

UML State Machines (Basics)

Software Design (40007) – 2023/2024

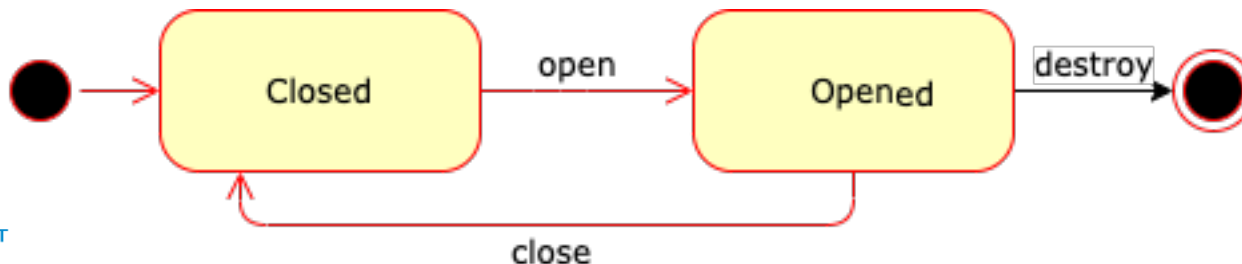
Justus Bogner
Ivano Malavolta

What is the state of an object?

- Concrete state

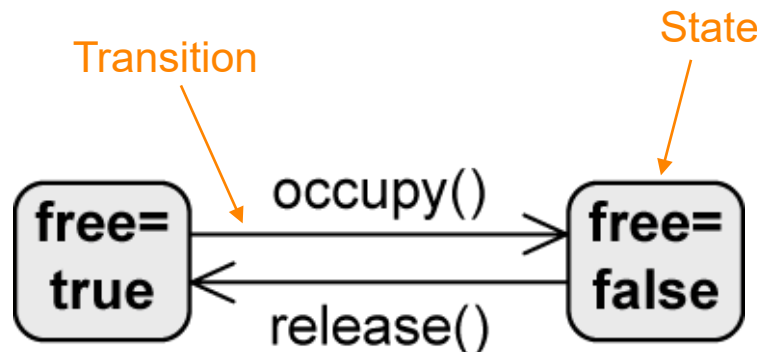
```
1 public class Door {  
2     private int height = 0;  
3     private int width = 0;  
4     private Color = Color.BLUE;  
5     private orientation = Orientation.SOUTHWEST;  
6     private bool closed = false;  
7 }
```

- Abstract state
 - Arbitrarily-defined set of **logical** states
 - Goal: to define the abstract state space of objects to better reason about the system and arrive at a suitable solution

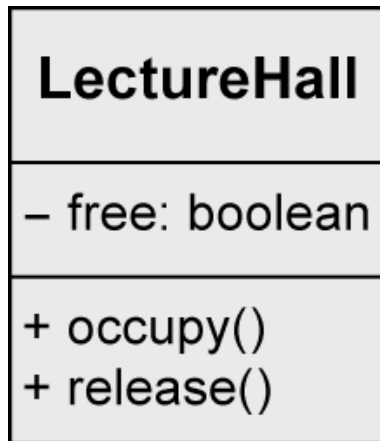
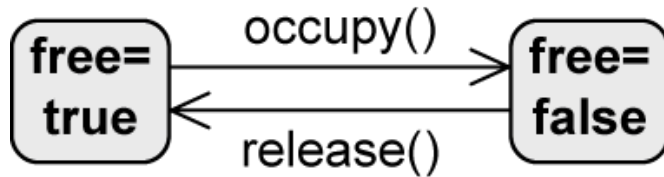


State machines

- Every domain object has a **finite** set of states during its life
- State machines are used to
 - reason about the **complexity** of the domain and the system
 - avoid overlooking important execution paths
- State machine diagrams
 - model the possible states of a system or object
 - show how state transitions occur as a consequence of events
 - show what behavior the system or object exhibits in each state
- Example: high-level behavior of a lecture hall



