

Lecture 13: Principal components analysis (PCA)

Lecturer: Jie Fu

High-Dimensional Data

- High-Dimensions = Lot of Features

Surveys Netflix

	movie 1	movie 2	movie 3	movie 4	movie 5	movie 6
Tom	5	?	?	1	3	?
George	?	?	3	1	2	5
Susan	4	3	1	?	5	1
Beth	4	3	?	2	4	2

Food preference

	kale	taco bell	sashimi	pop tarts
Alice	10	1	2	7
Bob	7	2	1	10
Carolyn	2	9	7	3
Dave	3	6	10	2

-
- PCA: Unsupervised learning techniques to extract hidden dimensional structure from high dimensional dataset
 - Visualization
 - Efficient use of resources.
 - Statistical: lower dimension --> better generalization.
 - Further processing for other machine learning algorithm.

Motivating problem

- Friends' preferences of four different food choice.
- Dimension of data points: 4
- Number of data points: 4

Can we visualize the data in less than 4 dimension?

	kale	taco bell	sashimi	pop tarts
Alice	10	1	2	7
Bob	7	2	1	10
Carolyn	2	9	7	3
Dave	3	6	10	2

Table 1: Your friends' ratings of four different foods.

Motivating problem

- Each row of the data can be expressed approximately:

	kale	taco bell	sashimi	pop tarts
Alice	10	1	2	7
Bob	7	2	1	10
Carolyn	2	9	7	3
Dave	3	6	10	2

Table 1: Your friends' ratings of four different foods.

Name	(a_1, a_2)
Alice	$(1, 1)$
Bob	$(1, -1)$
Carolyn	$(-1, -1)$
Dave	$(-1, 1)$

Table 1: Values of (a_1, a_2) for each person

$$\bar{\mathbf{x}} + a_1 \mathbf{v}_1 + a_2 \mathbf{v}_2,$$

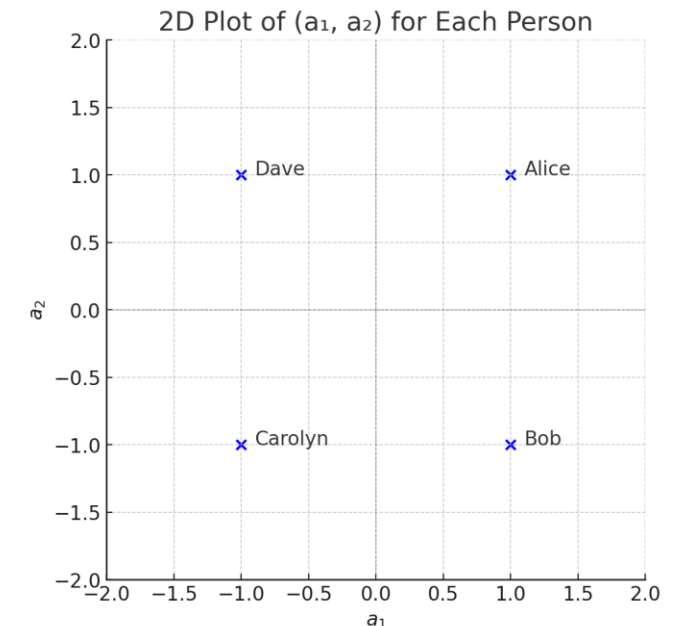
where

$$\bar{\mathbf{x}} = (5.5, 4.5, 5, 5.5)$$

is the average of the data points,

$$\mathbf{v}_1 = (3, -3, -3, 3),$$

$$\mathbf{v}_2 = (1, -1, 1, -1),$$



The role of PCA

- Reduce the dimensionality of data points (eg. 4 to 2):
- Given a list of m n -dimensional vectors (data points),

