



Introduction to Algorithms

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Recursion algorithm

&

divide-and-conquer



Recursion

- **Recursion** occurs when a thing is defined in terms of itself or of its type. Recursion is used in a variety of disciplines ranging from linguistics to logic.
- The most common application of **recursion** is in mathematics and computer science, where a function being defined is applied within its own definition. While this apparently defines an infinite number of instances (function values), it is often done in such a way that no loop or infinite chain of references can occur.



Formal definitions

In mathematics and computer science, a class of objects or methods exhibit recursive behavior when they can be defined by two properties:

1. A simple base case (or cases)—a terminating scenario that does not use recursion to produce an answer
 2. A set of rules that reduce all other cases toward the base case
- For example, the following is a recursive definition of a person's ancestors:
 - One's parents are one's ancestors (base case).
 - The ancestors of one's ancestors are also one's ancestors (recursion step).



- Substitution method
- 1. Guess the form of the solution.
- 2. Verify by induction.
- 3. Solve for constants.
- The most general method:
- Example: $T(n) = 4T(n/2) + n$
- [Assume that $T(1) = \Theta(1)$.] •
- Guess $O(n^3)$. (Prove O and Ω separately.)
- Assume that $T(k) \leq ck^3$ for $k < n$.
- Prove $T(n) \leq cn^3$ by induction



The Fibonacci sequence

Fibonacci numbers

Recursive definition:

$$F_n = \begin{cases} 0 & \text{if } n = 0; \\ 1 & \text{if } n = 1; \\ F_{n-1} + F_{n-2} & \text{if } n \geq 2. \end{cases}$$

0 1 1 2 3 5 8 13 21 34 ...

Naive recursive algorithm: $\Omega(\phi^n)$
(exponential time), where $\phi = (1 + \sqrt{5})/2$
is the **golden ratio**.



The Fibonacci sequence

- The Fibonacci sequence is a classic example of recursion:

$$F(n) = \begin{cases} 1 & n=0 \\ 1 & n=1 \\ F(n-1) + F(n-2) & n>1 \end{cases}$$

- $Fib(0) = 0$ as base case 1,
- $Fib(1) = 1$ as base case 2,
- For all integers $n > 1$, $Fib(n) := Fib(n-1) + Fib(n-2)$. {For all integers $n \geq 1$ }
- Many mathematical axioms are based upon recursive rules. For example, the formal definition of the natural numbers by the Peano axioms can be described as: 0 is a natural number, and each natural number has a successor, which is also a natural number. By this base case and recursive rule, one can generate the set of all natural numbers.
- Recursively defined mathematical objects include functions, sets, and especially fractals.



Example The Fibonacci sequence

无穷数列1, 1, 2, 3, 5, 8, 13, 21, 34, 55, ……, 称为 Fibonacci 数列。它可以递归地定义为：

$$F(n) = \begin{cases} 1 & n=0 \\ 1 & n=1 \\ F(n-1) + F(n-2) & n>1 \end{cases}$$

边界条件

递归方程

□第n个Fibonacci数可递归地计算如下：

```
int fibonacci(int n)
{
    if (n <= 1) return 1;
    return fibonacci(n-1)+fibonacci(n-2);
}
```

8



[java] view plain copy

```
public class Fibonacci {
    static void main(String[] args) {
        Fibonacci fibonacci=new Fibonacci();
        int result=fibonacci.fib(5);
        System.out.println(result);
    }

    public int fib(int index){
        if(index==1||index==2){
            return 1;
        }else{
            return fib(index-1)+fib(index-2);
        }
    }
}
```



Recursion (computer science)

- A common method of simplification is to divide a problem into subproblems of the same type.
- As a computer programming technique, this is called **divide and conquer** and is key to the design of many important algorithms.
- Divide and conquer** serves as a top-down approach to problem solving, where problems are solved by solving smaller and smaller instances.
- A contrary approach is dynamic programming.
- This approach serves as a bottom-up approach, where problems are solved by solving larger and larger instances, until the desired size is reached.



Recursion (computer science)

- A classic example of recursion is the definition of the factorial function, given here in C code:

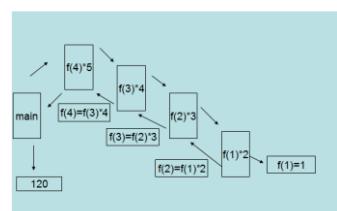
```
unsigned int factorial(unsigned int n) {
    if (n == 0) {
        return 1;
    } else {
        return n * factorial(n - 1);
    }
}
```



Recursion----n!

```
function fib(n)
    if n <= 1 return n
    return fib(n-1) + fib(n-2)
```

```
5!=?
description:递归求n的阶乘
result=factorial_Five.factorial(5);
public int factorial(int index){
    if(index==1){
        return 1;
    }else{
        return
factorial(index-1)*index;
    }
}
```





5!=?

```
function fib(n)
    if n <= 1 return n
    return fib(n - 1) + fib(n - 2)
```

- Notice that if we call, say, fib(5), we produce a call tree that calls the function on the same value many different times:
 - 1.fib(5)
 - 2.fib(4) + fib(3)
 - 3.(fib(3) + fib(2)) + (fib(2) + fib(1))
 - 4.((fib(2) + fib(1)) + (fib(1) + fib(0))) + ((fib(1) + fib(0)) + fib(1))
 - 5.(((fib(1) + fib(0)) + fib(1)) + (fib(1) + fib(0))) + ((fib(1) + fib(0)) + fib(1))



- This technique of saving values that have already been calculated is called memoization; this is the top-down approach, since we **first break the problem into subproblems** and then calculate and store values.

- In the bottom-up approach, we calculate the smaller values of fib first, then build larger values from them. This method also uses $O(n)$ time since it contains a loop that repeats $n - 1$ times, but it only takes constant ($O(1)$) space, in contrast to the top-down approach which requires $O(n)$ space to store the map.



