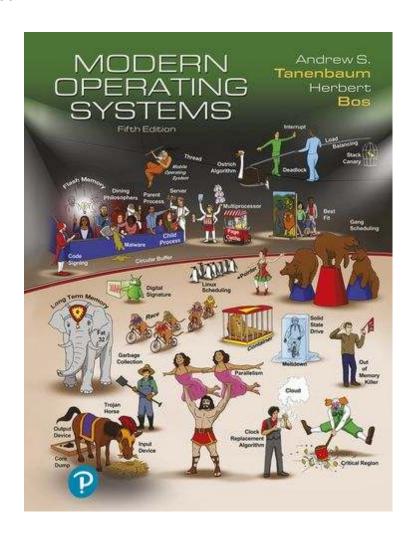
Modern Operating Systems

Fifth Edition



Chapter 3

Memory Management



Memory

Paraphrase of Parkinson's Law, "Programs expand to fill the memory available to hold them."

My laptop with 32GB of RAM has 20,000 times more memory than the IBM 7094 (32768 words of 36 bits)—the largest computer in the world in the early 1960s



Memory

- Memory Abstractions
- Virtual Memory
- Page Replacement Algorithms
- Design Issues for Paging Systems

No Memory Abstraction: Monoprogramming

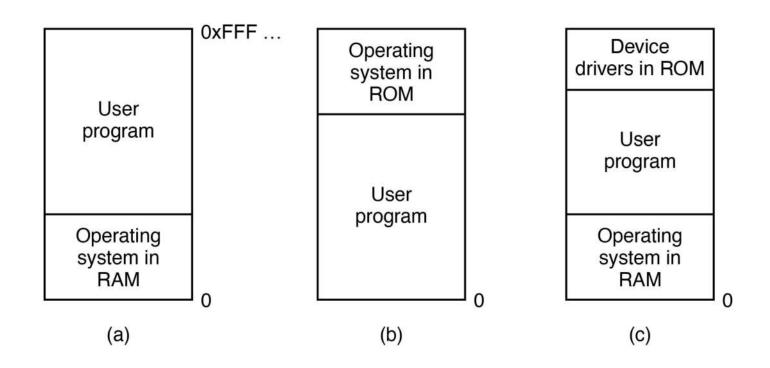


Figure 3-1. Three simple ways of organizing memory with an operating system and one user process.



No Memory Abstraction: Multiprogramming

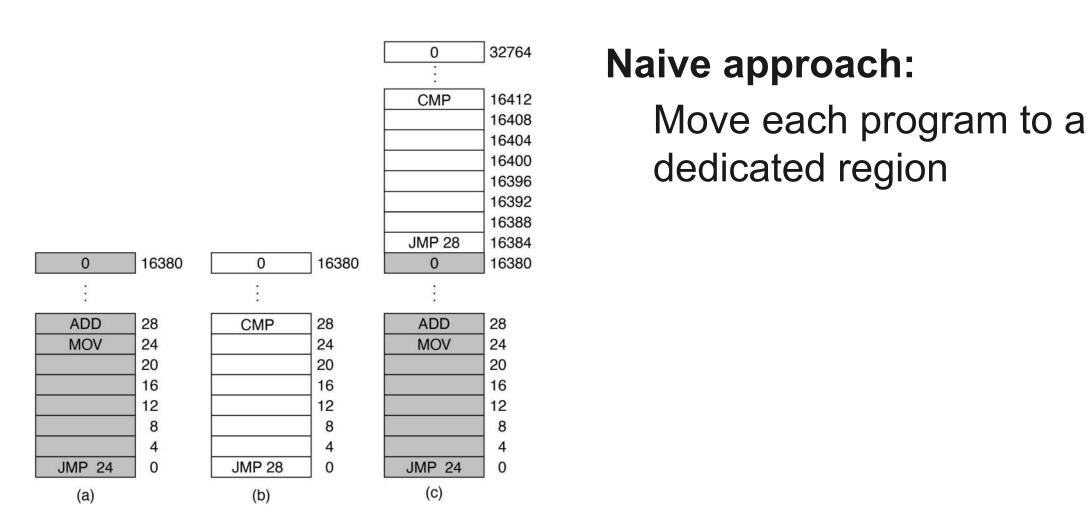


Figure 3-2. Relocation problem. Two 16 KB programs loaded consecutively into memory.



No Memory Abstraction: Multiprogramming

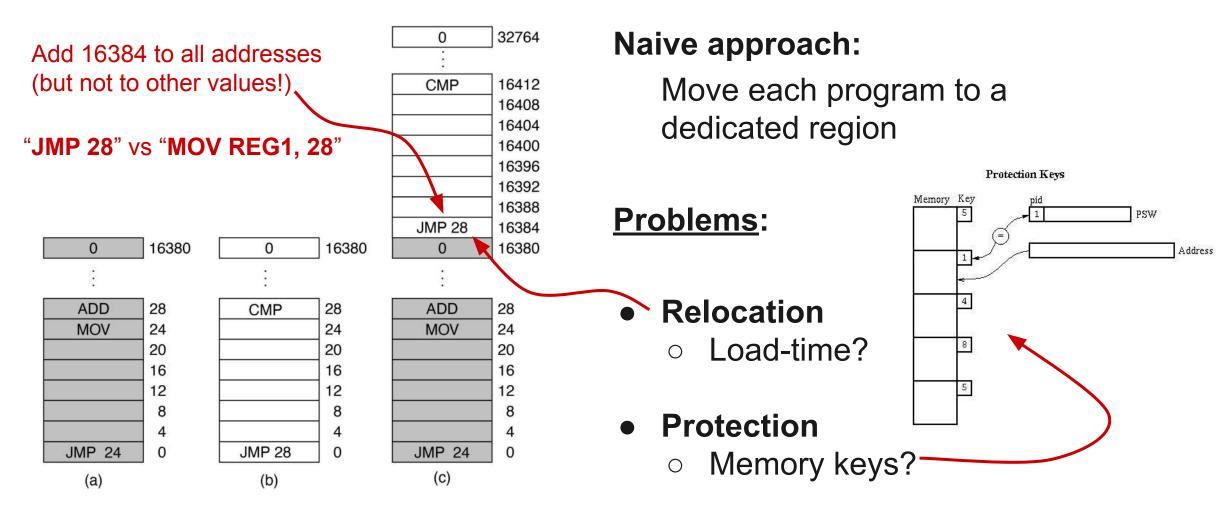


Figure 3-2. Relocation problem. Two 16 KB programs loaded consecutively into memory.



Memory Abstraction: Address Spaces

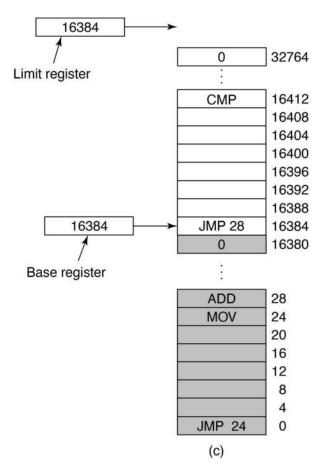


Figure 3-3. Base and limit registers

- Base register operates dynamic relocation
- Limit register enforces protection

Checks for MOV Reg1, Addr:

IF(Addr > LIMIT) → NOT OKAY

IF(BASE + Addr < BASE) → NOT OKAY

What if we run out of memory?

- Simplest solution: swapping of processes
 - bring in entire process, run it for a while, then put it back on disk/SSD
 - Idle processes do not take up any memory when they are not running
- Alternative: virtual memory ⇒ We will discuss this later!



An Improvement: Dynamic Partitions and Swapping (1/2)

Swapping may lead to memory fragmentation

→ Memory compaction

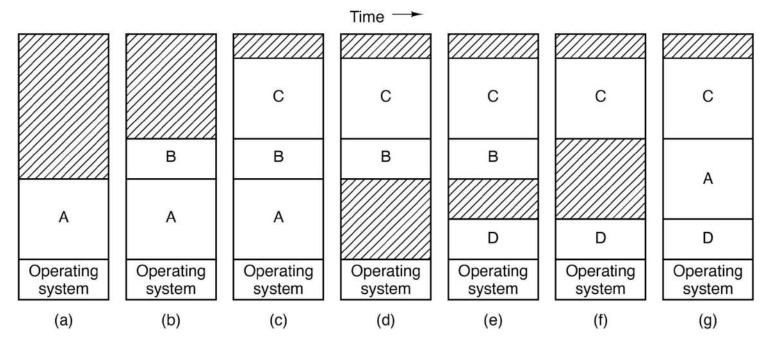


Figure 3-4. Memory allocation changes as processes come into memory and leave it.



An Improvement: Dynamic Partitions and Swapping (2/2)

Problem:

 We need to allow extra room for process growth

Issues:

- How much extra room?
 - Mem usage vs. OOM (Out-Of-Memory) risk
- What to do on OOMs?
 - Kill process
 - Relocate process
 - Swap out

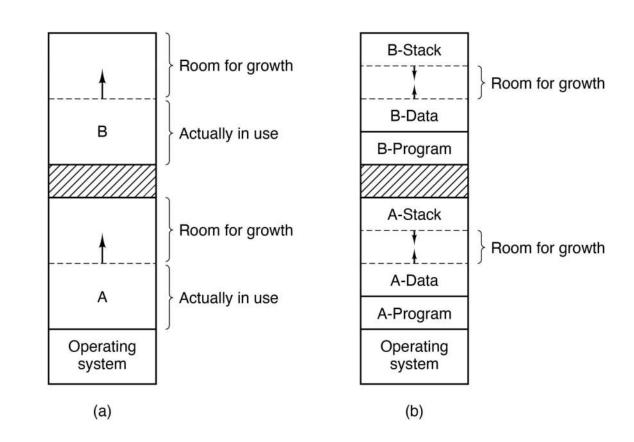


Figure 3-5. Allocating space for...

- (a) ... growing data segment
- (b) ... growing stack + growing data segment



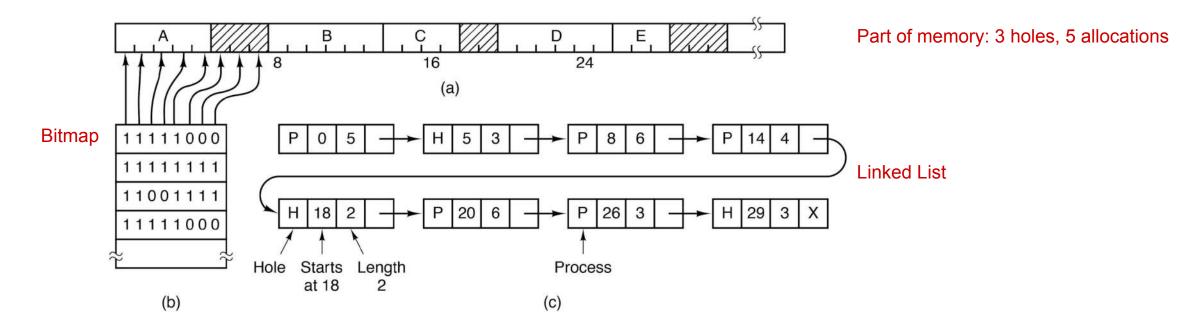
Memory Management

Question: Which part of the memory is allocated?

