

# UML Sequence Diagrams

Software Design (40007) – 2023/2024

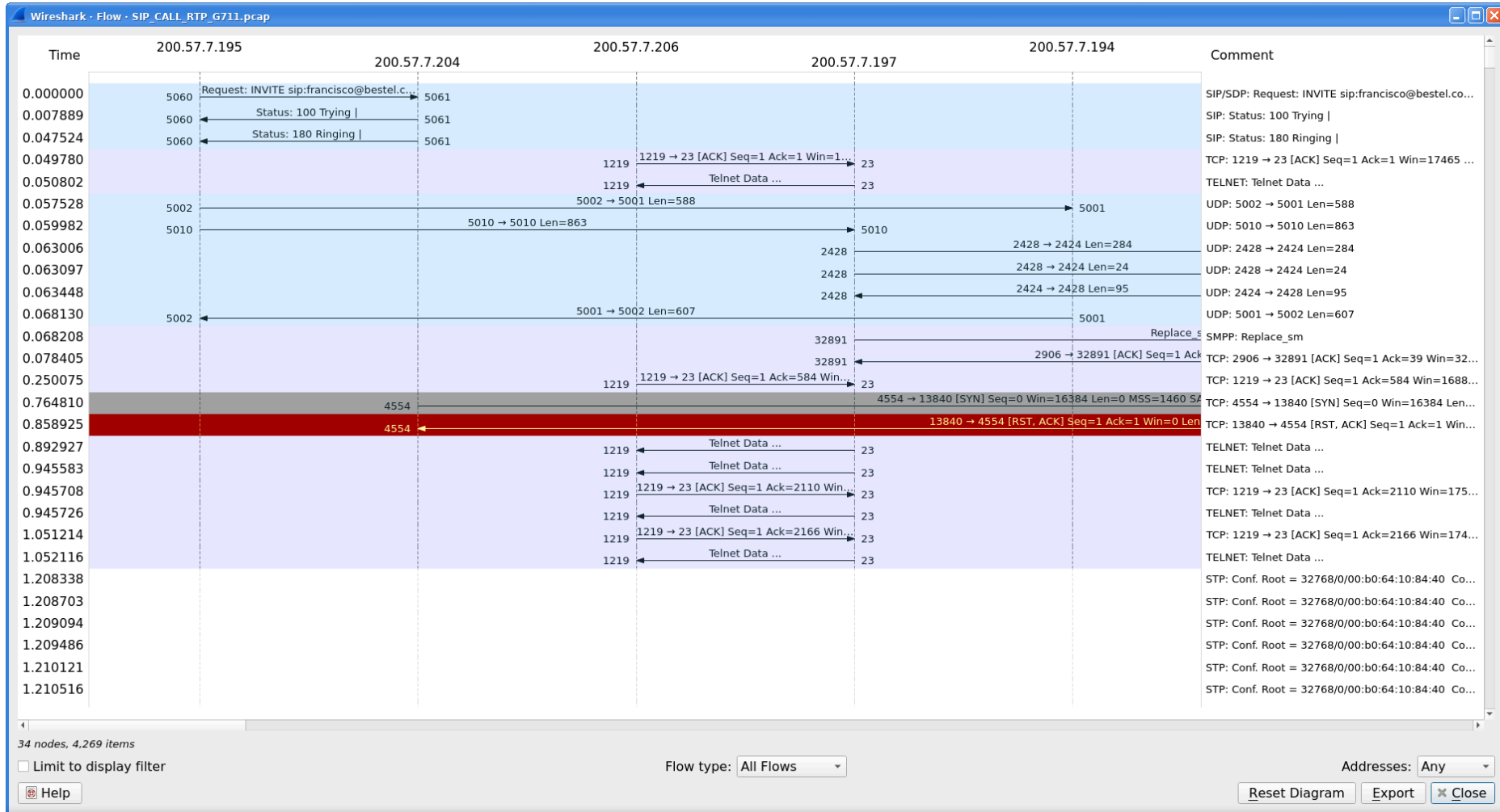
Justus Bogner  
Ivano Malavolta

# Roadmap

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- Basics
  - Interactions and interaction partners
  - Messages
- Combined fragments
  - Branches and loops
  - Concurrency and order
  - Filters and assertions
- Further modelling elements

# Example of interactions: Wireshark



[https://www.wireshark.org/docs/wsug\\_html/#ChStatFlowGraph](https://www.wireshark.org/docs/wsug_html/#ChStatFlowGraph)

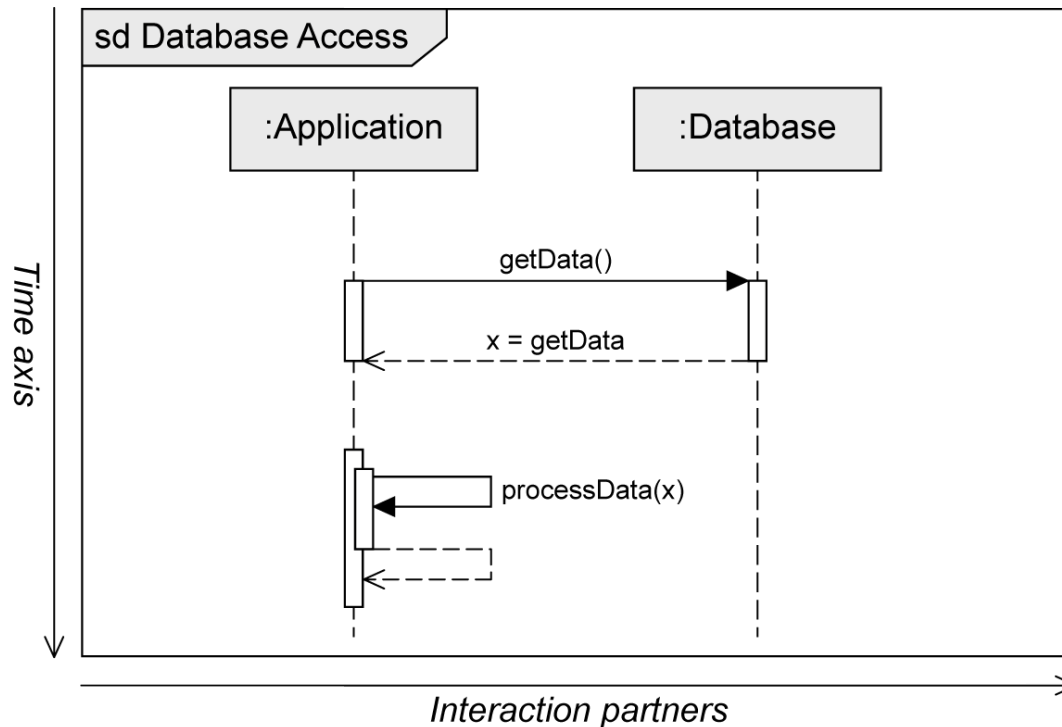
# Why UML sequence diagrams?

## Main Goal: To model interactions between partners

- Interaction
  - Specifies how messages and data are exchanged among partners
- Interaction partners
  - Human (lecturers, videogame players, users, administrators, ...)
  - Non-human (servers, printers, executable software, **objects**, ...)
- Examples of interactions
  - Conversation between persons
  - Message exchange between humans and a software system
  - Communication protocols
  - **Sequence of method calls in a program**
  - ...
- State machine diagrams: internal behavior of a single object
- Sequence diagrams: joint behavior of several objects

# Sequence diagram

- Two-dimensional diagram
  - Horizontal axis: involved interaction partners
  - Vertical axis: chronological order of the interaction
- Interaction = sequence of messages



# Interaction partners

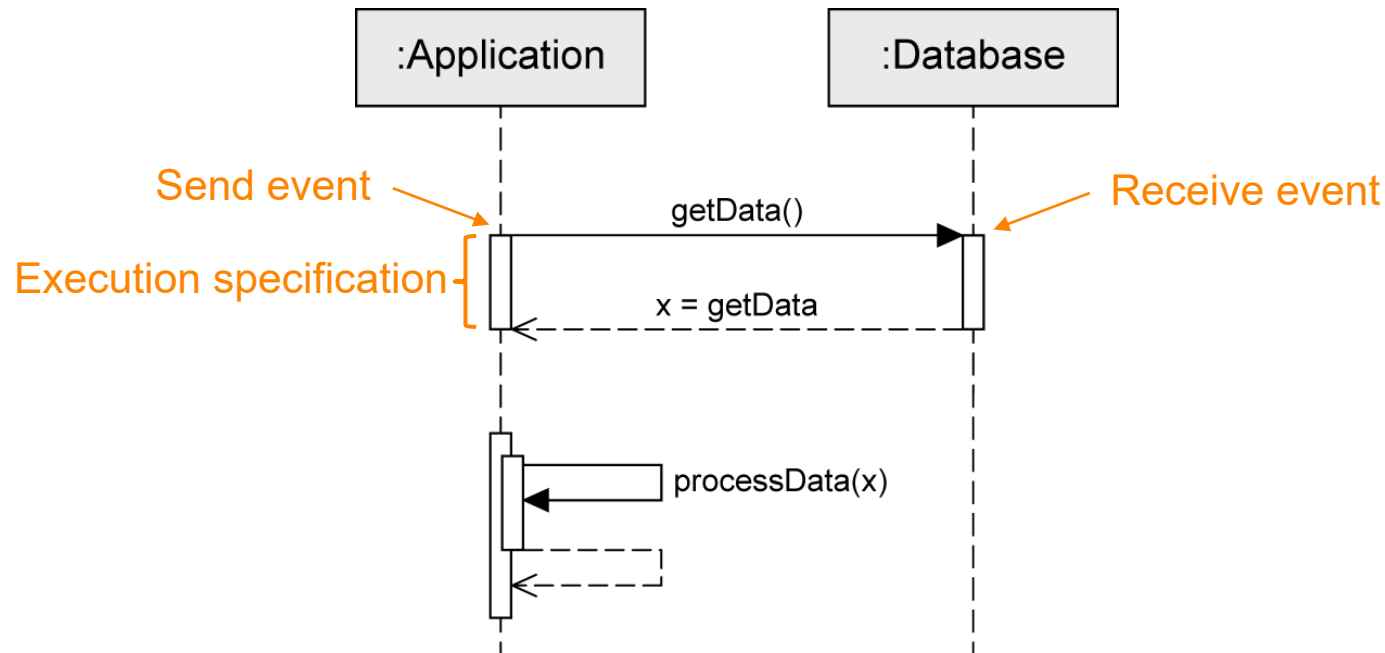
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- Interaction partners are depicted as **lifelines**
- Head of the lifeline
  - Rectangle that contains the expression **object:Class**
- Body of the lifeline
  - Vertical dashed line
  - Represents the lifetime of the object associated with it



# Exchanging Messages (1/2)

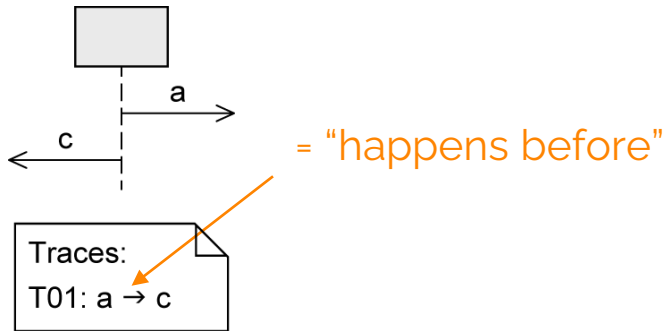
- A message is defined via a **send event** and a **receive event**
- Events are optionally linked via an **execution specification**
  - Visualized as a continuous bar
  - Indicates when the receiving partner executes some behavior



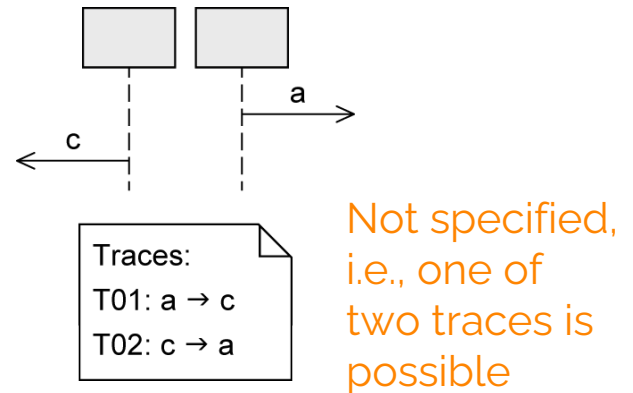
# Exchanging Messages (2/2)

## 3 rules about the order of messages:

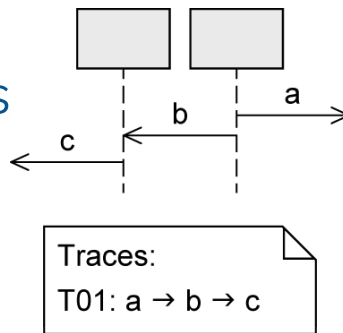
1. on one lifeline



2. on different lifelines without message exchanges



3. on different lifelines that exchange messages



Careful: non-deterministic behavior!