$$x_1, x_2, \dots, x_m \in R^n$$

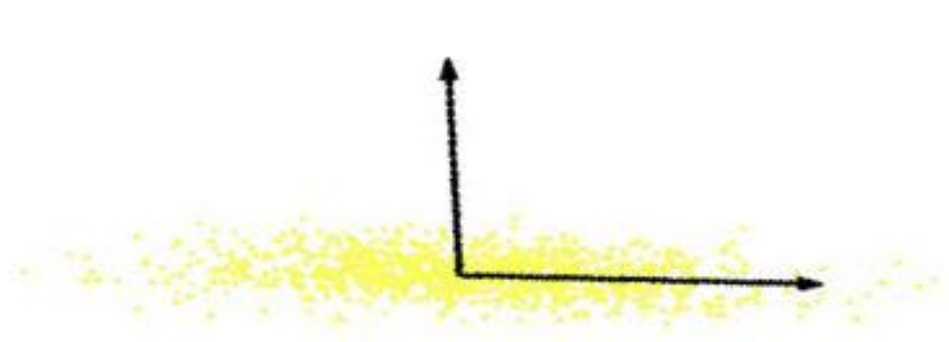
For each vector x_i , express it as linear combinations of k n -dimensional vectors $v_1, \dots, v_k \in R^n$ such that

$$x_i \approx \sum_{j=1}^k a_{ij} v_j$$

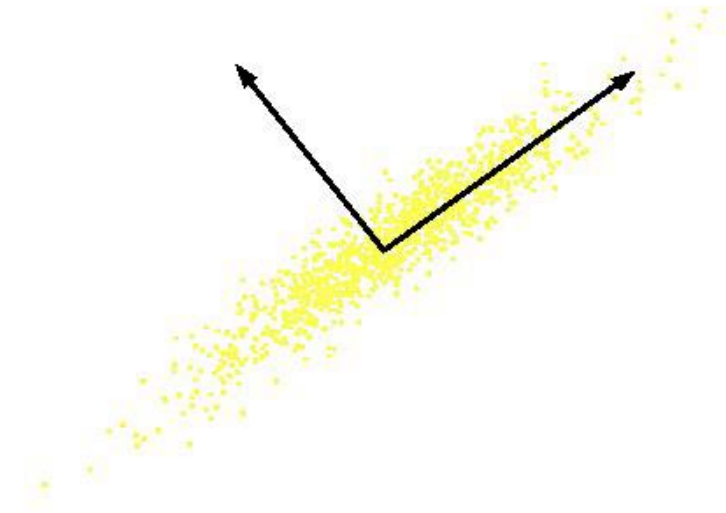
Dimension reduction: $n \rightarrow k$, which is smaller than n .

PCA

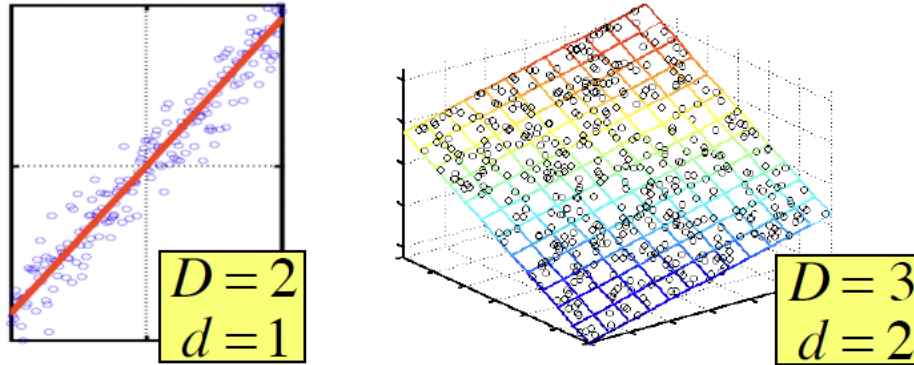
- PCA is an orthogonal projection or transformation of the data into a possible lower dimensional subspace so that **the variance of the projected data is maximized.**