- Divide memory in blocks
 - e.g. each block is 4 bytes
- Solution 1: Bitmap keeps track of which blocks are allocated
- Solution 2: Linked list keeps track of unallocated memory



Memory Management: Bitmaps vs Linked Lists



- Bitmap: finding holes requires (slow) scanning
- List: common vs. separate process/hole lists
 - Slow allocation vs. slow deallocation
 - Holes sorted by address for fast coalescing



Memory Management with Linked Lists

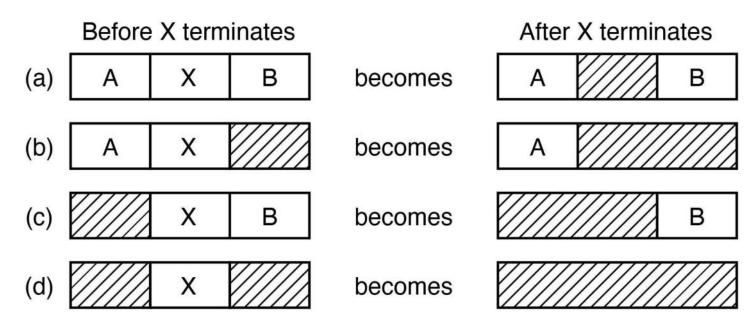


Figure 3-7. Four neighbor combinations for the terminating process, X.

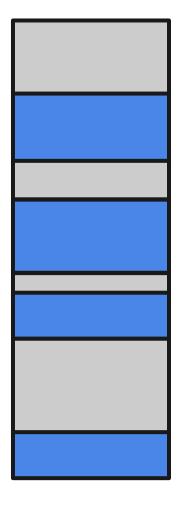
In practice, a doubly linked is often used ⇒ makes freeing easy

- Can easily check if previous free
- Can easily adjust the pointers



Memory Allocation Schemes

- First Fit: Take first fitting hole (MINIX 3)
 - Simplest option
- Next Fit: Take next fitting hole
 - Slower than first fit in practice
- Best Fit: Take best fitting hole
 - Prone to fragmentation
- Worst Fit: Take worst fitting hole
 - Poor performance in practice
- Quick Fit: Keep holes of different sizes
 - Poor coalescing performance
- Buddy allocation scheme (Linux)
 - Improves quick fit's coalescing performance





Extra material

The next few slides contain information that is not found in Chapter 3. It illustrates how memory allocators work in practice, in this case, in an operating system such as Linux. You can find some of this information in Chapter 10.4.



Buddy Memory Allocation

Extra material. See also: Sec.10.4

Originally: one area of size 64 "chunks"

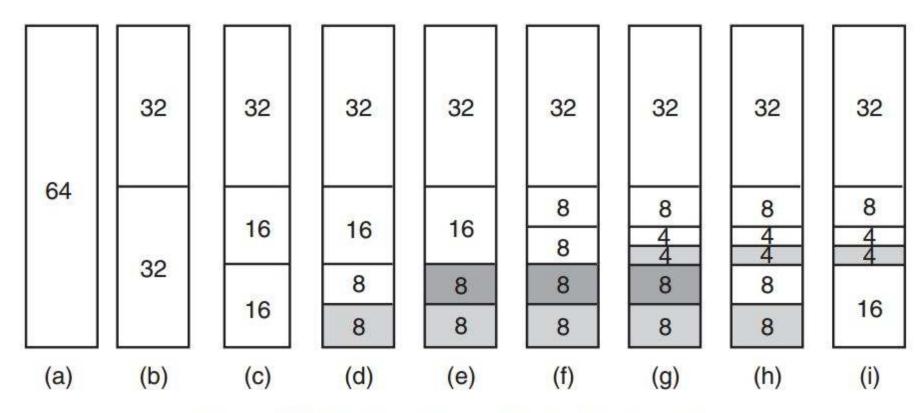


Figure 10-17. Operation of the buddy algorithm.



Buddy Memory Allocation (Based on Wikipedia Example)

https://en.wikipedia.org/wiki/Buddy_memory_allocation

Step	4K	4K	4K	4K	4K	4K	4K	4K	
2.1	2 ³	- (!							
2.2	2 ²				2 ²				
2.3	21		21		22				
2.4	20	20	2 ¹		2 ²				
2.5	A: 2 ⁰	20	21		2 ²				
3	A: 2 ⁰	2 ⁰	B: 2 ¹		2 ²				
4	A: 2 ⁰	C: 2 ⁰	B: 2 ¹		2 ²				
5.1	A: 2 ⁰	C: 2 ⁰	B: 2 ¹		2 ¹		21		
5.2	A: 2 ⁰	C: 2 ⁰	B: 2 ¹		D: 21		21		
6	A: 2 ⁰	C: 2 ⁰	2 ¹		D: 21		2 ¹		
7.1	A: 2 ⁰	C: 2 ⁰	2 ¹		2 ¹		21		
7.2	A: 2 ⁰	C: 2 ⁰	2 ¹		22				
8	20	C: 2 ⁰	2 ¹		2 ²				
9.1	20	2 ⁰	2 ¹		2 ²				
9.2	21	21			2 ²				
9.3	2 ²				2 ²				
9.4	23				L.				

Terminology:

Block of order n: (basic block size) * 2^n Here, basic block size = 4K

The following requests may have occurred:

- 1. The initial situation.
- 2. A requests 4 K (\Rightarrow order 0) \rightarrow repeated splits (Steps 2.1-5)
- 3. B requests 9 K (\Rightarrow order 1) \rightarrow available (Step 3)
- 4. C requests 3 K (\Rightarrow order 0) \rightarrow available (Step 4)
- 5. D requests 7 K (\Rightarrow order 1) \rightarrow split order 2 (Steps 5.1-2)
- 6. B releases memory → free order 1 block (Step 6)
- 7. D releases memory → free order 1 + coalesce (Steps 7.1-2)
- 8. A releases memory → free order 0 block.(Step 8)
- 9. C releases memory \rightarrow free order 0 block + 3 x coalesce



Slabs and Buddies

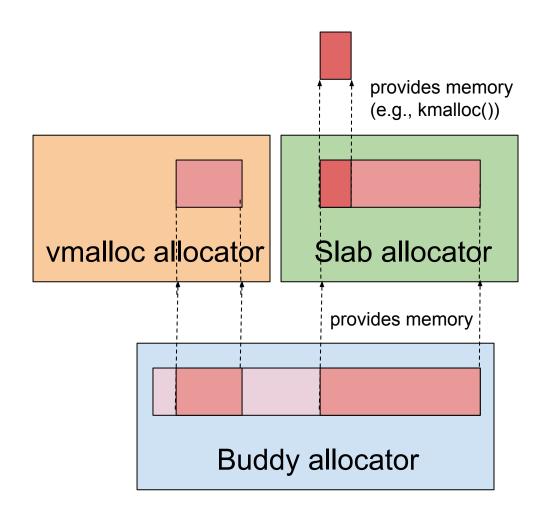
Extra material

Buddy allocator:

Fast and limits external fragmentation but considerable internal fragmentation

Often combined with other allocators E.g., in Linux, the vmalloc and slab allocators sit on top of buddy allocator

So slab allocator gets memory from buddy and parcels this out to callers of kmalloc()





Slab Allocator: Motivation

Extra material

Allocation + freeing of objects of the same type: very common in OS

- Speed is of the essence
- Unfortunately, allocating, initializing, and destroying objects all take time
 - E.g., list of free chunks → allocation requires traversing list to find a chunk of sufficient size

Goal:

- make metadata for allocator (e.g., to track what memory is free) very fast
- cache as much as possible

Solution:

Slab allocator



Slab Allocator: History

Extra material

Slab caches are an old idea: Jeff Bonwick (Sun Microsystems) 1994 Many incarnations

E.g., Linux:

- Adopted SLAB allocators in the 1990s.
- Multiple variants available in the kernel: SLOB, SLAB, SLUB

We will look at the general idea

Slab Allocator: Caching makes things simple and fast

Extra material

To allocate an object:

```
if (there's an object in the cache) {
   take it (no construction required);
} else {
   allocate memory;
   construct the object;
}
```

To free an object:

```
return it to the cache (no destruction required);
```

To reclaim memory from the cache:

```
take some objects from the cache;
destroy the objects;
free the underlying memory;
```



Slab Allocator: Caches for specific objects (or object sizes)

Extra material

Slab allocator supports mem allocation for kernel.

Kernel needs many different temporary objects:

E.g., dentry, mm_struct, inode, files_struct structures.

Temporary kernel objects

- can be both small and large
- are often allocated and often freed (efficiency is crucial)

The buddy allocator, which operates with areas composed of entire frames of memory, is not suitable for this.



Slab Allocator: Reuse and Lookups

Extra material

Goal: efficient memory allocation of objects

- Reduces fragmentation
- Retains allocated memory containing a data object of a certain type for reuse in later allocations of objects of the same type

By reusing freed objects, under favorable circumstances, you can avoid having to reinitialize them (leaving them partially filled in)

With only objects of the same type in a slab ⇒ fast lookup (simple index)



Slab Allocator: Caches for specific objects (or object sizes)

Extra material

For instance: a slab cache for inodes or for 16B objects, etc.

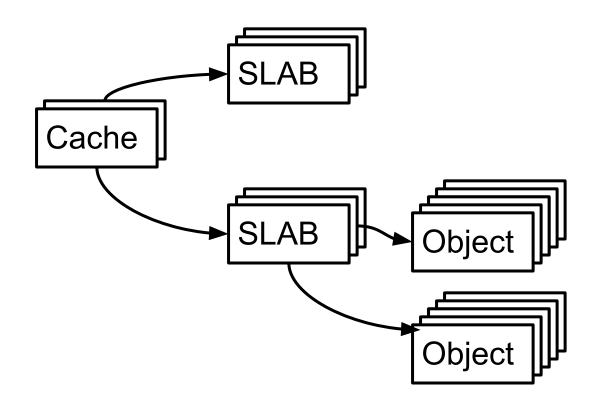
Slab primary unit of currency in slab allocator.

- When allocator needs to grow a cache: acquire an entire slab of objects.
- When allocator reclaims unused memory: relinquish a complete slab.



Slab Cache: Organisation

Extra material



Each slab cache may contain multiple slabs, each of which contains (or points to) multiple objects

See: https://www.kernel.org/doc/gorman/html/understand/understand011.html#Sec:%20Tracking%20Free%20Objects



Slab: Example (1/4)

Extra material

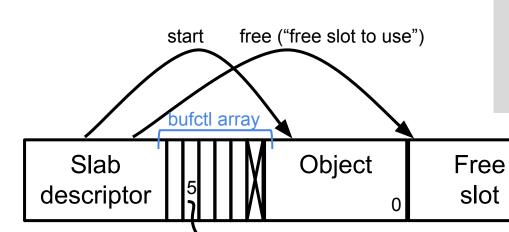
Slab		$ \rangle$	Object	Free		Object	Object	Object	Free	
descriptor		$\coprod M$	0	slot	1	2	3	4	Slot	5

Note 1: Slabs can be implemented in different ways. We will look at one example

Note 2: All slots have the same (known) size, making it easy to find the nth object in the slab

Slab: Example (2/4)

Extra material



In this example, a Slab contains:

- pointer to start of memory with object slots
- index of next free slot ("slot for next allocation")
- bufctl: array of indices ("after this free slot has been used for allocation, the next free slot is...")
- Slots for objects

```
Object Object Object Free Slot 5
```

Every entry in bufctl points to next free object (relative to this one). E.g. "the next free slot after this free slot (1) is the slot at index 5 (last slot)"

