

# differential-equations

Following the tutorial from:

Differential Equations in R Part 1: Representing Basic Dynamics

<https://www.youtube.com/watch?v=1iNXQypailI>

Differential Equations in R Part 2: Solving Lotka-Volterra Predation Equations

<https://www.youtube.com/watch?v=lJqiasw7OPs>

Note: I fixed a few mistakes with the functions where it was using more global scope than I wanted.

Install the library deSolve from Packages -> Install

Use the library deSolve and lattice

```
library(deSolve)
library(lattice)
```

Solving the continous equation

$$\frac{dN}{dt} = rN$$

Create a function

```
cgrowth <- function(times, y, parms) {
  r <- parms[1]
  N <- y[1]
  dN.dt <- r * N
  return(list(dN.dt))
}

p <- c(p=0.5)
y0 <- c(N=2)
t <- 0:20

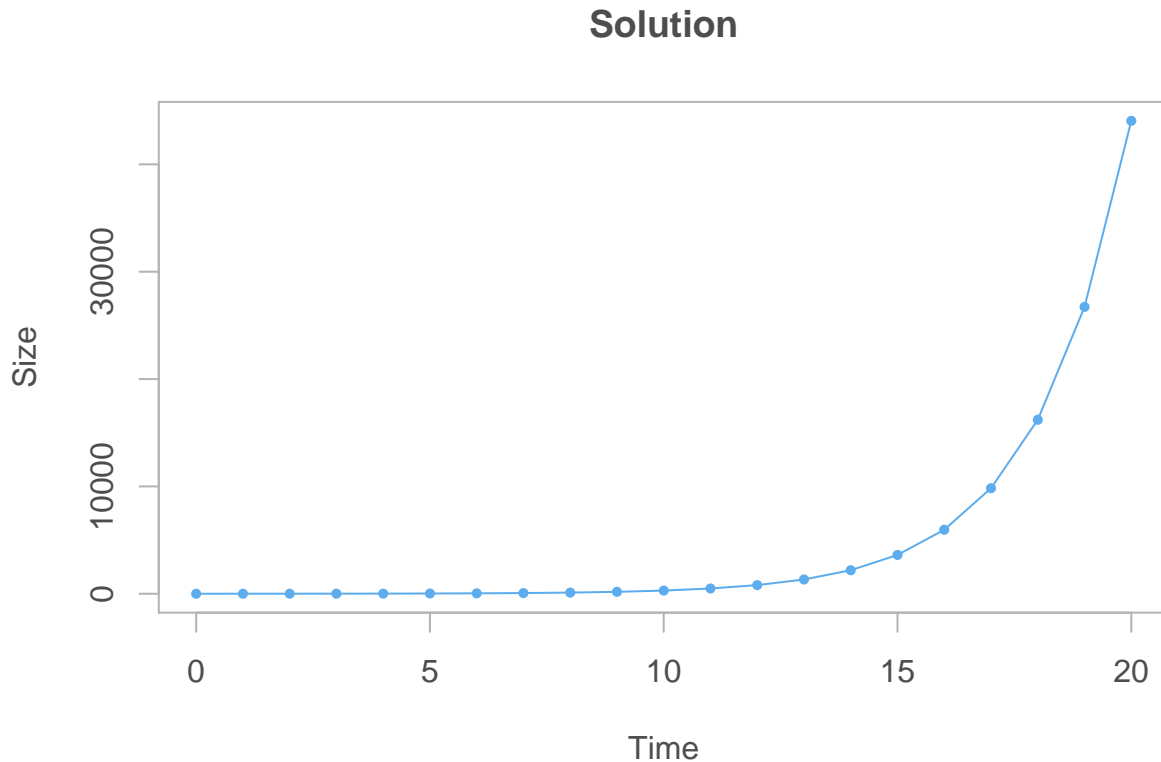
sol <- ode(y = y0, times = t, func = cgrowth, parms = p)
sol
```