Only one relevant feature



Both features are relevant, but

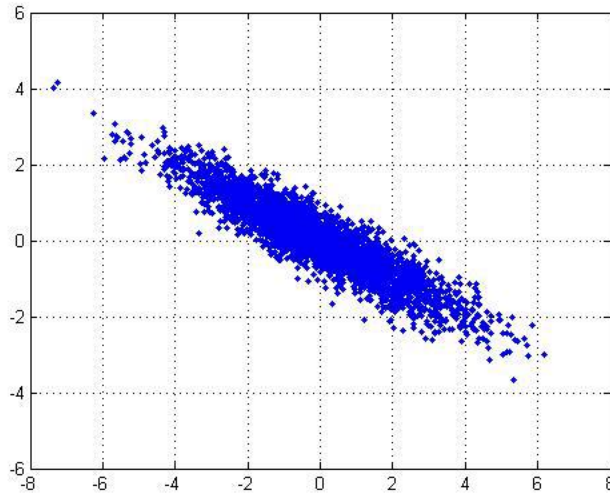


**Does the data mostly lie in a subspace?
If so, what is its dimensionality?**

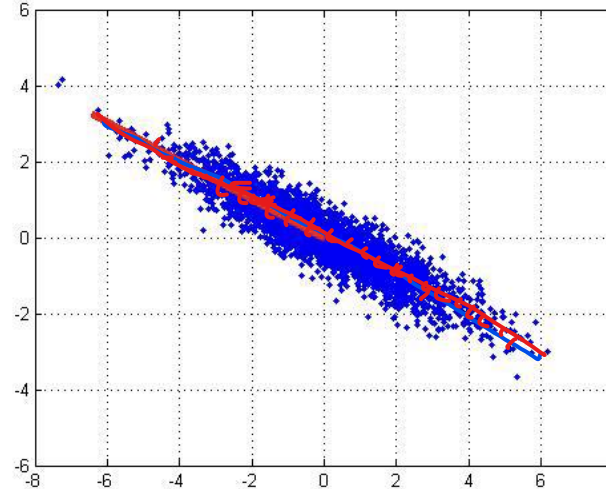
- The goal is to identify the axes or subspace the high-dimensional data should be projected into.

Maximize the variance

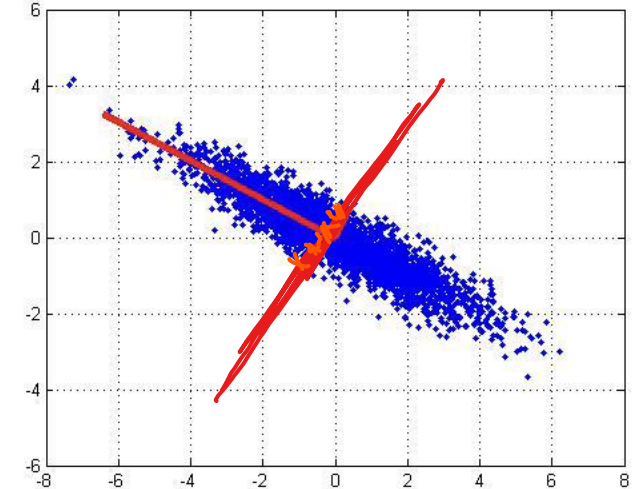
- Why maximize the variance of the projected data?