- In both examples, we only calculate fib(2) one time, and then use it to calculate both fib(4) and fib(3), instead of computing it every time either of them is evaluated.
- Note that the above method actually takes $\Omega(n^2)$ (n^2) time for large n because addition of two integers with $\Omega(n)$ bits each takes $\Omega(n)$ time.



- Also, there is a closed form for the Fibonacci sequence, known as Binet's formula, from which the n -th term can be computed in approximately $O(\log n)^2$ ($O(n(\log n)^2)$) time, which is more efficient than the above dynamic programming technique.
- However, the simple recurrence directly gives the matrix form that leads to an approximately $O(n \log n)$ ($O(n \log n)$) algorithm by fast matrix exponentiation.



例：假设 $S(n)$ 是前 n 个整数的和，那么 $S(1) = 1$ ，并且我们可以将 $S(n)$ 写成 $S(n) = S(n-1) + n$ 。

根据递归公式，我们可以得到对应的递归函数：

int S(int n) //求前n个整数的和

```
{
    if (n == 1)
        return 1;
    else
        return S(n-1) + n;
}
```

流程图

函数由递归公式得到，应该是好理解的，要想求出 $S(n)$ ，得先求出 $S(n-1)$ ，递归终止的条件（递归出口）是 ($n == 1$)。



前例中的函数都可以找到相应的非递归方式定义：

$$n! = 1 \cdot 2 \cdot 3 \cdots (n-1) \cdot n$$

$$F(n) = \frac{1}{\sqrt{5}} \left(\left(\frac{1+\sqrt{5}}{2} \right)^{n+1} - \left(\frac{1-\sqrt{5}}{2} \right)^{n+1} \right)$$

但是，有的函数却无法找到非递归定义，比如 Ackerman 函数。



The *divide-and-conquer* design paradigm

- 1. *Divide* the problem (instance) into subproblems.
- 2. *Conquer* the subproblems by solving them recursively.
- 3. *Combine* subproblem solutions.



Binary search

- Example: Find 9 3 5 7 8 9 12 15
- 3 5 7 8 9 12 15
- Find an element in a sorted array:
- 1. Divide: Check middle element.
- 2. Conquer: Recursively search 1 subarray.
- 3. Combine: Trivial



Divide-and-Conquer

- **Recursive in structure**
- **To solve P:**
 - Divide P into smaller problems P_1, P_2, \dots, P_k .
 - Conquer by solving the (smaller) subproblems recursively. **Recursively**
 - Combine the solutions to P_1, P_2, \dots, P_k into the solution for P



7 Quicksort



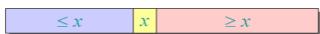
- Proposed by Hoare in 1962.
- Divide-and-conquer algorithm.
- Sorts “in place” (like insertion sort, but not like merge sort).
- Very practical (with tuning).



Divide and conquer

Quicksort an n -element array:

1. **Divide:** Partition the array into two subarrays around a **pivot** x such that elements in lower subarray $\leq x \leq$ elements in upper subarray.



2. **Conquer:** Recursively sort the two subarrays.
3. **Combine:** Trivial.



Pseudocode for quicksort

```

QUICKSORT(A, p, r)
    if p < r
        then q ← PARTITION(A, p, r)
            QUICKSORT(A, p, q-1)
            QUICKSORT(A, q+1, r)
Initial call: QUICKSORT(A, 1, n)
    
```



Partitioning subroutine

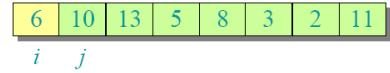
The key to the algorithm is the PARTITION procedure, which rearranges the subarray $A[p..r]$ in place.

```
PARTITION( $A, p, q$ )  $\triangleright A[p..q]$ 
   $x \leftarrow A[p]$             $\triangleright$  pivot =  $A[p]$ 
   $i \leftarrow p$ 
  for  $j \leftarrow p + 1$  to  $q$ 
    do if  $A[j] \leq x$ 
        then  $i \leftarrow i + 1$ 
        exchange  $A[i] \leftrightarrow A[j]$ 
  exchange  $A[p] \leftrightarrow A[i]$ 
  return  $i$ 
```

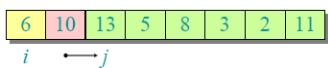
invariant:



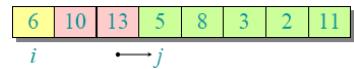
Example of partitioning



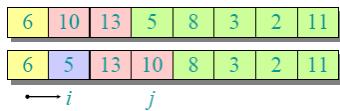
Example of partitioning



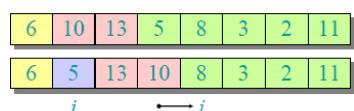
Example of partitioning



Example of partitioning

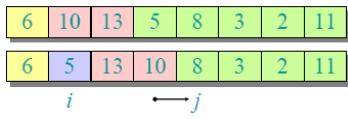


Example of partitioning

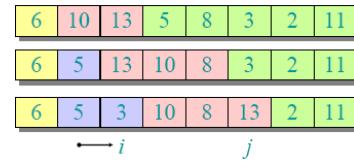




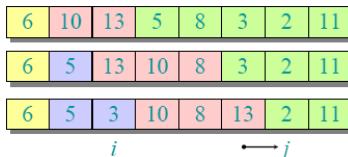
Example of partitioning



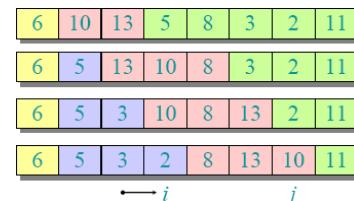
Example of partitioning



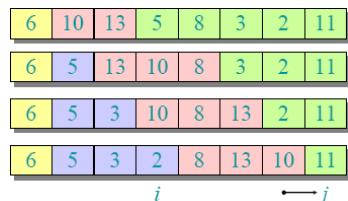
Example of partitioning



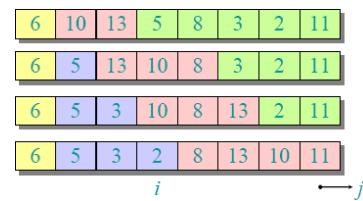
Example of partitioning



Example of partitioning



Example of partitioning





Example of partitioning

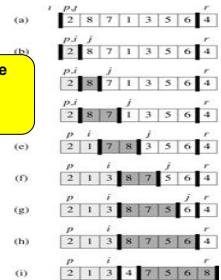
6	10	13	5	8	3	2	11
6	5	13	10	8	3	2	11
6	5	3	10	8	13	2	11
6	5	3	2	8	13	10	11
2	5	3	6	8	13	10	11