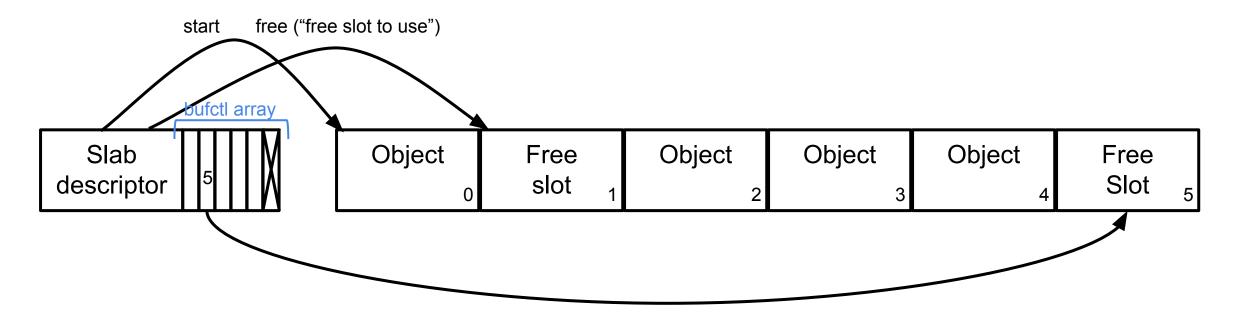
```
Initially: free =0, bufctl [0] = 1, bufctl [1]= 2, etc. Allocation: free points to next free object
```

```
Deallocation of entry n:
bufctl [n]:= free ;
free := n:
```



Slab: Example (3/4)

Extra material



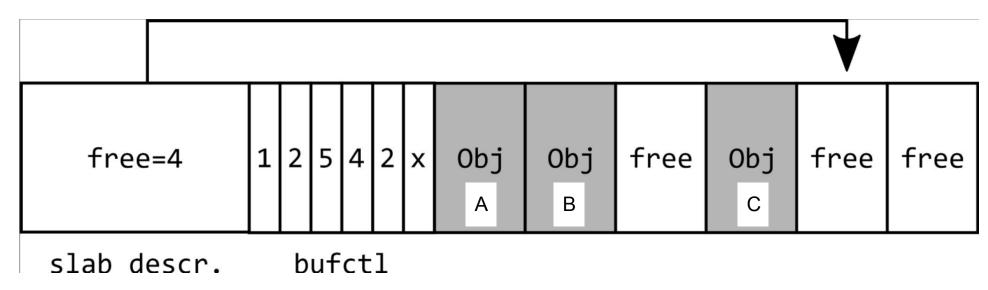
For larger objects the memory area can be decoupled from the descriptor



Slab: Example (4/4)

Quiz

Extra material



Given the initial state of the slab above and the following operations:

Q: Where is F allocated?

SLAB caches in Linux Extra material

Dedicated ones and "general" ones.

General: different powers of two

The following dedicated caches exist:

Check /proc/slabinfo for all slab caches



/proc/slabinfo

number of objects in use

total number of allocated objects

size of objects in this slab, in bytes

number of objects stored in each slab

number of pages allocated for each slab

number of active slabs

total number of slabs

Name	active	num	object	objs	pages	activ	e num
	objs	objs	size	per	per	slabs	slabs
			_	slab	slab	×	×
inode_cache	9174	9660	568	28	4	345	345
dentry	1532244	1532244	192	42	2 30	6483	36483
buffer_head	794118	794118	104	39	1 20	9362	20362
vm_area_struct	195838	204286	176	46	2	4441	4441
mm_struct	7658	8352	896	36	8	232	232
files_eache	5831	7314	784	46	8	159	159
signal_cache	3111	3780	1088	30	8	126	126
sighand cache	2094	2310	2112	15	8	154	154
task_struct	2793	3258	1776	18	8	181	181
anon_vma	91453	99584	64	64	1 :	1556	1556
radix_tree_node/	360485	553224	568	28	4 19	9758	19758
dma-kmalloc-8192	0	0	8192	4	8	0	0
dma-kmalloc-4096	0	0	4096	8	8	0	0
dma-kmalloc-2048	Ø	0	2048	16	8	0	0
dma-kmalloc-1024	0	0	1024	32	8	0	0
dma-kmalloc-512	32	32	512	32	4	1	1
dma-kmalloc-256	0	0	256	32	2	0	0
dma-kmalloc 128	0	0	128	32	1	0	0
dma-kmalloc-64	0	0	64	64	1	0	0
dma-kmalloc-32	0	0	32	128	1	0	0
dma-kmalloc-16	0	0	16	256	1	0	0
dma-kmalloc-8	0	0	8 !	512	1	0	0
dma-kmalloc-192	0	0	192	42	2	0	0
dma-kmalloc-96	0	0	96	42	1	0	0
kmalloc-8192	256	268	8192	4	8	67	67
kmalloc-4096	1595	1680	4096	8	8	210	210
kmalloc-2048	3200	3664	2048	16	8	229	229
kmalloc-1024	6786	7584	1024	32	8	237	237
kmalloc-512	12203	36096	512	32	4	1128	1128
kmalloc-256	64100	101408	256	32	2	3169	3169
kmalloc-128	138762	215136	128	32	1 (6723	6723
kmalloc-64	482131	782976	64	64	1 1	2234	12234
kmalloc-32	25499	33024	32	128	1	258	258

End of extra material



Virtual Memory

- There is a need to run programs that are too large to fit in memory
- Solution adopted in the 1960s, split programs into little pieces, called overlays
 - Kept on the disk, swapped in and out of memory
 - Initially, only the overlay manager (OM) was loaded
 - The OM would then load overlay 0 and run it
 - When done, it would tell the OM to load overlay 1, etc.
- Nowadays, we have a better solution: virtual memory
 - Often implemented using paging



Virtual memory

Problem: So far memory can only be given to processes in contiguous pieces

Solution:

- Create for the process the illusion of a large (e.g., 48 bit) address space
- This is known as the virtual address space
- The (much more limited) RAM is known as physical memory
- Translate virtual addresses (as used by the process) into physical addresses
- Typically done in the MMU

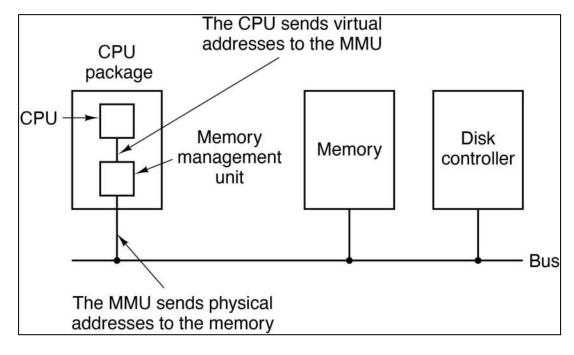


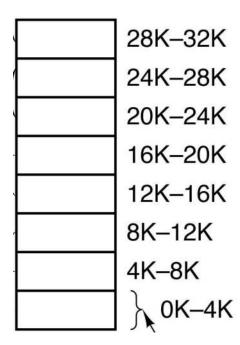
Figure 3-8. The position and function of the MMU.



Virtual memory and paging

Modern systems use paging:

- Divide physical and virtual memory into pages of fixed size (e.g. 4096 bytes)
- Translate virtual pages into physical pages (frames)





Virtual Address Space vs. Physical Address Space and Page Tables

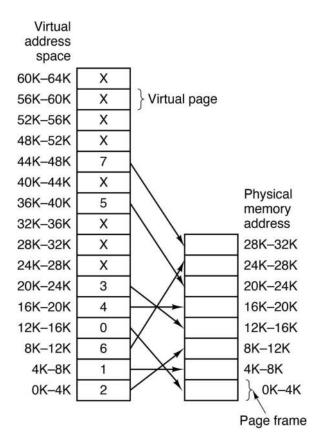


Figure 3-9. The relation between virtual and physical memory addresses is given by the page table.

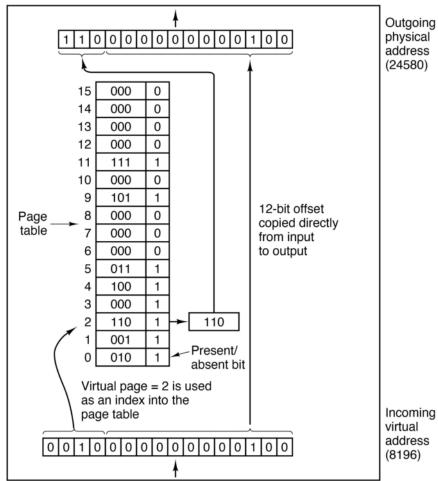


Figure 3-10. The internal operation of the MMU with 16 4-KB pages.



Structure of a Page Table Entry

Questions:

- Output Description
 Output
- How many page tables?

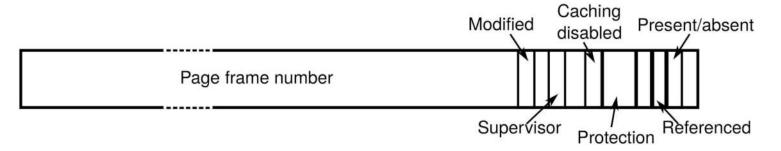


Figure 3-11. A typical page table entry.

- 4KB page size (typical)
- 32 bit systems:
 - 32 bit address space and 32 page table entries (PTEs)
- 64 bit systems
 - really: 48-bit or 57-bit address space (!) and 64-bit PTEs



0

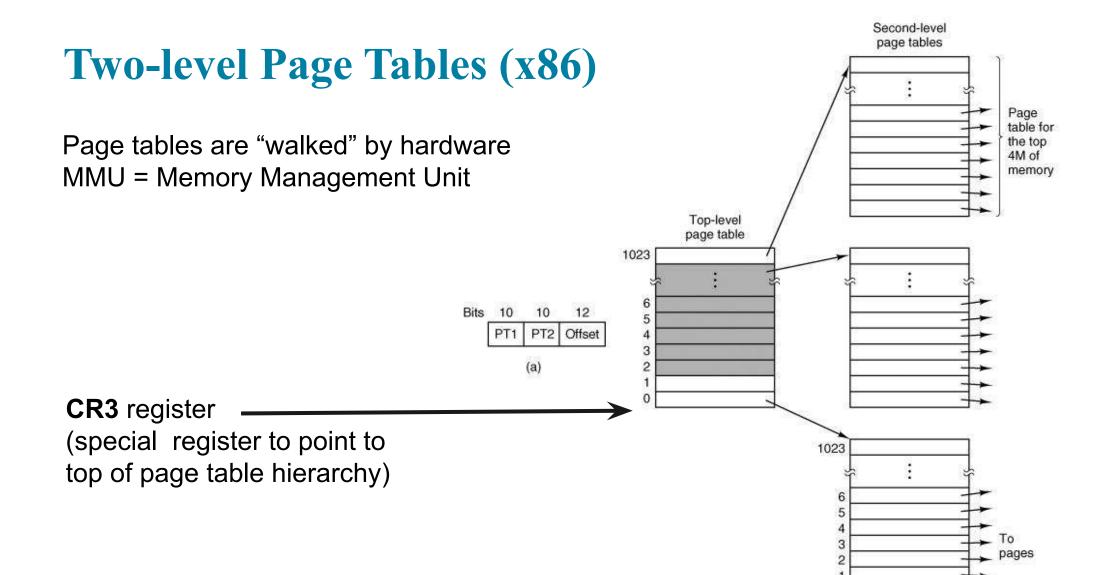
Page Table Sizes

A very large virtual address space would lead to a very large page table → not nice!