2D Gaussian dataset



1st principle component

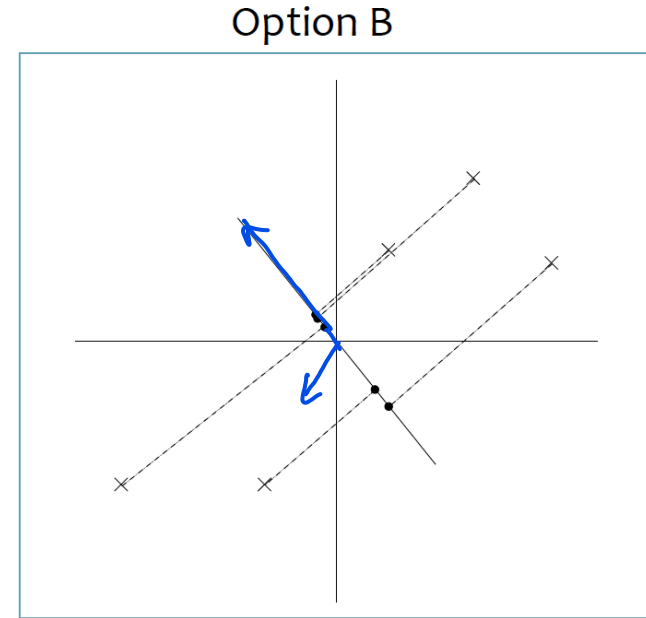
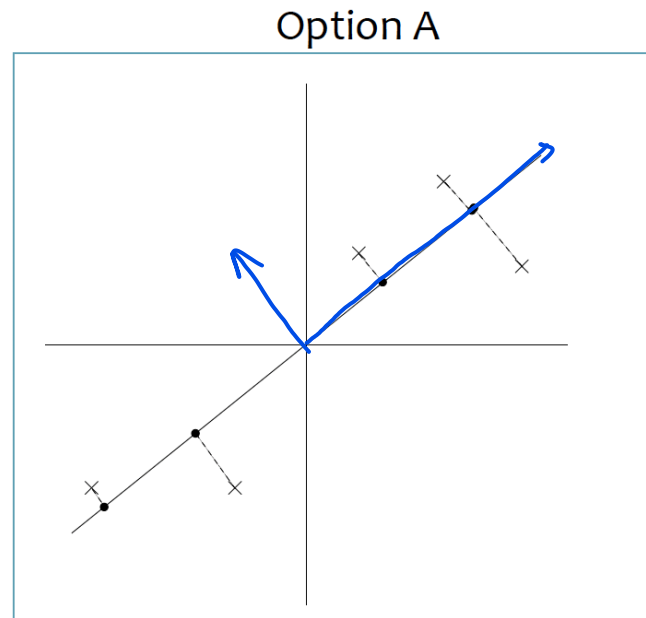


2nd principle component

Variance tells us how much information or “spread” a dataset has. In PCA, we assume directions with higher variance are more informative.

Maximize the variance

- Which of the two projections maximize the variance?



*Figures from Andrew Ng
(CS229 Lecture Notes)*

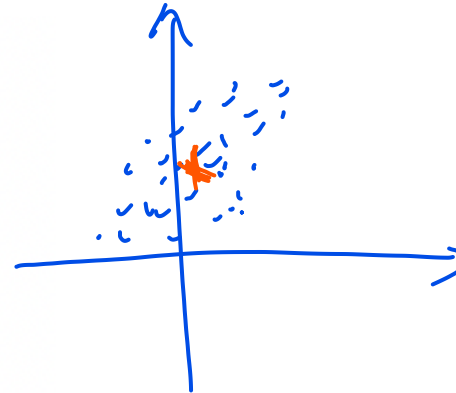
Maximize the variance

We want to find new axes (directions) to project our data such that:

- The projected data has **maximum variance**.
- The new features (called principal components) are **uncorrelated**.

	kale	taco bell	sashimi	pop tarts
Alice	10	1	2	7
Bob	7	2	1	10
Carolyn	2	9	7	3
Dave	3	6	10	2

Table 1: Your friends' ratings of four different foods.



Step 1: center the data matrix

Step 2: compute the covariance matrix of the centered data

Step 3: select top k principal components/features

Step 1 and step 2

- Center the data

$$\underline{X_c} = \underline{X} - \underline{\bar{X}}$$

- Example:

