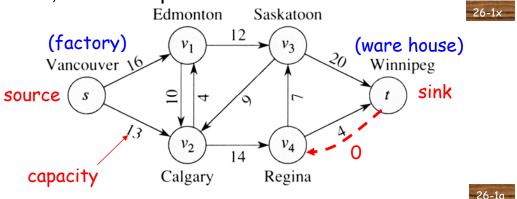
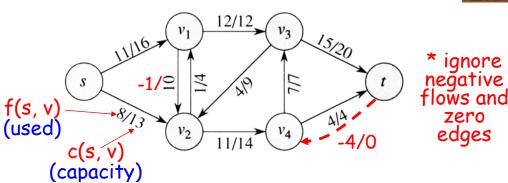
Maximum Flow

26.1 Flow networks

Flow networks: a directed graph G=(V, E), in which each $(u,v) \in E$ has a capacity $c(u,v) \ge 0$. If $(u,v) \notin E$, we assume c(u,v) = 0. There are a source vertex s and a sink vertex t in G. For every vertex v in G, there is a path $s \rightarrow v \rightarrow t$.





Flow: a real function $f: V \times V \rightarrow R$ satisfying the following three properties.

Capacity constraint: For all $u,v \in V$, $f(u,v) \le c(u,v)$ **Skew symmetry:** For all $u,v \in V$, f(u,v) = -f(v,u)**Flow conservation:** For all $u \in V - \{s, t\}$,

$$\sum_{v \in V} f(\underline{u}, v) = 0.$$
 -1 total flow out off $u = 0$

* **Positive net flow** entering (leaving) a vertex u: $\sum_{v \in V \text{ and } f(v,u) > 0} f(v,v) = \int_{v \in V \text{ and } f(u,v) > 0} f(u,v) = 0$

- * For all $u \in V \{s, t\}$, we have

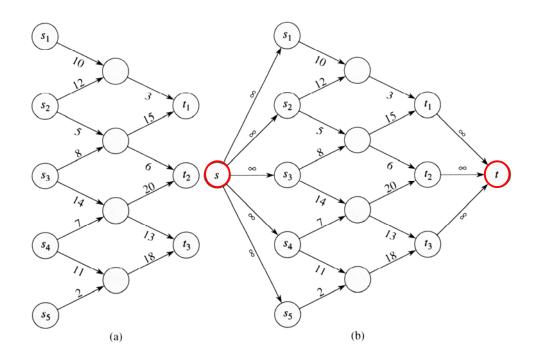
 Positive net flow entering u= Positive net flow leaving u.

 (flow conservation: positive in = positive out)
- * For all $u \in V \{s, t\}$, $\sum_{v \in V} f(v, u) = 0$. (Total flow into a vertex is 0. (flow conservation: total in = 0)
- * f(u,v) is called the **net flow** from u to v. It can be positive or negative.

 total out from s total into t
- * The value of a flow f is $|f| = \sum_{v \in V} f(s, v)$. $\stackrel{(= \sum_{v \in V} f(v, \underline{t}))}{v \in V}$
- * **Maximum-flow problem:** finding a flow of maximum value from s to t.

- * If $(u,v) \notin E$ and $(v,u) \notin E$, f(v,u)=f(u,v)=0. \implies find a path: O(E) (not $O(n^2)$) BFS or DFS
- * Nonzero net flow from u to v implies $(u,v) \in E$ or $(v,u) \in E$.

* Networks with multiple sources and sinks



* Let X and Y be sets of vertices. For simplicity, define

See 26-6 example

$$f(X, Y) = \sum_{X \in X} \sum_{y \in Y} f(x, y)$$
 and $c(X, Y) = \sum_{X \in X} \sum_{y \in Y} c(x, y)$.

26.2 The Ford-Fulkerson method

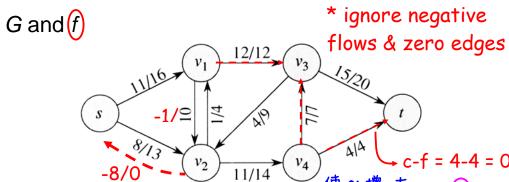
* We call it a method instead of algorithm, because it encompasses several implementations.

FORD-FULKERSON-METHOD (G, s, t)

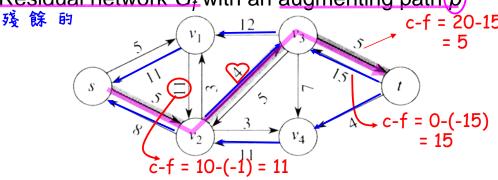
- 1 initialize flow f to 0 f = 0
- 2 while there exists an augmenting path p
- 3 **do** augment flow f along p
- 4 return f $f = f + f_p$

Example:

26-4x

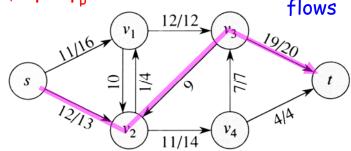


Residual network G_f with an augmenting path p

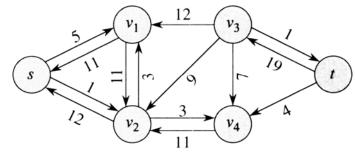


New $f \leftarrow f + f_p$ * ignore negative 26-5

flows



New G_f



Residual networks G_f

(1) <u>residual capacity</u> of (u, v) is given as

$$\frac{C_f(u,v)}{\text{capacity}} = \frac{C(u,v) - f(u,v)}{\text{capacity}}.$$

(2) $G_f = (V, E_f)$, where

only non-negative edges

$$E_f = \{(u, v) \in V \times V : c_f(u, v) > 0\}.$$

set of edges that still can be used!

Augmenting path: a simple path $s \rightarrow t$ in G_f .

Cut of a flow network: a partition of V into S and T=V-S such that $s \in S$ and $t \in T$.

Net flow across a cut: f(S, T).

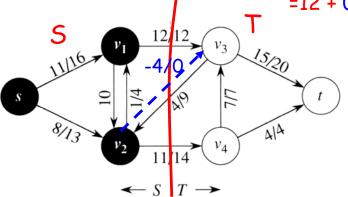
(See 26-3 for de

Capacity of a cut: c(S, T).

26-6x

Example: |f|=19, f(S, T)=19, and c(S, T)=26.

=12 + 0 + 14



Lemma 26.5: For any cut (S, T), f(S, T)=|f|. (flow conservation)

Corollary 26.6: For any f, $|f| \le c(S, T)$.

(capacity constraint)

Every cut sets an upper bound on $|f^*|$.

Fig 26-4

Theorem 26.7: (Maximum flow minimum cut) 26-7a The following are equivalent:

1. f is a maximum flow



- 2. G_f contains no augmenting paths
- 3. |f|=c(S, T) for some cut (S, T) of G.

 $|f| \le c(S, T) \longrightarrow c(S, T)$ is a minimum cut **Proof**: (1) \rightarrow (2) (By contraction) Suppose there is an augmenting path p. We have $|f+f_p|>|f|$, which contradicts to "f is a maximum flow."

 $(2)\rightarrow(3)$ Since (2), G_f contains no path from s to t. Define $S=\{v \mid \text{there is a } s \rightarrow v \text{ in } G_f\} \text{ and } T=V-S.$ Note that $t \in T$. Thus, (S, T) is a cut.

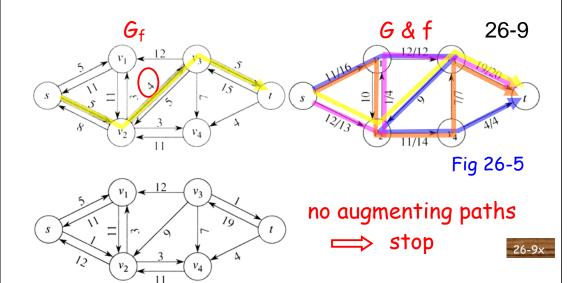
For each pair $u \in S$ and $v \in T$, we have f(u,v) =c(u,v), since otherwise $(u,v) \in E_f$ and v is in S. By lemma 26.5, |f|=f(S, T)=c(S, T).

(3) \rightarrow (1): By corollary 26.6, $|f| \le c(S, T)$ for all cuts. The condition |f|=c(S, T) thus implies f is a maximum flow.

Q.E.D.

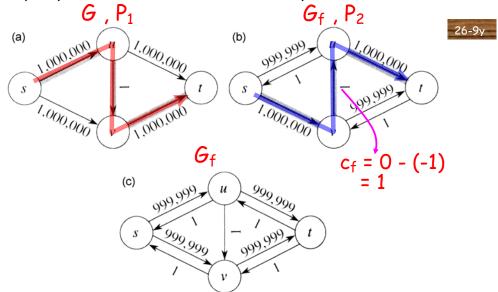
The basic algorithm

FORD-FULKERSON(G, s, t) for each edge $(u, v) \in E[G]$ **do** $f[u, v] \leftarrow 0$ $f[v,u] \leftarrow 0$ while there exists a path p from s to t in G_f $\operatorname{do}[c_f(p)] \leftarrow \min\{c_f(u,v) : (u,v) \text{ is in } p\}$ **for** each edge (u, v) in p**do** $f[u, v] \leftarrow f[u, v] + c_f(p)$ $7 f = f + f_n$ $f[v,u] \leftarrow -f[u,v]$ \rightarrow f[v,u] - c_f(p) (f=0)



Analysis:

(1) |f| is increasing. But, if p is chosen poorly, the algorithm might not even terminate (while c(u,v)'s are irrational numbers).