Example: lecture hall with details



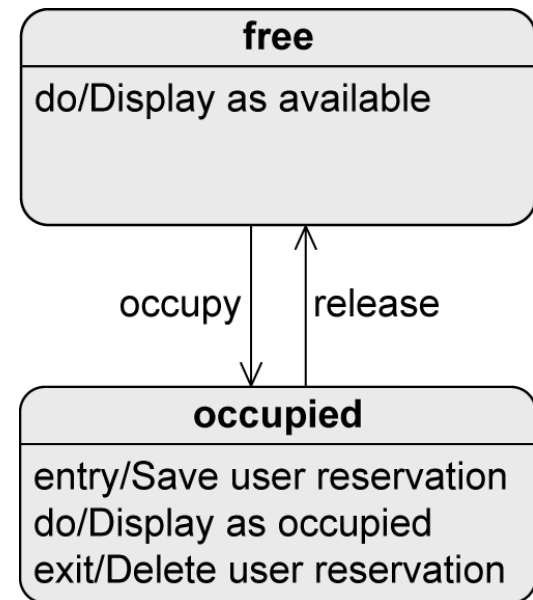
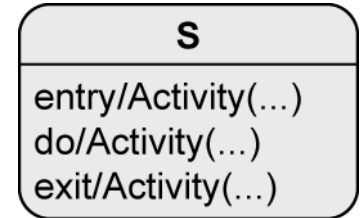
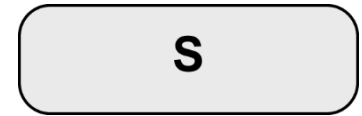
```
class LectureHall {  
    private boolean free;  
  
    public void occupy() {  
        this.free = false;  
    }  
    public void release() {  
        this.free = true;  
    }  
}
```

States

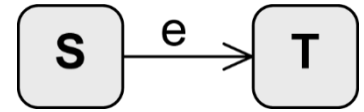
- States = nodes of the state machine
- When a state is active
 - The object is in that state
 - All **internal activities** specified in this state can be executed

Internal activities:

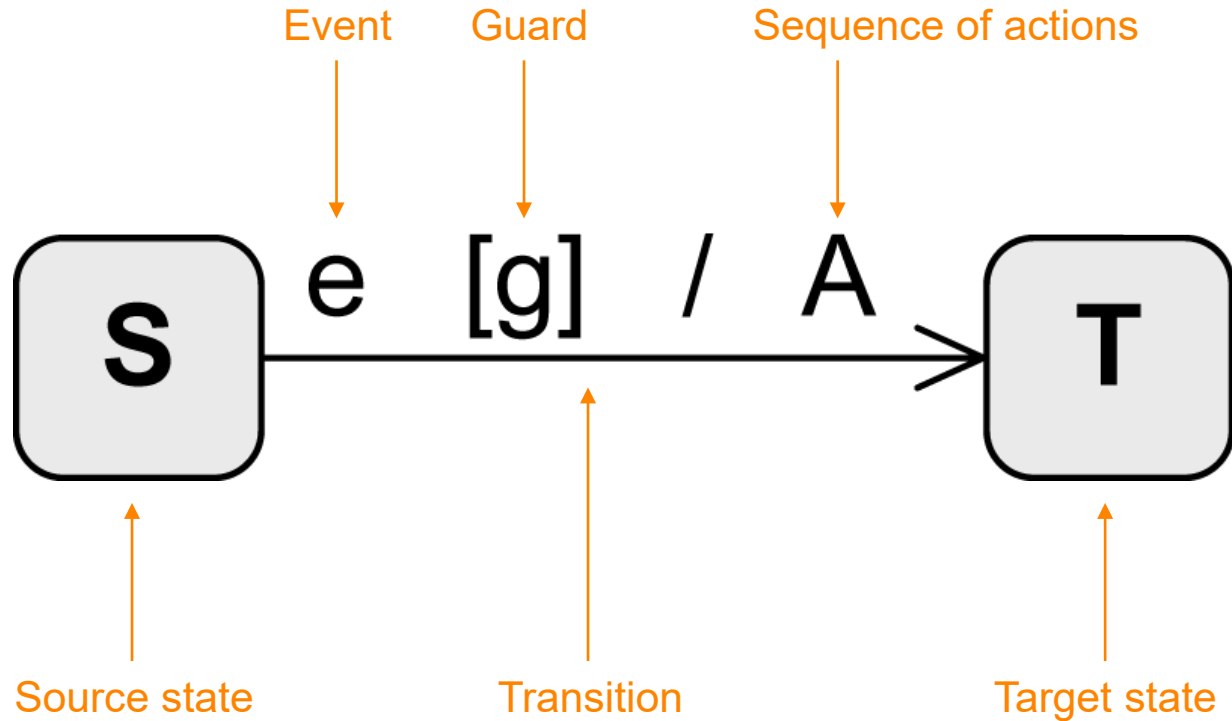
- entry / <activity>
 - Executed when the object enters the state
- exit / <activity>
 - Executed when the object leaves the state
- do / <activity>
 - Executed while the object remains in this state