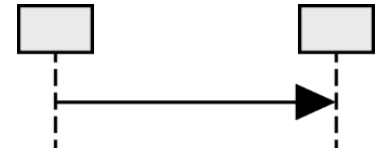




# Types of messages (1/3)

## ■ Synchronous message

- Sender waits until it has received a response message before continuing
- Syntax of message name: `msg (par1, ...)`
  - `msg`: name of the message
  - `pari`: parameters separated by commas



## ■ Asynchronous message

- Sender continues without waiting for a response message
- Syntax of message name: `msg (par1, ...)`



## ■ Response message

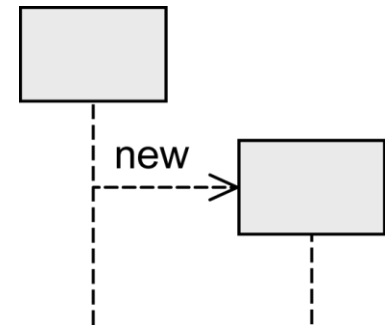
- May be omitted if content and location are obvious
- Syntax: `res = msg (par1, ...) : val`
  - `res`: response can optionally be assigned to a variable
  - `msg`: name of the message
  - `pari`: parameters separated by commas
  - `val`: return value



## Types of messages (2/3)

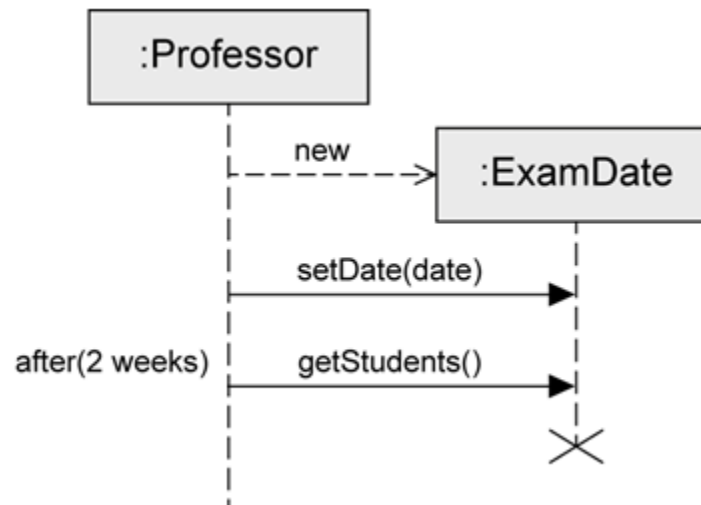
### ■ Object creation

- Dashed arrow with keyword `new`
- Arrowhead points to the head of the lifeline of the object to be created



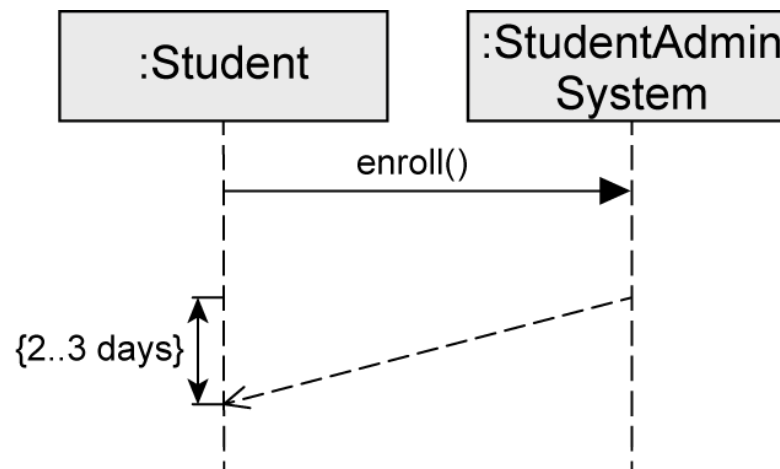
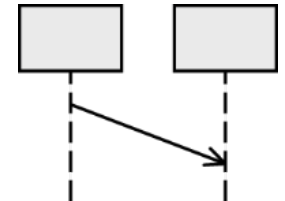
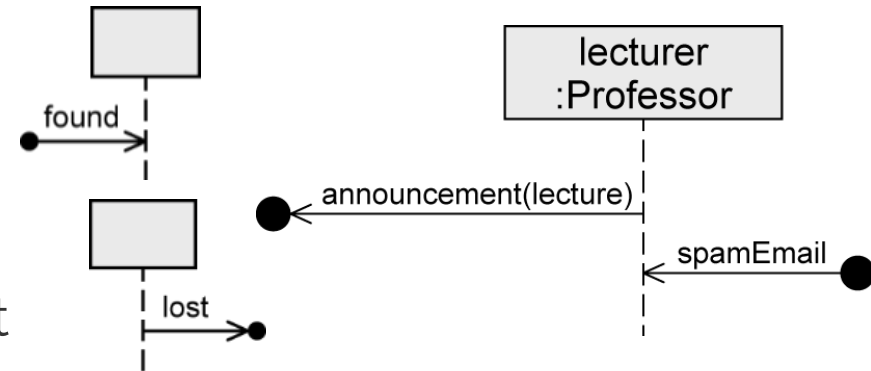
### ■ Object destruction

- Object is deleted
- Large cross (x) at the end of the lifeline



# Types of messages (3/3)

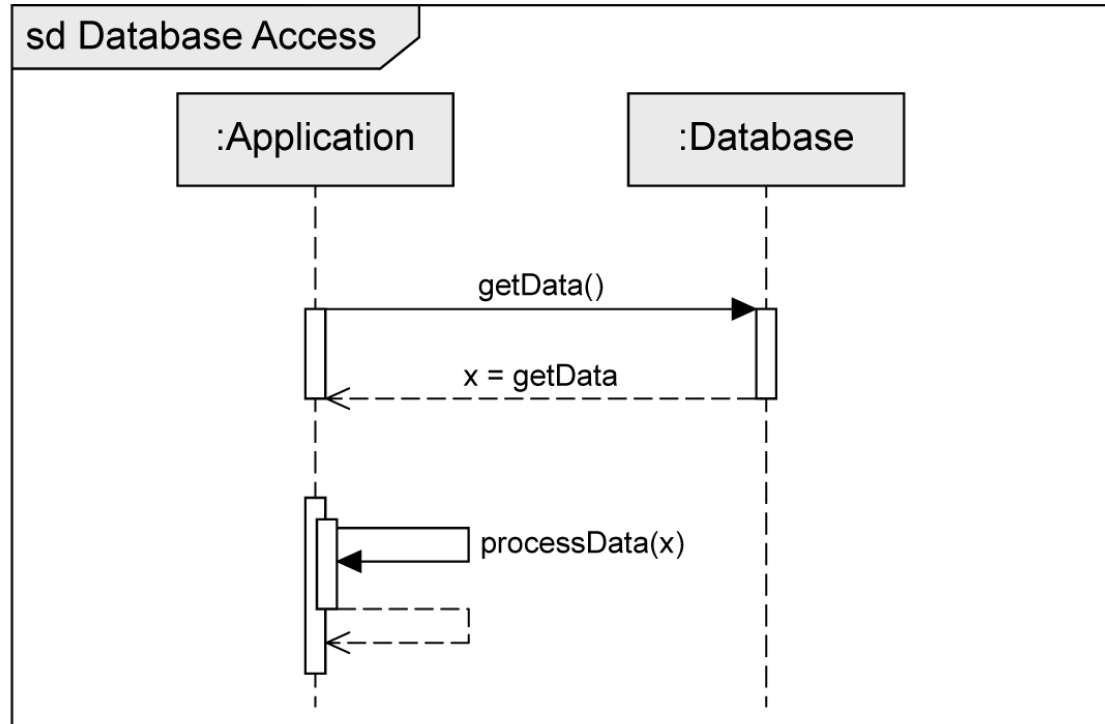
- Found message
  - Sender unknown or not relevant
- Lost message
  - Receiver unknown or not relevant
- Time-consuming message
  - "Message with duration"
  - Standard messages are transmitted instantly
  - Here: time elapses between sending and receiving



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# Combined Fragments

# Why combined fragments?

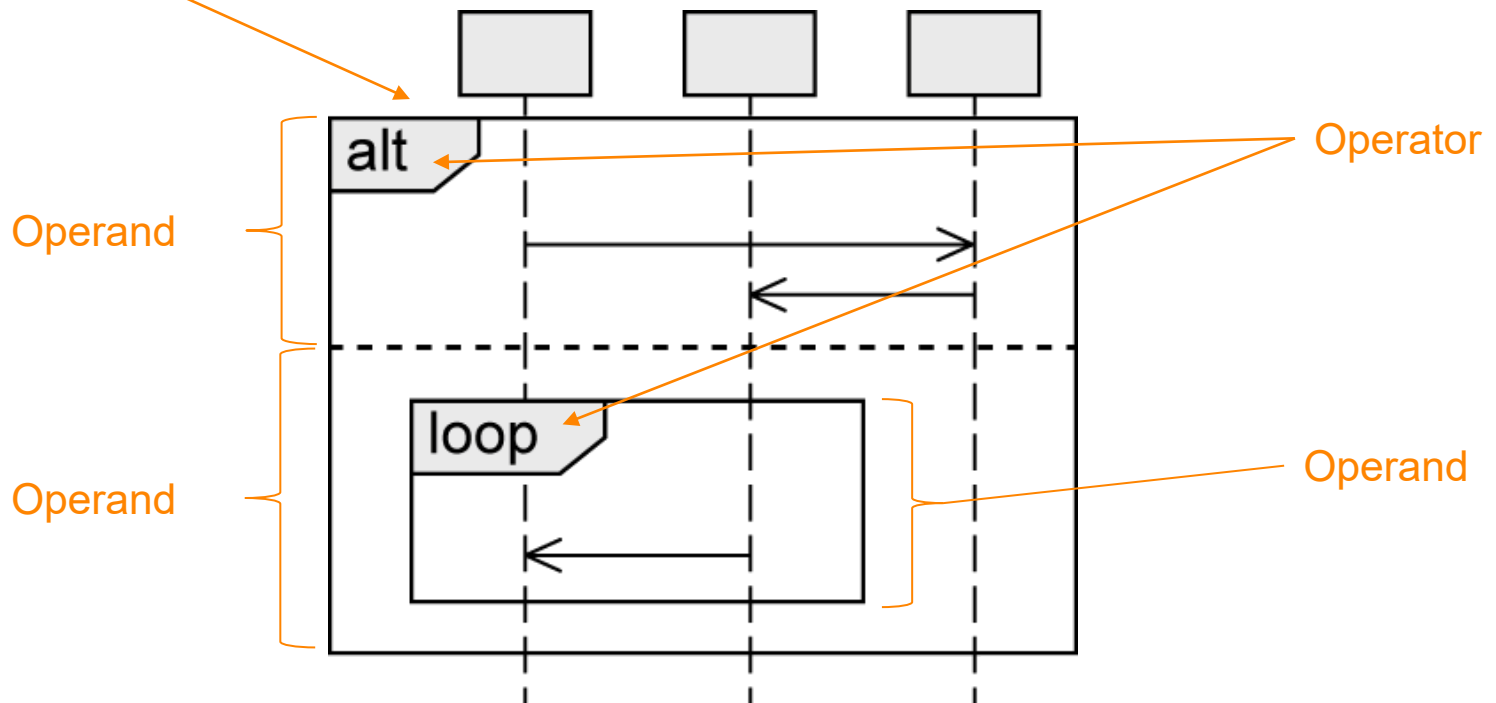


**These modelling constructs are suitable for simple, linear interactions but what about more complex interaction flows?**

