

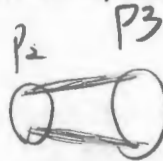
Linear Algebra Exam 2

1. (10%) Find the basis for both $N(T)$ and $R(T)$, then compute the nullity and rank of T , and determine whether T is one-to-one or onto.

$$T: P_2(\mathbb{R}) \rightarrow P_3(\mathbb{R}) \text{ defined by } T(f(x)) = xf(x) + f'(x)$$

$$6x^2 + 5x + 5$$

$$6x + 5$$



2. (5%) $T: M_{2 \times 2}(\mathbb{R}) \rightarrow P_2(\mathbb{R})$ by $T\begin{pmatrix} a & b \\ c & d \end{pmatrix} = (a+b) + (2d)x + bx^2$

$$\text{Let } \beta = \left\{ \begin{pmatrix} 1 & 0 \\ 0 & 0 \end{pmatrix}, \begin{pmatrix} 0 & 1 \\ 0 & 0 \end{pmatrix}, \begin{pmatrix} 0 & 0 \\ 1 & 0 \end{pmatrix}, \begin{pmatrix} 0 & 0 \\ 0 & 1 \end{pmatrix} \right\} \text{ and } \gamma = \{1, x, x^2\}$$

Compute $[T]_{\beta}^{\gamma}$.

3. (10%) Let $g(x) = 2x$. Let $T: P_2(\mathbb{R}) \rightarrow P_2(\mathbb{R})$ and $U: P_2(\mathbb{R}) \rightarrow \mathbb{R}^3$ be the linear transformations respectively defined by

$$T(f(x)) = f'(x)g(x) + 3f(x) \text{ and } U(a+bx+cx^2) = (a+2b, c, a-b)$$

Let β and γ be the standard ordered bases of $P_2(\mathbb{R})$ and \mathbb{R}^3 , respectively.

(a) Compute $[U]_{\gamma}^{\gamma}, [T]_{\beta}$

(b) Let $h(x) = 5 - x + x^2$. Compute $[h(x)]_{\beta}$ and $[U(h(x))]_{\gamma}$.

4. (5%) For each of the following pairs of ordered bases β and β' for $P_2(\mathbb{R})$, find the change of coordinate matrix that changes β' -coordinates into β -coordinates

(a) $\beta = \{x^2, x, 1\}$ and $\beta' = \{a_2x^2 + a_1x + a_0, b_2x^2 + b_1x + b_0, c_2x^2 + c_1x + c_0\}$

(b) $\beta = \{2x^2 - x, 3x^2 + 1, x^2\}$ and $\beta' = \{1, x, x^2\}$

5. (15%) For each of the following linear transformations T , determine whether T is invertible and justify your answer.

(a) $T: \mathbb{R}^2 \rightarrow \mathbb{R}^3$ defined by $T(a_1, a_2) = (a_1, a_1 + a_2, a_2)$

(b) $T: \mathbb{R}^3 \rightarrow \mathbb{R}^3$ defined by $T(a_1, a_2, a_3) = (a_1, a_1 + a_2, a_1 + a_2 + a_3)$

(c) $T: M_{2 \times 2}(\mathbb{R}) \rightarrow M_{2 \times 2}(\mathbb{R})$ defined by $T\begin{pmatrix} a & b \\ c & d \end{pmatrix} = \begin{pmatrix} a-b & d \\ a+c & b \end{pmatrix}$

6. (10%) Let V and W be vector spaces, and let $T: V \rightarrow W$ be linear. Prove that if T is invertible if and only if T is one-to-one and onto.

7. (15%) Please show the reasons for the statements S1, S2, and S3 below.

Theorem 2.3 (Dimension Theorem). Let V and W be vector spaces, and let $T: V \rightarrow W$ be linear. If V is finite-dimensional, then

$$\text{nullity}(T) + \text{rank}(T) = \dim(V).$$

Proof. Suppose that $\dim(V) = n$, $\dim(N(T)) = k$, and $\{v_1, v_2, \dots, v_k\}$ is a basis for $N(T)$. By the corollary to Theorem 1.11 (p. 51), we may extend $\{v_1, v_2, \dots, v_k\}$ to a basis $\beta = \{v_1, v_2, \dots, v_n\}$ for V . We claim that $S = \{T(v_{k+1}), T(v_{k+2}), \dots, T(v_n)\}$ is a basis for $R(T)$.