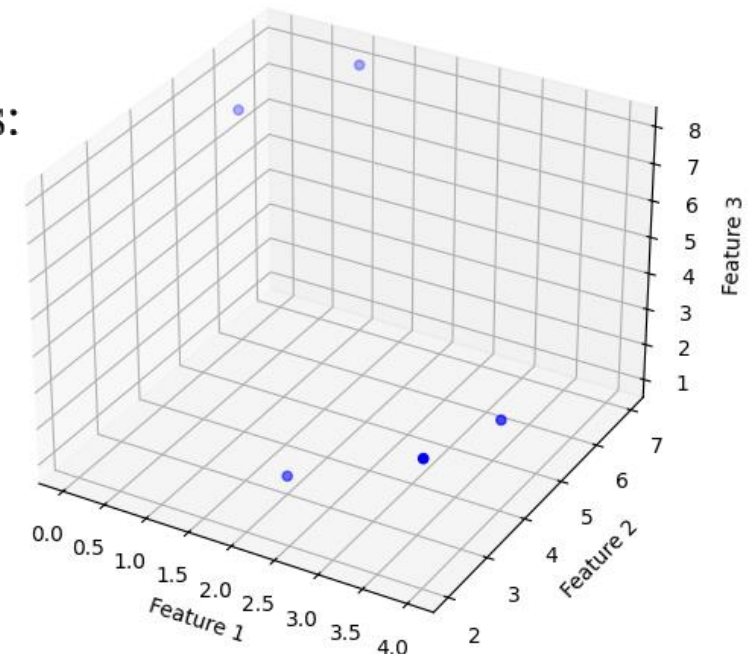
Consider the following dataset with 5 samples and 3 features:

$$X = \begin{bmatrix} 2 & 3 & 1 \\ 4 & 2 & 4 \\ 4 & 4 & 3 \\ 0 & 6 & 7 \\ 1 & 7 & 8 \end{bmatrix}$$

feature 1 2 3
↓ ↓ ↓
mean 2.2 4.4 4.6

Mean of each feature

3D Scatter Plot

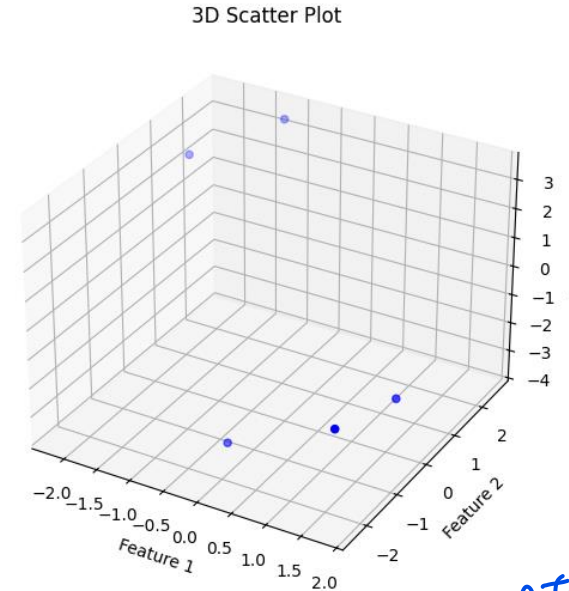


- Centered data matrix

$$X_c = \begin{bmatrix} -0.2 & -1.4 & -3.6 \\ 1.8 & -2.4 & -0.6 \\ 1.8 & -0.4 & -1.6 \\ -2.2 & 1.6 & 2.4 \\ -1.2 & 2.6 & 3.4 \end{bmatrix}$$

Step 2: compute the covariance matrix of the centered data (use the transposed.)

`np.cov(M_c.T)`



Covariance matrix after rotation $\leftarrow K = U \Lambda U^{-1}$

$$\Lambda = \begin{bmatrix} \lambda_1 & 0 & 0 \\ 0 & \lambda_2 & 0 \\ 0 & 0 & \lambda_3 \end{bmatrix}$$

The covariance matrix K is given by:

$$K = \frac{1}{n-1} X_c^T X_c$$

var(X_i)

Cov(X_2, X_1)

Cov(X_1, X_2)

$$\begin{bmatrix} 3.2 & -2.85 & -3.15 \\ -2.85 & 4.3 & 4.95 \\ -3.15 & 4.95 & 8.3 \end{bmatrix}$$

Eigenvalue and eigenvectors of a matrix

Let A be a $n \times n$ matrix.

$$A = \begin{bmatrix} 5 & 0 \\ 0 & 10 \end{bmatrix} \quad ? \quad A \vec{x} = \lambda \cdot \vec{x}$$

$$\begin{bmatrix} 5 & 0 \\ 0 & 10 \end{bmatrix} \cdot \begin{bmatrix} c \\ 0 \end{bmatrix} = 5 \cdot \begin{bmatrix} c \\ 0 \end{bmatrix}$$