# Combined fragments

- Allow modelling various control structures

Combined Fragment



# Types of combined fragments

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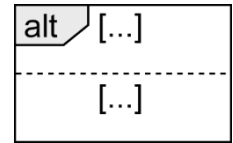
	Operator	Purpose
Branches and loops	<b>alt</b>	Alternative interaction
	<b>opt</b>	Optional interaction
	<b>loop</b>	Repeated interaction
	<b>break</b>	Exception interaction
Concurrency and order	<b>seq</b>	Weak order
	<b>strict</b>	Strict order
	<b>par</b>	Concurrent interaction
	<b>critical</b>	Atomic interaction
Filters and assertions	<b>ignore</b>	Irrelevant interaction
	<b>consider</b>	Relevant interaction
	<b>assert</b>	Asserted interaction
	<b>neg</b>	Invalid interaction

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# Branches and Loops

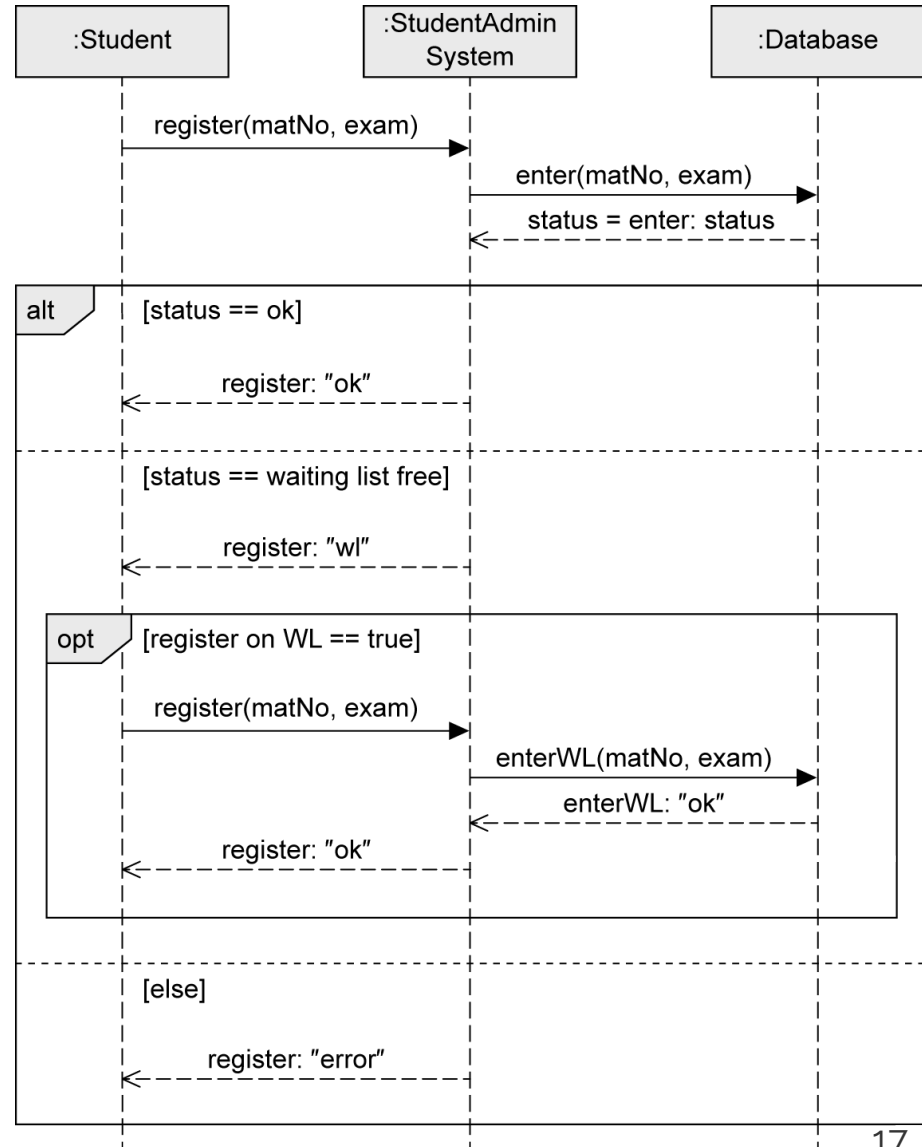


# alt fragment



## Model alternative sequences

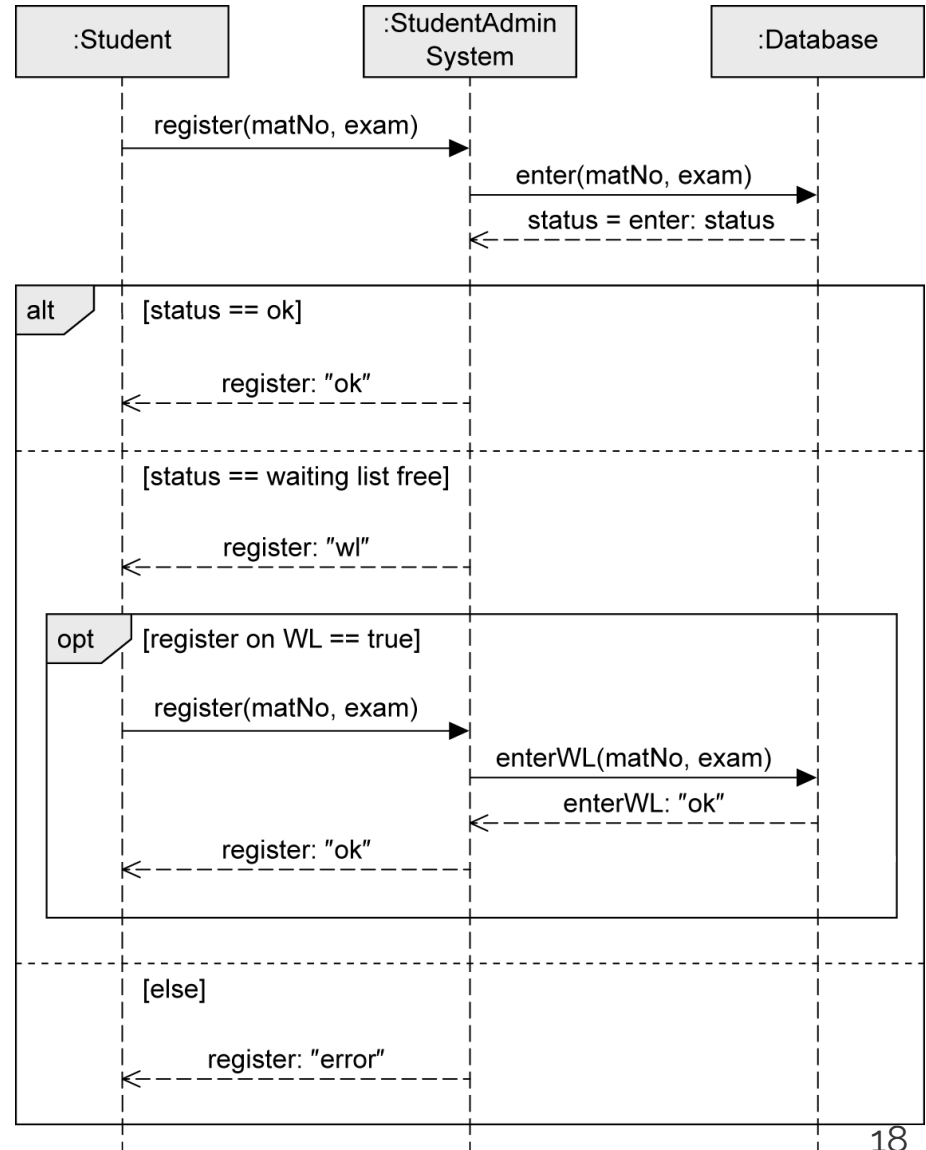
- Similar to **switch** or **if** statement in Java
- At least 2 operands
- Guards are used to select the path to be executed
  - Modeled in square brackets
  - default: `true`
  - Special guard: `[else]`
  - Must be mutually exclusive to avoid indeterministic behavior



# opt fragment

## Model an optional sequence

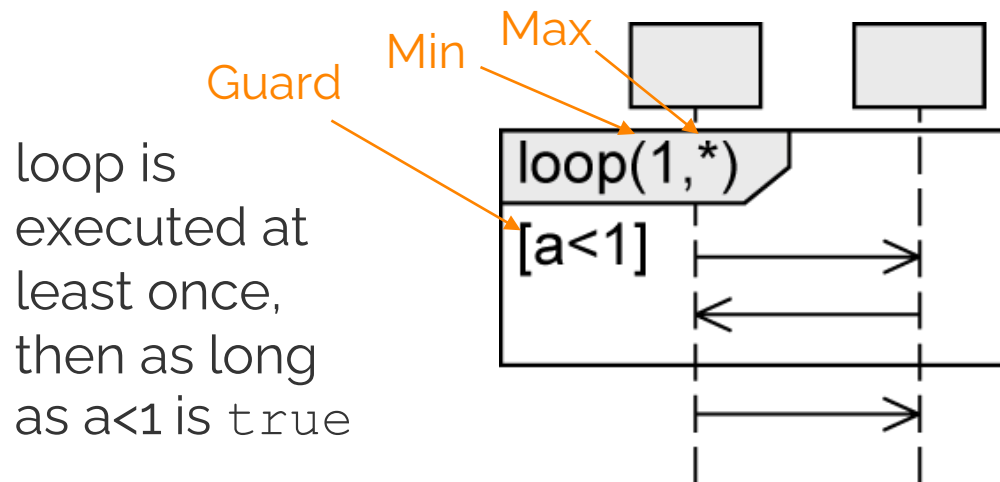
- Actual execution at runtime is dependent on a (required) guard
- Similar to **if** statement without **else** branch(es)
- Exactly one operand



