

Corrigendum and addendum to:  
 “Sided and symmetrized Bregman centroids”  
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**Abstract**

We correct and extend the results presented in [12].

## 1 Dissimilarities, dual centroids, and dual information radii

Let  $D(P : Q)$  denote the *dissimilarity* between two points  $P$  and  $Q$  of a space  $\mathbb{G}$  such that  $D(P : Q) \geq 0$  with equality if and only if  $P = Q$ . By analogy with the notion of Fréchet barycenters in metric spaces [7], we define the *D-barycenters* or *D-centroid*  $C_D(\mathcal{P})$  of a weighted point set  $\mathcal{P} = \{P_1, \dots, P_n\}$  with respect to  $D$  as

$$C_D(\mathcal{P}) := \arg \min_{X \in \mathbb{G}} \sum_{i=1}^n w_i D(P_i : X), \quad (1)$$

where  $w_i > 0$  and  $\sum_{i=1}^n w_i = 1$  (i.e.,  $w$  belongs to the  $(n-1)$ -dimensional standard simplex  $\Delta_{n-1}$ ). The centroids are special cases of barycenters obtained for the uniform weighting  $w_i = \frac{1}{n}$ . Notice that  $C_D(\mathcal{P})$  is generally a subset of points of  $\mathbb{G}$ , and may not necessarily exist nor be unique. For example, the centroid of two antipodal points on the unit Euclidean sphere is a great circle. In Riemannian geometry, other notions of barycenters have been defined [1]: Karcher local barycenters, exponential barycenters, etc.

Since  $D$  may be asymmetric  $D(P : Q) \neq D(Q : P)$  (oriented dissimilarity, hence the delimiter notation “:”), we define the *dual dissimilarity*  $D^*(P : Q) := D(Q : P)$ , and the *dual D-barycenter* or *left-sided D-barycenter*:

$$C_D^*(\mathcal{P}) := \arg \min_{X \in \mathbb{G}} \sum_{i=1}^n w_i D(X : P_i), \quad (2)$$

$$= \arg \min_{X \in \mathbb{G}} \sum_{i=1}^n w_i D^*(P_i : X), \quad (3)$$

$$= C_{D^*}(\mathcal{P}). \quad (4)$$

Notice that the dual of the dual dissimilarity is the original (primal) dissimilarity:  $D^{**} = D$  (involutive property of duality).

Let  $C_D(\mathcal{P})$  be the primal  $D$ -barycenter (*right-sided  $D$ -barycenter*) and  $C_D^*(\mathcal{P})$  be the dual  $D$ -barycenter (*left-sided  $D$ -barycenter*). The dual  $D$ -barycenter with respect to  $D$  amounts to the (primal)  $D^*$ -barycenter for the dual dissimilarity  $D^*$ . When  $D$  is the squared Euclidean distance, both primal and dual centroids coincide to the center of mass.

The (primal) *information radius* [13] is defined by

$$I_D(\mathcal{P}) := \sum_{i=1}^n w_i D(P_i : C), \quad C \in C_D(\mathcal{P}), \quad (5)$$

while the *dual information radius* is defined by

$$I_D^*(\mathcal{P}) := \sum_{i=1}^n w_i D(C : P_i), \quad C \in C_D^*(\mathcal{P}). \quad (6)$$

In general, we have  $I_D^*(\mathcal{P}) \neq I_D(\mathcal{P})$  because the left-sided and right-sided centroids may not coincide. (They coincide by default when the dissimilarity is symmetric.) The information radius for the squared Euclidean distance represents the variance of the point set.

## 2 Bregman centroids and Bregman information

Let  $F(\theta)$  be a strictly convex and differentiable real-valued function for  $\theta \in \Theta$ , where  $\Theta \subset \mathbb{R}^D$  denotes the open parameter space. We define the *Bregman divergence* [6] with respect to generator  $F$  as:

$$B_F(\theta : \theta') := F(\theta) - F(\theta') - (\theta - \theta')^\top \nabla F(\theta'), \quad (7)$$

for  $\theta, \theta' \in \Theta$ .

Bregman divergences are canonical smooth dissimilarities of *dually flat space* in information geometry [2, 8]: That is, we can build a canonical Bregman divergence from any dually flat space, and a Bregman divergence yields a dually flat space [3]. In a dually flat space (or *Bregman manifold* [9]), the dissimilarity between two points  $P$  and  $Q$  is expressed by

$$D_F(P : Q) := B_F(\theta(P) : \theta(Q)), \quad (8)$$

where  $\theta(\cdot)$  is a *global (affine) coordinate system* used to define the *potential function*  $F(\theta)$ , see [2, 8]. The dual divergence amounts to a dual Bregman divergence  $B_{F^*}$  as follows:

$$D_F^*(P : Q) = D(Q : P) = B_F(\theta(Q) : \theta(P)) = B_{F^*}(\eta(P) : \eta(Q)) = D_{F^*}(P : Q), \quad (9)$$

where  $F^*$  is the Legendre-Fenchel convex conjugate [9], and  $\eta(\theta) = \nabla F(\theta)$  the dual affine global coordinate system [2, 8]. We can introduce the *Legendre-Fenchel divergence* from the dual potential functions  $F$  and  $F^*$  as follows:

$$A_F(\theta : \eta') := F(\theta) + F^*(\eta') - \theta^\top \eta' \geq 0 \quad (10)$$

with equality if and only if  $\eta' = \nabla F(\theta)$ , or equivalently  $\theta = \nabla F^*(\eta')$ .