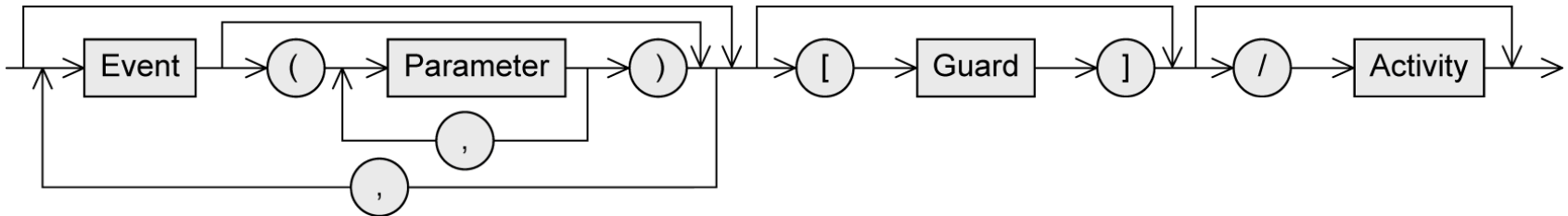
Transitions



Changing from one state to another



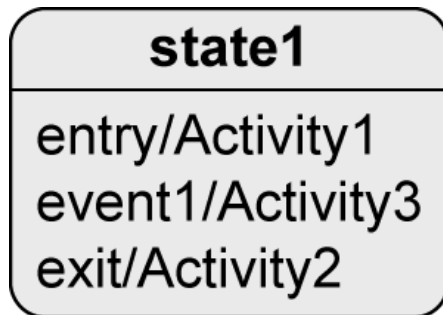
Transition – syntax



- Event(s) → trigger
 - Trigger a state transition
 - Can have parameters (like an operation)
- Guard → condition
 - Boolean expression to check if the event occurs
 - If the guard is `true`
 1. All activities in the current state are terminated
 2. All `exit` activities are executed
 3. The transition takes place
 - If the guard is `false`, no transition happens (event is **discarded**)
- Activity → effect
 - Sequence of actions executed during the state transition

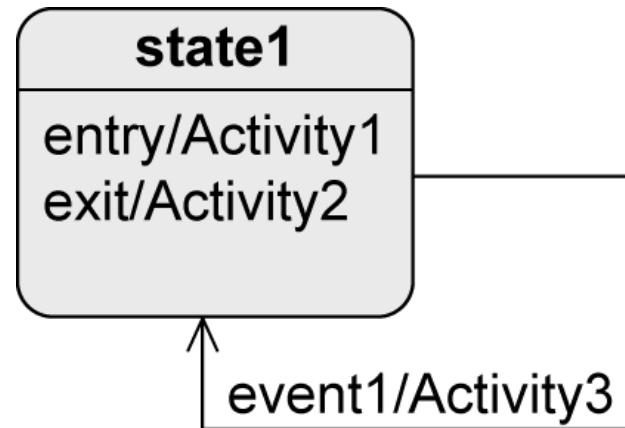
Transition – types (1/2)

Internal transition



- If **event1** occurs
 - Object remains in **state1**
 - **Activity3** is executed

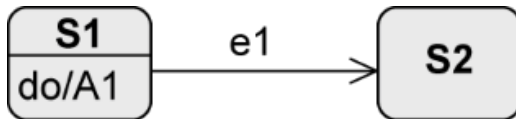
External transition



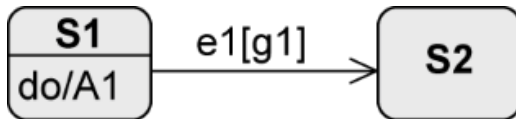
- If **event1** occurs
 - Object leaves **state1** and **Activity2** is executed
 - **Activity3** is executed
 - Object (re-)enters **state1** and **Activity1** is executed

Transition – types (2/2)

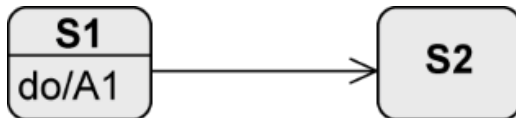
- When do the following transitions take place?



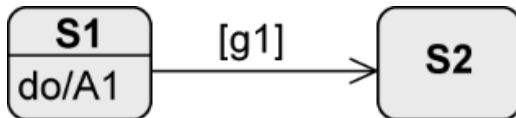
If **e1** occurs, **A1** is aborted and the object changes to **S2**



If **e1** occurs and **g1** evaluates to `true`, **A1** is aborted and the object changes to **S2**



As soon as the execution of **A1** is finished, a completion event is generated that initiates the transition to **S2**