Possible solutions:

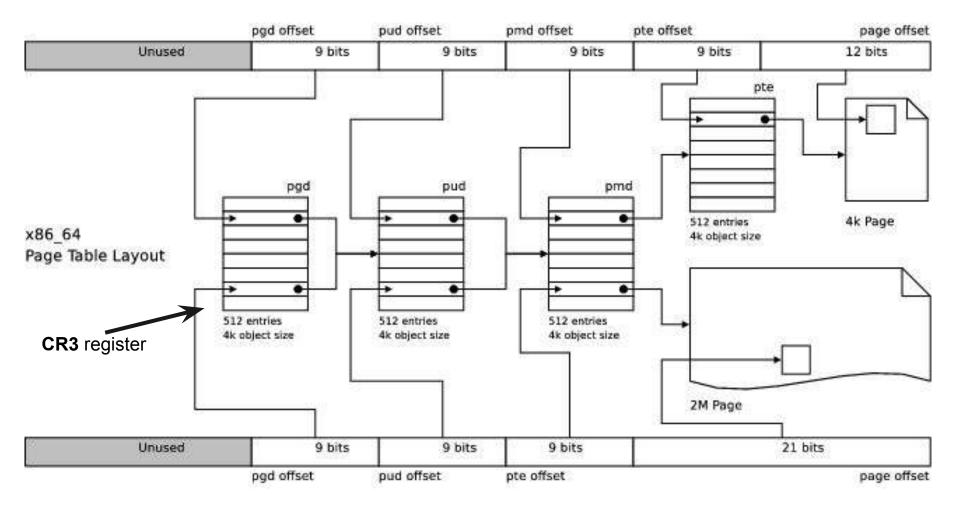
- multi-level page tables
- inverted page tables







Four-level Page Tables (x86-64)



PGD: Page Global Directory, PUD: Page Upper Directory, PMD: Page Mid-level Directory, PTE: page table entry



Inverted Page Tables (IA-64)

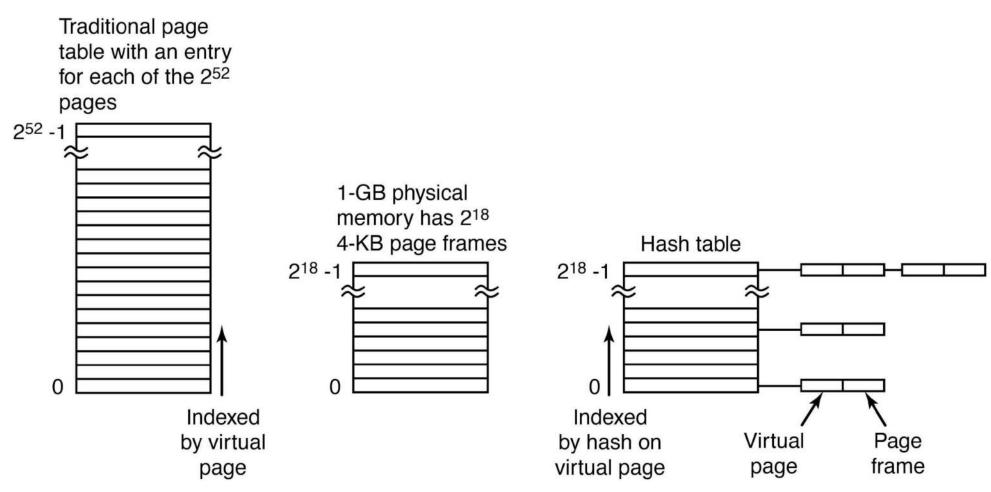
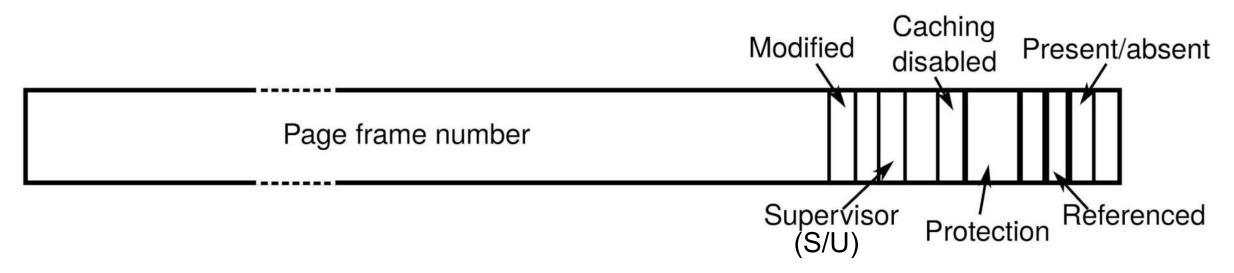


Figure 3-14. Comparison of a traditional page table with an inverted page table.



Going back to PTEs a minute...

Extra material



We have these at each level

What happens if we combine them?



What happens if...

Extra material

- 1. PD entry says : S/U==U, Prot==RO (*)
 PT entry says : S/U==U, Prot==R/W
- 2. PD entry says : S/U==U, Prot==RW PT entry says : S/U==U, Prot==RO
- 3. PD entry says : S/U==U
 PT entry says : S/U==S
- 4. PD entry says : S/U==S
 PT entry says : S/U==U

*S/U simply means supervisor flag (which can be **S**upervisor or **U**ser)



Combining Protection of Both Levels of Page Tables

Extra material

From the Intel® 64 and IA-32 Architectures Software Developer's Manual Volume 3A:

For any one page, the protection attributes of its page-directory entry (first-level page table) may differ from those of its page-table entry (second-level page table). The processor checks the protection for a page in both its page-directory and the page-table entries. Table 4-3 shows the protection provided by the possible combinations of protection attributes when the WP flag is clear.



Extra material

Perhaps surprising?

Note: CR0 is a special control register in x86

- In principle: protection = strictest subset
- However, if CR0.WP=0, supervisor always has RW access

Table 4-3. Combined Page-Directory and Page-Table Protection

Page-Directory Entry		Page-Table Entry		Combined Effect	
Privilege	Access Type	Privilege	Access Type	Privilege	Access Type
User	Read-Only	User	Read-Only	User	Read-Only
User	Read-Only	User	Read-Write	User	Read-Only
User	Read-Write	User	Read-Only	User	Read-Only
User	Read-Write	User	Read-Write	User	Read/Write
User	Read-Only	Supervisor	Read-Only	Supervisor	Read/Write*
User	Read-Only	Supervisor	Read-Write	Supervisor	Read/Write*
User	Read-Write	Supervisor	Read-Only	Supervisor	Read/Write*
User	Read-Write	Supervisor	Read-Write	Supervisor	Read/Write
Supervisor	Read-Only	User	Read-Only	Supervisor	Read/Write*
Supervisor	Read-Only	User	Read-Write	Supervisor	Read/Write*
Supervisor	Read-Write	User	Read-Only	Supervisor	Read/Write*
Supervisor	Read-Write	User	Read-Write	Supervisor	Read/Write
Supervisor	Read-Only	Supervisor	Read-Only	Supervisor	Read/Write*
Supervisor	Read-Only	Supervisor	Read-Write	Supervisor	Read/Write*
Supervisor	Read-Write	Supervisor	Read-Only	Supervisor	Read/Write*
Supervisor	Read-Write	Supervisor	Read-Write	Supervisor	Read/Write

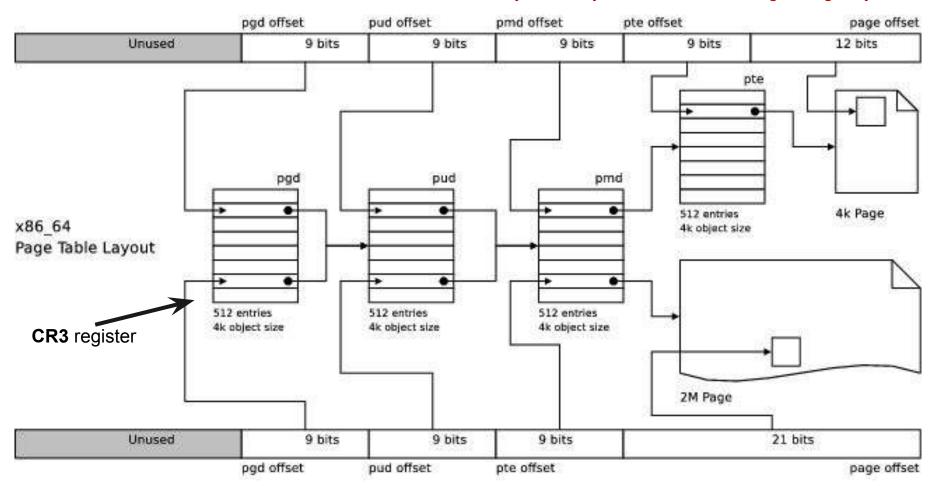
NOTE:



^{*} If CRO.WP = 1, access type is determined by the R/W flags of the page-directory and page-table entries. IF CRO.WP = 0, supervisor privilege permits read-write access.

Four-level Page Tables: Lots of Memory Accesses!

How many memory accesses for reading a single byte?



PGD: Page Global Directory, PUD: Page Upper Directory, PMD: Page Mid-level Directory, PTE: page table entry



Problem: MMU has to translate every single memory access

→ Performance problem

Solution: Cache previous translations, hoping programs exhibit a high degree of locality.

Valid	Virtual Page	Modified	Protection	Page Frame
1	140	1	RW	31
1	20	0	RX	38
1	130	1	RW	29
1	129	1	RW	62
1	19	0	RX	50
1	21	0	RX	45
1	860	1	RW	14
1	861	1	RW	75



Extra material

- How many TLBs?
- When to flush TLB?
- When to expect many TLB misses?

Valid	Virtual Page	Modified	Protection	Page Frame
1	140	1	RW	31
1	20	0	RX	38
1	130	1	RW	29
1	129	1	RW	62
1	19	0	RX	50
1	21	0	RX	45
1	860	1	RW	14
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Extra material

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- When to expect many TLB misses?

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1	19	0	RX	50
1	21	0	RX	45
1	860	1	RW	14
1	861	1	RW	75

- 1. Super expensive memory: small number of entries (e.g., 64-128)
- 2. Sometimes separate entries for huge (2MB) pages and normal (4KB) pages
- 3. Often separate TLBs for code and data
- 4. 1 per CPU, but sometimes multiple levels of TLB (L1 TLB vs L2 TLB)



Extra material

- How many TLBs?
- When to flush TLB?
- When to expect many TLB misses?

Valid	Virtual Page	Modified	Protection	Page Frame
1	140	1	RW	31
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1	129	1	RW	62
1	19	0	RX	50
1	21	0	RX	45
1	860	1	RW	14
1	861	1	RW	75

- 1. When entries change
- 2. Traditionally: at context switch?
- 3. Improvement: tag TLB entries with id of process (no need to flush if no other process uses your id)

Extra material

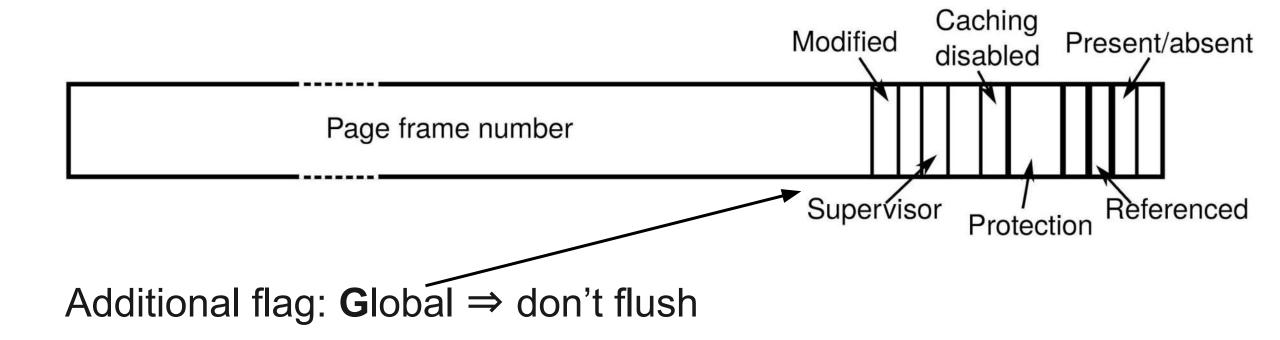
- How many TLBs?
- When to flush TLB?
- When to expect many TLB misses?