First we prove that S generates $R(T)$. Using Theorem 2.2 and the fact that $T(v_i) = 0$ for $1 \leq i \leq k$, we have

$$\text{S1} \quad R(T) = \frac{\text{span}(\{T(v_1), T(v_2), \dots, T(v_n)\})}{= \text{span}(\{T(v_{k+1}), T(v_{k+2}), \dots, T(v_n)\})} = \text{span}(S).$$

Now we prove that S is linearly independent. Suppose that

$$\sum_{i=k+1}^n b_i T(v_i) = 0 \quad \text{for } b_{k+1}, b_{k+2}, \dots, b_n \in F.$$

Using the fact that T is linear, we have

$$\text{S2} \quad T\left(\sum_{i=k+1}^n b_i v_i\right) = 0.$$

So

$$\sum_{i=k+1}^n b_i v_i \in N(T).$$

Hence there exist $c_1, c_2, \dots, c_k \in F$ such that

$$\text{S3} \quad \frac{\sum_{i=k+1}^n b_i v_i = \sum_{i=1}^k c_i v_i}{\text{or } \sum_{i=1}^k (-c_i) v_i + \sum_{i=k+1}^n b_i v_i = 0}.$$

8. (5%) Please show the reason for the statement below.

Theorem 2.9. Let V , W , and Z be vector spaces over the same field F , and let $T: V \rightarrow W$ and $U: W \rightarrow Z$ be linear. Then $UT: V \rightarrow Z$ is linear.

Proof. Let $x, y \in V$ and $a \in F$. Then

$$\begin{aligned} UT(ax + y) &= U(T(ax + y)) = U(aT(x) + T(y)) \\ &= aU(T(x)) + U(T(y)) = a(UT)(x) + UT(y). \end{aligned}$$

9. (5%) Please show the reason for the statement below.

Theorem 2.23

Theorem 2.23. Let T be a linear operator on a finite-dimensional vector space V , and let β and β' be ordered bases for V . Suppose that Q is the change of coordinate matrix that changes β' -coordinates into β -coordinates. Then

$$[T]_{\beta'} = Q^{-1}[T]_{\beta}Q.$$

Proof. Let I be the identity transformation on V . Then $T = IT = TI$; hence, by Theorem 2.11 (p. 88),

$$Q[T]_{\beta'} = [I]_{\beta'}^{\beta}[T]_{\beta'}^{\beta'} = [I]_{\beta'}^{\beta}[T]_{\beta'}^{\beta} = [T]_{\beta}^{\beta}[I]_{\beta'}^{\beta} = [T]_{\beta}Q.$$

Therefore $[T]_{\beta'} = Q^{-1}[T]_{\beta}Q$.

10. (10%) Please show the reasons for the statements S1 and S2 below.

Theorem 2.18 (1/2)

Theorem 2.18. Let V and W be finite-dimensional vector spaces with ordered bases β and γ , respectively. Let $T: V \rightarrow W$ be linear. Then T is invertible if and only if $[T]_{\beta}^{\gamma}$ is invertible. Furthermore, $[T^{-1}]_{\gamma}^{\beta} = ([T]_{\beta}^{\gamma})^{-1}$.

Proof. Suppose that T is invertible. By the lemma, we have $\dim(V) = \dim(W)$. Let $n = \dim(V)$. So $[T]_{\beta}^{\gamma}$ is an $n \times n$ matrix. Now $T^{-1}: W \rightarrow V$ satisfies $TT^{-1} = I_W$ and $T^{-1}T = I_V$.

Thus

S1

$$I_n = [I_V]_{\beta} = [T^{-1}T]_{\beta} = [T^{-1}]_{\gamma}^{\beta}[T]_{\beta}^{\gamma}.$$

Similarly, $[T]_{\beta}^{\gamma}[T^{-1}]_{\gamma}^{\beta} = I_n$. So $[T]_{\beta}^{\gamma}$ is invertible and $([T]_{\beta}^{\gamma})^{-1} = [T^{-1}]_{\gamma}^{\beta}$.

Theorem 2.18 (2/2)

Now suppose that $A = [T]_{\beta}^{\gamma}$ is invertible. Then there exists an $n \times n$ matrix B such that $AB = BA = I_n$. By Theorem 2.6 (p. 72), there exists $U \in \mathcal{L}(W, V)$ such that

$$U(w_j) = \sum_{i=1}^n B_{ij} v_i \quad \text{for } j = 1, 2, \dots, n,$$

S2

where $\gamma = \{w_1, w_2, \dots, w_n\}$ and $\beta = \{v_1, v_2, \dots, v_n\}$. It follows that $[U]_{\beta}^{\gamma} = B$.