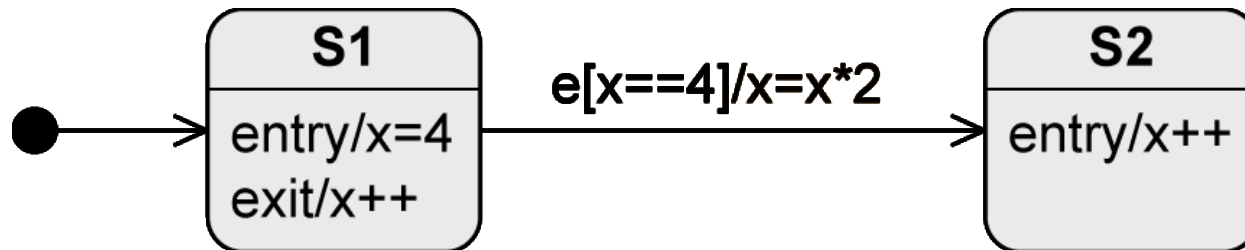


As soon as the execution of **A1** is finished, a completion event is generated;
if **g1** evaluates to `true`, the transition takes place; if not, this transition never happens

Typically overlooked

Transition – sequence of activity executions

Assume below state machine started and **e** occurred after some time. What is the final value of **x**?



S1 becomes active, **x** is set to the value 4

e occurs, the guard is checked and evaluates to true

S1 is left, **x** is set to 5

The transition takes place, **x** is set to 10

S2 is entered, **x** is set to 11

Event – types (1/2)

- **Signal event**

Receipt of a signal

- E.g., `rightMouseDown`, `sendSMS (message)`

- **Call event**

Operation call

- E.g., `occupy (user, lectureHall)`, `register (exam)`

- **Time event**

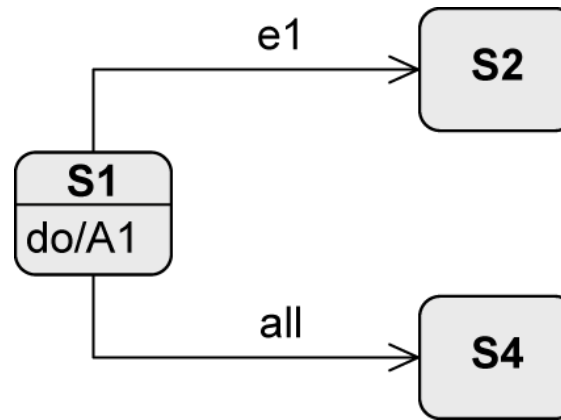
Time-based state transition

- Relative: based on the time of the occurrence of the event
 - E.g., `after (5 seconds)`
- Absolute
 - E.g., `when (time==16:00)`
`when (date==2015-01-01)`

Event – types (2/2)

■ “Any receive” event

- Occurs when any event occurs that does not trigger another transition from the active state
- Keyword **all**