Valid	Virtual Page	Modified	Protection	Page Frame
1	140	1	RW	31
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1	129	1	RW	62
1	19	0	RX	50
1	21	0	RX	45
1	860	1	RW	14
1	861	1	RW	75

- 1. After flushes
- 2. When the program exhibits little locality

Extra material

BTW when not to flush?



TLB miss and PF Handling

Software- vs. hardware-managed TLB:

- TLB misses handled by OS vs. hardware

 Hardware walks

 PTs and fills TLB
- Flexibility vs. Efficiency



E.g., OS may preload TLB entries that it expects to need later (say the entries for a server to which current process sends msg)



TLB Misses and Page Fault Handling

- TLB miss handling:
 - Walk page tables to find the mapping
 - If mapping found, fill new TLB entry (soft miss)
 - If mapping not found, page fault (hard miss)
- OS handles PFs (similar to interrupts), cases:
 - Access violation (segmentation fault)
 - Legal access, PF handler needs to fix up page tables:
 - The page is already in memory (minor PF) OR
 - The page must be fetched from disk (major PF)



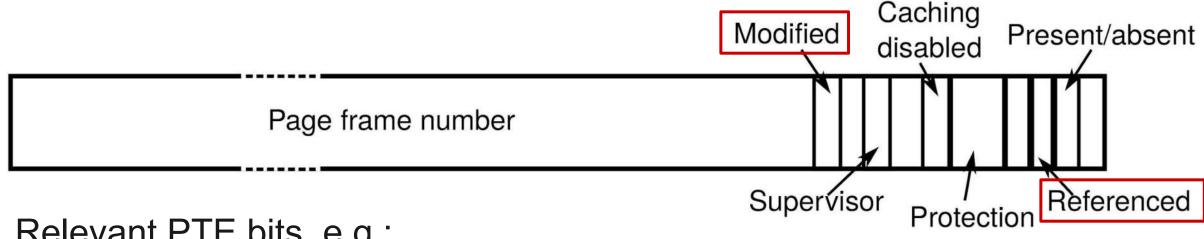
Page Replacement

- Computer might use more virtual memory than it has physical memory
- Paging creates the illusion of unlimited memory available to user processes
- When a logical page is not in memory (swapped out to a file/partition), the OS has to page it in on a page fault
- Swapping out: direct or indirect reclaim
- Another logical page has to be swapped out ⇒ which?



Page Replacement: Hardware Support

Extra material



Relevant PTE bits, e.g.:

- Modified (M): Set when page modified (aka "dirty" bit)
- Referenced (R): Set when page accessed (aka "accessed" bit)
- Available: Reserved for SW extensions
 - e.g., Soft-dirty bit on Linux, set by the kernel at every write page fault (PF) \rightarrow because "dirty" bit is also used for other internal purposes



Page Replacement Algorithms

- Optimal algorithm
- Not recently used algorithm
- First-in, first-out (FIFO) algorithm
- Second-chance algorithm
- Clock algorithm
- Least recently used (LRU) algorithm
- Working set algorithm
- WSClock algorithm



Page Replacement: Basic Algorithms

Optimal:

- Replace page that will be referenced as far in the future as possible
- Can this algorithm be implemented in practice?

Random:

Simply replace a page at random

Not Recently Used (NRU):

- Class of pages: Class 0: R=0, M=0, Class 1: R=0, M=1,
 Class 2: R=1, M=0, Class 3: R=1, M=1
- Periodically clear R/M bit for all the pages. Replace a page at random, but prioritize class 0, then class 1, etc.

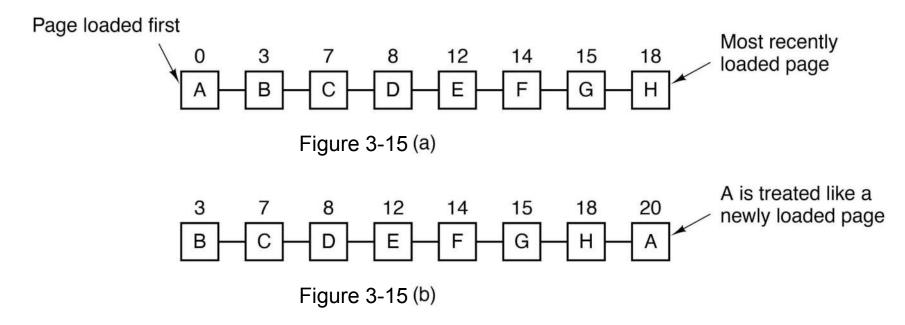
• FIFO:

However, oldest page

Build queue of faulting pages and replace the head may still be useful



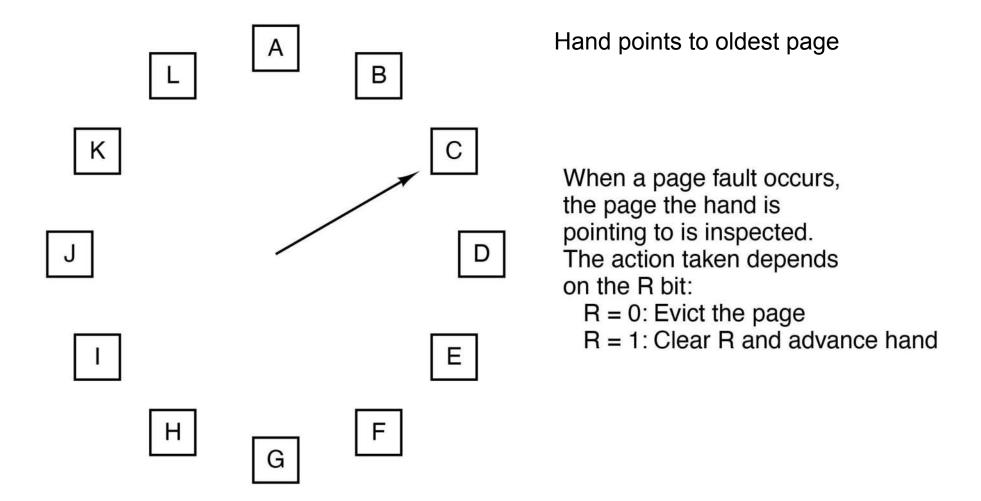
Page Replacement: Second Chance



- Improved FIFO to preserve important pages
- For each visited page:
 - If R=0 then replace page
 - If R=1 then set R=0 and move page to tail



Page Replacement: CLOCK





Page Replacement: Least Recently Used (LRU)

- Idea: Replace page that has been unused for the longest
 - Good predictor for optimal in many (but not all) cases
 - Can LRU ever perform worse than random?
- HW-assisted solutions:
 - Maintain an ordered page list at each reference
 - Head is LRU page
 - Maintain reference timestamps in PTEs
 - Oldest-timestamp PTE points to LRU page
 - Rarely implemented in practice



Page Replacement: LRU-like Strategies

Not Frequently Used (NFU):

- Maintain per-page counters and periodically add (and clear) the R bit to every counter
- Replace the page with the lowest counter
- Problem: NFU never "forgets" pages

Aging:

- Improve NFU by:
 - Add R bit to the leftmost bit
 - Shifting counters to the right
- Offers lower temporal resolution than "real" LRU
- CLOCK (and variations) more often used in practice



Simulating LRU in Software

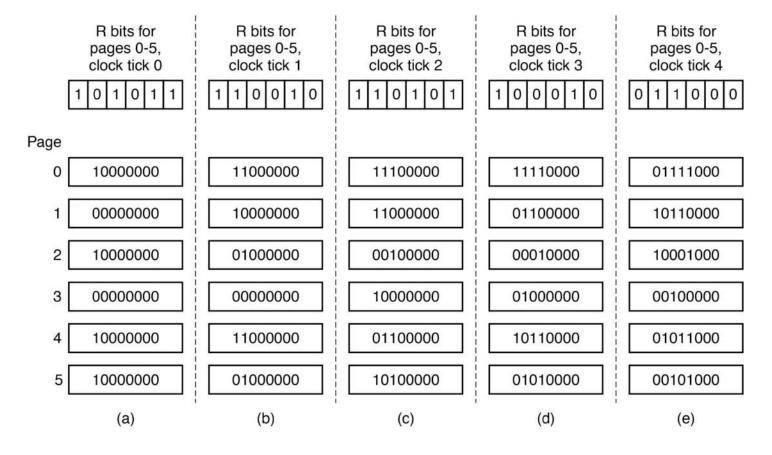


Figure 3-17. The aging algorithm simulates LRU in software.

Shown are six pages for five clock ticks. The five clock ticks are represented by (a) to (e).



Page Replacement: WS and WSClock

Working Set: set of pages that a process is currently using

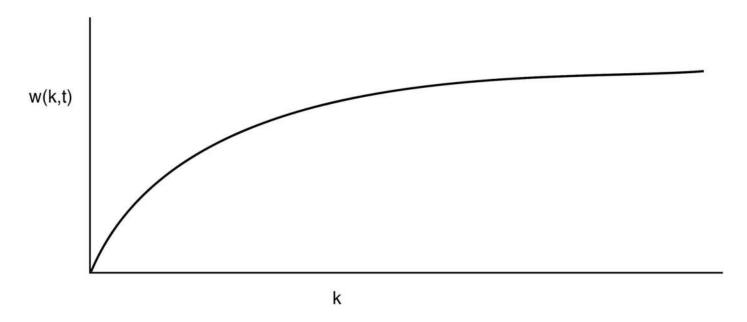


Figure 3-18. The working set is the set of pages used by the **k** most recent memory references. The function **w**(**k**, **t**) is the size of the working set at time **t**.



Working Set

If (WS in memory) \rightarrow few page faults Else \rightarrow many page faults

If (memory too small for WS) → thrashing Most programs exhibit locality of reference

Maybe ensure pages in WS not replaced?

Maybe ensure WS is in memory by prepaging?



Working Set Algorithm

WS = all pages referenced last τ seconds of virtual time (time consumed by process)

т spans multiple clock ticks



Working Set Algorithm (2 of 2)

NOTE: at periodic clock interrupt we clear R

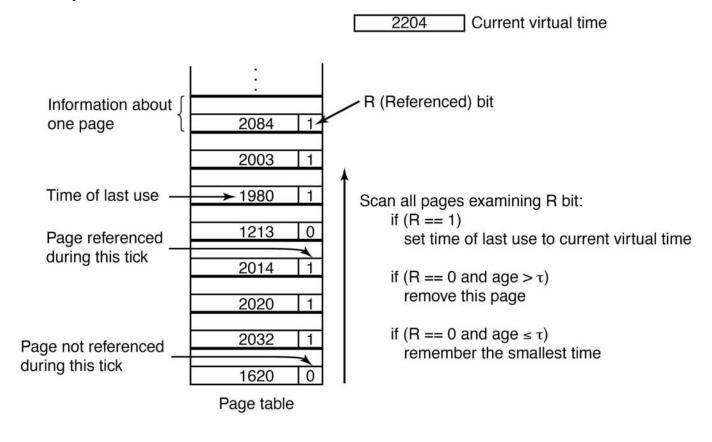


Figure 3-19. The working set algorithm.