# loop fragment

- Exactly one operand
- Minimum / maximum # of iterations
  - (**min..max**) or (**min,max**)
  - default: (\*) → no min and max, similar to `while (true)`
- Guard
  - Evaluated right after the minimum number of iterations
  - Checked for each subsequent iteration within the **max** limit
  - If the guard evaluates to `false`, the loop is terminated

## Model repeated sequences



loop is  
executed at  
least once,  
then as long  
as `a<1` is `true`

## Notation alternatives:

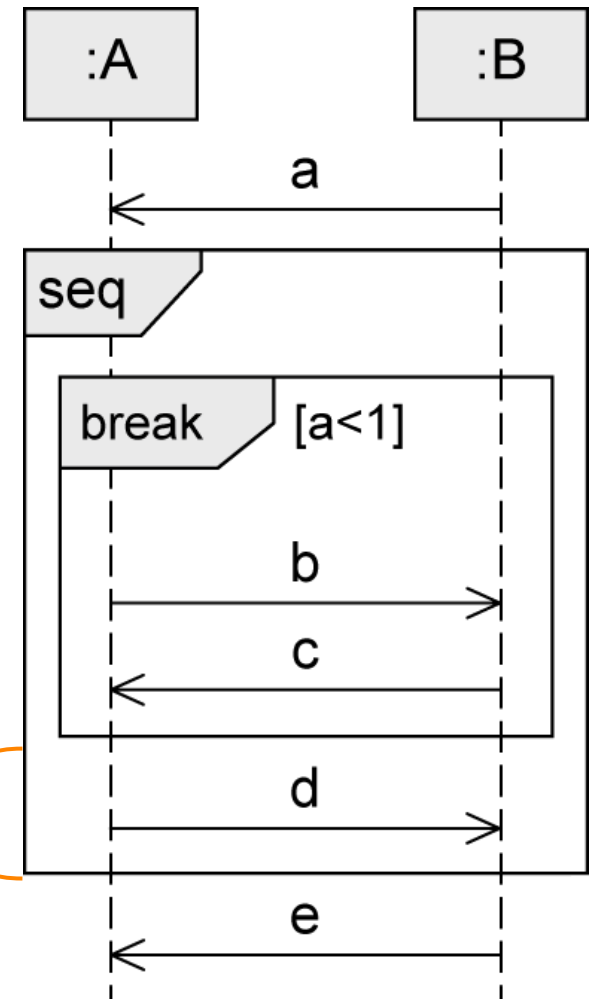
`loop(3,8) = loop(3..8)`  
`loop(8,8) = loop (8)`  
`loop = loop (*) = loop(0,*)`

# break fragment

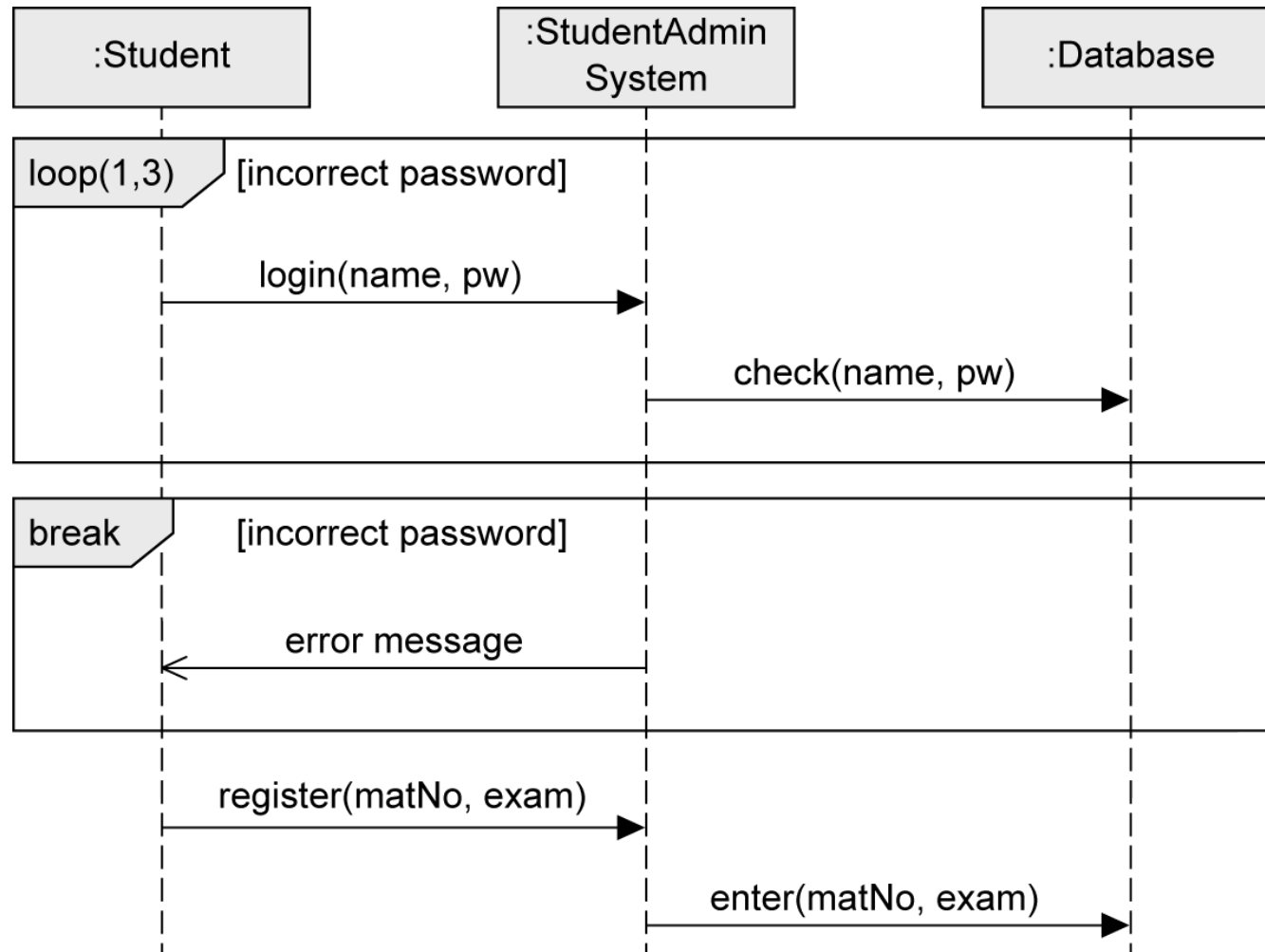
## Model exception handling

- Exactly one operand with a guard
- If the guard is `true`:
  - Interactions within this operand are executed ( $b \rightarrow c$ )
  - Remaining operations of the surrounding fragment are omitted (d)
  - Interaction continues in the next higher level fragment (e)

Not executed if  
break is executed



# Example: loop and break fragments



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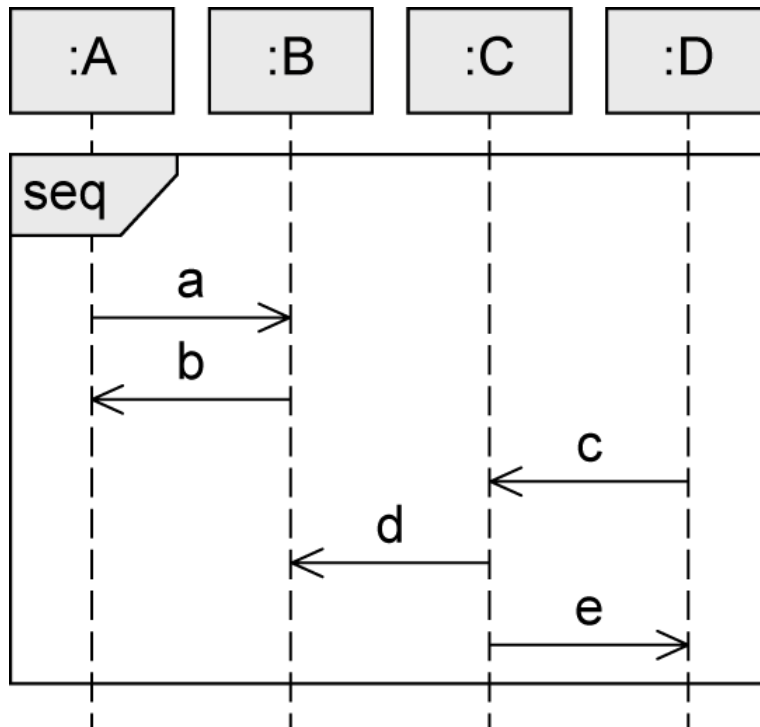
# Concurrency and Order

# Types of combined fragments

	Operator	Purpose
Branches and loops	<b>alt</b>	Alternative interaction
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	<b>neg</b>	Invalid interaction

# seq fragment

- Weak sequencing: the default order of events



**What are the 3 possible traces of messages?**

Traces:

T01:  $a \rightarrow b \rightarrow c \rightarrow d \rightarrow e$

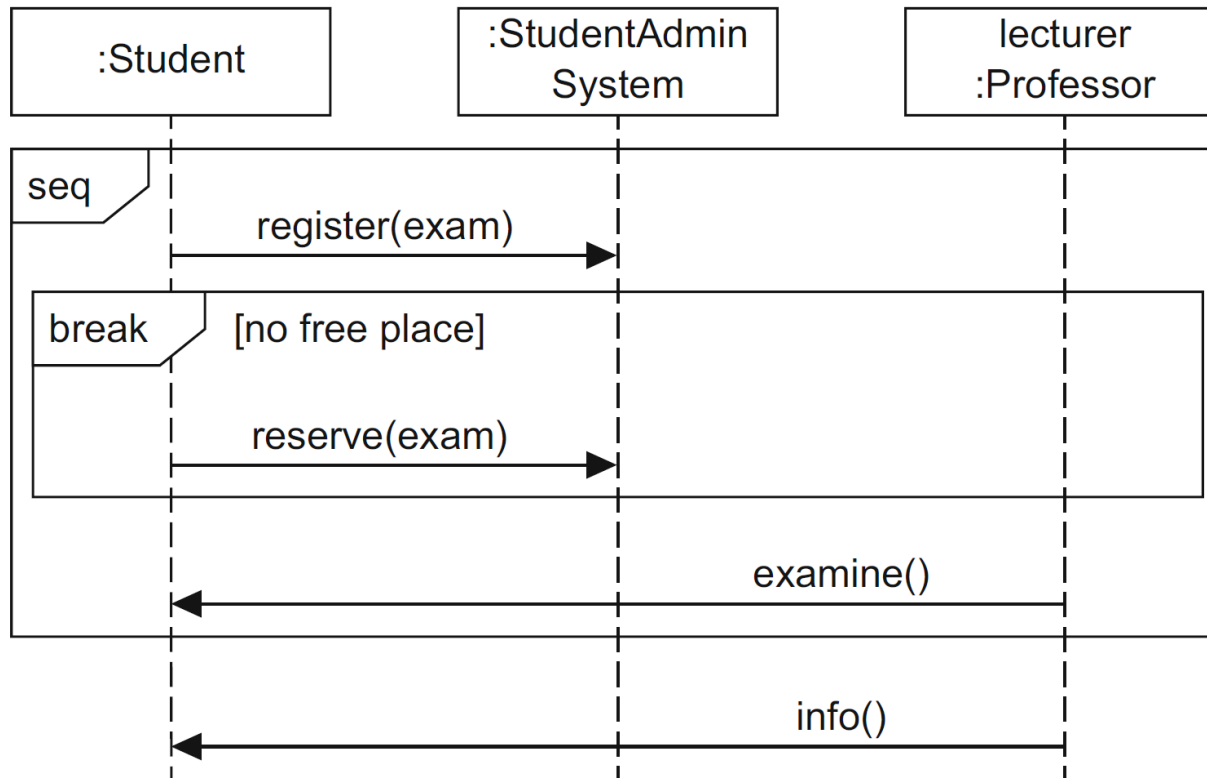
T02:  $a \rightarrow c \rightarrow b \rightarrow d \rightarrow e$