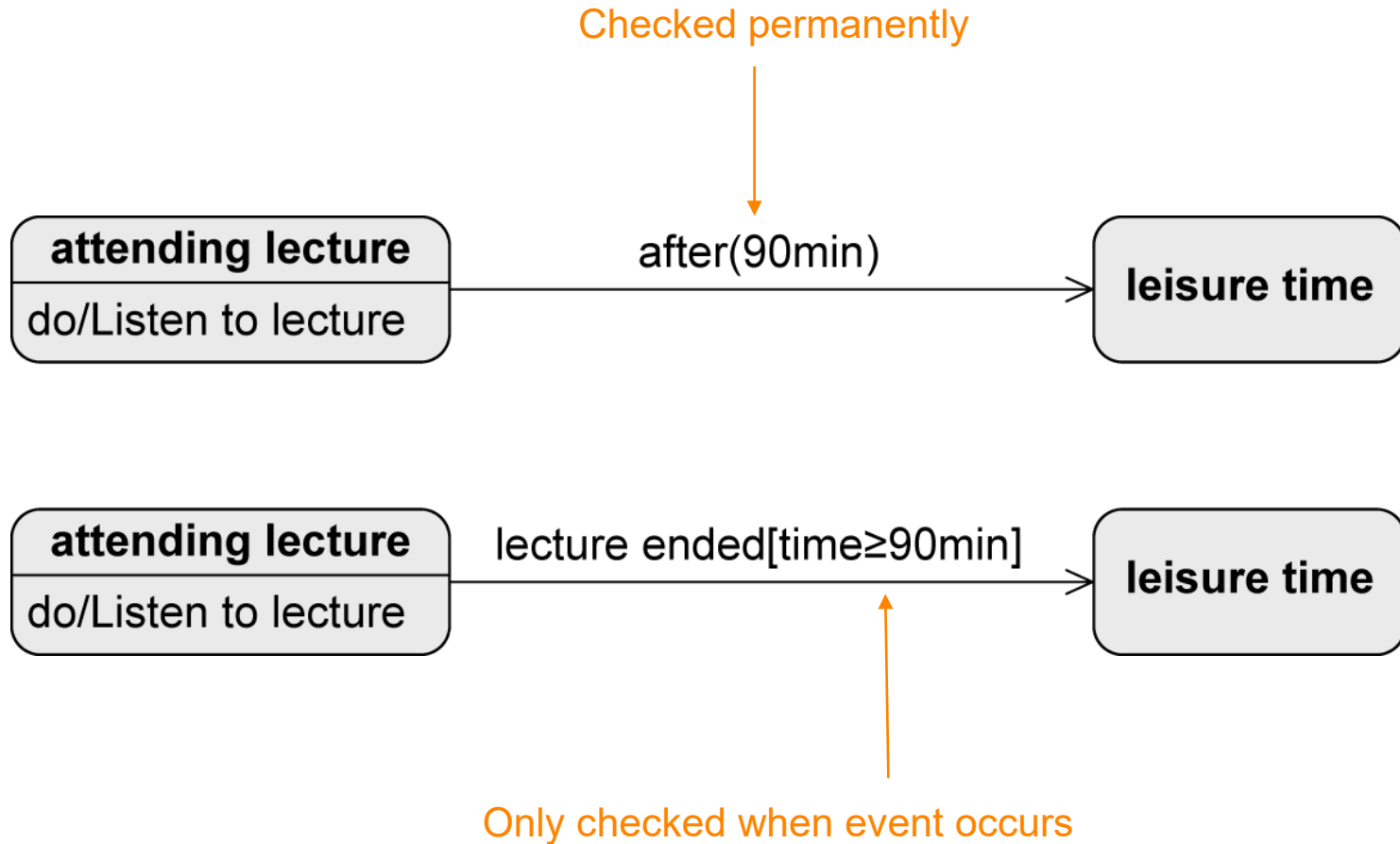
■ Completion event

- Generated automatically when everything to be done in the current state is completed (it is implicit)

■ Change event

- Permanently checking whether a condition becomes true
- E.g., **when (x > y)**

Change event vs. guard



Question: What if the lecture is shorter than 90min?

Initial state ●

- “Start” of a state machine diagram
- Pseudo state
 - Transient, i.e., system cannot remain in that state
 - Rather a control structure than a real state
- No incoming edges
- If >1 outgoing edges
 - Guards must be mutually exclusive and cover all possible cases to ensure that exactly one target state is reached
- If initial state becomes active, the object immediately switches to the next state
 - No events allowed on the outgoing edges

Final state and terminate node

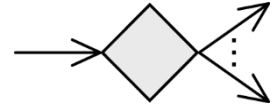
Final state

- Real state
- Marks the end of the sequence of states
- Object can remain in a final state forever

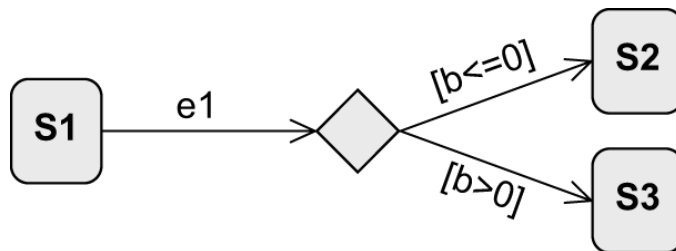
Terminate node

- Pseudo state
- Terminates the state machine
- The modeled object ceases to exist (= is deleted)

Decision node

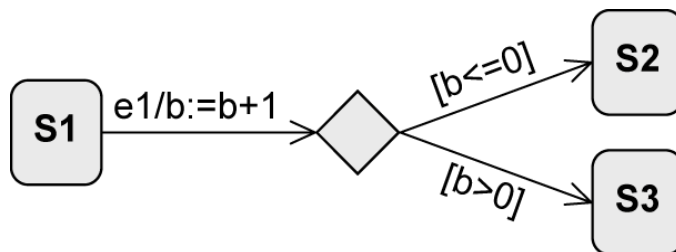
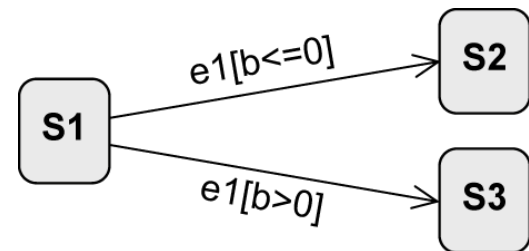


- Pseudo state
- Used to model alternative transitions



equivalent?

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equivalent?

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