- $\vec{x} \neq 0$ is an *eigenvector* of A if there is a scalar λ such that

$$\underset{\Delta^-}{A} \underset{\Delta^-}{\vec{x}} = \underset{\Delta^-}{\lambda} \underset{\Delta^-}{\vec{x}}$$

$$\begin{cases} 5x_1 + 0 \cdot x_2 = \lambda x_1 \\ 0 \cdot x_1 + 10 \cdot x_2 = \lambda x_2 \end{cases}$$

- the corresponding λ is called the *eigenvalue*.

$$\lambda = 5: \quad 10x_2 = 5x_2$$

$$\Downarrow x_2 = 0$$

$$\lambda = 10: \quad x_1 = 0$$

$$\begin{bmatrix} 0 \\ c_2 \end{bmatrix}$$

- Example: find the eigenvalue and eigenvector of A .

$$A = \begin{bmatrix} 4 & 2 \\ 1 & 3 \end{bmatrix}$$

Eigenvalue and eigenvectors of a matrix

$$Ax = \lambda x \Rightarrow (A - \lambda I)x = 0$$

λ be selected such that

$$\det(A - \lambda I) = 0$$

Eigenvalue and eigenvectors of a matrix

Diagonalizable Matrices

A $n \times n$ matrix with n linearly independent eigenvectors is said to be **diagonalizable**.

$$\begin{aligned} A \mathbf{u}_1 &= \lambda_1 \mathbf{u}_1, \\ A \mathbf{u}_2 &= \lambda_2 \mathbf{u}_2, \\ &\dots \\ A \mathbf{u}_n &= \lambda_n \mathbf{u}_n, \end{aligned}$$

$$\left[\begin{array}{c} \left[\right] \\ \mathbf{u}_1 \end{array} \quad \begin{array}{c} \left[\right] \\ \mathbf{u}_2 \end{array} \quad \dots \quad \begin{array}{c} \left[\right] \\ \mathbf{u}_n \end{array} \right]$$

In matrix form:

$$A \underbrace{(\mathbf{u}_1 \quad \dots \quad \mathbf{u}_n)}_{\mathbf{U}} = (\lambda_1 \mathbf{u}_1 \quad \dots \quad \lambda_n \mathbf{u}_n) = (\mathbf{u}_1 \quad \dots \quad \mathbf{u}_n) \underbrace{\begin{pmatrix} \lambda_1 & 0 & 0 \\ 0 & \ddots & 0 \\ 0 & 0 & \lambda_n \end{pmatrix}}_{\mathbf{D}}$$

This corresponds to a similarity transformation

$$AU = UD \Leftrightarrow A = \underbrace{UDU^{-1}}$$

PCA and eigen-decomposition of covariance matrix.

- Covariance matrix:

$$K[i, j] = \text{cov}(X_i - \bar{X}_i, X_j - \bar{X}_j)$$

\nearrow mean i \nearrow mean j

Property of covariance matrix:

$$K = U \Lambda U^T$$

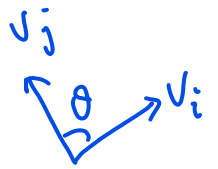
\nearrow diagonal matrix.

- It is symmetric \rightarrow for symmetric matrix, eigenvectors for distinct eigenvalues are orthogonal.

$$U = [v_1 \ v_2 \ \dots \ v_n]$$

any i, j

v_i, v_j are orthogonal.



$$\theta = \pm \frac{\pi}{2} : v_i \cdot v_j = v_i^T v_j = 0$$

- It is real: \rightarrow All eigenvalues of a real symmetric matrix are real.

\rightarrow $\text{linalg. eig}(A)$

orthonormal vectors

v_i, v_j $\|v_i\| = 1$

eg. $v_1 = \begin{bmatrix} 10 \\ 0 \end{bmatrix}$ $v_2 = \begin{bmatrix} 0 \\ 5 \end{bmatrix}$

$\downarrow \frac{v}{\|v\|}$

$v_1' = \begin{bmatrix} 1 \\ 0 \end{bmatrix}$ $v_2' = \begin{bmatrix} 0 \\ 1 \end{bmatrix}$

PCA and eigen-decomposition of covariance matrix.