T03:  $c \rightarrow a \rightarrow b \rightarrow d \rightarrow e$



## Example: seq fragment combined with break

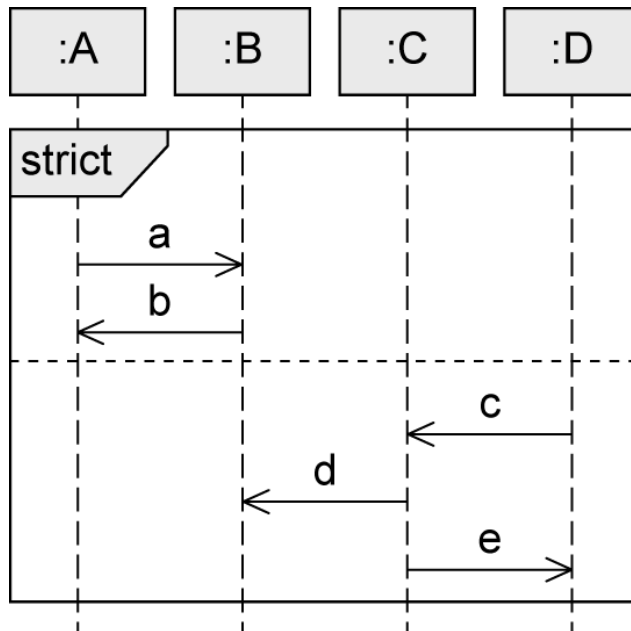
- seq is rarely useful on its own (default order), but is often valuable in combination with a break fragment



# strict fragment

## Model a fixed sequence of events across lifelines

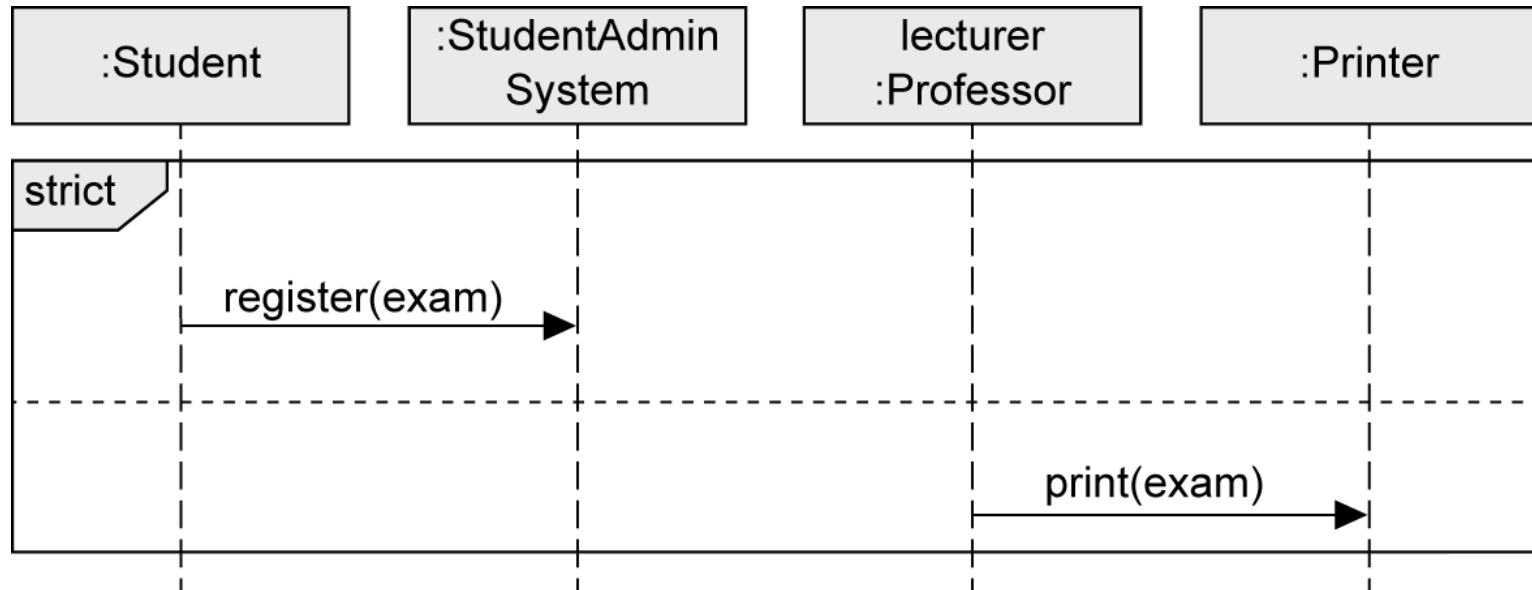
- Between different operands, the event order of the vertical axis becomes deterministic **even for unconnected lifelines**
- Messages in a higher-up operand are always exchanged **before** messages in a lower operand



Traces:

T01:  $a \rightarrow b \rightarrow c \rightarrow d \rightarrow e$

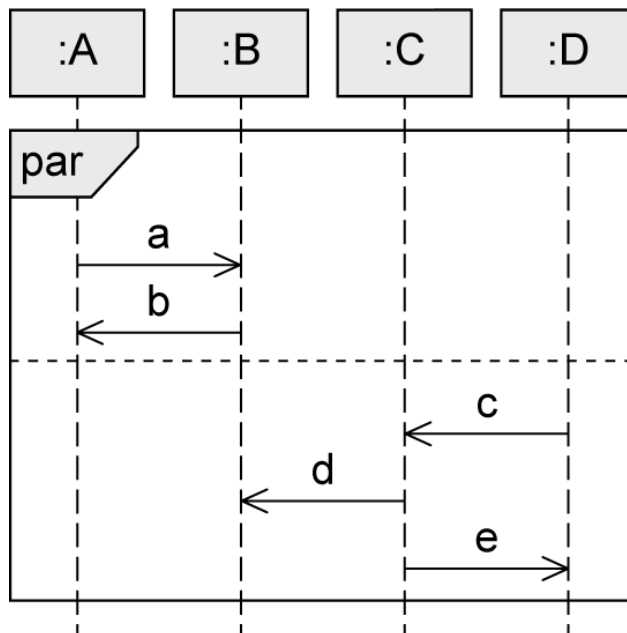
# Example: strict fragment



# par fragment

**Relax the chronological order between messages in different operands (concurrency)**

- Execution paths of different operands can be interleaved
- Restrictions within each operand need to be respected
- Order of the different operands is irrelevant



Traces:

T01:  $a \rightarrow b \rightarrow c \rightarrow d \rightarrow e$

T02:  $a \rightarrow c \rightarrow b \rightarrow d \rightarrow e$

T03:  $a \rightarrow c \rightarrow d \rightarrow b \rightarrow e$

T04:  $a \rightarrow c \rightarrow d \rightarrow e \rightarrow b$

T05:  $c \rightarrow a \rightarrow b \rightarrow d \rightarrow e$

T06:  $c \rightarrow a \rightarrow d \rightarrow b \rightarrow e$

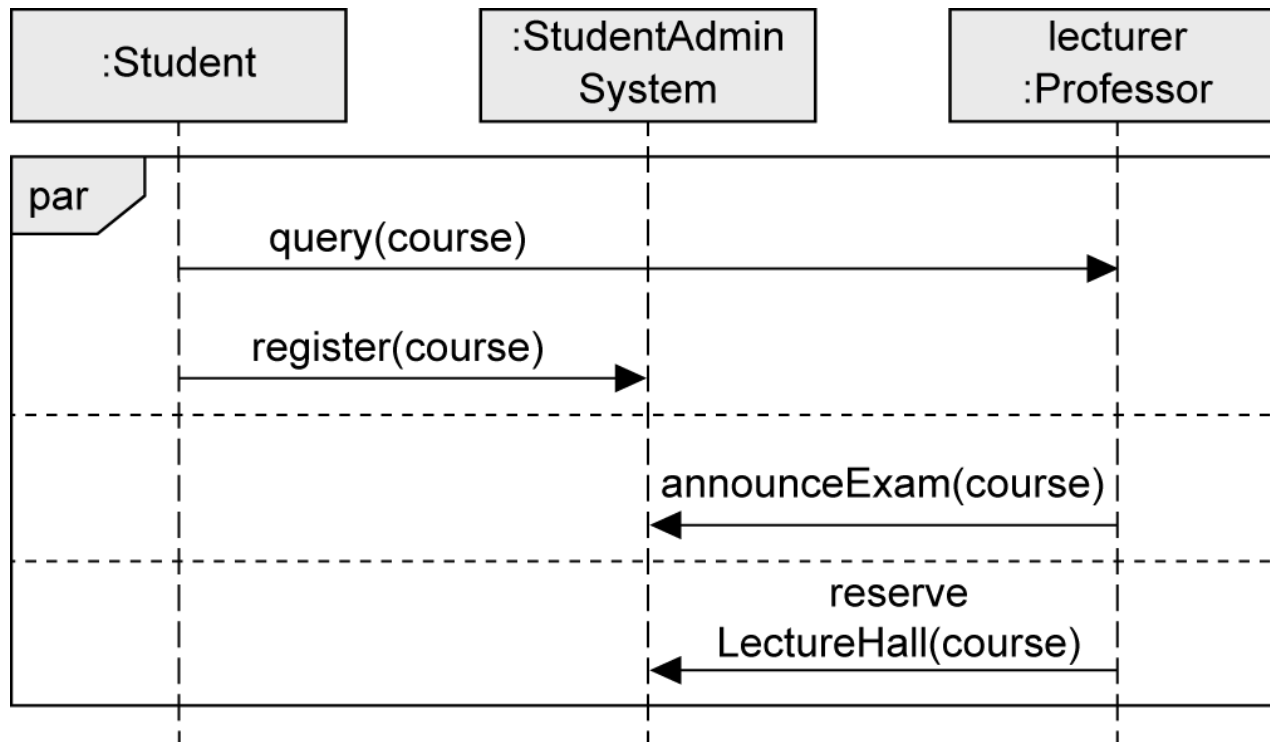
T07:  $c \rightarrow a \rightarrow d \rightarrow e \rightarrow b$