11. (10%) Please show the reasons for the statements S1 and S2 below.

Theorem 2.7. Let V and W be vector spaces over a field F , and let $T, U : V \rightarrow W$ be linear. For all $a \in F$, $aT + U$ is linear.

Proof. Let $x, y \in V$ and $c \in F$. Then

$$\begin{aligned} (aT + U)(cx + y) &= aT(cx + y) + U(cx + y) \\ &= a[T(cx + y)] + cU(x) + U(y) \\ &= a[cT(x) + T(y)] + cU(x) + U(y) \\ &= acT(x) + cU(x) + aT(y) + U(y) \\ &= c(aT + U)(x) + (aT + U)(y) \end{aligned}$$

S1

Proof. Let $x, y \in V$ and $c \in F$. Then

$$\begin{aligned} (aT + U)(cx + y) &= aT(cx + y) + U(cx + y) \\ &= a[T(cx + y)] + cU(x) + U(y) \\ &= a[cT(x) + T(y)] + cU(x) + U(y) \\ &= acT(x) + cU(x) + aT(y) + U(y) \\ &= c(aT + U)(x) + (aT + U)(y) \end{aligned}$$

S2

1. $N(T)$ is the subspace of all set that make $T(x) = 0$. -2
Basis $N(T)$?

$$N(T) = \{ f(x) = 0 : f(x) \in P^2 \} \quad \text{nullity}(T) = 0. \quad \checkmark$$

$\beta = \{1, x, x^2\}$ as a basis for $P_2(R)$.

$$R(T) = \text{span}(T(\beta)) = \text{span}(\{T(1), T(x), T(x^2)\})$$

$$= \text{span}(\{x, x^2+1, x^3+2x\}) \quad \checkmark$$

$$\text{rank}(T) = 3. \quad \checkmark$$

~~PROV~~

T is 1-1. for $\forall x_1, x_2, T(x_1) = T(x_2) \Rightarrow x_1 = x_2$.

and $N(T) = \{0\}$.

but not onto. we can't find $\forall y \in P^3 \exists x \in P^2, T(x) = y$. $(xf(x) + f(x))$ can't represent any vector in P^3 . ✓

2.

$$T\left(\begin{pmatrix} 1 & 0 \\ 0 & 0 \end{pmatrix}\right) = 1 + 0x + 0x^2$$

$$T\left(\begin{pmatrix} 0 & 1 \\ 0 & 0 \end{pmatrix}\right) = 1 + 0x + 1x^2$$

$$T\left(\begin{pmatrix} 0 & 0 \\ 1 & 0 \end{pmatrix}\right) = 0 + 0x + 0x^2$$

$$T\left(\begin{pmatrix} 0 & 0 \\ 0 & 1 \end{pmatrix}\right) = 0 + 2x + 0x^2$$

$$[T]_{\beta}^{\gamma} = \begin{bmatrix} 1 & 1 & 0 & 0 \\ 0 & 0 & 0 & 2 \\ 0 & 1 & 0 & 0 \end{bmatrix} \quad \checkmark$$

$$\text{rank}(T) = \dim \text{range}(T) = 3$$

3.

(a).

$$U(1) = (1, 0, 1)$$

$$U(x) = (2, 0, -1) \Rightarrow [U]_{\beta}^r = \begin{bmatrix} 1 & 2 & 0 \\ 0 & 0 & 1 \\ 1 & -1 & 0 \end{bmatrix}$$

$$U(x^2) = (0, 1, 0)$$

$$T(1) = 3 = 3 + 0x + 0x^2$$

$$T(x) = 2x + 3x = 0 + 5x + 0x^2$$

$$T(x^2) = 4x^2 + 3x^2 = 0 + 0x + 7x^2$$

$$\Rightarrow [T]_{\beta} = \begin{bmatrix} 3 & 0 & 0 \\ 0 & 5 & 0 \\ 0 & 0 & 7 \end{bmatrix}$$

(b)

$$[h(x)]_{\beta} = \begin{bmatrix} 5 \\ -1 \\ 1 \end{bmatrix}$$

$$[U(h(x))]_{\beta} = [U]_{\beta}^r \cdot [h(x)]_{\beta} = \begin{bmatrix} 1 & 2 & 0 \\ 0 & 0 & 1 \\ 1 & -1 & 0 \end{bmatrix} \begin{bmatrix} 5 \\ -1 \\ 1 \end{bmatrix} = \begin{bmatrix} 3 \\ 1 \\ 6 \end{bmatrix}$$

(by Thm 2.14).

