Frank Hsu

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Summary

I am now studying electrical engineering in UNSW and my course division is system and control. I am interested in implementing control theory in real world such as motor speed control and water level control. I also spend time on embedded system and coding which are important for realizing control algorithm with digital controller.

Education

02.2021 – Present	The University of New South Wales	Sydney, Australia
	Master of electrical engineering	
09.2014 - 06.2018	National Tsing Hua University	Hsinchu, Taiwan
	Bachelor of Science in Power Mechanical Engineering	

Work Experience

06.2019 – 10.2020 Academia Sinica (Institute of Physics)

Taipei, Taiwan

Research Assistant

- Design X ray tomography light path system including CAD design and manufacturing.
- Build communication UI on PC to send and receive signal of a robot controller (With RS-232)
- Design robot path planning for replacing experiment samples.

05.16.2022 - 05.28.2022

Academia Sinica (Institute of Information Scienece)

Project Experience

09.2017 – 01.2018 **Self-Driving Vehicle**

National Tsing Hua University

- Integrate motor control, computer vision and Bluetooth communication, based on ROS.
- Implement digital PI control algorithm development.
- Build coordinate system based on Apriltag

01.2017 – 06.2018 NTHU Racing Team

National Tsing Hua University

A team for building a race car and participating Formula Student competition in Japan.

- Lead steering system group to design and manufacture steering system hardware.
- Design battery management circuit (BMS) for low voltage system. Controls charging and discharging operation of a battery pack (Using four 21700 in series).
- Use Altium designer to produce schematic and PCB layout file.

06.2021 - 08.2021 **OV7670 camera with STM32**

- I2C communication between camera and the microcontroller.
- DCMI programming.
- Direct Memory Access (DMA) programming.

Skills

Programming

C, Python

Software & OS

Altium designer, Solidworks, Matlab, Git, Linux ubuntu, ROS

Hardware

STM32