T08:  $c \rightarrow d \rightarrow a \rightarrow b \rightarrow e$

T09:  $c \rightarrow d \rightarrow a \rightarrow e \rightarrow b$

T10:  $c \rightarrow d \rightarrow e \rightarrow a \rightarrow b$

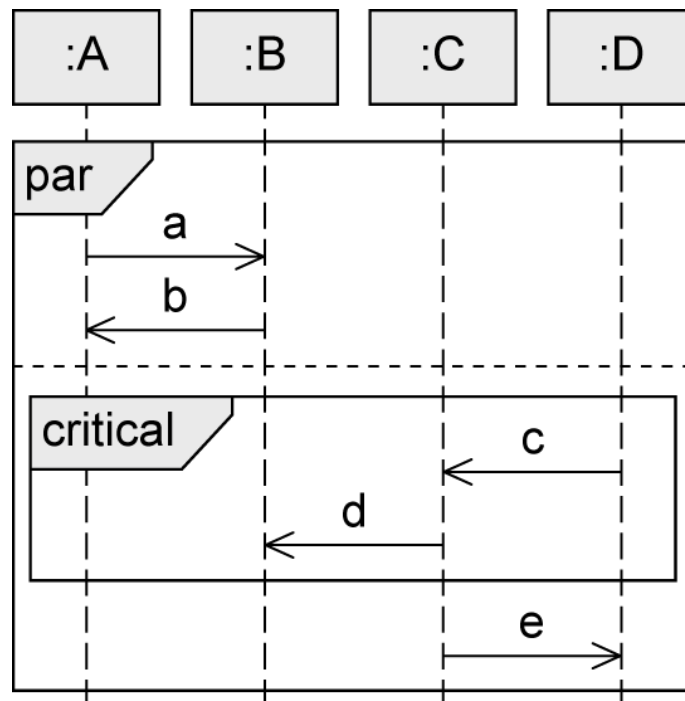
# Example: par fragment



# critical fragment

## Model atomic areas within indeterministic execution

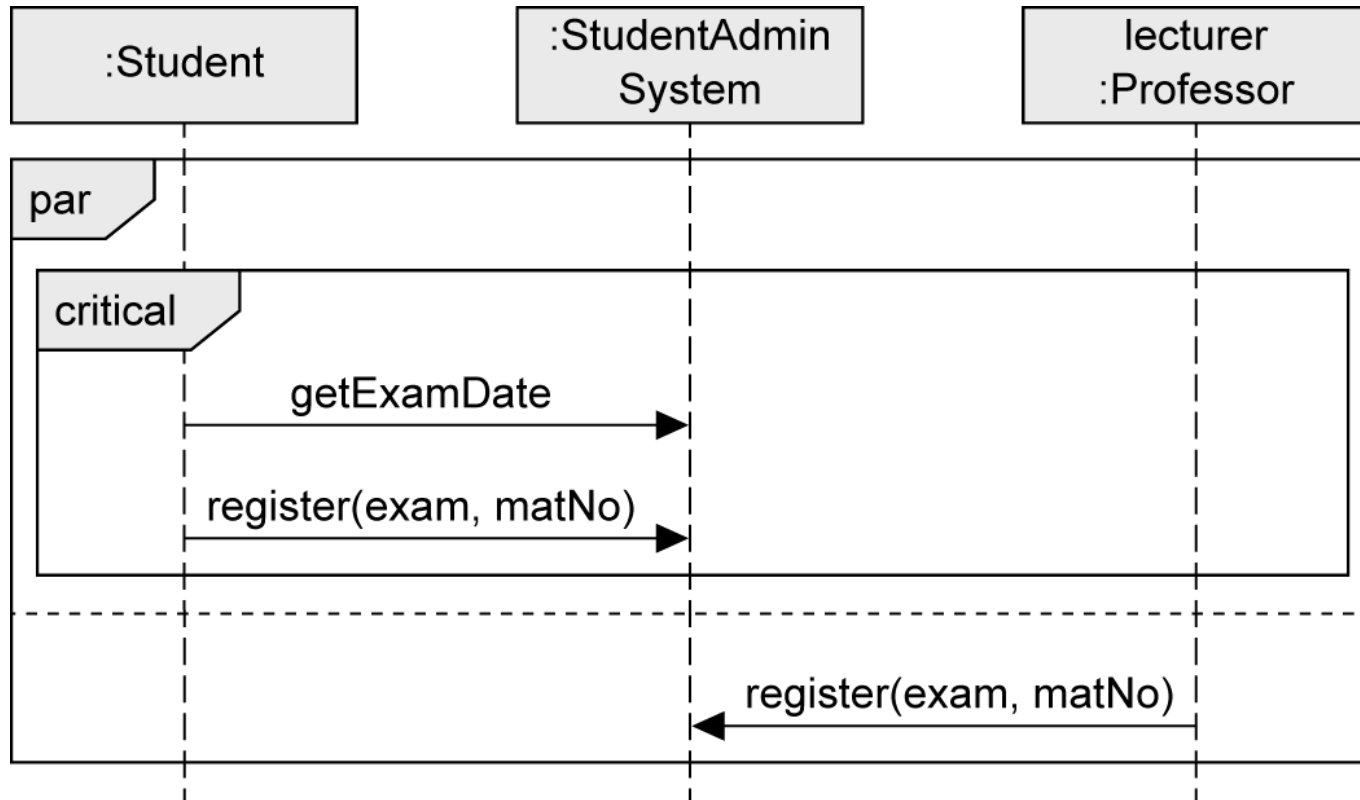
- To make sure that certain parts of an interaction are not interrupted by unexpected events



### Traces:

T01:  $a \rightarrow b \rightarrow c \rightarrow d \rightarrow e$   
 T02:  $a \rightarrow c \rightarrow d \rightarrow b \rightarrow e$   
 T03:  $a \rightarrow c \rightarrow d \rightarrow e \rightarrow b$   
 T04:  $c \rightarrow d \rightarrow a \rightarrow b \rightarrow e$   
 T05:  $c \rightarrow d \rightarrow a \rightarrow e \rightarrow b$   
 T06:  $c \rightarrow d \rightarrow e \rightarrow a \rightarrow b$

# Example: critical fragment



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# Filters and Assertions



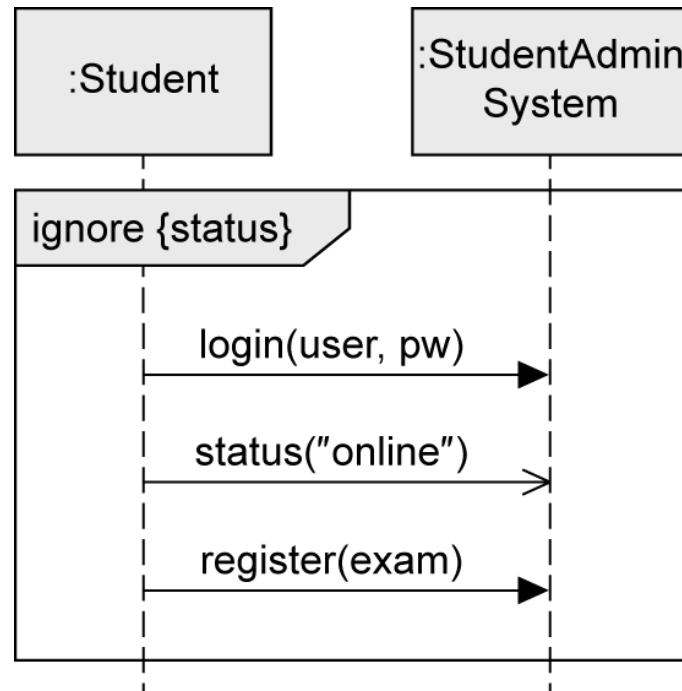
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# ignore fragment

## Model irrelevant messages

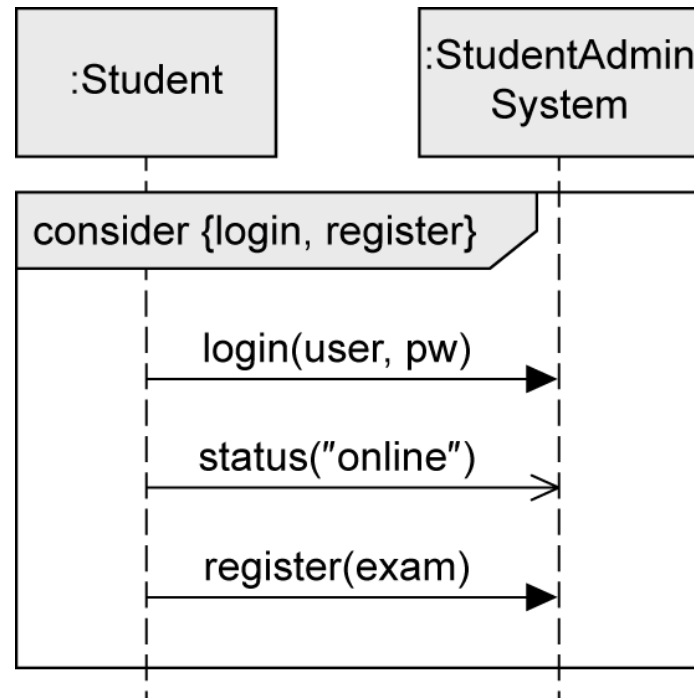
- Messages that occur at runtime without notable significance
- Exactly one operand
- Irrelevant messages in curly brackets after the keyword



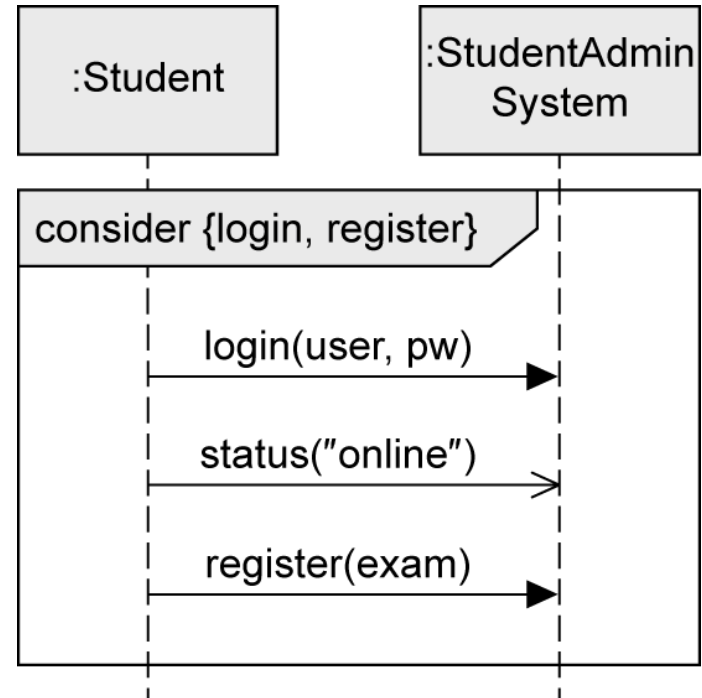
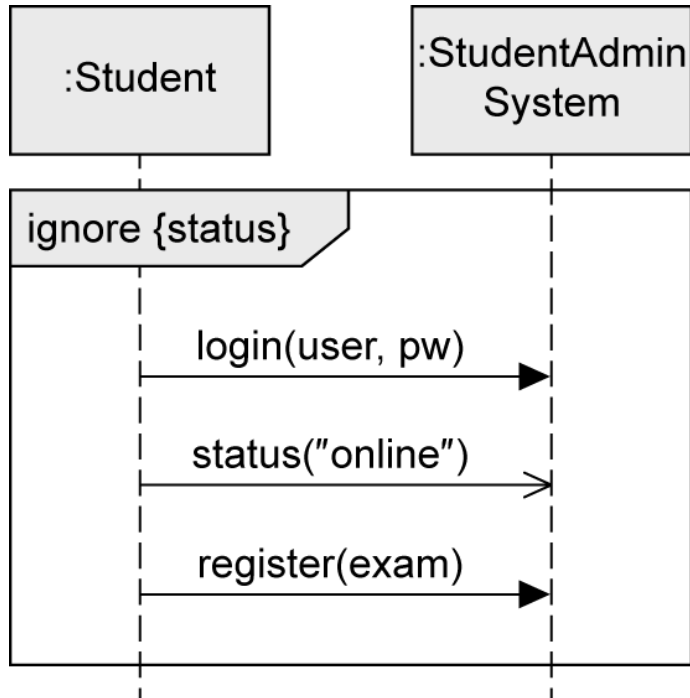
# consider fragment

