Program Summary

Overview

Figure 1: **Overview**

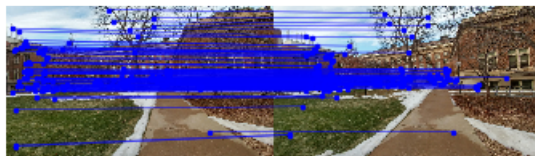**SIFT Feature Matching**

Figure 2: **SIFT Feature Matching**
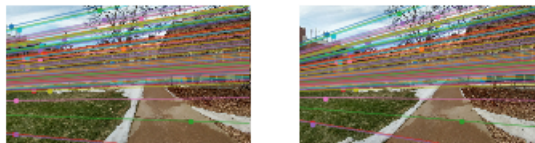
Fundamental Matrix Computation
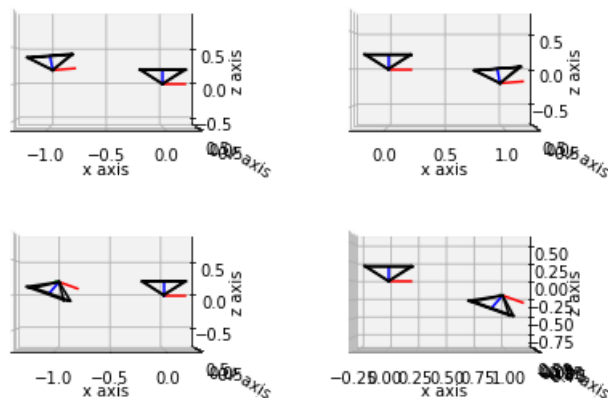

Figure 3: **Fundamental Matrix Computation**

Camera poses

Figure 4: **Camera poses**

Triangulation

Figure 5: **Triangulation**

Stereo
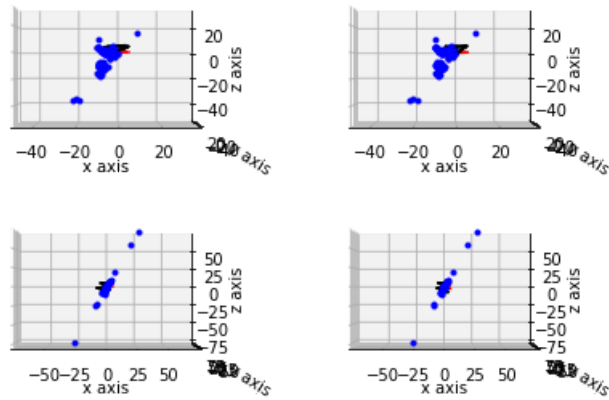

Figure 6: **Stereo**

stereo match

Figure 7: **stereo match**