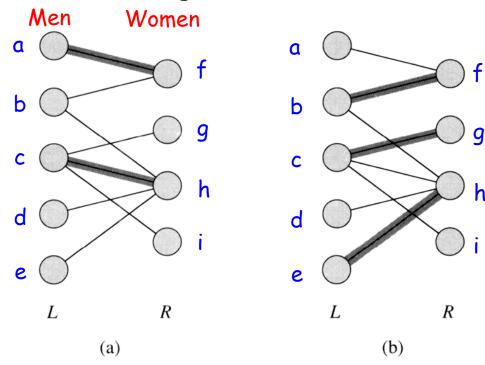
find a path: O(E) BFS or DFS 26-10

- (2) If c(u,v)'s are integers, it performs in $O(E|f^*|)$ time, where f^* is the maximum flow.

 at most $|f^*|$ times
- (3) If *p* is chosen by using breadth-first search, the algorithm is called the *Edmonds-Karp* algorithm. It performs in $O(VE^2)$ time. (We are not going to prove this.) at most VE times

26.3 Maximum bipartite matching

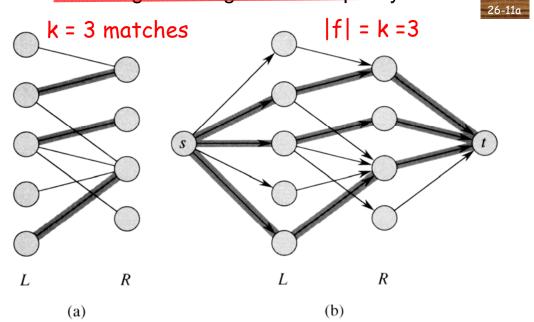
A <u>bipartite</u> graph (undirected) $G=(V=L\cup R,E)$ and two matchings



Corresponding flow network: G'=(V',E'), where

$$V = V \cup \{s, t\},\$$
 $E = \{(s,u): u \in L\}\$
 $\cup \{(u,v): u \in L, v \in R, \text{ and } (u,v) \in E\}$
 $\cup \{(v,t): v \in R\}, \text{ and }$

each edge is assigned unit capacity.



matchina <--> integer-valued flow

26-12

Lemma 26.10: If M is a matching in G, then there is an integer-valued flow f in G' with |M|=|f|. Conversely, if f is an integer-valued flow f in G', then there is a matching M in G with |M|=|f|.

Theorem 26.11: If all c(u,v)'s are integer, all $f^*(u,v)$'s produced by Ford-Fulkerson method are integers. (by induction.) $G,f \longrightarrow G_f \longrightarrow f_p \longrightarrow f + f_p$

Corollary 26.12: $|f^*|$ of G is equal to the cardinality of a maximum matching in G.

* The maximum bipartite matching problem can be solved in $O(Ef^*)=O(EV)$ time. $f^* \leq |V|/2$

Homework: Ex. 26.2-6, 26.2-11, Pro. 26-1, 26-2.

flow on undirected $G: \bigcirc 4 \bigcirc \Rightarrow \bigcirc 4$



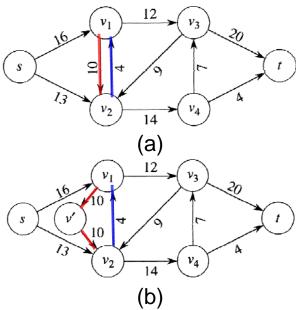
Differences in the 3rd Edition

(Consider only positive flows)

Flow networks:

Assume that *G* contains no *antiparallel* edges. (If $(u, v) \in E$, then $(v, u) \notin E$.)

Handling antiparallel edges:



Converting a network with antiparallel edges into one with no antiparallel edges

Flow: a real function f: $V \times V \rightarrow R$ satisfying the following TWO properties:

Capacity constraint: For all $u, v \in V$, $0 \le f(u,v) \le c(u,v)$. Only positive flows!!! *Flow conservation*: For all $u \in V - \{s, t\}$, $\sum f(v, u) = \sum f(u, v)$. (flow in equals flow out)

 $v \in V$ $v \in V$ positive in = positive out 1

The residual capacity:

(slightly complicated)

$$c_f(u,v) = \begin{cases} c(u,v) - f(u,v) & \text{if } (u,v) \in E, \\ f(v,u) & \text{if } (v,u) \in E, \\ 0 & \text{otherwise.} \end{cases}$$

The basic Ford-Fulkerson algorithm

FORD-FULKERSON $(G, s, t) \otimes$ (* needs converting)

- 1. **for** each edge $(u, v) \in E[G]$
- $\operatorname{do} f[u, v] \leftarrow 0$ one side (slightly simpler) \odot
- 3. while there exists a path p from s to t in G_f
- **do** $c_f(p) \leftarrow \min\{c_f(u, v): (u, v) \text{ is in } p\}$
- for each edge (u, v) in p do 5.
- (if-then-else) **if** $(u, v) \in E[G]$
- then $f[u, v] \leftarrow f[u, v] + c_f(p)$ else $f[v, u] \leftarrow f[v, u] c_f(p)$