WSClock

- Previous model is cumbersome as we must scan the page tables for each PF
- WSClock combines Clock and WS and is more efficient



WSClock

- Previous model is cumbersome as we must scan the page tables for each PF
- WSClock combines Clock and WS and is more efficient
 - Circular list of page frames (initially empty)
 - When page referenced→ add to list with time
 - Advance hand + check if R==0 (else R→0, skip after updating time)
 - If (R==0 && age > t && not dirty) → simply replace
 - If (R==0 && age > t && dirty) schedule write and cont.
 - If hand comes all the way around → 2 cases:
 - At least one page scheduled for write
 - No page scheduled for write

- → any clean page (if available)
- → otherwise current page``



WSClock Algorithm (1 of 2)

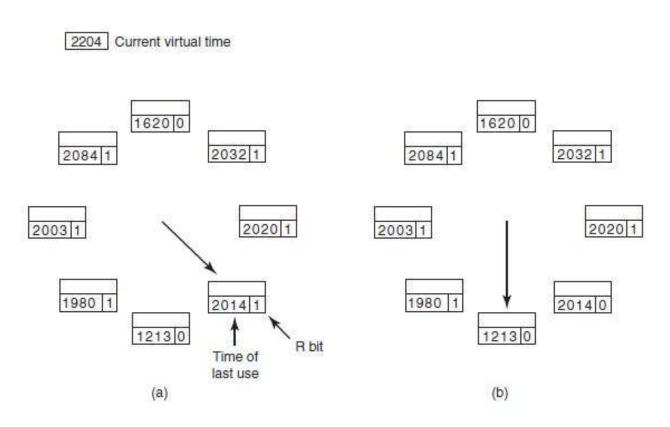


Figure 3-20. Operation of the WSClock algorithm. (a) and (b) give an example of what happens when R = 1.



WSClock Algorithm (2 of 2)

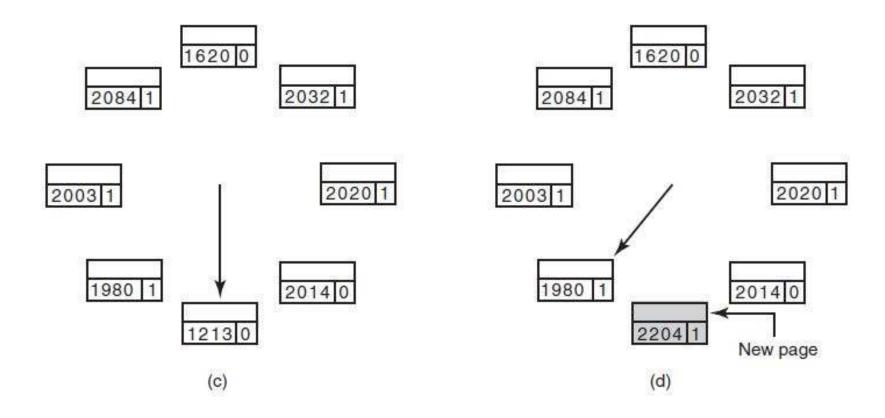


Figure 3-20. Operation of the WSClock algorithm. (c) and (d) give an example of R = 0.



Summary of Page Replacement Algorithms

Algorithm	Comment
Optimal	Not implementable, but useful as a benchmark
NRU (Not Recently Used)	Very crude approximation of LRU
FIFO (First-in, First-out)	Might throw out important pages
Second, chance	Big improvement over FIFO
Clock	Realistic
LRU (Least Recently Used)	Excellent, but difficult to implement exactly
NFU (Not Frequently Used)	Fairly crude approximation to LRU
Aging	Efficient algorithm that approximates LRU well
Working set	Somewhat expensive to implement
WSClock	Good efficient algorithm

Figure 3-21. Page replacement algorithms discussed in the text.



Design Issues: Paging Strategy

Demand paging:

- Lazily allocate pages to each process
- Exploits temporal locality to avoid frequent PFs

• Prepaging:

- Typically based on the working set model, i.e., the set of pages a process currently needs to execute
- Load the process working set in memory in advance when scheduling the process to avoid frequent PFs
- Need for working set estimation algorithms



Allocating memory

Extra material

Typical memory address space (Linux x86-64)

What happens if we allocate memory?

Different library functions:

malloc (+ friends) vs mmap

Different syscalls:

brk, sbrk vs mmap





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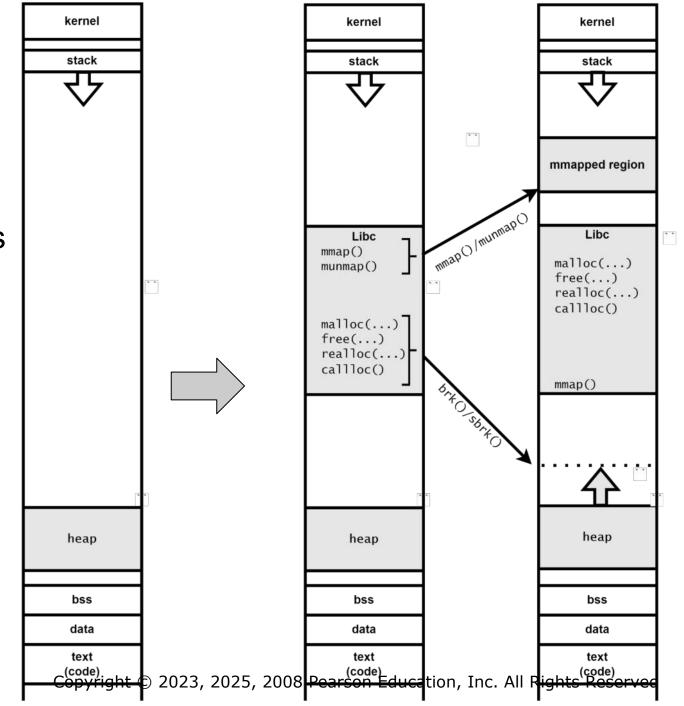
Allocating memory

Extra material

On Linux, malloc() results in

- (s)brk() syscall for small areas
- mmap() syscall for large areas

mmap() always results in mmap()





Allocating memory

Extra material

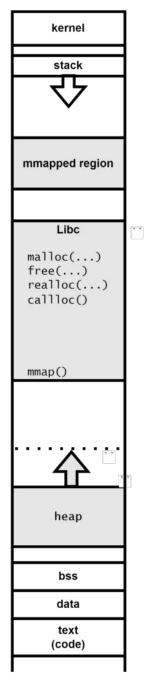
For all of the memory holds:

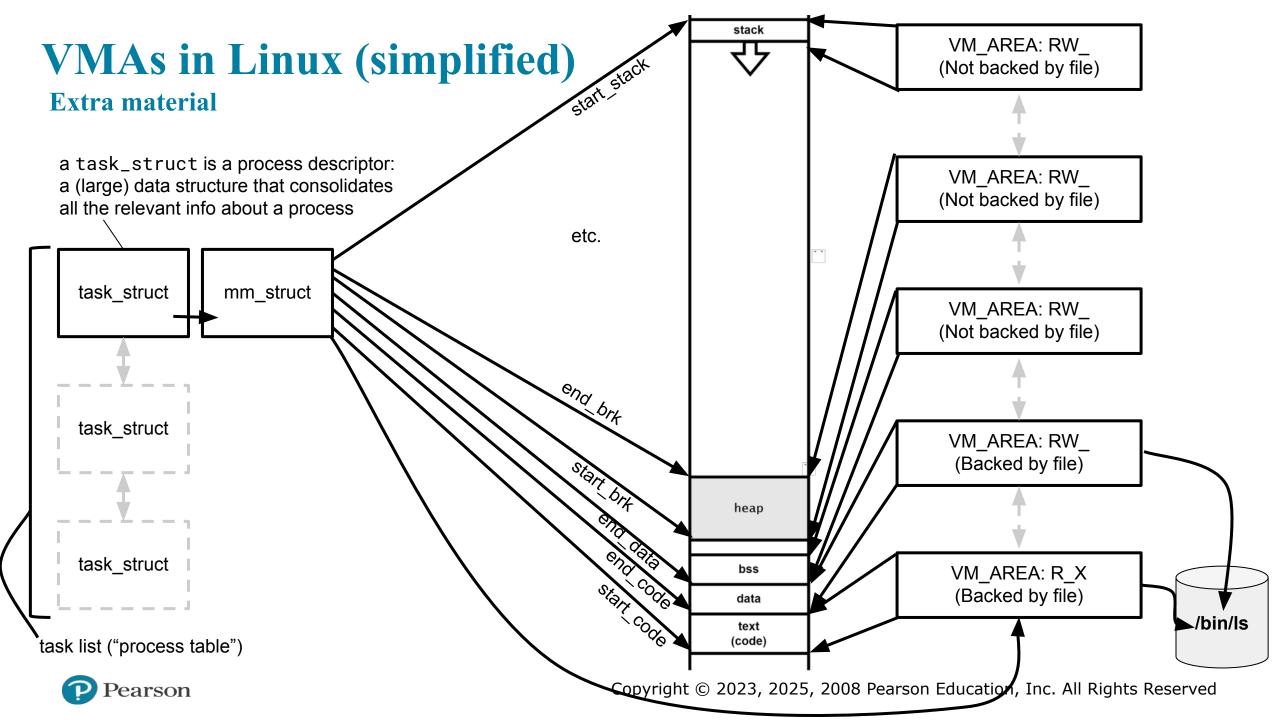
- access a location in memory ⇒ MMU
- may trigger PF
- may trigger SEGV

For instance, Linux maintains a doubly linked list of VMAs (Virtual Memory Areas) indicating which regions are allocated

Allocating virtual memory vs assigning physical memory

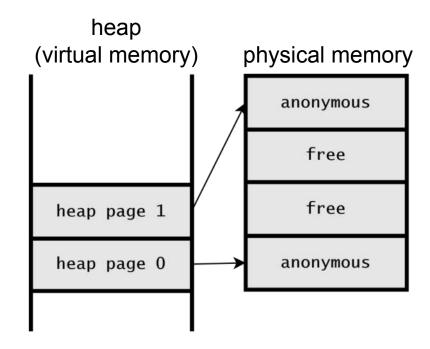
- OS may "allocate memory" (enter it as used in its administration) without assigning physical memory to it yet
- A physical page frame is assigned only when the program accesses a location on the virtual page → demand paging



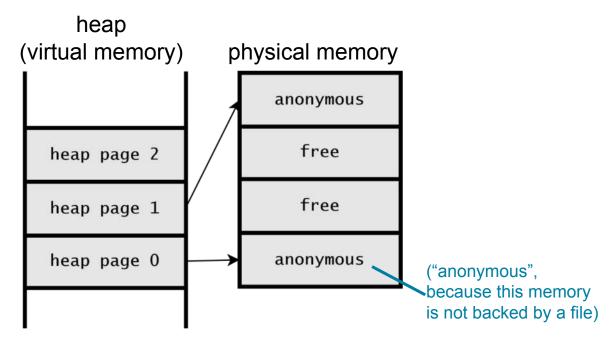


Demand paging (1/2)

Extra material



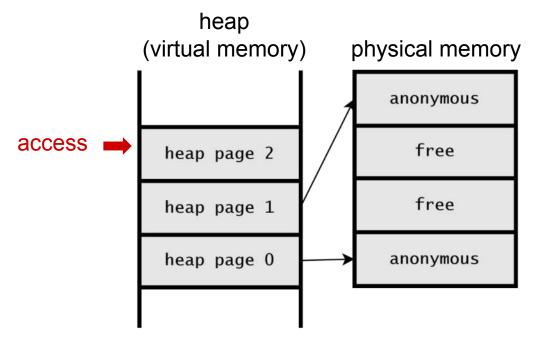
The program extends the heap with brk()



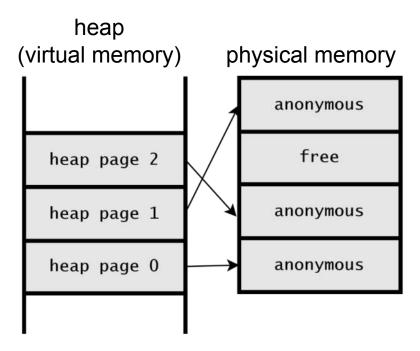
The heap is now extended, but no physical frame is assigned to page 2

Demand paging (2/2)

Extra material



Now the program reads from or writes to the new page on the heap \rightarrow PF



The OS maps a new physical frame to back the virtual page.