- Eigen-decomposition of covariance matrix

$$K = U\Lambda U^{-1}$$

↓ diagonal

cov after coordinate transform

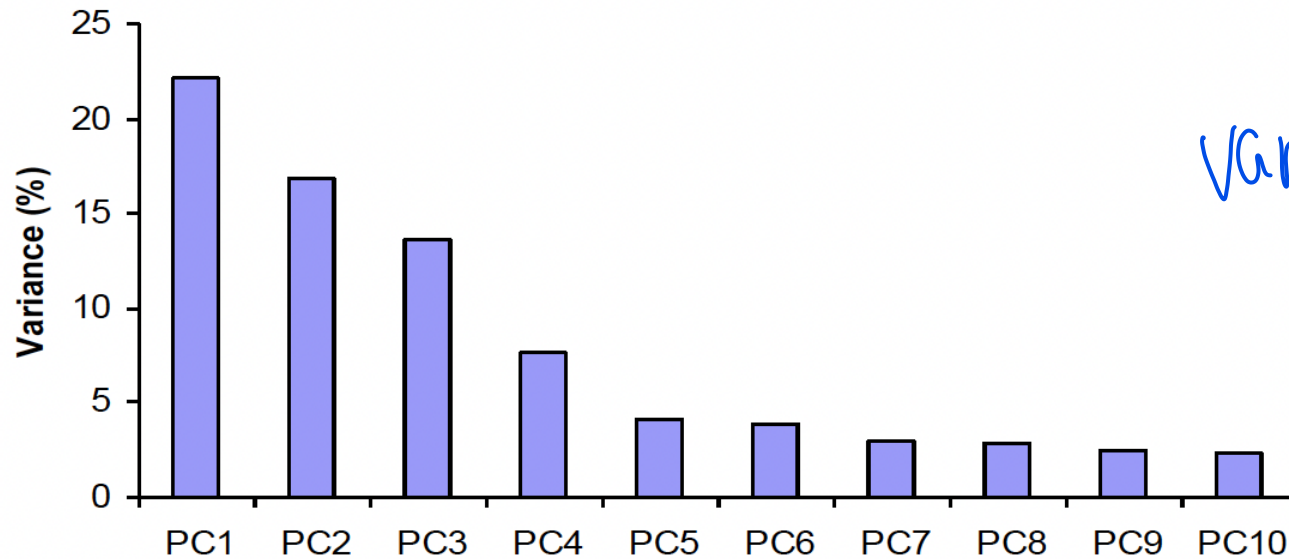
$$\begin{bmatrix} \lambda_1 & 0 \\ 0 & \ddots \\ 0 & & \lambda_n \end{bmatrix}$$

$$K = U\Lambda U^{-1}$$

- Columns of U are *eigenvectors* of K .
- Diagonal matrix Λ are eigenvalues of K , ordered in the order of eigenvectors.

$$\Lambda = \text{diag}(\lambda_1, \lambda_2, \dots, \lambda_n)$$

- We order these eigenvectors in an order of the values of eigenvalues and called these: 1st principal component, 2nd principal component, etc.
- Where does dimensionality reduction come from?
 - Can ignore the **components of lesser significance**.



$\lambda_1 \dots \lambda_n$

↓

Variance of features
after transform

Example

The covariance matrix K is given by:

$$\underline{X_c = X - \bar{X}} \rightarrow \overline{f}(X_c) = 0$$

$$K = \frac{1}{n-1} X_c^T X_c$$

$$X_c: \begin{matrix} t^1 & t^2 & t^3 \\ \textcircled{1} \\ \textcircled{2} \\ \textcircled{3} \\ \textcircled{4} \\ \textcircled{5} \end{matrix}$$

$$\begin{bmatrix} 3.2 & -2.85 & -3.15 \\ -2.85 & 4.3 & 4.95 \\ -3.15 & 4.95 & 8.3 \end{bmatrix}$$

eigenvalues, eigenvectors = LA.eig(K)

$$\begin{bmatrix} 13.38070762 & 1.82004592 & 0.59924646 \end{bmatrix}$$

$$\begin{bmatrix} -0.38263617 & 0.77297413 & -0.50606379 \\ 0.53188845 & -0.26357343 & -0.80475072 \\ 0.75543646 & 0.57709622 & 0.31028329 \end{bmatrix}$$

