightarrow$ Maclaurin: $T_n(x) = \sum_{i=0}^n \frac{f^{(i)}(0)}{i!} \cdot x^i$

Example: consider $f(x) = \cos(x)$ at $c=0$

The Maclaurin series for $f(x)$ is
$$\sum_{i=0}^{\infty} \frac{(-1)^i}{2i!} x^{2i}$$

So the Taylor polynomials, at $c=0$, are defined as:

$$T_k(x) = \sum_{i=0}^k \frac{(-1)^i}{2i!} x^{2i}$$

$$k=0 \rightarrow T_0(x) = \frac{(-1)^0}{0!} x^0 = 1$$

$$k=1 \rightarrow T_1(x) = \frac{(-1)^0}{0!} x^0 + \frac{(-1)^1}{2!} x^2 = 1 - \frac{1}{2} x^2$$

$$k=2 \rightarrow T_2(x) = \frac{(-1)^0}{0!} x^0 + \frac{(-1)^1}{2!} x^2 + \frac{(-1)^2}{4!} x^4 = 1 - \frac{1}{2} x^2 + \frac{1}{24} x^4$$

See .m files in the directory for a good idea of how this polynomials behave! :)