## Model messages with particular importance

- Exactly one operand
- Complementary to `ignore` fragment
- Considered messages in curly brackets after the keyword



# ignore VS. consider

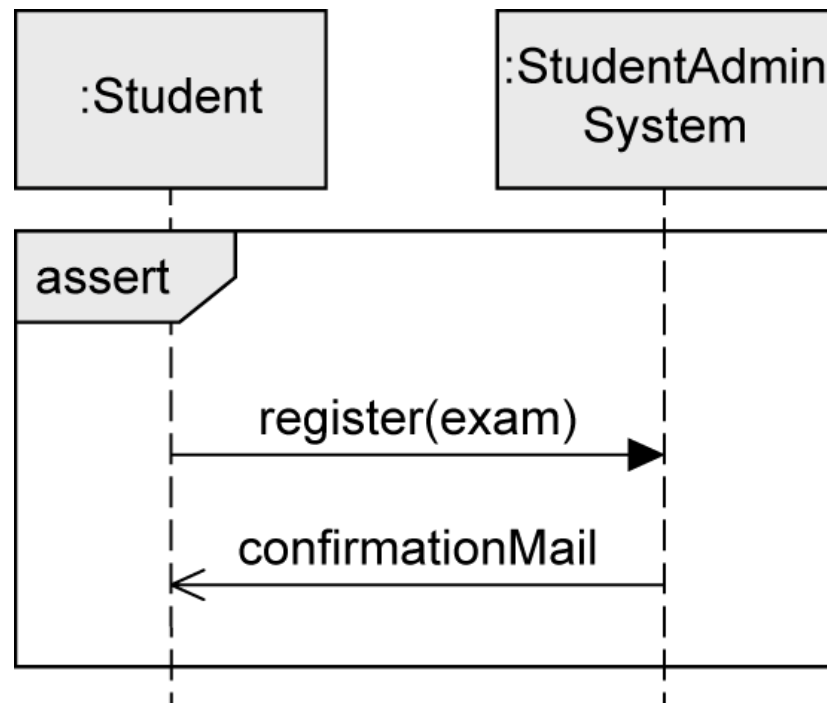


**These two ways of modeling the interaction are equivalent.**

# assert fragment

## Model an interaction as mandatory

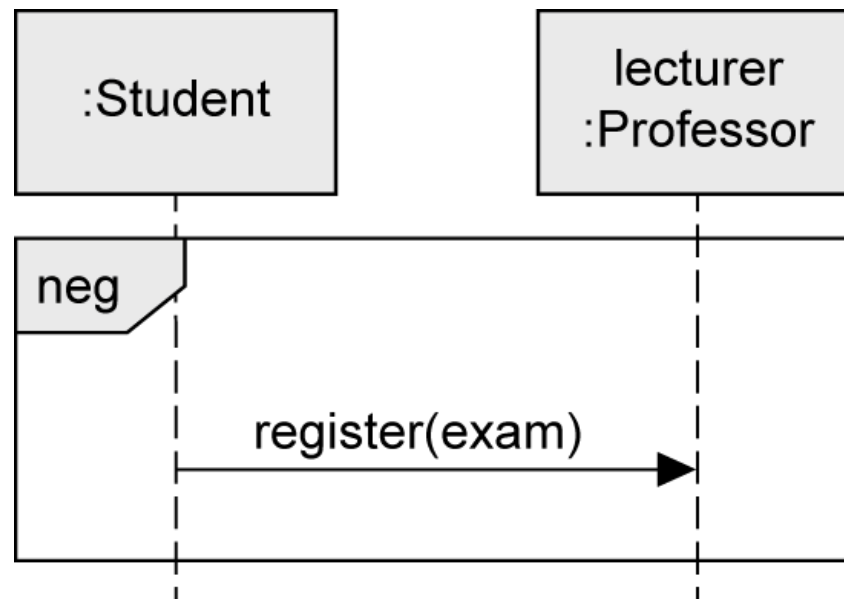
- Deviations that occur in the real world but are not included in the fragment lead to an error (not permitted)
- Reinforces the completeness of the diagram part



# neg fragment

## Model important invalid interactions

- Describing situations that must not occur
- Purpose:
  - Explicitly highlighting frequently occurring errors
  - Depicting relevant, incorrect sequences

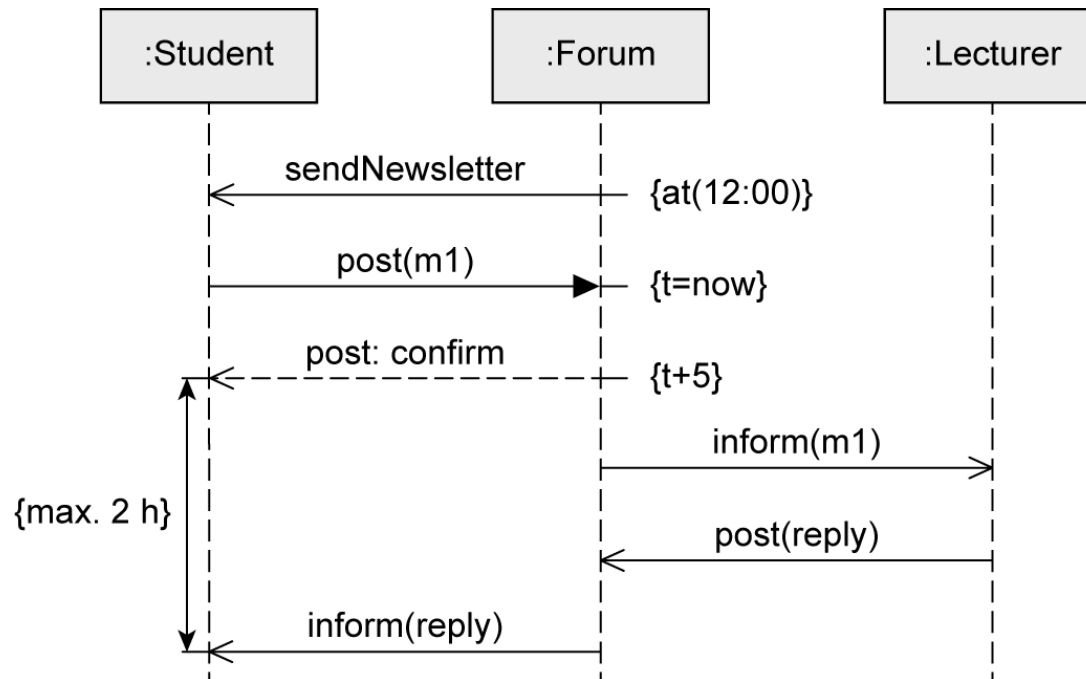


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# Further Modelling Elements

# Time constraints

- Time for event occurrence
  - Relative: e.g., after(5sec)
  - Absolute: e.g., at(12:00)
- Time between two events: {lower..upper}, e.g., {12:00..13:00}
- Current time as `now`: assign to attribute and use in a time constraint