- Project the Data onto the Principal Components: $\text{proj}_{\vec{v}} \vec{x} = \frac{\vec{x} \cdot \vec{v}}{\|\vec{v}\|} \cdot \frac{\vec{v}}{\|\vec{v}\|} = (\vec{x} \cdot \vec{v}) \cdot \underbrace{\frac{\vec{v}}{\|\vec{v}\|}}_{\text{normalization}}$
- If we want 2D dimension, project each **centered** data point into the first two pc:

$$X_c = \begin{bmatrix} \textcircled{1} & -0.2 & -1.4 & -3.6 \\ \textcircled{2} & 1.8 & -2.4 & -0.6 \\ \textcircled{3} & 1.8 & -0.4 & -1.6 \\ \textcircled{4} & -2.2 & 1.6 & 2.4 \\ \textcircled{5} & -1.2 & 2.6 & 3.4 \end{bmatrix}$$

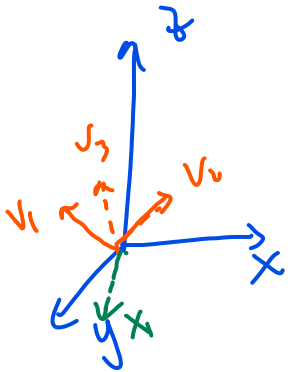
$$\text{proj}_{\vec{v}_1} \vec{v}_2 = \frac{\vec{v}_2 \cdot \vec{v}_1}{\|\vec{v}_1\|} \cdot \vec{v}_1$$

$$\begin{bmatrix} -0.38263617 & 0.77297413 & -0.50606379 \\ 0.53188845 & -0.26357343 & -0.80475072 \\ 0.75543646 & 0.57709622 & 0.31028329 \end{bmatrix}$$

$\underbrace{\hspace{1.5cm}}_{\vec{v}_1} \quad \underbrace{\hspace{1.5cm}}_{\vec{v}_2} \quad \underbrace{\hspace{1.5cm}}_{\vec{v}_3}$

$$\vec{X}_1 = a_1 \vec{v}_1 + a_2 \vec{v}_2 + a_3 \vec{v}_3$$

$$\begin{aligned} \text{proj}_{\vec{v}_1} \vec{X}_1 &= \text{proj}_{\vec{v}_1} (a_1 \vec{v}_1 + a_2 \vec{v}_2 + a_3 \vec{v}_3) = a_1 \text{proj}_{\vec{v}_1} \vec{v}_1 + a_2 \text{proj}_{\vec{v}_1} \vec{v}_2 + a_3 \text{proj}_{\vec{v}_1} \vec{v}_3 \\ &= a_1 \cdot \underbrace{(\vec{v}_1 \cdot \vec{v}_1)}_{\cancel{1}} \cdot \underbrace{\frac{\vec{v}_1}{\|\vec{v}_1\|}}_{\cancel{1}} + a_2 \cdot 0 + a_3 \cdot 0 = a_1 \vec{v}_1 \end{aligned}$$



$$a_i \vec{v_i} = \text{proj}_{\vec{v_i}} X_k$$

v_i : eigenvector (normalized)
orthogonal.

$$X = \sum_{i=1}^n a_i \vec{v_i}$$

n - features

$$\tilde{X} = \sum_{i=1}^K a_i \vec{v_i}$$

$$K < n$$

$$\left. \begin{array}{l} X = \sum_{i=1}^n a_i \vec{v_i} \\ n - \text{features} \end{array} \right\} X - \tilde{X} = \sum_{i=K+1}^n a_i \vec{v_i}$$