Partitioning subroutine

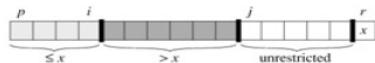
- PARTITION(A, p, r)
- $x \leftarrow A[p]$
- $i \leftarrow p-1$
- For $j \leftarrow p$ to $r-1$
 - do if $A[j] \leq x$
 - then $i \leftarrow i+1$
- exchange $A[i] \leftrightarrow A[j]$
- exchange $A[i+1] \leftrightarrow A[r]$
- return $i+1$



Running time
 $= O(n)$ for n elements.



Analysis of the partition:

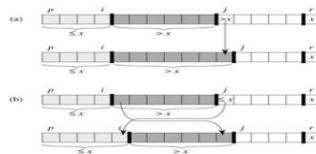


- If $p \leq k \leq i$, then $A[k] \leq x$.
- If $i+1 \leq k \leq j-1$, then $A[k] > x$.
- If $k = r$, then $A[k] = x$
- If $j \leq k \leq r-1$, then $A[k]$ can take on any values



[Initialization: the first two conditions of the loop invariant are trivially satisfied.](#)

- Maintenance: there are two cases to consider:
 - (a) shows what happens when $A[j] > x$;
 - (b) shows what happens when $A[j] \leq x$;
- Termination: At termination, $j = r$, and we have partitioned the values in the array into three sets: those less than or equal to x , those greater than x , and a singleton set containing x .



Analysis of quicksort

- Let $T(n)$ = worst-case running time on an array of n elements.



Worst-case of quicksort

- Input sorted or reverse sorted.
- Partition around min or max element.
- One side of partition always has no elements.

$$\begin{aligned}
 T(n) &= T(0) + T(n-1) + \Theta(n) \\
 &= \Theta(1) + T(n-1) + \Theta(n) \\
 &= T(n-1) + \Theta(n) \\
 &= \Theta(n^2) \quad (\text{arithmetic series})
 \end{aligned}$$



Worst-case recursion tree

$$T(n) = T(0) + T(n-1) + cn$$



Worst-case recursion tree

$$T(n) = T(0) + T(n-1) + cn$$

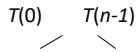
$T(n)$



Worst-case recursion tree

$$T(n) = T(0) + T(n-1) + cn$$

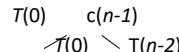
cn



Worst-case recursion tree

$$T(n) = T(0) + T(n-1) + cn$$

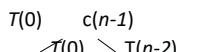
cn



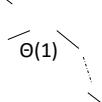
Worst-case recursion tree

$$T(n) = T(0) + T(n-1) + cn$$

cn



$T(0)$



Best-case analysis *(For intuition only!)*

If we're lucky, PARTITION splits the array evenly:

$$\begin{aligned} T(n) &= 2T(n/2) + \Theta(n) \\ &= \Theta(n \lg n) \quad (\text{same as merge sort}) \end{aligned}$$

What if the split is always 1/10:9/10?

$$T(n) = T(1/10n) + T(9/10n) + \Theta(n)$$

What is the solution to this recurrence?



Analysis of “almost-best” case

$T(n)$

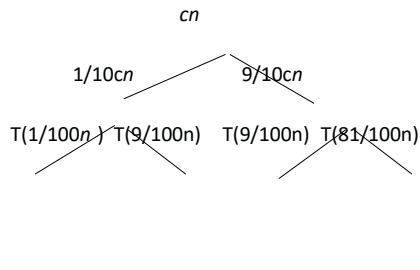


Analysis of “almost-best” case

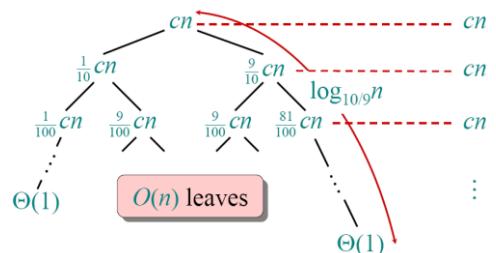
$\frac{cn}{T(1/10n)} \quad \frac{cn}{T(9/10n)}$



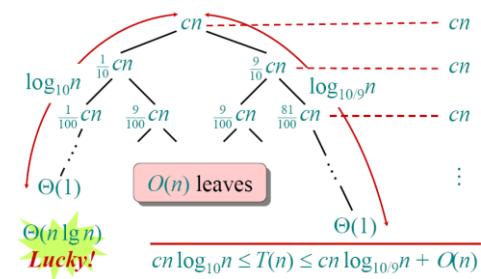
Analysis of “almost-best” case



Analysis of “almost-best” case



Analysis of “almost-best” case



More intuition

Suppose we alternate lucky, unlucky, lucky, unlucky,

$L(n) = 2U(n/2) + \Theta(n)$ **lucky**

$U(n) = L(n - 1) + \Theta(n)$ **unlucky**

Solving:

$$\begin{aligned} L(n) &= 2(L(n/2 - 1) + \Theta(n/2)) + \Theta(n) \\ &= 2L(n/2 - 1) + \Theta(n) \\ &= \Theta(n \lg n) \end{aligned}$$





Randomized quicksort

IDEA: Partition around a *random* element.