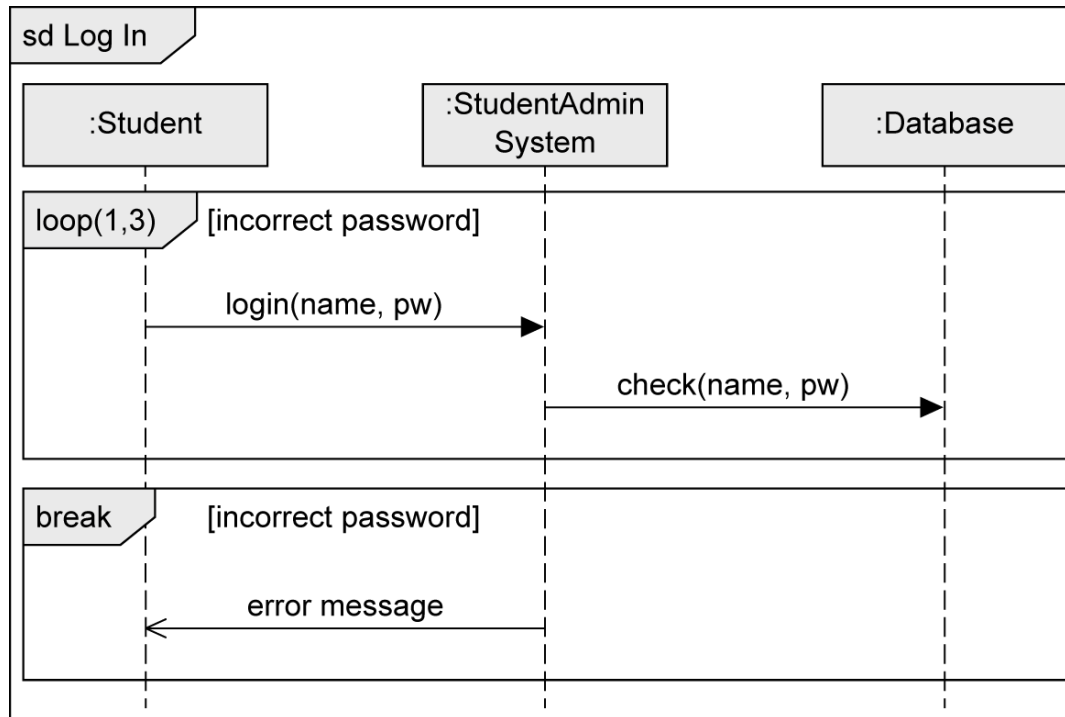




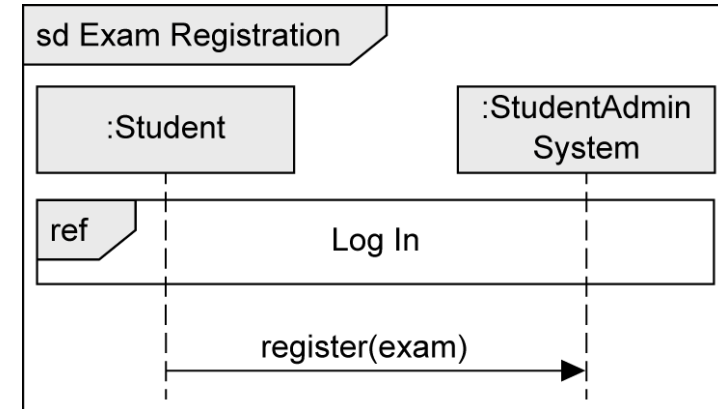
# Interaction reference

- Integrates one sequence diagram into another one via `ref`

## Definition

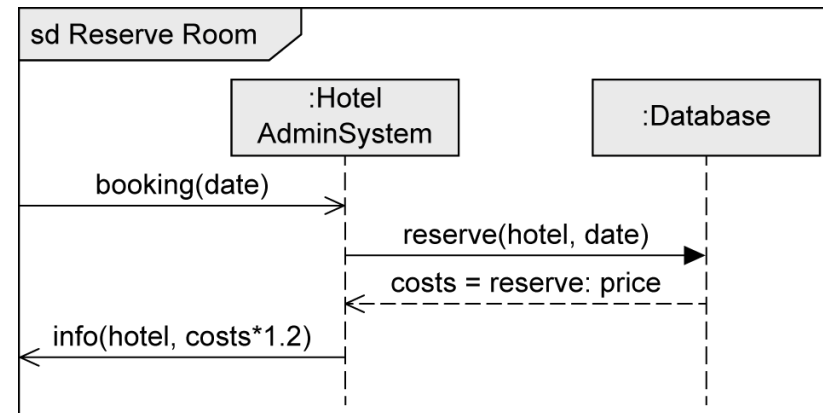
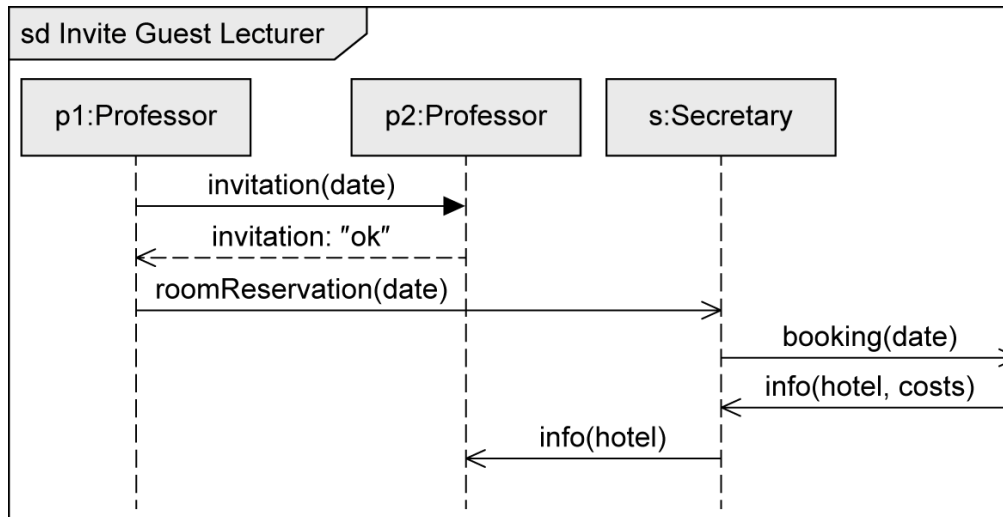


## Usage



# Gates

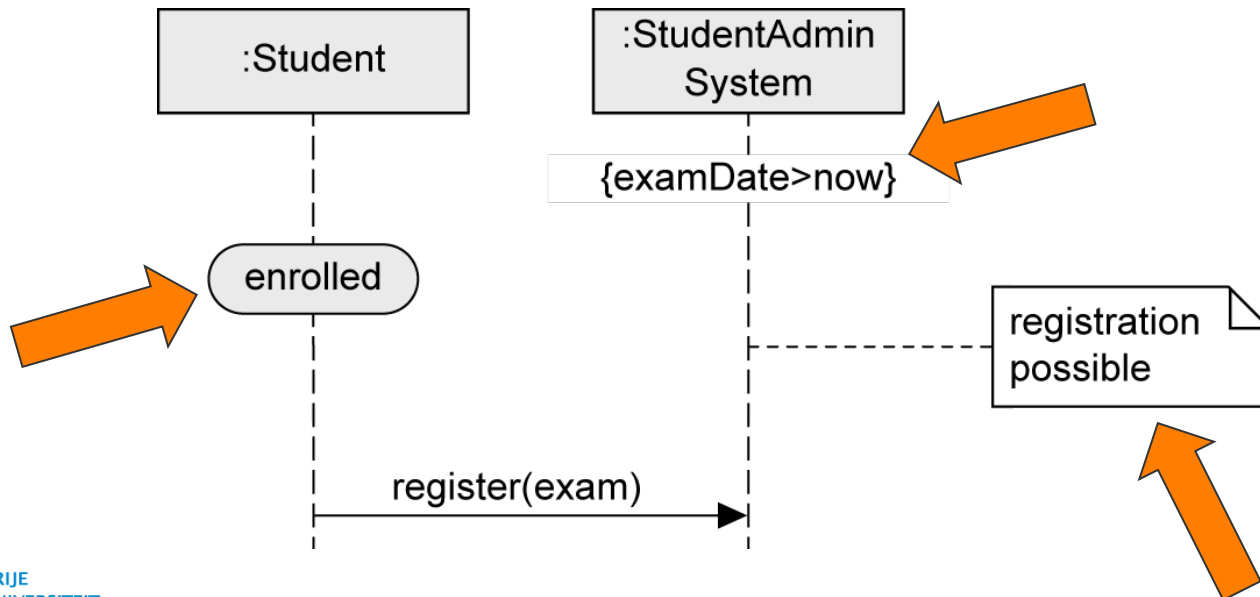
- Allow you to send and receive messages beyond the boundaries of interaction fragments or combined fragments
- Visualized by messages touching / originating from boundary



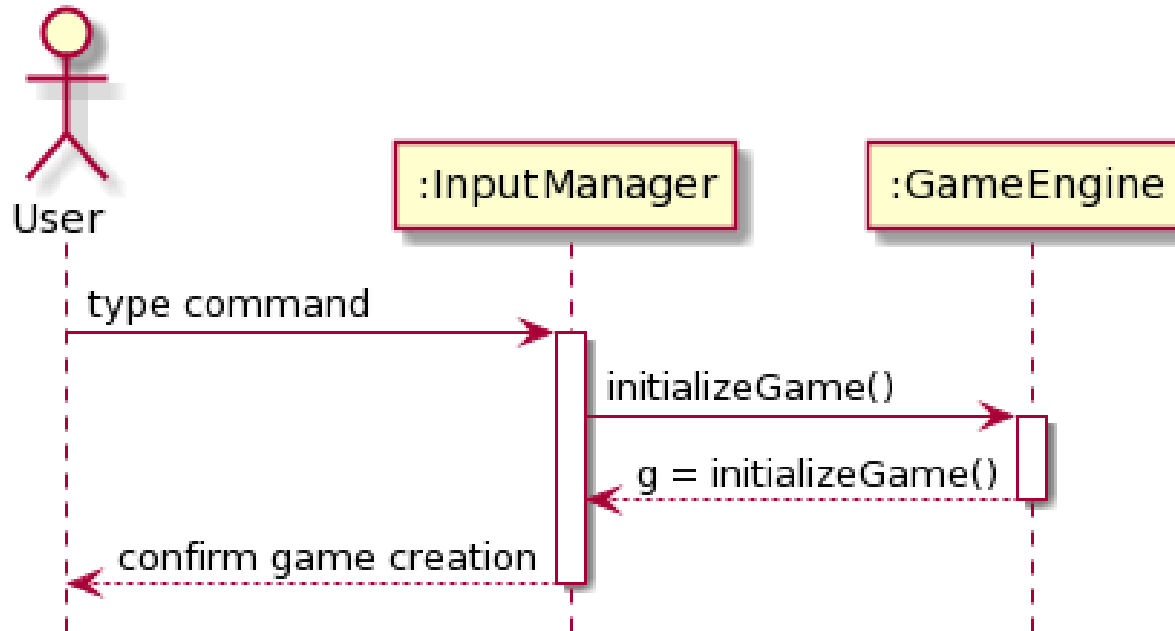
# State invariants

- Assert that a condition must be fulfilled at a certain time
- Evaluation before the subsequent event occurs
- If the state invariant is not `true`, either the model or the implementation is incorrect
- Three alternative notations:

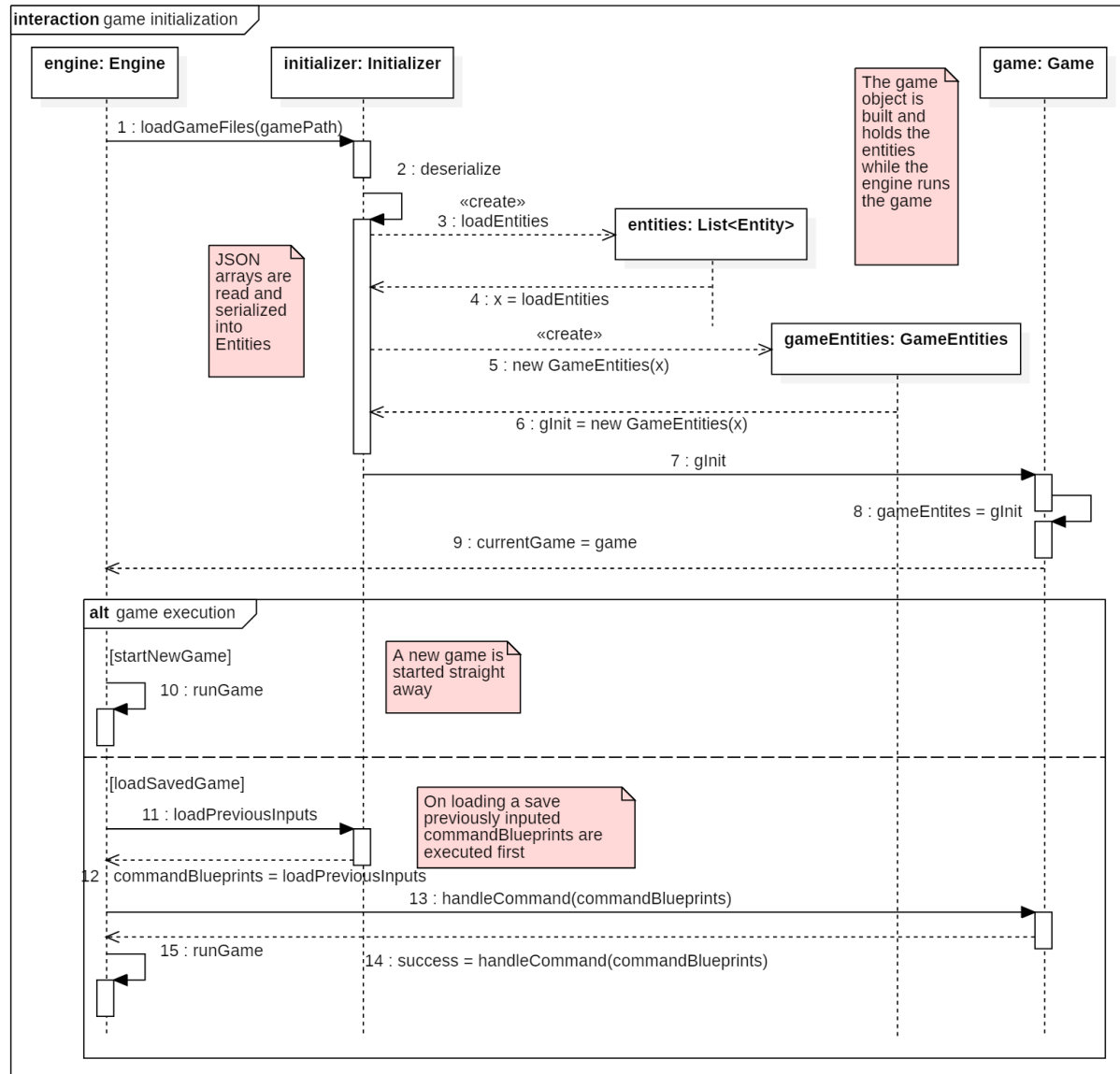
**Useful for linking your state machines and sequence diagrams**



# How to show user interaction



# A final example



# Key takeaways

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- You can now model how objects interact with each other!
- State machine diagram
  - Internal behavior of your objects
- Sequence diagram
  - How objects interact with each other (aka external behavior)
  - Stakeholders of your system can also be involved
  - Many options to model complex control flow  
(**combined fragments**)
    - Branches and loops
    - Concurrency and order
    - Filters and assertions

# Readings

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- UML@Classroom: An Introduction to Object-Oriented Modeling – Chapter 6
- A Philosophy of Software Design, Ch. 10, 11, 12