##	time	N
## 1	0	2.000000
## 2	1	3.297445
## 3	2	5.436572
## 4	3	8.963395
## 5	4	14.778153
## 6	5	24.365058
## 7	6	40.171205
## 8	7	66.231149
## 9	8	109.196755
## 10	9	180.035094
## 11	10	296.827805
## 12	11	489.386525
## 13	12	806.862352
## 14	13	1330.291724
## 15	14	2193.281112
## 16	15	3616.110779

```
## 17 16 5961.961552
## 18 17 9829.617263
## 19 18 16206.305348
## 20 19 26719.691878
## 21 20 44053.345008
```

Plotting it would be

```
plot(sol, type='o', xlab="Time", ylab="Size", main="Solution",
     pch=16, cex=0.7, fg="grey70", col="steelblue2", col.axis="grey30",
     col.lab="grey30", col.main="grey30")
```



Solving a continuous time logistic equation numerically

$$\frac{dN}{dt} = rN\left(1 - \frac{N}{K}\right)$$

```
clogistic <- function(times, y, parms) {
  r <- parms[1]
  K <- parms[2]
  N <- y[1]
  dN.dt <- r * N * (1 - (N / K))
  return(list(dN.dt))
}

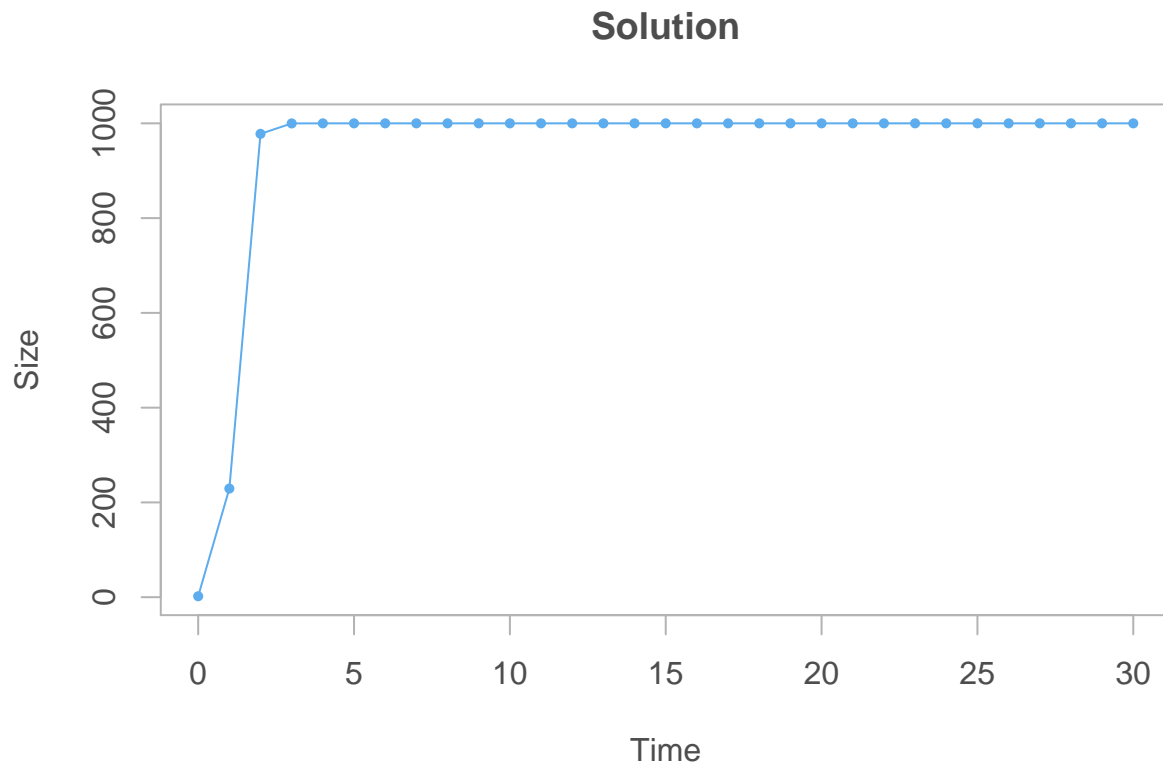
p <- c(r=5, K=1000)
y0 <- c(N=2)
t <- 0:30

sol2 <- ode(y = y0, times = t, func = clogistic, parms = p)
sol2
```