- Running time is independent of the input order.
- No assumptions need to be made about the input distribution.
- No specific input elicits the worst-case behavior.
- The worst case is determined only by the output of a random-number generator.



Randomized quicksort analysis

Let $T(n)$ = the random variable for the running time of randomized quicksort on an input of size n , assuming random numbers are independent.

For $k = 0, 1, \dots, n-1$, define the *indicator random variable*

$$X_k = \begin{cases} 1 & \text{if PARTITION generates a } k : n-k-1 \text{ split,} \\ 0 & \text{otherwise.} \end{cases}$$

$E[X_k] = \Pr\{X_k = 1\} = 1/n$, since all splits are equally likely, assuming elements are distinct.



Analysis (continued)

$$\begin{aligned} T(n) &= \begin{cases} T(0) + T(n-1) + \Theta(n) & \text{if } 0 : n-1 \text{ split,} \\ T(1) + T(n-2) + \Theta(n) & \text{if } 1 : n-2 \text{ split,} \\ \vdots \\ T(n-1) + T(0) + \Theta(n) & \text{if } n-1 : 0 \text{ split,} \end{cases} \\ &= \sum_{k=0}^{n-1} X_k (T(k) + T(n-k-1) + \Theta(n)). \end{aligned}$$



Calculating expectation

$$E[T(n)] = E\left[\sum_{k=0}^{n-1} X_k (T(k) + T(n-k-1) + \Theta(n))\right]$$



Calculating expectation

$$\begin{aligned} E[T(n)] &= E\left[\sum_{k=0}^{n-1} X_k (T(k) + T(n-k-1) + \Theta(n))\right] \\ &= \sum_{k=0}^{n-1} E[X_k (T(k) + T(n-k-1) + \Theta(n))] \end{aligned}$$

Linearity of expectation.



Calculating expectation

$$\begin{aligned} E[T(n)] &= E\left[\sum_{k=0}^{n-1} X_k (T(k) + T(n-k-1) + \Theta(n))\right] \\ &= \sum_{k=0}^{n-1} E[X_k (T(k) + T(n-k-1) + \Theta(n))] \\ &= \sum_{k=0}^{n-1} E[X_k] \cdot E[T(k) + T(n-k-1) + \Theta(n)] \end{aligned}$$

Independence of X_k from other random choices.



Calculating expectation

$$\begin{aligned} E[T(n)] &= E\left[\sum_{k=0}^{n-1} X_k (T(k) + T(n-k-1) + \Theta(n))\right] \\ &= \sum_{k=0}^{n-1} E[X_k (T(k) + T(n-k-1) + \Theta(n))] \\ &= \sum_{k=0}^{n-1} E[X_k] \cdot E[T(k) + T(n-k-1) + \Theta(n)] \\ &= \frac{1}{n} \sum_{k=0}^{n-1} E[T(k)] + \frac{1}{n} \sum_{k=0}^{n-1} E[T(n-k-1)] + \frac{1}{n} \sum_{k=0}^{n-1} \Theta(n) \end{aligned}$$



Calculating expectation

$$\begin{aligned} E[T(n)] &= E\left[\sum_{k=0}^{n-1} X_k (T(k) + T(n-k-1) + \Theta(n))\right] \\ &= \sum_{k=0}^{n-1} E[X_k (T(k) + T(n-k-1) + \Theta(n))] \\ &= \sum_{k=0}^{n-1} E[X_k] \cdot E[T(k) + T(n-k-1) + \Theta(n)] \\ &= \frac{1}{n} \sum_{k=0}^{n-1} E[T(k)] + \frac{1}{n} \sum_{k=0}^{n-1} E[T(n-k-1)] + \frac{1}{n} \sum_{k=0}^{n-1} \Theta(n) \\ &= \frac{2}{n} \sum_{k=1}^{n-1} E[T(k)] + \Theta(n) \quad \text{Summations have identical terms.} \end{aligned}$$



Hairy recurrence

$$E[T(n)] = \frac{2}{n} \sum_{k=2}^{n-1} E[T(k)] + \Theta(n)$$

(The $k=0, 1$ terms can be absorbed in the $\Theta(n)$.)

Prove: $E[T(n)] \leq an \lg n$ for constant $a > 0$.

- Choose a large enough so that $an \lg n$ dominates $E[T(n)]$ for sufficiently small $n \geq 2$.

Use fact: $\sum_{k=2}^{n-1} k \lg k \leq \frac{1}{2} n^2 \lg n - \frac{1}{8} n^2$ (exercise).



Substitution method

$$E[T(n)] \leq \frac{2}{n} \sum_{k=2}^{n-1} ak \lg k + \Theta(n)$$



Substitution method

$$\begin{aligned} E[T(n)] &\leq \frac{2}{n} \sum_{k=2}^{n-1} ak \lg k + \Theta(n) \\ &\leq \frac{2a}{n} \left(\frac{1}{2} n^2 \lg n - \frac{1}{8} n^2 \right) + \Theta(n) \end{aligned}$$



Substitution method

$$\begin{aligned} E[T(n)] &\leq \frac{2}{n} \sum_{k=2}^{n-1} ak \lg k + \Theta(n) \\ &\leq \frac{2a}{n} \left(\frac{1}{2} n^2 \lg n - \frac{1}{8} n^2 \right) + \Theta(n) \\ &= an \lg n - \left(\frac{an}{4} - \Theta(n) \right) \end{aligned}$$



Substitution method

$$\begin{aligned}
 E[T(n)] &\leq \frac{2}{n} \sum_{k=2}^{n-1} ak \lg k + \Theta(n) \\
 &= \frac{2a}{n} \left(\frac{1}{2} n^2 \lg n - \frac{1}{8} n^2 \right) + \Theta(n) \\
 &= an \lg n - \left(\frac{an}{4} - \Theta(n) \right) \\
 \text{if } &\leq an \lg n, \\
 an/4 &\text{ dominates the } \Theta(n).
 \end{aligned}$$



Quicksort in practice

- Quicksort is a great general-purpose sorting algorithm.
- Quicksort is typically over twice as fast as merge sort.
- Quicksort can benefit substantially from **code tuning**.
- Quicksort behaves well even with caching and virtual memory.



