

# Reflection about the geodesic passing through two given points in the Poincaré disk model of hyperbolic geometry

Frank Nielsen

December 14, 2023  
(December 2023)

A geodesic  $\gamma(l)$  is parameterized by constant speed so that  $\rho(\gamma(l), \gamma(l')) = |l - l'| \rho(\gamma(0), \gamma(1))$ . This is equivalent to saying that the geodesic  $\gamma(l)$  is parameterized by arc length  $l$ .

A pregeodesic  $\bar{\gamma}(t) = \bar{\gamma}(l(t))$  is a reparameterization of the geodesic such that  $l(t)$  is a smooth and invertible with inverse function  $t(l)$ . Pregeodesics can yield simplified mathematical expressions and express equivalently the geodesic curves:

$$c_\gamma = \{\gamma(l) : l \in [0, 1]\} = \{\bar{\gamma}(t) : t \in [0, 1]\}.$$

In the Klein model, pregeodesics passing through two points  $k_1$  and  $k_2$  of the unit disk are Euclidean line segments:

$$\bar{\gamma}_K(t) = k_1 + t(k_2 - k_1),$$

with  $c_{\gamma_K} = [k_1 k_2]$ . The geodesic equation in Klein model has been reported in [?], i.e., the function  $l(t)$  such that

$$\gamma_K(l) = \bar{\gamma}_K(l(t))$$

is given in closed-form.

To find  $\Gamma_K = \{\gamma_K(l) : l \in \mathbb{R}\}$ , we need to find  $t_m$  and  $t_M$  such that  $\Gamma_K$  is the line passing through  $[k_1 k_2]$  clipped to the unit disk. That is,  $t_m$  and  $t_M$  are the two solutions of the quadratic equation:

$$\langle k_1 + t(k_2 - k_1), k_1 + t(k_2 - k_1) \rangle = 1$$

Let  $\Delta = 4\langle k_1, k_2 - k_1 \rangle^2 - 4\|k_2 - k_1\|^2(\|k_1\|^2 - 1)$ .

A model of a geometry is said conformal if the angles of two curves  $c_1(t)$  and  $c_2(t)$  intersecting at  $t_0$  match the Euclidean angles. The Poincaré disk model is conformal but not the Klein model (except at the origin).

$$\begin{aligned} (30/3) \quad [a0 = -\frac{(b2-b1) b3^2 + (-b2^2+b1^2-a2^2+a1^2) b3+b1 b2^2+(-b1^2+a3^2-a1^2) b2+(a2^2-a3^2) b1}{(2 a2-2 a1) b3+(2 a1-2 a3) b2+(2 a3-2 a2) b1}, b0 = \\ \frac{(a2-a1) b3^2+(a1-a3) b2^2+(a3-a2) b1^2+(a2-a1) a3^2+(a1^2-a2^2) a3+a1 a2^2-a1^2 a2}{(2 a2-2 a1) b3+(2 a1-2 a3) b2+(2 a3-2 a2) b1}, r0 = \text{sqrt}((b2^2-2 b1 b2+b1^2+a2^2-2 a1 a2+a1^2) b3^4 + \\ (-2 b2^3+2 b1 b2^2+(2 b1^2-2 a2^2+4 a1 a2-2 a1^2) b2-2 b1^3+(-2 a2^2+4 a1 a2-2 a1^2) b1) b3^3+(b2^4+2 b1 b2^3+(-6 b1^2+2 a3^2+(-2 a2-2 a1) a3+2 a2^2-2 a1 a2+2 a1^2) b2^2 + \\ (2 b1^3+(-4 a3^2+(4 a2+4 a1) a3+2 a2^2-8 a1 a2+2 a1^2) b1) b2+b1^4+(2 a3^2+(-2 a2-2 a1) a3+2 a2^2-2 a1 a2+2 a1^2) b1^2+(2 a2^2-4 a1 a2+2 a1^2) a3^2 + \\ (-2 a2^3+2 a1 a2^2+2 a1^2 a2-2 a1^3) a3+a2^4-2 a1 a2^3+2 a1^2 a2^2-2 a1^3 a2+a1^4) b3^2+(-2 b1 b2^4+(2 b1^2-2 a3^2+4 a1 a3-2 a1^2) b2^3 + \\ (2 b1^3+(2 a3^2+(4 a2-8 a1) a3-4 a2^2+4 a1 a2+2 a1^2) b1) b2^2 + \\ (-2 b1^4+(2 a3^2+(4 a1-8 a2) a3+2 a2^2+4 a1 a2-4 a1^2) b1^2+(-2 a2^2+4 a1 a2-2 a1^2) a3^2+(4 a1 a2^2-8 a1^2 a2+4 a1^3) a3-2 a1^2 a2^2+4 a1^3 a2-2 a1^4) b2 + \\ (-2 a3^2+4 a2 a3-2 a2^2) b1^3+((-2 a2^2+4 a1 a2-2 a1^2) a3^2+(4 a2^3-8 a1 a2^2+4 a1^2 a2) a3-2 a2^4+4 a1 a2^3-2 a1^2 a2^2) b1) b3+(b1^2+a3^2-2 a1 a3+a1^2) b2^4 + \\ ((-2 a3^2+4 a1 a3-2 a1^2) b1-2 b1^3) b2^3 + \\ (b1^4+(2 a3^2+(-2 a2-2 a1) a3+2 a2^2-2 a1 a2+2 a1^2) b1^2+a3^4+(-2 a2-2 a1) a3^3+(2 a2^2+2 a1 a2+2 a1^2) a3^2+(-4 a1 a2^2+2 a1^2 a2-2 a1^3) a3+2 a1^2 a2^2-2 a1^3 a2+a1^4) b2^2 + \\ b2^2+((-2 a3^2+4 a2 a3-2 a2^2) b1^3+(-2 a3^4+(4 a2+4 a1) a3^3+(-2 a2^2-8 a1 a2-2 a1^2) a3^2+(4 a1 a2^2+4 a1^2 a2) a3-2 a1^2 a2^2) b1) b2+(a3^2-2 a2 a3+a2^2) b1^4 + \\ (a3^4+(-2 a2-2 a1) a3^3+(2 a2^2+2 a1 a2+2 a1^2) a3^2+(-2 a2^2+2 a1 a2^2-4 a1^2 a2) a3+a2^4-2 a1 a2^3+2 a1^2 a2^2) b1^2+(a2^2-2 a1 a2+a1^2) a3^4 + \\ (-2 a2^3+2 a1 a2^2+2 a1^2 a2-2 a1^3) a3^3+(a2^4+2 a1 a2^3-6 a1^2 a2^2+2 a1^3 a2+a1^4) a3^2+(-2 a1 a2^4+2 a1^2 a2^3+2 a1^3 a2^2-2 a1^4 a2) a3+a1^2 a2^4-2 a1^3 a2^3+a1^4 a2^2)/ \\ ((2 a2-2 a1) b3+(2 a1-2 a3) b2+(2 a3-2 a2) b1) J \end{aligned}$$