Thus, in a Bregman manifold, we have the dual divergences that can be expressed using the dual coordinate systems either by Bregman divergences or by Legendre-Fenchel divergences as follows:

$$D_F(P : Q) = B_F(\theta(P) : \theta(Q)) = A_F(\theta(P) : \eta(Q)) =: D_F^*(Q : P), \quad (11)$$

$$D_F^*(P : Q) = B_{F^*}(\eta(P) : \eta(Q)) = A_{F^*}(\eta(P) : \theta(Q)) =: D_F(Q : P). \quad (12)$$

**Theorem 1** *Theorem 3.1 and Theorem 3.2 of [12] Let  $\theta_i = \theta(P_i)$  and  $\eta_i = \eta(P_i)$  be the primal and dual coordinates of point  $P_i$  for  $P_i \in \mathcal{P} = \{P_1, \dots, P_n\}$ . Let  $\bar{\theta} = \sum_{i=1}^n w_i \theta_i$  and  $\bar{\eta} = \sum_{i=1}^n w_i \eta_i$  denote the center of mass in the primal  $\theta$ -coordinate system and dual  $\eta$ -coordinate system, respectively. The right-sided Bregman centroid  $C_{D_F}(\mathcal{P})$  and the left-sided Bregman centroid  $C_{D_F}^*(\mathcal{P})$  exist and are both unique, and we have  $\theta(C_{D_F}(\mathcal{P})) = \bar{\theta}$  and  $\eta(C_{D_F}^*(\mathcal{P})) = \bar{\eta}$ .*

**Proof:** We have

$$C_{D_F}(\mathcal{P}) = \arg \min_{X \in \mathbb{G}} \sum_{i=1}^n w_i D_F(P_i : X), \quad (13)$$

$$= \arg \min_{X \in \mathbb{G}} \sum_{i=1}^n w_i A_F(\theta_i : \eta(X)), \quad (14)$$

$$= \arg \min_{X \in \mathbb{G}} E(X) = \left( \sum_{i=1}^n w_i F(\theta_i) \right) + F^*(\eta(X)) - \bar{\theta}^\top \eta(X). \quad (15)$$

A point  $X \in C_{D_F}(\mathcal{P})$  if and only if  $\nabla_{\eta(X)} = 0$ :  $\nabla_{\eta} F^*(\eta(X)) = \bar{\theta}$ . That is:

$$\eta(X) = (\nabla F^*)^{-1}(\bar{\theta}) = (\nabla F^*)^{-1} \left( \sum_{i=1}^n w_i \nabla F^*(\eta_i) \right). \quad (16)$$

The right-sided centroid is unique since the Hessian  $\nabla_{\eta(X)}^2 E(X)$  is  $\nabla^2 F^*(\eta(X))$ , and  $\nabla^2 F^*$  is positive-definite ( $F^*$  is a strictly convex conjugate). The right-sided centroid is expressed in the  $\theta$ -coordinate system as  $\theta(C_{D_F}(\mathcal{P})) = (\nabla F^*)(\eta(C_{D_F}(\mathcal{P}))) = (\nabla F^*)((\nabla F^*)^{-1}(\bar{\theta})) = \bar{\theta}$ .

The proof for the left-sided centroid is similar, and we have  $\theta(C_{D_F}^*(\mathcal{P})) = (\nabla F)^{-1}(\bar{\eta}) = (\nabla F)^{-1}(\sum_{i=1}^n w_i \nabla F(\theta_i))$  so that  $C_{D_F}^*(\mathcal{P})$  expressed in the  $\eta$ -coordinate system is  $\bar{\eta}$ .  $\square$

To summarize, we have:

	$\theta$ -coordinate system	$\eta$ -coordinate system
Right-sided centroid $C_{D_F}(\mathcal{P})$	$\bar{\theta} = \sum_{i=1}^n w_i \theta_i$	$(\nabla F^*)^{-1}(\sum_{i=1}^n w_i \nabla F^*(\eta_i))$
Left-sided centroid $C_{D_F}^*(\mathcal{P})$	$(\nabla F)^{-1}(\sum_{i=1}^n w_i \nabla F(\theta_i))$	$\bar{\eta} = \sum_{i=1}^n w_i \eta_i$

In term of Bregman divergences, the right-sided Bregman centroid is the center of mass [4]. The Bregman information radius is called *Bregman information* in [4]. It was shown in [11, 5] that the only *symmetrized Bregman divergences* are squared Mahalanobis divergences. Thus the left-sided centroid and right-sided Bregman centroids coincide only for squared Mahalanobis divergences, and the dual Bregman information radii differ in the general case.

**Corollary 1** *Correct Corollary 3.3 of [12] The information radius  $I_{D_F}(\mathcal{P}) = J_F(\theta_1, \dots, \theta_n; w_1, \dots, w_n)$  where  $J_F$  denotes the Jensen diversity index [10]:*

$$J_F(\theta_1, \dots, \theta_n; w_1, \dots, w_n) := \sum_{i=1}^n w_i \theta_i - F \left( \sum_{i=1}^n w_i \theta_i \right) \geq 0. \quad (17)$$

*The dual information radius  $I_{D_F}^*(\mathcal{P}) = I_{D_F^*}(\mathcal{P}) = J_{F^*}(\eta_1, \dots, \eta_n; w_1, \dots, w_n)$  differs from the primal information radius except when  $D_F$  is a squared Mahalanobis divergence.*

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