Conclusion

- Divide and conquer is just one of several powerful techniques for algorithm design.
- Divide-and-conquer algorithms can be analyzed using recurrences and the master method (so practice this math).
- Can lead to more efficient algorithms



Example

Problem: sorting {12,3,25,5,31,7,9,1,10}

- **Divide:** it is too big to solve, if it is smaller we may solve it, so we divide it into two problem:
- **Sub-problem1:** sorting{12,3,25,5,31}
- **Sub-problem2:** sorting{7,9,1,10}



Example

- **Conquer:** we use some methods (any kind of) to solve it and get the sub-problems' solutions, that means we sort the two sub-problem:

sorting{12,3,25,5,31}

Solution of sub-problem1:{3,5,12,25,31}

sorting{7,9,1,10}

Solution of sub-problem2:{1,7,9,10}



Example

- **Combine:** we should use these two solutions to construct the solution of the original problem.



Designing algorithms

Divide the problem into a number of subproblems.

Conquer the subproblems by solving them recursively.

Combine the subproblem solutions to give a solution to the original problem.



Merge Sort Algorithm

• Using divide-and-conquer, we can obtain a merge-sort algorithm

– **Divide:** Divide the n elements into two subsequences of $n/2$ elements each.

– **Conquer:** Sort the two subsequences recursively.

– **Combine:** Merge the two sorted subsequences to produce the sorted answer.

• Assume we have procedure **MERGE(A, p, q, r)** which merges sorted $A[p \dots q]$ with sorted $A[q+1 \dots r]$ in $(r-p)$ time.



Merge Sort (1) By Divide-and-Conquer

基本思想: 将元素分成2个子集合, 分别对子集合进行排序, 最终将排好序的子集合合并为有序集合。n=1时中止。

```
void MergeSort(Type a[], int left, int right)
{
    if (left<right) { //至少有2个元素
        int i=(left+right)/2; //取中点
        MergeSort(a, left, i);
        MergeSort(a, i+1, right);
        merge(a, b, left, i, right); //合并到数组b
        copy(a, b, left, right); //复制回数组a
    }
}
```

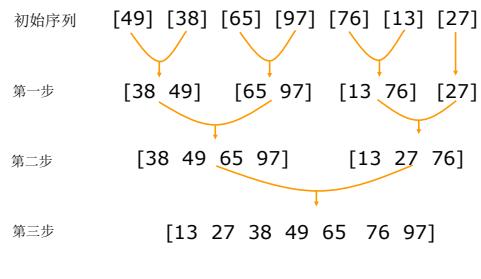
$$\text{复杂度分析} \quad T(n) = \begin{cases} O(1) & n \leq 1 \\ 2T(n/2) + O(n) & n > 1 \end{cases}$$

T(n)=O(nlogn) 演进意义上的最优算法



MergeSort

算法mergeSort的递归过程可以消去,



思想: 相邻元素(子数组段)两两配对, 用合并算法将其排序, 直至整个数组排好序。



Merge Sort (3) 自然排序

►自然排序是合并排序算法的一个变形。
e. g. [4, 8, 3, 7, 1, 5, 6, 2]

►1. 用一次对初始数组的扫描找出所有已排好序的子数组段 ; [4, 8], [3, 7], [1, 5, 6], [2]

►2. 将相邻排好序的数组两两合并, 直至完成整个数组的排序。[3, 4, 7, 8], [1, 2, 5, 6],

最坏时间复杂度: $O(nlogn)$
平均时间复杂度: $O(nlogn)$
最好时间复杂度: $O(n)$ (初始已排好序)



Merge sort

►A sorting algorithm based on **divide and conquer**.

►Its worst-case running time has a **lower order of growth** than insertion sort.



MERGE-SORT $A[1 \dots n]$

1. If $n = 1$, done.
2. Recursively sort $A[1 \dots n/2]$ and $A[n/2 + 1 \dots n]$.
3. **"Merge"** the 2 sorted lists.

Key subroutine: MERGE



Merging two sorted

Me

20	12
13	11
7	9
(2)	(1)



Merging two sorted

20	12
13	11
7	9
(2)	(1)
1	



Merging two sorted

20	12	20	12
13	11	13	11
7	9	7	9
(2)	(1)	(2)	
1			



Merging two sorted

20	12	20	12
13	11	13	11
7	9	7	9
(2)	(1)	(2)	
1		2	

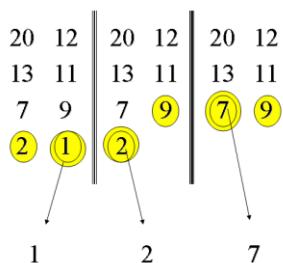


Merging two sorted

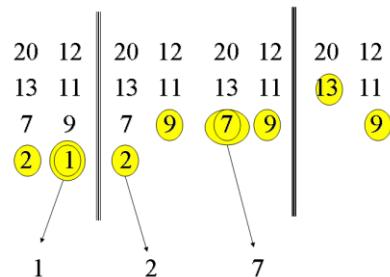
20	12	20	12	20	12
13	11	13	11	13	11
7	9	7	9	7	9
(2)	(1)	(2)		(7)	(9)
1		2			