4.

$$(a) a_2 x^2 + a_1 x + a_0 = a_2(x^2) + a_1(x) + a_0(1).$$

$$b_2 x^2 + b_1 x + b_0 = b_2(x^2) + b_1(x) + b_0(1).$$

$$c_2 x^2 + c_1 x + c_0 = c_2(x^2) + c_1(x) + c_0(1).$$

$$A = \begin{bmatrix} a_2 & b_2 & c_2 \\ a_1 & b_1 & c_1 \\ a_0 & b_0 & c_0 \end{bmatrix}$$

(b),

$$1 = a(2x^2 - x) + b(3x^2 + 1) + cx^2$$

$$= 0(2x^2 - x) + 1(3x^2 + 1) - 3x^2$$

$$x = a(2x^2 - x) + b(3x^2 + 1) + cx^2$$

$$= -1(2x^2 - x) + 0(3x^2 + 1) + 2x^2$$

$$x^2 = a(2x^2 - x) + b(3x^2 + 1) + cx^2$$

$$= 0(2x^2 - x) + 0(3x^2 + 1) + x^2$$

$$A: \begin{bmatrix} 0 & -1 & 0 \\ 1 & 0 & 0 \\ -3 & 2 & 1 \end{bmatrix}$$

$$\begin{cases} 2a + 3b + c = 0 \\ -a = 0 \\ b = 1 \\ \Rightarrow c = -3 \end{cases}$$

$$\begin{cases} 2a + 3b + c = 0 \\ -a = 1 \\ b = 0 \\ \Rightarrow c = 2 \end{cases}$$

$$\begin{cases} 2a + 3b + c = 1 \\ -a = 0 \\ b = 0 \\ \Rightarrow c = 1 \end{cases}$$

5.

(a) not invertible, They have different dimension

$\therefore \dim(R_2) < \dim(R_3) \Rightarrow$ is not on-to.

for example, $(0, 1, 0)$ in $R_3 \Rightarrow \begin{cases} a_1 = 0 \\ a_1 + a_2 = 1 \\ a_2 = 0 \end{cases} \Rightarrow$ 无解.

(b) Yes, when $T(a_1, a_2, a_3) = 0$, $a_1 = a_2 = a_3 = 0$.

$\Rightarrow T$ is 1-1.

$\Leftrightarrow N(T) = \{0\}$.

$\Leftrightarrow \text{rank}(T) = \dim(V)$, ($\dim(V) = \dim(W)$).

$\Leftrightarrow T$ is invertible.

(c) Yes, when $T\begin{pmatrix} a & b \\ c & d \end{pmatrix} = 0$, $a = b = c = d = 0$.

$\Rightarrow T$ is 1-1

$\Leftrightarrow N(T) = \{0\} \Leftrightarrow \text{rank}(T) = \dim(V)$, ($\dim(V) = \dim(W)$)

$\Leftrightarrow T$ is invertible.

6. Suppose T is invertible, and $U = T^{-1}$

there exist $y_1, y_2 \in W$.

then.

$$U(T(y_1)) = U(T(y_2))$$

$$\begin{array}{ccc} \parallel & & \parallel \\ U(T(y_1)) & & U(T(y_2)) \\ \parallel & = & \parallel \\ y_1 & = & y_2 \end{array} \quad (1-1)$$

$\forall y \in W, \exists x \in V, T(x) = y.$

let $x = U(y)$

$$T(U(y)) = I_W(y) = y. \quad (\text{onto}).$$

Suppose T is 1-1 and onto.

$\therefore 1-1$

$$\forall x \in V, UT(x) = U(T(x)) = U(y) = x.$$

$$\Rightarrow UT = I_V$$

\therefore onto.

$$\forall y \in W, TV(y) = T(U(y)) = T(x) = y.$$

$$\Rightarrow TV = I_W$$

$$\Rightarrow U = T^{-1}, \text{ it is invertible.}$$

7.