##	time	N
## 1	0	2.0000
## 2	1	229.2406
## 3	2	977.8473
## 4	3	999.8474
## 5	4	999.9990
## 6	5	1000.0000
## 7	6	1000.0000
## 8	7	1000.0000
## 9	8	1000.0000
## 10	9	1000.0000
## 11	10	1000.0000
## 12	11	1000.0000
## 13	12	1000.0000
## 14	13	1000.0000
## 15	14	1000.0000
## 16	15	1000.0000
## 17	16	1000.0000
## 18	17	1000.0000
## 19	18	1000.0000
## 20	19	1000.0000
## 21	20	1000.0000
## 22	21	1000.0000
## 23	22	1000.0000
## 24	23	1000.0000
## 25	24	1000.0000
## 26	25	1000.0000
## 27	26	1000.0000
## 28	27	1000.0000
## 29	28	1000.0000
## 30	29	1000.0000
## 31	30	1000.0000

Plotting it would be

```
plot(sol2, type='o', xlab="Time", ylab="Size", main="Solution",
     pch=16, cex=0.7, fg="grey70", col="steelblue2", col.axis="grey30",
     col.lab="grey30", col.main="grey30")
```



Lotka-Volterra Predation Equations (Coupled Differential Equations)

$$\frac{dN}{dt} = rN - aPN$$

$$\frac{dP}{dt} = -bP + fPN$$