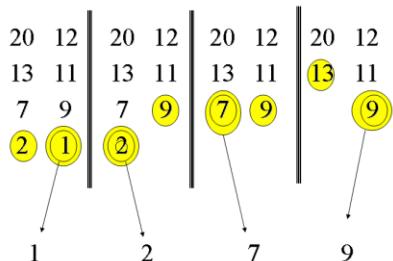
Merging two sorted arrays



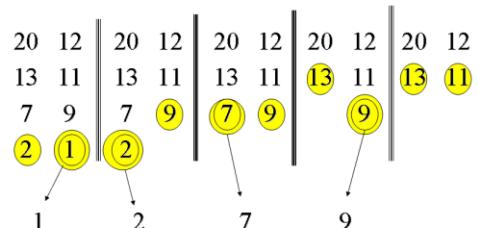
Merging two sorted arrays



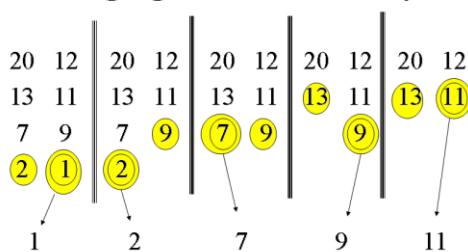
Merging two sorted arrays



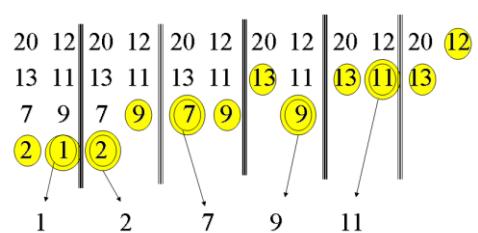
Merging two sorted arrays



Merging two sorted arrays

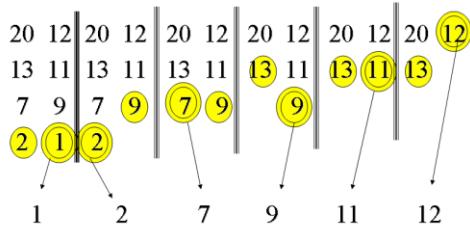


Merging two sorted arrays

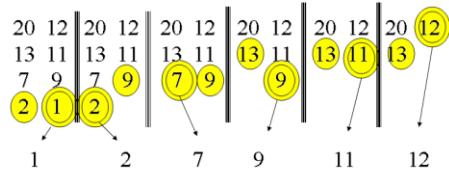




Merging two sorted arrays



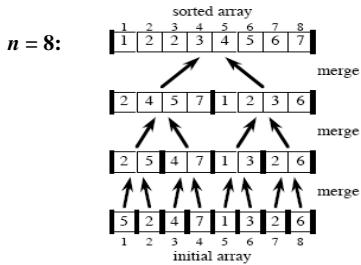
Merging two sorted arrays



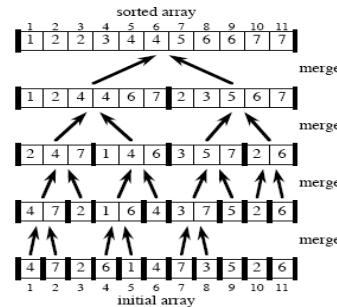
Time = $\Theta(n)$ to merge a total of n elements (linear time).



Examples



Examples



Merge-Sort (A, p, r)

INPUT: a sequence of n numbers stored in array A

OUTPUT: an ordered sequence of n numbers

```

MERGESORT
MERGE-SORT(A, p, r)
1 if p < r
2   then q ← ⌊(p+r)/2⌋
3     MERGE-SORT (A, p, q)
4     MERGE-SORT (A, q+1, r)
5     MERGE (A, p, q, r)

```



Pseudocode

```

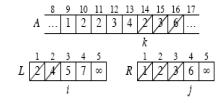
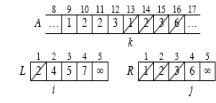
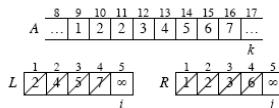
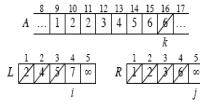
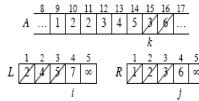
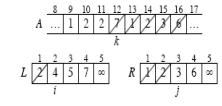
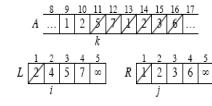
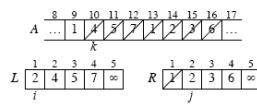
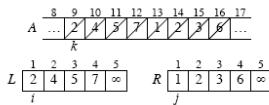
◆ MERGE(A, p, q, r)
◆ n1 ← q - p + 1
◆ n2 ← r - q
◆ create arrays L[1 .. n1 + 1] and R[1 .. n2 + 1]
◆ for i ← 1 to n1
◆   do L[i] ← A[p + i - 1]
◆ for j ← 1 to n2
◆   do R[j] ← A[q + j]
◆ L[n1 + 1] ← ∞
◆ R[n2 + 1] ← ∞
◆ i ← 1   j ← 1
◆ for k ← p to r
◆   do if L[i] ≤ R[j]
◆     then A[k] ← L[i]
◆           i ← i + 1
◆   else A[k] ← R[j]
◆           j ← j + 1

```

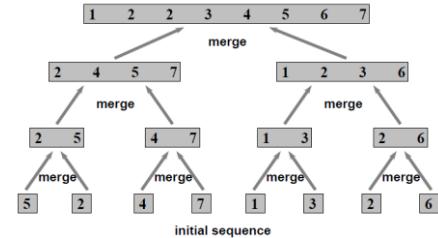
Running time:
The first two for loops take $\Theta(n_1 + n_2) = \Theta(n)$ time.
The last for loop makes n iterations, each taking constant time, for $\Theta(n)$ time.
Total time: $\Theta(n)$.



Example: A call of MERGE(9, 12, 16)



Merge-Sort (A, 1, length[A])



Solution!