(S1) if S is a basis for $R(T)$.

it should be 1. generates $R(T)$,
2. linearly independent.

$$\text{and } R(T) = \text{span}(\{T(v_1), T(v_2), \dots, T(v_n)\}) \quad (\text{for } T(v_i) = 0, \text{ for } 1 \leq i \leq k) \\ = \text{span}(\{T(v_{k+1}), \dots, T(v_n)\}) = \text{span}(S)$$

$\Rightarrow S$ generates $R(T)$.

Next time please write clearly

\therefore By Theorem 2.2

(S2).

We want to prove S is L.I.

$$\Rightarrow b_{\bar{\lambda}} = 0, \text{ for } k+1 \leq \bar{\lambda} \leq n$$

$$\Rightarrow b_{k+1}v_{k+1} + b_{k+2}v_{k+2} + \dots + b_nv_n = 0.$$

So we use the fact that T is linear, and have

$$T\left(\sum_{\bar{\lambda}=k+1}^n b_{\bar{\lambda}}v_{\bar{\lambda}}\right) = 0. \text{ To prove } b_{\bar{\lambda}} = 0, \text{ for } k+1 \leq \bar{\lambda} \leq n.$$

(there is a condition that $T(0) = 0$.)

this is the answer.

-2

(S3).

because β is L.I.

prove is by S3

$$\Rightarrow a_1v_1 + a_2v_2 + \dots + a_kv_k + a_{k+1}v_{k+1} + \dots + a_nv_n = 0, \text{ for } a_1 = a_2 = \dots = a_n = 0$$

$$\sum_{\bar{\lambda}=k+1}^n b_{\bar{\lambda}}v_{\bar{\lambda}} = 0 = \sum_{\bar{\lambda}=1}^k c_{\bar{\lambda}}v_{\bar{\lambda}} \quad (\because \{v_1, \dots, v_k\} \text{ is a basis of } N(T), \text{ we can find } c_1, \dots, c_k \in F, \text{ st. } \sum_{\bar{\lambda}=1}^k c_{\bar{\lambda}}v_{\bar{\lambda}} = 0)$$

$$\Rightarrow \sum_{\bar{\lambda}=k+1}^n b_{\bar{\lambda}}v_{\bar{\lambda}} = \sum_{\bar{\lambda}=1}^k c_{\bar{\lambda}}v_{\bar{\lambda}}$$

$$\Rightarrow -c_1v_1 - c_2v_2 - \dots - c_kv_k + b_{k+1}v_{k+1} + \dots + b_nv_n = 0$$

$$= a_1v_1 + \dots + a_kv_k + \dots + a_nv_n = 0.$$

\Rightarrow we know that $b_{\bar{\lambda}} = 0, k+1 \leq \bar{\lambda} \leq n$.

8.

$$U(aT(x) + T(y))$$

(for U is linear, $U(x+y) = U(x) + U(y)$, $U(cx) = cU(x)$)

$$= U(aT(x)) + U(T(y))$$

$$= aU(T(x)) + U(T(y)).$$

(S1) 11.

$(aT+U)(cx+y)$, (for T, U are linearly)

$$= aT(cx+y) + U(cx+y)$$

9. -1

$$Q[T]_{\beta} = [T]_{\beta} Q$$

$$(Q^{-1})Q[T]_{\beta} = (Q^{-1})[T]_{\beta} Q$$

$$[T]_{\beta} = Q^{-1}[T]_{\beta} Q$$

How do you know Q is invertible

(S2)

for U is linearly

10.

(S1)

$$I_n = [I_V]_{\beta}$$

$$(for $I_V = T^{-1}T$)$$

$$= [T^{-1}T]_{\beta}$$

(By Thm 2.17 $\Rightarrow T^{-1}$ is linear)

(By Thm 2.11)

$$= [T^{-1}]_{\beta}^r [T]_{\beta}^r$$

(S2) it would to show that $B = [U]_{\beta}^r$

$$v_{\bar{j}} = A_{\bar{j}\bar{i}} \quad (\bar{i}=1, \dots, n)$$

$$U(w_{\bar{j}}) = \sum_{\bar{i}=1}^n (B_{\bar{i}\bar{j}} \cdot A_{\bar{j}\bar{i}}) \quad \text{for } \bar{j}=1, \dots, n.$$

為何可以乘上 A_{ji} ?

$$[U]_{\beta}^r = B$$