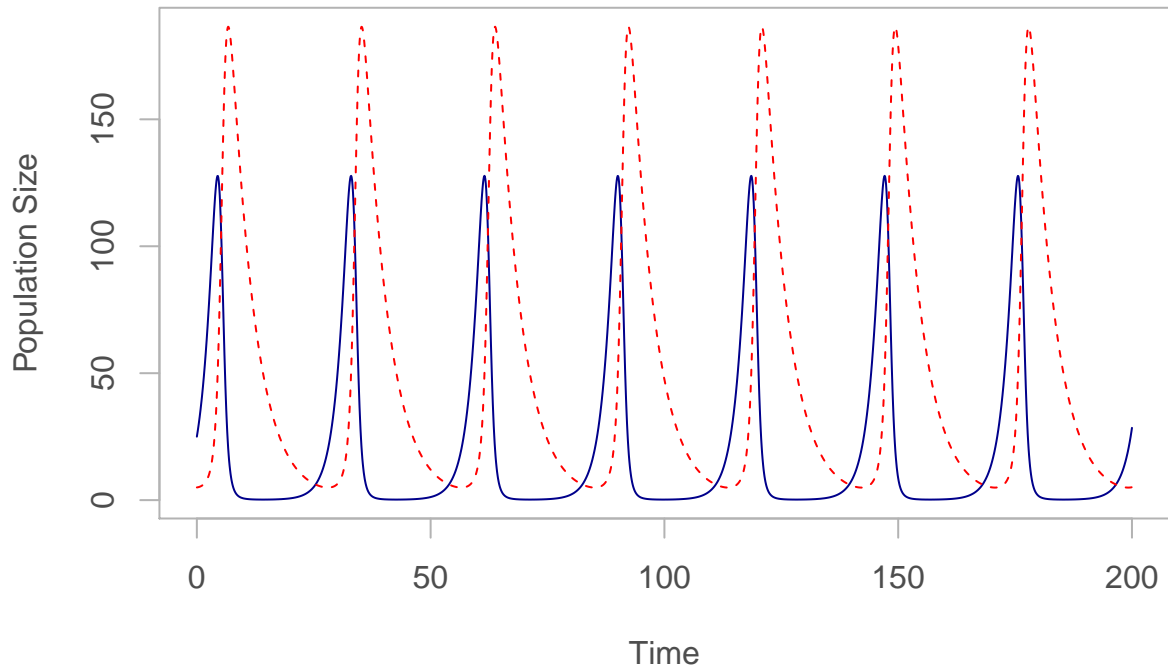
I use the `with` and `as.list` as short hands to not have to unbox/deconstruct variables

```
predpreyLV <- function(t, y, p) {
  with(c(as.list(y), as.list(p)), {
    dNdt <- r * N - a * P * N
    dPdt <- -b * P + f * P * N
    return(list(c(dNdt, dPdt)))
  })
}

r <- 0.50
a <- 0.01
f <- 0.01
b <- 0.20

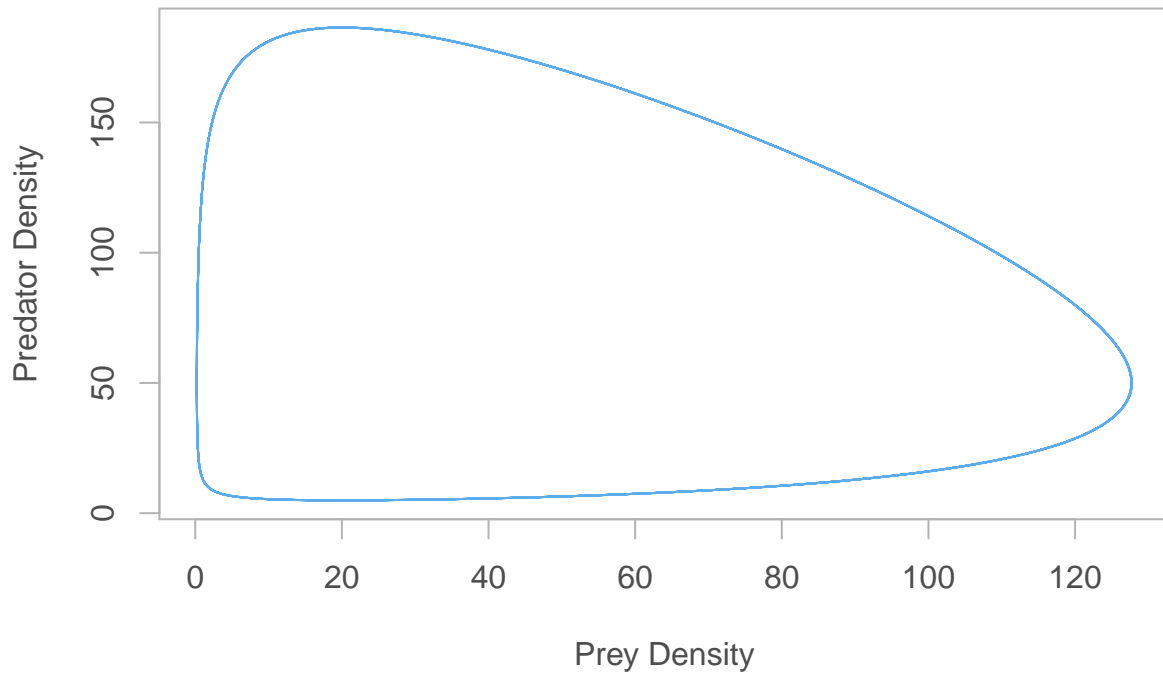
p <- c(r=r, a=a, b=b, f=f)
y0 <- c(N=25, P=5)
times <- seq(0, 200, 0.1)
LV.out <- ode(y = y0, times, predpreyLV, p)

matplot(LV.out[,1], (LV.out[,2:3]), type="l", xlab="Time",
        ylab="Population Size", fg="grey70", col=c("darkblue", "red"),
        col.axis="grey30", col.lab="grey30", col.main="grey30")
```



In phase space it would be

```
plot(LV.out[,2], LV.out[,3], type="l", xlab="Prey Density",
     ylab="Predator Density", fg="grey70", col="steelblue2",
     col.axis="grey30", col.lab="grey30", col.main="grey30")
```