Demand Paging: Linux Allocation Benchmark

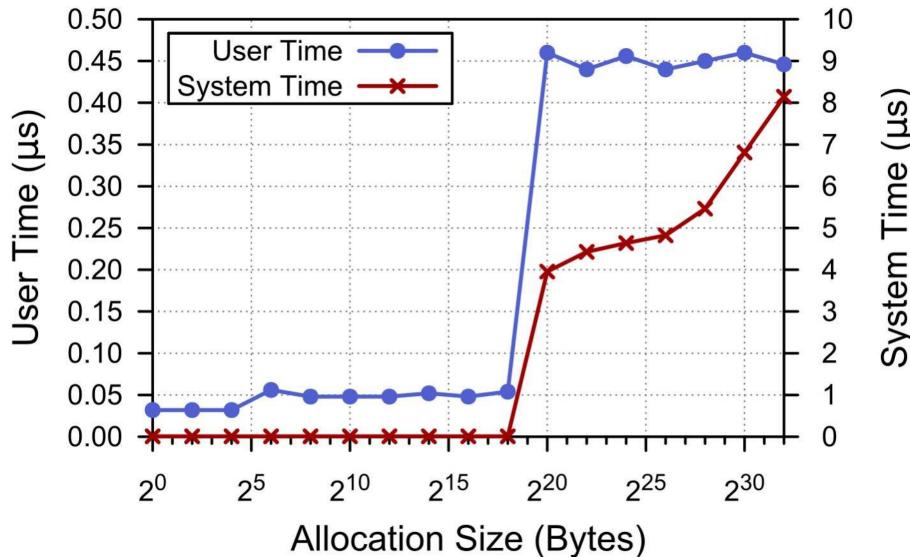
Extra material

```
#include <assert.h>
#include <stdlib.h>
int main(int argc, char* argv[])
    void *ptr;
    int i, size;
    assert (argc == 2);
    size = atoi(argv[1]);
    for (i=0;i<1000000;i++) {
         ptr = malloc(size);
                                        Note: we allocate and free immediately → no accesses
         assert(ptr);
                                        (demand paging, so not backed by physical memory)
         free (ptr);
                                        We run this code and plot the time
    return 0;
```

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Demand Paging: Linux Allocation Benchmark

Extra material





Design Issues: Allocation Policies

Local allocation:

- Replaces only pages of the current process
- Assumes static process memory allocation size
- Problems:
 - A growing working set leads to trashing
 - A shrinking working set leads to wasted memory

Global allocation:

- Replaces pages owned by any process. Strategies:
 - Treat every global page equally (or prioritize)
 - Dynamic memory balancing using working set size estimation
 - Selectively swap out processes (or OOM kill)



Design Issues:

Local versus Global Allocation Policies (1 of 2)

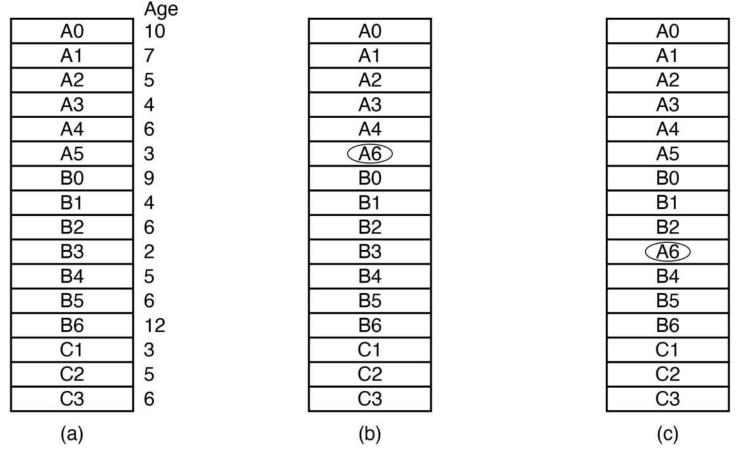


Figure 3-22. Local versus global page replacement. (a) Original configuration. (b) Local page replacement. (c) Global page replacement.



Design Issues: Local versus Global Allocation Policies (2 of 2)

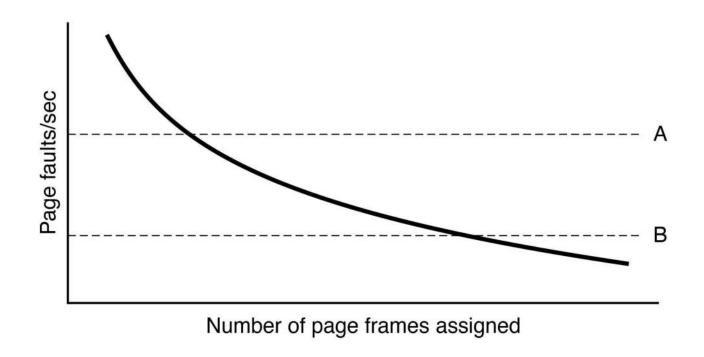


Figure 3-23. Page fault rate as a function of the number of page frames assigned.



Design Issues: Load Control

- Thrashing can be expected when the combined working sets of all processes exceed the capacity of memory
- Out of Memory killer (OOM) selectively kills processes when system is low memory
- Less drastic approach swaps some processes to nonvolatile storage and releases those pages
 - Similar to two-level scheduling
- Can also reduce memory usage via compaction/compression
 - Deduplication or same page merging



Design Issues: Page Size

Most paging systems support 4KB pages

relatively small: limits internal fragmentation / space wastage

not too small : limits number of pages to handle, entries in TLB

In addition, many support also larger pages. For instance:

2 MB

1GB



Design Issues: Separate Instruction and Data Spaces

Most computers have a single address space shared by program and data In the past some systems had a separate address space for instructions and data

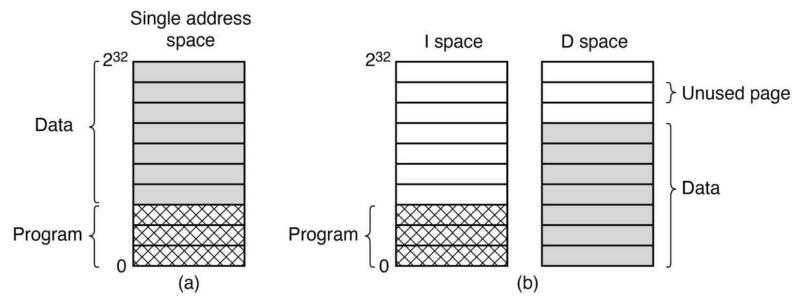


Figure 3-24. (a) One address space. (b) Separate I and D spaces.

Nowadays, we still see separate I and D spaces in caches and TLBs, etc.



Design Issues: Shared Pages

- Sharing improves efficiency.
- When one process exits, OS should realise there is another user of the the page

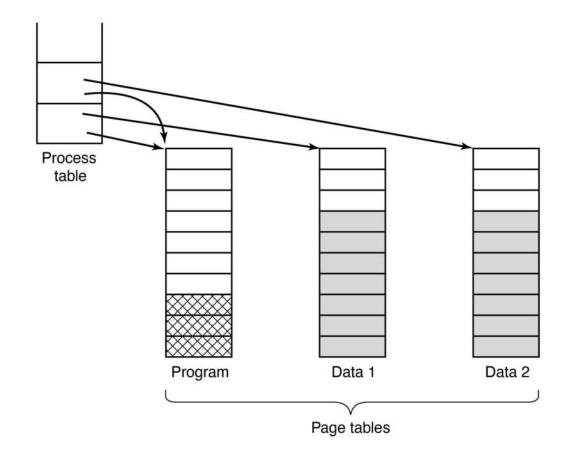


Figure 3-25. two processes sharing same program sharing its page table.



Design Issues: Shared Pages

- Sharing improves efficiency.
- When one process exits, OS should realise there is another user of the the page

Sharing data is trickier than sharing code

- After fork system call parent and child share program and text
 - To do so efficiently, each gets its own set page table, pointing to the same pages
 - Pages are mapped read-only
 - When a process writes to such a page: make a copy
 - This is known as copy-on-write

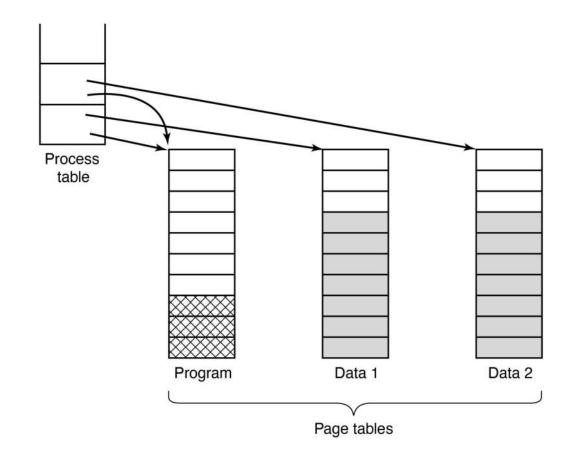
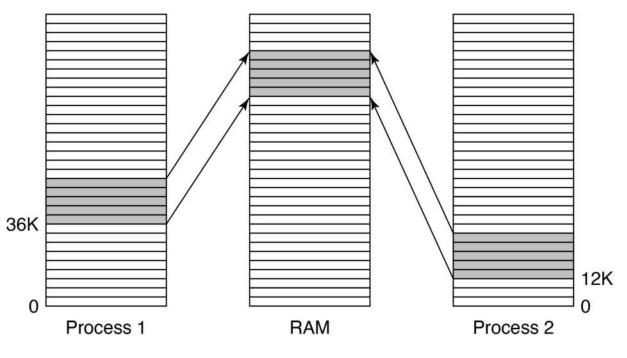


Figure 3-25. two processes sharing same program sharing its page table.



Design Issues: Shared Libraries

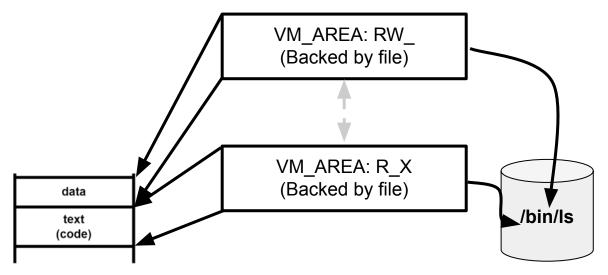


- Sharing libraries is very common
 - o easy: read-only
- Typically through Dynamic Link Libraries (DLLs)
 - often as position-independent code

Figure 3-26. A shared library being used by two processes.



Design Issues: Memory mapped files



Shared libs special cases of memory mapped files

As pages are touched → demand paged from disk

When process exits → write dirty pages back to disk

Mapped file



Design Issues: Cleaning policy

Paging works well if plenty of free pages. What if we run short?