{5,2,4,7, 1,3,2,6}

- Using the merge algorithm we get the
- solution:{1,2,2,3,4,5,6,7}

Any left problems?



Correctness

- Is your solution correct?
- Does your merge algorithm outcome a sorted array in any case?

• **loop invariant**

• **Initialization:** It is true prior to the first iteration of the loop.

• **Maintenance:** If it is true before an iteration of the loop, it remains true before the next iteration.

• **Termination:** When the loop terminates, the invariant.



Complexity

- How many memories does the algorithm use?
- How many steps does the algorithm use?



Analyzing divide-and-conquer algorithms

Let $T(n)$ = running time on a problem of size n .

◆ to make analysis cleaner, assume n is a power of 2



Analyzing merge sort

$T(n)$	MERGE-SORT $A[1 \dots n]$
$\Theta(1)$	1. If $n = 1$, done.
$2T(n/2)$	2. Recursively sort $A[1 \dots n/2]$
$\Theta(n)$	and $A[n/2 + 1 \dots n]$.
	3. "Merge" the 2 sorted lists

Sloppiness: Should be $T(n/2) + T(n/2)$,
but it turns out not to matter asymptotically.



Recurrence for merge sort

$$T(n) = \begin{cases} \Theta(1) & \text{if } n = 1; \\ 2T(n/2) + \Theta(n) & \text{if } n > 1. \end{cases}$$

- We shall usually omit stating the base case when $T(n) = \Theta(1)$ for sufficiently small n , but only when it has no effect on the asymptotic solution to the recurrence.



Left problems

- What is the upper bounds and lower bounds for the sorting problem?
- How to solve the recursive equality(or inequality)?
 $T(n)=2T(n/2)+\Theta(n)$
- How to solve the problem?
 - Recursion-tree method
 - Substitution method
 - Master method



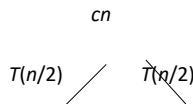
Recursion- tree method

- A recursion tree models the costs (time) of a recursive execution of an algorithm.
- The recursion tree method is good for generating guesses for the substitution method.
- The recursion-tree method promotes intuition, however.



Recursion tree

Solve $T(n) = 2T(n/2) + cn$, where $c > 0$ is constant.



For the original problem, we have a cost of cn , plus the two subproblems, each costing $T(n/2)$:



Recursion tree

Solve $T(n) = 2T(n/2) + cn$, where $c > 0$ is constant.

$T(n)$

Recursion tree

Solve $T(n) = 2T(n/2) + cn$, where $c > 0$ is constant.

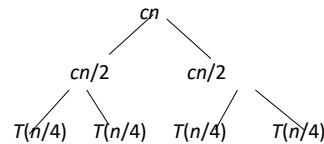
cn



For the original problem, we have a cost of cn , plus the two subproblems, each costing $T(n/2)$:

Recursion tree

Solve $T(n) = 2T(n/2) + cn$, where $c > 0$ is constant.



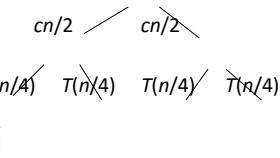
For each of the size- $n/2$ subproblems, we have a cost of $cn/2$, plus two subproblems, each costing $T(n/4)$:



Recursion tree

Solve $T(n) = 2T(n/2) + cn$, where $c > 0$ is constant.

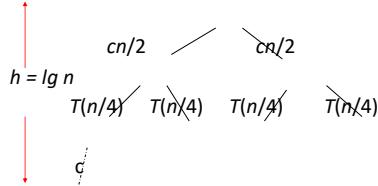
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Recursion tree

Solve $T(n) = 2T(n/2) + cn$, where $c > 0$ is constant.

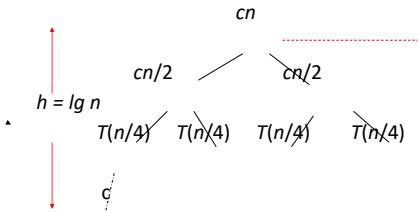
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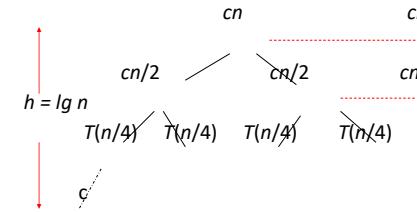
Recursion tree

Solve $T(n) = 2T(n/2) + cn$, where $c > 0$ is constant.



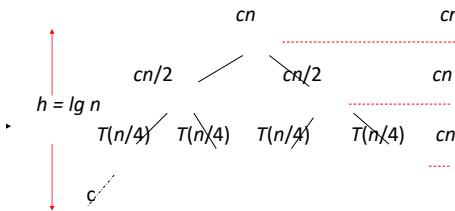
Recursion tree

Solve $T(n) = 2T(n/2) + cn$, where $c > 0$ is constant.



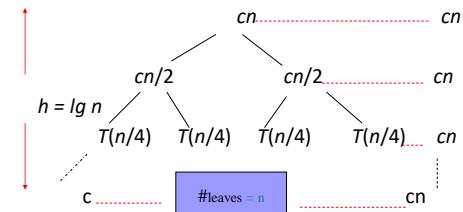
Recursion tree

Solve $T(n) = 2T(n/2) + cn$, where $c > 0$ is constant.



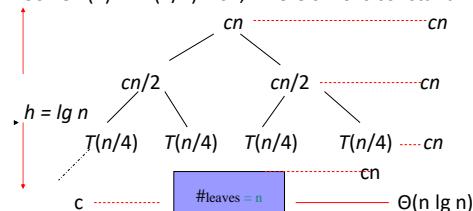
Recursion tree

Solve $T(n) = 2T(n/2) + cn$, where $c > 0$ is constant.



Recursion tree

Solve $T(n) = 2T(n/2) + cn$, where $c > 0$ is constant.