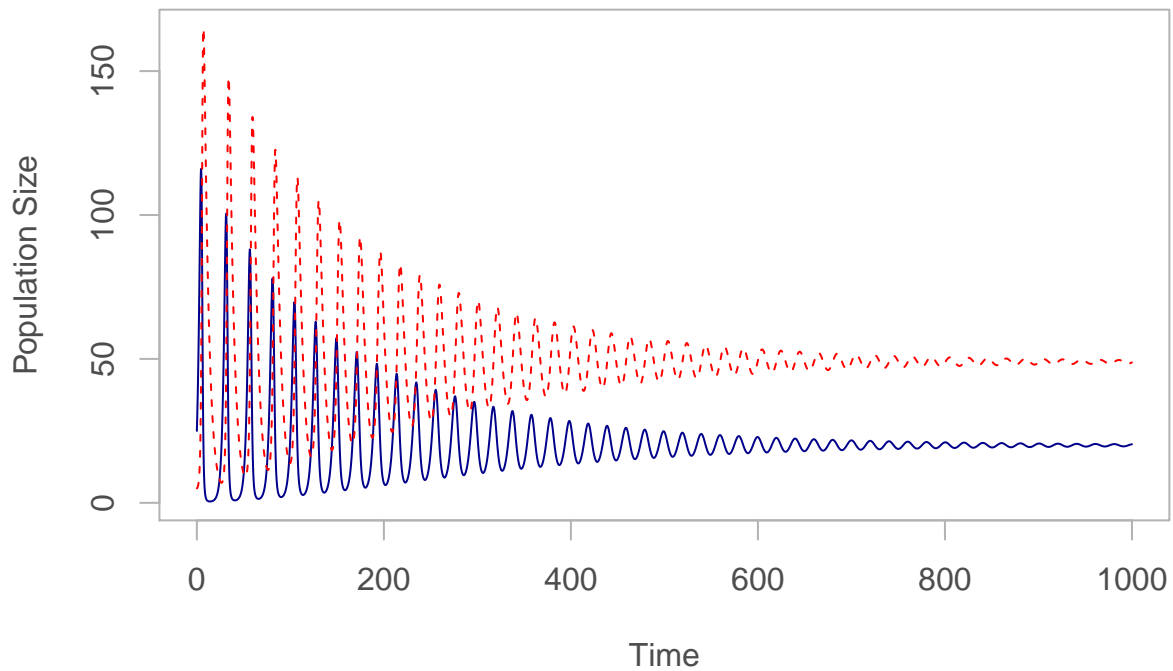
Making it more realistic by adding a carryig capacity to prey density

$$\frac{dN}{dt} = rN\left[1 - \left(\frac{N}{K}\right)\right] - aPN$$

$$\frac{dP}{dt} = -bP + fPN$$

Numerically in R that would be

```
predpreyCarryingLV <- function(t, y, p) {  
  with(c(as.list(y), as.list(p)), {  
    dNdt <- r * N * (1 - (N / K)) - a * P * N  
    dPdt <- -b * P + f * P * N  
    return(list(c(dNdt, dPdt)))  
  })  
}  
  
r <- 0.50  
a <- 0.01  
f <- 0.01  
b <- 0.20  
K <- 1000  
  
p <- c(r=r, a=a, b=b, f=f, K=K)  
y0 <- c(N=25, P=5)  
times <- seq(0, 1000, 0.1)  
LV.out <- ode(y = y0, times, predpreyCarryingLV, p)  
  
matplot(LV.out[,1], (LV.out[,2:3]), type="l", xlab="Time",  
        ylab="Population Size", fg="grey70", col=c("darkblue", "red"),  
        col.axis="grey30", col.lab="grey30", col.main="grey30")
```



As a phase diagram it would be

```
plot(LV.out[,2], LV.out[,3], type="l", xlab="Prey Density",  
     ylab="Predator Density", fg="grey70", col="steelblue2",  
     col.axis="grey30", col.lab="grey30", col.main="grey30")
```