Indirect reclaim: Paging daemon sleeps and then evicts pages if free pages are in short supply

Leaves them in memory -- easy reuse



Design Issues: Virtual Memory Interface

- Allocator interface
 - malloc family, mmap family
- Memory-mapped files
 - Treat files as memory objects for faster I/O
 - Facilitate code sharing for programs/shared libraries
- Copy-on-write semantics
 - Lazy copying for fork(), deduplication, checkpointing, etc.
- Shared memory
 - MAP_SHARED mappings, key-based, file-based
- Distributed shared memory
 - Shared memory semantics over the network



Page Fault Handling (1 of 3)

- 1. The hardware traps to kernel, saving program counter on stack.
- Assembly code routine started to save registers and other volatile info. Calls the page fault handler
- System discovers page fault has occurred, tries to discover which virtual page needed
- 4. Once virtual address caused fault is known, system checks to see if address valid and the protection consistent with access



Page Fault Handling (2 of 3)

- 5. If frame selected dirty, page is scheduled for transfer to nonvolatile storage, context switch takes place, suspending faulting process
- As soon as frame clean, operating system looks up disk address where needed page is, schedules disk or SSD operation to bring it in.
- 7. When disk or SSD interrupt indicates page has arrived, tables updated to reflect position, and frame marked as being in normal state.



Page Fault Handling (3 of 3)

- Faulting instruction backed up to state it had when it began and program counter is reset
- Faulting process is scheduled, operating system returns to routine that called it.
- 10. Routine reloads registers and other state information, returns to user space to continue execution where it left off



Separation of Policy and Mechanism (1 of 2)

Again: the separation is important for managing the complexity of the system.

Not always trivial. Example:

Memory management system is divided into three parts

- A low-level MMU handler.
- 2. A page fault handler that is part of the kernel.
- 3. An external pager running in user space.



Separation of Policy and Mechanism (2 of 2)

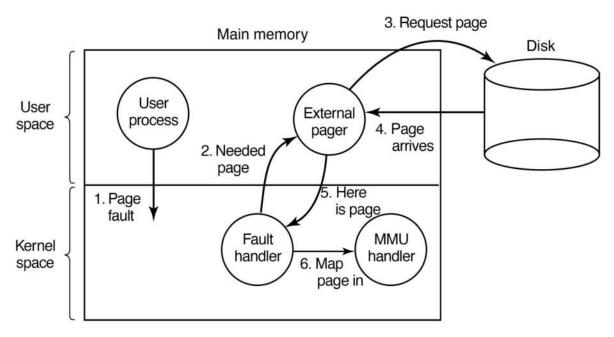


Figure 3-29. Page fault handling with an external pager.

- Kernel page fault handler:
 - machine independent
 - contains mechanism for paging
- External pager:
 - machine independent
 - can implement the policy
- Not always easy. For instance: cleanest if replacement algorithm in external pager
 - But may not have access to R and M bits
 - either need new mechanism to pass these bits to user space
 - or replacement algorithm in kernel



Segmentation: Paging is not the only option

Motivation: many programs have many dynamic areas.

Examples of tables generated by compiler:

- Source text being saved for the printed listing
- 2. Symbol table: names and attributes of variables.
- 3. Table containing integer and floating-point constants used.
- 4. Parse tree, syntactic analysis of the program.
- 5. Stack used for procedure calls within compiler.

Virtual address space Call stack Free Space currently being Parse tree used by the parse tree Constant table Source text Symbol table has bumped into the Symbol table source text table

Areas may bump into each other

Figure 3-30. In a one-dimensional address space with growing tables, one table may bump into another.



Segmentation: The Idea

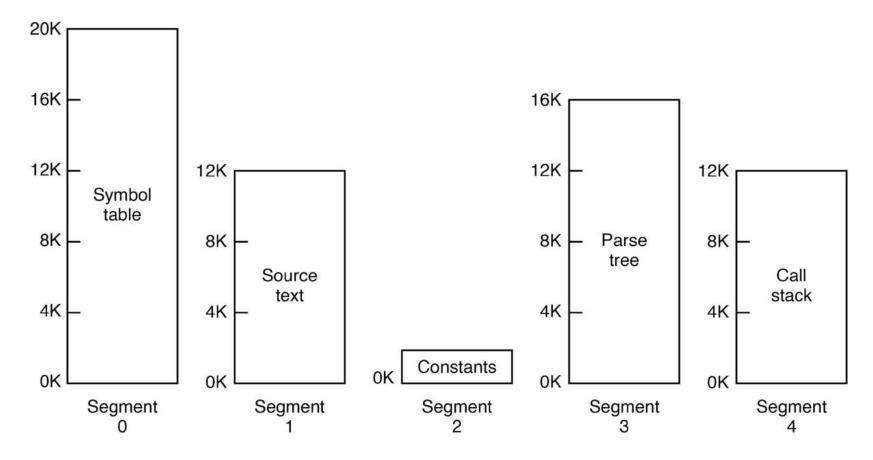


Figure 3-31. A segmented memory allows each table to grow or shrink independently of the other tables.



Implementation of Pure Segmentation

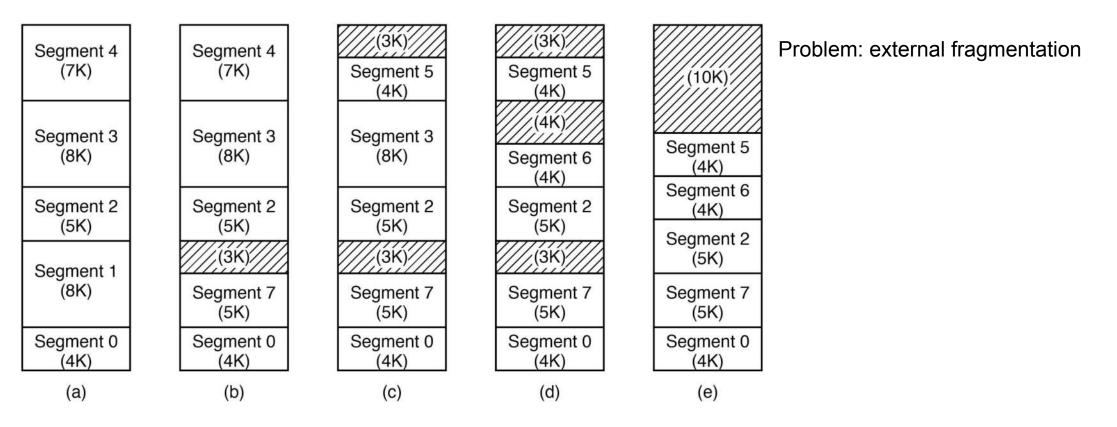


Figure 3-33. (a)-(d) Development of checkerboarding. (e) Removal of the checkerboarding by compaction.



Segmentation with Paging: MULTICS (1 of 5)

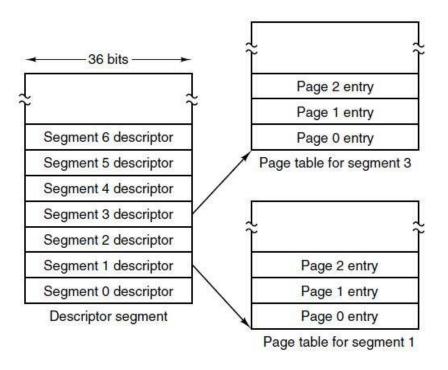


Figure 3-34. The MULTICS virtual memory. (a) The descriptor segment pointed to the page tables.



Segmentation with Paging: MULTICS (2 of 5)

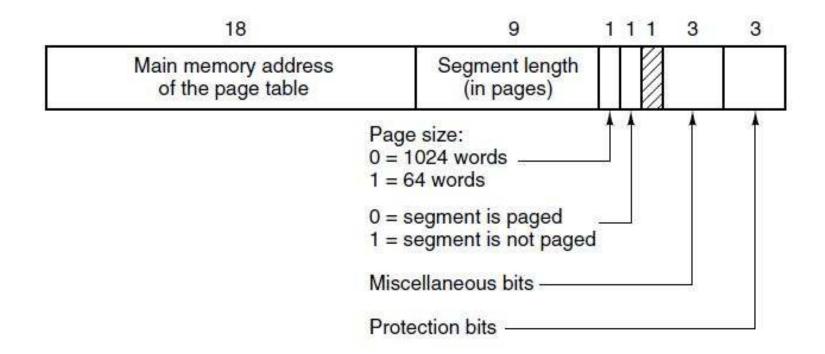


Figure 3-34. The MULTICS virtual memory. (b) A segment descriptor. The numbers are the field lengths.



Segmentation with Paging: MULTICS (3 of 5)

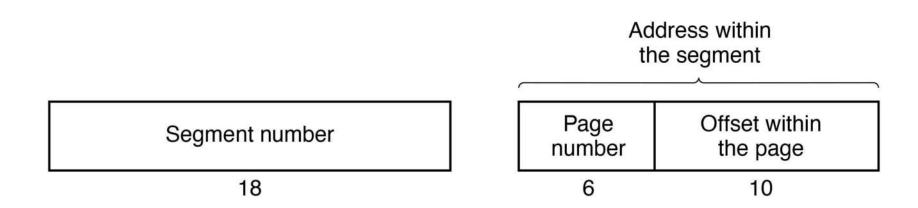


Figure 3-35. A 34-bit MULTICS virtual address.



Segmentation with Paging: MULTICS (4 of 5)

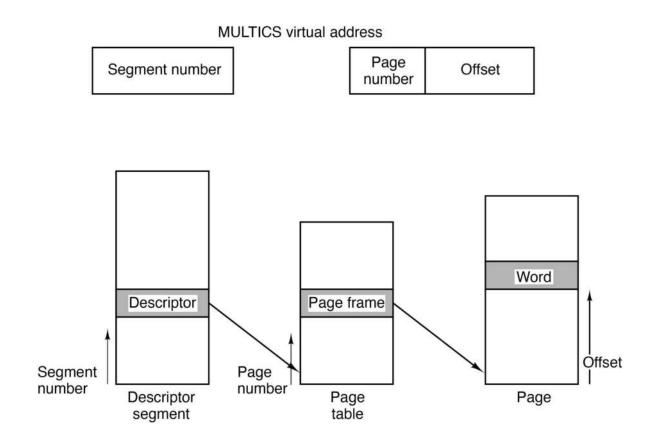


Figure 3-36. Conversion of a two-part MULTICS address into a main memory address.



Segmentation with Paging: MULTICS (5 of 5)

Comparison field					s this entry used?
Segment number	Virtual page	Page frame	Protection	Age	
4	1	7	Read/write	13	1
6	0	2	Read only	10	1
12	3	1	Read/write	2	1
					0
2	1	0	Execute only	7	1
2	2	12	Execute only	9	1
\sim					\smile

Figure 3-37. A simplified version of the MULTICS TLB. The existence of two page sizes made the actual TLB more complicated.



Segmentation (4 of 4)

Figure 3-32. Comparison of paging and segmentation

Consideration	Paging	Segmentation	
Need the programmer be aware that this technique is being used?	No	Yes	
How many linear address spaces are there?	1	Many	
Can the total address space exceed the size of physical memory?	Yes	Yes	
Can procedures and data be distinguished and separately protected?	No	Yes	
Can tables whose size fluctuates be accommodated easily?	No	Yes	
Is sharing of procedures between users facilitated?	No	Yes	
Why was this technique invented?	To get a large linear address space without having to buy more physical memory	To allow programs and data to be broken up into logically independent address spaces and to aid sharing and protection	



Summary

In this chapter, we looked at memory management (MM) in detail

We discussed many core concepts:

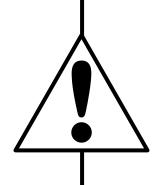
- memory abstractions
- virtual memory
- memory allocators
- paging
- page replacement
- segmentation
- design issues

On modern systems MM can be very complicated

Next, we will look at another core component: File Systems!



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