Conclusions

- $\Theta(n \lg n)$ grows more slowly than $\Theta(n^2)$.
- Therefore, merge sort asymptotically beats insertion sort in the worst case.
- In practice, merge sort beats insertion sort for $n > 30$ or so.
- Go test it out for yourself!



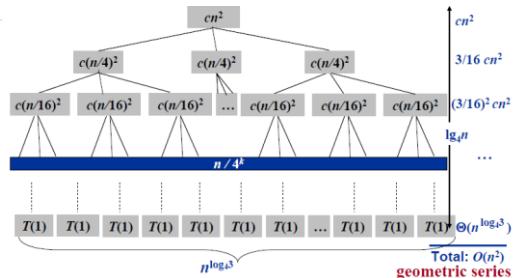
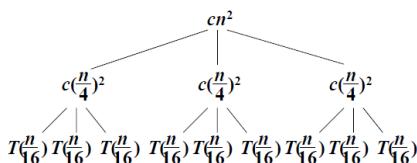
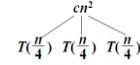
Example

Ex. $T(n) = T(n/4) + T(n/2) + n^2$

$$T(n) = 3T(n/4) + \Theta(n^2)$$



$$T(n) = 3T(n/4) + \Theta(n^2)$$



Substitution method

- The most general method:
- **Guess** the form of the solution.
- **Verify** by induction.
- **Solve** for constants.



Example

- Ex. $T(n) = 4T(n/2) + n$
- Assume that $T(1) = \Theta(1)$.
 - Guess $\Theta(n^3)$.
 - Assume that $T(k) \leq ck^3$ for $k < n$.
 - Prove $T(n) \leq cn^3$ by induction.



Master Method

- It provides a “cookbook” method for solving recurrences of the form:
 $T(n) = a T(n/b) + f(n)$
- where $a \geq 1$ and $b > 1$ are constants and $f(n)$ is an asymptotically positive function

Three common cases

- Based on the *master theorem*,
- Compare $n^{\log b^a}$ vs. $f(n)$:

- $f(n) = O(n^{\log b^a - \epsilon})$ for some constant $\epsilon > 0$.
- $f(n)$ grows polynomially slower than $n^{\log b^a}$

Solution: $T(n) = \Theta(n^{\log b^a})$



➢ Compare $n^{\log b^a}$ vs. $f(n)$:

- $f(n) = \Theta(n^{\log b^a} \lg^k n)$
- $f(n)$ and $n^{\log b^a}$ grow at similar rates.

➢ Compare $n^{\log b^a}$ vs. $f(n)$:

- $f(n) = \Theta(n^{\log b^a + \epsilon})$ for some constant $\epsilon > 0$.

- $f(n)$ grows polynomially faster than $n^{\log b^a}$ and $f(n)$ satisfies the regularity condition that $a f(n/b) \leq c f(n)$ for some constant $c < 1$.

Solution: $T(n) = \Theta(f(n))$

Solution: $T(n) = \Theta(n^{\log b^a} \lg^{k+1} n)$

Examples

Ex. Merge sort
 $T(n) = 2T(n/2) + \Theta(n)$

$$a = 2, b = 2 \Rightarrow n = n; f(n) = n.$$

CASE 2: k=0
 $T(n) = \Theta(n \lg n).$

Ex. $T(n) = 4T(n/2) + n$

$$a = 4, b = 2 \Rightarrow n^{\log b^a} = n^2; f(n) = n.$$

CASE 1: $f(n) = O(n^{2-\epsilon})$ for $\epsilon = 1$.
 $\therefore T(n) = \Theta(n^2).$

Examples

Ex. $T(n) = 4T(n/2) + n^2$

$$a = 4, b = 2 \Rightarrow n^{\log_b a} = n^2; f(n) = n^2.$$

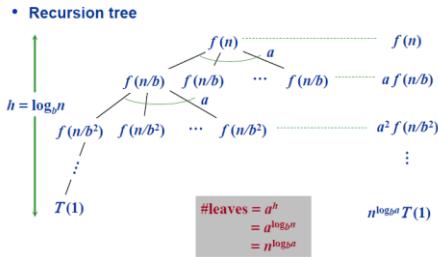
CASE 2: $f(n) = \Theta(n^2)$,

$$\therefore T(n) = \Theta(n^2 \lg n).$$

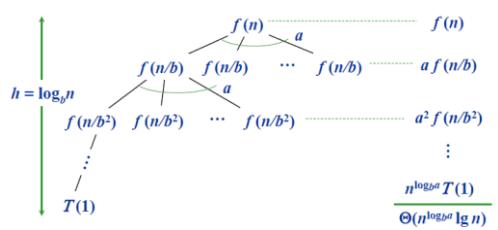
Ex. $T(n) = 4T(n/2) + n^3$

$$b = 4, b = 2 \Rightarrow = n^2; f(n) = n^3.$$

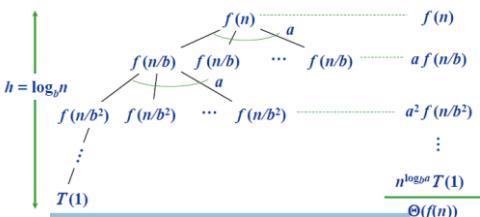
CASE 3: $f(n) = \Omega(n^{2+\epsilon})$ for $\epsilon = 1$
and $4(n/2)^3 \leq cn^3$ (reg. cond.) for $c = 1/2$.
 $\therefore T(n) = \Theta(n^3)$.



CASE 1: The weight increases geometrically from the root to the leaves. The leaves hold a constant fraction of the total weight.



CASE 2: ($k = 0$) The weight is approximately the same on each of the $\log_b n$ levels.



CASE 3: The weight decreases geometrically from the root to the leaves. The root holds a constant fraction of the total weight.